



### **General Description**

The MAX6870/MAX6871 EEPROM-configurable, multivoltage supply sequencers/supervisors monitor several voltage detector inputs, two auxiliary inputs, and four general-purpose logic inputs. The MAX6870/MAX6871 feature programmable outputs for highly configurable power-supply sequencing applications. The MAX6870 features six voltage detector inputs and eight programmable outputs, while the MAX6871 features four voltage detector inputs and five programmable outputs. Manual reset and margin disable inputs offer additional flexibility.

All voltage detectors offer two configurable thresholds for undervoltage/overvoltage or dual undervoltage detection. One high voltage input (IN1) provides detector threshold voltages from +2.5V to +13.2V in 50mV increments, or from +1.25V to +7.625V in 25mV increments. A bipolar input (IN2) provides detector threshold voltages from ±2.5V to ±15.25V in 50mV increments, or from ±1.25V to ±7.625V in 25mV increments. Positive inputs (IN3-IN6) provide detector threshold voltages from +1V to +5.5V in 20mV increments, or from +0.5V to +3.05V in 10mV increments.

Programmable output stages control power-supply sequencing or system resets/interrupts. Programmable output options include: active-high, active-low, opendrain, weak pullup, push-pull, and charge pump. Programmable timing delay blocks configure each output to wait between 25µs and 1600ms before deasserting. A fault register logs the condition that caused each output to assert (undervoltage, overvoltage, manual reset, etc.).

An internal 10-bit ADC monitors the voltage detector inputs, and two auxiliary inputs through a multiplexer that automatically sequences through all inputs every 200ms. A SMBus<sup>TM</sup>-/l<sup>2</sup>C<sup>T</sup>-compatible, serial data interface programs and communicates with the configuration EEPROM, the configuration registers, the internal 4kb user EEPROM, the ADC registers, and the fault registers of the MAX6870/MAX6871.

The MAX6870/MAX6871 are available in a 7mm x 7mm x 0.8mm 32-pin thin QFN package and operate over the extended -40°C to +85°C temperature range.

## **Applications**

Telecommunications/Central Office Systems Networking Systems Servers/Workstations Basestations Storage Equipment Multimicroprocessor/Voltage Systems

Pin Configurations, Typical Operating Circuit, and Selector Guide appear at end of data sheet.

**Features** 

- ♦ Six (MAX6870) or Four (MAX6871) Configurable **Input Voltage Detectors** 
  - One High Voltage Input (+1.25V to +7.625V or +2.5V to +13.2V Thresholds)
  - One Bipolar Voltage Input (±1.25V to ±7.625V or ±2.5V to ±15.25V Thresholds)
  - Four (MAX6870) or Two (MAX6871) Positive Voltage Inputs (+0.5V to +3.05V or +1V to +5.5V Thresholds)
- **♦** Four General-Purpose Logic Inputs
- **♦ Two Configurable Watchdog Timers**
- ♦ Eight (MAX6870) or Five (MAX6871) **Programmable Outputs** Active-High, Active-Low, Open-Drain, Weak Pullup, Push-Pull, Charge-Pump Timing Delays from 25µs to 1600ms
- ♦ 10-Bit Internal ADC Monitors the Input Voltage **Detectors and Two Auxiliary Inputs**
- **♦** Margining Disable and Manual Reset Controls
- ♦ Internal 1.25V Reference or External Reference Input
- ♦ 4kb Internal User EEPROM Endurance: 100,000 Erase/Write Cycles **Data Retention: 10 Years**
- **♦ I<sup>2</sup>C/SMBus-Compatible Serial Configuration/Communication Interface**
- ♦ ±1% Threshold Accuracy

## **Ordering Information**

| PART       | TEMP RANGE     | PIN-<br>PACKAGE | PKG<br>CODE |
|------------|----------------|-----------------|-------------|
| MAX6870ETJ | -40°C to +85°C | 32 Thin QFN     | T3277-2     |
| MAX6871ETJ | -40°C to +85°C | 32 Thin QFN     | T3277-2     |

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#### **ABSOLUTE MAXIMUM RATINGS**

All Voltages referenced to GND
IN3-IN6, ABP, SDA, SCL, A0, A1,
GPI1-GPI4, MR, MARGIN, PO5-PO8
(MAX6870), PO3/PO4/PO5 (MAX6871)...-0.3V to +6V
IN1, PO1-PO4 (MAX6870), PO1/PO2 (MAX6871)...-0.3V to +14V
IN2...-20V to +20V
DBP, AUXIN1, AUXIN2, REFIN...-0.3V to +3V
Input/Output Current (all pins)....±20mA

| Continuous Power Dissipation ( $T_A = +70^{\circ}C$ ) |        |
|---|--------|
| 32-Pin 7mm x 7mm Thin QFN                             |        |
| (derate 33.3mW/°C above +70°C)                        | 2667mW |
| Operating Temperature Range                           |        |
| Maximum Junction Temperature                          | +150°C |
| Storage Temperature Range                             |        |
| Lead Temperature (soldering, 10s)                     | +300°C |
|   |        |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{IN1} = +6.5V \text{ to } +13.2V, V_{IN2} = +10V, V_{IN3} \text{ to } V_{IN6} = +2.7V \text{ to } +5.5V, \text{AUXIN}\_ = \text{GPI}\_ = \text{GND}, \overline{\text{MARGIN}} = \overline{\text{MR}} = \text{DBP}, T_A = -40^{\circ}\text{C} \text{ to } +85^{\circ}\text{C}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}\text{C}$ .) (Notes 1 and 2)

| PARAMETER                                      | SYMBOL                                  | COND   | ITIONS  | MIN    | TYP | MAX    | UNITS             |
|--|---|--|---|--------|-----|--------|-------------------|
| Operating Voltage Range                        | V <sub>IN1</sub>                        | Voltage on IN1 to ensure the device is fully operational, IN3 to IN6 = GND |   | 4.0    |     | 13.2   | V                 |
| (Note 3)                                       | V <sub>IN3</sub> to<br>V <sub>IN6</sub> |  | Voltage on any one of IN3 to IN6 to ensure the device is fully operational, IN1 = GND |        |     | 5.5    | V                 |
| IN1 Supply Voltage<br>(Note 3)                 | V <sub>IN1P</sub>                       | Minimum voltage on IN device is powered thro                               | I1 to guarantee that the bugh IN1   |        |     | 6.5    | V                 |
| Undervoltage Lockout                           | V <sub>UVLO</sub>                       | Minimum voltage on or guarantee the device is                              | ne of IN3 to IN6 to<br>s EEPROM configured.   |        |     | 2.5    | V                 |
|  |   | $V_{IN1} = +13.2V$ , IN2 to I  | N6 = GND, no load   |        | 1.2 | 1.5    |                   |
| Supply Current                                 | Icc                                     | Writing to configuration no load   | registers or EEPROM,  |        | 1.3 | 2      | mA                |
|  |   | V <sub>IN1</sub> (50mV increments)   |   | 2.5    |     | 13.2   |                   |
|  |   | V <sub>IN1</sub> (25mV increments)   |   | 1.250  |     | 7.625  | V                 |
| Threshold Range                                | V <sub>TH</sub>                         | V <sub>IN2</sub> (50mV increments)   |   | ±2.50  |     | ±15.25 |                   |
| Threshold Harige                               | VIH                                     | V <sub>IN2</sub> (25mV increments)   |   | ±1.250 |     | ±7.625 |                   |
|  |   | V <sub>IN3</sub> to V <sub>IN6</sub> (20mV increments)                     |   | 1.0    |     | 5.5    |                   |
|  |   | V <sub>IN3</sub> to V <sub>IN6</sub> (10mV increments)                     |   | 0.50   |     | 3.05   |                   |
|  |   | IN1 to IN6 positive,   | $T_A = +25^{\circ}C$  | -1.0   |     | +1.0   |                   |
|  |   | V <sub>IN</sub> _ falling  | $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$   | -1.5   |     | +1.5   | <u></u> %         |
| Threshold Accuracy                             |   | $-15.25V \le V_{1N2} \le -5V$ ,  | $T_A = +25^{\circ}C$  | -1.5   |     | +1.5   | /                 |
| Throughout Alebaraey                           | ļ                                       | V <sub>IN2</sub> falling   | $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$   | -2     |     | +2     |                   |
|  |   | $-5V \le V_{1N2} \le 0, V_{1N2}$   | $T_A = +25^{\circ}C$  | -75    |     | +75    | mV                |
|  |   | falling  | $T_A = -40^{\circ}C \text{ to } +85^{\circ}C$   | -100   |     | +100   |                   |
| Threshold Hysteresis                           | V <sub>TH-H</sub> yst                   |  |   |        | 0.3 |        | % V <sub>TH</sub> |
| Reset Threshold Temperature<br>Coefficient     | ΔV <sub>TH</sub> /°C                    |  |   |        | 10  |        | ppm/<br>°C        |
| Threshold-Voltage Differential<br>Nonlinearity | V <sub>TH</sub> DNL                     |  |   | -1     |     | +1     | LSB               |

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## **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{IN1} = +6.5V \text{ to } +13.2V, V_{IN2} = +10V, V_{IN3} \text{ to } V_{IN6} = +2.7V \text{ to } +5.5V, \text{AUXIN}\_ = \text{GPI}\_ = \text{GND}, \overline{\text{MARGIN}} = \overline{\text{MR}} = \text{DBP}, T_A = -40^{\circ}\text{C}$  to +85°C, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}\text{C}$ .) (Notes 1 and 2)

| PARAMETER  | SYMBOL                                  | CON   | CONDITIONS   |                            | TYP    | MAX   | UNITS |
|--|---|---|--|----------------------------|--------|-------|-------|
| IN1 Input Leakage Current  | I <sub>LIN1</sub>                       | For V <sub>IN1</sub> < the highe  | est of V <sub>IN3</sub> to V <sub>IN6</sub>  |                            | 100    | 140   | μΑ    |
| IN2 Input Impedance  | R <sub>IN2</sub>                        |   |  | 160                        | 230    | 320   | kΩ    |
| IN3 to IN6 Input Impedance   | R <sub>IN3</sub> to<br>R <sub>IN6</sub> | V <sub>IN1</sub> > 6.5V   | V <sub>IN1</sub> > 6.5V  |                            | 100    | 145   | kΩ    |
| Power-Up Delay   | tpu                                     | V <sub>ABP</sub> ≥ V <sub>U</sub> V <sub>L</sub> O  |  |                            |        | 3.5   | ms    |
| IN_ to PO_ Delay   | tDPO                                    | V <sub>IN</sub> _ falling or rising,  | 100mV overdrive  |                            | 25     |       | μs    |
|  |   |   | 000  |                            | 25     |       | μs    |
|  |   |   | 001  | 1.406                      | 1.5625 | 1.719 |       |
|  |   |   | 010  | 5.625                      | 6.25   | 6.875 |       |
| DO Time out Deviced  |   | Register contents   | 011  | 22.5                       | 25     | 27.5  |       |
| PO_ Timeout Period   | t <sub>RP</sub>                         | (Table 25)  | 100  | 45                         | 50     | 55    | ms    |
|  |   |   | 101  | 180                        | 200    | 220   |       |
|  |   |   | 110  | 360                        | 400    | 440   |       |
|  |   |   | 111  | 1440                       | 1600   | 1760  |       |
| PO1-PO4 (MAX6870), PO1/PO2   |   | V <sub>ABP</sub> ≥ +2.5V, I <sub>SINK</sub>   | = 500µA  |                            |        | 0.3   |       |
| (MAX6871) Output Low (Note 3)  | V <sub>OL</sub>                         | V <sub>ABP</sub> ≥ +4.0V, I <sub>SINK</sub>   | = 2mA  |                            |        | 0.4   | V     |
| PO5-PO8 (MAX6870), PO3/PO4/  |   | V <sub>ABP</sub> ≥ +2.5V, I <sub>SINK</sub> = 1mA   |  |                            |        | 0.3   |       |
| PO5 (MAX6871) Output Low (Note 3)  | V <sub>OL</sub>                         | V <sub>ABP</sub> ≥ +4.0V, I <sub>SINK</sub>   | = 4mA  | İ                          |        | 0.4   | V     |
| PO1-PO8 Output Initial Pulldown<br>Current   | I <sub>PD</sub>                         | V <sub>ABP</sub> ≤ V <sub>UVLO</sub> , V <sub>PO</sub> _  | = 0.8V   |                            | 10     | 40    | μΑ    |
| PO1–PO8 Output Open-Drain<br>Leakage Current   | I <sub>LKG</sub>                        | Output high impedar   | nce  | -1                         |        | +1    | μΑ    |
| PO1-PO8 Output Pullup<br>Resistance, Weak Pullup Selected                                | R <sub>PU</sub>                         | V <sub>PO</sub> _ = 2V  |  | 6.6                        | 10     | 15.0  | kΩ    |
| PO1–PO4 (MAX6870), PO1/PO2<br>(MAX6871) Turn-On Time, Charge<br>Pump Selected (Note 4)   | ton                                     | C <sub>PO</sub> _ = 1500pF, V <sub>AB</sub><br>V <sub>PO</sub> _ = +7.8V  | BP = +3.3V,  | 0.5                        | 1.5    | 3.0   | ms    |
| PO1–PO4 (MAX6870), PO1/PO2<br>(MAX6871) Turn-Off Time, Charge<br>Pump Selected           | toff                                    | C <sub>PO</sub> _ = 1500pF, V <sub>AB</sub><br>V <sub>PO</sub> _ = +0.5V  | C <sub>PO</sub> _ = 1500pF, V <sub>ABP</sub> = +3.3V,<br>V <sub>PO</sub> _ = +0.5V |                            | 30     |       | μs    |
| PO1-PO4 (MAX6870), PO1/PO2   |   | With respect to VABP  | p, I <sub>PO</sub> < 100nA   |                            | 5.5    |       |       |
| (MAX6871) Output High,<br>Charge Pump Selected (Notes 3, 4)                              | VOHCP                                   | With respect to VABP, IPO_ < 1µA  |  | 4.0                        | 5.0    | 6.0   | V     |
|  |   | Any one of V <sub>IN3</sub> to V <sub>IN6</sub> ≥ +2.7V, I <sub>SOURCE</sub> = 10mA, output pulled up to the same IN_ |  | 1.5                        |        |       |       |
| PO5-PO8 (MAX6870), PO3/PO4/<br>PO5 (MAX6871) Output High,<br>Push-Pull Selected (Note 3) | Vон                                     | Any one of V <sub>IN3</sub> to V <sub>I</sub><br>1mA, output pulled u   | IN6 ≥ +2.7V, ISOURCE = up to the same IN_  | 0.8 x<br>V <sub>IN</sub> _ |        |       | V     |
| T don't un dolocioù (Note d)   |   | Any one of $V_{IN3}$ to $V_{IN6} \ge +4.5V$ , $I_{SOURCE} = 2mA$ , output pulled up to the same $IN_{\perp}$          |  | 0.8 x<br>V <sub>IN</sub> _ |        |       |       |

## **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{IN1} = +6.5V \text{ to } +13.2V, V_{IN2} = +10V, V_{IN3} \text{ to } V_{IN6} = +2.7V \text{ to } +5.5V, \text{AUXIN}\_ = \text{GPI}\_ = \text{GND}, \overline{\text{MARGIN}} = \overline{\text{MR}} = \text{DBP}, T_A = -40^{\circ}\text{C}$  to +85°C, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}\text{C}$ .) (Notes 1 and 2)

| MR Input Pulse Width   MR   MR   MR   MR   MR   MR   MR   M  | PARAMETER                                 | SYMBOL             | CONDI                       | TIONS  | MIN   | TYP    | MAX    | UNITS |  |
|--|---|--------------------|-----------------------------|--|-------|--------|--------|-------|--|
| MR Input Pulse Width   Mg  | MP MARCIN CRI Input Voltage               | $V_{IL}$           |                             |  |       |        | 0.8    | \/    |  |
| MR Gitch Rejection   MR to VPO_Delay   1DMR   VMR = +1.4V   5   10   15   μA   MR to VPO_P Pullup Current   MMR file M VMR = +1.4V   5   10   15   μA   MR file M VPO_P Pullup Current   MMRGIN   VMRAGIN    | MR, MARGIN, GPI_ Input voltage            | VIH                |                             |  | 1.4   |        |        | \ \   |  |
| MR to PO_ Delay   MR   MR   VMR = +1.4V   5   10   15  | MR Input Pulse Width                      | t <sub>MR</sub>    |                             |  | 1     |        |        | μs    |  |
| MR to VDBP Pullup Current   IMR   VMR = +1.4V   5   10   15   μA   MARGIN to VDBP Pullup Current   IMARGIN   VMARGIN = +1.4V   5   10   15   μA   μA   MARGIN to VDBP Pullup Current   IDBPL   VBPL = +0.8V   5   10   15   μA   Margin   VBPL = +0.8V   VBPL = +0.8V   5   10   15   μA   Margin   VBPL = +0.8V   V   | MR Glitch Rejection                       |                    |                             |  |       | 100    |        | ns    |  |
| MARGIN to VDBP Pullup Current   MARGIN   VMARGIN = 1.4V   5   10   15   μA   10   15   μA   10   10   15   μA   10   10   10   10   15   μA   10   10   10   10   10   10   10   1   | MR to PO_ Delay                           | t <sub>DMR</sub>   |                             |  |       | 2      |        | μs    |  |
| GPI_ to PO_ Delay         toGPI_ squade         togAl to the politic   | MR to V <sub>DBP</sub> Pullup Current     | I <sub>MR</sub>    | V <u>MR</u> = +1.4V         |  | 5     | 10     | 15     | μΑ    |  |
| GPL   Pulldown Current   IGPL   VGPL = +0.8V   5   10   15   pA  | MARGIN to V <sub>DBP</sub> Pullup Current | IMARGIN            | VMARGIN = +1.4V             |  | 5     | 10     | 15     | μΑ    |  |
| Watchdog Input Pulse Width   two   GP   configured as a watchdog input   50  | GPI_ to PO_ Delay                         | tDGPI_             |                             |  |       | 200    |        | ns    |  |
| Watchdog Timeout Period         No         5.625 (6.25 (6.25 (27.5)) (2  | GPI_ Pulldown Current                     | I <sub>GPI</sub> _ | V <sub>GPI_</sub> = +0.8V   |  | 5     | 10     | 15     | μΑ    |  |
| Heat the part of | Watchdog Input Pulse Width                | twDI               | GPI_ configured as a w      | atchdog input                                    | 50    |        |        | ns    |  |
| Watchdog Timeout Period         HVD         Register Contents (Table 28)         010         90         100         440         440           HVD         401         360         400         440         400         440         400         400         440         400 </td <td></td> <td></td> <td></td> <td>000</td> <td>5.625</td> <td>6.25</td> <td>6.875</td> <td></td>  |   |                    |                             | 000  | 5.625 | 6.25   | 6.875  |       |  |
| Watchdog Timeout Period         Name of the priod                                 |   |                    |                             | 001  | 22.5  | 25     | 27.5   |       |  |
| Watchdog Timeout Period         Name of Table 28)         Table 28)         100         1.44         1.60         1.76         4         1.76         4         1.76         1.76         6.40         7.04         7.04         8         8         8         8         8         110         5.76         6.40         7.04         7.04         8         8         8         110         23.04         25.60         28.16         7         9         110         23.04         25.60         28.16         7         9         111         92.16         102.40         112.64         12.25         1.25  |   |                    |                             | 010  | 90    | 100    | 110    | ms    |  |
| Mathematical Parameters   Mathematical P   | Watah dag Tipaggut Dagia d                | twD                | Register Contents           | 011  | 360   | 400    | 440    |       |  |
| Page    | watchdog Timeout Period                   |                    | (Table 28)                  | 100  | 1.44  | 1.60   | 1.76   |       |  |
| Reference Input Voltage Range   VREFIN   1111   92.16   102.40   112.64     Reference Input Voltage Range   VREFIN   VREFIN   1.25V   1.25   1.25   1.275   V     Reference Input Resistance   RREFIN   VREFIN = +1.25V   0   1.225   1.25   1.275   V     Reference Input Resistance   RREFIN   VREFIN = +1.25V   0   1.225   1.25   1.275   V     Reference Input Resistance   RREFIN   VREFIN = +1.25V   0   1.225   1.25   V     Reference Input Resistance   RREFIN   VREFIN = +1.25V   0   1.225   1.25   V     IN1, LSB = 18.3mV   0   1.22   1.25   1.25   V     IN2, LSB = 9.16mV   0   1.22   1.25   V     IN3 to IN6, LSB = 7.32mV   0   1.249   1.249     IN1 to IN6 positive   1.249   1.249   1.249     IN1 to IN6 positive   1.249   1.249   1.249     ADC Total Unadjusted Error (Note 5)   1.249   1.249     ADC Differential Nonlinearity   DNL   (Note 7)   1.249   1.25   1.25   1.25   1.25     ADC Total Monitoring Cycle Time   tc   Monitors all 8 inputs   1.25   1.25   1.25   1.25   1.25     ADC Total Monitoring Cycle Time   tc   Monitors all 8 inputs   200   266   ms     AUXIN_Input Leakage Current   I_LAUXIN_   VAUXIN_ = 1.25V   -1   1.1   1.4     SERIAL INTERFACE LOGIC (SDA, SCL, A0, A1)   1.26   1.27   1.25   1.25   1.27   1.25     Logic Input High Voltage   VIL   0.8   0.8   V     Input Leakage Current   I_LKG   I_LKG   1.25   1.25   1.25   1.25   1.25   1.25   1.25   1.25   1.25   1.25   1.25     Input Leakage Current   I_LKG    |   |                    |                             | 101  | 5.76  | 6.40   | 7.04   | S     |  |
| Reference Input Voltage Range         VREFIN         L.25         1.25         1.25         1.275         V           Reference Input Resistance         RREFIN         VREFIN = +1.25V         500         kΩ         kΩ           ABA DE Range         IN1, LSB = 18.3mV         0         13.2  |   |                    |                             | 110  | 23.04 | 25.60  | 28.16  |       |  |
| Reference Input Resistance   RREFIN   VREFIN = ±1.25V   500   KΩ   |   |                    |                             | 111  | 92.16 | 102.40 | 112.64 |       |  |
| ADC Range  | Reference Input Voltage Range             | VREFIN             |                             |  | 1.225 | 1.25   | 1.275  | V     |  |
| ADC Range    N1, LSB = 9.16mV  | Reference Input Resistance                | RREFIN             | V <sub>REFIN</sub> = +1.25V |  |       | 500    |        | kΩ    |  |
| $ \begin{tabular}{ c c c c c c c c c c c c c c c c c c c$  |   |                    | IN1, LSB = 18.3mV           |  | 0     |        | 13.2   |       |  |
| $ \begin{tabular}{ c c c c c c c c c c c c c c c c c c c$  |   |                    | IN1, LSB = 9.16mV           |  | 0     |        | 9.366  |       |  |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$   |   |                    | IN2, LSB = 18.3mV           |  | 0     |        | ±15.25 |       |  |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$   | ADC Range                                 |                    | IN2, LSB = 9.16mV           |  | 0     |        | ±9.366 | V     |  |
| AUXIN_, LSB = 1.2mV  |   |                    | IN3 to IN6, LSB = 7.32n     | nV   | 0     |        | 5.50   |       |  |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$   |   |                    | IN3 to IN6, LSB = 3.66mV    |  | 0     |        | 3.746  |       |  |
| ADC Total Unadjusted Error (Note 5)         TUE         Internal Reference         IN2 negative         ±1.0         %FSR           ADC Differential Nonlinearity         DNL         (Note 7)         ±1         LSB           ADC Total Monitoring Cycle Time         t <sub>C</sub> Monitors all 8 inputs         200         266         ms           AUXIN_ Input Leakage Current         I <sub>LAUXIN_</sub> V <sub>AUXIN_</sub> = 1.25V         -1         +1         μA           SERIAL INTERFACE LOGIC (SDA, SCL, A0, A1)           Logic Input Low Voltage         V <sub>IL</sub> 0.8         V           Logic Input High Voltage         V <sub>IH</sub> 2.0         V           Input Leakage Current         I <sub>LKG</sub> -1         +1         μA           Output Voltage Low         V <sub>OL</sub> I <sub>SINK</sub> = 3mA         0.4         V   |   |                    | AUXIN_, LSB = 1.2mV         |  | 0     |        | 1.249  |       |  |
| TUE  |   |                    | latawa al Dafawa a          | IN1 to IN6 positive                              |       |        | ±1.0   |       |  |
| External Reference, IN1 to IN6 positive (Note 6)   |   | TUE                | Internal Reference          | IN2 negative                                     |       | ±1.0   |        | %FSR  |  |
| ADC Total Monitoring Cycle Time         t <sub>C</sub> Monitors all 8 inputs         200         266         ms           AUXIN_ Input Leakage Current         I <sub>LAUXIN_</sub> V <sub>AUXIN_</sub> = 1.25V         -1         +1         μA           SERIAL INTERFACE LOGIC (SDA, SCL, A0, A1)         Logic Input Low Voltage         V <sub>IL</sub> 0.8         V           Logic Input High Voltage         V <sub>IH</sub> 2.0         V           Input Leakage Current         I <sub>LKG</sub> -1         +1         μA           Output Voltage Low         V <sub>OL</sub> I <sub>SINK</sub> = 3mA         0.4         V   | (Note 3)                                  |                    | External Reference, IN1 to  | External Reference, IN1 to IN6 positive (Note 6) |       |        | ±1.0   |       |  |
| AUXIN_ Input Leakage Current   | ADC Differential Nonlinearity DNL         |                    | (Note 7)                    |  |       | ±1     |        | LSB   |  |
| SERIAL INTERFACE LOGIC (SDA, SCL, A0, A1)           Logic Input Low Voltage         V <sub>IL</sub> 0.8         V           Logic Input High Voltage         V <sub>IH</sub> 2.0         V           Input Leakage Current         I <sub>LKG</sub> -1         +1         μA           Output Voltage Low         V <sub>OL</sub> I <sub>SINK</sub> = 3mA         0.4         V  | ADC Total Monitoring Cycle Time           | tc                 | Monitors all 8 inputs       |  |       | 200    | 266    | ms    |  |
| SERIAL INTERFACE LOGIC (SDA, SCL, A0, A1)           Logic Input Low Voltage         V <sub>IL</sub> 0.8         V           Logic Input High Voltage         V <sub>IH</sub> 2.0         V           Input Leakage Current         I <sub>LKG</sub> -1         +1         μA           Output Voltage Low         V <sub>OL</sub> I <sub>SINK</sub> = 3mA         0.4         V  | AUXIN_ Input Leakage Current              | ILAUXIN_           | •                           |  | -1    |        | +1     | μΑ    |  |
| Logic Input High Voltage         V <sub>IH</sub> 2.0         V           Input Leakage Current         I <sub>LKG</sub> -1         +1         μA           Output Voltage Low         V <sub>OL</sub> I <sub>SINK</sub> = 3mA         0.4         V  | SERIAL INTERFACE LOGIC (SDA               |                    |                             |  |       |        |        |       |  |
| Logic Input High Voltage         V <sub>IH</sub> 2.0         V           Input Leakage Current         I <sub>LKG</sub> -1         +1         μA           Output Voltage Low         V <sub>OL</sub> I <sub>SINK</sub> = 3mA         0.4         V  | Logic Input Low Voltage                   | V <sub>IL</sub>    |                             |  |       |        | 0.8    | V     |  |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$   | Logic Input High Voltage                  |                    |                             |  | 2.0   |        |        | V     |  |
| Output Voltage Low VoL ISINK = 3mA 0.4 V   | Input Leakage Current                     | 1                  |                             |  | -1    |        | +1     | μΑ    |  |
| Input/Output Capacitance CI/O 10 pF  | Output Voltage Low                        | 1                  | ISINK = 3mA                 |  |       |        | 0.4    | V     |  |
|  | Input/Output Capacitance                  | C <sub>I/O</sub>   |                             |  |       | 10     |        | pF    |  |

### **TIMING CHARACTERISTICS**

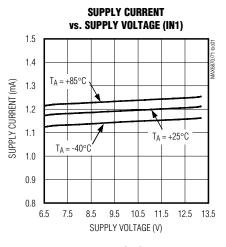
(IN1 = GND,  $V_{IN2}$  = +10V,  $V_{IN3}$  to  $V_{IN6}$  = +2.7V to +5.5V, AUXIN\_ = GPI\_ = GND,  $\overline{MARGIN}$  =  $\overline{MR}$  = DBP,  $T_A$  = -40°C to +85°C unless otherwise noted. Typical values are at  $T_A$  = +25°C.) (Notes 1 and 2)

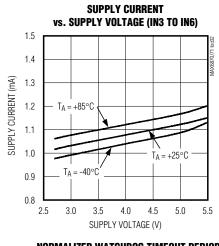
| PARAMETER                         | SYMBOL          | CONDITIONS               | MIN                               | TYP                               | MAX | UNITS |
|-----------------------------------|-----------------|--------------------------|-----------------------------------|-----------------------------------|-----|-------|
| TIMING CHARACTERISTICS (Figure 2) |                 |                          |                                   |                                   |     |       |
| Serial Clock Frequency            | fscl            |                          |                                   |                                   | 400 | kHz   |
| Clock Low Period                  | tLOW            |                          | 1.3                               |                                   |     | μs    |
| Clock High Period                 | tHIGH           |                          | 0.6                               |                                   |     | μs    |
| Bus-Free Time                     | tBUF            |                          | 1.3                               |                                   |     | μs    |
| START Setup Time                  | tsu:sta         |                          | 0.6                               |                                   |     | μs    |
| START Hold Time                   | thd:Sta         |                          | 0.6                               |                                   |     | μs    |
| STOP Setup Time                   | tsu:sto         |                          | 0.6                               |                                   |     | μs    |
| Data-In Setup Time                | tsu:DAT         |                          | 100                               |                                   |     | ns    |
| Data-In Hold Time                 | thd:dat         |                          | 0                                 |                                   | 900 | ns    |
| Receive SCL/SDA Minimum Rise Time | t <sub>R</sub>  | (Note 8)                 |                                   | 20 +<br>0.1 x<br>C <sub>BUS</sub> |     | ns    |
| Receive SCL/SDA Maximum Rise Time | t <sub>R</sub>  | (Note 8)                 |                                   | 300                               |     | ns    |
| Receive SCL/SDA Minimum Fall Time | tF              | (Note 8)                 |                                   | 20 +<br>0.1 x<br>C <sub>BUS</sub> |     | ns    |
| Receive SCL/SDA Maximum Fall Time | t <sub>F</sub>  | (Note 8)                 |                                   | 300                               |     | ns    |
| Transmit SDA Fall Time            | tF              | C <sub>BUS</sub> = 400pF | 20 +<br>0.1 x<br>C <sub>BUS</sub> |                                   | 300 | ns    |
| Pulse Width of Spike Suppressed   | tsp             | (Note 9)                 |                                   | 50                                |     | ns    |
| EEPROM Byte Write Cycle Time      | t <sub>WR</sub> | (Note 10)                |                                   |                                   | 11  | ms    |

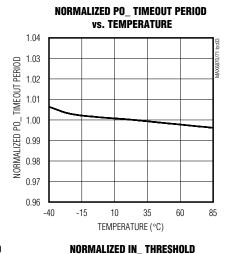
- **Note 1:** Specifications guaranteed for the stated global conditions. The device also meets the parameters specified when 0 < V<sub>IN1</sub> < +6.5V, and at least one of V<sub>IN3</sub> through V<sub>IN6</sub> is between +2.7V and +5.5V, while the remaining V<sub>IN3</sub> through V<sub>IN6</sub> are between 0 and +5.5V.
- Note 2: Device may be supplied from any one of IN, except IN2.
- **Note 3:** The internal supply voltage, measured at ABP, equals the maximum of IN3 to IN6 if  $V_{IN1} = 0$ , or equals +5.4V if  $V_{IN1} > +6.5$ V. For +4V <  $V_{IN1} < +6.5$ V and  $V_{IN3}$  through  $V_{IN6} > +2.7$ V, the input that powers the device cannot be determined.
- **Note 4:** 100% production tested at  $T_A = +25$ °C and  $T_A = +125$ °C. Specifications at  $T_A = -40$ °C are guaranteed by design.
- **Note 5:**  $V_{IN} > 0.3 \times ADC$  range.
- **Note 6:** Does not include the inaccuracy of the external +1.25V voltage reference.
- Note 7: DNL implicitly guaranteed by design in a sigma-delta converter.
- Note 8: CBUS = total capacitance of one bus line in pF. Rise and fall times are measured between 0.1 x VBUS and 0.9 x VBUS.
- Note 9: Input filters on SDA, SCL, A0, and A1 suppress noise spikes < 50ns.
- Note 10: An additional cycle is required when writing to configuration memory for the first time.

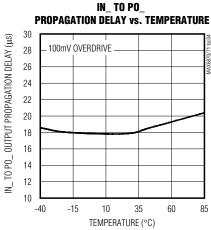
## **Typical Operating Characteristics**

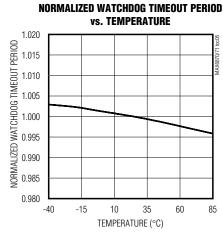
 $(V_{IN1} = +6.5V \text{ to } +13.2V, V_{IN2} = +10V, V_{IN3} - IN6 = +2.7V \text{ to } +5.5V, AUXIN\_ = GPI\_ = GND, \overline{MARGIN} = \overline{MR} = DBP, T_A = +25^{\circ}C, unless otherwise noted.)$ 

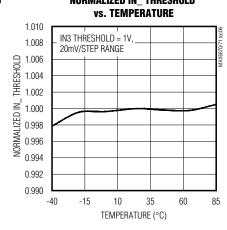


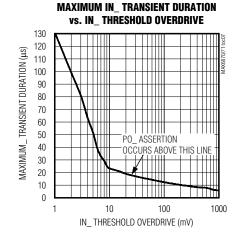


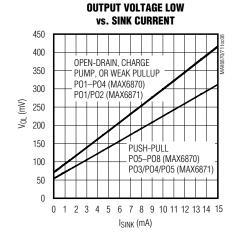








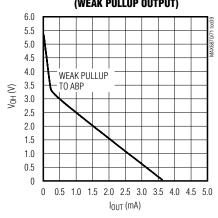




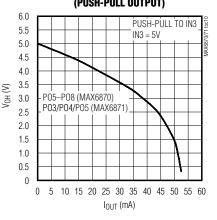
## Typical Operating Characteristics (continued)

 $(V_{IN1} = +6.5V \text{ to } +13.2V, V_{IN2} = +10V, V_{IN3} - IN6 = +2.7V \text{ to } +5.5V, \text{AUXIN}_{-} = \text{GPI}_{-} = \text{GND}, \overline{\text{MARGIN}} = \overline{\text{MR}} = \text{DBP}, T_{A} = +25^{\circ}\text{C}, unless otherwise noted.}$ 

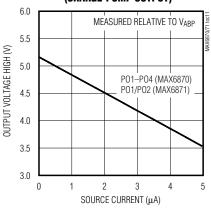
## OUTPUT VOLTAGE HIGH vs. SOURCE CURRENT (WEAK PULLUP OUTPUT)



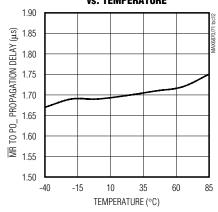
## OUTPUT VOLTAGE HIGH vs. SOURCE CURRENT (PUSH-PULL OUTPUT)



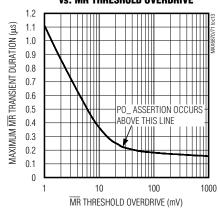
## OUTPUT VOLTAGE HIGH vs. SOURCE CURRENT (CHARGE-PUMP OUTPUT)



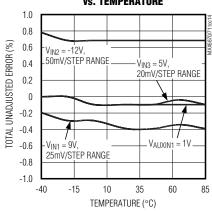
## MR TO PO\_ PROPAGATION DELAY vs. TEMPERATURE



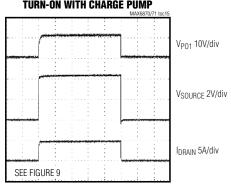
## MAXIMUM MR TRANSIENT DURATION vs. MR THRESHOLD OVERDRIVE



## ADC ACCURACY vs. TEMPERATURE



## FET (IRF7811W) TURN-ON WITH CHARGE PUMP



## **Pin Description**

| PIN     |                            |        |  |  |  |  |  |
|---------|----------------------------|--------|--|--|--|--|--|
| MAX6870 | MAX6871 NAME               |        | FUNCTION   |  |  |  |  |
| 1       | 3                          | PO2    | Programmable Output 2. Configurable, active-high, active-low, open-drain, weak pullup, or charge-pump output. PO2 pulls low with a 10µA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO2 assumes its programmed conditional output state when ABP exceeds UVLO.  |  |  |  |  |
| 2       | 5                          | PO3    | Programmable Output 3. Configurable, active-high, active-low, open-drain, weak pullup (MAX6870), push-pull (MAX6871), or charge-pump (MAX6870) output. PO3 pulls low with a 10μA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO3 assumes its programmed conditional output state when ABP exceeds UVLO.             |  |  |  |  |
| 3       | 6                          | PO4    | Programmable Output 4. Configurable, active-high, active-low, open-drain, weak pullup (MAX6870), push-pull (MAX6871), or charge-pump (MAX6870) output. PO4 pulls low with a 10μA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO4 assumes its programmed conditional output state when ABP exceeds UVLO.             |  |  |  |  |
| 4       | 4                          | GND    | Ground   |  |  |  |  |
| 5       | 7                          | PO5    | Programmable Output 5. Configurable, active-high, active-low, open-drain, weak pullup, or push-pull output. PO5 pulls low with a 10μA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO5 assumes its programmed conditional output state when ABP exceeds UVLO.  |  |  |  |  |
| 6       | _                          | PO6    | Programmable Output 6. Configurable, active-high, active-low, open-drain, weak pullup, or push-pull output. PO6 pulls low with a 10μA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO6 assumes its programmed conditional output state when ABP exceeds UVLO.  |  |  |  |  |
| 7       | _                          | P07    | Programmable Output 7. Configurable, active-high, active-low, open-drain, weak pullup, or push-pull output. PO7 pulls low with a 10μA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO7 assumes its programmed conditional output state when ABP exceeds UVLO.  |  |  |  |  |
| 8       | _                          | PO8    | Programmable Output 8. Configurable, active-high, active-low, open-drain, weak pullup, or push-pull output. PO8 pulls low with a 10µA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO8 assumes its programmed conditional output state when ABP exceeds UVLO.  |  |  |  |  |
| 9, 10   | 1, 8, 9, 10,<br>25, 26, 32 | N.C.   | No Connection. Not internally connected.   |  |  |  |  |
| 11      | 11                         | MARGIN | Margin Input. Configure MARGIN to either assert PO_ into a programmed state or to hold PO_ in its existing state when driving MARGIN low. See Table 8. Leave MARGIN unconnected or connect to DBP if unused. MARGIN overrides MR if both assert at the same time. MARGIN is internally pulled up to DBP through a 10µA current source.         |  |  |  |  |
| 12      | 12                         | MR     | Manual Reset Input. Configure $\overline{\text{MR}}$ to either assert PO_ into a programmed state or to have no effect on PO_ when driving $\overline{\text{MR}}$ low. See Table 7. Leave $\overline{\text{MR}}$ unconnected or connect to DBP if unused. $\overline{\text{MR}}$ is internally pulled up to DBP through a 10µA current source. |  |  |  |  |
| 13      | 13                         | SDA    | Serial Data Input/Output (Open-Drain). SDA requires an external pullup resistor.   |  |  |  |  |
| 14      | 14                         | SCL    | Serial Clock Input. SCL requires an external pullup resistor.  |  |  |  |  |
| 15      | 15                         | A0     | Address Input 0. Address inputs allow up to four MAX6870/MAX6871 connections on one common bus. Connect A0 to GND or to the serial interface power supply.   |  |  |  |  |
| 16      | 16                         | A1     | Address Input 1. Address inputs allow up to four MAX6870/MAX6871 connections on one common bus. Connect A1 to GND or to the serial interface power supply.   |  |  |  |  |

## Pin Description (continued)

| PIN     |         |        | FUNCTION   |  |  |  |
|---------|---------|--------|--|--|--|--|
| MAX6870 | MAX6871 | NAME   | FUNCTION   |  |  |  |
| 17      | 17      | GPI4   | General-Purpose Logic Input 4. An internal 10µA current source pulls GPI4 to GND. Configure GPI4 to control watchdog timer functions or the programmable outputs.  |  |  |  |
| 18      | 18      | GPI3   | General-Purpose Logic Input 3. An internal 10µA current source pulls GPI3 to GND. Configure GPI3 to control watchdog timer functions or the programmable outputs.  |  |  |  |
| 19      | 19      | GPI2   | General-Purpose Logic Input 2. An internal 10µA current source pulls GPI2 to GND. Configure GPI2 to control watchdog timer functions or the programmable outputs.  |  |  |  |
| 20      | 20      | GPI1   | General-Purpose Logic Input 1. An internal 10µA current source pulls GPI1 to GND. Configure GPI1 to control watchdog timer functions or the programmable outputs.  |  |  |  |
| 21      | 21      | ABP    | Internal Power-Supply Output. Bypass ABP to GND with a 1µF ceramic capacitor. ABP powers the internal circuitry of the MAX6870/MAX6871. ABP supplies the input voltage to the internal charge pumps when the programmable outputs are configured as charge-pump outputs. Do not use ABP to supply power to external circuitry.   |  |  |  |
| 22      | 22      | DBP    | Internal Digital Power-Supply Output. Bypass DBP to GND with a 1µF ceramic capacitor. DBP supplies power to the EEPROM memory and the internal logic circuitry. Do not use DBP to supply power to external circuitry.  |  |  |  |
| 23      | 23      | AUXIN2 | Auxiliary Input 2. A 10-bit ADC monitors the input voltage at AUXIN2. The high-impedance AUXIN2 input accepts input voltages up to V <sub>REFIN</sub> . AUXIN2 does not influence EEPROM-configurable power-supply sequencing or reset detection functions.  |  |  |  |
| 24      | 24      | AUXIN1 | Auxiliary Input 1. A 10-bit ADC monitors the input voltage at AUXIN1. The high-impedance AUXIN1 input accepts input voltages up to V <sub>REFIN</sub> . AUXIN1 does not influence EEPROM-configurable power-supply sequencing or reset detection functions.  |  |  |  |
| 25      | _       | IN6    | Voltage Input 6. Configure IN6 to detect voltage thresholds between +1V and +5.5V in 20mV increments, or +0.5V to +3.05V in 10mV increments. For improved noise immunity, bypass IN6 to GND with a 0.1µF capacitor installed as close to the device as possible.   |  |  |  |
| 26      | _       | IN5    | Voltage Input 5. Configure IN5 to detect voltage thresholds between +1V and +5.5V in 20mV increments, or +0.5V to +3.05V in 10mV increments. For improved noise immunity, bypass IN5 to GND with a 0.1µF capacitor installed as close to the device as possible.   |  |  |  |
| 27      | 27      | IN4    | Voltage Input 4. Configure IN4 to detect voltage thresholds between +1V and +5.5V in 20mV increments, or +0.5V to +3.05V in 10mV increments. For improved noise immunity, bypass IN4 to GND with a 0.1µF capacitor installed as close to the device as possible.   |  |  |  |
| 28      | 28      | IN3    | Voltage Input 3. Configure IN3 to detect voltage thresholds between +1V and +5.5V in 20mV increments, or +0.5V to +3.05V in 10mV increments. For improved noise immunity, bypass IN3 to GND with a 0.1µF capacitor installed as close to the device as possible.   |  |  |  |
| 29      | 29      | IN2    | Bipolar Voltage Input 2. Configure IN2 to detect negative voltage thresholds from -2.5V to -15.25V in 50mV increments or -1.25V to -7.625V in 25mV increments. Alternatively, configure IN2 to detect positive voltage thresholds from +2.5V to +15.25V in 50mV increments or +1.25V to +7.625V in 25mV increments. For improved noise immunity, bypass IN2 to GND with a $0.1\mu F$ capacitor installed as close to the device as possible. |  |  |  |

### **Pin Description (continued)**

| PI      | PIN     |         | PIN NAME  |  | FUNCTION |  |  |  |
|---------|---------|---------|---|--|----------|--|--|--|
| MAX6870 | MAX6871 | INAIVIE | FONCTION  |  |          |  |  |  |
| 30      | 30      | IN1     | High Voltage Input 1. Configure IN1 to detect voltage thresholds from +2.5V to +13.2V in 50mV increments or +1.25V to +7.625V in 25mV increments. For improved noise immunity, bypass IN1 to GND with a 0.1µF capacitor installed as close to the device as possible.                           |  |          |  |  |  |
| 31      | 31      | REFIN   | Reference Voltage Input. Configure the MAX6870/MAX6871 to use either an internal reference or external reference (see Table 9). When configured for an internal reference, leave REFIN unconnected. When configured for an external reference, connect a +1.225V to +1.275V reference to REFIN. |  |          |  |  |  |
| 32      | 2       | PO1     | Programmable Output 1. Configurable active-high, active-low, open-drain, weak pullup, or charge-pump output. PO1 pulls low with a weak 10µA internal current sink for +1V < V <sub>ABP</sub> < V <sub>UVLO</sub> . PO1 assumes its programmed conditional output state when ABP exceeds UVLO.   |  |          |  |  |  |
| _       | _       | EP      | Exposed Paddle. Exposed paddle is internally connected to GND.  |  |          |  |  |  |

### **Detailed Description**

The MAX6870/MAX6871 EEPROM-configurable, multivoltage supply sequencers/supervisors monitor several voltage-detector inputs, two auxiliary inputs and four general-purpose logic inputs, and feature programmable outputs for highly-configurable, power-supply sequencing applications. The MAX6870 features six voltage-detector inputs and eight programmable outputs, while the MAX6871 features four voltage-detector inputs and five programmable outputs. Manual reset and margin disable inputs simplify board-level testing during the manufacturing process. The MAX6870/MAX6871 feature an accurate internal 1.25V reference. For greater accuracy, connect an external +1.25V reference to REFIN.

All voltage detectors provide two configurable thresholds for undervoltage/overvoltage or dual undervoltage detection. One high-voltage input (IN1) provides detector threshold voltages from +1.25V to +7.625V in 25mV increments or +2.5V to +13.2V in 50mV increments. A bipolar input (IN2) provides detector threshold voltages from  $\pm 1.25$ V to  $\pm 7.625$ V in 25mV increments, or  $\pm 2.5$ V to  $\pm 15.25$ V in 50mV increments. Positive inputs (IN3–IN6) provide detector threshold voltages from +0.5V to +3.05V in 10mV increments, or +1.0V to +5.5V in 20mV increments.

An internal 10-bit ADC monitors the voltage-detector inputs and two auxiliary inputs through a multiplexer that automatically sequences through all inputs every 200ms. The host controller communicates with the MAX6870/MAX6871s' internal 4kb user EEPROM, configuration EEPROM, configuration registers, ADC registers, and fault registers through an SMBus/I<sup>2</sup>C-compatible serial interface (see Figure 1).

Programmable output options include active-high, active-low, open-drain, weak pullup, push-pull, and charge pump. Select the charge-pump output feature to drive n-channel FETs for power-supply sequencing (see the *Applications Information* section). The outputs swing between 0 and (V<sub>ABP</sub> + 5V) when configured for charge-pump operation.

Program each output to assert on any voltage-detector input, general-purpose logic input, watchdog timer, manual reset, or other output stages. Programmable timing-delay blocks configure each output to wait between 25µs and 1600ms before deasserting. A fault register logs the conditions that caused each output to assert (undervoltage, overvoltage, manual reset, etc.).

The MAX6870/MAX6871 feature two watchdog timers, adding flexibility. Program each watchdog timer to assert one or more programmable outputs. Program each

watchdog timer to clear on a combination of one GPI\_input and one programmable output, one of the GPI\_inputs only, or one of the programmable outputs only. The initial and normal watchdog timeout periods are independently programmable from 6.25ms to 102.4s.

A virtual diode-ORing scheme selects the input that powers the MAX6870/MAX6871. The MAX6870/MAX6871

derive power from IN1 if  $V_{IN1} > +6.5 V$  or from the highest voltage on IN3–IN6 if  $V_{IN1} < +2.7 V$ . The power source cannot be determined if  $+4 V < V_{IN1} < +6.5 V$  and one of  $V_{IN3}$  through  $V_{IN6} > +2.7 V$ . The programmable outputs maintain the correct programmed logic state for  $V_{ABP} > V_{UVLO}$ . One of IN3 through IN6 must be greater than +2.7 V or IN1 must be greater than +4 V for device operation.

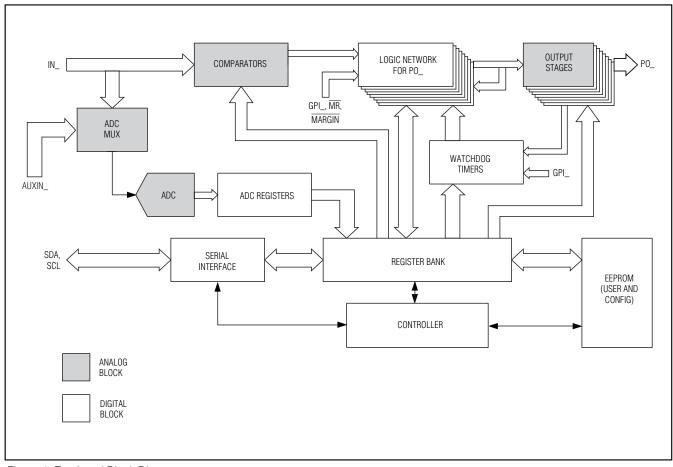
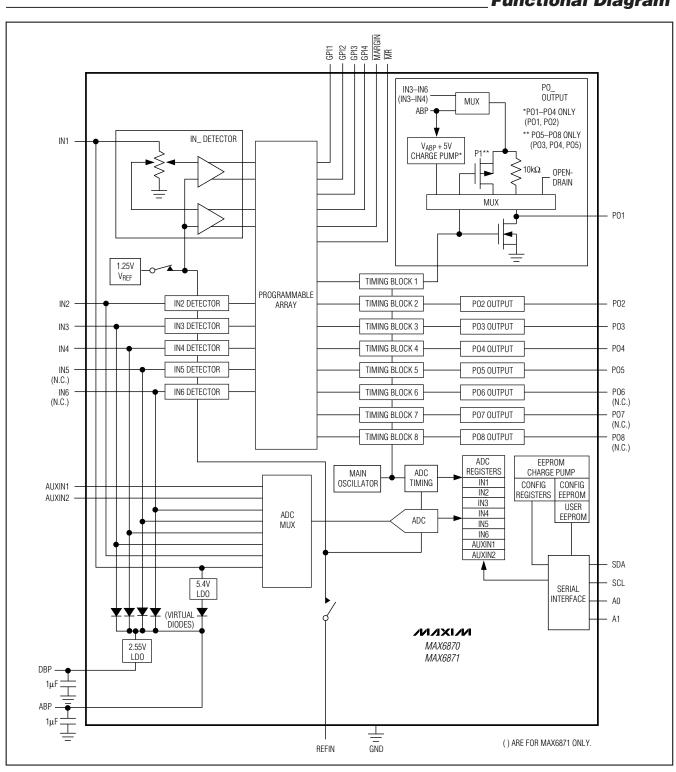


Figure 1. Top Level Block Diagram

## **Functional Diagram**



#### Powering the MAX6870/MAX6871

The MAX6870/MAX6871 derive power from the positive voltage-detector inputs: IN1, or IN3–IN6. A virtual diode-ORing scheme selects the positive input that supplies power to the device (see the *Functional Diagram*). IN1 must be at least +4V or one of IN3–IN6 (MAX6870)/IN3/IN4 (MAX6871) must be at least +2.7V to ensure device operation. An internal LDO regulates IN1 down to +5.4V.

The highest input voltage on IN3-IN6 (MAX6870)/ IN3/IN4 (MAX6871) supplies power to the device, unless  $V_{\rm IN1} \geq +6.5V$ , in which case IN1 supplies power to the device. For +4V <  $V_{\rm IN1} < +6.5V$  and one of  $V_{\rm IN3}$  through  $V_{\rm IN6} > +2.7V$ , the input power source cannot be determined due to the dropout voltage of the LDO. Internal hysteresis ensures that the supply input that initially powered the device continues to power the device when multiple input voltages are within 50mV of each other.

ABP powers the analog circuitry; bypass ABP to GND with a 1 $\mu$ F ceramic capacitor installed as close to the device as possible. The internal supply voltage, measured at ABP, equals the maximum of IN3-IN6 (MAX6870)/IN3/IN4 (MAX6871) if V<sub>IN1</sub> = 0, or equals +5.4V when V<sub>IN1</sub> > +6.5V. Do not use ABP to provide power to external circuitry.

The MAX6870/MAX6871 also generate a digital supply voltage (DBP) for the internal logic circuitry and the EEPROM; bypass DBP to GND with a 1µF ceramic capacitor installed as close to the device as possible. The nominal DBP output voltage is +2.55V. Do not use DBP to provide power to external circuitry.

#### ADC

The MAX6870/MAX6871 feature an internal 10-bit ADC that monitors the voltage-detector inputs and auxiliary inputs through an internal multiplexer that sequences through all input voltages in 200ms. Registers 50h to 5Fh store the ADC data. Read the ADC data from the MAX6870/MAX6871 with the serial interface. The ADC strictly monitors input voltages and has no effect on power-supply sequencing, reset detection, or the programmable outputs.

#### Inputs

The MAX6870/MAX6871 contain multiple logic and voltage-detector inputs. Each voltage-detector input is simultaneously monitored for primary and secondary thresholds. The primary threshold must be an undervoltage threshold. The secondary threshold may be an undervoltage or overvoltage threshold. Table 1 summarizes these various inputs.

**Table 1. Programmable Features** 

| FEATURE  | DESCRIPTION   |
|--|---|
| High Voltage Input (IN1)   | <ul> <li>Primary undervoltage threshold</li> <li>Secondary overvoltage or undervoltage threshold</li> <li>+2.5V to +13.2V threshold in 50mV increments</li> <li>+1.25V to +7.625V threshold in 25mV increments</li> </ul>   |
| Bipolar Voltage Input<br>(IN2)   | <ul> <li>Primary undervoltage threshold</li> <li>Secondary overvoltage or undervoltage threshold</li> <li>±2.5V to ±15.25V threshold in 50mV increments</li> <li>±1.25V to ±7.625V threshold in 25mV increments</li> </ul>  |
| Positive Voltage Input<br>IN3-IN6 (MAX6870)<br>IN3, IN4 (MAX6871)        | <ul> <li>Primary undervoltage threshold</li> <li>Secondary overvoltage or undervoltage threshold</li> <li>+1V to +5.5V threshold in 20mV increments</li> <li>+0.5V to +3.05V threshold in 10mV increments</li> </ul>  |
| Programmable Outputs<br>PO1-PO4 (MAX6870),<br>PO1, PO2 (MAX6871)         | <ul> <li>Active high or active low</li> <li>Open-drain, weak pullup, or charge-pump output</li> <li>Weak pullup to IN3-IN6 (IN3 or IN4 for MAX6871) or ABP</li> <li>Dependent on MR, MARGIN, IN_, GPI1-GPI4, WDI1 and WDI2, and/or PO_</li> <li>Programmable timeout periods of 25µs, 1.5625ms, 6.25ms, 25ms, 50ms, 200ms, 400ms, or 1.6s</li> </ul>  |
| Programmable Outputs<br>PO5-PO8 (MAX6870),<br>PO3, PO4, PO5<br>(MAX6871) | <ul> <li>Active high or active low</li> <li>Open-drain, weak pullup, or push-pull output</li> <li>Weak pullup to IN3–IN6 (IN3 or IN4 for MAX6871) or ABP</li> <li>Push-pull to IN3–IN6 (IN3 or IN4 for MAX6871)</li> <li>Dependent on MR, MARGIN, IN_, GPI1–GPI4, WDI1 and WDI2, and/or IN_</li> <li>Programmable timeout periods of 25µs, 1.5625ms, 6.25ms, 50ms, 200ms, 400ms, or 1.6s</li> </ul> |

Table 1. Programmable Features (continued)

| FEATURE                                     | DESCRIPTION  |
|---|--|
| General-Purpose Logic<br>Inputs (GPI1–GPI4) | <ul> <li>Active high or active low logic levels</li> <li>Configure GPI_ as inputs to watchdog timers or programmable output stages</li> </ul>  |
| Watchdog Timers                             | <ul> <li>Clear dependent on any combination of one GPI_ input and one programmable output, a GPI_ input only, or a programmable output only</li> <li>Initial watchdog timeout period of 6.25ms, 25ms, 100ms, 400ms, 1.6s, 6.4s, 25.6s, or 102.4s</li> <li>Normal watchdog timeout period of 6.25ms, 25ms, 100ms, 400ms, 1.6s, 6.4s, 25.6s, or 102.4s</li> <li>Watchdog enable/disable</li> <li>Initial watchdog timeout period enable/disable</li> </ul> |
| Auxiliary Inputs<br>(AUXIN1, AUXIN2)        | Monitored by the internal 10-bit ADC   |
| Manual Reset Input<br>(MR)                  | <ul> <li>Forces PO_ into the active output state when MR = GND</li> <li>PO_ deassert after MR releases high and the PO_ timeout period expires</li> <li>PO_ cannot be a function of MR only</li> </ul>   |
| Margining Input<br>(MARGIN)                 | <ul> <li>Holds PO_ in existing state or asserts PO_ to a programmed output state, independent of changes in monitored inputs or watchdog timers, when MARGIN = GND</li> <li>Overrides MR when both assert at the same time</li> </ul>  |
| Reference Input<br>(REFIN)                  | <ul> <li>Internal +1.25V reference voltage</li> <li>Goes high-impedance when internal reference selected</li> <li>External reference voltage input from +1.225V to +1.275V</li> <li>Sets ADC voltage range</li> </ul>  |
| 10-Bit ADC*                                 | Monitors IN_, AUXIN1, and AUXIN2     Completes conversion of all eight inputs in 200ms     Reference voltage sets ADC range     Read ADC data from SMBus/I <sup>2</sup> C interface  |
| Write Disable                               | Locks user EEPROM based on PO_   |
| Configuration Lock                          | Locks configuration EEPROM   |

<sup>\*</sup>ADC does not control programmable outputs.

Set the primary and secondary threshold voltages for each voltage-detector input with registers 00h–0Bh. Each primary threshold voltage must be an undervoltage threshold. Configure each secondary threshold voltage as an undervoltage or overvoltage threshold (see register 0Ch). Set the threshold range for each voltage detector with register 0Dh.

#### High Voltage Input (IN1)

IN1 offers threshold voltages of +2.5V to +13.2V in 50mV increments, or +1.25V to +7.625V in 25mV increments. Use the following equations to set the threshold voltages for IN1:

$$x = \frac{V_{TH} - 2.5V}{0.05V}$$
 for +2.5V to +13.2V range

$$x = \frac{V_{TH} - 1.25V}{0.025V}$$
 for +1.25V to +7.625V range

where  $V_{TH}$  is the desired threshold voltage and x is the decimal code for the desired threshold (Table 2). For the +2.5V to +13.2V range, x must equal 214 or less, otherwise the threshold exceeds the maximum operating voltage of IN1.

### Bipolar Voltage Input (IN2)

IN2 offers negative thresholds from -2.5V to -15.25V in 50mV increments, or from -1.25V to -7.625V in 25mV increments. Alternatively, IN2 offers positive thresholds from +2.5V to +15.25V in 50mV increments, or +1.25V to +7.625V in 25mV increments. Use the following equations to set the threshold voltages for IN2:

IN3-IN6

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$$x = \frac{-(V_{TH} - 2.5V)}{0.05V}$$
 for -2.5V to -15.25V range

$$x = \frac{-(V_{TH} - 1.25V)}{0.025V}$$
 for -1.25V to -7.625V range

$$x = \frac{V_{TH} - 2.5V}{0.05V}$$
 for +2.5V to +15.25V range

$$x = \frac{V_{TH} - 1.25V}{0.025V}$$
 for +1.25V to +7.625V range

where V<sub>TH</sub> is the desired threshold voltage and x is the decimal code for the desired threshold (Table 3).

IN3–IN6 offer positive voltage detectors monitor voltages from +1V to +5.5V in 20mV increments, or +0.5V to +3.05V in 10mV increments. Use the following equations to set the threshold voltages for IN\_:

$$x = \frac{V_{TH} - 1V}{0.02V}$$
 for +1V to +5.5V range

$$x = \frac{V_{TH} - 0.5V}{0.01V}$$
 for +0.5V to +3.05V range

where  $V_{TH}$  is the desired threshold voltage and x is the decimal code for the desired threshold (Table 4). For the +1V to +5.5V range, x must equal 225 or less, otherwise the threshold exceeds the maximum operating voltage of IN3–IN6.

### **Table 2. IN1 Threshold Settings**

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | DESCRIPTION  |
|---------------------|-----------------------------|--------------|--|
| 00h                 | 8000h                       | [7:0]        | IN1 primary undervoltage detector threshold (V1A) (see equations in the <i>High Voltage Input (IN1)</i> section).        |
| 06h                 | 8006h                       | [7:0]        | IN1 secondary undervoltage/overvoltage detector threshold (V1B) (see equations in the High Voltage Input (IN1) section). |
| 0Ch                 | 800Ch                       | [0]          | IN1 secondary overvoltage/undervoltage selection. 0 = overvoltage threshold. 1 = undervoltage threshold.                 |
| 0Dh                 | 800Dh                       | [0]          | IN1 range selection.<br>0 = 2.5V to 13.2V range in 50mV increments. 1 = 1.25V to 7.625V range in 25mV increments.        |

## **Table 3. IN2 Threshold Settings**

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | DESCRIPTION  |
|---------------------|-----------------------------|--------------|--|
| 01h                 | 8001h                       | [7:0]        | IN2 primary undervoltage detector threshold (V2A) (see equations in the <i>Bipolar Voltage Input (IN2)</i> section).   |
| 07h                 | 8007h                       | [7:0]        | IN2 secondary undervoltage/overvoltage detector threshold (V2B) (see equations in the <i>Bipolar Voltage Input (IN2)</i> section).   |
| 0Ch                 | 800Ch                       | [1]          | IN2 secondary overvoltage/undervoltage selection. 0 = overvoltage threshold. 1 = undervoltage threshold.   |
| 0Dh                 | 800Dh                       | [7:6]        | IN2 range selection.  00 = -2.5V to -15.25V range in 50mV increments.  01 = -1.25V to -7.625V range in 25mV increments.  10 = +2.5V to +15.25V range in 50mV increments.  11 = +1.25V to +7.625V range in 25mV increments. |

## Table 4. IN3-IN6 Threshold Settings

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS  | BIT<br>RANGE   | DESCRIPTION  |
|---------------------|--|--|--|
| 02h                 | 8002h  | [7:0]  | IN3 primary undervoltage detector threshold (V3A) (see equations in the IN3–IN6 section).  |
| 03h                 | 8003h  | [7:0]  | IN4 primary undervoltage detector threshold (V4A) (see equations in the IN3–IN6 section).  |
| 04h                 | 8004h  | [7:0]  | IN5 (MAX6870 only) primary undervoltage detector threshold (V5A) (see equations in the IN3–IN6 section).   |
| 05h                 | 8005h  | [7:0]  | IN6 (MAX6870 only) primary undervoltage detector threshold (V6A) (see equations in the IN3–IN6 section).   |
| 08h                 | 8008h  | [7:0]  | IN3 secondary undervoltage/overvoltage detector threshold (V3B) (see equations in the IN3–IN6 section).  |
| 09h                 | 8009h  | [7:0]  | IN4 secondary undervoltage/overvoltage detector threshold (V4B) (see equations in the IN3–IN6 section).  |
| 0Ah                 | 800Ah  | [7:0]  | IN5 (MAX6870 only) secondary undervoltage/overvoltage detector threshold (V5B) (see equations in the <i>IN3–IN6</i> section).  |
| 0Bh                 | 800Bh  | [7:0]  | IN6 (MAX6870 only) secondary undervoltage/overvoltage detector threshold (V6B) (see equations in the <i>IN3–IN6</i> section).  |
|                     | 800Ch  | [2]  | IN3 secondary overvoltage/undervoltage selection. 0 = overvoltage threshold. 1 = undervoltage threshold.   |
|                     |  | [3]  | IN4 secondary overvoltage/undervoltage selection. 0 = overvoltage threshold. 1 = undervoltage threshold.   |
| 0Ch                 |  | [4]  | IN5 (MAX6870 only) secondary overvoltage/undervoltage selection. 0 = overvoltage threshold. 1 = undervoltage threshold.  |
|                     |  | [5]  | IN6 (MAX6870 only) secondary overvoltage/undervoltage selection.  0 = overvoltage threshold. 1 = undervoltage threshold.   |
|                     |  | [7:6]  | Not used.  |
|                     |  | [1]  | IN3 range selection. $0 = +1V \text{ to } +5.5V \text{ range in } 20\text{mV} \text{ increments. } 1 = +0.5V \text{ to } +3.05V \text{ range in } 10\text{mV} \text{ increments.}$ |
|                     | 800Dh [3] IN5 (MAX6870 only) range of the second of the se | IN4 range selection.<br>0 = +1V to +5.5V range in 20mV increments. $1 = +0.5V$ to +3.05V range in 10mV increments. |  |
| 0Dh                 |  | [3]  | IN5 (MAX6870 only) range selection. $0 = +1V$ to $+5.5V$ range in 20mV increments. $1 = +0.5V$ to $+3.05V$ range in 10mV increments.   |
|                     |  | [4]  | IN6 (MAX6870 only) range selection.  0 = +1V to +5.5V range in 20mV increments. 1 = +0.5V to +3.05V range in 10mV increments.  |
|                     |  | [5]  | Not used.  |

#### **AUXIN1 and AUXIN2**

The AUXIN1 and AUXIN2 high-impedance analog inputs are intended to monitor two additional system voltages not required for power-supply sequencing or reset purposes. The internal 10-bit ADC monitors AUXIN1 and AUXIN2 and stores the data in the ADC registers (Table

Table 5. ADC Registers for AUXIN1 and AUXIN2 (Read Only)

| REGISTER<br>ADDRESS | BIT<br>RANGE | DESCRIPTION                    |
|---------------------|--------------|--------------------------------|
| 5Ch                 | [7:0]        | AUXIN1 measured value, 8 MSBs. |
| 5Dh                 | [1:0]        | AUXIN1 measured value, 2 LSBs. |
| וועכ                | [7:2]        | Not used.                      |
| 5Eh                 | [7:0]        | AUXIN2 measured value, 8 MSBs. |
| 5Fh                 | [1:0]        | AUXIN2 measured value, 2 LSBs. |
| ) JEII              | [7:2]        | Not used.                      |

### Table 6. GPI1-GPI4 Active Logic States

| REGISTER<br>ADDRESS | BIT<br>RANGE | DESCRIPTION                            |
|---------------------|--------------|--|
|                     | [0]          | GPI1. 0 = active low. 1 = active high. |
| 3Bh                 | [1]          | GPI2. 0 = active low. 1 = active high. |
| SDII                | [2]          | GPI3. 0 = active low. 1 = active high. |
|                     | [3]          | GPI4. 0 = active low. 1 = active high. |

5). AUXIN1 and AUXIN2 do not assert any of the programmable outputs. The AUXIN1 and AUXIN2 inputs accept power-supply voltages or other system voltages scaled to the +1.25V ADC input voltage range.

#### GPI1-GPI4

The GPI1–GPI4 programmable logic inputs control power-supply sequencing (programmable outputs), reset/interrupt signaling, and watchdog functions (see the *Configuring the Watchdog Timers (Registers 3Ch–3Fh)* section). Configure GPI1–GPI4 for active-low or active-high logic (Table 6). GPI1–GPI4 internally pull down to GND through a 10µA current sink.

### MR

The manual reset  $(\overline{MR})$  input initiates a reset condition. Register 40h determines the programmable outputs that assert while  $\overline{MR}$  is low (Table 7). All affected programmable outputs remain asserted (see the *Programmable Outputs* section) for their PO\_ timeout periods after  $\overline{MR}$  releases high. An internal 10µA current source pulls  $\overline{MR}$  to DBP. Leave  $\overline{MR}$  unconnected or connect to DBP if unused. A programmable output cannot depend solely on  $\overline{MR}$ .

## Table 7. Programmable Output Behavior and MR

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS  | BIT<br>RANGE | DESCRIPTION  |
|---------------------|--|--------------|--|
|                     |  | [0]          | PO1 (MAX6870 only). $0 = PO1$ independent of $\overline{MR}$ . $1 = PO1$ asserts when $\overline{MR} = low$ .                |
|                     |  | [1]          | PO2 (MAX6870 only). $0 = PO2$ independent of $\overline{MR}$ . $1 = PO2$ asserts when $\overline{MR} = low$ .                |
|                     |  | [2]          | PO3 (MAX6870)/PO1 (MAX6871). 0 = PO3/PO1 independent of $\overline{MR}$ .<br>1 = PO3/PO1 asserts when $\overline{MR}$ = low. |
|                     | [3] PO4 (MAX6870)/PO2 (MAX6871). $0 = PO4/PO2$ independent of $\overline{MR}$ . $1 = PO4/PO2$ asserts when $\overline{MR} = low$ . |              |  |
| 40h                 | 8040h  | [4]          | PO5 (MAX6870)/PO3 (MAX6871). 0 = PO5/PO3 independent of $\overline{MR}$ .<br>1 = PO5/PO3 asserts when $\overline{MR}$ = low. |
|                     |  | [5]          | PO6 (MAX6870)/PO4 (MAX6871). 0 = PO6/PO4 independent of $\overline{MR}$ .<br>1 = PO6/PO4 asserts when $\overline{MR}$ = low. |
|                     |  | [6]          | PO7 (MAX6870)/PO5 (MAX6871). 0 = PO7/PO5 independent of $\overline{MR}$ .<br>1 = PO7/PO5 asserts when $\overline{MR}$ = low. |
|                     |  | [7]          | PO8 (MAX6870 only). $0 = PO8$ independent of $\overline{MR}$ . $1 = PO8$ asserts when $\overline{MR} = low$ .                |

#### MARGIN

MARGIN allows system-level testing while power supplies exceed the normal ranges. Registers 41h and 42h determine whether the programmable outputs assert to a predetermined state or hold the last state as MARGIN is driven low (Table 8). Drive MARGIN low to set the programmable outputs in a known state while system-

level testing occurs. Leave  $\overline{MARGIN}$  unconnected or connect to DBP if unused. An internal 10µA current source pulls  $\overline{MARGIN}$  to DBP. The internal ADC continually monitors IN\_ while  $\overline{MARGIN}$  is low. The state of each programmable output does not change while  $\overline{MARGIN}$  = GND.  $\overline{MARGIN}$  overrides  $\overline{MR}$  if both assert at the same time.

Table 8. Programmable Output Behavior and MARGIN

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | AFFECTED OUTPUT                | DESCRIPTION  |
|---------------------|-----------------------------|--------------|--------------------------------|--|
|                     |                             | [0]          | PO1<br>(MAX6870 only)          | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[0]). |
|                     |                             | [1]          | PO2<br>(MAX6870 only)          | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[1]). |
|                     |                             | [2]          | PO3 (MAX6870)<br>PO1 (MAX6871) | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[2]). |
| 41h                 | 8041h                       | [3]          | PO4 (MAX6870)<br>PO2 (MAX6871) | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[3]). |
| 4111                | 004111                      | [4]          | PO5 (MAX6870)<br>PO3 (MAX6871) | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[4]). |
|                     |                             | [5]          | PO6 (MAX6870)<br>PO4 (MAX6871) | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[5]). |
|                     |                             | [6]          | PO7 (MAX6870)<br>PO5 (MAX6871) | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[6]). |
|                     |                             | [7]          | PO8<br>(MAX6870 only)          | 0 = output held in existing state.<br>1 = output asserts high or low (see 42h[7]). |
|                     |                             | [0]          | PO1<br>(MAX6870 only)          | 0 = output asserts low if 41h[0] = 1.<br>1 = output asserts high if 41h[0] = 1.    |
|                     |                             | [1]          | PO2<br>(MAX6870 only)          | 0 = output asserts low if 41h[1] = 1.<br>1 = output asserts high if 41h[1] = 1.    |
|                     |                             | [2]          | PO3 (MAX6870)<br>PO1 (MAX6871) | 0 = output asserts low if 41h[2] = 1.<br>1 = output asserts high if 41h[2] = 1.    |
| 42h                 | 90.42h                      | [3]          | PO4 (MAX6870)<br>PO2 (MAX6871) | 0 = output asserts low if 41h[3] = 1.<br>1 = output asserts high if 41h[3] = 1.    |
| 4211                | 8042h                       | [4]          | PO5 (MAX6870)<br>PO3 (MAX6871) | 0 = output asserts low if 41h[4] = 1.<br>1 = output asserts high if 41h[4] = 1.    |
|                     |                             | [5]          | PO6 (MAX6870)<br>PO4 (MAX6871) | 0 = output asserts low if 41h[5] = 1.<br>1 = output asserts high if 41h[5] = 1.    |
|                     |                             | [6]          | PO7 (MAX6870)<br>PO5 (MAX6871) | 0 = output asserts low if 41h[6] = 1.<br>1 = output asserts high if 41h[6] = 1.    |
|                     |                             | [7]          | PO8<br>(MAX6870 only)          | 0 = output asserts low if 41h[7] = 1.<br>1 = output asserts high if 41h[7] = 1.    |

#### REFIN

The MAX6870/MAX6871 feature an internal +1.25V voltage reference. The voltage reference sets the threshold of the voltage detectors and provides a reference voltage for the internal ADC. Program register 44h to use the internal reference or an external reference (Table 9). Leave REFIN unconnected when using the internal reference. REFIN accepts an external reference in the +1.225V to +1.275V range.

**Table 9. Reference Register** 

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | DESCRIPTION  |
|---------------------|-----------------------------|--------------|--|
| 44h                 | 8044h                       | [0]          | 0 = internal reference.<br>1 = external reference. |
|                     |                             | [7:1]        | Not used.  |

### **Programmable Outputs**

The MAX6870 features eight programmable outputs, while the MAX6871 features five programmable outputs. Selectable output-stage configurations include: active low or active high, open drain, weak pullup, push-pull, or charge pump. During power-up, the programmable outputs pull to GND with an internal 10µA current sink for 1V < VABP < VUVLO. The programmable outputs remain in their active states until PO\_ timeout period expires, and all of the programmed conditions are met for each output. Any output programmed to depend on no condition always remains in its active state (Table 22). An active-high configured output is considered asserted when that output is logic-high. No output can depend solely on MR.

The positive voltage monitors generate fault signals (logical 0) to the MAX6870/MAX6871's logic array when an input voltage is below the programmed undervoltage threshold, or when that voltage is above the overvoltage threshold. The negative voltage monitor (IN2) generates a fault signal to the logic array when the input voltage is less negative than the undervoltage threshold, or when that voltage is more negative than the overvoltage threshold.

Registers 0Eh through 3Ah and 40h configure each of the programmable outputs. Programmable timing blocks set the PO\_ timeout period from 25µs to 1600ms for each programmable output. See register 3Ah (Table 22) to set the active state (active-high or active-low) for each programmable output and registers 11h, 15h, 1Ch, 23h, 2Ah, 31h, 35h, and 39h to select the output stage types (Tables 23 and 24), and PO\_ timeout periods (Table 25) for each output.

Control selected programmable outputs with a sum of products (Tables 10–21). Each product allows a different set of conditions to assert each output. Outputs PO3 (MAX6870)/PO1 (MAX6871) and PO6 (MAX6870)/PO4 (MAX6871) allow two sets of different conditions to assert each output. Outputs PO1 and PO2 (MAX6870 only), PO7 (MAX6870)/PO5 (MAX6871), and PO8 (MAX6870 only) allow only one set of conditions to assert each output.

For example, Product 1 of the PO3 (MAX6870—Table 12) programmable output may depend on the IN1 primary undervoltage threshold, and the states of GPI1, PO1, and PO2. Write a one to R16h[0], R17h[6], and R18h[3:2] to configure Product 1 as indicated. IN1 must be above the primary undervoltage threshold (Table 2), GPI1 must be inactive (Table 6), and PO1 (Tables 10 and 22) and PO2 (Tables 12 and 23) must be in their deasserted states for Product 1 to be a logical 1. Product 1 is equivalent to the logic statement: V1A • GPI1 • PO1 • PO2.

Product 2 of PO3 (MAX6870, Table 13) may depend on an entirely different set of conditions, or the same conditions, depending on the system requirements. For example, Product 2 may depend on the IN1 undervoltage threshold, and the states of GPI2 and WDI1. Write ones to R19h[6, 0] and R1Ah[7] to configure Product 2 as indicated. IN1 must be above the primary undervoltage threshold (Table 2), GPI2 must be inactive (Table 6), and the WDI1 timer must not have expired (Tables 27 and 28) for Product 2 to be a logical 1. Product 2 is equivalent to the logic statement: V1A • GPI2 • WDI1. PO3 deasserts if either Product 1 or Product 2 is a logical 1. The logical statement: Product 1 + Product 2 determines the state of PO3.

Table 10. PO1 (MAX6870 Only) Output Dependency

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS                            | BIT | OUTPUT ASSERTION CONDITIONS  |
|---------------------|--|-----|--|
|                     |  | [0] | 1 = PO1 assertion depends on IN1 primary undervoltage threshold (Table 2).               |
|                     |  | [1] | 1 = PO1 assertion depends on IN2 primary undervoltage threshold (Table 3).               |
|                     |  | [2] | 1 = PO1 assertion depends on IN3 primary undervoltage threshold (Table 4).               |
| 0Eh                 | 800Eh  | [3] | 1 = PO1 assertion depends on IN4 primary undervoltage threshold (Table 4).               |
| UEN                 | 800EN  | [4] | 1 = PO1 assertion depends on IN5 primary undervoltage threshold (Table 4).               |
|                     |  | [5] | 1 = PO1 assertion depends on IN6 primary undervoltage threshold (Table 4).               |
|                     |  | [6] | 1 = PO1 assertion depends on watchdog 1 (Tables 27 and 28).                              |
|                     |  | [7] | 1 = PO1 assertion depends on watchdog 2 (Tables 27 and 28).                              |
|                     |  | [0] | 1 = PO1 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2). |
|                     |  | [1] | 1 = PO1 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3). |
|                     | 800Fh  | [2] | 1 = PO1 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4). |
| 0Fh                 |  | [3] | 1 = PO1 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4). |
| 0111                |  | [4] | 1 = PO1 assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). |
|                     |  | [5] | 1 = PO1 assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). |
|                     |  | [6] | 1 = PO1 assertion depends on GPI1 (Table 6).   |
|                     |  | [7] | 1 = PO1 assertion depends on GPI2 (Table 6).   |
|                     |  | [0] | 1 = PO1 assertion depends on GPI3 (Table 6).   |
|                     |  | [1] | 1 = PO1 assertion depends on GPI4 (Table 6).   |
|                     |  | [2] | 1 = PO1 assertion depends on PO2 (Table 11).   |
| 10h                 | 8010h  | [3] | 1 = PO1 assertion depends on PO3 (Tables 12 and 13).                                     |
| 1011                | 001011   | [4] | 1 = PO1 assertion depends on PO4 (Tables 14 and 15).                                     |
|                     |  | [5] | 1 = PO1 assertion depends on PO5 (Tables 16 and 17).                                     |
|                     |  | [6] | 1 = PO1 assertion depends on PO6 (Tables 18 and 19).                                     |
|                     |  | [7] | 1 = PO1 assertion depends on PO7 (Table 20).   |
| 11h                 | 8011h [0] 1 = PO1 assertion depends on PO8 (Table 21). |     | 1 = PO1 assertion depends on PO8 (Table 21).   |
| 40h                 | 8040h  | [0] | 1 = PO1 asserts when $\overline{\text{MR}}$ = low (Table 7).                             |

Table 10 only applies to PO1 of the MAX6870. Write a 0 to a bit to make the PO1 output independent of the respective signal (IN1-IN6 primary or secondary

thresholds, WDI1 or WDI2, GPI1–GPI4,  $\overline{MR}$ , or other programmable outputs).

Table 11. PO2 (MAX6870 Only) Output Dependency

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | ВІТ | OUTPUT ASSERTION CONDITIONS  |
|---------------------|-----------------------------|-----|--|
|                     |                             | [0] | 1 = PO2 assertion depends on IN1 primary undervoltage threshold (Table 2).               |
|                     |                             | [1] | 1 = PO2 assertion depends on IN2 primary undervoltage threshold (Table 3).               |
|                     |                             | [2] | 1 = PO2 assertion depends on IN3 primary undervoltage threshold (Table 4).               |
| 12h                 | 8012h                       | [3] | 1 = PO2 assertion depends on IN4 primary undervoltage threshold (Table 4).               |
| 1211                | 801211                      | [4] | 1 = PO2 assertion depends on IN5 primary undervoltage threshold (Table 4).               |
|                     |                             | [5] | 1 = PO2 assertion depends on IN6 primary undervoltage threshold (Table 4).               |
|                     |                             | [6] | 1 = PO2 assertion depends on watchdog 1 (Tables 27 and 28).                              |
|                     |                             | [7] | 1 = PO2 assertion depends on watchdog 2 (Tables 27 and 28).                              |
|                     |                             | [0] | 1 = PO2 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2). |
|                     |                             | [1] | 1 = PO2 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3). |
|                     | 8013h                       | [2] | 1 = PO2 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4). |
| 13h                 |                             | [3] | 1 = PO2 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4). |
| 1311                | 001311                      | [4] | 1 = PO2 assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). |
|                     |                             | [5] | 1 = PO2 assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). |
|                     |                             | [6] | 1 = PO2 assertion depends on GPI1 (Table 6).   |
|                     |                             | [7] | 1 = PO2 assertion depends on GPI2 (Table 6).   |
|                     |                             | [0] | 1 = PO2 assertion depends on GPI3 (Table 6).   |
|                     |                             | [1] | 1 = PO2 assertion depends on GPI4 (Table 6).   |
|                     |                             | [2] | 1 = PO2 assertion depends on PO1 (Table 10).   |
| 14h                 | 8014h                       | [3] | 1 = PO2 assertion depends on PO3 (Tables 12 and 13).                                     |
| 1411                | 001411                      | [4] | 1 = PO2 assertion depends on PO4 (Tables 14 and 15).                                     |
|                     |                             | [5] | 1 = PO2 assertion depends on PO5 (Tables 16 and 17).                                     |
|                     |                             | [6] | 1 = PO2 assertion depends on PO6 (Tables 18 and 19).                                     |
|                     |                             | [7] | 1 = PO2 assertion depends on PO7 (Table 20).   |
| 15h                 | 8015h                       | [0] | 1 = PO2 assertion depends on PO8 (Table 21).   |
| 40h                 | 8040h                       | [1] | 1 = PO2 asserts when $\overline{MR}$ = low (Table 7).                                    |

Table 11 only applies to PO2 of the MAX6870. Write a 0 to a bit to make the PO2 output independent of the respective signal (IN1-IN6 primary or secondary

thresholds, WDI1 or WDI2, GPI1–GPI4,  $\overline{\text{MR}}$ , or other programmable outputs).

Table 12. PO3 (MAX6870)/PO1 (MAX6871) Output Dependency (Product 1)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |
|---------------------|-----------------------------|-----|---|
|                     |                             | [0] | 1 = PO3/PO1 assertion depends on IN1 primary undervoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO3/PO1 assertion depends on IN2 primary undervoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO3/PO1 assertion depends on IN3 primary undervoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO3/PO1 assertion depends on IN4 primary undervoltage threshold (Table 4).  |
| 16h                 | 8016h                       | [4] | 1 = PO3 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [5] | 1 = PO3 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [6] | 1 = PO3/PO1 assertion depends on watchdog 1 (Tables 27 and 28).   |
|                     |                             | [7] | 1 = PO3/PO1 assertion depends on watchdog 2 (Tables 27 and 28).   |
|                     | 8017h                       | [0] | 1 = PO3/PO1 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO3/PO1 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO3/PO1 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO3/PO1 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |
| 17h                 |                             | [4] | 1 = PO3 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [5] | 1 = PO3 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [6] | 1 = PO3/PO1 assertion depends on GPI1 (Table 6).  |
|                     |                             | [7] | 1 = PO3/PO1 assertion depends on GPI2 (Table 6).  |
|                     |                             | [0] | 1 = PO3/PO1 assertion depends on GPI3 (Table 6).  |
|                     |                             | [1] | 1 = PO3/PO1 assertion depends on GPI4 (Table 6).  |
|                     |                             | [2] | 1 = PO3 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |
| 18h                 | 8018h                       | [3] | 1 = PO3 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |
| 1011                | 00 1011                     | [4] | 1 = PO3/PO1 assertion depends on PO4 (MAX6870)/PO2 (MAX6871) (Tables 14 and 15).  |
|                     |                             | [5] | 1 = PO3/PO1 assertion depends on PO5 (MAX6870)/PO3 (MAX6871) (Tables 16 and 17).  |
|                     |                             | [6] | 1 = PO3/PO1 assertion depends on PO6 (MAX6870)/PO4 (MAX6871) (Tables 18 and 19).  |
|                     |                             | [7] | 1 = PO3/PO1 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |
| 1Ch                 | 801Ch                       | [0] | 1 = PO3 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |
| 40h                 | 8040h                       | [2] | 1 = PO3/PO1 asserts when $\overline{MR}$ = low (Table 7).   |

Table 12 only applies to PO3 of the MAX6870 and PO1 of the MAX6871. Write a 0 to a bit to make the PO3/PO1 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1-GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 13 for Product 2. PO3 (MAX6870)/PO1 (MAX6871) deasserts when Product 1 or Product 2 = 1.

Table 13. PO3 (MAX6870)/PO1 (MAX6871) Output Dependency (Product 2)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |
|---------------------|-----------------------------|-----|---|
|                     |                             | [0] | 1 = PO3/PO1 assertion depends on IN1 primary undervoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO3/PO1 assertion depends on IN2 primary undervoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO3/PO1 assertion depends on IN3 primary undervoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO3/PO1 assertion depends on IN4 primary undervoltage threshold (Table 4).  |
| 19h                 | 8019h                       | [4] | 1 = PO3 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [5] | 1 = PO3 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [6] | 1 = PO3/PO1 assertion depends on watchdog 1 (Tables 27 and 28).   |
|                     |                             | [7] | 1 = PO3/PO1 assertion depends on watchdog 2 (Tables 27 and 28).   |
|                     |                             | [0] | 1 = PO3/PO1 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO3/PO1 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO3/PO1 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO3/PO1 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |
| 1Ah                 | 801Ah                       | [4] | 1 = PO3 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [5] | 1 = PO3 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [6] | 1 = PO3/PO1 assertion depends on GPI1 (Table 6).  |
|                     |                             | [7] | 1 = PO3/PO1 assertion depends on GPI2 (Table 6).  |
|                     |                             | [0] | 1 = PO3/PO1 assertion depends on GPI3 (Table 6).  |
|                     |                             | [1] | 1 = PO3/PO1 assertion depends on GPI4 (Table 6).  |
|                     |                             | [2] | 1 = PO3 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |
| 1Bh                 | 801Bh                       | [3] | 1 = PO3 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |
| IDII                | 001011                      | [4] | 1 = PO3/PO1 assertion depends on PO4 (MAX6870)/PO2 (MAX6871) (Tables 14 and 15).  |
|                     |                             | [5] | 1 = PO3/PO1 assertion depends on PO5 (MAX6870)/PO3 (MAX6871) (Tables 16 and 17).  |
|                     |                             | [6] | 1 = PO3/PO1 assertion depends on PO6 (MAX6870)/PO4 (MAX6871) (Tables 18 and 19).  |
|                     |                             | [7] | 1 = PO3/PO1 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |
| 1Ch                 | 801Ch                       | [1] | 1 = PO3 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |
| 40h                 | 8040h                       | [2] | $1 = PO3/PO1$ asserts when $\overline{MR} = low$ (Table 7).   |

Table 13 only applies to PO3 of the MAX6870 and PO1 of the MAX6871. Write a 0 to a bit to make the PO3/PO1 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1-GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 12 for Product 1. PO3 (MAX6870)/PO1 (MAX6871) deasserts when Product 1 or Product 2 = 1.

Table 14. PO4 (MAX6870)/PO2 (MAX6871) Output Dependency (Product 1)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |  |
|---------------------|-----------------------------|-----|---|--|
|                     |                             | [0] | 1 = PO4/PO2 assertion depends on IN1 primary undervoltage threshold (Table 2).  |  |
|                     |                             | [1] | 1 = PO4/PO2 assertion depends on IN2 primary undervoltage threshold (Table 3).  |  |
|                     |                             | [2] | 1 = PO4/PO2 assertion depends on IN3 primary undervoltage threshold (Table 4).  |  |
|                     |                             | [3] | 1 = PO4/PO2 assertion depends on IN4 primary undervoltage threshold (Table 4).  |  |
| 1Dh                 | 801Dh                       | [4] | 1 = PO4 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |  |
|                     |                             | [5] | 1 = PO4 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |  |
|                     |                             | [6] | 1 = PO4/PO2 assertion depends on watchdog 1 (Tables 27 and 28).   |  |
|                     |                             | [7] | 1 = PO4/PO2 assertion depends on watchdog 2 (Tables 27 and 28).   |  |
|                     |                             | [0] | 1 = PO4/PO2 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |  |
|                     |                             | [1] | 1 = PO4/PO2 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |  |
|                     |                             | [2] | 1 = PO4/PO2 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |  |
|                     |                             | [3] | 1 = PO4/PO2 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |  |
| 1Eh                 | 801Eh                       | [4] | 1 = PO4 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |  |
|                     |                             | [5] | 1 = PO4 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |  |
|                     |                             | [6] | 1 = PO4/PO2 assertion depends on GPI1 (Table 6).  |  |
|                     |                             | [7] | 1 = PO4/PO2 assertion depends on GPI2 (Table 6).  |  |
|                     |                             | [0] | 1 = PO4/PO2 assertion depends on GPI3 (Table 6).  |  |
|                     |                             | [1] | 1 = PO4/PO2 assertion depends on GPI4 (Table 6).  |  |
|                     |                             | [2] | 1 = PO4 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |  |
| 1Fh                 | 801Fh                       | [3] | 1 = PO4 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |  |
|                     | 00 1711                     | [4] | 1 = PO4/PO2 assertion depends on PO3 (MAX6870)/PO1 (MAX6871) (Tables 12 and 13).  |  |
|                     |                             | [5] | 1 = PO4/PO2 assertion depends on PO5 (MAX6870)/PO3 (MAX6871) (Tables 16 and 17).  |  |
|                     |                             | [6] | 1 = PO4/PO2 assertion depends on PO6 (MAX6870)/PO4 (MAX6871) (Tables 18 and 19).  |  |
|                     |                             | [7] | 1 = PO4/PO2 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |  |
| 23h                 | 8023h                       | [0] | 1 = PO4 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |  |
| 40h                 | 8040h                       | [3] | $1 = PO4/PO2$ asserts when $\overline{MR} = low$ (Table 7).   |  |

Table 14 only applies to PO4 of the MAX6870 and PO2 of the MAX6871. Write a 0 to a bit to make the PO4/PO2 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1-GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 15 for Product 2. PO4 (MAX6870)/PO2 (MAX6871) deasserts when Product 1 or Product 2 = 1.

Table 15. PO4 (MAX6870)/PO2 (MAX6871) Output Dependency (Product 2)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |
|---------------------|-----------------------------|-----|---|
|                     |                             | [0] | 1 = PO4/PO2 assertion depends on IN1 primary undervoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO4/PO2 assertion depends on IN2 primary undervoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO4/PO2 assertion depends on IN3 primary undervoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO4/PO2 assertion depends on IN4 primary undervoltage threshold (Table 4).  |
| 20h                 | 8020h                       | [4] | 1 = PO4 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [5] | 1 = PO4 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [6] | 1 = PO4/PO2 assertion depends on watchdog 1 (Tables 27 and 28).   |
|                     |                             | [7] | 1 = PO4/PO2 assertion depends on watchdog 2 (Tables 27 and 28).   |
|                     |                             | [0] | 1 = PO4/PO2 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO4/PO2 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO4/PO2 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO4/PO2 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |
| 21h                 | 8021h                       | [4] | 1 = PO4 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [5] | 1 = PO4 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [6] | 1 = PO4/PO2 assertion depends on GPI1 (Table 6).  |
|                     |                             | [7] | 1 = PO4/PO2 assertion depends on GPI2 (Table 6).  |
|                     |                             | [0] | 1 = PO4/PO2 assertion depends on GPI3 (Table 6).  |
|                     |                             | [1] | 1 = PO4/PO2 assertion depends on GPI4 (Table 6).  |
|                     |                             | [2] | 1 = PO4 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |
| 22h                 | 8022h                       | [3] | 1 = PO4 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |
| 2211                | OUZZII                      | [4] | 1 = PO4/PO2 assertion depends on PO3 (MAX6870)/PO1 (MAX6871) (Tables 12 and 13).  |
|                     |                             | [5] | 1 = PO4/PO2 assertion depends on PO5 (MAX6870)/PO3 (MAX6871) (Tables 16 and 17).  |
|                     |                             | [6] | 1 = PO4/PO2 assertion depends on PO6 (MAX6870)/PO4 (MAX6871) (Tables 18 and 19).  |
|                     |                             | [7] | 1 = PO4/PO2 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |
| 23h                 | 8023h                       | [1] | 1 = PO4 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |
| 40h                 | 8040h                       | [3] | 1 = PO4/PO2 asserts when MR = low (Table 7).  |

Table 15 only applies to PO4 of the MAX6870 and PO2 of the MAX6871. Write a 0 to a bit to make the PO4/PO2 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1 to GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 14 for Product 1. PO4 (MAX6870)/PO2 (MAX6871) deasserts when Product 1 or Product 2 = 1.

Table 16. PO5 (MAX6870)/PO3 (MAX6871) Output Dependency (Product 1)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |
|---------------------|-----------------------------|-----|---|
|                     |                             | [0] | 1 = PO5/PO3 assertion depends on IN1 primary undervoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO5/PO3 assertion depends on IN2 primary undervoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO5/PO3 assertion depends on IN3 primary undervoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO5/PO3 assertion depends on IN4 primary undervoltage threshold (Table 4).  |
| 24h                 | 8024h                       | [4] | 1 = PO5 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [5] | 1 = PO5 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [6] | 1 = PO5/PO3 assertion depends on watchdog 1 (Tables 27 and 28).   |
|                     |                             | [7] | 1 = PO5/PO3 assertion depends on watchdog 2 (Tables 27 and 28).   |
|                     | 8025h                       | [0] | 1 = PO5/PO3 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO5/PO3 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO5/PO3 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO5/PO3 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |
| 25h                 |                             | [4] | 1 = PO5 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [5] | 1 = PO5 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [6] | 1 = PO5/PO3 assertion depends on GPI1 (Table 6).  |
|                     |                             | [7] | 1 = PO5/PO3 assertion depends on GPI2 (Table 6).  |
|                     |                             | [0] | 1 = PO5/PO3 assertion depends on GPI3 (Table 6).  |
|                     |                             | [1] | 1 = PO5/PO3 assertion depends on GPI4 (Table 6).  |
|                     |                             | [2] | 1 = PO5 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |
| 26h                 | 8026h                       | [3] | 1 = PO5 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |
| 2011                | 802011                      | [4] | 1 = PO5/PO3 assertion depends on PO3 (MAX6870)/PO1 (MAX6871) (Tables 12 and 13).  |
|                     |                             | [5] | 1 = PO5/PO3 assertion depends on PO4 (MAX6870)/PO2 (MAX6871) (Tables 14 and 15).  |
|                     |                             | [6] | 1 = PO5/PO3 assertion depends on PO6 (MAX6870)/PO4 (MAX6871) (Tables 18 and 19).  |
|                     |                             | [7] | 1 = PO5/PO3 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |
| 2Ah                 | 802Ah                       | [0] | 1 = PO5 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |
| 40h                 | 8040h                       | [4] | $1 = PO5/PO3$ asserts when $\overline{MR} = low$ (Table 7).   |

Table 16 only applies to PO5 of the MAX6870 and PO3 of the MAX6871. Write a 0 to a bit to make the PO5/PO3 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1-GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 17 for Product 2. PO5 (MAX6870)/PO3 (MAX6871) deasserts when Product 1 or Product 2 = 1.

Table 17. PO5 (MAX6870)/PO3 (MAX6871) Output Dependency (Product 2)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |
|---------------------|-----------------------------|-----|---|
|                     |                             | [0] | 1 = PO5/PO3 assertion depends on IN1 primary undervoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO5/PO3 assertion depends on IN2 primary undervoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO5/PO3 assertion depends on IN3 primary undervoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO5/PO3 assertion depends on IN4 primary undervoltage threshold (Table 4).  |
| 27h                 | 8027h                       | [4] | 1 = PO5 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [5] | 1 = PO5 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [6] | 1 = PO5/PO3 assertion depends on watchdog 1 (Tables 27 and 28).   |
|                     |                             | [7] | 1 = PO5/PO3 assertion depends on watchdog 2 (Tables 27 and 28).   |
|                     |                             | [0] | 1 = PO5/PO3 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |
|                     | 8028h                       | [1] | 1 = PO5/PO3 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO5/PO3 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO5/PO3 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |
| 28h                 |                             | [4] | 1 = PO5 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [5] | 1 = PO5 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [6] | 1 = PO5/PO3 assertion depends on GPI1 (Table 6).  |
|                     |                             | [7] | 1 = PO5/PO3 assertion depends on GPI2 (Table 6).  |
|                     |                             | [0] | 1 = PO5/PO3 assertion depends on GPI3 (Table 6).  |
|                     |                             | [1] | 1 = PO5/PO3 assertion depends on GPI4 (Table 6).  |
|                     |                             | [2] | 1 = PO5 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |
| 29h                 | 8029h                       | [3] | 1 = PO5 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |
| ا ال                | 002311                      | [4] | 1 = PO5/PO3 assertion depends on PO3 (MAX6870)/PO1 (MAX6871) (Tables 12 and 13).  |
|                     |                             | [5] | 1 = PO5/PO3 assertion depends on PO4 (MAX6870)/PO2 (MAX6871) (Tables 14 and 15).  |
|                     |                             | [6] | 1 = PO5/PO3 assertion depends on PO6 (MAX6870)/PO4 (MAX6871) (Tables 18 and 19).  |
|                     |                             | [7] | 1 = PO5/PO3 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |
| 3Bh                 | 803Bh                       | [4] | 1 = PO5 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |
| 40h                 | 8040h                       | [4] | 1 = PO5/PO3 asserts when $\overline{MR}$ = low (Table 7).   |

Table 17 only applies to PO5 of the MAX6870 and PO3 of the MAX6871. Write a 0 to a bit to make the PO5/PO3 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1-GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 16 for Product 1. PO5 (MAX6870)/PO3 (MAX6871) deasserts when Product 1 or Product 2 = 1.

Table 18. PO6 (MAX6870)/PO4 (MAX6871) Output Dependency (Product 1)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |  |  |
|---------------------|-----------------------------|-----|---|--|--|
|                     |                             | [0] | 1 = PO6/PO4 assertion depends on IN1 primary undervoltage threshold (Table 2).  |  |  |
|                     |                             | [1] | 1 = PO6/PO4 assertion depends on IN2 primary undervoltage threshold (Table 3).  |  |  |
|                     |                             | [2] | 1 = PO6/PO4 assertion depends on IN3 primary undervoltage threshold (Table 4).  |  |  |
|                     |                             | [3] | 1 = PO6/PO4 assertion depends on IN4 primary undervoltage threshold (Table 4).  |  |  |
| 2Bh                 | 802Bh                       | [4] | 1 = PO6 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |  |  |
|                     |                             | [5] | 1 = PO6 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |  |  |
|                     |                             | [6] | 1 = PO6/PO4 assertion depends on watchdog 1 (Tables 27 and 28).   |  |  |
|                     |                             | [7] | 1 = PO6/PO4 assertion depends on watchdog 2 (Tables 27 and 28).   |  |  |
|                     |                             | [0] | 1 = PO6/PO4 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |  |  |
|                     |                             | [1] | 1 = PO6/PO4 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |  |  |
|                     |                             | [2] | 1 = PO6/PO4 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |  |  |
|                     |                             | [3] | 1 = PO6/PO4 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |  |  |
| 2Ch                 | 802Ch                       | [4] | 1 = PO6 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |  |  |
|                     |                             | [5] | 1 = PO6 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |  |  |
|                     |                             | [6] | 1 = PO6/PO4 assertion depends on GPI1 (Table 6).  |  |  |
|                     |                             | [7] | 1 = PO6/PO4 assertion depends on GPI2 (Table 6).  |  |  |
|                     |                             | [0] | 1 = PO6/PO4 assertion depends on GPI3 (Table 6).  |  |  |
|                     |                             | [1] | 1 = PO6/PO4 assertion depends on GPI4 (Table 6).  |  |  |
|                     |                             | [2] | 1 = PO6 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |  |  |
| 2Dh                 | 802Dh                       | [3] | 1 = PO6 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |  |  |
| 2011                | 002011                      | [4] | 1 = PO6/PO4 assertion depends on PO3 (MAX6870)/PO1 (MAX6871) (Tables 12 and 13).  |  |  |
|                     |                             | [5] | 1 = PO6/PO4 assertion depends on PO4 (MAX6870)/PO2 (MAX6871) (Tables 14 and 15).  |  |  |
|                     |                             | [6] | 1 = PO6/PO4 assertion depends on PO5 (MAX6870)/PO3 (MAX6871) (Tables 16 and 17).  |  |  |
| [7]                 |                             | [7] | 1 = PO6/PO4 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |  |  |
| 31h                 | 8031h                       | [0] | 1 = PO6 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |  |  |
| 40h                 | 8040h                       | [5] | 1 = PO6/PO4 asserts when $\overline{MR}$ = low (Table 7).   |  |  |

Table 18 only applies to PO6 of the MAX6870 and PO4 of the MAX6871. Write a 0 to a bit to make the PO6/PO4 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1-GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 19 for Product 2. PO6 (MAX6870)/PO4 (MAX6871) deasserts when Product 1 or Product 2 = 1.

Table 19. PO6 (MAX6870)/PO4 (MAX6871) Output Dependency (Product 2)

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | ВІТ | OUTPUT ASSERTION CONDITIONS   |
|---------------------|-----------------------------|-----|---|
|                     |                             | [0] | 1 = PO6/PO4 assertion depends on IN1 primary undervoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO6/PO4 assertion depends on IN2 primary undervoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO6/PO4 assertion depends on IN3 primary undervoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO6/PO4 assertion depends on IN4 primary undervoltage threshold (Table 4).  |
| 2Eh                 | 802Eh                       | [4] | 1 = PO6 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [5] | 1 = PO6 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |
|                     |                             | [6] | 1 = PO6/PO4 assertion depends on watchdog 1 (Tables 27 and 28).   |
|                     |                             | [7] | 1 = PO6/PO4 assertion depends on watchdog 2 (Tables 27 and 28).   |
|                     | 802Fh                       | [0] | 1 = PO6/PO4 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |
|                     |                             | [1] | 1 = PO6/PO4 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |
|                     |                             | [2] | 1 = PO6/PO4 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |
|                     |                             | [3] | 1 = PO6/PO4 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |
| 2Fh                 |                             | [4] | 1 = PO6 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [5] | 1 = PO6 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |
|                     |                             | [6] | 1 = PO6/PO4 assertion depends on GPI1 (Table 6).  |
|                     |                             | [7] | 1 = PO6/PO4 assertion depends on GPI2 (Table 6).  |
|                     |                             | [0] | 1 = PO6/PO4 assertion depends on GPI3 (Table 6).  |
|                     |                             | [1] | 1 = PO6/PO4 assertion depends on GPI4 (Table 6).  |
|                     |                             | [2] | 1 = PO6 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |
| 30h                 | 8030h                       | [3] | 1 = PO6 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |
| 3011                | 003011                      | [4] | 1 = PO6/PO4 assertion depends on PO3 (MAX6870)/PO1 (MAX6871) (Tables 12 and 13).  |
|                     |                             | [5] | 1 = PO6/PO4 assertion depends on PO4 (MAX6870)/PO2 (MAX6871) (Tables 14 and 15).  |
|                     |                             | [6] | 1 = PO6/PO4 assertion depends on PO5 (MAX6870)/PO3 (MAX6871) (Tables 16 and 17).  |
|                     |                             | [7] | 1 = PO6/PO4 assertion depends on PO7 (MAX6870)/PO5 (MAX6871) (Table 20).  |
| 3Bh                 | 803Bh                       | [5] | 1 = PO6 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |
| 40h                 | 8040h                       | [5] | 1 = PO6/PO4 asserts when MR = low (Table 7).  |

Table 19 only applies to PO6 of the MAX6870 and PO4 of the MAX6871. Write a 0 to a bit to make the PO6/PO4 output independent of the respective signal (IN\_ primary or secondary thresholds, WDI1 or WDI2, GPI1-GPI4,

 $\overline{\text{MR}}$ , or other programmable outputs). See Table 18 for Product 1. PO6 (MAX6870)/PO4 (MAX6871) deasserts when Product 1 or Product 2 = 1.

## Table 20. PO7 (MAX6870)/PO5 (MAX6871) Output Dependency

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS   |  |  |
|---------------------|-----------------------------|-----|---|--|--|
|                     |                             | [0] | 1 = PO7/PO5 assertion depends on IN1 primary undervoltage threshold (Table 2).  |  |  |
|                     |                             | [1] | 1 = PO7/PO5 assertion depends on IN2 primary undervoltage threshold (Table 3).  |  |  |
|                     |                             | [2] | 1 = PO7/PO5 assertion depends on IN3 primary undervoltage threshold (Table 4).  |  |  |
|                     |                             | [3] | 1 = PO7/PO5 assertion depends on IN4 primary undervoltage threshold (Table 4).  |  |  |
| 32h                 | 8032h                       | [4] | 1 = PO7 (MAX6870 only) assertion depends on IN5 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |  |  |
|                     |                             | [5] | 1 = PO7 (MAX6870 only) assertion depends on IN6 primary undervoltage threshold (Table 4). Must be set to 0 for the MAX6871.               |  |  |
|                     |                             | [6] | 1 = PO7/PO5 assertion depends on watchdog 1 (Tables 27 and 28).   |  |  |
|                     |                             | [7] | 1 = PO7/PO5 assertion depends on watchdog 2 (Tables 27 and 28).   |  |  |
|                     |                             | [0] | 1 = PO7/PO5 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2).  |  |  |
|                     |                             | [1] | 1 = PO7/PO5 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3).  |  |  |
|                     |                             | [2] | 1 = PO7/PO5 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4).  |  |  |
|                     | 8033h                       | [3] | 1 = PO7/PO5 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4).  |  |  |
| 33h                 |                             | [4] | 1 = PO7 (MAX6870 only) assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |  |  |
|                     |                             | [5] | 1 = PO7 (MAX6870 only) assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). Must be set to 0 for the MAX6871. |  |  |
|                     |                             | [6] | 1 = PO7/PO5 assertion depends on GPI1 (Table 6).  |  |  |
|                     |                             | [7] | 1 = PO7/PO5 assertion depends on GPI2 (Table 6).  |  |  |
|                     |                             | [0] | 1 = PO7/PO5 assertion depends on GPI3 (Table 6).  |  |  |
|                     |                             | [1] | 1 = PO7/PO5 assertion depends on GPI4 (Table 6).  |  |  |
|                     |                             | [2] | 1 = PO7 (MAX6870 only) assertion depends on PO1 (Table 10). Must be set to 0 for the MAX6871.   |  |  |
| 34h                 | 8034h                       | [3] | 1 = PO7 (MAX6870 only) assertion depends on PO2 (Table 11). Must be set to 0 for the MAX6871.   |  |  |
| 3411                | 003411                      | [4] | 1 = PO7/PO5 assertion depends on PO3 (MAX6870)/PO1 (MAX6871) (Tables 12 and 13).  |  |  |
|                     |                             | [5] | 1 = PO7/PO5 assertion depends on PO4 (MAX6870)/PO2 (MAX6871) (Tables 14 and 15).  |  |  |
|                     |                             | [6] | 1 = PO7/PO5 assertion depends on PO5 (MAX6870)/PO3 (MAX6871) (Tables 16 and 17).  |  |  |
|                     | •                           | [7] | 1 = PO7/PO5 assertion depends on PO6 (MAX6870)/PO4 (MAX6871) (Tables 18 and 19).  |  |  |
| 35h                 | 8035h                       | [0] | 1 = PO7 (MAX6870 only) assertion depends on PO8 (Table 21). Must be set to 0 for the MAX6871.   |  |  |
| 40h                 | 8040h                       | [6] | 1 = PO7 asserts when MR = low (Table 7).  |  |  |

Table 20 only applies to PO7 of the MAX6870 and PO5 of the MAX6871. Write a 0 to a bit to make the PO7/PO5 output independent of the respective signal (IN\_ primary

or secondary thresholds, WDI1 or WDI2, GPI1–GPI4, MR, or other programmable outputs).

Table 21. PO8 (MAX6870 only) Output Dependency

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT | OUTPUT ASSERTION CONDITIONS  |
|---------------------|-----------------------------|-----|--|
|                     |                             | [0] | 1 = PO8 assertion depends on IN1 primary undervoltage threshold (Table 2).               |
|                     |                             | [1] | 1 = PO8 assertion depends on IN2 primary undervoltage threshold (Table 3).               |
|                     |                             | [2] | 1 = PO8 assertion depends on IN3 primary undervoltage threshold (Table 4).               |
| 36h                 | 8036h                       | [3] | 1 = PO8 assertion depends on IN4 primary undervoltage threshold (Table 4).               |
| 3011                | 803611                      | [4] | 1 = PO8 assertion depends on IN5 primary undervoltage threshold (Table 4).               |
|                     |                             | [5] | 1 = PO8 assertion depends on IN6 primary undervoltage threshold (Table 4).               |
|                     |                             | [6] | 1 = PO8 assertion depends on watchdog 1 (Tables 27 and 28).                              |
|                     |                             | [7] | 1 = PO8 assertion depends on watchdog 2 (Tables 27 and 28).                              |
|                     |                             | [0] | 1 = PO8 assertion depends on IN1 secondary undervoltage/overvoltage threshold (Table 2). |
|                     | 8037h                       | [1] | 1 = PO8 assertion depends on IN2 secondary undervoltage/overvoltage threshold (Table 3). |
|                     |                             | [2] | 1 = PO8 assertion depends on IN3 secondary undervoltage/overvoltage threshold (Table 4). |
| 37h                 |                             | [3] | 1 = PO8 assertion depends on IN4 secondary undervoltage/overvoltage threshold (Table 4). |
| 3/11                |                             | [4] | 1 = PO8 assertion depends on IN5 secondary undervoltage/overvoltage threshold (Table 4). |
|                     |                             | [5] | 1 = PO8 assertion depends on IN6 secondary undervoltage/overvoltage threshold (Table 4). |
|                     |                             | [6] | 1 = PO8 assertion depends on GPI1 (Table 6).   |
|                     |                             | [7] | 1 = PO8 assertion depends on GPI2 (Table 6).   |
|                     |                             |     | 1 = PO8 assertion depends on GPI3 (Table 6).   |
|                     |                             | [1] | 1 = PO8 assertion depends on GPI4 (Table 6).   |
|                     |                             | [2] | 1 = PO8 assertion depends on PO1 (Table 10).   |
| 38h                 | 8038h                       | [3] | 1 = PO8 assertion depends on PO2 (Table 11).   |
| 3011                | 003011                      | [4] | 1 = PO8 assertion depends on PO3 (Tables 12 and 13).                                     |
|                     |                             | [5] | 1 = PO8 assertion depends on PO4 (Tables 14 and 15).                                     |
|                     |                             | [6] | 1 = PO8 assertion depends on PO5 (Tables 16 and 17).                                     |
|                     |                             | [7] | 1 = PO8 assertion depends on PO6 (Tables 18 and 19).                                     |
| 39h                 | 8039h                       | [0] | 1 = PO8 assertion depends on PO7 (Table 20).   |
| 40h                 | 8040h                       | [7] | 1 = PO8 asserts when $\overline{MR}$ = low (Table 7).                                    |

Table 21 only applies to PO8 of the MAX6870. Write a 0 to a bit to make the PO8 output independent of the respective signal (IN1–IN6 primary or secondary thresholds, WDI1 or WDI2, GPI1–GPI4,  $\overline{\text{MR}}$ , or other programmable outputs).

### **Output Stage Configurations**

Independently program each programmable output as active-high or active-low (Table 22). Additionally, program each programmable output as weak pullup, pushpull, open-drain, or charge pump (Tables 23 and 24). Every programmable output can be configured as open-drain or weak pullup; however, only PO1–PO4 (MAX6870) or PO1/PO2 (MAX6871) can be configured

as charge-pump outputs, and only PO5–PO8 (MAX6870) or PO3/PO4/PO5 (MAX6871) can be configured as push-pull outputs. Finally, set the PO\_ timeout period for each programmable output (Table 25).

An internal  $10k\Omega$  resistor provides the pullup resistance for outputs configured as weak pullup stages. Program each weak pullup output stage to refer to ABP or one of the IN3–IN6 inputs. The programmable outputs source up to 10mA and sink up to 4mA when configured as pushpull stages. Program each push-pull output stage to reference to one of IN3–IN6. PO1–PO4 (MAX6870)/PO1/P02 (MAX6871) pull to VABP + 5V when configured as charge-pump outputs.

**Table 22. Programmable Output Active States** 

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | DESCRIPTION   |
|---------------------|-----------------------------|--------------|---|
|                     | [0]                         |              | PO1 (MAX6870 only). 0 = active-low, 1 = active-high.          |
|                     |                             | [1]          | PO2 (MAX6870 only). 0 = active-low, 1 = active-high.          |
|                     |                             | [2]          | PO3 (MAX6870)/PO1 (MAX6871). 0 = active-low, 1 = active-high. |
| 0.4 h               | 00046                       | [3]          | PO4 (MAX6870)/PO2 (MAX6871). 0 = active-low, 1 = active-high. |
| 3Ah                 | 803Ah                       | [4]          | PO5 (MAX6870)/PO3 (MAX6871). 0 = active-low, 1 = active-high. |
|                     |                             | [5]          | PO6 (MAX6870)/PO4 (MAX6871). 0 = active-low, 1 = active-high. |
|                     |                             | [6]          | PO7 (MAX6870)/PO5 (MAX6871). 0 = active-low, 1 = active-high. |
|                     |                             | [7]          | PO8 (MAX6870 only). 0 = active-low, 1 = active-high.          |

## **Table 23. Programmable Output Stage Options (MAX6870)**

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | AFFECTED<br>OUTPUT | DESCRIPTION   |  |  |
|---------------------|-----------------------------|--------------|--------------------|---|--|--|
| 11h                 | 8011h                       | [6:4]        | PO1                |   |  |  |
| 15h                 | 8015h                       | [6:4]        | PO2                | 000 = open-drain, 001 = weak pullup to IN3, 010 = weak pullup to IN4,   |  |  |
| 1Ch                 | 801Ch                       | [7:5]        | PO3                | 011 = weak pullup to IN5, 100 = weak pullup to IN6, 101 = weak pullup to ABP, 110 = charge-pump output, 111 = not used. |  |  |
| 23h                 | 8023h                       | [7:5]        | PO4                | 7 El , 110 = Gharge pamp edipat, 111 = Het dood.  |  |  |
| 2Ah                 | 802Ah                       | [7:4]        | PO5                | 0000 = open-drain, 0001 = weak pullup to IN3, 0010 = weak pullup to IN4,  |  |  |
| 31h                 | 8031h                       | [7:4]        | PO6                | 0011 = weak pullup to IN5, 0100 = weak pullup to IN6, 0101 = weak pullup to   |  |  |
| 35h                 | 8035h                       | [7:4]        | PO7                | ABP, 0110 = push-pull to IN3, 0111 = push-pull to IN4, 1000 = push-pull to  |  |  |
| 39h                 | 8039h                       | [7:4]        | PO8                | IN5, 1001 = push-pull to IN6, 1010 through 1111 = not used.   |  |  |

## **Table 24. Programmable Output Stage Options (MAX6871)**

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | AFFECTED<br>OUTPUT | DESCRIPTION   |
|---------------------|-----------------------------|--------------|--------------------|---|
| 1Ch                 | 801Ch                       | [7:5]        | PO1                | 000 = open-drain, 001 = weak pullup to IN3, 010 = weak pullup to IN4, 011-100 = not used, 101 = weak pullup to ABP, 110 = charge-pump output, |
| 23h                 | 8023h                       | [7:5]        | PO2                | 111 = not used.   |
| 2Ah                 | 802Ah                       | [7:4]        | PO3                | 0000 = open-drain, 0001 = weak pullup to IN3, 0010 = weak pullup to IN4,  |
| 31h                 | 8031h                       |              |                    | 0011-0100 = not used, 0101 = weak pullup to ABP, 0110 = push-pull to IN3,   |
| 35h                 | 8035h                       | [7:4]        | PO5                | 0111 = push-pull to IN4, 1000–1111 = not used.  |

Table 25. PO\_ Timeout Periods

| REGISTER | EEPROM<br>MEMORY | BIT RANGE | AFFECTE | OUTPUTS | DESCRIPTION                       |  |  |
|----------|------------------|-----------|---------|---------|-----------------------------------|--|--|
| ADDRESS  | ADDRESS          | BII KANGE | MAX6870 | MAX6871 | DESCRIPTION                       |  |  |
| 11h      | 8011h            | [3:1]     | PO1     | _       |                                   |  |  |
| 15h      | 8015h            | [3:1]     | PO2     | _       | $000 = 25\mu s$<br>001 = 1.5625ms |  |  |
| 1Ch      | 801Ch            | [4:2]     | PO3     | PO1     | 010 = 1.36231118<br>010 = 6.25ms  |  |  |
| 23h      | 8023h            | [4:2]     | PO4     | PO2     | 011 = 25ms                        |  |  |
| 2Ah      | 802Ah            | [3:1]     | PO5     | PO3     | 100 = 50ms                        |  |  |
| 31h      | 8031h            | [3:1]     | PO6     | PO4     | 101 = 200ms                       |  |  |
| 35h      | 8035h            | [3:1]     | PO7     | PO5     | 110 = 400ms<br>111 = 1600ms       |  |  |
| 39h      | 8039h            | [3:1]     | PO8     | _       | - 111 = 10001110                  |  |  |

#### Charge-Pump Output Configuration

Configure the programmable outputs of the MAX6870/ MAX6871 as charge-pump outputs to drive n-channel FETs for power-supply sequencing applications. Only PO1–PO4 (MAX6870) or PO1 and PO2 (MAX6871) can be configured as charge-pump output stages. The charge-pump output high voltage is typically VABP +5.5V when unloaded.

### **Push-Pull Output Configuration**

The MAX6870/MAX6871's programmable outputs sink 4mA and source 10mA when configured as push-pull outputs. Only PO5–PO8 (MAX6870), or PO3/PO4/PO5 (MAX6871) can be configured as push-pull output stages. The push-pull output stages refer to any of IN3–IN6 (MAX6870)/IN3/IN4 (MAX6871) as configured in Tables 23 and 24. Use the push-pull output configuration to drive loads with fast rise/fall times, or those with low impedance.

#### Weak Pullup Output Configuration

The MAX6870/MAX6871's programmable outputs sink 4mA when configured as weak pullups. The weak pullup of  $10k\Omega$  refers to any of IN3–IN6 (MAX6870)/IN3/IN4 (MAX6871) or ABP as configured in Tables 23 and 24. All programmable outputs of the MAX6870/MAX6871 may be configured as weak pullups.

#### Open-Drain Output Configuration

Connect an external pullup resistor from the programmable output to an external voltage when configured as an open-drain output. PO1–PO4 (PO1 and PO2 for the MAX6871) may be pulled up to +13.2V. PO5–PO8 (PO3–PO5 for the MAX6871) may be pulled up to a voltage less than or equal to ABP. Choose the pullup resistor depending on the number of devices connected to the open-drain output and the allowable current consumption. The open-drain output configuration

allows wire-ORed connections, and provides flexibility in setting the pullup current.

### Configuring the MAX6870/MAX6871

The MAX6870/MAX6871 factory-default configuration sets all registers to 00h except 3Ah, which is set to FFh. Each device requires configuration before full power is applied to the system. To configure the MAX6870/ MAX6871, first apply an input voltage to IN1 or one of IN3-IN6 (MAX6870)/IN3/IN4 (MAX6871) (see the Powering the MAX6870/MAX6871 section). V<sub>IN1</sub> > +4V or one of  $V_{IN3}$ – $V_{IN6}$  > +2.7V, to ensure device operation. Next, transmit data through the serial interface. Use the block write protocol to quickly configure the device. Write to the configuration registers first to ensure the device is configured properly. After completing the setup procedure, use the read word protocol to verify the data from the configuration registers. Lastly, use the write word protocol to write this data to the EEPROM registers. After completing EEPROM register configuration, apply full power to the system to begin normal operation. The nonvolatile EEPROM stores the latest configuration upon removal of power. Write 0's to all EEPROM registers to clear the memory.

### Software Reboot

A software reboot allows the user to restore the EEPROM configuration to the volatile registers without cycling the power supplies. Use the send byte command with data byte 88h to initiate a software reboot. The 3.5ms (max) power-up delay also applies after a software reboot.

### SMBus/I<sup>2</sup>C-Compatible Serial Interface

The MAX6870/MAX6871 feature an I<sup>2</sup>C/SMBus-compatible serial interface consisting of a serial data line (SDA) and a serial clock line (SCL). SDA and SCL allow bidirectional communication between the MAX6870/MAX6871

and the master device at clock rates up to 400kHz. Figure 2 shows the interface timing diagram. The MAX6870/MAX6871 are transmit/receive slave-only devices, relying upon a master device to generate a clock signal. The master device (typically a microcontroller) initiates data transfer on the bus and generates SCL to permit that transfer.

A master device communicates to the MAX6870/ MAX6871 by transmitting the proper address followed by command and/or data words. Each transmit sequence is framed by a START (S) or REPEATED START (SR) condition and a STOP (P) condition. Each word transmitted over the bus is 8 bits long and is always followed by an acknowledge pulse.

SCL is a logic input, while SDA is a logic input/opendrain output. SCL and SDA both require external pullup resistors to generate the logic-high voltage. Use 4.7k $\!\Omega$  for most applications.

#### Bit Transfer

Each clock pulse transfers one data bit. The data on SDA must remain stable while SCL is high (Figure 3), otherwise the MAX6870/MAX6871 register a START or STOP condition (Figure 4) from the master. SDA and SCL idle high when the bus is not busy.

### Start and Stop Conditions

Both SCL and SDA idle high when the bus is not busy. A master device signals the beginning of a transmission with a START (S) condition (Figure 4) by transitioning SDA from high to low while SCL is high. The master device issues a STOP (P) condition (Figure 4) by transitioning SDA from low to high while SCL is high. A STOP

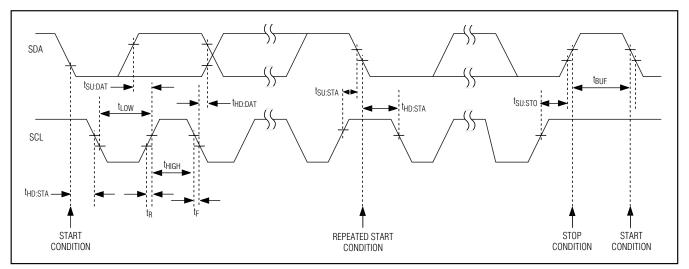


Figure 2. Serial-Interface Timing Details

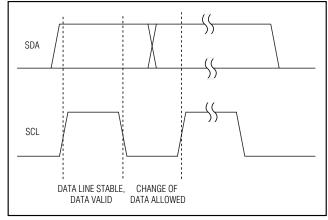


Figure 3. Bit Transfer

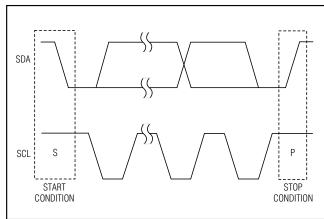


Figure 4. Start and Stop Conditions

condition frees the bus for another transmission. The bus remains active if a REPEATED START condition is generated, such as in the block read protocol (see Figure 7).

### Early STOP Conditions

The MAX6870/MAX6871 recognize a STOP condition at any point during transmission except if a STOP condition occurs in the same high pulse as a START condition. This condition is not a legal I<sup>2</sup>C format. At least one clock pulse must separate any START and STOP condition.

### Repeated START Conditions

A REPEATED START (SR) condition may indicate a change of data direction on the bus. Such a change occurs when a command word is required to initiate a read operation (see Figure 7). SR may also be used when the bus master is writing to several I<sup>2</sup>C devices and does not want to relinquish control of the bus. The MAX6870/MAX6871 serial interface supports continuous write operations with or without an SR condition separating them. Continuous read operations require SR conditions because of the change in direction of data flow.

### Acknowledge

The acknowledge bit (ACK) is the 9th bit attached to any 8-bit data word. The receiving device always generates

an ACK. The MAX6870/MAX6871 generate an ACK when receiving an address or data by pulling SDA low during the 9th clock period (Figure 5). When transmitting data, such as when the master device reads data back from the MAX6870/MAX6871, the MAX6870/MAX6871 wait for the master device to generate an ACK. Monitoring ACK allows for detection of unsuccessful data transfers. An unsuccessful data transfer occurs if the receiving device is busy or if a system fault has occurred. In the event of an unsuccessful data transfer, the bus master should reattempt communication at a later time. The MAX6870/MAX6871 generate a NACK after the slave address during a software reboot, while writing to the EEPROM, or when receiving an illegal memory address.

### Slave Address

The MAX6870/MAX6871 slave address conforms to the following table:

| SA7<br>(MSB) | SA6 | SA5 | SA4 | SA3 | SA2 | SA1 | SA0<br>(LSB) |
|--------------|-----|-----|-----|-----|-----|-----|--------------|
| 1            | 0   | 1   | 0   | A1  | Α0  | Χ   | R/W          |

X = Don't care.

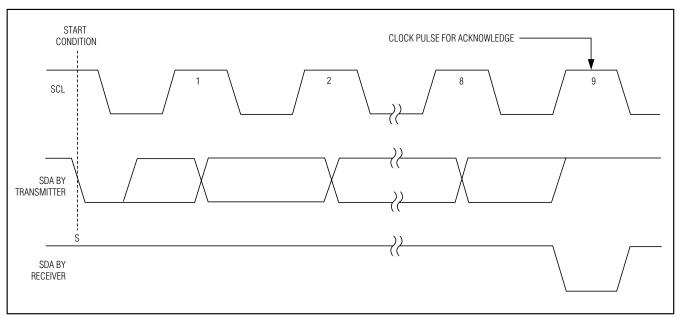


Figure 5. Acknowledge

SA7 through SA4 represent the standard interface address (1010) for devices with EEPROM. SA3 and SA2 correspond to the A1 and A0 address inputs of the MAX6870/MAX6871 (hard-wired as logic-low or logic-high). SA0 is a read/write flag bit (0 = write, 1 = read).

The A0 and A1 address inputs allow up to four MAX6870/MAX6871 devices to connect to one bus. Connect A0 and A1 to GND or to the serial interface power supply (see Figure 6).

### Send Byte

The send byte protocol allows the master device to send one byte of data to the slave device (see Figure 7). The send byte presets a register pointer address for a subsequent read or write. The slave sends a NACK instead of an ACK if the master tries to send an address that is not allowed. If the master sends 80h, 81h, or 82h, the data is ACK. This could be start of the write byte/word protocol, and the slave expects at least one further data byte. If the master sends a stop condition, the internal address pointer does not change. If the master sends 84h, this signifies that the block read protocol is expected, and a repeated start condition should follow. The device reboots if the master sends 88h. The send byte procedure follows:

- 1) The master sends a start condition.
- 2) The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends an 8-bit data byte.
- 5) The addressed slave asserts an ACK on SDA.
- 6) The master sends a stop condition.

### Write Byte/Word

The write byte/word protocol allows the master device to write a single byte in the register bank, preset an EEPROM (configuration or user) address for a subsequent read, or to write a single byte to the configuration or user EEPROM (see Figure 7). The write byte/word procedure follows:

- 1) The master sends a start condition.
- The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends an 8-bit command code.
- 5) The addressed slave asserts an ACK on SDA.
- 6) The master sends an 8-bit data byte.
- 7) The addressed slave asserts an ACK on SDA.
- 8) The master sends a stop condition or sends another 8-bit data byte.
- 9) The addressed slave asserts an ACK on SDA.
- 10) The master sends a stop condition.

To write a single byte to the register bank, only the 8-bit command code and a single 8-bit data byte are sent. The command code must be in the range of 00h to 45h. The data byte is written to the register bank if the command code is valid. The slave generates a NACK at step 5 if the command code is invalid.

To preset an EEPROM (configuration or user) address for a subsequent read, the 8-bit command code and a single 8-bit data byte are sent. The command code must be 80h if the write is to be directed into the configuration EEPROM, or 81h or 82h, if the write is to be

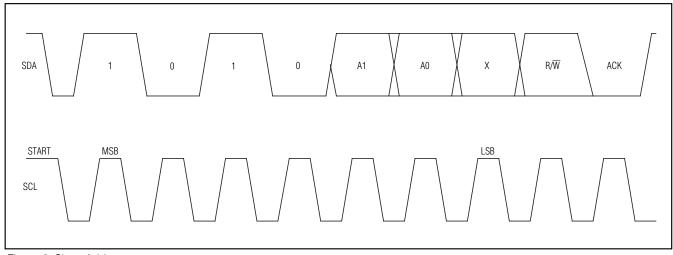


Figure 6. Slave Address

#### **SEND BYTE FORMAT**

| S | ADDRESS | WR | ACK | DATA   | ACK | Р |
|---|---------|----|-----|--------|-----|---|
|   | 7 bits  | 0  |     | 8 bits |     |   |

Slave Address equivalent to chipselect line of a 3wire interface. Data Byte-presets the internal address pointer.

### WRITE WORD FORMAT

| S | ADDRESS | WR | ACK | COMMAND | ACK | DATA   | ACK | DATA   | ACK | Р |
|---|---------|----|-----|---------|-----|--------|-----|--------|-----|---|
|   | 7 bits  | 0  |     | 8 bits  |     | 8 bits |     | 8 bits |     |   |

Slave Address equivalent to chipselect line of a 3wire interface. Command Byte– MSB of the EEPROM register being written. Data Byte–first byte is the LSB of the EEPROM address. Second byte is the actual data.

#### RECEIVE BYTE FORMAT

| S | ADDRESS | WR | ACK | DATA   | ACK | Р |
|---|---------|----|-----|--------|-----|---|
|   | 7 bits  | 1  |     | 8 bits |     |   |

Slave Address equivalent to chipselect line of a 3wire interface. Data Byte—reads data from the register commanded by the last read byte or write byte transmission. Also dependent on a send byte.

#### WRITE BYTE FORMAT

| S | ADDRESS | WR | ACK | COMMAND | ACK | DATA   | ACK | Р |
|---|---------|----|-----|---------|-----|--------|-----|---|
|   | 7 bits  | 0  |     | 8 bits  |     | 8 bits |     |   |

Slave Address equivalent to chipselect line of a 3wire interface. Command Byteselects register being written. Data Byte-data goes into the register set by the command byte if the command is below 50h. If the command is 80h, 81h, or 82h, the data byte presets the LSB of an EEPROM address.

#### **BLOCK WRITE FORMAT**

| S | ADDRESS | WR | ACK | COMMAND | ACK | BYTE<br>COUNT= N | ACK | DATA BYTE<br>1 | ACK | DATA BYTE<br> | ACK | DATA BYTE<br>N | ACK | Р |
|---|---------|----|-----|---------|-----|------------------|-----|----------------|-----|---------------|-----|----------------|-----|---|
|   | 7 bits  | 0  |     | 8 bits  |     | 8 bits           |     | 8 bits         |     | 8 bits        |     | 8 bits         |     |   |

Slave Address equivalent to chipselect line of a 3wire interface. Command Byte prepares device for block operation. Data Byte-data goes into the register set by the command byte.

### **BLOCK READ FORMAT**

| S | ADDRESS | WR | ACK | COMMAND | ACK | SR | ADDRESS | WR | ACK | BYTE<br>COUNT= 16 | ACK | DATA BYTE<br>1 | ACK | DATA BYTE | ACK | DATA BYTE<br>N | ACK | Р |
|---|---------|----|-----|---------|-----|----|---------|----|-----|-------------------|-----|----------------|-----|-----------|-----|----------------|-----|---|
|   | 7 bits  | 0  |     | 8 bits  |     |    | 7 bits  | 1  |     | 10h               |     | 8 bits         |     | 8 bits    |     | 8 bits         |     |   |

Slave Address equivalent to chipselect line of a 3wire interface. Command Byte prepares device for block operation. Slave Address equivalent to chipselect line of a 3wire interface. Data Byte–data goes into the register set by the command byte.

 $S = Start \ condition. \qquad Shaded = Slave \ transmission. \\ P = Stop \ condition. \qquad SR = Repeated \ start \ condition.$ 

Figure 7. SMBus/I<sup>2</sup>C Protocols



directed into the user EEPROM. If the command code is 80h, the data byte must be in the range of 00h to 45h. If the command code is 81h or 82h, the data byte can be 00h to FFh. A NACK is generated in step 7 if none of the above conditions are true.

To write a single byte of data to the user or configuration EEPROM, the 8-bit command code and a single 8-bit data byte are sent. The following 8-bit data byte is written to the addressed EEPROM location.

#### **Block Write**

The block write protocol allows the master device to write a block of data (1 to 16 bytes) to the EEPROM or to the register bank (see Figure 7). The destination address must already be set by the send byte or write byte protocol and the command code must be 83h. If the number of bytes to be written causes the address pointer to exceed 45h for the configuration register or configuration EEPROM, the address pointer stays at 45h, overwriting this memory address with the remaining bytes of data. The last data byte sent is stored at register address 45h. If the number of bytes to be written exceeds the address pointer FFh for the user EEPROM, the address pointer loops back to 00h, and continues writing bytes until all data is written. The block write procedure follows:

- 1) The master sends a start condition.
- 2) The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends the 8-bit command code for block write (83h).
- 5) The addressed slave asserts an ACK on SDA.
- 6) The master sends the 8-bit byte count (1 to 16 bytes) N.
- 7) The addressed slave asserts an ACK on SDA.
- 8) The master sends 8-bits of data.
- 9) The addressed slave asserts an ACK on SDA.
- 10) Repeat steps 8 and 9 one time.
- 11) The master generates a stop condition.

### Receive Byte

The receive byte protocol allows the master device to read the register content of the MAX6870/MAX6871 (see Figure 7). The EEPROM or register address must be preset with a send byte or write word protocol first. Once the read is complete, the internal pointer increases by one. Repeating the receive byte protocol reads

the contents of the next address. The receive byte procedure follows:

- 1) The master sends a start condition.
- 2) The master sends the 7-bit slave address and a read bit (high).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The slave sends 8 data bits.
- 5) The master asserts a NACK on SDA.
- 6) The master generates a stop condition.

#### Block Read

The block read protocol allows the master device to read a block of 16 bytes from the EEPROM or register bank (see Figure 7). Read fewer than 16 bytes of data by issuing an early STOP condition from the master, or by generating a NACK with the master. The send byte or write byte protocol predetermines the destination address with a command code of 84h. The block read procedure follows:

- 1) The master sends a start condition.
- The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends 8 bits of the block read command (84h).
- 5) The slave asserts an ACK on SDA, unless busy.
- 6) The master generates a repeated start condition.
- 7) The master sends the 7-bit slave address and a read bit (high).
- 8) The slave asserts an ACK on SDA.
- 9) The slave sends the 8-bit byte count (16).
- 10) The master asserts an ACK on SDA.
- 11) The slave sends 8 bits of data.
- 12) The master asserts an ACK on SDA.
- 13) Repeat steps 8 and 9 fifteen times.
- 14) The master generates a stop condition.

## Address Pointers

Use the send byte protocol to set the register address pointers before read and write operations. For the configuration registers, valid address pointers range from 00h to 45h. Register addresses outside of this range result in a NACK being issued from the MAX6870/MAX6871. When using the block write protocol, the

address pointer automatically increments after each data byte, except when the address pointer is already at 45h. If the address pointer is already 45h, and more data bytes are being sent, these subsequent bytes overwrite address 45h repeatedly, leaving only the last data byte sent stored at this register address.

For the configuration EEPROM, valid address pointers range from 8000h to 8045h. Registers 8046h to 804Fh are reserved and should not be overwritten. Register addresses from 8050h to 80FFh return a NACK from the MAX6870/MAX6871. When using the block write protocol, the address pointer automatically increments after each data byte, except when the address pointer is already at 8045h. If the address pointer is already 8045h, and more data bytes are being sent, these subsequent bytes overwrite address 8045h repeatedly, leaving only the last data byte sent stored at this register address.

For the user EEPROM, valid address pointers range from 8100h to 81FFh and 8200h to 82FFh. Block write and block read protocols allow the address pointer to reset (to 8100h or 8200h) when attempting to write or read beyond 81FFh or 82FFh.

### **Configuration EEPROM**

The configuration EEPROM addresses range from 8000h to 8045h. Write data to the configuration EEPROM to automatically set up the MAX6870/MAX6871 upon power-up. Data transfers from the configuration EEPROM to the configuration registers when ABP exceeds UVLO during power-up or after a software reboot. After ABP exceeds UVLO, an internal 1MHz clock starts after a 5µs delay, and data transfer begins. Data transfer disables access

to the configuration registers and EEPROM. The data transfer from EEPROM to configuration registers takes 3.5ms (max). Read configuration EEPROM data at any time after power-up or software reboot. Write commands to the configuration EEPROM are allowed at any time after power-up or software reboot, unless the configuration lock bit is set (see Table 30). The maximum cycle time to write a single byte is 11ms (max).

#### **User EEPROM**

The 512 byte user EEPROM addresses range from 8100h to 82FFh (see Figure 8). Store software-revision data, board-revision data, and other data in these registers. The maximum cycle time to write a single byte is 11ms (max).

### Configuration Register Bank and EEPROM

The configuration registers can be directly modified by the serial interface without modifying the EEPROM after the power-up procedure terminates and the configuration EEPROM data has been loaded into the configuration register bank. Use the write byte or block write protocols to write directly to the configuration registers. Changes to the configuration registers take effect immediately and are lost upon power removal.

At device power-up, the register bank loads configuration data from the EEPROM. Configuration data may be directly altered in the register bank during application development, allowing maximum flexibility. Transfer the new configuration data, byte by byte, to the configuration EEPROM with the write byte protocol. The next device power-up or software reboot automatically loads the new configuration.

**Table 26. Register Map** 

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | READ/<br>WRITE | DESCRIPTION   |
|---------------------|-----------------------------|----------------|---|
| 00h                 | 8000h                       | R/W            | IN1 primary undervoltage detector threshold (Table 2).                              |
| 01h                 | 8001h                       | R/W            | IN2 primary undervoltage detector threshold (Table 3).                              |
| 02h                 | 8002h                       | R/W            | IN3 primary undervoltage detector threshold (Table 4).                              |
| 03h                 | 8003h                       | R/W            | IN4 primary undervoltage detector threshold (Table 4).                              |
| 04h                 | 8004h                       | R/W            | IN5 primary undervoltage detector threshold (MAX6870 only) (Table 4).               |
| 05h                 | 8005h                       | R/W            | IN6 primary undervoltage detector threshold (MAX6870 only) (Table 4).               |
| 06h                 | 8006h                       | R/W            | IN1 secondary undervoltage/overvoltage detector threshold (Table 2).                |
| 07h                 | 8007h                       | R/W            | IN2 secondary undervoltage/overvoltage detector threshold (Table 3).                |
| 08h                 | 8008h                       | R/W            | IN3 secondary undervoltage/overvoltage detector threshold (Table 4).                |
| 09h                 | 8009h                       | R/W            | IN4 secondary undervoltage/overvoltage detector threshold (Table 4).                |
| 0Ah                 | 800Ah                       | R/W            | IN5 secondary undervoltage/overvoltage detector threshold (MAX6870 only) (Table 4). |

## **Table 26. Register Map (continued)**

|                     |                             | wap (cc        |  |
|---------------------|-----------------------------|----------------|--|
| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | READ/<br>WRITE | DESCRIPTION  |
| 0Bh                 | 800Bh                       | R/W            | IN6 secondary undervoltage/overvoltage detector threshold (MAX6870 only) (Table 4).  |
| 0Ch                 | 800Ch                       | R/W            | Secondary undervoltage/overvoltage selection (Tables 2, 4).  |
| 0Dh                 | 800Dh                       | R/W            | Threshold range selection (Tables 2–4).  |
| 0Eh                 | 800Eh                       | R/W            | PO1 (MAX6870 only) input selection (Table 10).   |
| 0Fh                 | 800Fh                       | R/W            | PO1 (MAX6870 only) input selection (Table 10).   |
| 10h                 | 8010h                       | R/W            | PO1 (MAX6870 only) input selection (Table 10).   |
| 11h                 | 8011h                       | R/W            | PO1 (MAX6870 only) input selection, PO_ timeout period, and output type selection (Tables 10, 23, and 25).                                   |
| 12h                 | 8012h                       | R/W            | PO2 (MAX6870 only) input selection (Table 11).   |
| 13h                 | 8013h                       | R/W            | PO2 (MAX6870 only) input selection (Table 11).   |
| 14h                 | 8014h                       | R/W            | PO2 (MAX6870 only) input selection (Table 11).   |
| 15h                 | 8015h                       | R/W            | PO2 (MAX6870 only) input selection, PO_ timeout period, and output type selection (Tables 11, 23, and 25).                                   |
| 16h                 | 8016h                       | R/W            | PO3 (MAX6870)/PO1 (MAX6871) input selection—Product 1 (Table 12).  |
| 17h                 | 8017h                       | R/W            | PO3 (MAX6870)/PO1 (MAX6871) input selection—Product 1 (Table 12).  |
| 18h                 | 8018h                       | R/W            | PO3 (MAX6870)/PO1 (MAX6871) input selection—Product 1 (Table 12).  |
| 19h                 | 8019h                       | R/W            | PO3 (MAX6870)/PO1 (MAX6871) input selection—Product 2 (Table 13).  |
| 1Ah                 | 801Ah                       | R/W            | PO3 (MAX6870)/PO1 (MAX6871) input selection—Product 2 (Table 13).  |
| 1Bh                 | 801Bh                       | R/W            | PO3 (MAX6870)/PO1 (MAX6871) input selection—Product 2 (Table 13).  |
| 1Ch                 | 801Ch                       | R/W            | PO3 (MAX6870)/PO1 (MAX6871) input selection—Products 1 and 2, PO_ timeout period, and output type selection (Tables 12, 13, 23, 24, and 25). |
| 1Dh                 | 801Dh                       | R/W            | PO4 (MAX6870)/PO2 (MAX6871) input selection—Product 1 (Table 14).  |
| 1Eh                 | 801Eh                       | R/W            | PO4 (MAX6870)/PO2 (MAX6871) input selection—Product 1 (Table 14).  |
| 1Fh                 | 801Fh                       | R/W            | PO4 (MAX6870)/PO2 (MAX6871) input selection—Product 1 (Table 14).  |
| 20h                 | 8020h                       | R/W            | PO4 (MAX6870)/PO2 (MAX6871) input selection—Product 2 (Table 15).  |
| 21h                 | 8021h                       | R/W            | PO4 (MAX6870)/PO2 (MAX6871) input selection—Product 2 (Table 15).  |
| 22h                 | 8022h                       | R/W            | PO4 (MAX6870)/PO2 (MAX6871) input selection—Product 2 (Table 15).  |
| 23h                 | 8023h                       | R/W            | PO4 (MAX6870)/PO2 (MAX6871) input selection—Products 1 and 2, PO_ timeout period, and output type selection (Tables 14, 15, 23, 24, and 25). |
| 24h                 | 8024h                       | R/W            | PO5 (MAX6870)/PO3 (MAX6871) input selection—Product 1 (Table 16).  |
| 25h                 | 8025h                       | R/W            | PO5 (MAX6870)/PO3 (MAX6871) input selection—Product 1 (Table 16).  |
| 26h                 | 8026h                       | R/W            | PO5 (MAX6870)/PO3 (MAX6871) input selection—Product 1 (Table 16).  |
| 27h                 | 8027h                       | R/W            | PO5 (MAX6870)/PO3 (MAX6871) input selection—Product 2 (Table 17).  |
| 28h                 | 8028h                       | R/W            | PO5 (MAX6870)/PO3 (MAX6871) input selection—Product 2 (Table 17).  |
| 29h                 | 8029h                       | R/W            | PO5 (MAX6870)/PO3 (MAX6871) input selection—Product 2 (Table 17).  |
| 2Ah                 | 802Ah                       | R/W            | PO5 (MAX6870)/PO3 (MAX6871) input selection—Products 1 and 2, PO_ timeout period, and output type selection (Tables 16, 23, 24, and 25).     |
| 2Bh                 | 802Bh                       | R/W            | PO6 (MAX6870)/PO4 (MAX6871) input selection—Product 1 (Table 18).  |
| 2Ch                 | 802Ch                       | R/W            | PO6 (MAX6870)/PO4 (MAX6871) input selection—Product 1 (Table 18).  |

**Table 26. Register Map (continued)** 

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | READ/<br>WRITE | DESCRIPTION  |
|---------------------|-----------------------------|----------------|--|
| 2Dh                 | 802Dh                       | R/W            | PO6 (MAX6870)/PO4 (MAX6871) input selection—Product 1 (Table 18).  |
| 2Eh                 | 802Eh                       | R/W            | PO6 (MAX6870)/PO4 (MAX6871) input selection—Product 2 (Table 19).  |
| 2Fh                 | 802Fh                       | R/W            | PO6 (MAX6870)/PO4 (MAX6871) input selection—Product 2 (Table 19).  |
| 30h                 | 8030h                       | R/W            | PO6 (MAX6870)/PO4 (MAX6871) input selection—Product 2 (Table 19).  |
| 31h                 | 8031h                       | R/W            | PO6 (MAX6870)/PO4 (MAX6871) input selection—Products 1 and 2, reset timeout period, and output type selection (Tables 18, 23, 24, and 25). |
| 32h                 | 8032h                       | R/W            | PO7 (MAX6870)/PO5 (MAX6871) input selection (Table 20).  |
| 33h                 | 8033h                       | R/W            | PO7 (MAX6870)/PO5 (MAX6871) input selection (Table 20).  |
| 34h                 | 8034h                       | R/W            | PO7 (MAX6870)/PO5 (MAX6871) input selection (Table 20).  |
| 35h                 | 8035h                       | R/W            | PO7 (MAX6870)/PO5 (MAX6871) input selection, PO_ timeout period, and output type selection (Tables 20, 23, 24, and 25).                    |
| 36h                 | 8036h                       | R/W            | PO8 (MAX6870 only) input selection (Table 21).   |
| 37h                 | 8037h                       | R/W            | PO8 (MAX6870 only) input selection (Table 21).   |
| 38h                 | 8038h                       | R/W            | PO8 (MAX6870 only) input selection (Table 21).   |
| 39h                 | 8039h                       | R/W            | PO8 (MAX6870 only) input selection, PO_ timeout period, and output type selection. (Tables 21, 23, 24, and 25).                            |
| 3Ah                 | 803Ah                       | R/W            | Programmable output polarity (active-high/active-low) (Table 22).  |
| 3Bh                 | 803Bh                       | R/W            | GPI_ input polarity, PO5, PO6 (Tables 6, 17, and 19).  |
| 3Ch                 | 803Ch                       | R/W            | WDI1 input selection and timeout enable (Table 27).  |
| 3Dh                 | 803Dh                       | R/W            | WDI1 initial and normal timeout duration (Table 28).   |
| 3Eh                 | 803Eh                       | R/W            | WDI2 input selection and timeout enable (Table 27).  |
| 3Fh                 | 803Fh                       | R/W            | WDI2 initial and normal timeout duration (Table 28).   |
| 40h                 | 8040h                       | R/W            | MR input and programmable output behavior (Table 7).   |
| 41h                 | 8041h                       | R/W            | MARGIN and programmable output behavior (Table 8).   |
| 42h                 | 8042h                       | R/W            | Programmable output state with MARGIN assertion (Table 8).   |
| 43h                 | 8043h                       | R/W            | User EEPROM write disable (Table 31).  |
| 44h                 | 8044h                       | R/W            | Internal/external reference selection (Table 9).   |
| 45h                 | 8045h                       | R/W            | Configuration lock (Table 30).   |
| 46h                 | 8046h                       | _              | Reserved. Should not be overwritten.   |
| 47h                 | 8047h                       | _              | Reserved. Should not be overwritten.   |
| 48h                 | 8048h                       | _              | Reserved. Should not be overwritten.   |
| 49h                 | 8049h                       | _              | Reserved. Should not be overwritten.   |
| 4Ah                 | 804Ah                       | _              | Reserved. Should not be overwritten.   |
| 4Bh                 | 804Bh                       | _              | Reserved. Should not be overwritten.   |
| 4Ch                 | 804Ch                       | _              | Reserved. Should not be overwritten.   |
| 4Dh                 | 804Dh                       | _              | Reserved. Should not be overwritten.   |
| 4Eh                 | 804Eh                       | _              | Reserved. Should not be overwritten.   |
| 4Fh                 | 804Fh                       | _              | Reserved. Should not be overwritten.   |

## **Table 26. Register Map (continued)**

|  |   |   | Ţ  |
|--|---|---|--|
| REGISTER ADDRESS EEPROM MEMORY ADDRESS READ/ WRITE |   | _ | DESCRIPTION  |
| 50h  | _ | R | ADC data for IN1 (8 MSBs).                                 |
| 51h  |   | R | ADC data for IN1 (2 LSBs).                                 |
| 52h  |   | R | ADC data for IN2 (8 MSBs).                                 |
| 53h  | _ | R | ADC data for IN2 (2 LSBs).                                 |
| 54h  | _ | R | ADC data for IN3 (8 MSBs).                                 |
| 55h  | _ | R | ADC data for IN3 (2 LSBs).                                 |
| 56h  | _ | R | ADC data for IN4 (8 MSBs).                                 |
| 57h  | _ | R | ADC data for IN4 (2 LSBs).                                 |
| 58h  | _ | R | ADC data for IN5 (8 MSBs, MAX6870 only).                   |
| 59h  | _ | R | ADC data for IN5 (2 LSBs, MAX6870 only).                   |
| 5Ah  |   | R | ADC data for IN6 (8 MSBs, MAX6870 only).                   |
| 5Bh  |   | R | ADC data for IN6 (2 LSBs, MAX6870 only).                   |
| 5Ch  | _ | R | ADC data for AUXIN1 (8 MSBs) (Table 5).                    |
| 5Dh  |   | R | ADC data for AUXIN1 (2 LSBs) (Table 5).                    |
| 5Eh  | _ | R | ADC data for AUXIN2 (8 MSBs) (Table 5).                    |
| 5Fh  | _ | R | ADC data for AUXIN2 (2 LSBs) (Table 5).                    |
| 60h  | _ | R | Fault flags for IN1-IN6 (primary thresholds) (Table 29).   |
| 61h  | _ | R | Fault flags for IN1-IN6 (secondary thresholds) (Table 29). |
| 62h  | _ | R | Fault flags for WDI_, GPI_, and MR (Table 29).             |

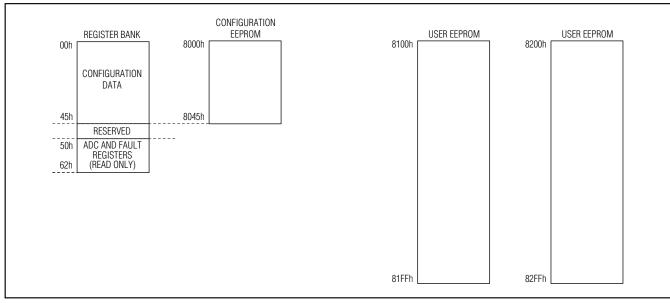


Figure 8. Memory Map

## Configuring the Watchdog Timers (Registers 3Ch–3Fh)

A watchdog timer monitors microprocessor ( $\mu P$ ) software execution for a stalled condition and resets the  $\mu P$  if it stalls. The output of a watchdog timer (one of the programmable outputs) connects to the reset input or a nonmaskable interrupt of the  $\mu P$ .

Registers 3Ch–3Fh configure the watchdog functionality of the MAX6870/MAX6871. Program each watchdog timer to assert one or more programmable outputs (see Tables 10–21). Program each watchdog timer to reset on one of the GPI\_ inputs, one of the programmable outputs, or a combination of one GPI\_ input and one programmable output.

Each watchdog timer features independent initial and normal watchdog timeout periods. The initial watchdog timeout period applies immediately after power-up, after a reset event takes place, or after enabling the watchdog timer. The initial watchdog timeout period allows the µP to

Table 27. Watchdog Inputs (Addresses 3Ch (Watchdog 1), 3Eh (Watchdog 2))

| BIT   | NAME                                       | DESCRIPTION   |
|-------|--|---|
| [1:0] | Watchdog<br>Input<br>Selection             | 00 = GPI1 input<br>01 = GPI2 input<br>10 = GPI3 input<br>11 = GPI4 input  |
| [4:2] | Watchdog<br>Internal<br>Input<br>Selection | 000 = PO1 (MAX6870), not used (MAX6871)<br>001 = PO2 (MAX6870), not used (MAX6871)<br>010 = PO3 (MAX6870), PO1 (MAX6871)<br>011 = PO4 (MAX6870), PO2 (MAX6871)<br>100 = PO5 (MAX6870), PO3 (MAX6871)<br>101 = PO6 (MAX6870), PO4 (MAX6871)<br>110 = PO7 (MAX6870), PO5 (MAX6871)<br>111 = PO8 (MAX6870), not used (MAX6871) |
| [6:5] | Watchdog<br>Dependency<br>on Inputs        | 00 = 11 = watchdog clear depends on both GPI_ from 3Ch[1:0] and PO_ from 3Ch[4:2]. 01 = watchdog clear depends only on PO_ from 3Ch[4:2]. 10 = watchdog clear depends only on GPI_ from 3Ch[1:0].   |
| [7]   | Initial<br>Watchdog<br>Timeout<br>Enable   | 0 = disables initial watchdog timeout period (normal watchdog timeout not affected). 1 = enables initial watchdog timeout period.   |

perform its initialization process. If no pulse occurs during the initial watchdog timeout period, the  $\mu P$  is taking too long to initialize, indicating a potential problem.

The normal watchdog timeout period applies in every other cycle after the initial watchdog timeout period occurs. The normal watchdog timeout period monitors a pulsed output of the  $\mu P$  that indicates when normal processor behavior occurs. If no pulse occurs during the normal watchdog timeout period, this indicates that the processor has stopped operating or is stuck in an infinite execution loop.

Disable or enable each initial timeout period through registers 3Ch and 3Eh. Registers 3Dh and 3Fh program the initial and normal watchdog timeout periods, and enable or disable each watchdog timer. See Tables 27 and 28 for a summary of the watchdog behavior.

#### Fault Detector

Registers 60h–62h store all fault conditions, including undervoltage, overvoltage, GPI\_, and watchdog timer faults (see Table 29). Fault registers are read-only and lose contents upon power removal. The first read command from the fault registers after power-up gives invalid data. Any MR assertion writes to the fault register. Reading the fault register clears all fault flags. Both GPI\_

## Table 28. Watchdog Timeout Period Selection (Addresses 3Dh (Watchdog 1), 3Fh (Watchdog 2))

| BIT   | NAME   | DESCRIPTION   |
|-------|--|---|
| [2:0] | Normal<br>Watchdog<br>Timeout Period   | 000 = 6.25ms<br>001 = 25ms<br>010 = 100ms<br>011 = 400ms<br>100 = 1.6s<br>101 = 6.4s<br>110 = 25.6s<br>111 = 102.4s |
| [5:3] | Initial Watchdog<br>Timeout Period<br>(Immediately<br>following power-<br>up, reset event,<br>or enabling<br>watchdog) | 000 = 6.25ms<br>001 = 25ms<br>010 = 100ms<br>011 = 400ms<br>100 = 1.6s<br>101 = 6.4s<br>110 = 25.6s<br>111 = 102.4s |
| [6]   | Watchdog<br>Enable   | 0 = disables watchdog timer<br>1 = enables watchdog timer   |
| [7]   | _  | Not used  |

## Table 29. Fault Registers (60h-62h)

| REGISTER<br>ADDRESS | BIT<br>RANGE | DESCRIPTION   |  |  |  |  |  |  |  |
|---------------------|--------------|---|--|--|--|--|--|--|--|
|                     | [0]          | 1 = IN1 falls below primary undervoltage threshold.   |  |  |  |  |  |  |  |
|                     | [1]          | 1 = IN2 falls below primary undervoltage threshold.   |  |  |  |  |  |  |  |
|                     | [2]          | 1 = IN3 falls below primary undervoltage threshold.   |  |  |  |  |  |  |  |
| 60h                 | [3]          | 1 = IN4 falls below primary undervoltage threshold.   |  |  |  |  |  |  |  |
|                     | [4]          | 1 = IN5 (MAX6870 only) falls below primary undervoltage threshold.  |  |  |  |  |  |  |  |
|                     | [5]          | 1 = IN6 (MAX6870 only) falls below primary undervoltage threshold.  |  |  |  |  |  |  |  |
|                     | [7:6]        | Not used.   |  |  |  |  |  |  |  |
|                     | [0]          | 1 = IN1 falls below secondary undervoltage threshold or rises above secondary overvoltage threshold, depending on the settings in register 0Ch (see Tables 2, 3, and 4).                |  |  |  |  |  |  |  |
|                     | [1]          | 1 = IN2 falls below secondary undervoltage threshold or rises above secondary overvoltage threshold, depending on the settings in register 0Ch (see Tables 2, 3, and 4).                |  |  |  |  |  |  |  |
|                     | [2]          | 1 = IN3 falls below secondary undervoltage threshold or rises above secondary overvoltage threshold, depending on the settings in register 0Ch (see Tables 2, 3, and 4).                |  |  |  |  |  |  |  |
| 61h                 | [3]          | 1 = IN4 falls below secondary undervoltage threshold or rises above secondary overvoltage threshold, depending on the settings in register 0Ch (see Tables 2, 3, and 4).                |  |  |  |  |  |  |  |
|                     | [4]          | 1 = IN5 (MAX6870 only) falls below secondary undervoltage threshold or rises above secondary overvoltage threshold, depending on the settings in register 0Ch (see Tables 2, 3, and 4). |  |  |  |  |  |  |  |
|                     | [5]          | 1 = IN6 (MAX6870 only) falls below secondary undervoltage threshold or rises above secondary overvoltage threshold, depending on the settings in register 0Ch (see Tables 2, 3, and 4). |  |  |  |  |  |  |  |
|                     | [7:6]        | Not used.   |  |  |  |  |  |  |  |
|                     | [0]          | 1 = WDI1 asserted.  |  |  |  |  |  |  |  |
|                     | [1]          | 1 = WDI2 asserted.  |  |  |  |  |  |  |  |
|                     | [2]          | 1 = GPI1 asserted.  |  |  |  |  |  |  |  |
| 62h                 | [3]          | 1 = GPI2 asserted.  |  |  |  |  |  |  |  |
| UZII                | [4]          | 1 = GPI3 asserted.  |  |  |  |  |  |  |  |
|                     | [5]          | 1 = GPI4 asserted.  |  |  |  |  |  |  |  |
|                     | [6]          | 1 = MR asserted.  |  |  |  |  |  |  |  |
|                     | [7]          | Not used.   |  |  |  |  |  |  |  |

and WDI\_ bits assert if any of the GPI\_ inputs are configured as watchdog inputs (WDI\_) and a watchdog fault occurs.

### **Configuration Lock**

Lock the configuration register bank and configuration EEPROM contents after initial programming by setting the lock bit high (see Table 30). Locking the configuration prevents write operations to all registers except the configuration lock register. Clear the lock bit to reconfigure the device.

### Write Disable

A unique write disable feature protects the MAX6870/ MAX6871 from inadvertent user EEPROM writes. As input voltages that power the serial interface, a  $\mu$ P, or any other writing devices fall, unintentional data may be written onto the data bus. The user EEPROM write disable function (see Table 31) ensures that unintentional data does not corrupt the MAX6870/MAX6871 EEPROM data.

**Table 30. Configuration Lock Register** 

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | DESCRIPTION  |
|---------------------|-----------------------------|--------------|--|
| 45h                 | 8045h                       | [0]          | 0 = configuration unlocked.<br>1 = configuration locked. |
|                     |                             | [7:1]        | Not used.  |

## **Table 31. Write Disable Register**

| REGISTER<br>ADDRESS | EEPROM<br>MEMORY<br>ADDRESS | BIT<br>RANGE | DESCRIPTION  |  |  |  |  |     |
|---------------------|-----------------------------|--------------|--|--|--|--|--|-----|
|                     |                             | [0]          | 0 = write not disabled if PO1 asserts (MAX6870).<br>1 = write disabled if PO1 asserts (MAX6870). Set to 0 (MAX6871).         |  |  |  |  |     |
|                     |                             | [1]          | 0 = write not disabled if PO2 asserts (MAX6870).<br>1 = write disabled if PO2 asserts (MAX6870). Set to 0 (MAX6871).         |  |  |  |  |     |
|                     |                             | [2]          | 0 = write not disabled if PO3 (MAX6870)/PO1 (MAX6871) asserts.<br>1 = write disabled if PO3 (MAX6870)/PO1 (MAX6871) asserts. |  |  |  |  |     |
| 43h                 | 8043h                       | [3]          | 0 = write not disabled if PO4 (MAX6870)/PO2 (MAX6871) asserts.<br>1 = write disabled if PO4 (MAX6870)/PO2 (MAX6871) asserts. |  |  |  |  |     |
| 4311                | 604311                      | 004311       | [4]  | 0 = write not disabled if PO5 (MAX6870)/PO3 (MAX6871) asserts.<br>1 = write disabled if PO5 (MAX6870)/PO3 (MAX6871) asserts. |  |  |  |     |
|                     |                             |              |  |  |  |  |  | [5] |
|                     |                             | [6]          | 0 = write not disabled if PO7 (MAX6870)/PO5 (MAX6871) asserts.<br>1 = write disabled if PO7 (MAX6870)/PO5 (MAX6871) asserts. |  |  |  |  |     |
|                     |                             | [7]          | 0 = write not disabled if PO8 asserts (MAX6870).<br>1 = write disabled if PO8 asserts (MAX6870). Set to 0 (MAX6871).         |  |  |  |  |     |

## Applications Information

## **Configuration Download at Power-up**

The configuration of the MAX6870/MAX6871 (undervoltage/overvoltage thresholds, PO\_ timeout periods, watchdog behavior, programmable output conditions and configurations, etc.) depends on the contents of the EEPROM. The EEPROM is comprised of buffered latches that store the configuration. The local volatile memory latches lose their contents at power-down. Therefore, at power-up, the device configuration must be restored by downloading the contents of the EEP-ROM (non-volatile memory) to the local latches. This download occurs in a number of steps:

- 1) Programmable outputs go high impedance with no power applied to the device.
- When ABP exceeds +1V, all programmable outputs are weakly pulled to GND through a 10μA current sink.
- 3) When ABP exceeds UVLO, the configuration EEP-ROM starts to download its contents to the volatile configuration registers. The programmable outputs assume their programmed conditional output state when download is complete.
- Any attempt to communicate with the device prior to this download completion results in a NACK being issued from the MAX6870/MAX6871.

## Forcing Programmable Outputs High During Power-Up

A weak 10µA pulldown holds all programmable outputs low during power-up until ABP exceeds the undervoltage lockout (UVLO) threshold. Applications requiring a guaranteed high programmable output for ABP down to GND require external pullup resistors to maintain the logic state until ABP exceeds UVLO. Use  $20 k\Omega$  resistors for most applications.

## Driving High-Side MOSFET Switches with the MAX6870/MAX6871

High-side MOSFET switches are commonly used in power-supply sequencing applications. First, configure the programmable output of the MAX6870/MAX6871 as an active-low charge-pump output and set the conditions to assert this output. Connect the programmable output to the gate of an n-channel MOSFET. As the conditions to deassert this output are met, the output deasserts high (VABP +5V), turning on the FET, thus allowing the voltage on the drain to pass through to the downstream device (see Figure 9).

## Uses for General-Purpose Inputs (GPI1-GPI4)

## Watchdog Timer

Program GPI\_ as an input to one of the watchdog timers in the MAX6870/MAX6871. The GPI\_ input must toggle within the watchdog timeout period, otherwise any programmable output dependent on the watchdog timer asserts.

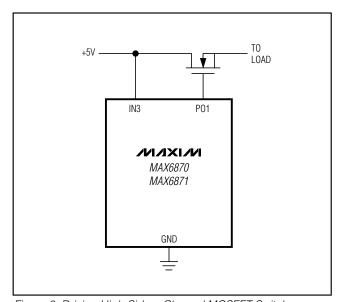


Figure 9. Driving High-Side n-Channel MOSFET Switches

#### Additional Manual Reset Functions

The PO7 (MAX6870)/PO5 (MAX6871) programmable outputs allow a single set (Product 1 only) of conditions to assert the output. Program the set of conditions to depend on one of the GPI\_ inputs. Any output that depends on GPI\_ asserts when GPI\_ is held in its active state, effectively acting as a manual reset input.

### Other Fault Signals from µC

Connect a general purpose output from a  $\mu$ C to one of the GPI\_ inputs to allow interrupts to assert any output of the MAX6870/MAX6871. Configure one of the programmable outputs to assert on whichever GPI\_ input connects to the general purpose output of the  $\mu$ C.

#### **Uses for AUXIN1 and AUXIN2**

### Analog Output of Current-Sense Amplifier

Figure 10 shows the MAX6870/MAX6871 in a current-sensing application with the MAX4374. The MAX4374 generates an analog output voltage (OUT) proportional to the voltage difference between RS+ and RS- and a latched comparator output (COUT) indicating an over-current condition. Connect OUT to AUXIN1 to provide continuous monitoring of the load current on the 12V supply. The internal ADC of the MAX6870/MAX6871 digitizes VOUT and stores the results in read-only registers 5Ch through 5Fh. COUT latches high for VCIN > 600mV, and clears with the RESET input of the MAX4374. Configure GPI1 as an active-high input and configure PO7 (MAX6870)/PO5 (MAX6871) to depend on GPI1. PO7/PO5 asserts to its active state when an overcurrent condition exists.

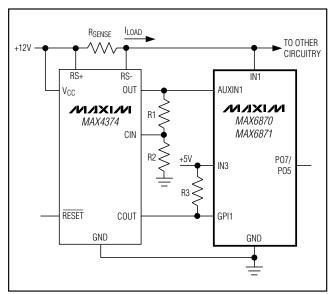


Figure 10. Monitoring Current-Sense Amplifier Outputs

### **Temperature Sensor Outputs**

Figure 11 shows the MAX6870/MAX6871 in a temperature-sensing application with the DS600. The DS600 generates an analog output voltage proportional to the sensed temperature through VouT and logic outputs on TO and  $\overline{\text{TO}}$  (only TO is shown). The internal ADC of the MAX6870/MAX6871 digitizes the analog output voltage of the DS600 and stores the results in read-only registers 5Ch through 5Fh. V<sub>TH</sub> sets the threshold voltage that VouT must exceed for TO to generate a logic-high signal. V<sub>TH</sub> must be less than 1.25V, otherwise the overcurrent condition will occur after the internal ADC attains its full-scale input voltage. Configure GPI1 as an active-high input and configure PO7 (MAX6870)/PO5 (MAX6871) to depend on GPI1. When Vout increases above V<sub>TH</sub>, TO asserts high, causing PO7/PO5 to assert to its active state.

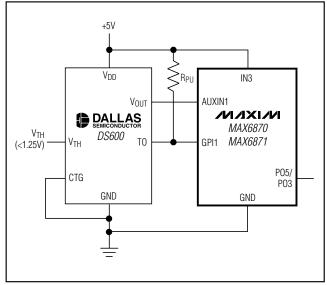


Figure 11. Temperature Sensor Outputs

### Monitoring Other Voltages

Use AUXIN\_ to monitor any voltage up to 1.25V. The internal ADC of the MAX6870/MAX6871 digitizes the voltage and stores the results in read-only registers 5Ch through 5Fh. The internal ADC cycles through the voltage monitor inputs and the auxiliary inputs every 200ms.

### Layout and Bypassing

For better noise immunity, bypass each of the voltage detector inputs to GND with  $0.1\mu\text{F}$  capacitors installed as close to the device as possible. Bypass ABP and DBP to GND with  $1\mu\text{F}$  capacitors installed as close to the device as possible. ABP and DBP are internally generated voltages and should not be used to supply power to external circuitry.

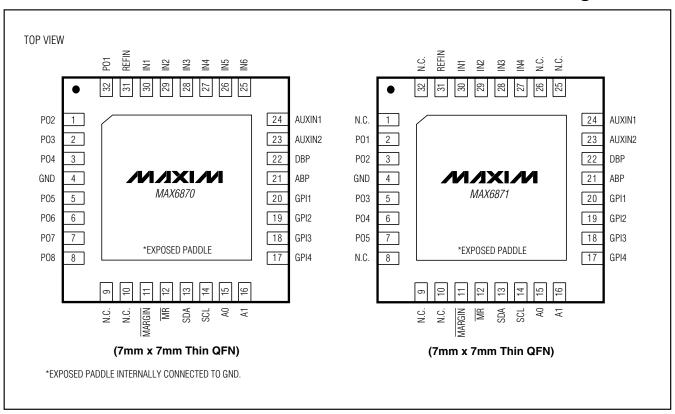
### **Configuration Latency Period**

A delay of less than 5µs occurs between writing to the configuration registers and the time when these changes actually take place, except when changing one of the voltage-detector thresholds. Changing a voltage-detector threshold typically takes 150µs. When changing EEPROM contents, a software reboot or cycling of power is required for these changes to transfer to volatile memory.

**Chip Information** 

PROCESS: BICMOS

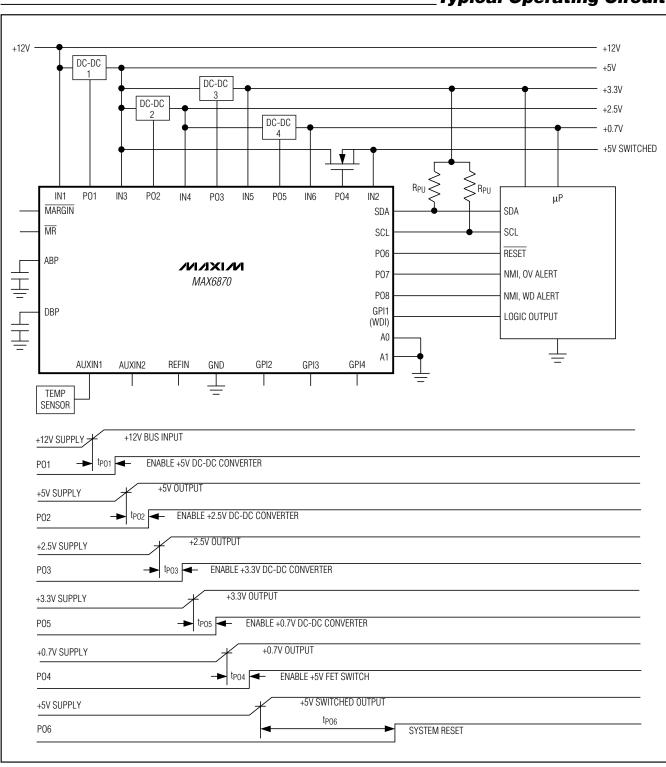
## **Pin Configurations**



### **Selector Guide**

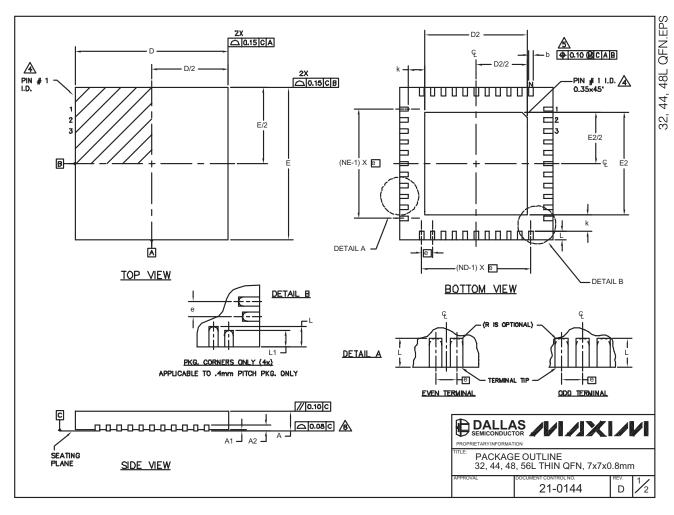
| PART       | VOLTAGE-<br>DETECTOR INPUTS | INTERNAL ADC | GENERAL-PURPOSE<br>INPUTS | PROGRAMMABLE<br>OUTPUTS | AUXILIARY<br>INPUTS |
|------------|-----------------------------|--------------|---------------------------|-------------------------|---------------------|
| MAX6870ETJ | 6                           | $\sqrt{}$    | 4                         | 8                       | $\sqrt{}$           |
| MAX6871ETJ | 4                           | $\sqrt{}$    | 4                         | 5                       | V                   |

## **Typical Operating Circuit**



## Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <a href="https://www.maxim-ic.com/packages">www.maxim-ic.com/packages</a>.)



## Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <a href="https://www.maxim-ic.com/packages">www.maxim-ic.com/packages</a>.)

|        | COMMON DIMENSIONS |        |           |           |           |         |           |           |         |                          |           |         |           |      |      |
|--------|-------------------|--------|-----------|-----------|-----------|---------|-----------|-----------|---------|--------------------------|-----------|---------|-----------|------|------|
|        |                   |        |           |           |           |         |           |           |         | CUSTOM PKG.<br>(T4877-1) |           |         |           |      |      |
| PKG    | ;                 | 32L 7x | 7         | 44L 7x7   |           | 48L 7x7 |           |           | 48L 7x7 |                          |           | 56L 7x7 |           |      |      |
| SYMBOL | MIN.              | NOM.   | MAX.      | MIN.      | NOM.      | MAX.    | MIN.      | NOM.      | MAX.    | MIN.                     | NOM.      | MAX.    | MIN.      | NOM. | MAX. |
| Α      | 0.70              | 0.75   | 0.80      | 0.70      | 0.75      | 0.80    | 0.70      | 0.75      | 0.80    | 0.70                     | 0.75      | 0.80    | 0.70      | 0.75 | 0.80 |
| A1     | 0                 | 0.02   | 0.05      | 0         | 0.02      | 0.05    | ۵         | 0.02      | 0.05    | 0                        | 0.02      | 0.05    | a         | l -  | 0.05 |
| A2     | 0.20 REF.         |        | 0.20 REF. |           | 0.20 REF. |         |           | 0.20 REF. |         |                          | 0.20 REF. |         |           |      |      |
| b      | 0.25              | 0.30   | 0.35      | 0.20      | 0.25      | 0.30    | 0.20      | 0.25      | 0.30    | 0.20                     | 0.25      | 0.30    | 0.15      | 0.20 | 0.25 |
| D      | 6.90              | 7.00   | 7.10      | 6.90      | 7.00      | 7.10    | 6.90      | 7.00      | 7.10    | 6.90                     | 7.00      | 7.10    | 6.90      | 7.00 | 7.10 |
| E      | 6.90              | 7.00   | 7.10      | 6.90      | 7.00      | 7.10    | 6,90      | 7,00      | 7.10    | 6.90                     | 7.00      | 7.10    | 6.90      | 7.00 | 7.10 |
| e      | 0                 | .65 BS | C.        | 0.50 BSC. |           |         | 0.50 BSC. |           |         | 0.50 BSC.                |           |         | 0.40 BSC. |      |      |
| k      | 0.25              | ı      | _         | 0.25      | _         | -       | 0.25      | _         | _       | 0.25                     | _         | _       | 0.25      | 0.35 | 0.45 |
| L      | 0.45              | 0.55   | 0.65      | 0.45      | 0.55      | 0.65    | 0.30      | 0.40      | 0.50    | 0.45                     | 0.55      | 0.65    | 0.40      | 0.50 | 0.60 |
| L1     | -                 | -      | -         | -         | -         | -       | _         | -         | -       | -                        | -         | -       | 0.30      | 0.40 | 0.50 |
| N      | 32                |        | 44        |           | 48        |         | 44        |           |         | 56                       |           |         |           |      |      |
| ND     | 8                 |        | 11        |           | 12        |         |           | 10        |         |                          | 14        |         |           |      |      |
| NE     | 8                 |        |           | 11        |           | 12      |           |           | 12      |                          |           | 14      |           |      |      |

| EXPOSED PAD VARIATIONS |             |      |           |      |      |           |      |                |               |  |
|------------------------|-------------|------|-----------|------|------|-----------|------|----------------|---------------|--|
| PKG.                   | DEPOPULATED |      | D2        |      |      | E2        |      | JEDEC<br>MO220 | DOWN<br>BONDS |  |
| CODES                  | LEADS       | MIN. | NOM. MAX. |      | MIN. | NOM. MAX. |      | REV. C         | ALLOWE        |  |
| T3277-1                | -           | 4.55 | 4.70      | 4.85 | 4.55 | 4.70      | 4.85 | -              | NO            |  |
| T3277-2                | -           | 4.55 | 4.70      | 4.85 | 4.55 | 4.70      | 4.85 | ı              | YES           |  |
| T4477-1                | -           | 4.55 | 4.70      | 4.85 | 4.55 | 4.70      | 4.85 | WKKD-1         | NO            |  |
| T4477-2                | -           | 4.55 | 4.70      | 4.85 | 4.55 | 4.70      | 4.85 | WKKD-1         | YES           |  |
| T4477-3                | -           | 4.55 | 4.70      | 4.85 | 4.55 | 4.70      | 4.85 | WKKD-1         | YES           |  |
| T4877-1**              | 13,24,37,48 | 4.20 | 4.30      | 4.4D | 4.20 | 4.30      | 4.40 | -              | NO            |  |
| T4877-2                | -           | 5.45 | 5.60      | 5.63 | 5.45 | 5,60      | 5,63 | -              | NO            |  |
| T4877-3                | -           | 4.95 | 5.10      | 5.25 | 4.95 | 5.10      | 5.25 | -              | YES           |  |
| T4877-4                | -           | 5.45 | 5.60      | 5.63 | 5.45 | 5.60      | 5.63 | -              | YES           |  |
| T4877-5                | -           | 2.40 | 2.50      | 2.60 | 2.40 | 2.50      | 2.60 | -              | NO            |  |
| T4877-6                | -           | 5.45 | 5.60      | 5.63 | 5.45 | 5.60      | 5.63 | -              | NO            |  |
| T5677-1                | -           | 5.20 | 5.30      | 5.4D | 5.20 | 5.30      | 5.40 | -              | YES           |  |

\*\* NOTE: T4877-1 IS A CUSTON 48L PKG. WITH 4 LEADS DEPOPULATED. TOTAL NUMBER OF LEADS ARE 44.

#### NOTES:

- 1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
- 2. ALL DIMENSIONS ARE IN MILLIMETERS, ANGLES ARE IN DEGREES.
- 3. N IS THE TOTAL NUMBER OF TERMINALS.
- THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JESD 95-1 SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
- DIMENSION 5 APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm FROM TERMINAL TIP.
- 6. ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
- 7. DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
- (A) COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
- DRAWING CONFORMS TO JEDEC MO220 EXCEPT THE EXPOSED PAD DIMENSIONS OF T3277-1; T4877-1/-2/-3/-4/-5/-6 & T5677-1.
- 10. WARPAGE SHALL NOT EXCEED 0.10 mm.



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