

TMR265x

High Frequency Response Programmable TMR Linear Magnetic Sensor

Description

The TMR265x is a tunneling magnetoresistance (TMR) linear sensor with a dedicated signal conditioning circuit built in. The integrated signal conditioning circuit of TMR265x is able to calibrate zero offset, gain, temperature coefficient of sensitivity (TCS) and temperature coefficient of zero offset (TCO) of the TMR bridge circuit, and outputs the conditioned voltage signals.

In addition to TMR's intrinsic advantages of high resolution, high signal-to-noise ratio, and low power consumption, TMR265x series linear sensors also provide the following characteristics:

- 1. Fixed voltage output range in linear range
- 2. Excellent sensitivity consistency
- 3. Minimal zero drift
- 4. Low temperature coefficient of sensitivity
- 5. Low temperature coefficient of offset

This improvement greatly enhances the convenience of design and use of TMR linear sensor products.

The TMR265x linear magnetic sensor is available in DFN6L (3 mm \times 2 mm \times 0.75mm) package with P/N of TMR2651D and TMR2652D.



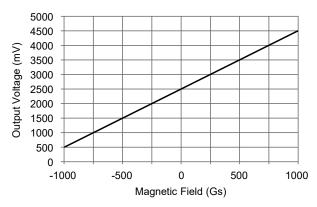
DFN6L

Features and Benefits

- Tunneling magnetoresistance (TMR) technology
- · High frequency response: DC to 2 MHz
- Large dynamic range: TMR2651D: ±1000 Gs TMR2652D: ±500 Gs
- Wide range supply voltages: 3 V to 5.5 V
- · Nonlinearity: 0.2%
- · Programmable sensitivity and zero offset
- Programmable temperature compensation
- RoHS & REACH compliant

Applications

- · Current sensor
- · Linear position sensor
- Gaussmeter
- Encoder



TMR2651D ±1000 Gs Output Curve





Selection Guide

Part Number	Supply Voltage	Linear Range	Non-Linearity	Package	Packing Form
TMR2651D	3 V to 5.5 V	±1000 Gs	0.2 %	DFN6L	Tape & Reel
TMR2652D	3 V to 5.5 V	±500 Gs	0.2 %	DFN6L	Tape & Reel

Catalogue

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1. Functional Block Diagram

TMR265x integrates a linear TMR magnetic sensor and a dedicated signal conditioning chip with a single-ended analog voltage output signal. The V_{OUT} pin can be reused as the OWI (one-wire-interface) protocol programming interface, to adjust zero-point, sensitivity, reference voltage V_{REF} and other parameters in a targeted manner.

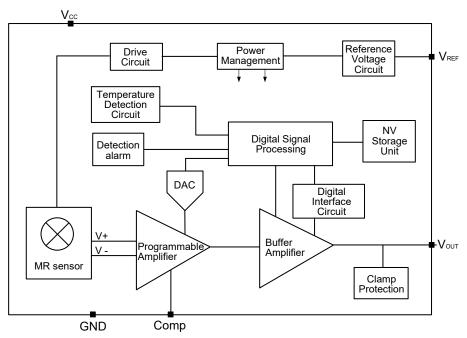


Figure 1. Block diagram of TMR265x

2. Pin Configuration

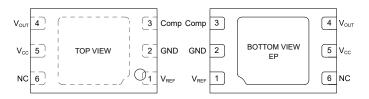


Figure 2. Pin configuration (DFN6L)

Number	Name	Function	
1	V_{REF}	Reference voltage output	
2	GND	Ground	
3	Comp	Analog voltage	
4	V _{OUT} Analog output / OWI communication interfa		
5	V _{CC} Power supply		
6	NC	Not connected	
	EP	Heat dissipation	

3. Sensing Direction

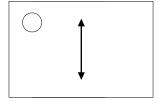


Figure 3. Sensing direction



4. Absolute Maximum Ratings

Parameters	Symbol	Min.	Max.	Unit
Supply voltage	Supply voltage V _{cc}		5.5	V
Supply current	I _{cc} ¹⁾	-	8	mA
External magnetic field	В	-	4000	Gs
ESD performance (HBM) V _{ESD}		-	4	kV
Operating ambient temperature T _A		-40	125	°C
Storage ambient temperature T _{STG}		-50	150	°C

¹⁾ Supply current I_{CC} refers to the current to operate after calibration.

5. Electrical Specifications

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit	Applicable Part Number
Supply voltage	V _{cc}	T _A = 25 °C	3	3.3/5	5.5	V	All parts
Supply current	I _{cc}	V _{CC} = 5 V, T _A = 25 °C	-	5	8	mA	All parts
Power-on time	t _{PO}	T _A = 25 °C	-	100	-	μs	All parts
Linaannaa	_	-	-1000	-	1000	Gs	TMR2651D
Linear range	B _{LIN}	-	-500	-	500	Gs	TMR2652D
Compiting to	SEN ²⁾	V _{CC} = 5 V, T _A = 25 °C	4 to 400 mm managements			mV/Gs	All parts
Sensitivity		V _{CC} = 3.3 V, T _A = 25 °C	1 to 100 programmable		mv/Gs	All parts	
Zero offset	V	V _{CC} = 5 V, T _A = 25 °C	-	2.5	-	V	All parts
Zero oliset	V _{OFFSET}	$V_{CC} = 3.3 \text{ V}, T_A = 25 \text{ °C}$	-	1.65	-	V	All parts
Poforonoo voltago	V _{REF}	V _{CC} = 5 V, T _A = 25 °C	-	2.5	-	V	All parts
Reference voltage		V _{CC} = 3.3 V, T _A = 25 °C	-	1.65	-	V	All parts
	HYS	T _A = 25 °C, ±200 Gs	-	0.2	-	Gs	All parts
Hysteresis		T _A = 25 °C, ±500 Gs	-	0.5	-	Gs	All parts
Hysteresis		T _A = 25 °C, ±1000 Gs	-	1	-	Gs	All parts
		T _A = 25 °C, ±1500 Gs	-	1.5	-	Gs	All parts
Nonlinearity	NONL	T _A = 25 °C	-	0.2	-	%FS	All parts
Temperature coefficient of sensitivity	TCS ³⁾	-40 °C to 125 °C	-	50	-	PPM/°C	All parts
Noise	Noise	T _A = 25 °C, 1Hz	-	150	-	nT/rt(Hz)	All parts
		1 _A - 25 C, 1HZ	-	20	-	μV/rt(Hz)	All parts
Temperature coefficient of offset	TCO ⁴⁾	-40 °C to 125 °C	-	0.1	-	mV/°C	All parts
Response frequency	F	varies with gain	DC to 2 MHz		All parts		

²⁾ The typical value of sensitivity is programmable via OWI protocol.

³⁾ The sensor can be programmed to perform multi-point temperature measurement to calibrate TCS for better performance.

⁴⁾ The sensor can be programmed to perform multi-point temperature measurement to calibrate TCO for better performance.



6. Typical Bandwidth Characteristics

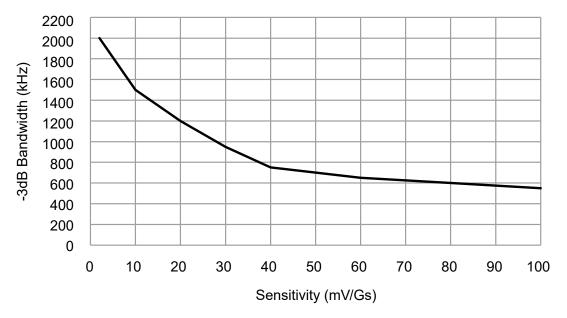
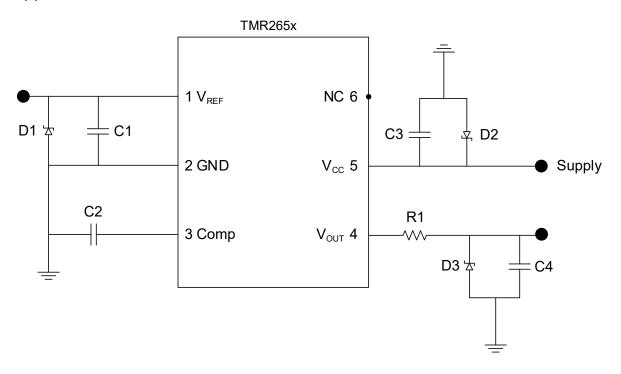


Figure 4. Bandwidth versus sensitivity



7. Application Information



Note:

R1	-	R1/C4: for output pin RC filtering	
C1	20 pF	Connects V _{REF} to GND for reference voltage filtering	
C2	20 pF	Connects Comp to V _{OUT} for output voltage filtering	
C3	0.1 μF	Connects V _{CC} to GND for supply voltage filtering	
C4	-	R1/C4: for output pin RC filtering	
D1	ESD5341N_5V/NA	Dual lead bidirectional 5V transient voltage suppression devices for ESD/surge protection.	
D2	ESD5341N_5V/NA	Dual lead bidirectional 5V transient voltage suppression devices for ESD/surge protection.	
D3	ESD5341N_5V/NA	Dual lead bidirectional 5V transient voltage suppression devices for ESD/surge protection.	

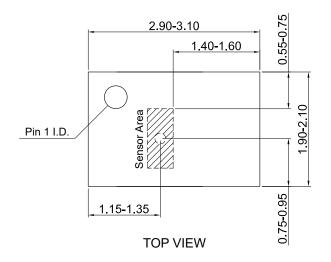
Figure 5. Typical application circuit

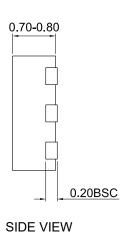
Please refer to the TMR265x product application manual for more product applications and OWI programming instructions.

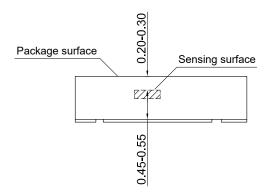


8. Dimensions

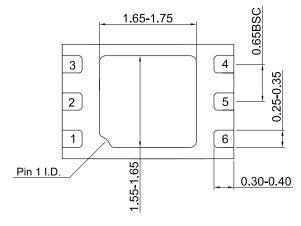
DFN6L Package







SIDE VIEW



BOTTOM VIEW

Figure 6. Package outline of DFN6L (unit: mm)

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