



# AlphaBot2 robot building kit for Raspberry Pi Zero/Zero W (no Pi)

SKU 110060862

Description

**Note:** Raspberry Pi Zero/Zero W is NOT included.

This AlphaBot2 robot kit is designed to use with Raspberry Pi Zero/Zero W (not included). It features rich common robot functions including line tracking, obstacle avoiding, ultrasonic ranging, Bluetooth/infrared/Wi-Fi remote control (Bluetooth and Wi-Fi are Zero W specific), video monitoring, etc.

Thanks to the highly integrated modular design, it is fairly easy to assemble by a snap, no soldering, no wiring. After a few minutes spent on hardware assembled, you're almost there, our open source demo codes will ready to help you get started fast.

AlphaBot2 employs a 2-layer structure to provide excellent stability and compatibility.

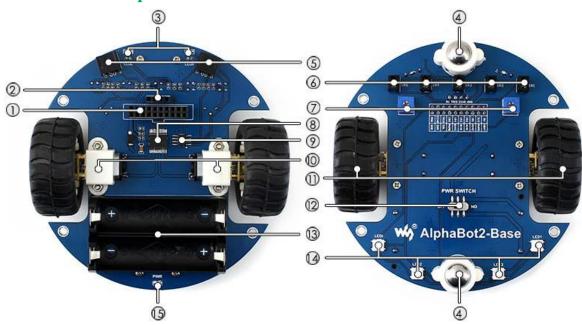
#### AlphaBot2-Base, the lower base chassis:

- •5-ch infrared sensor, analog output, combined with PID algorithm, stable line tracking
- •Onboard modules like line tracking, obstacle avoiding, needs no messy wiring
- •TB6612FNG dual H-bridge motor driver, compared with L298P, it's more efficient, more compact, and less heating
- •N20 micro gear motor, with metal gears, low noise, high accuracy
- •Onboard RGB LEDs, true color lighting, pretty cool

#### AlphaBot2-PiZero, the upper adapter board for controller:

- •LM2596 voltage regulator, provides the Pi with stable 5V power
- •TLC1543 AD acquisition chip, allows the Pi to use analog sensors
- •PCA9685 servo controller, make it more smoothly to rotate the pan head
- •CP2102 UART converter, easy for controlling the Pi via UART
- •USB HUB chip, more USB ports for devices like NIC

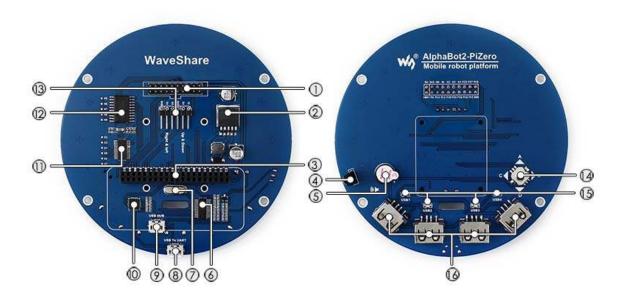
#### What's on the AlphaBot2-Base



- 1. AlphaBot2 control interface: for connecting sorts of controller adapter board
- 2.Ultrasonic module interface
- 3.**Obstacle avoiding indicators**
- 4.0mni-direction wheel
- 5.**ST188:**reflective infrared photoelectric sensor, for obstacle avoiding
- 6.**ITR20001/T:** reflective infrared photoelectric sensor, for line tracking
- 7.**Potentiometer** for adjusting obstacle avoiding range

- 8.**TB6612FNG** dual H-bridge motor driver
- 9.**LM393** voltage comparator
- 10.**N20 micro gear motor** reduction rate 1:30, 6V/600RPM
- 11. Rubber wheels diameter 42mm, width 19mm
- 12.Power switch
- 13. Battery holder: supports 14500 batteries
- 14.WS2812B: true color RGB LEDs
- 15.Power indicator

#### What's on the AlphaBot2-PiZero



- 1. AlphaBot2 control interface: for connecting AlphaBot2-Base
- 2.**LM2596:**5V voltage regulator
- 3. Raspberry Pi interface: for connecting Raspberry Pi Zero/Zero W
- 4.IR receiver
- 5.Buzzer
- 6.**FE1.1S:** USB HUB chip
- 7.12M crystal
- 8. **USB TO UART:** easy for controlling the Pi via UART
- 9.**USB HUB interface:** extends the USB port of Raspberry Pi Zero/Zero W
- 10.CP2102:USB TO UART converter
- 11.**PCA9685**:servo controller, make it more smoothly to rotate the pan head
- 12.**TLC1543:** 10-bit AD acquisition chip, allows the Pi to use analog sensors
- 13.Servo interface
- 14. USB indicators
- 15.**USB ports:** more USB capability

## Base board + Adapter board Compatible with multi controller boards



# Modular design, Easy installing without wiring







#### WiFi remote control

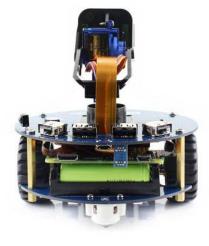
Via Webpage
Via Qt software on PC
Via Android APP
Supports routing, allows creating WiFi hotspot

### Video monitoring

5M pixels camera, 1080P
2-DOF pan and tilt
Hardware PWM servo, rotates smoothly



## Clever design, Proper layout, Stable structure



# Full functions, How to play, Up to you

Auto obstacle avoiding
Infrared obstacle avoiding
Easily get out of obstacles in the way





## Ultrasonic sensing

Ultrasonic ranging
Ultrasonic obstacle avoiding







#### **Technical Details**

| Dimensions | 220mm x 165mm x 70mm |
|------------|----------------------|
| Weight     | G.W 399g             |
| Battery    | Exclude              |

#### Part List

| AlphaBot2-PiZero (adapter board)  AlphaBot2-Base (base chassis)  1  RPi Camera (B)  Ultrasonic sensor  1  Micro SD Card 16GB  1  Power adapter US standard 5V/2.5A USB output  1  SG90 servo  2  2 DOF pan and tilt kit  1  IR remote controller  1  FC-20P cable 8cm  1  Micro USB connector | Part List                                    |   |
|---|--|---|
| RPi Camera (B) 1  Ultrasonic sensor 1  Micro SD Card 16GB 1  Power adapter US standard 5V/2.5A USB output 1  SG90 servo 2  2 DOF pan and tilt kit 1  IR remote controller 1  FC-20P cable 8cm 1   | AlphaBot2-PiZero (adapter board)             | 1 |
| Ultrasonic sensor 1  Micro SD Card 16GB 1  Power adapter US standard 5V/2.5A USB output 1  SG90 servo 2  2 DOF pan and tilt kit 1  IR remote controller 1  FC-20P cable 8cm 1   | AlphaBot2-Base (base chassis)                | 1 |
| Micro SD Card 16GB 1  Power adapter US standard 5V/2.5A USB output 1  SG90 servo 2  2 DOF pan and tilt kit 1  IR remote controller 1  FC-20P cable 8cm 1  | RPi Camera (B)                               | 1 |
| Power adapter US standard 5V/2.5A USB output 1  SG90 servo 2  2 DOF pan and tilt kit 1  IR remote controller 1  FC-20P cable 8cm 1  | Ultrasonic sensor                            | 1 |
| SG90 servo 2  2 DOF pan and tilt kit 1  IR remote controller 1  FC-20P cable 8cm 1  | Micro SD Card 16GB                           | 1 |
| 2 DOF pan and tilt kit  1  IR remote controller  1  FC-20P cable 8cm  1   | Power adapter US standard 5V/2.5A USB output | 1 |
| IR remote controller 1  FC-20P cable 8cm 1  | SG90 servo                                   | 2 |
| FC-20P cable 8cm 1  | 2 DOF pan and tilt kit                       | 1 |
|   | IR remote controller                         | 1 |
| Micro USB connector 1   | FC-20P cable 8cm                             | 1 |
|   | Micro USB connector                          | 1 |

| RPi Zero V1.3 Camera Cable 30cm       | 1 |
|---------------------------------------|---|
| USB type A plug to micro B plug cable | 1 |
| AlphaBot2-PiZero screws               | 1 |
| Screwdriver                           | 1 |
| Micro SD Card Reader                  | 1 |

| Package Contents         |  | Products                  |                  |                              |            |                                  |  |
|--------------------------|--|---------------------------|------------------|------------------------------|------------|----------------------------------|--|
| ltem                     | Description  | AlphaBot2-<br>Ar Acc Pack | AlphaBot2-<br>Ar | AlphaBot2-<br>Pi Acc<br>Pack | AlphaBot2- | AlphaBot2-<br>PiZero Acc<br>Pack |  |
| AlphaBot2-Base           | Motor driver, integrates sensors for obstacle avoiding, line tracking    | 4                         | V                | √                            | √          | √                                |  |
| AlphaBot2-Ar             | Adapter board, for connecting Arduino                                    | √                         | V                |                              |            |                                  |  |
| AlphaBot2-Pi             | Adapter board, for connecting RPi3 B                                     |                           |                  | √                            | √          |                                  |  |
| AlphaBot2-PiZero         | Adapter board, for connecting RPI<br>Zero W                              |                           |                  |                              |            | V                                |  |
| RPi3 B                   | Raspberry Pi 3 Model B   |                           |                  |                              | √.         |                                  |  |
| UNO PLUS                 | Enhanced Arduino compatible board  |                           | V                |                              |            |                                  |  |
| Dual-mode<br>Bluetooth   | Dual-mode Bluetooth module   |                           | V                |                              |            |                                  |  |
| Ultrasonic sensor        | Ultrasonic obstacle avoiding, ranging                                    | √                         | V                |                              |            | <b>V</b>                         |  |
| IR remote controller     | remotely control the robot   | √                         | V                | V                            | V          | V                                |  |
| RPi Camera (B)           | Raspberry Pi camera, adjustable focus                                    |                           |                  | 1                            | √          | V                                |  |
| SG90                     | Servo, working with the pan head, controlling the rotation of the camera |                           |                  | √                            | V          | <b>V</b>                         |  |
| Micro SD Card 16GB       | 16GB Miro SD Card, class 10  |                           |                  | √                            | √          | V                                |  |
| 5V 2.5A Power<br>Adapter | RPi3 B requires 2.5A or above power supply                               |                           |                  | 4                            | 4          | 4                                |  |

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