

## Lithium Ion Charge Management IC with Integrated Switching Controller

### Features

- ▶ Safe charge of Li-Ion battery packs
- ▶ Pulse-width modulation control for current and voltage regulation
- ▶ Programmable high-side/low-side current-sense
- ▶ Fast charge terminated by selectable minimum current; safety backup termination at maximum time
- ▶ Pre-charge qualification detects shorted or damaged cells and conditions battery
- ▶ Charging continuously qualified by temperature and voltage limits
- ▶ Direct LED control outputs to display charge status and fault conditions

### General Description

The bq2954 Li-Ion Charge-Management IC uses a flexible pulse-width modulation regulator to control voltage and current during charging. The regulator frequency is set by an external capacitor for design flexibility. The switch-mode design minimizes power dissipation.

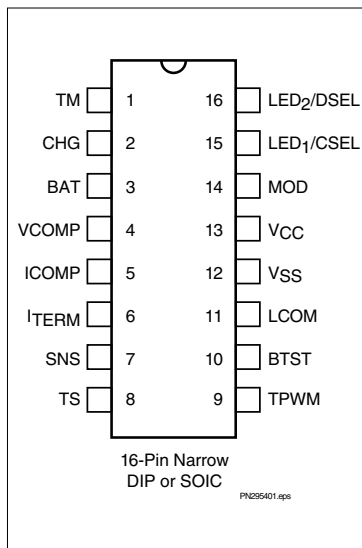
For safety, the bq2954 inhibits fast charging until the battery voltage and temperature are within configured limits. If the battery voltage is less than the low-voltage threshold, the bq2954 provides low-current conditioning of the battery.

For charge qualification, the bq2954 uses an external thermistor to measure battery temperature. Charging begins when power is applied or the battery is inserted.

The bq2954 charges a battery in two phases. First a constant-current phase replenishes approximately 70% of battery capacity. Then a voltage-regulation phase completes the battery charge.

The bq2954 provides status indications of all charger states and faults for accurate determination of the battery and charge-system conditions.

### Pin Connections



### Pin Names

TM	Time-out programming input	TPWM	Regulator timebase input
CHG	Charge active output	BTST	Battery test output
BAT	Battery voltage input	LCOM	Common LED output
VCOMP	Voltage loop comp input	VSS	System ground
ICOMP	Current loop comp input	VCC	5.0V±10% power
ITERM	Minimum current termination select input	MOD	Modulation control output
SNS	Sense resistor input	LED1/CSEL	Charge status output 1/ Charge sense select input
TS	Temperature sense input	LED2/DSEL	Charge status output 2/ Display select input

# bq2954

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## Pin Descriptions

<b>TM</b>	<b>Time-out programming input</b>  Sets the maximum charge time. The resistor and capacitor values are determined using Equation 5. Figure 10 shows the resistor/capacitor connection.	<b>TPWM</b>	<b>Regulation timebase input</b>  Uses an external timing capacitor to ground to set the pulse-width modulation (PWM) frequency. See Equation 7.
<b>CHG</b>	<b>Charge active output</b>  An open-drain output is driven low when the battery is removed, during a temperature pend, when a fault condition is present, or when charge is done. CHG can be used to disable a high-value load capacitor to detect quickly any battery removal.	<b>BTST</b>	<b>Battery test output</b>  Driven high in the absence of a battery in order to provide a potential at the battery terminal when no battery is present.
<b>BAT</b>	<b>Battery voltage input</b>  Sense input. This potential is generally developed using a high-impedance resistor divider network connected between the positive and the negative terminals of the battery. See Figures 6 and 7 and Equation 1.	<b>LCOM</b>	<b>Common LED output</b>  Common output for LED <sub>1-2</sub> . This output is in a high-impedance state during initialization to read programming input on DSEL and CSEL.
<b>VCOMP</b>	<b>Voltage loop compensation input</b>  Connects to an external R-C network to stabilize the regulated voltage.	<b>VSS</b>	<b>Ground</b>
<b>ICOMP</b>	<b>Current loop compensation input</b>  Connects to an external R-C network to stabilize the regulated current.	<b>VCC</b>	<b>VCC supply</b>  5.0V, ±10%
<b>ITERM</b>	<b>Charge full and minimum current termination select</b>  Three-state input is used to set I <sub>FULL</sub> and I <sub>MIN</sub> for fast charge termination. See Table 4.	<b>MOD</b>	<b>Current-switching control output</b>  Pulse-width modulated push/pull output used to control the charging current to the battery. MOD switches high to enable current flow and low to inhibit current flow. (The maximum duty cycle is 80%.)
<b>SNS</b>	<b>Charging current sense input</b>  Battery current is sensed via the voltage developed on this pin by an external sense-resistor.	<b>LED<sub>1</sub>-LED<sub>2</sub></b>	<b>Charger display status 1-2 outputs</b>  Drivers for the direct drive of the LED display. These outputs are tri-stated during initialization so that DSEL and CSEL can be read.
<b>TS</b>	<b>Temperature sense input</b>  Used to monitor battery temperature. An external resistor-divider network sets the lower and upper temperature thresholds. (See Figures 8 and 9 and Equations 3 and 4.)	<b>DSEL</b>	<b>Display select input (shared pin with LED<sub>2</sub>)</b>  Three-level input that controls the LED <sub>1-2</sub> charge display modes.
		<b>CSEL</b>	<b>Charge sense-select input (shared pin with LED<sub>1</sub>)</b>  Input that controls whether current is sensed on low side of battery or high side of battery. A current mirror is required for high-side sense.

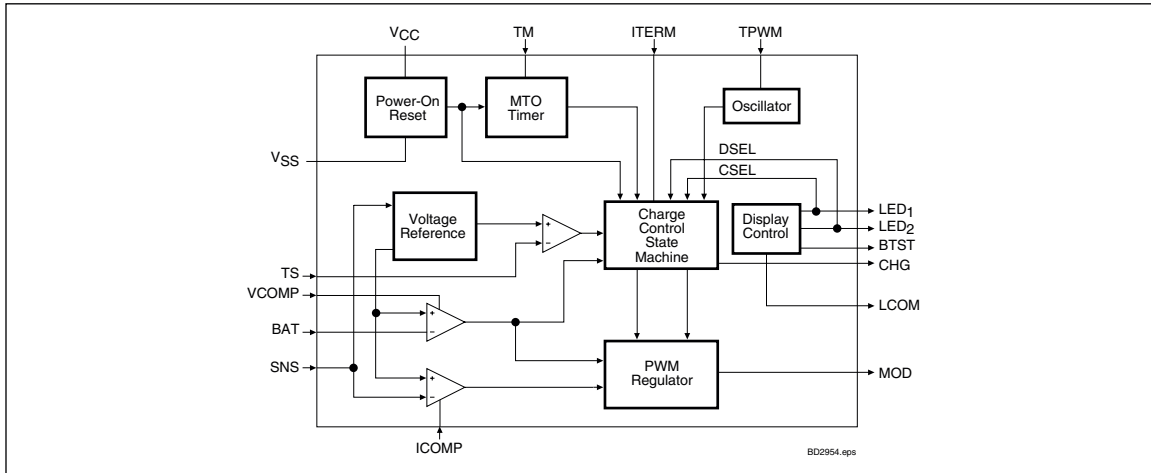


Figure 1. Functional Block Diagram

## Functional Description

The bq2954 functional operation is described in terms of the following (Figure 1):

- Charge algorithm
- Charge qualification
- Charge status display
- Configuring the display and termination
- Voltage and current monitoring
- Battery insertion and removal
- Temperature monitoring
- Maximum time-out
- Charge regulation
- Recharge after fast charge

## Charge Algorithm

The bq2954 uses a two-phase fast-charge algorithm. In phase 1, the bq2954 regulates constant current until the voltage on the BAT pin,  $V_{BAT}$ , rises to the internal threshold,  $V_{REG}$ . The bq2954 then transitions to phase 2 and regulates constant voltage ( $V_{BAT} = V_{REG}$ ) until the charging current falls below the programmed  $I_{MIN}$  threshold. Fast charge then terminates, and the bq2954 enters the Charge Complete state. (See Figure 2.)

## Charge Qualification

The bq2954 starts a charge cycle when power is applied while a battery is present or when a battery is inserted. Figure 2 shows the state diagram for the bq2954. The bq2954 first checks that the battery temperature is within the allowed, user-configurable range. If the temperature is out of range, the bq2954 remains in the QUALIFICATION state (S01) and waits until the battery temperature and voltage are within the allowed range.

If during any state of charge, a temperature excursion occurs HOT, the bq2954 proceeds to the DONE state (S04) and indicates this state on the LED outputs and provides no current. If this occurs, the bq2954 remains in the DONE state unless the following two conditions are met:

- Temperature falls within valid charge range
- $V_{BAT}$  falls below the internal threshold,  $V_{RCHG}$

If these two conditions are met, a new charge cycle begins. During any state of charge, if a temperature excursion occurs COLD, the bq2954 terminates charge and returns to the QUALIFICATION state (S01). Charge restarts if  $V_{BAT}$  and temperature are in valid range.

When the temperature and voltage are valid, the bq2954 enters the CONDITIONING state (S02) and regulates current to  $I_{COND} (=I_{MAX}/10)$ . After an initial holdoff period  $t_{HO}$  (which prevents the IC from reacting to transient voltage spikes that may occur when charge current is first applied), the IC begins monitoring  $V_{BAT}$ . If  $V_{BAT}$  does not rise to at least  $V_{MIN}$  before the expiration of

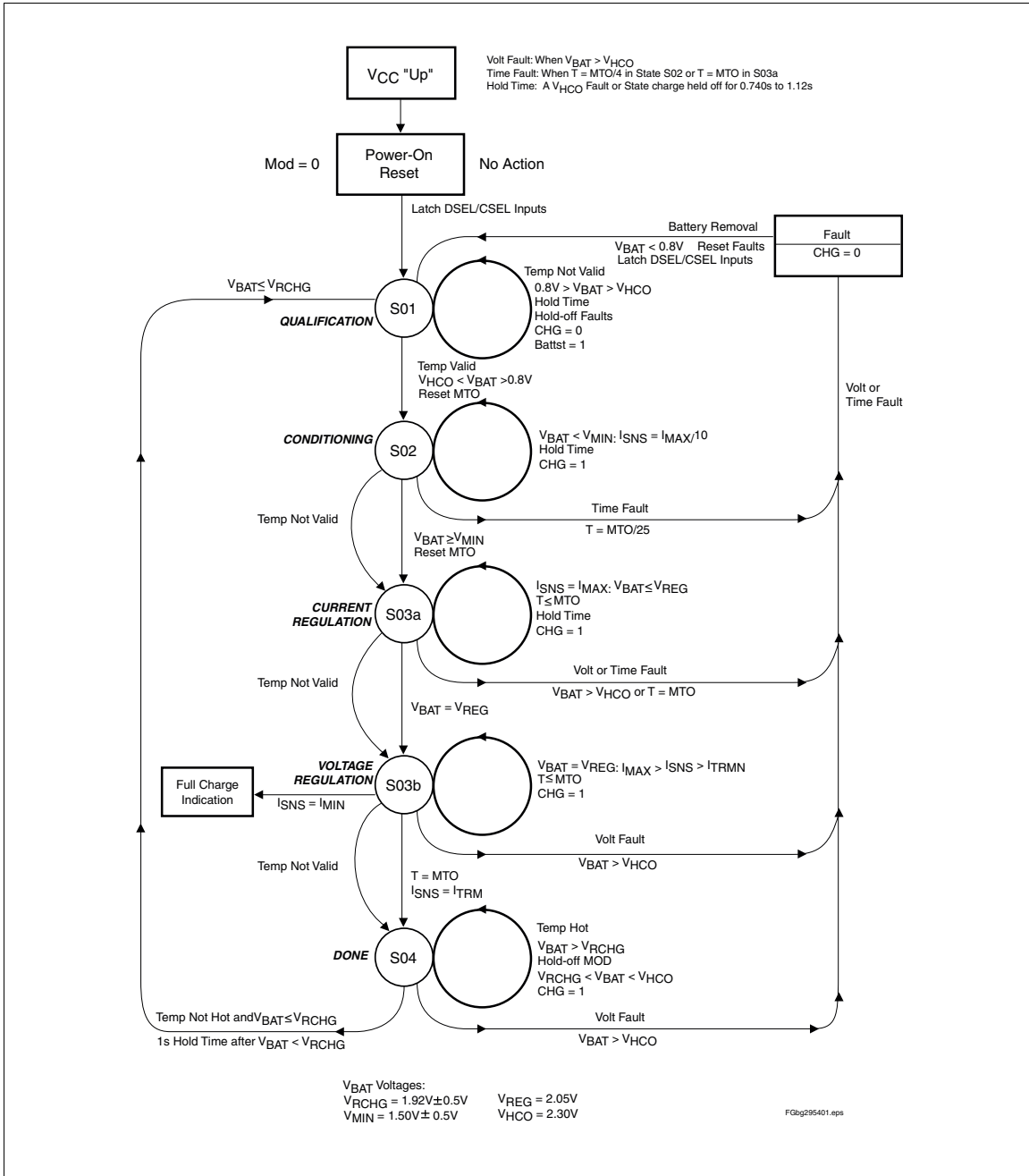


Figure 2. bq2954 Charge Algorithm

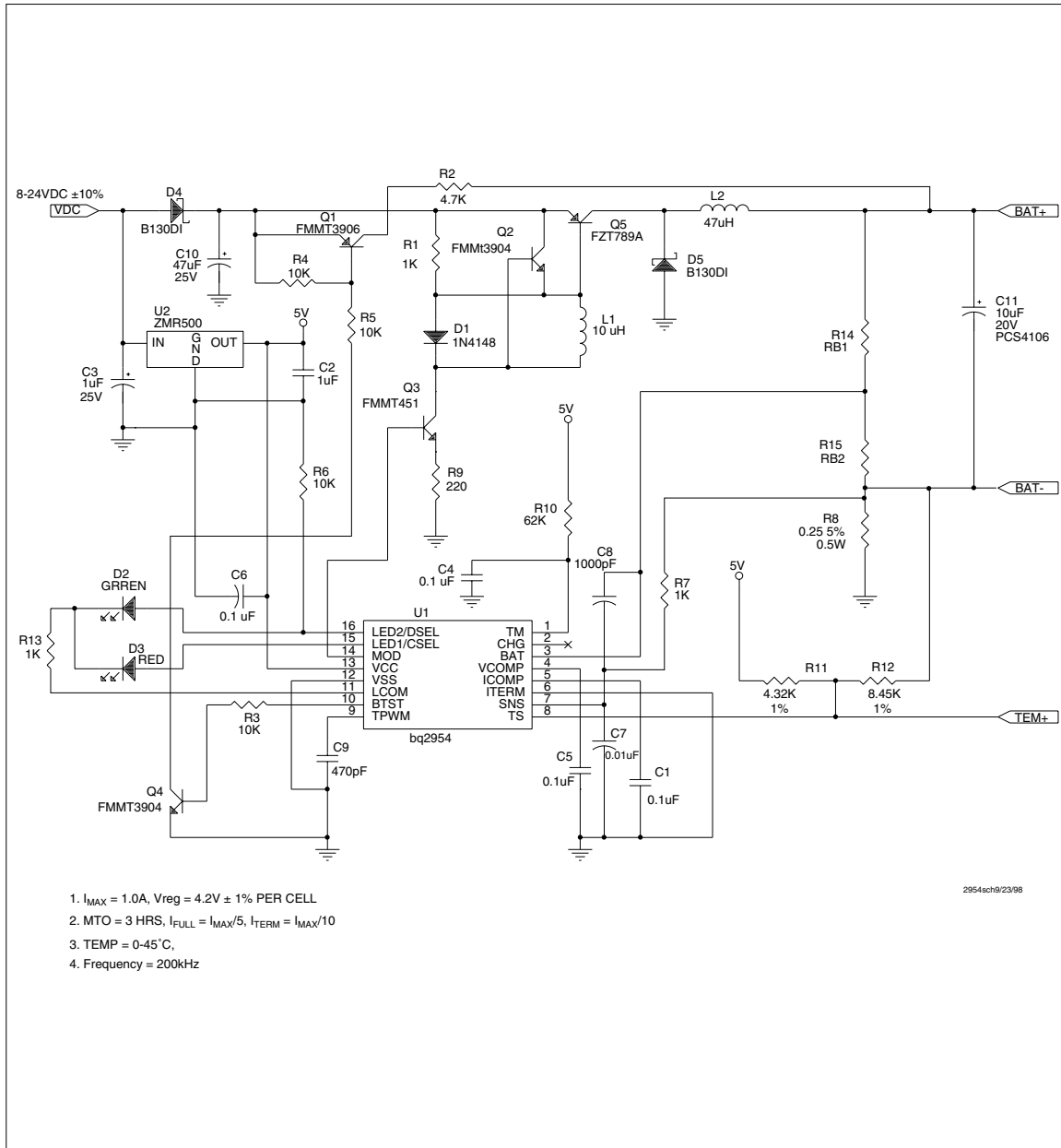
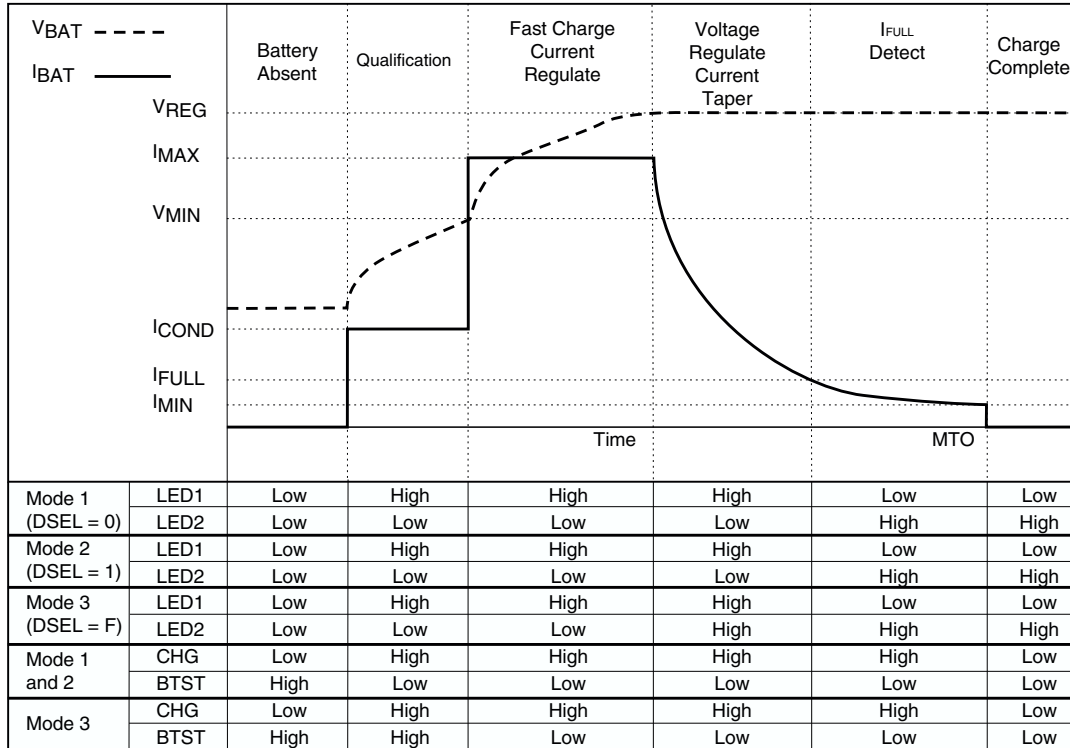


Figure 3. High-Efficiency Li-Ion Charger for 1-4 Cells

**Table 1. Normal Fast Charge Cycle**



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time-out limit  $t_{QT}$  (i.e., the battery has failed short), the bq2954 enters the Fault state. Then  $t_{QT}$  is set to 25% of  $t_{MTO}$ . If  $V_{MIN}$  is achieved before expiration of the time limit, the bq2954 begins fast charging.

Once in the Fault state, the bq2954 waits until  $V_{CC}$  is cycled or a new battery insertion is detected. It then starts a new charge cycle and begins the qualification process again.

**Charge Status Display**

Charge status is indicated by the LED driver outputs LED<sub>1</sub>–LED<sub>2</sub>. Three display modes (Tables 1– 3) are available in the bq2954 and are selected by configuring pin DSEL. Table 1 illustrates a normal fast charge cycle, Table 2 a recharge-after-fast-charge cycle, and Table 3 an abnormal condition.

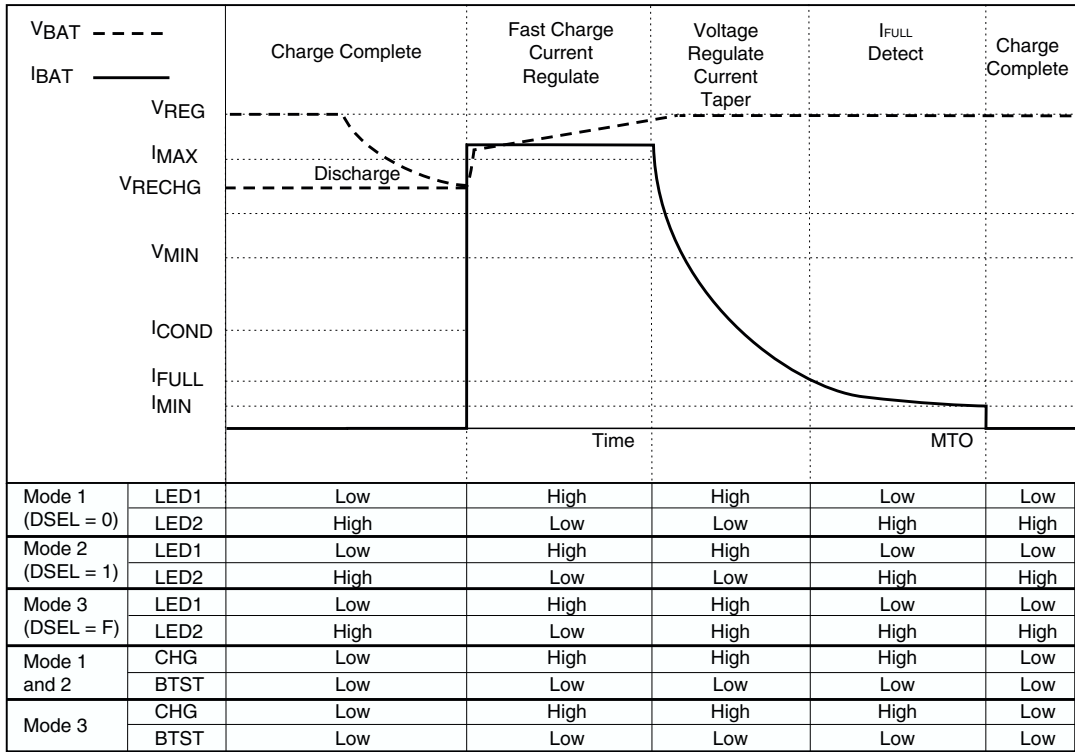
**Configuring the Display Mode,  $I_{FULL}/I_{MIN}$ , and  $I_{SENSE}$**

DSEL/LED<sub>2</sub> and CSEL/LED<sub>1</sub> are bi-directional pins with two functions: as LED driver pins (output) and as programming pins (input). The selection of pull-up, pull-down, or no-resistor programs the display mode on DSEL as shown in Tables 1 through 3. A pull-down or no-resistor programs the current-sense mode on CSEL.

The bq2954 latches the programming data sensed on the DSEL and CSEL input when  $V_{CC}$  rises to a valid level. The LEDs go blank for approximately 400ms (typical) while new programming data are latched.

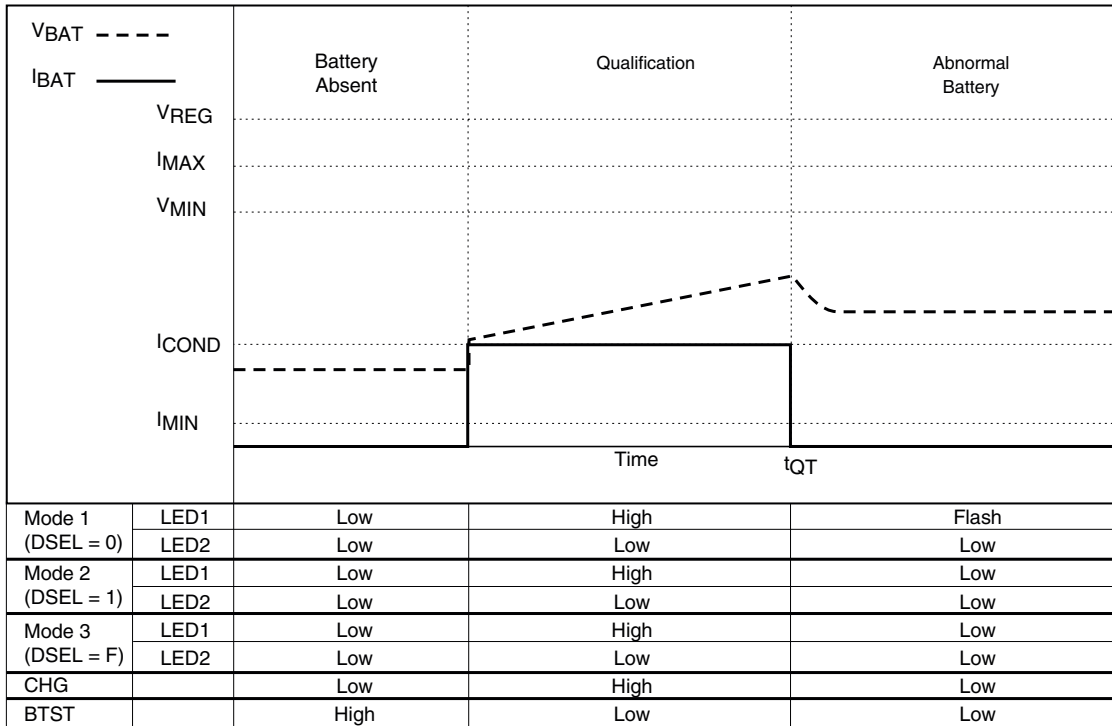
When fast charge reaches a condition where the charging current drops below  $I_{FULL}$ , the LED1 and LED2 outputs indicate a full-battery condition. Fast charge terminates when the charging current drops below the

**Table 2. Recharge After Fast Charge Cycle**



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**Table 3. Abnormal Condition**



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**Table 4. IFULL and IMIN Thresholds**

ITERM	IFULL	IMIN
0	IMAX/5	IMAX/10
1	IMAX/10	IMAX/15
Z	IMAX/15	IMAX/20



minimum current threshold,  $I_{MIN}$ . The  $I_{FULL}$  and  $I_{MIN}$  thresholds are programmed using the  $I_{TERM}$  input pin (See Table 4.)

Figures 4 and 5 show the bq2954 configured for display mode 2 and  $I_{FULL} = I_{MAX}/5$  while  $I_{MIN} = I_{MAX}/10$ .

## Voltage and Current Monitoring

In low-side current sensing, the bq2954 monitors the battery pack voltage as a differential voltage between BAT and pins. In high-side current sensing, the bq2954 monitors the battery pack voltage as a differential voltage between BAT and VSS pins. This voltage is derived by scaling the battery voltage with a voltage divider. (See Figures 6 and 7.) The resistance of the voltage divider must be high enough to minimize battery drain but low enough to minimize noise susceptibility.  $RB1 + RB2$  is typically between  $150k\Omega$  and  $1M\Omega$ . The voltage-divider resistors are calculated from the following:

$$\frac{RB1}{RB2} = \frac{N * V_{CELL}}{V_{REG}} - 1 \quad (1)$$

where

$V_{CELL}$  = Manufacturer-specified charging cell voltage  
 $N$  = Number of cells in series  
 $V_{REG} = 2.05V$

The current sense resistor,  $R_{SNS}$  (see Figures 6 and 7), determines the fast-charge current. The value of  $R_{SNS}$  is given by the following:

$$R_{SNS} = \frac{0.25V}{I_{MAX}} \quad (2)$$

where  $I_{MAX}$  is the current during the constant-current phase of the charge cycle. (See Table 1.)

## Battery Insertion and Removal

$V_{BAT}$  is interpreted by the bq2954 to detect the presence or absence of a battery. The bq2954 determines that a battery is present when  $V_{BAT}$  is between the High-Voltage Cutoff ( $V_{HCO} = V_{REG} + 0.25V$ ) and the Low-Voltage Cutoff ( $V_{LCO} = 0.8V$ ). When  $V_{BAT}$  is outside this range, the bq2954 determines that no battery is present and transitions to the battery test state, testing for valid battery voltage. The bq2954 detects battery removal when  $V_{BAT}$  falls below  $V_{LCO}$ . The  $BTST$  pin is driven high during battery test and can activate an external battery contact pull-up. This pull-up may be used to activate an over-discharged Li-Ion battery pack. The  $V_{HCO}$  limit implicitly serves as an over-voltage charge fault. The  $CHG$  output can be used to disconnect capacitors from the regulation circuitry in order to quickly detect a battery-removed condition.

Battery insertion is detected within 500ms. Transition to the fast-charge phase, however, will not occur for time  $t_{HO}$  (approximately one second), even if voltage qualification  $V_{MIN}$  is reached. This delay prevents a voltage spike at the BAT input from causing premature entry into the fast-charge phase. It also creates a delay in detection of battery removal if the battery is removed during this hold-off period.

## Temperature Monitoring

Temperature is measured as a *differential* voltage between TS and BAT-. This voltage is typically generated by a NTC (negative temperature coefficient) thermistor and thermistor linearization network. The bq2954 compares this voltage to its internal threshold voltages to determine if charging is allowed. These thresholds are the following:

- High-Temperature Cutoff Voltage:  $V_{TCO} = 0.4 * V_{CC}$   
This voltage corresponds to the maximum temperature (TCO) at which charging is allowed.
- High-Temperature Fault Voltage:  $V_{HTF} = 0.44 * V_{CC}$   
This voltage corresponds to the temperature (HTF) at which charging resumes after exceeding TCO.
- Low-Temperature Fault Voltage:  $V_{LTF} = 0.6 * V_{CC}$   
This voltage corresponds to the minimum temperature (LTF) at which charging is allowed.

Charging is inhibited if the temperature is outside the LTF—TCO window. Once the temperature exceeds TCO, it must drop below HTF before charging resumes.

RT1 and RT2 for the thermistor linearization network are determined as follows:

$$0.6 * V_{CC} = \frac{V}{1 + \frac{RT1 * (RT2 + R_{LTF})}{(RT2 * R_{LTF})}} \quad (3)$$

$$0.44 = \frac{1}{1 + \frac{RT1 * (RT2 + R_{HTF})}{(RT2 * R_{HTF})}} \quad (4)$$

where

$R_{LTF}$  = thermistor resistance at LTF

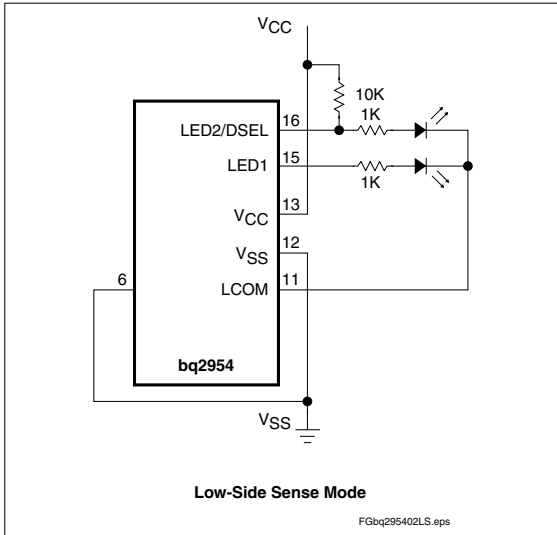
$R_{HTF}$  = thermistor resistance at HTF

$V = V_{CC} - 0.250$  in low-side current sensing

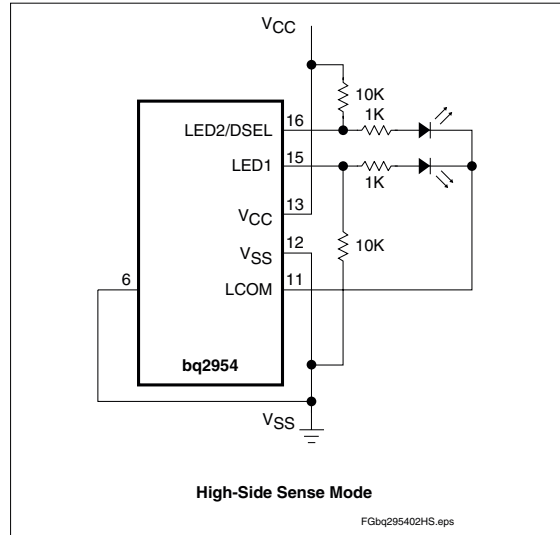
$V = V_{CC}$  in high-side current sensing

TCO is determined by the values of RT1 and RT2. 1% resistors are recommended.

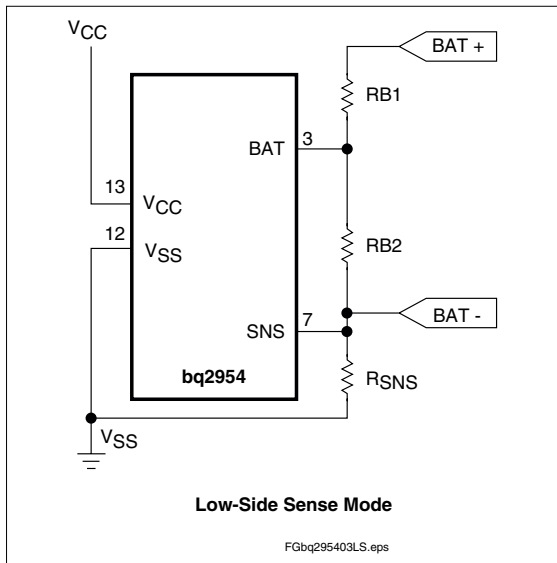
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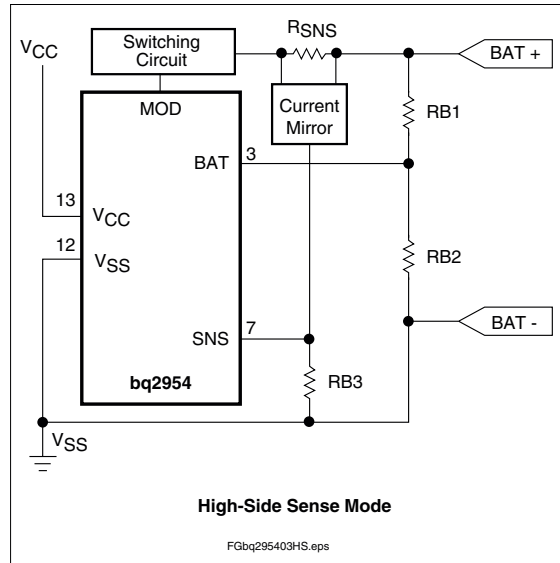
**Figure 4. Configured Display Mode (Low-Side Sense)**



**Figure 5. Configured Display Mode (High-Side Sense)**



**Figure 6. Configuring the Battery Divider (Low-Side Sense)**



**Figure 7. Configuring the Battery Divider (High-Side Sense)**

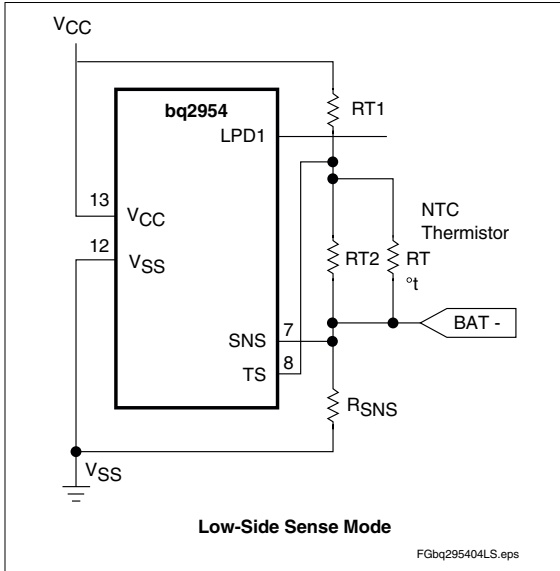


Figure 8. Low-Side Temperature Sensing

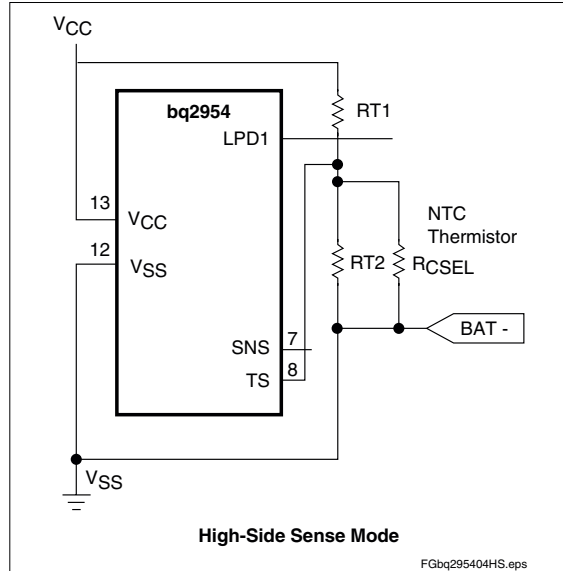


Figure 9. High-Side Temperature Sensing

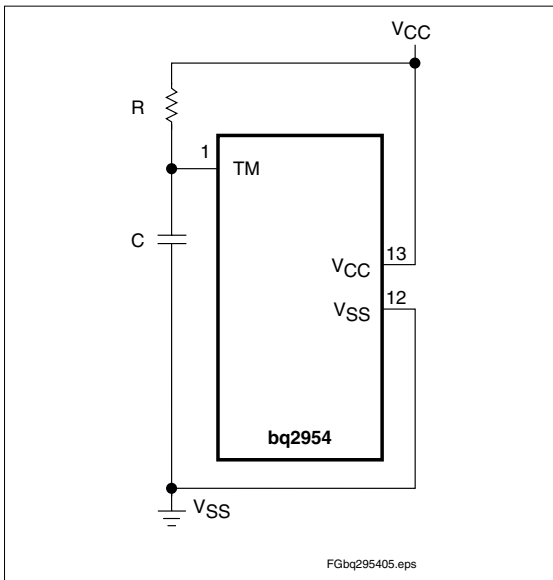


Figure 10. R-C Network/Setting MTO

### Disabling Temperature Sensing

Temperature sensing can be disabled by placing a 10kΩ resistor between TS and BAT- and a 10kΩ resistor between TS and VCC. See Figures 8 and 9.

### Maximum Time-Out

Maximum Time-Out period ( $t_{MTO}$ ) is programmed from 1 to 24 hours by an R-C network on the TM pin (see Figure 10) per the following equation:

$$t_{MTO} = 500 * R * C \tag{5}$$

where R is in ohms, C is in Farads, and  $t_{MTO}$  is in hours. The recommended value for C is 0.1μF.

The MTO timer is reset at the beginning of fast charge. If the MTO timer expires during the voltage regulation phase, fast charging terminates and the bq2954 enters the Charge Complete state. If the conditioning phase continues for time equal to  $t_{QT}$  ( $MTO/4$ ) and the battery potential does not reach  $V_{MIN}$ , the bq2954 enters the fault state and terminates charge. See Table 3. If the MTO timer expires during the current-regulation phase ( $V_{BAT}$  never reaches  $V_{REG}$ ), fast charging is terminated, and the bq2954 enters the fault state.

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### Charge Regulation

The bq2954 controls charging through pulse-width modulation of the MOD output pin, supporting both constant-current and constant-voltage regulation. Charge current is monitored at the SNS pin, and charge voltage is monitored at the BAT pin. These voltages are compared to an internal reference, and the MOD output is modulated to maintain the desired value. The maximum duty cycle is 80% .

Voltage at the SNS pin is determined by the value of resistor  $R_{SNS}$ , so nominal regulated current is set by the following equation:

$$I_{MAX} = V_{SNS} / R_{SNS} \quad (6)$$

The switching frequency of the MOD output is determined by an external capacitor ( $C_{PWM}$ ) between the pin TPWM and VSS pins, per the following:

$$f_{PWM} = \frac{1 * 10^{-4}}{C_{PWM}} \quad (7)$$

Where C is in Farads and the frequency is in Hz. A typical switching rate is 100kHz, implying  $C_{PWM} = 0.001\mu F$ . MOD pulse width is modulated between 0 and 80% of the switching period.

To prevent oscillation in the voltage and current control loops, frequency compensation networks (C and R-C respectively) are typically required on the VCOMP and ICOMP pins .

### Recharge After Fast Charge

Once charge completion occurs, a fast charge is initiated when the battery voltage falls below VRECHG threshold. A delay of approximately one second passes before recharge begins so that adequate time is allowed to detect battery removal. (See Table 1.)

## Absolute Maximum Ratings

Symbol	Parameter	Minimum	Maximum	Unit	Notes
V <sub>CC</sub>	V <sub>CC</sub> relative to V <sub>SS</sub>	-0.3	+7.0	V	
V <sub>T</sub>	DC voltage applied on any pin excluding V <sub>CC</sub> relative to V <sub>SS</sub>	-0.3	+7.0	V	
T <sub>OPR</sub>	Operating ambient temperature	-20	+70	°C	Commercial
		-40	+85	°C	Industrial "N"
T <sub>STG</sub>	Storage temperature	-55	+125	°C	
T <sub>SOLDER</sub>	Soldering temperature	-	+260	°C	10s max.

**Note:** Permanent device damage may occur if **Absolute Maximum Ratings** are exceeded. Functional operation should be limited to the Recommended DC Operating Conditions detailed in this data sheet. Exposure to conditions beyond the operational limits for extended periods of time may affect device reliability.

## DC Thresholds (T<sub>A</sub> = T<sub>OPR</sub>; V<sub>CC</sub> = 5V ± 10%)

Symbol	Parameter	Rating	Unit	Tolerance	Notes
V <sub>REG</sub>	Internal reference voltage	2.05	V	1%	TA = 25°C
	Temperature coefficient	-0.5	mV/°C	10%	
V <sub>LTF</sub>	TS maximum threshold	0.6 * V <sub>CC</sub>	V	±0.03V	Low-temperature fault
V <sub>HTF</sub>	TS hysteresis threshold	0.44 * V <sub>CC</sub>	V	±0.03V	High-temperature fault
V <sub>TCO</sub>	TS minimum threshold	0.4 * V <sub>CC</sub>	V	±0.03V	Temperature cutoff
V <sub>HCO</sub>	High cutoff voltage	V <sub>REG</sub> + 0.25V	V	±0.03V	
V <sub>MIN</sub>	Under-voltage threshold at BAT	1.5	V	±0.05V	
V <sub>RECHG</sub>	Recharge voltage threshold at BAT	1.92	V	±0.05V	
V <sub>LCO</sub>	Low cutoff voltage	0.8	V	±0.03V	
V <sub>SNS</sub>	Current sense at SNS	0.250	V	10%	I <sub>MAX</sub>
		0.025	V	10%	I <sub>COND</sub>

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### Recommended DC Operating Conditions ( $T_A = T_{OPR}$ )

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
V <sub>CC</sub>	Supply voltage	4.5	5.0	5.5	V	
V <sub>TEMP</sub>	TS voltage potential	0	-	V <sub>CC</sub>	V	V <sub>TS</sub> - V <sub>SNS</sub>
V <sub>BAT</sub>	BAT voltage potential	0	-	V <sub>CC</sub>	V	
I <sub>CC</sub>	Supply current	-	2	4	mA	Outputs unloaded
I <sub>IZ</sub>	DSEL tri-state open detection	-2	-	2	μA	Note
	ITERM tri-state open detection	-2	-	2	μA	
V <sub>IH</sub>	Logic input high	V <sub>CC</sub> - 0.3	-	-	V	DSEL, ITERM
V <sub>IL</sub>	Logic input low	-	-	V <sub>SS</sub> + 0.3	V	DSEL, CSEL, ITERM
V <sub>OH</sub>	LED <sub>1</sub> , LED <sub>2</sub> , BTST, output high	V <sub>CC</sub> - 0.8	-	-	V	I <sub>OH</sub> ≤ 10mA
	MOD output high	V <sub>CC</sub> - 0.8	-	-	V	I <sub>OH</sub> ≤ 10mA
V <sub>OL</sub>	LED <sub>1</sub> , LED <sub>2</sub> , BTST, output low	-	-	V <sub>SS</sub> + 0.8	V	I <sub>OL</sub> ≤ 10mA
	MOD output low	-	-	V <sub>SS</sub> + 0.8	V	I <sub>OL</sub> ≤ 10mA
	CHG output low	-	-	V <sub>SS</sub> + 0.8	V	I <sub>OL</sub> ≤ 5mA, Note 3
	LCOM output low	-	-	V <sub>SS</sub> + 0.5	V	I <sub>OL</sub> ≤ 30mA
I <sub>OH</sub>	LED <sub>1</sub> , LED <sub>2</sub> , BTST, source	-10	-	-	mA	V <sub>OH</sub> = V <sub>CC</sub> - 0.5V
	MOD source	-5.0	-	-	mA	V <sub>OH</sub> = V <sub>CC</sub> - 0.5V
I <sub>OL</sub>	LED <sub>1</sub> , LED <sub>2</sub> , BTST, sink	10	-	-	mA	V <sub>OL</sub> = V <sub>SS</sub> + 0.5V
	MOD sink	5	-	-	mA	V <sub>OL</sub> = V <sub>SS</sub> + 0.8V
	CHG sink	5	-	-	mA	V <sub>OL</sub> = V <sub>SS</sub> + 0.8V, Note 3
	LCOM sink	30	-	-	mA	V <sub>OL</sub> = V <sub>SS</sub> + 0.5V
I <sub>IL</sub>	DSEL logic input low source	-	-	+30	μA	V = V <sub>SS</sub> to V <sub>SS</sub> + 0.3V, Note 2
	ITERM logic input low source	-	-	+70	μA	V = V <sub>SS</sub> to V <sub>SS</sub> + 0.3V
I <sub>IH</sub>	DSEL logic input high source	-30	-	-	μA	V = V <sub>CC</sub> - 0.3V to V <sub>CC</sub>
	ITERM logic input high source	-70	-	-	μA	V = V <sub>CC</sub> - 0.3V to V <sub>CC</sub>

- Notes:**
1. All voltages relative to V<sub>SS</sub>.
  2. Conditions during initialization after V<sub>CC</sub> applied.
  3. SNS = 0V.

**Impedance** ( $T_A = T_{OPR}$ ;  $V_{CC} = 5V \pm 10\%$ )

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
R <sub>BATZ</sub>	BAT pin input impedance	50	-	-	MΩ	
R <sub>SNSZ</sub>	SNS pin input impedance	50	-	-	MΩ	
R <sub>TSZ</sub>	TS pin input impedance	50	-	-	MΩ	
R <sub>PROG1</sub>	Soft-programmed pull-up or pull-down resistor value (for programming)	-	-	10	kΩ	DSEL, CSEL
R <sub>PROG2</sub>	Pull-up or pull-down resistor value	-	-	3	kΩ	ITERM
R <sub>MTO</sub>	Charge timer resistor	20	-	480	kΩ	

**Timing** ( $T_A = T_{OPR}$ ;  $V_{CC} = 5V \pm 10\%$ )

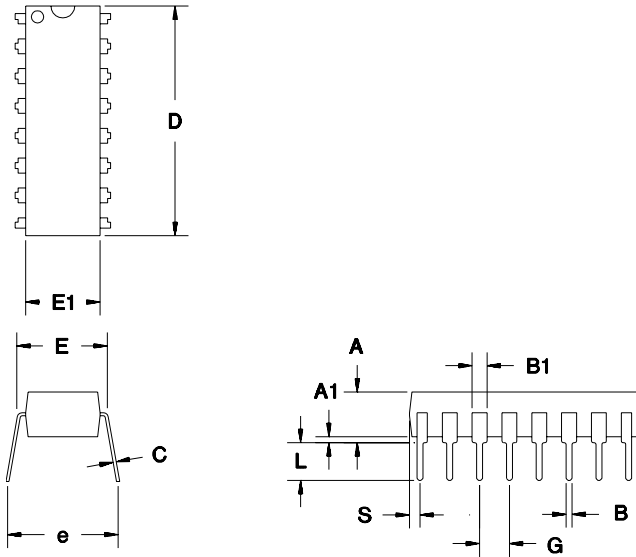
Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
t <sub>MTO</sub>	Charge time-out range	1	-	24	hours	See Figure 10
t <sub>QT</sub>	Pre-charge qual test time-out period	-	0.25 * t <sub>MTO</sub>	-	-	
t <sub>HO</sub>	Pre-charge qual test hold-off period	300	600	900	ms	
f <sub>PWM</sub>	PWM regulator frequency range	-	100	200	kHz	See Equation 7
d <sub>PWM</sub>	Duty cycle	0	-	80	%	

**Capacitance**

Symbol	Parameter	Minimum	Typical	Maximum	Unit
C <sub>MTO</sub>	Charge timer capacitor	-	-	0.1	μF
C <sub>PWM</sub>	PWM capacitor	-	0.001	-	μF

# bq2954

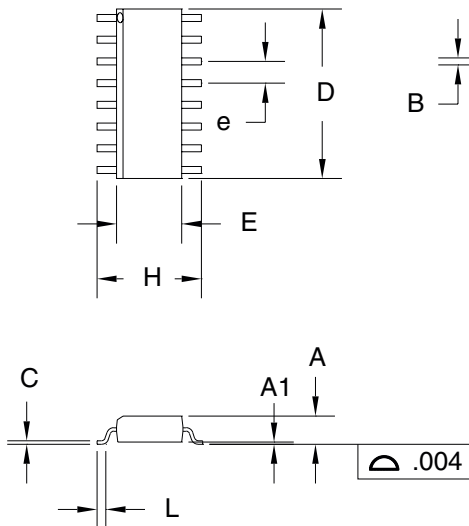
## 16-Pin DIP Narrow (PN)



### 16-Pin PN (0.300" DIP)

Dimension	Inches		Millimeters	
	Min.	Max.	Min.	Max.
A	0.160	0.180	4.06	4.57
A1	0.015	0.040	0.38	1.02
B	0.015	0.022	0.38	0.56
B1	0.055	0.065	1.40	1.65
C	0.008	0.013	0.20	0.33
D	0.740	0.770	18.80	19.56
E	0.300	0.325	7.62	8.26
E1	0.230	0.280	5.84	7.11
e	0.300	0.370	7.62	9.40
G	0.090	0.110	2.29	2.79
L	0.115	0.150	2.92	3.81
S	0.020	0.040	0.51	1.02

## 16-Pin SOIC Narrow (SN)



### 16-Pin SN (0.150" SOIC)

Dimension	Inches		Millimeters	
	Min.	Max.	Min.	Max.
A	0.060	0.070	1.52	1.78
A1	0.004	0.010	0.10	0.25
B	0.013	0.020	0.33	0.51
C	0.007	0.010	0.18	0.25
D	0.385	0.400	9.78	10.16
E	0.150	0.160	3.81	4.06
e	0.045	0.055	1.14	1.40
H	0.225	0.245	5.72	6.22
L	0.015	0.035	0.38	0.89



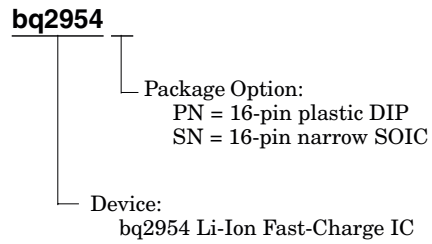
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### Data Sheet Revision History

Change No.	Page No.	Description of Change
1	All	“Final” changes from “Preliminary” version

**Note:** Change 1 = Oct. 1998 B changes from Nov. 1997 “Preliminary.”

### Ordering Information



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