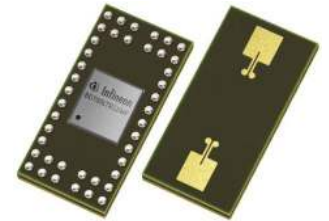


Low power 60 GHz Doppler radar sensor with antennas in package

Features

- 60 GHz transceiver MMIC with one transmitter and one receiver unit
- Antennas in package (AIP) (6.7 × 3.3 × 0.56 mm³)
- Pulsed Doppler mode of operation for low power consumption
- Autonomous mode
 - Integrated detector for motion and direction of movement
 - Direct output of motion detection signal
 - 15 configurable thresholds for target detection range
 - 16 configurations for detection status hold time
 - 4 configurable operating frequencies
 - 4 configurable pulse repetition rates
- High performance enabled from Infineon’s BiCMOS technology
 - Fully integrated low phase noise VCO and PLL
 - Medium power amplifier with configurable output power and integrated power detector
 - Low noise variable gain baseband amplifiers
 - Fully ESD protected device



Potential applications

The BGT60LTR11AIP adds ‘smartness’ to traditional motion sensing applications and beyond:

- Smart home devices (thermostats, smoke detectors, smart speakers, etc.)
- Smart building (contactless switches, occupancy and proximity sensors, etc.)
- Smart appliances (service robots, washing machine, and kitchen appliances)
- Smart lighting systems and security systems including IP cameras
- Screen based systems (TVs, monitors, laptops, or tablets)

Product validation

Qualified for industrial applications according to the relevant tests of JEDEC47/20/22.

Description

The BGT60LTR11AIP is a fully integrated millimeter wave Doppler motion sensor with antenna in package. The sensor detects the motion as well as the direction of a moving target. It supports the following two operation modes, which can be selected via hardware preset pins:

- Autonomous mode: the sensor configuration parameters, detection threshold and hold time are set via external resistors; the pulse repetition rate and the operation frequency are set via hardware preset pins
- SPI mode: it allows the SPI connection to a microcontroller for more real time sensor configurations, that can be written in the internal registers through SPI

The BGT60LTR11AIP integrates a medium power amplifier with configurable/adjustable output power, which can be controlled via SPI. The transmitted power is monitored by an integrated power detector. The packaged monolithic microwave integrated circuit (MMIC) features integrated broad-beam antennas for maximum area coverage.

| Product type | Package | Marking | Ordering code | Description |
|----------------|--------------|---------|--------------------------|---|
| BGT60LTR11AIP | PG-UF2BGA-42 | L11E | BGT60LTR11AIP E6327XUMA2 | Operates in the frequency band from 61 GHz to 61.5 GHz |
| BGT60LTR11BAIP | PG-UF2BGA-42 | L11J | BGT60LTR11BAIP XUMA1 | Operates in the frequency band from 60.5 GHz to 61 GHz (Japanese ISM band) |
| BGT60LTR11SAIP | PG-UF2BGA-42 | S11E | BGT60LTR11SAIP XUMA1 | BGT60LTR11AIP down-specified version with reduced detection range (autonomous mode) and operating temperature from -10 to +70°C |

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1 Electrical characteristics

1.1 Absolute maximum ratings

Table 1 Absolute maximum ratings

$T_{OP} = -20^{\circ}\text{C} \dots 85^{\circ}\text{C}$ for BGT60LTR11AIP and BGT60LTR11BAIP; $T_{OP} = -10^{\circ}\text{C} \dots 70^{\circ}\text{C}$ for BGT60LTR11SAIP; all voltages with respect to ground, positive current flowing into pin (unless otherwise specified).

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|--|--------------|--------|------|--------------|--------------------|---|
| | | Min. | Typ. | Max. | | |
| Supply voltage | V_{DD} | -0.3 | – | 1.9 | V | |
| Voltage applied to non-RF I/O pins | $V_{DC,I/O}$ | -0.3 | – | $V_{DD}+0.3$ | V | |
| Total power dissipation | P_{DISS} | – | – | 300 | mW | |
| Storage temperature range | T_{STG} | -40 | – | 150 | $^{\circ}\text{C}$ | |
| Operational temperature range (BGT60LTR11AIP and BGT60LTR11BAIP) | T_{OP} | -20 | – | +85 | $^{\circ}\text{C}$ | Temperature at package soldering point |
| Operational temperature range (BGT60LTR11SAIP) | T_{OP} | -10 | – | +70 | $^{\circ}\text{C}$ | Temperature at package soldering point |
| Thermal resistance of package | $R_{th,P}$ | – | 67 | – | K/W | Represents bulk silicon to solder balls |

Attention: Stresses above the maximum values listed here may cause permanent damage to the device. Maximum ratings are absolute ratings; exceeding only one of these values may cause irreversible damage to the integrated circuit. Exposure to conditions at or below absolute maximum rating but above the specified maximum operation conditions may affect device reliability and lifetime. Functionality of the device might not be given under these conditions.

1.2 ESD integrity

Table 2 ESD integrity

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|--------------------|---------------|--------|------|------|------|------------------------|
| | | Min. | Typ. | Max. | | |
| ESD robustness HBM | $V_{ESD-HBM}$ | -1 | – | 1 | kV | All pins |
| ESD robustness CDM | $V_{ESD-CDM}$ | -500 | – | 500 | V | All pins |

1 Electrical characteristics

1.3 Power supply

Table 3 Power supply electrical characteristics

$T_{OP} = -20^{\circ}\text{C} \dots 85^{\circ}\text{C}$ for BGT60LTR11AIP and BGT60LTR11BAIP; $T_{OP} = -10^{\circ}\text{C} \dots 70^{\circ}\text{C}$ for BGT60LTR11SAIP.

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|--|------------------|--------|------|------|------|------------------------------------|
| | | Min. | Typ. | Max. | | |
| Supply voltage | V_{DD} | 1.45 | 1.5 | 1.6 | V | |
| Current consumption in pulse-on phase | I_{Pulse_ON} | – | 128 | – | mA | |
| Current consumption in pulse-off phase | I_{Pulse_OFF} | – | 0.8 | – | mA | |
| Pulsed mode average power consumption | $P_{5/2000}$ | – | 2.3 | – | mW | Duty cycle of 5/2000 μs |
| | $P_{5/1000}$ | – | 3.4 | – | mW | Duty cycle of 5/1000 μs |
| | $P_{5/500}$ | – | 5.6 | – | mW | Duty cycle of 5/500 μs |
| | $P_{5/250}$ | – | 10.3 | – | mW | Duty cycle of 5/250 μs |

1.4 System parameters

Table 4 System parameters

$T_{OP} = -20^{\circ}\text{C} \dots 85^{\circ}\text{C}$ for BGT60LTR11AIP and BGT60LTR11BAIP; $T_{OP} = -10^{\circ}\text{C} \dots 70^{\circ}\text{C}$ for BGT60LTR11SAIP.

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|--|---------------------|--------|-------|------|-------|---|
| | | Min. | Typ. | Max. | | |
| Supply voltage | V_{DD} | 1.45 | 1.5 | 1.6 | V | |
| Transmitted frequency (BGT60LTR11AIP and BGT60LTR11SAIP) | f_{TX} | 61 | 61.25 | 61.5 | GHz | $V_{tune} = V_{CPOUTPLL}$ |
| Transmitted frequency (BGT60LTR11BAIP) | f_{TX_B} | 60.5 | 60.75 | 61 | GHz | $V_{tune} = V_{CPOUTPLL}$ |
| Output power (EIRP ¹⁾) | P_{TX} | – | +10 | – | dBm | |
| Spurious emission < 40 GHz (EIRP) | P_{SPUR1} | – | – | -42 | dBm | FCC 15.209 |
| Spurious emission > 40 GHz and < 57 GHz (EIRP) | P_{SPUR2} | – | – | -20 | dBm | ETSI EN 305 550 |
| Spurious emission > 64 GHz and < 78 GHz (EIRP) | P_{SPUR3} | – | – | -20 | dBm | ETSI EN 305 550 |
| Spurious emission > 78 GHz (EIRP) | P_{SPUR4} | – | – | -30 | dBm | ETSI EN 305 550 |
| Frequency drift vs. temperature | $\Delta f/\Delta T$ | – | -10 | – | MHz/K | $T_{OP} = -20^{\circ}\text{C} \dots +85^{\circ}\text{C}$ $V_{DD} = 1.5\text{ V}$ Free running VCO |

1) Equivalent isotropic radiated power.

1.5 PLL parameters

Table 5 PLL parameters

$T_{OP} = -20^{\circ}\text{C} \dots 85^{\circ}\text{C}$ for BGT60LTR11AIP and BGT60LTR11BAIP; $T_{OP} = -10^{\circ}\text{C} \dots 70^{\circ}\text{C}$ for BGT60LTR11SAIP; $V_{DD} = 1.45\text{ V} \dots 1.6\text{ V}$.

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|---|------------|--------|------|------|------|------------------------|
| | | Min. | Typ. | Max. | | |
| External crystal frequency | f_{CRY} | – | 38.4 | – | MHz | |
| PLL lock frequency (BGT60LTR11AIP and BGT60LTR11SAIP) ¹⁾ | f_L | 61 | – | 61.5 | GHz | |
| PLL lock frequency (BGT60LTR11BAIP) ¹⁾ | f_{L_B} | 60.5 | – | 61 | GHz | |

1) Programmed through Reg5 (for more information refer to AN625). Keep a 50 MHz guard band each side from the band edge to avoid outside of ISM band emission.

Warning: *Sensors operating in close vicinity at the same operating frequency can interfere!*

1.6 Frequency divider

Table 6 Frequency divider electrical characteristics

$T_{OP} = -20^{\circ}\text{C} \dots 85^{\circ}\text{C}$ for BGT60LTR11AIP and BGT60LTR11BAIP; $T_{OP} = -10^{\circ}\text{C} \dots 70^{\circ}\text{C}$ for BGT60LTR11SAIP; $V_{DD} = 1.45\text{ V} \dots 1.6\text{ V}$, Freq = 61.25 GHz.

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|------------------------------|---------------|--------|----------|----------|------|---|
| | | Min. | Typ. | Max. | | |
| Divider output frequency 1 | f_{DIV1} | – | 9.6 | – | MHz | Selectable via SPI (divided by 4 from crystal oscillator) |
| Dividing factor 2 | D_{DIV1} | – | 2^{14} | – | – | Selectable via SPI |
| Dividing factor 3 | D_{DIV2} | – | 2^{17} | – | – | Selectable via SPI |
| Dividing factor 4 | D_{DIV3} | – | 2^{21} | – | – | Selectable via SPI |
| Divider output voltage range | V_{DIV} | 0 | – | V_{DD} | V | |
| External capacitive load | $C_{extLoad}$ | – | – | 15 | pF | |

1.7 Antenna characteristics

Table 7 Antenna in package specifications

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|--|--------------|--------|------|------|------|------------------------|
| | | Min. | Typ. | Max. | | |
| Operating frequency range (BGT60LTR11AIP and BGT60LTR11SAIP) | f_{op} | 60.5 | – | 61.5 | GHz | |
| Transmitter antenna gain | G_{TX} | – | 6 | – | dBi | @ Freq = 61.25 GHz |
| Receiver antenna gain | G_{RX} | – | 6 | – | dBi | @ Freq = 61.25 GHz |
| Horizontal -6dB beamwidth | H_{-6dBbw} | – | ±50 | – | deg | @ Freq = 61.25 GHz |
| Vertical -6dB beamwidth | E_{-6dBbw} | – | ±70 | – | deg | @ Freq = 61.25 GHz |
| Horizontal sidelobe level (H-SLL) | | – | 12 | – | dB | @ Freq = 61.25 GHz |
| Vertical sidelobe level (V-SLL) | | – | 12 | – | dB | @ Freq = 61.25 GHz |
| TX-RX isolation on antenna level | | – | 35 | – | dB | @ Freq = 61.25 GHz |

2 SPI interface

2.1 SPI timing requirements

The BGT60LTR11AIP is configured using a 4-wire SPI. It is used to configure the internal blocks of the BGT60LTR11AIP chip registers. The main tasks are to set the mode of operation of the TX and/or RX chain and the baseband section. Communication with an external microcontroller is possible through the four dedicated pins SPIDI, SPIDO, SPICS and SPICLK. [Figure 1](#) demonstrates how the timing of the SPI behaves. The “working edge” is the rising edge of the clock SPICLK. The master application processor presents data for BGT60LTR11AIP at the falling edge on SPIDI, while BGT60LTR11AIP samples data at the rising edge. Read data is presented for the master on the rising edge on SPIDO. Asynchronous reset (SPIRSTN) must be de-asserted at least 10 ns before the falling edge of SPICLK. Refer to the application note AN625 for all details related to the SPI registers to control the MMIC.

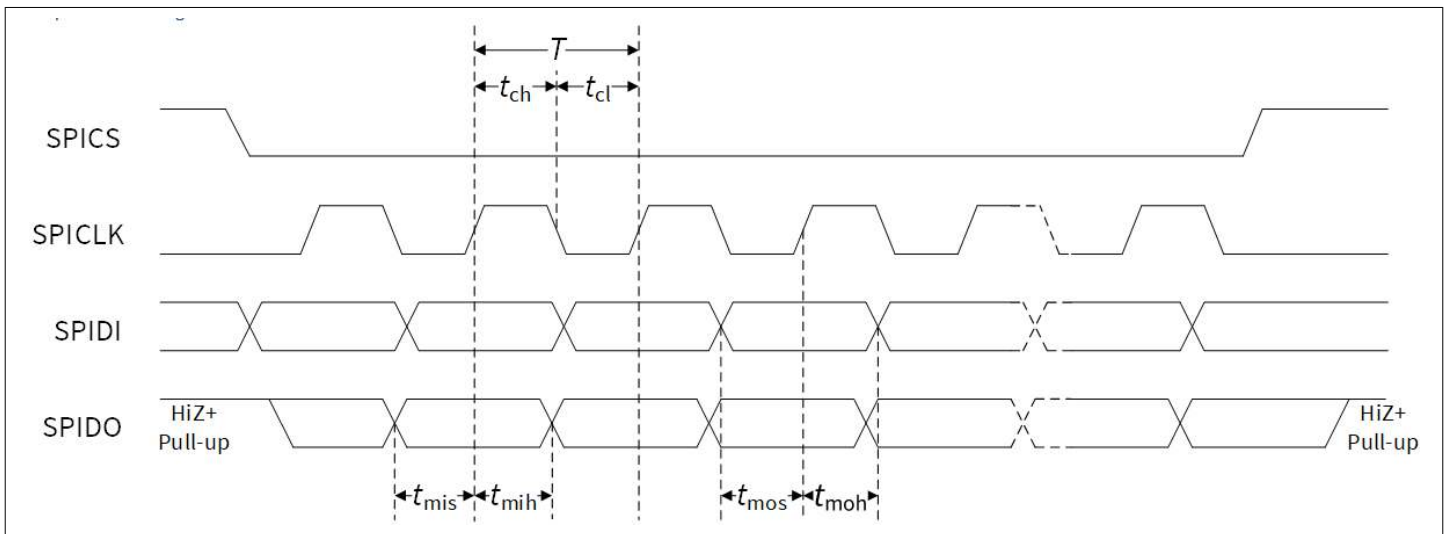


Figure 1 SPI timing diagram

Table 8 SPI timing requirements

| Parameter | Symbol | Values | | | Unit | Note or Test Condition |
|------------------|-----------|--------|------|------|------|-------------------------------|
| | | Min. | Typ. | Max. | | |
| SPI clock period | T | 20 | – | – | ns | 50 MHz, with <1% clock jitter |
| Clock high time | t_{ch} | 9 | – | – | ns | |
| Clock low time | t_{cl} | 9 | – | – | ns | |
| Setup time SPIDI | t_{mos} | 5 | – | – | ns | |
| Hold time SPIDI | t_{moh} | 5 | – | – | ns | |
| Setup time SPIDO | t_{mis} | 5 | – | – | ns | |
| Hold time SPIDO | t_{mih} | 4 | – | – | ns | |

3 Block diagram and pin description

3.1 Block diagram

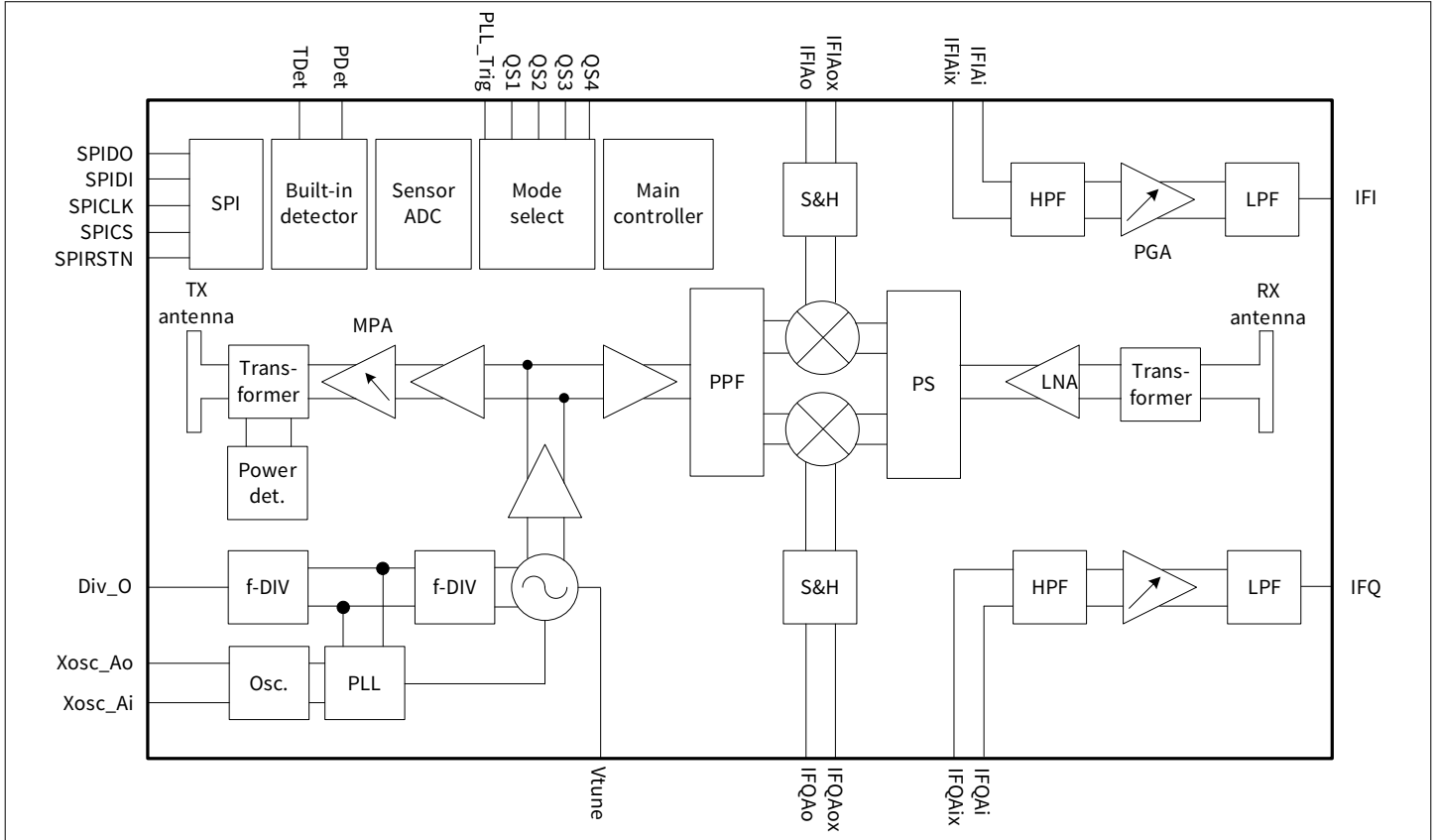


Figure 2 BGT60LTR11AIP block diagram

3.2 Pin out

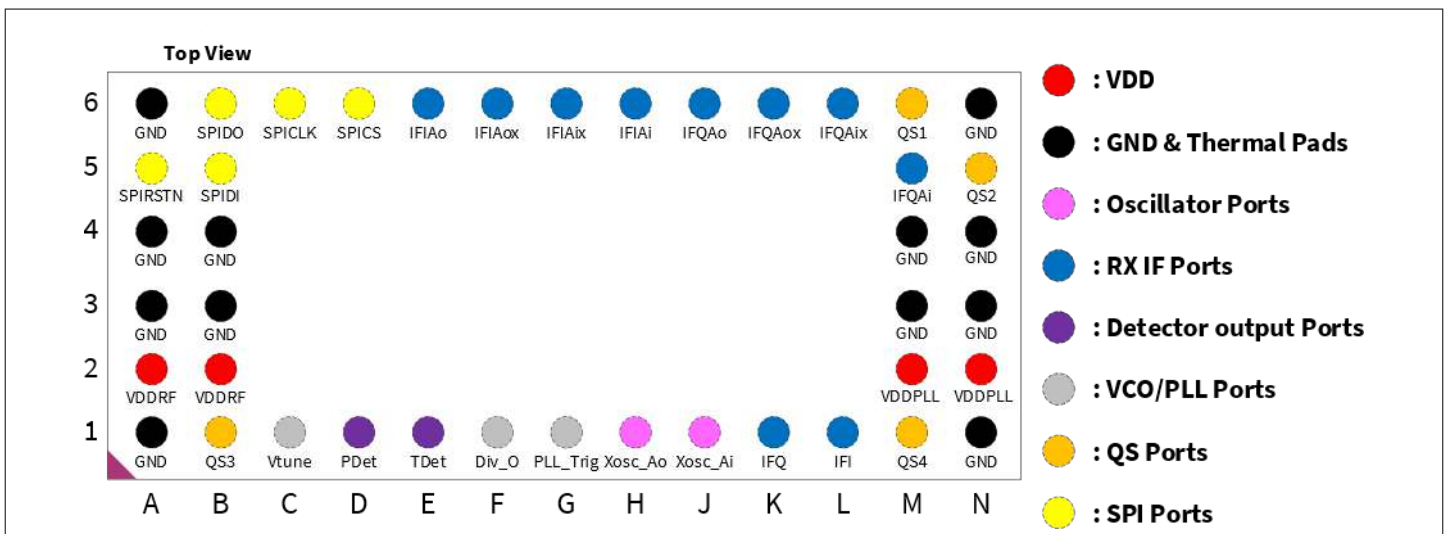


Figure 3 BGT60LTR11AIP pin out (top view)

3.3 Pin definition and function

Table 9 Pin definition and function

| Pin number | Name | Function |
|--|---------------|--|
| A1, N1, A3, B3, M3, N3, A4, B4, M4, N4, A6, N6 | GND | Ground |
| A2, B2 | VDDRF | DC supply of 1.5 V to internal RF circuitry |
| M2, N2 | VDDPLL | DC supply of 1.5 V to internal PLL circuitry |
| M6 | QS1 | Quad state input 1 – voltage value |
| N5 | QS2 | Quad state input 2 or analog input to configure detector threshold |
| B1 | QS3 | Quad state input 3 or analog input to configure detector hold time |
| M1 | QS4 | Quad state input 4 |
| A5 | SPIRSTN | SPI reset, active low |
| B5 | SPIDI | SPI data in |
| B6 | SPIDO | SPI data out |
| C6 | SPICLK | SPI clock |
| D6 | SPICS | SPI chip select, active low |
| E6, F6 | IFIAo, IFIAox | Complementary in phase down converter IF output |
| J6, K6 | IFQAo, IFQAox | Complementary quadrature phase down converter IF output |
| G6, H6 | IFIAix, IFIAi | Analog IF input PGA – complementary in phase |
| L6, M5 | IFQAix, IFQAI | Analog IF input PGA – complementary quadrature phase |
| K1 | IFQ | ABB output – Q Channel |
| L1 | IFI | ABB output – I Channel |
| C1 | Vtune | VCO tuning voltage |
| D1 | PDet | Detector output – direction of movement |
| E1 | TDet | Detector output – motion |
| F1 | Div_O | Frequency divider output |
| G1 | PLL_Trig | “Advance mode” and “Basic mode” switch |
| H1 | Xosc_Ao | Internal oscillator quartz node |
| J1 | Xosc_Ai | Internal oscillator quartz node |

4 Package dimensions and footprint

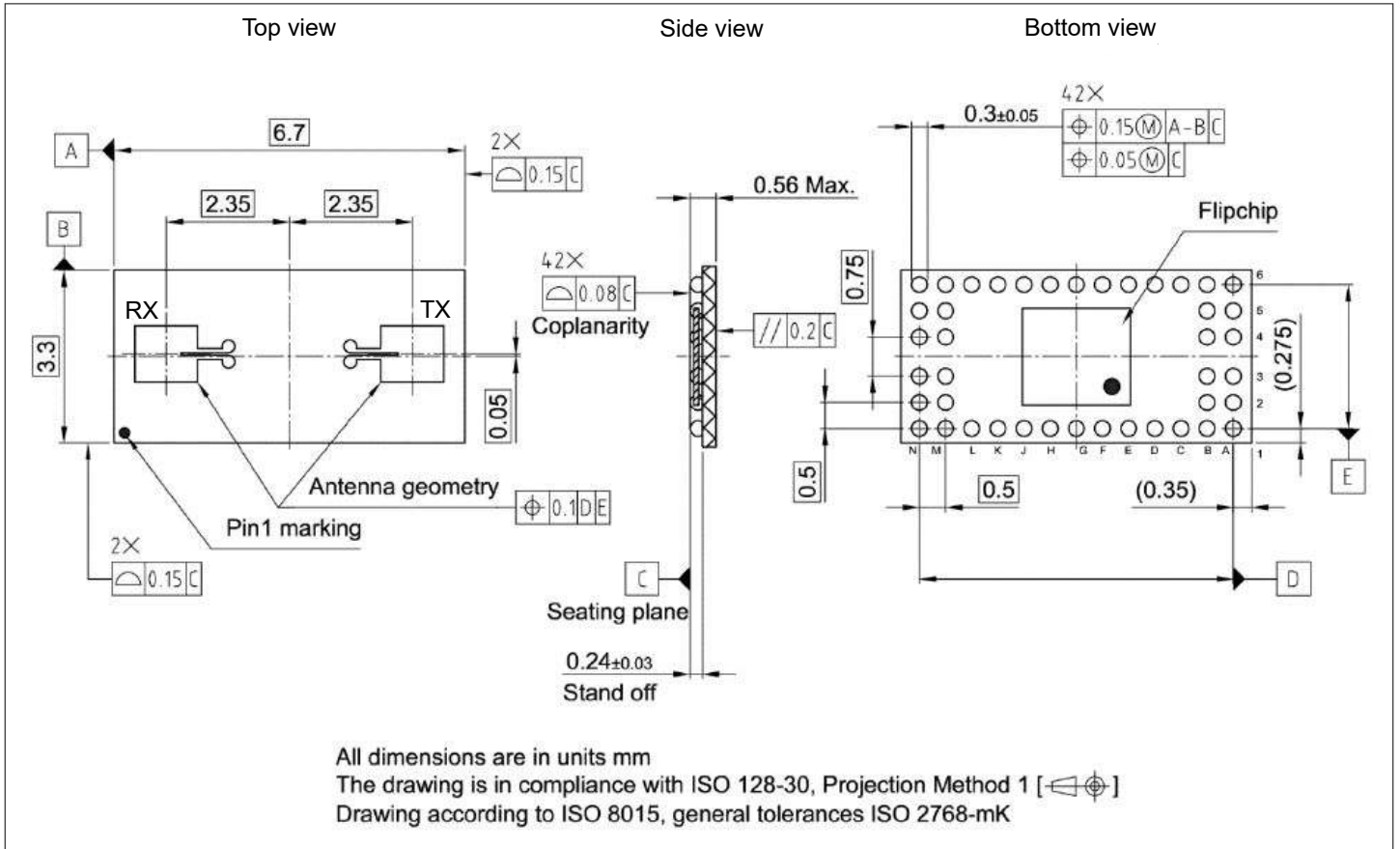


Figure 4 Package outline. Top, side and bottom view of PG-UF2BGA-42-1

Revision history

| Document version | Date of release | Description of changes |
|-------------------------|------------------------|--|
| V2.4 | 2021-10-11 | Updated preliminary datasheet |
| V2.5 | 2021-11-05 | First formal release version |
| V2.6 | 2022-08-01 | Support BGT60LTR11SAIP down-specified MMIC version |

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