



UAV GNSS RECEIVER
GPM-808G
(GPS/GLONASS/BEIDOU+QMC5883)

Dimensions :52*52*20.5 mm

Cable length: 30CM



Applications

- UAV positioning

- **Features**

- Multi-satellite positioning systems support

- GPS/QZSS/GLONASS (GPM-808G)

- GPS/QZSS/Beidou (GPM-808B)

- Based on u-blox8 low power single chip

- Sensitivity

- Acquisition: -148dBm

- Tracking: -167dBm

- Low power: 40mA at continuous tracking

- SBAS (WAAS, EGNOS, MSAS) support

- Higher update rate option (default 1Hz)

- RTCM 2.3 support

- A-GPS support, OMA SUPL/3GPP TS25.171 (GSM/UMTS) compliant

- Easy to use: built-in patch antenna & 6-pin wire to

board connector w/ pitch of 1.0mm

- Backup battery support for faster position fix

- Fully EMI shielded

- Industrial operating temperature range: -40 ~ 85

Default shipment: TTL protocol, 9600,1HZ, standard NMEA-0183 protocol output.

1.Optional 1 baud rate, 4800/9600/19200/38400/57600/115200.

2 .output protocol optional, NMEA-0183 or UBX.

3 .output frequency optional, 1HZ--10HZ output.

Power Supply:DC Voltage3.3V~5.5V,Typical:3.3V or 5.0V

Consumption:Capture 50mA

Receiving Format:GPS,GLONASS,BeiDou,QZSS and SBAS

Receiving Channel:72 Searching Channel

Receiving Sensitivity:Trace -167dBm

Capture-148dBm

Positioning Time:Cold Start:avg36s

Warm Start:avg25s

Hot Start:avg1s

Level Positioning Precison:2.5m At Open Wind

Output Frequency:1Hz-10Hz,Default 1Hz

Speed Precison:0.1 m/s (Without Aid)

Acceleration Precison:0.1 m/s (Without Aid)

Dynamic Characteristics:Max Height:18000m

Max Speed:5153m/s

Max Acceleration:4G

Support Rate:4800bps to 115200bps,Default9600dps

Working Temperature: -40-+8

Technical Specifications

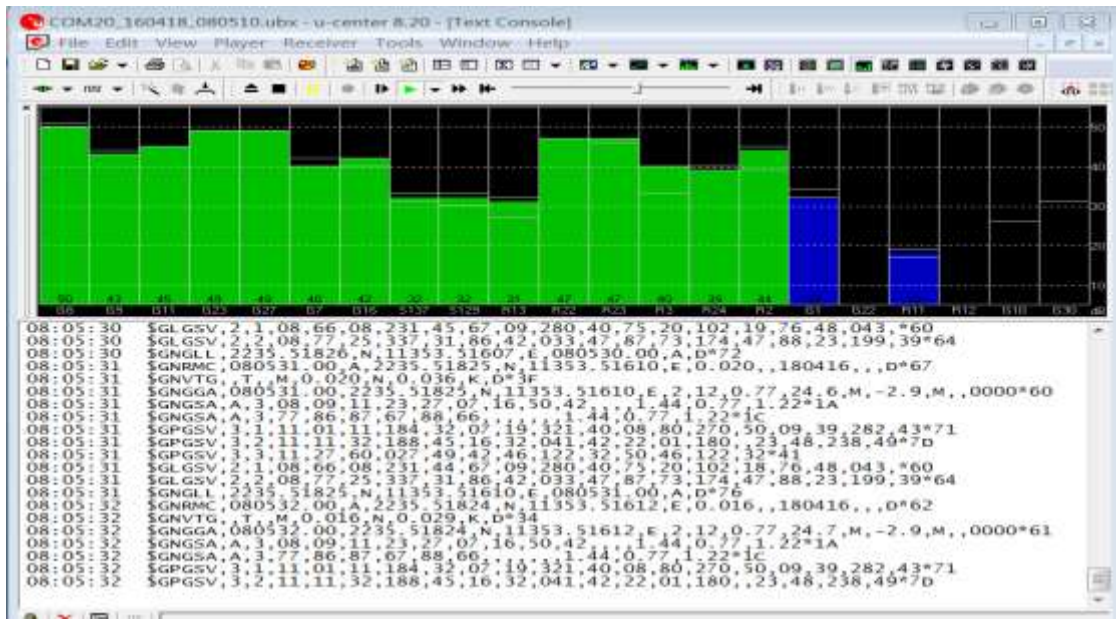
Receiver Performance Data

| | |
|-------------------------------------|--|
| Receiver Type | 72-channel u-blox 8 engine GPS & QZSS: L1 C/A, 1575.42MHz, GLONASS (GPM-808G): L1OF, 1598.0625~1605.375MHz BEIDOU (GPM-808B): B1 1561.098 MHz SBAS: WAAS, EGNOS, MSAS |
| Horizontal Position Accuracy | 2.5m (Autonomous) 2.0m (WAAS) |
| Accuracy | (including SBAS & QZSS; CEP, 50% 24hr static, -130dBm, >6 SVs) |
| Velocity Accuracy | 0.05 m/s (speed) <0.3(heading) (50% @ 30m/s) |
| Time Pulse | 30ns (RMS) |
| Signal Accuracy | <60ns (99%) |
| Time Pulse Frequency | 0.25 Hz ~ 10 MHz |
| Time To First Fix | Autonomous |
| Hot start | 1.5 sec |
| Cold start | 26 sec (50% -130dBm) |
| Sensitivity (Autonomous) | -148dBm (acquisition) -167dBm (tracking) |
| Navigation. Update Rate | Max. 10Hz, GPS & GLONASS or GPS & Beidou Max. 18Hz, GPS only Default 1Hz |
| Max. Altitude | 50,000 m |
| Max. Velocity | <1,852 km/hr |
| Protocol Support | NMEA 0183 v2.3 and V4.x UART: 9600bps N,8,1; GGA, GLL, GSA, GSV, RMC, VTG, TXT |
| SBAS Support | WAAS, EGNOS, MSAS |
| RTCM 2.3 | Messages 1, 2, 3, 9 |
| Dynamics | <4g |

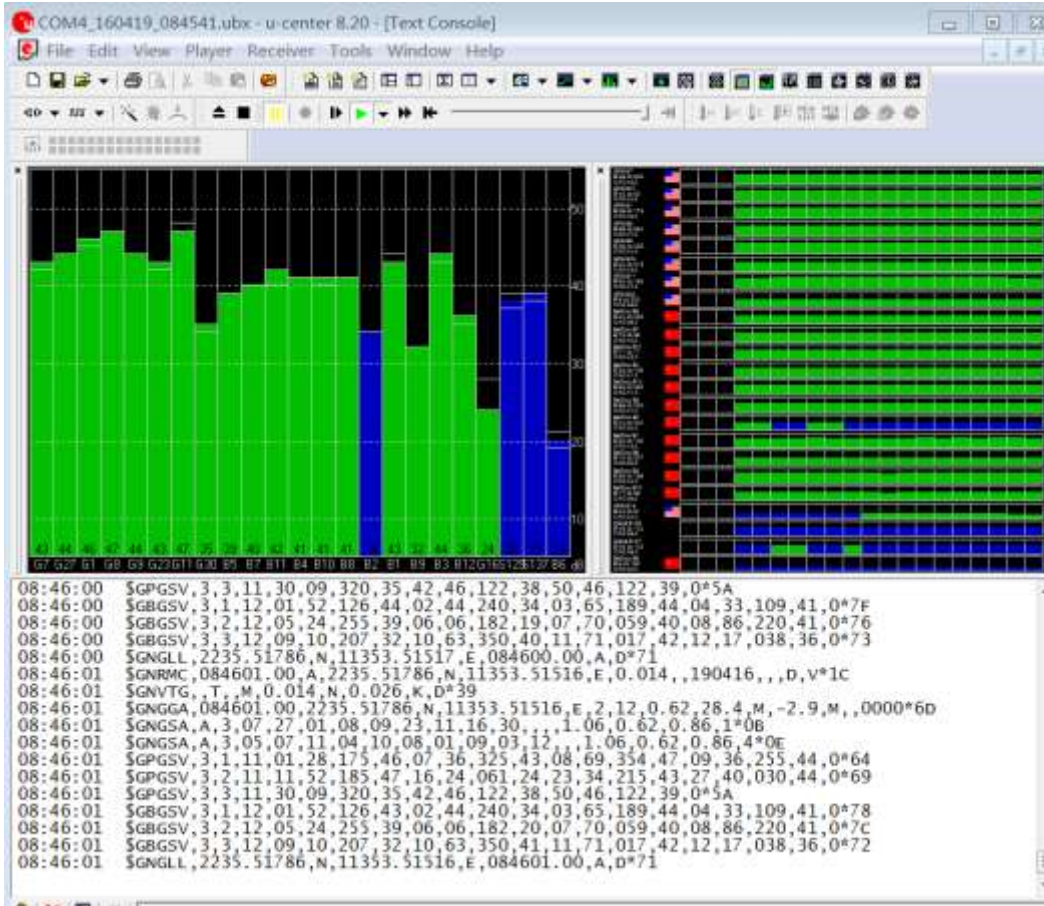
Shock

Half sine 30g/11ms

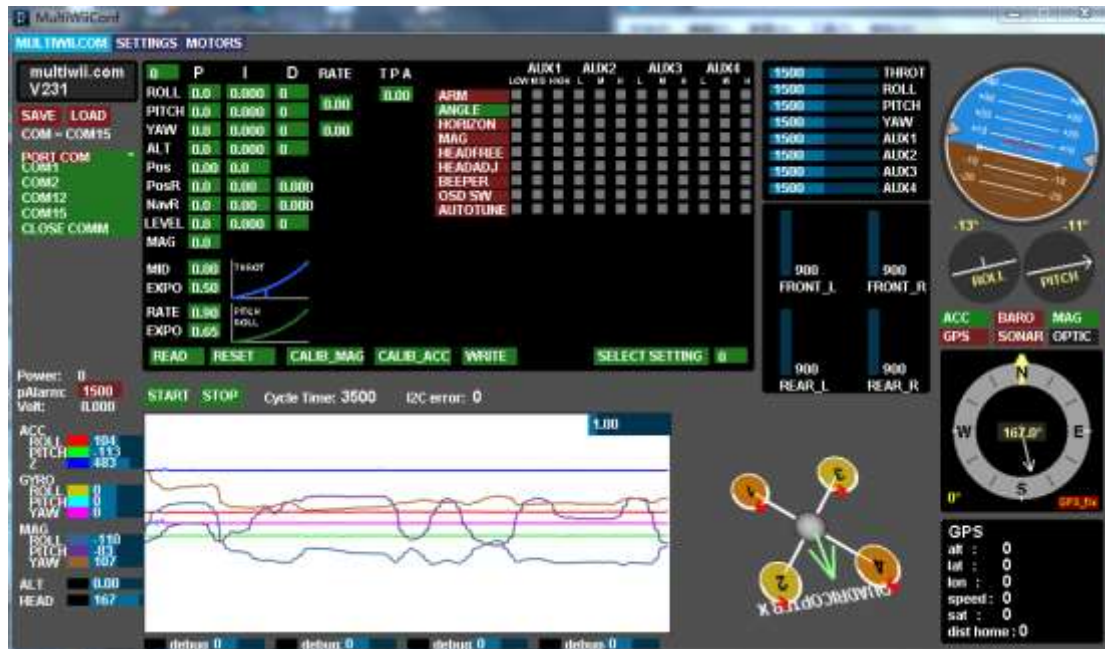
Test data(GPS+GLONASS):



Test data(GPS+BEI DOU):



QMC5883 Test Data:



PIN definition:

Connector PIN definition:

