



ESD Sensitive

Date of Issue: November 7, 2013

3.0 x 3.0 mm

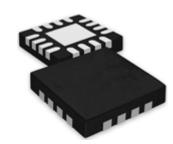
Revision : A

Page 1 of 37

Abracon Drawing #453568

### Features

- Ultra-low supply current (all at 3V):
  - 14 nA with RC oscillator
  - 22 nA with RC oscillator and Autocalibration
- 55 nA with crystal oscillator
- Baseline timekeeping features:
  - 32.768 kHz crystal oscillator with integrated load capacitor/resistor
  - Counters for hundredths, seconds, minutes, hours, date, month, year, century, and week-day
  - Alarm capability on all counters
  - Programmable output clock generation (32.768 kHz to 1 year)
  - Countdown timer with repeat function
  - Automatic leap year calculation
- Advanced timekeeping features:
  - Integrated power optimized RC oscillator
  - Advanced crystal calibration to ± 2 ppm
  - Advanced RC calibration to ± 16 ppm
  - Automatic calibration of RC oscillator to crystal oscillator
  - Watchdog timer with hardware reset
  - Up to 256 bytes of general purpose RAM
- Power management features:
  - Integrated  ${\sim}1\Omega$  power switch for off-chip components such as a host MCU
  - System sleep manager for managing host processor wake/sleep states
  - External reset signal monitor
  - Reset output generator
  - Supercapacitor trickle charger with programmable charging current
  - Automatic switchover to VBAT
  - External interrupt monitor
  - Programmable low battery detection threshold
    Programmable analog voltage comparator
- I<sup>2</sup>C (up to 400 kHz) and 3-wire or 4-wire SPI (up to 2 MHz) serial interfaces available
- Operating voltage 1.5-3.6 V
- Clock and RAM retention voltage 1.5-3.6 V
- Operating temperature –40 to 85 °C
- All inputs include Schmitt Triggers
- 3x3 mm QFN-16 package



## Applications

- Smart cards
- · Wireless sensors and tags
- Medical electronics
- Utility meters
- Data loggers
- Appliances
- Handsets
- Consumer electronics
- Communications equipment

## Description

The ABRACON AB18XX Real Time Clock with Power Management family provides а groundbreaking combination of ultra-low power coupled with a highly sophisticated feature set. With power requirements significantly lower than any other industry RTC (as low as 14 nA), these are the first semiconductors based on innovative SPOT<sup>TM</sup> (Subthreshold Power Optimized Technology) CMOS platform. The AB18XX includes on-chip oscillators to provide minimum power consumption, full RTC functions includina batterv backup and programmable counters and alarms for timer and watchdog functions, and either an I<sup>2</sup>C or SPI serial interface for communication with a host controller. An integrated power switch and a sophisticated system sleep manager with counter, timer, alarm, and interrupt capabilities allows the AM18XX to be used as a supervisory component in a host microcontroller based system.

**Disclaimer:** AB18XX series of devices are based on innovative SPOT technology, proprietary to Ambiq Micro.

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 2 of 37	Abracon Drawing #453568	Revision : A

## 1. Family Summary

The AB18XX family consists of several members (see Table 1). All devices are supplied in a standard 3x3 mm QFN-16 package. Members of the software and pin compatible AB18XX RTC family are also listed.

		aseline ekeeping		Advanced Timekeeping			Power Management			ent	
Part #	XT Osc	Number of GP Outputs	RC Osc	Calib/ Auto- calib	Watch- dog	RAM (B)	VBAT Switch	Reset Mgmt	Ext Int	Power Switch and Sleep FSM	Interface
AB1801	•	2		•		0				•	l <sup>2</sup> C
AB1803	•	2		•		64				■	l <sup>2</sup> C
AB1804	•	4	•		•	256			-		l <sup>2</sup> C
AB1805	•	4	•	•		256			-	■	l <sup>2</sup> C
AB1811	•	2	•	•		0					SPI
AB1813	•	2				64	•				SPI
AB1814		3				256					SPI
AB1815	•	3	-			256	•				SPI
			Softw	are and Pin	Compatib	ole AB08X	X Family	Component	s		
AB0801		2		•		0					l <sup>2</sup> C
AB0803	•	2		•		64					l <sup>2</sup> C
AB0804	•	4	•		•	256			-		l <sup>2</sup> C
AB0805	•	4		•	•	256			-		l <sup>2</sup> C
AB0811	•	2	•	•		0					SPI
AB0813		2	-			64					SPI
AB0814		3				256					SPI
AB0815	•	3	-	•	•	256	•		-		SPI

#### Table 1: Family Summary

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 3 of 37	Abracon Drawing #453568	Revision : A

## 2. Functional Description

Figure 1 illustrates the AB18XX functional design.

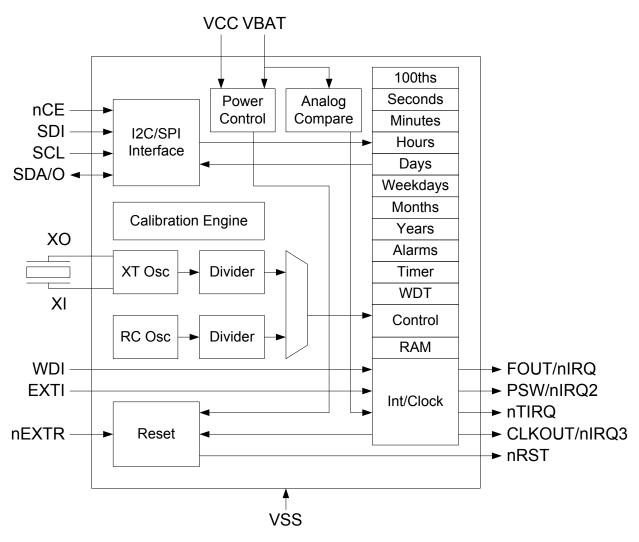


Figure 1. Detailed Block Diagram

AB18XX serves as a companion part for host processors including microcontrollers, radios, and digital signal processors. It tracks time as in a typical RTC product and additionally provides unique power management functionality that makes it ideal for highly energy-constrained applications. To support such operation, the AB18XX includes 3 distinct feature groups: 1) baseline timekeeping features, 2) advanced timekeeping features, and 3) power management features. Functions from each feature group may be controlled via I/O offset mapped registers. These registers are accessed using either an I<sup>2</sup>C serial interface (e.g., in the AB1805) or a SPI serial interface (e.g., in the AB1815). Each feature group is described briefly below and in greater detail in subsequent sections.

The baseline timekeeping feature group supports the standard 32.786 kHz crystal (XT) oscillation mode for maximum frequency accuracy with an ultra-low current draw of 55 nA. The baseline timekeeping feature group also includes a standard set of counters monitoring hundredths of a second up through centuries. A

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 4 of 37	Abracon Drawing #453568	Revision : A

complement of countdown timers and alarms may additionally be set to initiate interrupts or resets on several of the outputs.

The advanced timekeeping feature group supports two additional oscillation modes: 1) RC oscillator mode, and 2) Autocalibration mode. At only 14 nA, the temperature-compensated RC oscillator mode provides an even lower current draw than the XT oscillator for applications with reduced frequency accuracy requirements. A proprietary calibration algorithm allows the AB18XX to digitally tune the RC oscillator frequency and the XT oscillator frequency with accuracy as low as 2 ppm at a given temperature. In Autocalibration mode, the RC oscillator is used as the primary oscillation source and is periodically calibrated against the XT oscillator. Autocalibration may be done automatically every 8.5 minutes or 17 minutes and may also be initiated via software. This mode enables average current draw of only 22 nA with frequency accuracy similar to the XT oscillator. The advanced timekeeping feature group also includes a rich set of input and output configuration options that enables the monitoring of external interrupts (e.g., pushbutton signals), the generation of clock outputs, and watchdog timer functionality.

Power management features built into the AB18XX enable it to operate as a backup device in both linepowered and battery-powered systems. An integrated power control module automatically detects when main power (VCC) falls below a threshold and switches to backup power (VBAT). Up to 256B of ultra-low leakage RAM enable the storage of key parameters when operating on backup power. VBAT power switching is included in the AB1803, AB1813, AB1813 and AB1815 parts only.

The AB18XX is the first RTC to incorporate a number of more advanced power management features. In particular, the AB18XX includes a finite state machine (integrated with the Power Control block in Figure 1) that can control a host processor as it transitions between sleep/reset states and active states. Digital outputs can be configured to control the reset signal or interrupt input of the host controller. The AB18XX additionally integrates a power switch with ~1  $\Omega$  impedance that can be used to cut off ground current on the host microcontroller and reduce sleep current to <1 nA. The AB18XX parts can wake up a sleeping system using internally generated timing interrupts or externally generated interrupts generated by digital inputs (e.g., using a pushbutton) or an analog comparator. The aforementioned functionality enables users to seamlessly power down host processors, leaving only the energy-efficient AB18XX chip awake. The AB18XX also includes voltage detection on the backup power supply.

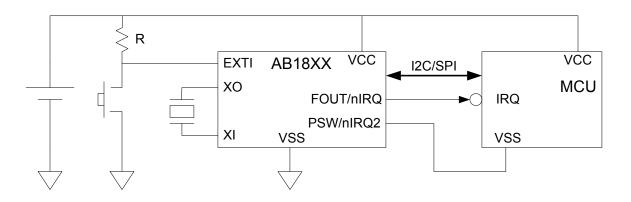
he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 5 of 37	Abracon Drawing #453568	Revision : A

## 3. AB18XX Application Examples

The AB18XX enables a variety of system implementations in which the AB18XX can control power usage by other elements in the system. This is typically used when the entire system is powered from a battery and minimizing total power usage is critical. The backup RAM in the AB18XX can be used to hold key MCU parameters when it is powered down.

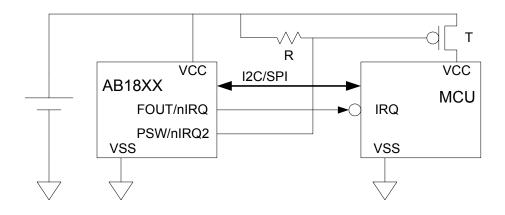
## 3.1 VSS Power Switched

In the recommended implementation, the internal power switch of the AB18XX is used to completely turn off the MCU and/or other system elements. In this case the PSW/nIRQ2 output is configured to generate the Sleep function. Under normal circumstances, the PSW/nIRQ2pin is pulled to VSS with less than 1 ohm of resistance, so that the MCU receives full power. The MCU initiates a SLP operation, and when the AB18XX enters Sleep Mode the PSW/nIRQ2 pin is opened and power is completely removed from the MCU. This results in significant additional power savings relative to the other alternatives. A variety of interrupts, including alarms, timers and external interrupts created by a pushbutton as shown, may be used to exit Sleep Mode and restore MCU power. The RAM of the AB18XX may be used to retain critical MCU parameters.



## 3.2 VCC Power Switched

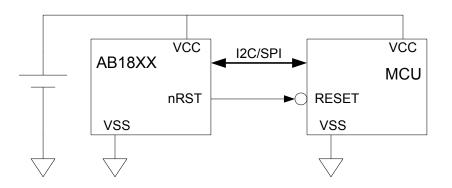
An external transistor switch T may also be used to turn off power to the MCU. This implementation allows switching higher current and maintains a common ground. R can be on the order of megohms, so that negligible current is drawn when the circuit is active and PSW/nIRQ2 is low.



The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 6 of 37	Abracon Drawing #453568	Revision : A

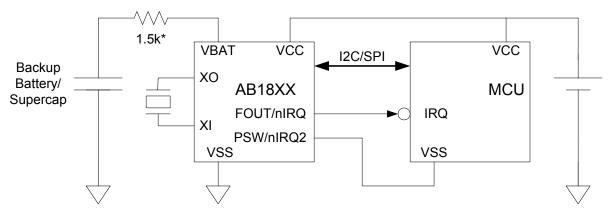
### 3.3 Reset Driven

In another implementation the AB18XX controls the system MCU using the reset function rather than switching power. Since many MCUs use much less power when reset, this implementation can save system power in some cases.



## 3.4 Battery Backup

In many systems the main power supply is a battery, so the AB18XX can minimize its current draw by powering down the MCU and other peripherals. This battery may be replaceable, and a supercapacitor charged via the AB18XX trickle charger can maintain system time and key parameters when the main battery is removed.



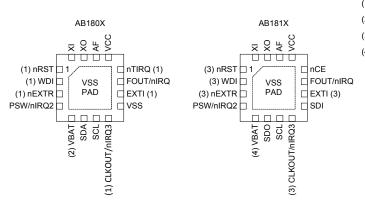
\* Total battery series impedance = 1.5k ohms, which may require an external resistor

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 7 of 37	Abracon Drawing #453568	Revision : A

## 4. Package Pins

## 4.1 Pin Configuration and Connections

Figure 2 and Table 2 show the QFN-16 pin configurations for the AB18XX parts. Pins labeled NC must be left unconnected. The thermal pad, pin 17, on the QFN-16 packages must be connected to VSS.



<sup>(1)</sup> Available in AB1804 and AB1805 only, else NC
 <sup>(2)</sup> Available in AB1803 and AB1805 only, else VSS
 <sup>(3)</sup> Available in AB1814 and AB1815 only, else NC
 <sup>(4)</sup> Available in AB1813 and AB1815 only, else VSS

### Figure 2. Pin Configuration Diagram

#### **Table 2: Pin Connections**

Pin Name	Pin		Function									
Fiirindiile	Туре	Function	01	03	04	05	11	13	14	15		
VSS	Power	Ground	5,9,17	9,17	5,9,17	9,17	5,17	17	5,17	17		
VCC	Power	System power supply	13	13	13	13	13	13	13	13		
XI	XT	Crystal input	16	16	16	16	16	16	16	16		
хо	XT	Crystal output	15	15	15	15	15	15	15	15		
AF	Output	Autocalibration filter	14	14	14	14	14	14	14	14		
VBAT	Power	Battery power supply		5		5		5		5		
SCL	Input	I <sup>2</sup> C or SPI interface clock	7	7	7	7	7	7	7	7		
SDO	Output	SPI data output					6	6	6	6		
SDI	Input	SPI data input					9	9	9	9		
nCE	Input	SPI chip select					12	12	12	12		
SDA	Input	I <sup>2</sup> C data input/output	6	6	6	6						
EXTI	Input	External interrupt input			10	10			10	10		
WDI	Input	Watchdog reset input			2	2			2	2		
nEXTR	Input	External reset input			3	3			3	3		
FOUT/nIRQ	Output	Int 1/function output	11	11	11	11	11	11	11	11		
nIRQ2	Output	Int 2 output	4	4	4	4	4	4	4	4		

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 8 of 37	Abracon Drawing #453568	Revision : A

#### **Table 2: Pin Connections**

Pin Name	Pin	Function			Pir	n Numbe	r in AB18	XX		
	Туре	i dilotori	01	03	04	05	11	13	14	15
CLKOUT/nIRQ3	Output	Int 3/clock output			8	8			8	8
nTIRQ	Output	Timer interrupt output			12	12				
nRST	Output	Reset output			1	1			1	1

## 4.2 Pin Descriptions

Table 3 provides a description of the pin connections.

#### Table 3: Pin Descriptions

Pin Name	Description
VSS	Ground connection. In the QFN-16 packages the ground slug on the bottom of the package must be connected to VSS.
VCC	Primary power connection. If a single power supply is used, it must be connected to VCC.
VBAT	Battery backup power connection. If a backup battery is not present, VBAT is normally left floating or grounded, but it may also be used to provide the analog input to the internal comparator (see Analog-Comparator).
XI	Crystal oscillator input connection.
ХО	Crystal oscillator output connection.
AF	Autocalibration filter connection. A 47pF ceramic capacitor should be placed between this pin and VSS for improved Autocalibration mode timing accuracy.
SCL	I/O interface clock connection. It provides the SCL input in both I <sup>2</sup> C and SPI interface parts.
SDA (only available in I <sup>2</sup> C environments)	I/O interface I <sup>2</sup> C data connection.
SDO (only available in SPI environments)	I/O interface SPI data output connection.
SDI	I/O interface SPI data input connection.
nCE (only available in SPI environments)	I/O interface SPI chip select input connection. It is an active low signal. A pull-up resistor is recom- mended to be connected to this pin to ensure it is not floating. A pull-up resistor also prevents inadver- tent writes to the RTC during power transitions.
EXTI	External interrupt input connection. It may be used to generate an External 1 interrupt with polarity selected by the EX1P bit if enabled by the EX1E bit. The value of the EXTI pin may be read in the EXIN register bit. This pin does not have an internal pull resistor. It must not be left floating or the RTC may consume higher current.
WDI	Watchdog Timer reset input connection. It may also be used to generate an External 2 interrupt with polarity selected by the EX2P bit if enabled by the EX2E bit. The value of the WDI pin may be read in the WDIN register bit. This pin does not have an internal pull resistor. It must not be left floating or the RTC may consume higher current.
nEXTR	External reset input connection. If nEXTR is low and the RS1E bit is set, the nRST output will be driven to its asserted value as determined by the RSP bit. This pin does not have an internal pull resistor. It must not be left floating or the RTC may consume higher current.

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 9 of 37	Abracon Drawing #453568	Revision : A

### Table 3: Pin Descriptions

Pin Name	Description
	Primary interrupt output connection. FOUT/nIRQ may be configured to generate several signals as a function of the OUT1S field(see 0x11 - Control2). FOUT/nIRQ is also asserted low on a power up until the AB18XX has exited the reset state and is accessible via the I/O interface.
FOUT/nIRQ	<ol> <li>FOUT/nIRQ can drive the value of the OUT bit.</li> <li>FOUT/nIRQ can drive the inverse of the combined interrupt signal IRQ (see Interrupts).</li> <li>FOUT/nIRQ can drive the square wave output (see 0x13 - SQW) if enabled by SQWE.</li> <li>FOUT/nIRQ can drive the inverse of the alarm interrupt signal AIRQ (see Interrupts).</li> </ol>
	Secondary interrupt output connection. It is an open drain output. PSW/nIRQ2 may be configured to generate several signals as a function of the OUT2S field (see 0x11 - Control2). This pin will be configured as an ~1 $\Omega$ switch if the PWR2 bit is set.
PSW/nIRQ2	<ol> <li>PSW/nIRQ2 can drive the value of the OUTB bit.</li> <li>PSW/nIRQ2 can drive the square wave output (see 0x13 - SQW) if enabled by SQWE.</li> <li>PSW/nIRQ2 can drive the inverse of the combined interrupt signal IRQ(see Interrupts).</li> <li>PSW/nIRQ2 can drive the inverse of the alarm interrupt signal AIRQ(see Interrupts).</li> <li>PSW/nIRQ2 can drive either sense of the timer interrupt signal TIRQ.</li> <li>PSW/nIRQ2 can function as the power switch output for controlling the power of external devices (see Sleep Control).</li> </ol>
nTIRQ (only available in I <sup>2</sup> C environments)	Timer interrupt output connection. It is an open drain output. nTIRQ always drives the active low nTIRQ signal.
CLKOUT/nIRQ3	<ul> <li>Square Wave output connection. It is a push-pull output, and may be configured to generate one of two signals.</li> <li>1. CLKOUT/nIRQ3 can drive the value of the OUT bit.</li> <li>2. CLKOUT/nIRQ3 can drive the square wave output (see 0x13 - SQW) if enabled by SQWE.</li> </ul>
nRST	External reset output connection. It is an open drain output. The polarity is selected by the RSP bit, which will initialize to 0 on power up to produce an active low output. See Autocalibration Fail Interrupt ACIRQ for details of the generation of nRST.

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 10 of 37	Abracon Drawing #453568	Revision : A

# 5. Electrical Specifications

## 5.1 Absolute Maximum Ratings

Table 4 lists the absolute maximum ratings.

Table 4:	Absolute	Maximum	Ratings

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>CC</sub>	System Power Voltage		-0.3		3.8	V
V <sub>BAT</sub>	Battery Voltage		-0.3		3.8	V
VI	Input voltage	VCC Power state	-0.3		V <sub>CC</sub> + 0.3	V
VI	Input voltage	VBAT Power state	-0.3		V <sub>BAT</sub> + 0.3	V
V <sub>O</sub>	Output voltage	VCC Power state	-0.3		V <sub>CC</sub> + 0.3	V
V <sub>O</sub>	Output voltage	VBAT Power state	-0.3		V <sub>BAT</sub> + 0.3	V
I <sub>I</sub>	Input current		-10		10	mA
I <sub>O</sub>	Output current		-20		20	mA
I <sub>OPC</sub>	PSW Output continuous current				50	mA
I <sub>OPP</sub>	PSW Output pulsed current	1 second pulse			150	mA
V		CDM			±500	V
V <sub>ESD</sub>	ESD Voltage	НВМ			±4000	V
I <sub>LU</sub>	Latch-up Current				100	mA
T <sub>STG</sub>	Storage Temperature		-55		125	°C
T <sub>OP</sub>	Operating Temperature		-40		85	°C
T <sub>SLD</sub>	Lead temperature	Hand soldering for 10 seconds			300	°C
T <sub>REF</sub>	Reflow soldering temperature	Reflow profile per JEDEC J- STD-020D			260	°C

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 11 of 37	Abracon Drawing #453568	Revision : A

### 5.2 Power Supply Parameters

Figure 3 and Table 5 describe the power supply and switchover parameters. See Power Control and Switching for a detailed description of the operations.

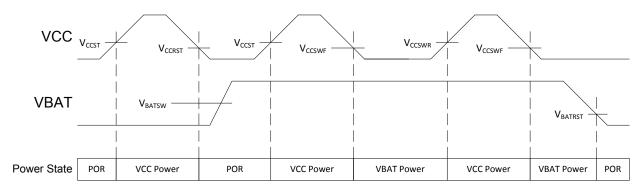


Figure 3. Power Supply Switchover

For Table 5,  $T_A = -40$  °C to 85 °C, TYP values at 25 °C.

SYMBO L	PARAMETER	PWR	TYPE	POWER STATE	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
V <sub>CC</sub>	System Power Voltage	VCC	Static	VCC Power	Clocks operating and RAM and registers retained	1.5		3.6	v
V <sub>CCIO</sub>	VCC I/O Interface Voltage	vcc	Static	VCC Power	I <sup>2</sup> C or SPI opera- tion	1.5		3.6	V
V <sub>CCST</sub>	VCC Start-up Voltage <sup>(1)</sup>	VCC	Rising	POR -> V <sub>CC</sub> Power		1.6			V
V <sub>CCRST</sub>	VCC Reset Voltage	VCC	Falling	VCC Power -> POR	$V_{BAT} < V_{BAT,MIN}$ or no $V_{BAT}$		1.3	1.5	V
V <sub>CCSWR</sub>	VCC Rising Switch-over Threshold Voltage	VCC	Rising	VBAT Power -> VCC Power	V <sub>BAT</sub> ≥ V <sub>BATRST</sub>		1.6	1.7	V
V <sub>CCSWF</sub>	VCC Falling Switch-over Threshold Voltage	vcc	Falling	VCC Power -> VBAT Power	V <sub>BAT</sub> ≥ V <sub>BATSW,MIN</sub>	1.2	1.5		V
V <sub>CCSWH</sub>	VCC Switchover Thresh- old Hysteresis <sup>(2)</sup>	vcc	Hyst.	VCC Power <-> VBAT Power			70		mV
V <sub>CCFS</sub>	VCC Falling Slew Rate to switch to VBAT state <sup>(4)</sup>	vcc	Falling	VCC Power -> VBAT Power	V <sub>CC</sub> < V <sub>CCSW,MAX</sub>	0.7	1.4		V/ms
V <sub>BAT</sub>	Battery Voltage	VBAT	Static	VBAT Power	Clocks operating and RAM and reg- isters retained	1.4		3.6	v
V <sub>BATSW</sub>	Battery Switchover Volt- age Range <sup>(5)</sup>	VBAT	Static	VCC Power -> VBAT Power		1.6		3.6	V

#### **Table 5: Power Supply and Switchover Parameters**

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 12 of 37	Abracon Drawing #453568	Revision : A

#### **Table 5: Power Supply and Switchover Parameters**

SYMBO L	PARAMETER	PWR	TYPE	POWER STATE	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>BATRST</sub>	Falling Battery POR Volt- age <sup>(7)</sup>	VBAT	Falling	VBAT Power -> POR	V <sub>CC</sub> < V <sub>CCSWF</sub>		1.1	1.4	V
V <sub>BMRG</sub>	$V_{BAT}$ Margin above $V_{CC}^{(3)}$	VBAT	Static	V <sub>BAT</sub> Power		200			mV
V <sub>BATESR</sub>	$V_{\text{BAT}}$ supply series resistance^{(6)}	VBAT	Static	V <sub>BAT</sub> Power		1.0	1.5		kΩ

 $^{(1)}V_{CC}$  must be above  $V_{CCST}$  to exit the POR state, independent of the  $V_{BAT}$  voltage.

 $^{(2)}\mbox{Difference}$  between  $V_{\mbox{CCSWR}}$  and  $V_{\mbox{CCSWF}}$ 

 $^{(3)}V_{BAT}$  must be higher than V<sub>CC</sub> by at least this voltage to ensure the AB18XX remains in the VBAT Power state.

<sup>(4)</sup> Maximum VCC falling slew rate to guarantee correct switchover to VBAT Power state. There is no V<sub>CC</sub> falling slew rate requirement if switching to the VBAT power source is not required.

 $^{(5)}V_{BAT}$  voltage to guarantee correct transition to VBAT Power state when V<sub>CC</sub> falls.

<sup>(6)</sup> Total series resistance of the power source attached to the VBAT pin. The optimal value is  $1.5k\Omega$ , which may require an external resistor. VBAT power source ESR + external resistor value =  $1.5k\Omega$ .

 $^{(7)}V_{BATRST}$  is also the static voltage required on  $V_{BAT}$  for register data retention.

### 5.3 Operating Parameters

Table 6 lists the operating parameters.

For Table 6,  $T_A = -40$  °C to 85 °C, TYP values at 25 °C.

SYMBOL	PARAMETER	TEST CONDITIONS	V <sub>CC</sub>	MIN	ТҮР	МАХ	UNIT
V <sub>T+</sub>	Positive-going Input Thresh-		3.0V		1.5	2.0	V
• [+	old Voltage		1.8V		1.1	1.25	v
V_	V <sub>T-</sub> Negative-going Input Thresh- old Voltage		3.0V	0.8	0.9		V
v 1-			1.8V	0.5	0.6		v
I <sub>ILEAK</sub>	Input leakage current		3.0V		0.02	80	nA
Cl	Input capacitance				3		pF
V <sub>OH</sub>	High level output voltage on push-pull outputs		1.7V – 3.6V	0.8•V <sub>CC</sub>			V
V <sub>OL</sub>	Low level output voltage		1.7V – 3.6V			0.2•V <sub>CC</sub>	V
			1.7V	-2	-3.8		
I <sub>OH</sub>	High level output current on	V <sub>OH</sub> = 0.8●V <sub>CC</sub>	1.8V	-3	-4.3		~ ^
	push-pull outputs	•OH - 0.0● •CC	3.0V	-7	-11		mA
			3.6V	-8.8	-15		

 Table 6: Operating Parameters

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 13 of 37	Abracon Drawing #453568	Revision : A

### Table 6: Operating Parameters

SYMBOL	PARAMETER	TEST CONDITIONS	$v_{cc}$	MIN	ТҮР	МАХ	UNIT
			1.7V	3.3	5.9		
	Low level output current	$V_{OL} = 0.2 \bullet V_{CC}$	1.8V	6.1	6.9		mA
I <sub>OL</sub> Low level out		VOL - 0.2 VCC	3.0V	17	19		
			3.6V	18	20		
			1.7V		1.7	5.8	
D	PSW output resistance to	DSW Enchlad	1.8V		1.6	5.4	Ω
R <sub>DSON</sub>	VSS	PSW Enabled	3.0V		1.1	3.8	Ω
			3.6V		1.05	3.7	
I <sub>OLEAK</sub>	Output leakage current				0.02	80	nA

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 14 of 37	Abracon Drawing #453568	Revision : A

#### 5.4 Oscillator Parameters

Table 7 lists the oscillator parameters.

For Table 7,  $T_A = -40$  °C to 85 °C unless otherwise indicated.  $V_{CC} = 1.7$  to 3.6V, TYP values at 25 °C and 3.0V.

#### Table 7: Oscillator Parameters

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
F <sub>XT</sub>	XI and XO pin Crystal Fre- quency			32.768		kHz
F <sub>OF</sub>	XT Oscillator failure detection frequency			8		kHz
C <sub>INX</sub>	Internal XI and XO pin capac- itance			1		pF
C <sub>EX</sub>	External XI and XO pin PCB capacitance			1		pF
OA <sub>XT</sub>	XT Oscillation Allowance	At 25°C using a 32.768 kHz crystal	270	320		kΩ
F <sub>RCC</sub>	Calibrated RC Oscillator Fre- quency <sup>(1)</sup>	Factory Calibrated at 25°C, VCC = 2.8V		128		Hz
F <sub>RCU</sub>	Uncalibrated RC Oscillator Frequency	Calibration Disabled (OFF- SETR = 0)	89	122	220	Hz
	RC Oscillator cycle-to-cycle	Calibration Disabled (OFF- SETR = 0) – 128 Hz		2000		
J <sub>RCCC</sub>	jitter	Calibration Disabled (OFF- SETR = 0) – 1 Hz		500		ppm
A <sub>XT</sub>	XT mode digital calibration accuracy <sup>(1)</sup>	Calibrated at an initial tem- perature and voltage	-2		2	ppm
		24 hour run time		35		
A <sub>AC</sub>	Autocalibration mode timing accuracy, 512 second period,	1 week run time		20		ppm
	$T_{A} = -10^{\circ}C \text{ to } 60^{\circ}C^{(1)}$	1 month run time		10		
		1 year run time		3		
T <sub>AC</sub>	Autocalibration mode operat- ing temperature <sup>(2)</sup>		-10		60	°C

(1) Timing accuracy is specified at 25°C after digital calibration of the internal RC oscillator and 32.768 kHz crystal. A typical 32.768 kHz tuning fork crystal has a negative temperature coefficient with a parabolic frequency deviation, which can result in a change of up to 150 ppm across the entire operating temperature range of -40°C to 85°C in XT mode. Autocal-ibration mode timing accuracy is specified relative to XT mode timing accuracy from -10°C to 60°C.

<sup>(2)</sup> Outside of this temperature range, the RC oscillator frequency change due to temperature may be outside of the allowable RC digital calibration range (+/-12%) for autocalibration mode. When this happens, an autocalibration failure will occur and the ACF interrupt flag is set. The AB18XX should be switched to use the XT oscillator as its clock source when this occurs. Please see the Autocalibration Fail section for more details.

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant		
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive		
Page 15 of 37	Abracon Drawing #453568	Revision : A		

Figure 4 shows the typical calibrated RC oscillator frequency variation vs. temperature. RC oscillator calibrated at 2.8V, 25°C.

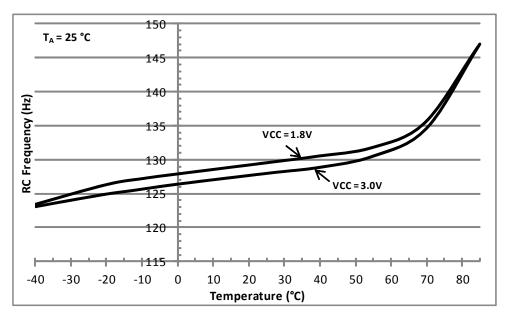


Figure 4. Calibrated RC Oscillator Typical Frequency Variation vs. Temperature

Figure 5 shows the typical uncalibrated RC oscillator frequency variation vs. temperature.

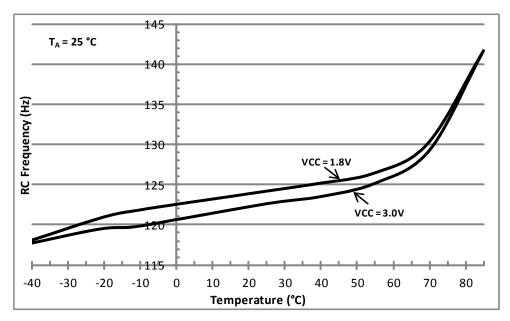


Figure 5. Uncalibrated RC Oscillator Typical Frequency Variation vs. Temperature

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant		
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive		
Page 16 of 37	Abracon Drawing #453568	Revision : A		

### 5.5 V<sub>CC</sub> Supply Current

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Table 8 lists the current supplied into the VCC power input under various conditions.

Ŕ	For Table 8, $T_A = -40$ °C to 85 °C, VBAT = 0 V to 3.6 V
B	TYP values at 25 °C, MAX values at 85 °C, VCC Power state

SYMBOL	PARAMETER	TEST CONDITIONS	VCC	MIN	ТҮР	MAX	UNIT
IVCC:12C	V <sub>CC</sub> supply current during I <sup>2</sup> C	400kHz bus speed, 2.2k pull-up	3.0V		6	10	μA
1000:120	burst read/write	resistors on SCL/SDA <sup>(1)</sup>	1.8V		1.5	3	μΛ
has some	V <sub>CC</sub> supply current during SPI	2 MHz bus speed <sup>(2)</sup>	3.0V		8	12	μA
IVCC:SPIW	burst write		1.8V		4	6	μΑ
	V <sub>CC</sub> supply current during SPI	2 Mile hus speed (2)	3.0V		23	37	
IVCC:SPIR	burst read	2 MHz bus speed <sup>(2)</sup>	1.8V		13	21	μA
I <sub>VCC:XT</sub>	V <sub>CC</sub> supply current in XT oscil-	Time keeping mode with XT	h XT 3.0V	55	330	nA	
	lator mode	oscillator running <sup>(3)</sup>	1.8V		51	290	
	V <sub>CC</sub> supply current in RC oscil-	Time keeping mode with only the RC oscillator running (XT oscillator is off) <sup>(3)</sup>	3.0V		14	220	nA
IVCC:RC	lator mode		1.8V		11	170	
Average V	Average V <sub>CC</sub> supply current in	Time keeping mode with only	3.0V		22	235	
I <sub>VCC:ACAL</sub>	Autocalibrated RC oscillator mode	RC oscillator running and Auto- calibration enabled. ACP = 512 seconds <sup>(3)</sup>	1.8V		18	190	nA
I <sub>VCC:CK32</sub>	Additional V <sub>CC</sub> supply current		3.0V		3.6	8	_
	with CLKOUT at 32.786 kHz		1.8V		2.2	5	μA
IVCC:CK128	Additional V <sub>CC</sub> supply current	All time keeping modes, 128 Hz square wave on CLKOUT <sup>(4)</sup>	3.0V		7	35	nA
·VUU.UK128	with CLKOUT at 128 Hz		1.8V		2.5	20	

#### Table 8: V<sub>CC</sub> Supply Current

<sup>(1)</sup> Excluding external peripherals and pull-up resistor current. All other inputs (besides SDA and SCL) are at 0V or V<sub>CC</sub>. AB180X only. Test conditions: Continuous burst read/write, 0x55 data pattern, 25 μs between each data byte, 20 pF load on each bus pin.

<sup>(2)</sup> Excluding external peripheral current. All other inputs (besides SDI, nCE and SCL) are at 0V or V<sub>CC</sub>. AB181X only. Test conditions: Continuous burst write, 0x55 data pattern, 25 μs between each data byte, 20 pF load on each bus pin.

 $^{(3)}\mbox{All}$  inputs and outputs are at 0 V or  $\mbox{V}_{\mbox{CC}}.$ 

 $^{(4)}\mbox{All}$  inputs and outputs except CLKOUT are at 0 V or V $_{CC}$ . 15 pF capacitive load on CLKOUT.

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant		
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive		
Page 17 of 37	Abracon Drawing #453568	Revision : A		

Figure 6 shows the typical VCC power state operating current vs. temperature in XT mode.

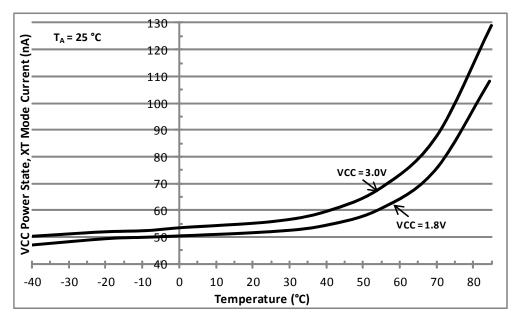


Figure 6. Typical VCC Current vs. Temperature in XT Mode

Figure 7 shows the typical VCC power state operating current vs. temperature in RC mode.

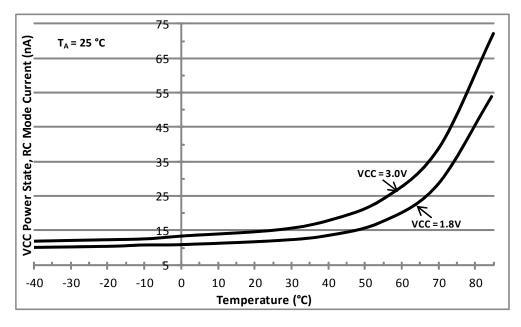


Figure 7. Typical VCC Current vs. Temperature in RC Mode

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant		
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive		
Page 18 of 37	Abracon Drawing #453568	Revision : A		

Figure 8 shows the typical VCC power state operating current vs. temperature in RC Autocalibration mode.

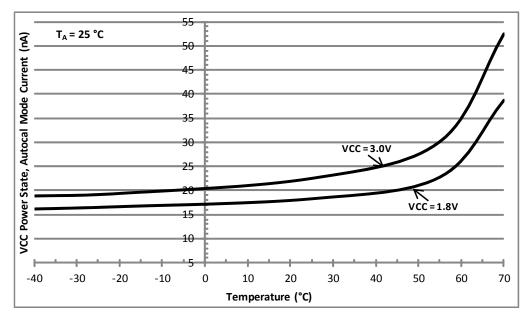


Figure 8. Typical VCC Current vs. Temperature in RC Autocalibration Mode

Figure 9 shows the typical VCC power state operating current vs. voltage for XT Oscillator and RC Oscillator modes and the average current in RC Autocalibrated mode.

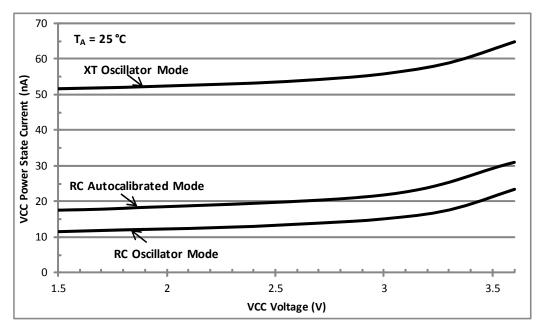


Figure 9. Typical VCC Current vs. Voltage, Different Modes of Operation

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant		
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive		
Page 19 of 37	Abracon Drawing #453568	Revision : A		

Figure 10 shows the typical VCC power state operating current during continuous I<sup>2</sup>C and SPI burst read and write activity. Test conditions:  $T_A = 25$  °C, 0x55 data pattern, 25 µs between each data byte, 20 pF load on each bus pin, pull-up resistor current not included.

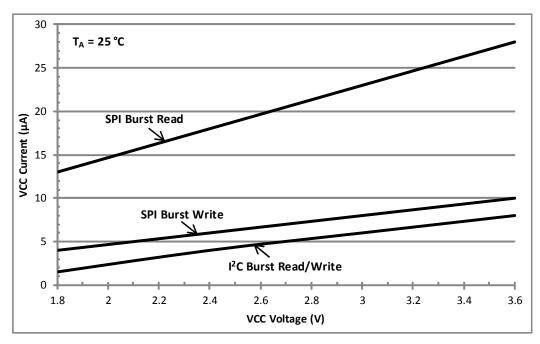


Figure 10. Typical VCC Current vs. Voltage, I<sup>2</sup>C and SPI Burst Read/Write

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant		
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive		
Page 20 of 37	Abracon Drawing #453568	Revision : A		

Figure 11 shows the typical VCC power state operating current with a 32.768 kHz clock output on the CLKOUT pin. Test conditions:  $T_A = 25$  °C, All inputs and outputs except CLKOUT are at 0 V or VCC. 15 pF capacitive load on the CLKOUT pin.

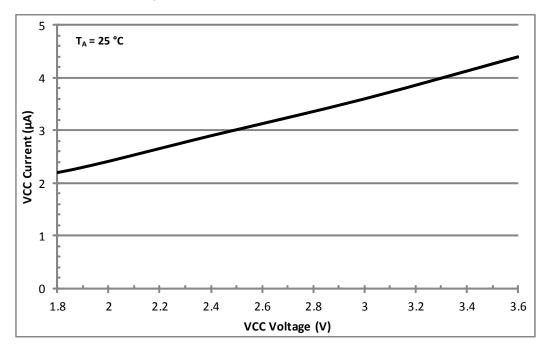


Figure 11. Typical VCC Current vs. Voltage, 32.768 kHz Clock Output

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant			
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive			
Page 21 of 37	Abracon Drawing #453568	Revision : A			

### 5.6 VBAT Supply Current

Table 9 lists the current supplied into the VBAT power input under various conditions.

For Table 9,  $T_A = -40$  °C to 85 °C, TYP values at 25 °C, MAX values at 85 °C,  $V_{BAT}$  Power state.

	TEST CONDITIONS	V <sub>CC</sub>	V <sub>BAT</sub>	MIN	TYP	MAX	UNIT
VBAT supply current in	Time keeping mode with	< Voonur	3.0V		56	330	nA
XT oscillator mode	XT oscillator running <sup>(1)</sup>	* * CCSWF	1.8V		52	290	
I <sub>VBAT:RC</sub> VBAT supply current in RC oscillator mode	Time keeping mode with		3.0V		16	220	
	ning (XT oscillator is off) <sup>(1)</sup>	< V <sub>CCSWF</sub>	1.8V		12	170	nA
AverageVBATsupplycurrent in AutocalibratedTime keeping mode with the RC oscillator running. Autocalibration enabled. ACP = 512 seconds <sup>(1)</sup>	Time keeping mode with		3.0V		24	235	
	< V <sub>CCSWF</sub>	1.8V		20	190	nA	
VBAT supply current in	) (	17 36V	3.0V	-5	0.6	20	nA
VBAT:VCC VCC powered mode V <sub>CC</sub> powered n		1.7 - 3.0 V	1.8V	-10	0.5	16	
	(T oscillator mode /BAT supply current in RC oscillator mode Average VBAT supply surrent in Autocalibrated RC oscillator mode /BAT supply current in /CC powered mode	(T oscillator modeXT oscillator running(1)(BAT supply current in RC oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator is off)(1)werage VBAT supply surrent in Autocalibrated RC oscillator modeTime keeping mode with the RC oscillator running. Autocalibration enabled. ACP = 512 seconds(1)//BAT supply current in //BAT supply current inVer powered mode(1)	CT oscillator modeXT oscillator running <sup>(1)</sup> $< V_{CCSWF}$ //BAT supply current in RC oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator is off) <sup>(1)</sup> $< V_{CCSWF}$ //Werage VBAT supply surrent in Autocalibrated RC oscillator modeTime keeping mode with the RC oscillator running. Autocalibration enabled. ACP = 512 seconds <sup>(1)</sup> $< V_{CCSWF}$ //BAT supply current in //CC powered mode $V_{CC}$ powered mode <sup>(1)</sup> $1.7 - 3.6 V$	AT supply current in CT oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator run- ning (XT oscillator is off)^{(1)} $< V_{CCSWF}$ $1.8V$ /BAT supply current in RC oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator is off)^{(1)} $< V_{CCSWF}$ $3.0V$ /Werage VBAT supply current in Autocalibrated RC oscillator modeTime keeping mode with the RC oscillator running. Autocalibration enabled. ACP = 512 seconds^{(1)} $< V_{CCSWF}$ $3.0V$ /BAT supply current in /CC powered mode $V_{CC}$ powered mode $1.7 - 3.6 V$ $3.0V$	AT supply current in CT oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator is off)^{(1)} $< V_{CCSWF}$ $1.8V$ /BAT supply current in RC oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator is off)^{(1)} $< V_{CCSWF}$ $3.0V$ /Werage VBAT supply current in Autocalibrated RC oscillator modeTime keeping mode with the RC oscillator running. Autocalibration enabled. ACP = 512 seconds^{(1)} $< V_{CCSWF}$ $3.0V$ /BAT supply current in /CC powered mode $V_{CC}$ powered mode $1.7 - 3.6 V$ $3.0V$ $-5$	Ar supply current in CT oscillator modeTime kceping mode with only the RC oscillator run- ning (XT oscillator is off)^{(1)} $< V_{CCSWF}$ $1.8V$ $52$ /BAT supply current in RC oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator is off)^{(1)} $< V_{CCSWF}$ $3.0V$ $16$ werage VBAT supply current in Autocalibrated RC oscillator modeTime keeping mode with the RC oscillator running. Autocalibration enabled. ACP = 512 seconds^{(1)} $< V_{CCSWF}$ $3.0V$ $24$ /BAT supply current in /CC powered mode $V_{CC}$ powered mode $1.7 - 3.6 V$ $3.0V$ $-5$ $0.6$	AT supply current in CT oscillator modeTime keeping mode with only the RC oscillator running $< V_{CCSWF}$ $1.8V$ $52$ $290$ /BAT supply current in RC oscillator modeTime keeping mode with only the RC oscillator run- ning (XT oscillator is off) $< V_{CCSWF}$ $3.0V$ $16$ $220$ /BAT supply current in Average VBAT supply current in Autocalibrated RC oscillator modeTime keeping mode with the RC oscillator running. Autocalibration enabled. ACP = 512 seconds $< V_{CCSWF}$ $3.0V$ $24$ $235$ /BAT supply current in /CC powered mode $V_{CC}$ powered mode $< V_{CCSWF}$ $3.0V$ $20$ $190$

Table 9: V<sub>BAT</sub> Supply Current

Figure 12 shows the typical VBAT power state operating current vs. temperature in XT mode.

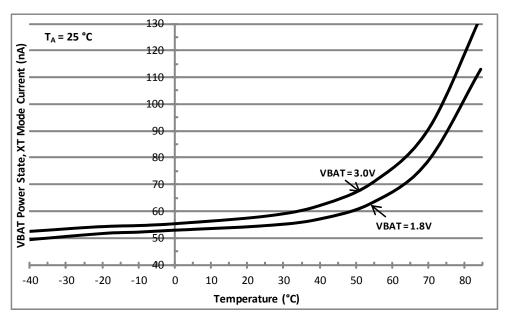


Figure 12. Typical VBAT Current vs. Temperature in XT Mode

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant		
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive		
Page 22 of 37	Abracon Drawing #453568	Revision : A		

Figure 13 shows the typical VBAT power state operating current vs. temperature in RC mode.

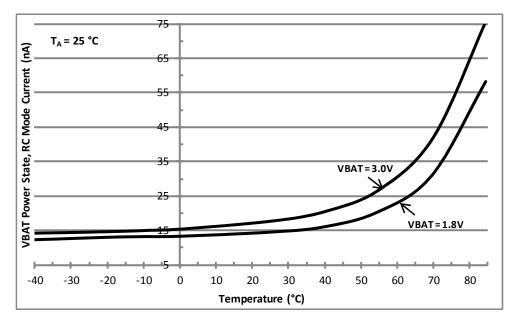


Figure 13. Typical VBAT Current vs. Temperature in RC Mode

Figure 14 shows the typical VBAT power state operating current vs. temperature in RC Autocalibration mode.

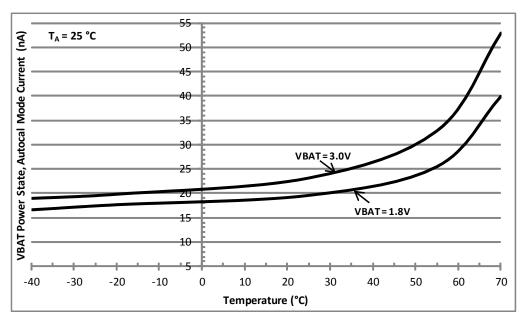


Figure 14. Typical VBAT Current vs. Temperature in RC Autocalibration Mode

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 23 of 37	Abracon Drawing #453568	Revision : A

Figure 15 shows the typical VBAT power state operating current vs. voltage for XT Oscillator and RC Oscillator modes and the average current in RC Autocalibrated mode, VCC = 0 V.

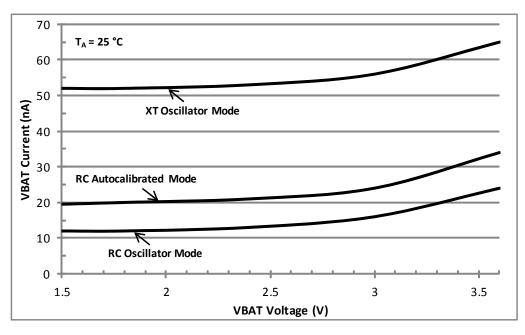


Figure 15. Typical VBAT Current vs. Voltage, Different Modes of Operation

Figure 16 shows the typical VBAT current when operating in the VCC power state, VCC = 1.7 V.

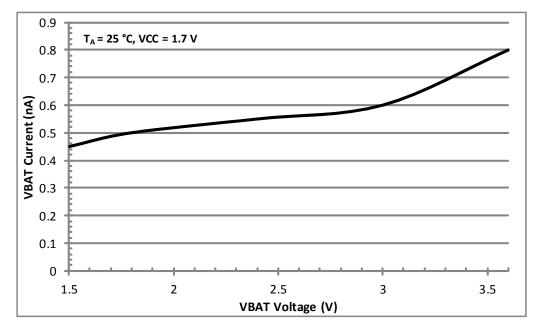


Figure 16. Typical VBAT Current vs. Voltage in VCC Power State

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 24 of 37	Abracon Drawing #453568	Revision : A

### 5.7 BREF Electrical Characteristics

Table 10 lists the parameters of the VBAT voltage thresholds. BREF values other than those listed in the table are not supported.

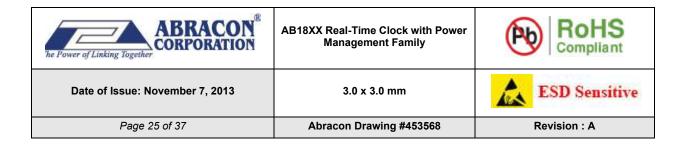
For Table 10,  $T_A$  = -20 °C to 70 °C, TYP values at 25 °C, VCC = 1.7 to 3.6V.

SYMBOL	PARAMETER	BREF	MIN	ТҮР	MAX	UNIT
		0111	2.3	2.5	3.3	
V <sub>BRF</sub>	VPAT falling throshold	1011	1.9	2.1	2.8	v
VBRF	VBAT falling threshold	1101	1.6	1.8	2.5	v
		1111		1.4		
	VBAT rising threshold	0111	2.6	3.0	3.4	v
V <sub>BRR</sub>		1011	2.1	2.5	2.9	
*BRR		1101	1.9	2.2	2.7	
		1111		1.6		
		0111		0.5		
V <sub>BRH</sub>	VPAT throshold hystoresis	1011		0.4		V
VBRH	VBAT threshold hysteresis	1101		0.4		v
		1111		0.2		
T <sub>BR</sub>	VBAT analog comparator recom- mended operating temperature range	All values	-20		70	°C

Table 10: BREF Parameters

## 5.8 I<sup>2</sup>C AC Electrical Characteristics

Figure 17 and Table 11 describe the  $I^2C$  AC electrical parameters.



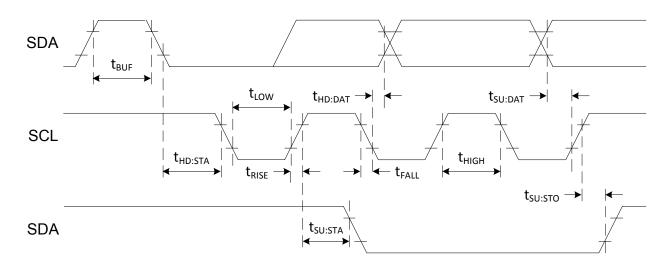


Figure 17. I<sup>2</sup>C AC Parameter Definitions

0	For Table 11, $T_A = -4$	0 °C to 85 °C,	TYP values at 25 °C.
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SYMBOL	PARAMETER	vcc	MIN	ТҮР	MAX	UNIT
f <sub>SCL</sub>	SCL input clock frequency	1.7V-3.6V	10		400	kHz
t <sub>LOW</sub>	Low period of SCL clock	1.7V-3.6V	1.3			μs
t <sub>HIGH</sub>	High period of SCL clock	1.7V-3.6V	600			ns
t <sub>RISE</sub>	Rise time of SDA and SCL	1.7V-3.6V			300	ns
t <sub>FALL</sub>	Fall time of SDA and SCL	1.7V-3.6V			300	ns
t <sub>HD:STA</sub>	START condition hold time	1.7V-3.6V	600			ns
t <sub>SU:STA</sub>	START condition setup time	1.7V-3.6V	600			ns
t <sub>SU:DAT</sub>	SDA setup time	1.7V-3.6V	100			ns
t <sub>HD:DAT</sub>	SDA hold time	1.7V-3.6V	0			ns
t <sub>SU:STO</sub>	STOP condition setup time	1.7V-3.6V	600			ns
t <sub>BUF</sub>	Bus free time before a new transmission	1.7V-3.6V	1.3			μs

## Table 11: I<sup>2</sup>C AC Electrical Parameters

## 5.9 SPI AC Electrical Characteristics

Figure 18, Figure 19, and Table 12 describe the SPI AC electrical parameters.

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 26 of 37	Abracon Drawing #453568	Revision : A

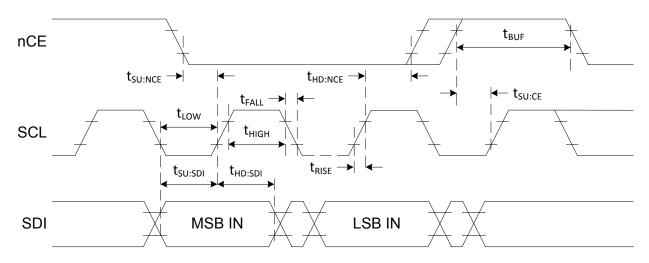
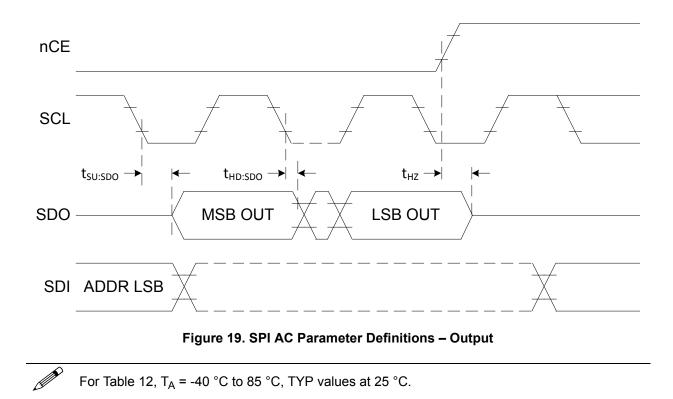


Figure 18. SPI AC Parameter Definitions – Input



The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 27 of 37	Abracon Drawing #453568	Revision : A

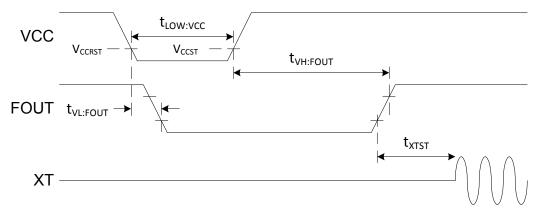
### Table 12: SPI AC Electrical Parameters

SYMBOL	PARAMETER	VCC	MIN	ТҮР	MAX	UNIT
f <sub>SCL</sub>	SCL input clock frequency	1.7V–3.6V	0.01		2	MHz
t <sub>LOW</sub>	Low period of SCL clock	1.7V–3.6V	200			ns
t <sub>HIGH</sub>	High period of SCL clock	1.7V–3.6V	200			ns
t <sub>RISE</sub>	Rise time of all signals	1.7V–3.6V			1	μs
t <sub>FALL</sub>	Fall time of all signals	1.7V–3.6V			1	μs
t <sub>SU:NCE</sub>	nCE low setup time to SCL	1.7V–3.6V	200			ns
t <sub>HD:NCE</sub>	nCE hold time to SCL	1.7V–3.6V	200			ns
t <sub>SU:CE</sub>	nCE high setup time to SCL	1.7V–3.6V	200			ns
t <sub>SU:SDI</sub>	SDI setup time	1.7V–3.6V	40			ns
t <sub>HD:SDI</sub>	SDI hold time	1.7V–3.6V	50			ns
t <sub>SU:SDO</sub>	SDO output delay from SCL	1.7V–3.6V			150	ns
t <sub>HD:SDO</sub>	SDO output hold from SCL	1.7V–3.6V	0			ns
t <sub>HZ</sub>	SDO output Hi-Z from nCE	1.7V–3.6V			250	ns
t <sub>BUF</sub>	nCE high time before a new transmission	1.7V-3.6V	200			ns

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 28 of 37	Abracon Drawing #453568	Revision : A

### 5.10 Power On AC Electrical Characteristics

Figure 20 and Table 13 describe the power on AC electrical characteristics for the FOUT pin and XT oscillator.



#### Figure 20. Power On AC Electrical Characteristics

For Table 13,  $T_A = -40$  °C to 85 °C, VBAT < 1.2 V

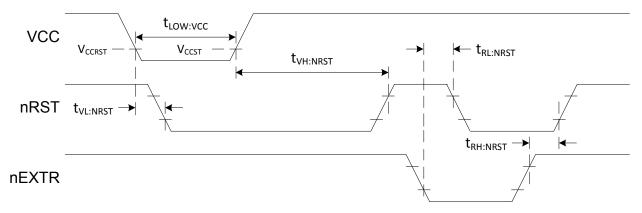
SYMBOL	PARAMETER	VCC	T <sub>A</sub>	MIN	ТҮР	MAX	UNIT
tLOW:VCC	Low period of VCC to oppure a valid POP		85 °C		0.1		
		1.7V–3.6V	25 °C		0.1		s
	Low period of VCC to ensure a valid POR	1.7 V-3.0V	-20 °C		1.5		5
			-40 °C		10		
			85 °C		0.1		
t <sub>VL:FOUT</sub> VCC low to FOUT low		1.7V–3.6V	25 °C		0.1		- S
		1.7 V-3.0V	-20 °C		1.5		
			-40 °C		10		
		1.7V–3.6V	85 °C		0.4		- S - S
t	VCC high to FOUT high		25 °C		0.5		
t <sub>vh:fout</sub>			-20 °C		3		
			-40 °C		20		
			85 °C		0.4		
t	EQUIT high to XT oppillator start	171/261/	25 °C		0.4		
t <sub>XTST</sub>	FOUT high to XT oscillator start	1.7V–3.6V	-20 °C		0.5		
			-40 °C		1.5		

#### Table 13: Power On AC Electrical Parameters

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 29 of 37	Abracon Drawing #453568	Revision : A

## 5.11 nRST AC Electrical Characteristics

Figure 21 and Table 14 describe the nRST and nEXTR AC electrical characteristics.



#### Figure 21. nRST AC Parameter Characteristics

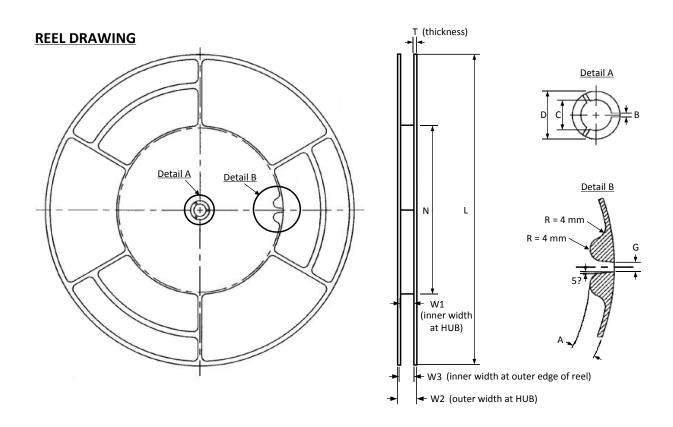
For Table 14,  $T_A = -40$  °C to 85 °C, TYP at 25 °C unless specified otherwise, VBAT < 1.2 V.

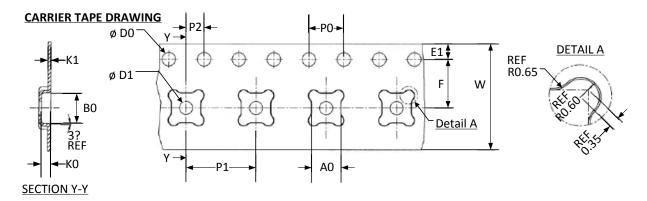
SYMBOL	PARAMETER	VCC	T <sub>A</sub>	MIN	ТҮР	MAX	UNIT		
			85 °C		0.1				
t <sub>LOW:VCC</sub>	Low period of VCC to ensure a	1.7V-3.6V	25 °C		0.1		s		
LOW:ACC	valid POR	1.7 - 5.0 -	-20 °C		1.5		5		
			-40 °C		10				
			85 °C		0.1				
tu NDOT	/L:NRST VCC low to nRST low 1.	1.7V-3.6V	25 °C		0.1		s		
VL:NRS1		1.7 - 5.0 -	-20 °C		1.5		3		
					-40 °C		10		
			85 °C		0.5				
t <sub>VH:NRST</sub>	VCC high to nRST high	VCC high to pRST high	VCC high to pPST high	1.7V-3.6V	25 °C		0.5		s
VH:NRS1	voo nigh to nixor nigh	1.7 0-0.00	-20 °C		3.5		3		
			-40 °C		25				
t <sub>RL:NRST</sub>	nEXTR low to nRST low	1.7V-3.6V	-40 °C to 85 °C		30	50	ns		
t <sub>RH:NRST</sub>	nEXTR high to nRST high	1.7V-3.6V	-40 °C to 85 °C		50	80	ns		

#### Table 14: nRST AC Electrical Parameters

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 30 of 37	Abracon Drawing #453568	Revision : A

# 6. Tape and Reel Information





The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 31 of 37	Abracon Drawing #453568	Revision : A

330 x 178 x 12 mm Reel Dimensions			3x3 QFN Carrier Tape Dimensions						
Symbol	MIN	ТҮР	MAX	Units	Symbol	MIN	ТҮР	MAX	Units
Т	2.3	2.5	2.7		B0	3.2	3.3	3.4	
Ν		178.0			K0	0.9	1.0	1.1	
L			330.0		K1	0.25	0.3	0.35	
W1	12.4	12.4	12.6		D0	1.50	1.55	1.60	
W2			18.4		D1	1.5			
W3	12.4		15.4		P0	3.9	4.0	4.1	
С	12.8	13.0	13.5	mm	P1	7.9	8.0	8.1	mm
D	20.2				P2	1.9	2.0	2.1	
А		10.0			A0	3.2	3.3	3.4	
G		4.0			E1	1.65	1.75	1.85	
В	1.5			1	F	5.4	5.5	5.6	
				1	W	11.7	12.0	12.3	

#### Table 15: Tape and Reel Dimensions

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 32 of 37	Abracon Drawing #453568	Revision : A

## 7. Reflow Profile

Figure 22 illustrates the reflow soldering requirements.

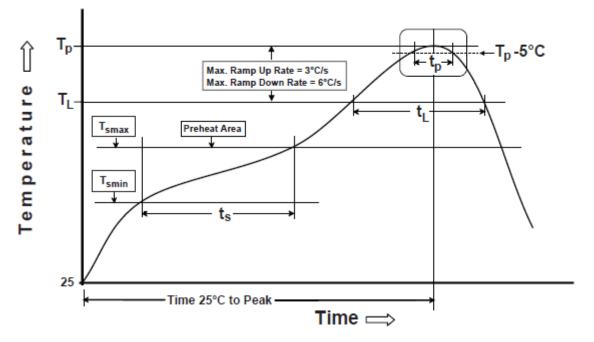


Figure 22.	Reflow	Soldering	Diagram
		•••••	

Profile Feature	Requirement
Preheat/Soak Temperature Min (T <sub>smin</sub> ) Temperature Max (T <sub>smax</sub> ) Time (ts) from (T <sub>smin</sub> to T <sub>smax</sub> )	150 °C 200 °C 60-120 seconds
Ramp-up rate (T <sub>L</sub> to Tp)	3 °C/second max.
Liquidous temperature (T <sub>L</sub> ) Time (t <sub>L</sub> ) maintained above T <sub>L</sub>	217 °C 60-150 seconds
Peak package body temperature (T <sub>p</sub> )	260 °C max.
Time ( $t_p$ ) within 5 °C of $T_p$	30 seconds max.
Ramp-down rate $(T_p \text{ to } T_L)$	6 °C/second max.
Time 25 °C to peak temperature	8 minutes max.

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 33 of 37	Abracon Drawing #453568	Revision : A

# 8. Ordering Information

### Table 17: Ordering Information

AB18XX O	rderable Part Numbers	Package	Temperature	MSL Level <sup>(2)</sup>	
P/N	Tape and Reel Qty	i ackage	Range		
AB1801-T3	3000pcs/reel				
AB1803-T3	3000pcs/reel				
AB1804-T3	3000pcs/reel			1	
AB1805-T3	3000pcs/reel	Pb-Free <sup>(1)</sup> 16-Pin QFN 3 x	40.4		
AB1811-T3	3000pcs/reel	3 mm	-40 to +85 <sup>o</sup> C		
AB1813-T3	3000pcs/reel				
AB1814-T3	3000pcs/reel				
AB1815-T3	3000pcs/reel				
<ul> <li><sup>(1)</sup>Compliant and certified with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in raw homogeneous materials. The package was designed to be soldered at high temperatures (per reflow profile) and can be used in specified lead-free processes.</li> <li><sup>(2)</sup>Moisture Sensitivity Level rating according to the JEDEC J-STD-020D industry standard classifications.</li> </ul>					

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 34 of 37	Abracon Drawing #453568	Revision : A

## 9. Notes

- i. The parts are manufactured in accordance with this specification. If other conditions and specifications which are required for this specification, please contact ABRACON for more information.
- ii. ABRACON will supply the parts in accordance with this specification unless we receive a written request to modify prior to an order placement.
- iii. In no case shall ABRACON be liable for any product failure from in appropriate handling or operation of the item beyond the scope of this specification.
- iv. When changing your production process, please notify ABRACON immediately.
- v. ABRACON Corporation's products are COTS Commercial-Off-The-Shelf products; suitable for Commercial, Industrial and, where designated, Automotive Applications. ABRACON's products are not specifically designed for Military, Aviation, Aerospace, Life-dependant Medical applications or any application requiring high reliability where component failure could result in loss of life and/or property. For applications requiring high reliability and/or presenting an extreme operating environment, written consent and authorization from ABRACON Corporation is required. Please contact ABRACON Corporation for more information.
- vi. All specifications and Marking will be subject to change without notice.

he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 35 of 37	Abracon Drawing #453568	Revision : A

## **10. ABRACON CORPORATION – TERMS & CONDITIONS OF SALE**

The following are the terms and conditions under which Abracon Corporation ("AB") agrees to sell, to the entity named on the face hereof ("Buyer"), the products specified on the face hereof (the "Products"). Notwithstanding Buyer's desire to use standardized RFQs, purchase order forms, order forms, acknowledgment forms and other documents which may contain terms in addition to or at variance with these terms, it is expressly understood and agreed that other forms shall neither add to, nor vary, these terms whether or not these terms are referenced therein. Buyer may assent to these terms by written acknowledgment, implication and/or by acceptance or payment of goods ordered any of which will constitute assent.

- 1. <u>Prices</u>: Prices shown on the face hereof are in US dollars, with delivery terms specified herein and are exclusive of any other charges including, without limitation, fees for export, special packaging, freight, insurance and similar charges. AB reserves the right to increase the price of Products by written notice to Buyer at least thirty (30) days prior to the original date of shipment. When quantity price discounts are quoted by AB, the discounts are computed separately for each type of product to be sold and are based upon the quantity of each type and each size ordered at any one time. If any discounted order is reduced by Buyer with AB's consent, the prices shall be adjusted to the higher prices, if applicable, for the remaining order.
- 2. <u>Taxes</u>: Unless otherwise specified in the quotation, the prices do not include any taxes, import or export duties, tariffs, customs charges or any such other levies. Buyer agrees to reimburse AB the amount of any federal, state, county, municipal, or other taxes, duties, tariffs, or custom charges AB is required to pay. If Buyer is exempt from any such charges, Buyer must provide AB with appropriate documentation.
- 3. <u>Payment Terms</u>: For each shipment, AB will invoice Buyer for the price of the Products plus all applicable taxes, packaging, transportation, insurance and other charges. Unless otherwise stated in a separate agreement or in AB's quotation, payments are due within thirty (30) days from the date of invoice, subject to AB's approval of Buyer's credit application. All invoicing disputes must be submitted in writing to AB within ten (10) days of the receipt of the invoice accompanied by a reasonably detailed explanation of the dispute. Payment of the undisputed amounts shall be made timely. AB reserves the right to require payment in advance or C.O.D. and otherwise modified credit terms. When partial shipments are made, payments for such shipments shall become due in accordance with the above terms upon submission of invoices. If, at the request of Buyer, shipment is postponed for more than thirty (30) days, payment will become due thirty days after notice to Buyer that Products are ready for shipment. Any unpaid due amounts will be subject to interest at one decimal five percent (1.5%) per month, or, if less, the maximum rate allowed by law.
- 4. <u>Delivery and Shipment</u>: Shipment dates are estimates only. Failure to deliver by a specified date shall neither entitle Buyer to any compensation nor impose any liability on AB. AB reserves the right to ship and bill ten percent more or less than the exact quantity specified on the face hereof. All shipments will be made Ex Works as per Incoterms 2000 from AB's place of shipment. In the absence of specific instructions, AB will select the carrier. Claims against AB for shortages must be made in writing within ten (10) days after the arrival of the shipment. AB is not required to notify Buyer of the shipment. Buyer shall pay all freight charges, insurance and other shipping expenses. Freight charges, insurance and other shipping expenses. Buyer must pay actual costs.
- 5. Purchase Order Changes and Cancellations: Purchase orders for standard AB Products may not be canceled within sixty (60) days of the original shipping date. Purchase orders for non-standard AB Products are non-cancelable and non-returnable. All schedule changes must be requested at least thirty (30) days prior to original shipping date. Maximum schedule change "push-out" shall be no more than thirty (30) days from original shipping date. AB may terminate or cancel this order, in whole or in part, at any time prior to the completion of performance by written notice to Buyer without incur-

The Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 36 of 37	Abracon Drawing #453568	Revision : A

ring any liability to Buyer for breach of contract or otherwise. AB reserves the right to allocate Products in its sole discretion among Buyer and other potential buyers, or defer or delay the shipment of any Product, which is in short supply due to any reason.

- 6. <u>Title and Risk of Loss</u>: AB's responsibility for any loss or damage ends, and title passes, when Products are delivered Ex Works as per Incoterms 2000 at AB's designated shipping location to carrier, to Buyer or to Buyer's agent, whichever occurs first.
- 7. <u>Packing</u>: Packaging shall be AB's standard shipping materials or as specified on the face hereof. Any cost of non-standard packaging and handling requested by Buyer shall be abided by AB provided Buyer gives reasonable prior notice and agrees in writing to pay additional costs.
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- 9. <u>Specifications</u>: Specifications for each Product are the specifications specified in the published datasheets of such Product, as of the date of AB's quotation (the "Specifications"). Except as otherwise agreed, AB reserves the right to modify the Specifications at any time without adversely affecting the functionality.
- 10. <u>Acceptance</u>: Unless Buyer notifies AB in writing within ten (10) days from the date of receipt of Products that the Products fail to conform to the Specifications, the Products will be deemed accepted by Buyer. No such claim of non-conformity shall be valid if (i) the Products have been altered, modified or damaged by Buyer, (ii) the rejection notice fails to explain the non-conformance in reasonable detail and is not accompanied by a test report evidencing the non-conformity, or (iii) rejected Products are not returned to AB within thirty (30) days of rejection; provided, that no Product returns may be made without a return material authorization issued by AB.
- 11. Limited Warranties and Disclaimers: AB warrants to Buyer that each Product, for a period of twelve (12) months from shipment date thereof, will conform to the Specifications and be free from defects in materials and workmanship. AB's sole liability and Buyer's exclusive remedy for Products that fail to conform to this limited warranty ("Defective Products") is limited to repair or replacement of such Defective Products, or issue a credit or rebate of no more than the purchase price of such Defective Products, at AB's sole option and election. This warranty shall not apply: (i) if Products have been damaged or submitted to abnormal conditions (mechanical, electrical, or thermal) during transit, storage, installation, or use; or (ii) if Products are subject to Improper Use (as defined below); or (iii) if the non-conformance of Products results from misuse, neglect, improper testing, storage, installation, unauthorized repair, alteration, or excess usage at or beyond the maximum values (temperature limit, maximum voltage, and other Specification limits) defined by AB; (iv) to any other default not attributable to AB; or (v) removal, alteration, or tampering of the original AB product labeling. This warranty does not extend to Products or components purchased from entities other than AB or AB's authorized distributors or to third-party software or documentation that may be supplied with any Product. In the event no defect or breach of warranty is discovered by AB upon receipt of any returned Product, such Product will be returned to Buyer at Buyer's expense and Buyer will reimburse AB for the transportation charges, labor, and associated charges incurred in testing the allegedly Defective Product. The above warranty is for Buyer's benefit only, and is non-transferable. OTHER THAN THE LIMITED WARRANTY SET FORTH ABOVE, AB MAKES NO WARRANTIES, EXPRESS, STATUTORY, IMPLIED, OR OTHERWISE AND SPECIFICALLY DISCLAIMS THE IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NON-INFRINGEMENT, TO THE MAXIMUM EXTENT PERMITTED BY LAW. WITHOUT LIMITING THE GENERALITY OF THE FOREGOING DISCLAIMERS, AB INCORPORATES BY REFERENCE ANY PRODUCT-SPECIFIC WARRANTY DISCLAIMERS SET FORTH IN THE PUBLISHED PRODUCT DATASHEETS.
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he Power of Linking Together	AB18XX Real-Time Clock with Power Management Family	RoHS Compliant
Date of Issue: November 7, 2013	3.0 x 3.0 mm	ESD Sensitive
Page 37 of 37	Abracon Drawing #453568	Revision : A

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