# <span id="page-0-0"></span>**1. General description**

The TDA8024 is a complete and cost-efficient analog interface for asynchronous 3 V or 5 V smart cards. It can be placed between the card and the microcontroller to perform all supply, protection and control functions. Very few external components are required. The TDA8024AT is a direct replacement for the TDA8004AT.

More information can be obtained from the NXP internet site (www.nxp.com[\) and from](http://www.nxp.com/)  *"Application note AN10141"*.

### **CAUTION**



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the *ANSI/ESD S20.20*, *IEC/ST 61340-5*, *JESD625-A* or equivalent standards.

# <span id="page-0-1"></span>**2. Features and benefits**

- IC card interface
- 3 V or 5 V supply for the IC ( $V_{DD}$  and GND)
- Three specifically protected half-duplex bidirectional buffered I/O lines to card contacts C4, C7 and C8
- DC-to-DC converter for  $V_{CC}$  generation separately powered from a 5 V  $\pm$  20% supply  $(V<sub>DDP</sub>$  and PGND)
- 3 V or 5 V  $\pm$  5% regulated card supply voltage (V<sub>CC</sub>) with appropriate decoupling has the following capabilities:
	- $I_{\text{CC}}$  < 80 mA at  $V_{\text{DDP}}$  = 4 V to 6.5 V
	- ◆ Handles current spikes of 40 nAs up to 20 MHz
	- ◆ Controls rise and fall times
	- ◆ Filtered overload detection at approximately 120 mA
- Thermal and short-circuit protection on all card contacts
- Automatic activation and deactivation sequences; initiated by software or by hardware in the event of a short-circuit, card take-off, overheating,  $V_{DD}$  or  $V_{DDP}$  drop-out
- **Enhanced ESD protection on card side (** $>6$  **kV)**
- 26 MHz integrated crystal oscillator
- Clock generation for cards up to 20 MHz (divided by 1, 2, 4 or 8 through CLKDIV1 and CLKDIV2 signals) with synchronous frequency changes
- Non-inverted control of RST via pin RSTIN
- ISO 7816, GSM11.11 and EMV (payment systems) compatibility



- Supply supervisor for spike-killing during power-on and power-off and Power-on reset (threshold fixed internally or externally by a resistor bridge); not for TDA8024AT
- Built-in debounce on card presence contacts
- One multiplexed status signal OFF

# <span id="page-1-1"></span>**3. Applications**

- IC card readers for banking
- **Electronic payment**
- **I**I Identification
- **Pay TV**

# <span id="page-1-2"></span>**4. Quick reference data**

#### <span id="page-1-0"></span>**Table 1. Quick reference data**





### **Table 1. Quick reference data** *…continued*

# <span id="page-2-0"></span>**5. Ordering information**

### **Table 2. Ordering information**



# **NXP Semiconductors TDA8024**

**Standard smart card interface**

# <span id="page-3-1"></span>**6. Block diagram**

<span id="page-3-0"></span>

**NXP Semiconductors TDA8024**

**Standard smart card interface**

# <span id="page-4-0"></span>**7. Pinning information**

<span id="page-4-1"></span>

# **7.1 Pinning**

# <span id="page-5-0"></span>**7.2 Pin description**





<span id="page-6-0"></span>[1] The noise margin on  $V_{CC}$  will be higher with the 220 nF capacitor.

# <span id="page-6-2"></span><span id="page-6-1"></span>**8. Functional description**

Throughout this document it is assumed that the reader is familiar with ISO7816 terminology.

## **8.1 Power supply**

The supply pins for the IC are  $V_{DD}$  and GND.  $V_{DD}$  should be in the range of 2.7 V to 6.5 V. All signals interfacing with the system controller are referred to  $V_{DD}$ , therefore  $V_{DD}$  should also supply the system controller. All card reader contacts remain inactive during power-on or power-off.

The internal circuits are maintained in the reset state until  $V_{DD}$  reaches  $V_{th2} + V_{hvs2}$  and for the duration of the internal Power-on reset pulse,  $t_W$  (see [Figure 5\)](#page-7-1). When  $V_{DD}$  falls below  $V_{th2}$ , an automatic deactivation of the contacts is performed.

A DC-to-DC converter is incorporated to generate the 5 V or 3 V card supply voltage  $(V_{\text{CC}})$ . The DC-to-DC converter should be supplied separately by  $V_{\text{DDP}}$  and PGND. Due to the possibility of large transient currents, the two 100 nF capacitors of the DC-to-DC converter should be located as near as possible to the IC and have an ESR less than 100 m $\Omega$ .

The DC-to-DC converter functions as a voltage doubler or a voltage follower according to the respective values of  $V_{CC}$  and  $V_{DDP}$  (both have thresholds with a hysteresis of 100 mV).

The DC-to-DC converter function changes as follows.

- $V_{CC} = 5$  V and  $V_{DDP} > 5.8$  V; voltage follower
- $V_{CC} = 5$  V and  $V_{DDP} < 5.7$  V; voltage doubler
- $V_{CC} = 3$  V and  $V_{DDP} > 4.1$  V; voltage follower
- $V_{CC} = 3$  V and  $V_{DDP} < 4.0$  V; voltage doubler.

Supply voltages  $V_{DD}$  and  $V_{DDP}$  may be applied to the IC in any sequence.

After powering the device, OFF remains LOW until CMDVCC is set HIGH.

During power off,  $\overline{\text{OFF}}$  falls LOW when  $V_{\text{DD}}$  is below the falling threshold voltage.

## **8.2 Voltage supervisor**

### <span id="page-7-3"></span><span id="page-7-2"></span>**8.2.1 Without external divider on pin PORADJ (or with TDA8024AT)**

The voltage supervisor surveys the  $V_{DD}$  supply. A defined reset pulse of approximately 8 ms ( $t_W$ ) is used internally to keep the IC inactive during power-on or power-off of the  $V_{DD}$ supply (see [Figure 5\)](#page-7-1).

As long as  $V_{DD}$  is less than  $V_{th2} + V_{hys2}$ , the IC remains inactive whatever the levels on the command lines. This state also lasts for the duration of t<sub>W</sub> after  $V_{DD}$  has reached a level higher than  $V_{th2} + V_{hvs2}$ .

When  $V_{DD}$  falls below  $V_{th2}$ , a deactivation sequence of the contacts is performed.



## <span id="page-7-1"></span><span id="page-7-0"></span>**8.2.2 With an external divider on pin PORADJ (not for the TDA8024AT)**

If an external resistor bridge is connected to pin PORADJ (R1 and R2 in [Figure 1](#page-3-0)), then the following occurs:

• The internal threshold voltage  $V_{th2}$  is overridden by the external voltage and by the hysteresis, therefore:

$$
V_{th2(ext)(rise)} = \left(I + \frac{RI}{R2}\right) \times \left(V_{bridge} + \frac{V_{hys(ext)}}{2}\right)
$$

$$
V_{th2(ext)(fall)} = \left(I + \frac{RI}{R2}\right) \times \left(V_{bridge} - \frac{V_{hys(ext)}}{2}\right)
$$

where  $V_{\text{bridge}} = 1.25$  V typ. and  $V_{\text{hvs}(\text{ext})} = 60$  mV typ.

• The reset pulse width t<sub>W</sub> is doubled to approximately 16 ms.

Input PORADJ is biased internally with a pull-down current source of 4  $\mu$ A which is removed when the voltage on pin PORADJ exceeds 1 V. This ensures that after detection of the external bridge by the IC during power-on, the input current on pin PORADJ does not cause inaccuracy of the bridge voltage.

The minimum threshold voltage should be higher than 2 V.

The maximum threshold voltage may be up to  $V_{DD}$ .

# <span id="page-8-1"></span>**8.2.3 Applications examples**

The voltage supervisor is used as Power-on reset and as supply dropout detection during a card session.

Supply dropout detection is to ensure that a proper deactivation sequence is followed before the voltage is too low.

For the internal voltage supervisor to function, the system microcontroller should operate down to 2.35 V to ensure a proper deactivation sequence. If this is not possible, external resistor values can be chosen to overcome the problem.

## <span id="page-8-0"></span>**8.2.3.1 Microcontroller requiring a 3.3 V**  $\pm$  **20 % supply**

For a microcontroller supplied by 3.3 V with a  $\pm 5\%$  regulator and with resistors R1, R2 having a  $\pm$ 1% tolerance, the minimum supply voltage is 3.135 V.

 $V_{\text{PORADJ}} = k \times V_{\text{DD}}$ , where  $k = \frac{SI}{S I_{\text{SLO}}}$  with S1 and S2 the actual values of nominal resistors R1 and R2.  $=\frac{S I}{S I + S 2}$ 

This can be shown as:

 $0.99 \times R1 < S1 < 1.01 \times R1$  and  $0.99 \times R2 < S2 < 1.01 \times R2$ 

Transposed, this becomes

$$
I + \left(0.98 \times \frac{R}{R} \right) = I + \left(\frac{0.99}{I.01}\right) \times \frac{R}{R} \times \frac{I}{k}
$$

$$
\frac{l}{k}
$$

If V1 =  $V_{th(ext)(rise)(max)}$  and V2 =  $V_{th(ext)(fall)(min)}$  activation will always be possible if  $V_{PORADJ}$  $>$  V1 and deactivation will always be done for  $V_{PORADJ}$  < V2.

Activation is always possible for  $V_{DD}$   $>$   $\frac{VI}{k}$  and deactivation is always possible for  $>$  $\frac{VI}{k}$  and deactivation is always possible for  $V_{DD}$  <  $\frac{V2}{k}$  $\frac{V_2}{k}$ 

That is V1 = 1.31 V and V2 = 1.19 V and 
$$
\frac{R1}{R2} < (\frac{3.135}{1.31} - 1) \times 0.98 = 1.365
$$

Suppose R1 + R2 = 100 k
$$
\Omega
$$
, then  $R2 = \frac{100 k\Omega}{2.365} = 42.3 k\Omega$  and R1 = 57.7 k $\Omega$ .

Deactivation will be effective at  $V2 \times (1 + 1.02 \times 1.365) = 2.847$  V in any case.

If the microcontroller continues to function down to 2.80 V, the slew rate on  $V_{DD}$  should be less than 2 V/ms to ensure that clock CLK is correctly delivered to the card until time  $t_{12}$ (see [Figure 9\)](#page-14-0).

## <span id="page-8-2"></span>**8.2.3.2 Microcontroller requiring a 3.3 V 10% supply**

For a microcontroller supplied by a 3.3 V with a  $\pm$ 1% regulator and with resistors R1, R2 having a  $\pm 0.1$ % tolerance, the minimum supply voltage is 3.267 V.

The same calculations as in [Section 8.2.3.1](#page-8-0) conclude:

$$
\frac{R1}{R2} < \left(\frac{3.267}{1.310} - 1\right) \times 0.998 = 1.491
$$

Therefor  $R2 = \frac{100 kΩ}{2.49} = 40.14 kΩ$  and R1 = 59.86 kΩ.

Deactivation will be effective at  $V2 \times (1 + 1.002 \times 1.491) = 2.967$  V in any case.

If the microcontroller continues to function down to 2.97 V, the slew rate on  $V_{DD}$  should be less than 0.20 V/ms to ensure that clock CLK is correctly delivered to the card until time  $t_{12}$  (see [Figure 9\)](#page-14-0).

## <span id="page-9-2"></span>**8.3 Clock circuitry**

The card clock signal (CLK) is derived from a clock signal input to pin XTAL1 or from a crystal operating at up to 26 MHz connected between pins XTAL1 and XTAL2.

The clock frequency can be  $f_{\text{XTAL}}$ ,  $1/2 \times f_{\text{XTAL}}$ ,  $1/4 \times f_{\text{XTAL}}$  or  $1/8 \times f_{\text{XTAL}}$ . Frequency selection is made via inputs CLKDIV1 and CLKDIV2 (see [Table 4](#page-9-1)).

<b>CLKDIV1</b>	<b>CLKDIV2</b>	f <sub>CLK</sub>
0	0	$f_{XTAL}$ 8
0		$f_{XTAL}$ $\overline{4}$
		$f_{XTAL}$ 2
	0	$f_{XTAL}$

<span id="page-9-1"></span>**Table 4. Clock frequency selection[\[1\]](#page-9-0)**

<span id="page-9-0"></span>[1] The status of pins CLKDIV1 and CLKDIV2 must not be changed simultaneously; a delay of 10 ns minimum between changes is needed; the minimum duration of any state of CLK is eight periods of XTAL1.

The frequency change is synchronous, which means that during transition no pulse is shorter than 45% of the smallest period, and that the first and last clock pulses about the instant of change have the correct width.

When changing the frequency dynamically, the change is effective for only eight periods of XTAL1 after the command.

The duty factor of  $f_{\text{XTAL}}$  depends on the signal present at pin XTAL1.

In order to reach a 45% to 55% duty factor on pin CLK, the input signal on pin XTAL1 should have a duty factor of 48% to 52% and transition times of less than 5% of the input signal period.

If a crystal is used, the duty factor on pin CLK may be 45% to 55% depending on the circuit layout and on the crystal characteristics and frequency.

In other cases, the duty factor on pin CLK is guaranteed between 45% and 55% of the clock period.

The crystal oscillator runs as soon as the IC is powered up. If the crystal oscillator is used, or if the clock pulse on pin XTAL1 is permanent, the clock pulse is applied to the card as shown in the activation sequences shown in [Figure 7](#page-12-0) and [8.](#page-13-0)

If the signal applied to XTAL1 is controlled by the system microcontroller, the clock pulse will be applied to the card when it is sent by the system microcontroller (after completion of the activation sequence).

## <span id="page-10-0"></span>**8.4 I/O transceivers**

The three data lines I/O, AUX1 and AUX2 are identical.

The Idle-state is realized by both I/O and I/OUC lines being pulled HIGH via a 11  $k\Omega$ resistor (I/O to  $V_{CC}$  and I/OUC to  $V_{DD}$ ).

Pin I/O is referenced to  $V_{\text{CC}}$ , and pin I/OUC to  $V_{\text{DD}}$ , thus allowing operation when  $V_{\text{CC}}$  is not equal to  $V_{DD}$ .

The first side of the transceiver to receive a falling edge becomes the master. An anti-latch circuit disables the detection of falling edges on the line of the other side, which then becomes a slave.

After a time delay  $t_{d(edae)}$ , an N-transistor on the slave side is turned on, thus transmitting the logic 0 present on the master side.

When the master side returns to logic 1, a P-transistor on the slave side is turned on during the time delay  $t_{\text{out}}$  and then both sides return to their idle states.

This active pull-up feature ensures fast LOW-to-HIGH transitions; as shown in [Figure 6](#page-11-0), it is able to deliver more than 1 mA at an output voltage of up to  $0.9V_{CC}$  into an 80 pF load. At the end of the active pull-up pulse, the output voltage depends only on the internal pull-up resistor and the load current.

The current to and from the card I/O lines is limited internally to 15 mA and the maximum frequency on these lines is 1 MHz.



## <span id="page-11-2"></span><span id="page-11-0"></span>**8.5 Inactive mode**

After a Power-on reset, the circuit enters the inactive mode. A minimum number of circuits are active while waiting for the microcontroller to start a session:

- All card contacts are inactive (approximately 200  $\Omega$  to GND)
- Pins I/OUC, AUX1UC and AUX2UC are in the high-impedance state  $(11 k\Omega)$  pull-up resistor to  $V_{DD}$ )
- **•** Voltage generators are stopped
- **•** XTAL oscillator is running
- **•** Voltage supervisor is active
- **•** The internal oscillator is running at its low frequency

### <span id="page-11-3"></span>**8.6 Activation sequence**

After power-on and after the internal pulse width delay, the system microcontroller can check the presence of a card using the signals OFF and CMDVCC as shown in [Table 5](#page-11-1).

<span id="page-11-1"></span>



If the card is in the reader (this is the case if PRES or PRES is active), the system microcontroller can start a card session by pulling CMDVCC LOW. The following sequence then occurs (see [Figure 6](#page-11-0)):

1. CMDVCC is pulled LOW and the internal oscillator changes to its high frequency  $(t_0)$ .

- 2. The voltage doubler is started (between  $t_0$  and  $t_1$ ).
- 3. V<sub>CC</sub> rises from 0 to 5 V (or 3 V) with a controlled slope ( $t_2 = t_1 + 1.5 \times T$ ) where T is 64 times the period of the internal oscillator (approximately  $25 \mu s$ ).
- 4. I/O, AUX1 and AUX2 are enabled  $(t_3 = t_1 + 4T)$

(these were pulled LOW until this moment).

- 5. CLK is applied to the C3 contact of the card reader  $(t_4)$ .
- 6. RST is enabled  $(t_5 = t_1 + 7T)$ .

The clock may be applied to the card using the following sequence:

- 1. Set RSTIN HIGH.
- 2. Set CMDVCC LOW.
- 3. Reset RSTIN LOW between  $t_3$  and  $t_5$ ; CLK will start at this moment.
- 4. RST remains LOW until t<sub>5</sub>, when RST is enabled to be the copy of RSTIN.
- 5. After  $t_5$ , RSTIN has no further affect on CLK; this allows a precise count of CLK pulses before toggling RST.

If the applied clock is not needed, then CMDVCC may be set LOW with RSTIN LOW. In this case, CLK will start at  $t_3$  (minimum 200 ns after the transition on I/O), and after  $t_5$ , RSTIN may be set HIGH in order to obtain an Answer To Request (ATR) from the card.

Activation should not be performed with RSTIN held permanently HIGH.

<span id="page-12-0"></span>



## <span id="page-13-1"></span><span id="page-13-0"></span>**8.7 Active mode**

When the activation sequence is completed, the TDA8024 will be in its active mode. Data is exchanged between the card and the microcontroller via the I/O lines. The TDA8024 is designed for cards without  $V_{PP}$  (the voltage required to program or erase the internal non-volatile memory).

## <span id="page-13-2"></span>**8.8 Deactive sequence**

When a session is completed, the microcontroller sets the CMDVCC line HIGH. The circuit then executes an automatic deactivation sequence by counting the sequencer back and finishing in the inactive mode (see [Figure 9\)](#page-14-0):

- 1. RST goes LOW  $(t_{10})$ .
- 2. CLK is held LOW ( $t_{12} = t_{10} + 0.5 \times T$ ) where T is 64 times the period of the internal oscillator (approximately  $25 \mu s$ ).
- 3. I/O, AUX1 and AUX2 are pulled LOW  $(t_{13} = t_{10} + T)$ .
- 4. V<sub>CC</sub> starts to fall towards zero  $(t_{14} = t_{10} + 1.5 \times T)$ .
- 5. The deactivation sequence is complete at  $t_{\text{de}}$ , when  $V_{\text{CC}}$  reaches its inactive state.
- 6. V<sub>UP</sub> falls to zero ( $t_{15} = t_{10} + 5T$ ) and all card contacts become low-impedance to GND; I/OUC, AUX1UC and AUX2UC remain at  $V_{DD}$  (pulled-up via a 11 k $\Omega$  resistor).
- 7. The internal oscillator returns to its lower frequency.



# <span id="page-14-1"></span><span id="page-14-0"></span>8.9 V<sub>CC</sub> generator

The  $V_{CG}$  generator has a capacity to supply up to 80 mA continuously at 5 V and 65 mA at 3 V.

An internal overload detector operates at approximately 120 mA. Current samples to the detector are internally filtered, allowing spurious current pulses up to 200 mA with a duration in the order of  $\mu$ s to be drawn by the card without causing deactivation. The average current must stay below the specified maximum current value.

For reasons of V<sub>CC</sub> voltage accuracy, a 100 nF capacitor with an ESR < 100 m $\Omega$  should be tied to CGND near to pin  $V_{CC}$ , and a 100 nF or 220 nF capacitor (220 nF is the best choice) with the same ESR should be tied to CGND near card reader contact C1.

## <span id="page-14-2"></span>**8.10 Fault detection**

The following fault conditions are monitored:

- Short-circuit or high current on V<sub>CC</sub>
- **•** Removal of a card during a transaction
- V<sub>DD</sub> dropping
- DC-to-DC converter operating out of the specified values (V<sub>DDP</sub> too low or current from  $V_{UP}$  too high)
- **•** Overheating

There are two different cases (see [Figure 10\)](#page-15-0):

• CMDVCC HIGH outside a card session. Output OFF is LOW if a card is not in the card reader, and HIGH if a card is in the reader. A voltage drop on the  $V_{DD}$  supply is detected by the supply supervisor, this generates an internal Power-on reset pulse but does not act upon OFF. No short-circuit or overheating is detected because the card is not powered-up.

• CMDVCC LOW within a card session. Output OFF goes LOW when a fault condition is detected. As soon as this occurs, an emergency deactivation is performed automatically (see [Figure 11](#page-15-1)). When the system controller resets CMDVCC to HIGH it may sense the OFF level again after completing the deactivation sequence. This distinguishes between a hardware problem or a card extraction (OFF goes HIGH again if a card is present).

Depending on the type of card-present switch within the connector (normally-closed or normally-open) and on the mechanical characteristics of the switch, bouncing may occur on the PRES signals at card insertion or withdrawal.

There is a debounce feature in the device with an 8 ms typical duration (see [Figure 10](#page-15-0)). When a card is inserted, output OFF goes HIGH only at the end of the debounce time.

When the card is extracted, an automatic deactivation sequence of the card is performed on the first true/false transition on PRES or PRES and output OFF goes LOW.



<span id="page-15-0"></span>

<span id="page-15-1"></span>TDA8024 **All information provided in this document is subject to legal disclaimers. COMP Semiconductors N.V. 2016. All rights reserved.** 

# <span id="page-16-5"></span>**9. Limiting values**

#### **Table 6. Limiting values**

*In accordance with the Absolute Maximum Rating System (IEC 60134).*



<span id="page-16-0"></span>[1] All card contacts are protected against any short-circuit with any other card contact.

<span id="page-16-1"></span>[2] Every pin withstands the ESD test according to MIL-STD-883C class 3 for card contacts, class 2 for the remaining. Method 3015 (HBM; 1500  $\Omega$  and 100 pF) 3 pulses positive and 3 pulses negative on each pin referenced to ground.

<span id="page-16-2"></span>[3] In accordance with EIA/JESD22-A114-B, June 2000.

<span id="page-16-3"></span>[4] In accordance with EIA/JESD22-A115-A, October 1997.

# <span id="page-16-6"></span>**10. Thermal characteristics**

#### **Table 7. Thermal characteristics**



<span id="page-16-4"></span>[1] This figure was obtained using the following Printed-Circuit Board (PCB) technology: FR, 4 layers, 0.5 mm thickness, class 5, copper thickness 35 µm, Ni/Go plating, ground plane in internal layers.

# <span id="page-17-0"></span>**11. Characteristics**

#### **Table 8. Characteristics**

*VDD = 3.3 V; VDDP = 5 V; Tamb = 25 C; fXTAL = 10 MHz; all currents flowing into the IC are positive: see [Table note 1;](#page-21-0) unless otherwise specified.*



*VDD = 3.3 V; VDDP = 5 V; Tamb = 25 C; fXTAL = 10 MHz; all currents flowing into the IC are positive: see Table note 1; unless otherwise specified.*



*VDD = 3.3 V; VDDP = 5 V; Tamb = 25 C; fXTAL = 10 MHz; all currents flowing into the IC are positive: see Table note 1; unless otherwise specified.*

![](_page_19_Picture_423.jpeg)

*VDD = 3.3 V; VDDP = 5 V; Tamb = 25 C; fXTAL = 10 MHz; all currents flowing into the IC are positive: see Table note 1; unless otherwise specified.*

<b>Symbol</b>	<b>Parameter</b>	<b>Conditions</b>	Min	<b>Typ</b>	<b>Max</b>	<b>Unit</b>		
$t_{t(DO)}$	data output transition time	$V_0 = 0$ to $V_{DD}$ ; C <sub>L</sub> < 30 pF; 10% to 90%			0.1	μS		
$R_{\text{pu}}$	integrated pull-up resistor	pull-up resistor to V <sub>DD</sub>	9	11	13	kΩ		
$I_{\text{pu}}$	current when pull-up active	$V_{OH} = 0.9V_{DD}$ ; C = 30 pF	$-1$			mA		
<b>Internal oscillator</b>								
frequency of internal $f_{\text{OSC(int)}}$ oscillator		inactive mode	55	140	200	kHz		
		active mode	2.2	2.7	3.2	MHz		
<b>Reset output to card reader (pin RST)</b>								
$V_{o(inactive)}$	output voltage	inactive mode						
		no load	0		0.1	V		
		$I_{o(inactive)} = 1$ mA	0		0.3	v		
I <sub>O</sub> (inactive)	output current	inactive mode; pin grounded			$-1$	mA		
$t_{d(RSTIN-RST)}$	<b>RSTIN to RST delay</b>	<b>RST</b> enabled			$\overline{c}$	μS		
$V_{OL}$	LOW-level output voltage	$I_{OL} = 200 \mu A$	0		0.2	V		
		$I_{OL}$ = 20 mA (current limit)	$V_{\text{CC}}$ – 0.4		$V_{\rm CC}$	V		
<b>V<sub>OH</sub></b>	HIGH-level output voltage	$I_{OH} = -200 \mu A$	$0.9V_{CC}$		$V_{\rm CC}$	v		
		$I_{OH} = -20$ mA (current limit)	0		0.4	v		
$ t_r$	rise time	$C_L$ = 100 pF; $V_{CC}$ = 5 V or 3 V	$\overline{a}$		0.1	μS		
t	fall time	$C_L$ = 100 pF; $V_{CC}$ = 5 V or 3 V	$\frac{1}{2}$		0.1	μS		
	<b>Clock output to card reader (pin CLK)</b>							
$V_{o(inactive)}$	output voltage	inactive mode						
		no load	0		0.1	V		
		$I_{o(inactive)} = 1$ mA	0		0.3	v		
$I_{o(inactive)}$	output current	CLK inactive; pin grounded	0		$-1$	mA		
$V_{OL}$	LOW-level output voltage	$I_{OL} = 200 \mu A$	0		0.3	v		
		$I_{OL}$ = 70 mA (current limit)	$V_{\text{CC}}$ – 0.4		$V_{\rm CC}$	v		
V <sub>OH</sub>	HIGH-level output voltage	$I_{OH} = -200 \mu A$	$0.9V_{CC}$		$V_{\rm CC}$	V		
		$I_{OH} = -70$ mA (current limit)	0		0.4	V		
$ t_r$	rise time	[5] $C_L = 30 pF$			16	ns		
$t_f$	fall time	$\boxed{5}$ $C_L = 30 pF$			16	ns		
$\delta$	duty factor (except for $f_{\text{XTAL}}$	[5] $C_L = 30 pF$	45		55	$\%$		
<b>SR</b>	slew rate	slew up or down; $C_L = 30$ pF	0.2			V/ns		
Control inputs (pins CLKDIV1, CLKDIV2, CMDVCC, RSTIN and 5V/3V) <sup>[6]</sup>								
VIL	LOW-level input voltage		$-0.3$		$+0.3VDD$	V		
V <sub>IH</sub>	HIGH-level input voltage		0.7V <sub>DD</sub>		$V_{DD} + 0.3$	V		
$ I_{LIL} $	LOW-level input leakage	$0 < V_{IL} < V_{DD}$			1	μA		
	current							
$ I_{LIH} $	HIGH-level input leakage current	$0 < V_{IH} < V_{DD}$			1	μA		

*VDD = 3.3 V; VDDP = 5 V; Tamb = 25 C; fXTAL = 10 MHz; all currents flowing into the IC are positive: see Table note 1; unless otherwise specified.*

![](_page_21_Picture_387.jpeg)

<span id="page-21-0"></span>[1] All parameters remain within limits but are tested only statistically for the temperature range. When a parameter is specified as a function of  $V_{DD}$  or  $V_{CC}$  it means their actual value at the moment of measurement.

<span id="page-21-1"></span>[2] If no external bridge is used then, to avoid any disturbance, it is recommended to connect pin 18 to ground. Pin 18 is not connected in the TDA8024AT.

[3] To meet these specifications, pin V<sub>CC</sub> should be decoupled to CGND using two ceramic multilayer capacitors of low ESR both with values of 100 nF, or one 100 nF and one 220 nF (see [Figure 13\)](#page-23-0).

<span id="page-21-3"></span><span id="page-21-2"></span>[4] Permitted capacitor values are 100 nF, or 100 nF + 100 nF, or 220 nF, or 220 nF + 100 nF, or 330 nF.

[5] Transition time and duty factor definitions are shown in Figure 12; 
$$
\delta = \frac{t_1}{t_1 + t_2}
$$

<span id="page-21-4"></span>[6] Pin CMDVCC is active LOW; pin RSTIN is active HIGH; for CLKDIV1 and CLKDIV2 functions see [Table 1.](#page-1-0)

<span id="page-21-5"></span>[7] Pin PRES is active LOW; pin PRES is active HIGH; PRES has an integrated 1.25 µA current source to GND (PRES to V<sub>DD</sub>); the card is considered present if at least one of the inputs PRES or PRES is active.

![](_page_22_Figure_3.jpeg)

# <span id="page-22-1"></span>**12. Application information**

<span id="page-22-0"></span>Performance can be affected by the layout of the application. For example, an additional cross-capacitance of 1 pF between card reader contacts C2 and C3 or C2 and C7 can cause contact C2 to be polluted with high frequency noise from C3 (or C7). In this case, include a 100 pF capacitor between contacts C2 and CGND.

Application recommendations:

- **•** Ensure there is ample ground area around the TDA8024 and the connector; place the TDA8024 very near to the connector; decouple the  $V_{DD}$  and  $V_{DDP}$  lines (these lines are best positioned under the connector)
- The TDA8024 and the microcontroller must use the same V<sub>DD</sub> supply. Pins CLKDIV1, CLKDIV2, RSTIN, PRES, PRES, AUX1UC, I/OUC, AUX2UC, 5V/3V, CMDVCC, and  $\overline{\text{OFF}}$  are referred to  $V_{DD}$ ; if pin XTAL1 is to be driven by an external clock, also refer this pin to  $V_{DD}$
- **•** Track C3 should be placed as far as possible from the other tracks
- **•** The track connecting CGND to C5 should be straight (the two capacitors on C1 should be connected to this ground track)
- **•** Avoid ground loops between CGND, PGND and GND
- Decouple V<sub>DDP</sub> and V<sub>DD</sub> separately; if the two supplies are the same in the application, then they should be connected in star on the main track.

With all these layout precautions, noise should be kept to an acceptable level and jitter on C3 should be less than 100 ps.

Reference layouts are provided in *"Application note 10141"*, available on request.

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![](_page_23_Figure_3.jpeg)

- (1) These capacitors must be of the low ESR-type and be placed near the IC (within 100 mm).
- (2) TDA8024 and the microcontroller must use the same  $V_{DD}$  supply.
- (3) Make short, straight connections between CGND, C5 and the ground connection to the capacitor.
- (4) Mount one low ESR-type 100 nF capacitor close to pin  $V_{CC}$ .
- (5) Mount one low ESR-type 100 or 220 nF capacitor close to C1 contact (less than 100 mm from it).
- (6) The connection to C3 should be routed as far from C2, C7, C4 and C8 and, if possible, surrounded by grounded tracks.
- (7) Optional resistor bridge for changing the threshold of  $V_{DD}$ . If this bridge is not required pin 18 should be connected to ground; see [Section 8.2.2.](#page-7-0) Pin 18 is not connected in the TDA8024AT.

<span id="page-23-0"></span>**Fig 13. Application diagram**

# <span id="page-24-0"></span>**13. Package outline**

![](_page_24_Figure_4.jpeg)

#### **Fig 14. Package outline SOT136-1 (SO28)**

![](_page_25_Figure_3.jpeg)

**Fig 15. Package outline SOT361-1 (TSSOP28)**

# <span id="page-26-0"></span>**14. Soldering of SMD packages**

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

## <span id="page-26-1"></span>**14.1 Introduction to soldering**

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

## <span id="page-26-2"></span>**14.2 Wave and reflow soldering**

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- **•** Through-hole components
- **•** Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- **•** Board specifications, including the board finish, solder masks and vias
- **•** Package footprints, including solder thieves and orientation
- **•** The moisture sensitivity level of the packages
- **•** Package placement
- **•** Inspection and repair
- **•** Lead-free soldering versus SnPb soldering

## <span id="page-26-3"></span>**14.3 Wave soldering**

Key characteristics in wave soldering are:

- **•** Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- **•** Solder bath specifications, including temperature and impurities

## <span id="page-27-2"></span>**14.4 Reflow soldering**

Key characteristics in reflow soldering are:

- **•** Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 16\)](#page-28-0) than a SnPb process, thus reducing the process window
- **•** Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- **•** Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 9](#page-27-0) and [10](#page-27-1)

#### <span id="page-27-0"></span>**Table 9. SnPb eutectic process (from J-STD-020D)**

![](_page_27_Picture_162.jpeg)

#### <span id="page-27-1"></span>**Table 10. Lead-free process (from J-STD-020D)**

![](_page_27_Picture_163.jpeg)

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 16](#page-28-0).

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![](_page_28_Figure_3.jpeg)

<span id="page-28-0"></span>For further information on temperature profiles, refer to Application Note *AN10365 "Surface mount reflow soldering description"*.

# <span id="page-29-0"></span>**15. Revision history**

![](_page_29_Picture_71.jpeg)

#### **Table 11. Revision history**

# <span id="page-30-3"></span>**16. Legal information**

# <span id="page-30-4"></span>**16.1 Data sheet status**

![](_page_30_Picture_384.jpeg)

<span id="page-30-0"></span>[1] Please consult the most recently issued document before initiating or completing a design.

<span id="page-30-1"></span>[2] The term 'short data sheet' is explained in section "Definitions".

<span id="page-30-2"></span>The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status<br>information is available on the Internet a

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# <span id="page-31-1"></span>**17. Contact information**

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# <span id="page-32-0"></span>**18. Contents**

![](_page_32_Picture_199.jpeg)

**[17 Contact information . 32](#page-31-1) [18 Contents. 33](#page-32-0)**

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