

[TPS63901](https://www.ti.com/product/TPS63901)

[SLVSGC1A](https://www.ti.com/lit/pdf/SLVSGC1) – DECEMBER 2021 – REVISED JUNE 2022

TPS63901 1.8-V to 5.5-V, 75-nA IQ Buck-Boost Converter with Input Current Limit and DVS in a WCSP Package

1 Features

Texas

INSTRUMENTS

- 1.8-V to 5.5-V input voltage range
- 1.8-V to 5-V output voltage range (100-mV steps)
	- Programmable with external resistors
	- SEL pin to toggle between two output voltage presets
- $>$ 400-mA output current for V_I \geq 2.0 V, V_O = 3.3 V
	- Stackable: parallel multiple devices for higher output current
- > 90% efficiency at 10-µA load current
	- 75-nA quiescent current
	- 60-nA shutdown current
- Single-mode operation
	- Eliminates mode transitions between buck, buck-boost and boost operation
	- Low output ripple
	- Excellent transient performance
- Robust operation features
	- Integrated soft start
	- Programmable input current limit with eight settings (1 mA to 100 mA and unlimited)
	- Output short-circuit and overtemperature protection
- Tiny solution size
	- Small 2.2-µH inductor, single 22-µF output capacitor
	- $-$ 12-ball, 1.5-mm \times 1.15-mm, 0.35-mm pitch WCSP package

2 Applications

- **[Smart watch](https://www.ti.com/solution/smartwatch)**
- **[Smart tracker](https://www.ti.com/solution/smart-tracker)**
- [Wearable electronics](https://www.ti.com/applications/personal-electronics/wearables/overview.html)
- [Medical sensor patches](https://www.ti.com/solution/medical-sensor-patch) and [patient monitors](https://www.ti.com/solution/multiparameter-patient-monitor)
- [Smart meters and sensor nodes](https://www.ti.com/applications/industrial/grid-infrastructure/overview.html)
- **[Electronic smart locks](https://www.ti.com/solution/electronic-smart-lock)**
- [Industrial IoT \(smart sensors\) and NB-IoT](https://www.ti.com/technologies/internet-of-things/overview.html)

3 Description

The TPS63901 device is a high-efficiency synchronous buck-boost converter with an extremely low quiescent current (75 nA typical). The device has 32 user-programmable output voltage settings from 1.8 V to 5 V.

A dynamic voltage-scaling feature lets applications switch between two output voltages during operation; for example, to save power by using a lower system supply voltage during standby operation.

With its wide supply voltage range and programmable input current limit (1 mA to 100 mA and unlimited), the device is ideal for use with a wide range of primary like 3S Alkaline, 1S Li-MnO₂ or 1S Li-SOCl₂, and secondary battery types.

The high-output current capability supports commonly-used RF standards like sub-1-GHz, BLE, LoRa, wM-Bus, and NB-IoT.

Device Information

| Part Number (1) Package | | Body Size (NOM) | |
|------------------------------|------------------|----------------------------|--|
| TPS63901 | WCSP (12) | 1.50 mm \times 1.15 mm | |

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic

Table of Contents

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

5 Pin Configuration and Functions

Figure 5-1. 12-Ball WCSP Package (Top View)

Table 5-1. Pin Functions

6 Specifications

6.1 Absolute Maximum Ratings

over operating junction temperature range (unless otherwise noted)⁽¹⁾

(1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

(2) All voltage values are with respect to network ground terminal, unless otherwise noted.

6.2 ESD Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

(1) Effective capacitance after DC bias effects have been considered.

6.4 Thermal Information

(1) For more information about traditional and new thermal metrics, see the *[Semiconductor and IC Package Thermal Metrics](https://www.ti.com/lit/pdf/SPRA953)* application report.

6.5 Electrical Characteristics

 ${\sf T_J}$ = –40°C to 125°C, V_I = 3.0 V, V_O = 2.5 V . Typical values are at T $_{\sf J}$ = 25°C (unless otherwise noted).

6.5 Electrical Characteristics (continued)

 T_J = –40°C to 125°C, V_I = 3.0 V, V_O = 2.5 V . Typical values are at T_J = 25°C (unless otherwise noted).

6.6 Typical Characteristics

7 Detailed Description

7.1 Overview

The TPS63901 device is a four-switch synchronous buck-boost converter with a maximum output current of 400 mA. The device has a single-mode operation that allows the device to regulate the output voltage to a level above, below, or equal to the input voltage without displaying the mode-switching transients and unpredictable inductor current ripple from which many other buck-boost devices suffer.

The switching frequency of the TPS63901 device varies with the operating conditions: it is lowest when I_0 is low and increases smoothly as I_O increases.

7.2 Functional Block Diagram

7.3 Feature Description

7.3.1 Trapezoidal Current Control

Figure 7-1 shows a simplified block diagram of the power stage of the device. Inductor current is sensed in series with Q1 (the peak current) and Q4 (the valley current).

Figure 7-1. Power Stage Simplified Block Diagram

The device uses a trapezoidal inductor current to regulate its output under all operating conditions. Thus, the device only has one operating mode and does not display any of the mode-change transients or unpredictable switching displayed by many other buck-boost devices.

There are four phases of operation:

- Phase $A Q1$ and $Q3$ are on and $Q2$ and $Q4$ are off.
- Phase $B Q1$ and $Q4$ are on and $Q2$ and $Q3$ are off.
- Phase C Q2 and Q4 are on and Q1 and Q3 are off.
- Phase $D Q2$ and $Q3$ are on and $Q1$ and $Q4$ are off.

Figure 7-2 shows the inductor current waveform when V_I > V_O, Figure 7-3 shows the current waveform when V_I = V_O, and Figure 7-4 shows the current waveform when V_I < V_O.

Figure 7-2 through Figure 7-4 show the typical waveforms during continuous conduction mode (CCM) switching for three operating conditions. During discontinuous conduction mode (DCM), the typical inductor current waveforms look similar to CCM with Phase D at 0-A inductor current. In deep boost mode, where V_I << V_O, Phase C length gradually decreases to zero until the switching waveform becomes triangular.

Figure 7-2. Inductor Current Waveform when V^I > VO (CCM)

Figure 7-3. Inductor Current Waveform when V^I = VO (CCM)

Figure 7-4. Inductor Current Waveform when V^I < VO (CCM)

The ideal relationship between V_{I} and V_{O} (that is, assuming no losses) is:

$$
V_{\rm O} = V_{\rm I} \left(\frac{t_{w({\rm A})} + t_{w({\rm B})}}{t_{w({\rm B})} + t_{w({\rm C})}} \right)
$$

where

- V_1 is the input voltage.
- $V_{\rm O}$ is the output voltage.
- $t_{w(A)}$ is the duration of phase A.
- $t_{w(B)}$ is the duration of phase B.
- $t_{w(C)}$ is the duration of phase C.

By varying relative duration of each phase, the device can regulate V_O to be less than, equal to, or greater than VI .

7.3.2 Device Enable and Disable

The device turns on when *all* of the following conditions are true:

- The supply voltage is greater than the positive-going undervoltage lockout (UVLO) threshold.
- The EN pin is high.

The device turns off when *at least one* of the following conditions is true:

- The supply voltage is less than the negative-going UVLO threshold.
- The EN pin is low.

[Figure 7-13](#page-15-0) shows a complete state diagram.

After the device turns on, the internal reference system starts, then the trimming information and the CFG pins are read out. The device ignores any further changes to the CFG pins during device operation.

Figure 7-5 shows the internal start-up sequence.

Figure 7-5. Internal Start-Up Sequence

7.3.3 Soft Start

The device has a soft-start feature that starts the device typically with 500-mA peak current limit until $V_O = 1.8 V$ and 500 µs elapsed when the input current limit is set to unlimited (see [Section 7.3.4\)](#page-11-0). Afterward, the output voltage ramps in a series of discrete steps (see [Figure 7-6](#page-10-0)).

- When $V_{\Omega} \le 1.8$ V, peak current is limited to 500 mA typical for 500 µs.
- When V_O > 1.8 V, each step is 100 mV high and has a duration of 125 µs.

The total soft-start ramp-up time can be calculated with Equation 2.

$$
t_{r(SS)} = V_O \times 1.25 \, \text{[ms/}}_V \text{]} - 1.75 \, \text{[ms]}
$$
 (2)

where

- $t_{r(SS)}$ is the rise time of the output voltage in milliseconds.
- $V_{\rm O}$ is the output voltage in volts.

Figure 7-6 shows a typical start-up case.

Figure 7-6. Start-Up Behavior

Figure 7-7. Typical Soft-Start Ramp Step Size

Table 7-1 shows the typical start-up time for a number of standard output voltages.

Table 7-1. Typical Start-Up Times

If the output is prebiased – that is, the initial output voltage is not zero – the start-up behavior is as follows:

- If the prebias voltage is *lower* than the target voltage, the device does not start switching until the ramping output voltage is greater than the prebias voltage (see [Figure 7-8](#page-11-0)).
- If the prebias voltage is *higher* than the target voltage, the device does not start to switch until the output voltage has decreased to the target voltage (see [Figure 7-9](#page-11-0)). The device cannot actively discharge the output to the target voltage and relies on the load current to discharge the output capacitor and decrease the output voltage to the target value.

Figure 7-9. Start-Up Behavior into Prebiased (High) Output

7.3.4 Input Current Limit

The device can limit the current drawn from its supply, so that it can be used with batteries that do not support high peak currents. The input current limit is active during normal operation and at start-up to avoid high inrush current. The device has eight current limit settings:

- 1 mA
- 2.5 mA
- 5 mA
- 10 mA
- 25 mA
- 50 mA
- 100 mA
- **Unlimited**

CFG1 and CFG2 pins select which setting is active (see [Section 7.3.6](#page-12-0)).

7.3.5 Dynamic Voltage Scaling

The device has a dynamic voltage scaling function to switch between the two output voltage settings. When the SEL pin changes state, the output voltage ramps to the new value in 100-mV steps. The duration of each step is 125 µs (see [Figure 7-10](#page-12-0)).

The device does not actively discharge the output capacitor when the output voltage ramps to a lower level. This leads to a longer output voltage settling time when light load is applied (see [Figure 7-11\)](#page-12-0). The settling time can be calculated with Equation 3.

$$
t_{\text{settle}} = C_{\text{O}} \times \frac{V_{\text{O(HIGH)}} - V_{\text{O(LOW)}}}{I_{\text{O}}}
$$
(3)

 $V_{O(1)}$

Load

7.3.6 Device Configuration (Resistor-to-Digital Interface)

The device has three configuration pins (CFG1, CFG2, and CFG3) that control its operation. When the device starts up, a resistor-to-digital (R2D) interface reads the values of the configuration resistors on the CFG pins and transfers the setting to an internal configuration register (see Figure 7-12).

- CFG1 and CFG2 set $V_{O(2)}$ level and the input current limit.
- CFG3 sets $V_{O(1)}$ level.

To reduce power consumption, the device reads the value of the resistors connected to the configuration pins during start-up and then disables these pins. Once the device has started to operate, changes to the configuration pins have no effect.

Figure 7-12. Resistor-to-Digital Interface Block Diagram

Table 7-2 summarizes the resistor values needed to configure the device for different input current limit and output voltage (SEL = high) settings. For correct operation, use resistors with a tolerance of $\pm 1\%$ or better and a temperature coefficient of ±200 ppm or better.

Note

For correct operation, TI recommends that the total RMS error of the configuration resistors – including initial tolerance, temperature drift, and aging – is less than ±3%.

| 1800 μ and 2000 and 2000 and 2000 and 2000 and 2000 and 2000 and 200 | | | | | | | | |
|--|-------------------|----------------------------|--------------|-----------------|-----------------|-----------------|--------------------------|--------------------|
| Output Voltage - $V_{O(2)}$ $(SEL = HIGH)$ | | Input Current Limit | | | | | | |
| | | UNLIMITED | 100 mA | 50 mA | 25 mA | 10 mA | 5 m A | 2.5 _m A |
| 1.8V | R _{CFG1} | 0Ω | | | | | | |
| | R _{CEG2} | 0Ω | 511 Ω | 1.15 k Ω | 1.87 k Ω | 2.74 k Ω | $3.83 \; \text{k}\Omega$ | 5.11 k Ω |
| 1.9V | R_{CFG1} | 511 Ω | | | | | | |
| | R _{CFG2} | 0Ω | 511 Ω | 1.15 k Ω | 1.87 $k\Omega$ | $2.74 k\Omega$ | $3.83 \text{ k}\Omega$ | 5.11 k Ω |

Table 7-2. Input Current Limit and Output Voltage (SEL = High) Settings

Table 7-2. Input Current Limit and Output Voltage (SEL = High) Settings (continued)

Table 7-2. Input Current Limit and Output Voltage (SEL = High) Settings (continued)

Table 7-3 summarizes the resistor values needed to configure the device for different output voltage (SEL = low) settings. For correct operation, use resistors with a tolerance of ±1% or better and a temperature coefficient of better than ±200 ppm.

Table 7-3. Output Voltage (SEL Pin = Low) Settings

7.3.7 SEL Pin

The SEL pin selects which configuration bits control the output voltage.

- When SEL = high, the output voltage $V_{O(2)}$ is set.
- When SEL = low, the output voltage $V_{O(1)}$ is set.

7.3.8 Short-Circuit Protection

7.3.8.1 Current Limit Setting = 'Unlimited'

The device has a built-in short circuit protection function to limit the current through Q1. The maximum current that flows is limited by the peak current limit. The output voltage decreases if the load is higher than the peak current limit. If the output voltage falls below 1.25 typically, the short circuit protection is activated. With short circuit protection activated, the input current is limited to 26 mA on average.

The device automatically restarts to normal operation after the short condition is removed.

7.3.8.2 Current Limit Setting = 1 mA to 100 mA

The input current limiting function automatically limits current during a short-circuit condition. The device regulates the average input current for as long as the short-circuit condition exists. If the output voltage falls below 1.25 V typically, the short circuit protection is activated. For input current limit settings of 100 mA, 50 mA, and 25 mA, the short circuit protection limits the input current to 26 mA on average. For input current limit setting of 10 mA, 5 mA, 2.5 mA, and 1 mA, the short circuit protection limits the input current to slightly above the typical values for each setting. Table 7-4 shows the typical short circuit currents for each input current limit setting.

The device automatically restarts to previous operation after the short condition is removed.

Table 7-4. Typical Input Current During Short Circuit Condition (V_O < 1.25 V Typically) for All Input **Current Limit Settings**

| Input Current Limit Setting | Typical Short Circuit Input Current |
|------------------------------------|--|
| 1 mA | 1.2 mA |
| 2.5 mA | 2.8 mA |
| 5 _m A | 5.2 mA |
| 10 mA | 12 mA |
| 25 mA | 26 mA |
| 50 mA | 26 mA |
| 100 mA | 26 mA |
| Unlimited | 26 mA |

7.3.9 Thermal Shutdown

The device has a thermal shutdown function that disables the device if it gets too hot for correct operation. When the device cools down, it automatically restarts operation after a typical delay of $t_{d(RESTART)} = 10$ ms. The device starts with the soft-start feature (see [Section 7.3.3](#page-9-0)) and keeps the previously read CFG pin setting.

7.4 Device Functional Modes

The device has two functional modes: on and off. The device enters on mode when the voltage on the VIN pin is higher than the UVLO threshold and a high logic level is applied to the EN pin. The device enters off mode when the voltage on the VIN pin is lower than the UVLO threshold or a low logic level is applied to the EN pin.

Figure 7-13. Device Functional Modes

8 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The TPS63901 is a high-efficiency, non-inverting buck-boost converter with an extremely low quiescent current, suitable for applications that need a regulated output voltage from an input supply that can be higher or lower than the output voltage. The input current limit and output voltage are set through resistors connected to the three CFGx pins.

8.2 Typical Application

Figure 8-1. 3.3-V_{OUT} Typical Application

8.2.1 Design Requirements

The design guideline provides a component selection to operate the device within the *[Recommended Operating](#page-3-0) [Conditions](#page-3-0)*.

Table 8-1. Matrix of Output Capacitor and Inductor Combinations

(1) Inductor tolerance and current derating is anticipated. The effective inductance can vary by 20% and –30%.

(2) Capacitance tolerance and DC bias voltage derating is anticipated. The effective capacitance can vary by 20% and –50%.
(3) Output voltage ripple increases versus typical application.

Output voltage ripple increases versus typical application.

(4) Typical application. Other check marks indicate possible filter combinations.

(5) Start-up time increased

8.2.2 Detailed Design Procedure

The first step is the selection of the output filter components. To simplify this process, the *[Recommended](#page-3-0) [Operating Conditions](#page-3-0)* outlines minimum and maximum values for inductance and capacitance. Tolerance and derating must be taken into account when selecting nominal inductance and capacitance.

8.2.2.1 Inductor Selection

The inductor selection is affected by several parameters such as inductor ripple current, output voltage ripple, transition point into power save mode, and efficiency. See Table 8-2 for typical inductors.

For high efficiencies, the inductor must have a low DC resistance to minimize conduction losses. Especially at high-switching frequencies, the core material has a high impact on efficiency. When using small chip inductors, the efficiency is reduced mainly due to higher inductor core losses, which needs to be considered when selecting the appropriate inductor. The inductor value determines the inductor ripple current. The larger the inductor value, the smaller the inductor ripple current and the lower the core and conduction losses of the converter. Conversely, larger inductor values cause a slower load transient response. To avoid saturation of the inductor, the peak current for the inductor in steady state operation is calculated using Equation 5. Only the equation that defines the switch current in boost mode is shown because this provides the highest value of current and represents the critical current value for selecting the right inductor.

Put
$$
y \text{ is } B \text{ is } D = \frac{V_{OUT} - V_{IN}}{V_{OUT}}
$$
\n(4)

$$
I_{PEAK} = \frac{Iout}{\eta \times (1 - D)} + \frac{Vin \times D}{2 \times f \times L}
$$
 (5)

where

- D is duty cycle in boost mode.
- *f* is the converter switching frequency.
- L is the inductor value.
- η is the estimated converter efficiency (use the number from the efficiency curves or 0.9 as an assumption).

Note

The calculation must be done for the minimum input voltage in boost mode.

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current of the inductor needed. TI recommends choosing an inductor with a saturation current 20% higher than the value calculated using Equation 5. Possible inductors are listed in Table 8-2.

| Inductor Value $[\mu H]^{(1)}$ | Saturation Current [A] | DCR [m Ω] | Part Number | Manufacturer | Size ($L \times W \times$ H mm) |
|--|-------------------------------|---------------------|--------------------|---------------------|---------------------------------------|
| 2.2 | 3.5 | 21 | XFL4020-222ME | Coilcraft | $4 \times 4 \times 2$ |
| 2.2 | 1.7 | 72 | SRN3015TA-2R2M | Bourns | $3 \times 3 \times 1.5$ |
| 2.2 | 3.3 | 82 | DFE252012F-2R2M | Murata | $2.5 \times 2 \times 1.2$ |
| 2.2 | 2.4 | 116 | DFE201612E-2R2M | Murata | $2.0 \times 1.6 \times 1.2$ |
| 2.2 | 2.0 | 190 | DFE201210U-2R2M | Murata | $2.0 \times 1.2 \times 1.0$ |

Table 8-2. List of Recommended Inductors

(1) See the *[Third-party Products Disclaimer](#page-25-0)*.

8.2.2.2 Output Capacitor Selection

For the output capacitor, use of small ceramic capacitors placed as close as possible to the VOUT and GND pins of the IC is recommended. The recommended nominal output capacitor value is a single 22 µF. If, for any reason, the application requires the use of large capacitors, which cannot be placed close to the IC, use a smaller ceramic capacitor in parallel to the large capacitor. The small capacitor must be placed as close as possible to the VOUT and GND pins of the IC.

It is important that the effective capacitance is given according to the recommended value in the *Recommended Operating Conditions*. In general, consider DC bias effects resulting in less effective capacitance. The choice of the output capacitance is mainly a trade-off between size and transient behavior as higher capacitance reduces

transient response overshoot and undershoot and increases transient response time. Possible output capacitors are listed in Table 8-3.

There is no upper limit for the output capacitance value.

At light load currents, the output voltage ripple is dependent on the output capacitor value. Larger output capacitors reduce the output voltage ripple. The leakage current of the output capacitor adds to the overall quiescent current.

| Capacitor Value [μ F] ⁽¹⁾ | Voltage Rating [V] Part Number | | Manufacturer | Size (Metric) |
|---|---|-------------------|---------------------|---------------|
| 22 | 6.3 | GRM187R60J226ME15 | Murata | 0603 (1608) |
| 22 | 6.3 | GRM219R60J476ME44 | Murata | 0805 (3210) |
| 47 | 6.3 | GRM188R60J476ME15 | Murata | 0603 (1608) |

Table 8-3. List of Recommended Capacitors

(1) See the *[Third-party Products Disclaimer](#page-25-0)*.

8.2.2.3 Input Capacitor Selection

A 10-µF input capacitor is recommended to improve line transient behavior of the regulator and EMI behavior of the total power supply circuit. An X5R or X7R ceramic capacitor placed as close as possible to the VIN and GND pins of the IC is recommended. This capacitance can be increased without limit. If the input supply is located more than a few inches from the TPS63901 converter, additional bulk capacitance can be required in addition to the ceramic bypass capacitors. An electrolytic or tantalum capacitor with a value of 47 µF is a typical choice.

When operating from a high impedance source, a larger input buffer capacitor is recommended to avoid voltage drops during start-up and load transients.

The input capacitor can be increased without any limit for better input voltage filtering. The leakage current of the input capacitor adds to the overall quiescent current.

| Capacitor Value [μ F] ⁽¹⁾ | Voltage Rating [V] | Part Number | Manufacturer | Size (Metric) |
|---|---------------------------|--------------------|---------------------|---------------|
| 10 | 6.3 | GRM188R60J106ME47 | Murata | 0603 (1608) |
| 10 | 10 | GRM188R61A106ME69 | Murata | 0603 (1608) |
| 22 | 6.3 | GRM187R60J226ME15 | Murata | 0603 (1608) |

Table 8-4. List of Recommended Capacitors

(1) See the *[Third-party Products Disclaimer](#page-25-0)*.

8.2.2.4 Setting The Output Voltage

The output voltage is set with the CFGx pins (see [Section 7.3.6](#page-12-0)).

8.2.3 Application Curves

Table 8-5. Components for Application Characteristic Curves for V_{OUT} = 3.3 V

(1) See the *[Third-Party Products Discalimer](#page-25-0)*

 (2) For other output voltages, refer to [Table 8-1](#page-16-0) for resistor values.

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Figure 8-7. Typical Burst Switching Frequency vs Output Current

Figure 8-6. Typical Burst Switching Frequency vs Output Current

Texas

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9 Power Supply Recommendations

The TPS63901 device is designed to operate with input supplies from 1.8 V to 5.5 V. The input supply must be stable and free of noise to achieve the full performance of the device. If the input supply is located more than a few centimeters away from the device, additional bulk capacitance can be required. The input capacitance shown in the application schematics in this data sheet is sufficient for typical applications.

10 Layout

10.1 Layout Guidelines

PCB layout is an important part of any switching power supply design. A poor layout can cause unstable operation, load regulation problems, increased ripple and noise, and EMI issues.

The following PCB layout design guidelines are recommended:

- Place the input and output capacitors close to the device.
- Minimize the area of the input loop, and use short, wide traces on the top layer to connect the input capacitor to the VIN and GND pins.
- Minimize the area of the output loop, and use short, wide traces on the top layer to connect the output capacitor to the VOUT and GND pins.
- The location of the inductor on the PCB is less important than the location of the input and output capacitors. Place the inductor after the input and output capacitors have been placed close to the device. Route the traces to the inductor on an inner layer if necessary.

10.2 Layout Example

Figure 10-1 shows an example of a PCB layout that follows the recommendations of the previous section.

Figure 10-1. PCB Layout Example

11 Device and Documentation Support

11.1 Device Support

11.1.1 Third-Party Products Disclaimer

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following:

Texas Instruments, *[TPS63901 EVM User Guide](https://www.ti.com/lit/pdf/SLVUBU0)*

11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com.](https://www.ti.com) Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.4 Support Resources

TI E2E™ [support forums](https://e2e.ti.com) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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11.5 Trademarks

TI E2E™ is a trademark of Texas Instruments.

All trademarks are the property of their respective owners.

11.6 Electrostatic Discharge Caution

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.7 Glossary

[TI Glossary](https://www.ti.com/lit/pdf/SLYZ022) This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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TEXAS

TAPE AND REEL INFORMATION

ISTRUMENTS

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

www.ti.com www.ti.com 9-Aug-2022

PACKAGE MATERIALS INFORMATION

*All dimensions are nominal

PACKAGE OUTLINE

YCJ0012 DSBGA - 0.35 mm max height

DIE SIZE BALL GRID ARRAY

NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

YCJ0012 DSBGA - 0.35 mm max height

DIE SIZE BALL GRID ARRAY

NOTES: (continued)

3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).

EXAMPLE STENCIL DESIGN

YCJ0012 DSBGA - 0.35 mm max height

DIE SIZE BALL GRID ARRAY

NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

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