

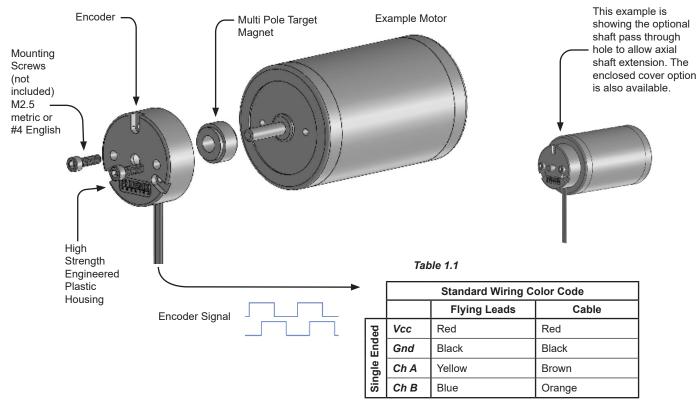
Features and Benefits

- 30 mm O.D. Miniature size
- Magnetic technology offers robust performance.
- 100% Non-contacting design (no bearings or bushings) provides an extremely long life and is tolerant to harsh environments.
- Simple two piece design (target magnet + encoder) for easy alignment and installation.
- Bi-directional two channel incremental quadrature output.
- Mounting holes for 2-bolt (.750" BHC x .125" O.D.) or 3-bolt pattern (.823" BHC x .078" O.D.)
- Target magnet for standard shaft sizes from 2 mm to 8mm. Custom bore sizes available.
- Options for 32 2500 pulse per channel per revolution.
- Customizable lead wires, cables, and or connectors.



Kit - Encoder with Target Magnet
Shown with shaft pass through hole and single ended wiring
Wire color order varies with part configuration

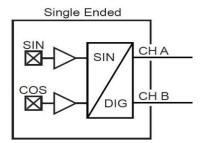
Application Example



Other colors available upon request. Contact sales@phoenixamerica.com.



Electrical Circuit



Absolute Maximum Ratings

Table 2.1

TUDIC E.T			
Characteristic	Symbol	Rating	Units
Forward Supply Voltage	V _{cc}	12	V
Reverse Supply Voltage	V _{RCC}	-0.3	V
Storage Temperature	T _s	125	°C
ESD (HMB, 100pF/1.5Kohm)		2	kV
Operating Temperature*		-40 to 125	°C

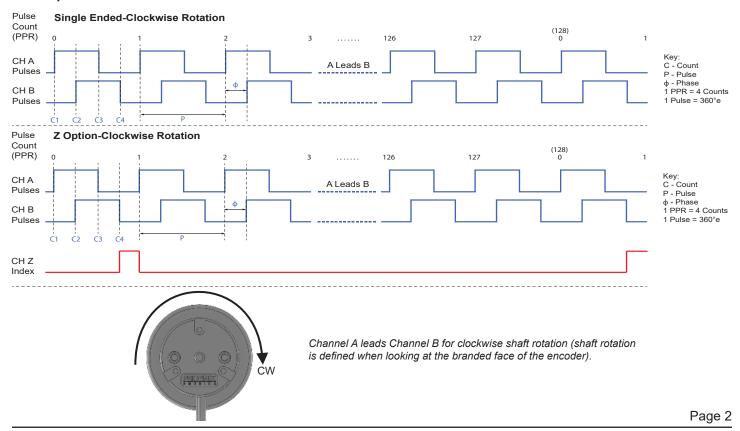
^{*}For plastic housing and electronics

Electrical Specifications - (Vcc= 5V, Ambient Temperature= 23 °C)

Table 2.2

Tuble E.E					
Characteristic	Symbol	Min.	Тур.	Max.	Unit
Supply Voltage	V _{cc}	3.3	5	6	V
Supply Current	I _{cc}	-	14	20	mA
Duty Cycle	-	40	50	60	%
Phase	-	70	90	110	°e
Output Frequency	fout	-	-	42	kHz

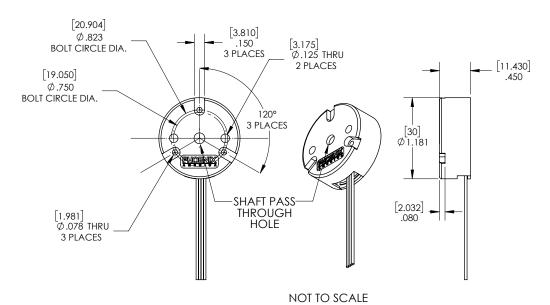
Output Waveforms



Phoenix America, LLC 4717 Clubview Drive Fort Wayne, IN 46804 Tel: (888)-801-1422 Local: (260)-432-9664 Fax: (260)-432-9967 www.phoenixamerica.com sales@phoenixamerica.com © Copywrite PAL 2022, PDS-DK 07/22



Encoder Physical Outline

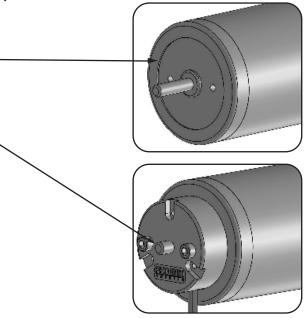


Other shaft pass through hole sizes available upon request. Contact sales@phoenixamerica.com.

Encoder Mounting Guidelines

Concentricity of the encoder housing to the target magnet is critical for optimal encoder performance. Considering the following during the design phase will ensure concentricity and ease of assembly.

- Tight molding tolerances allow for the outside diameter of the encoder to be used to locate the encoder housing concentric to the motor shaft and target magnet. A machined pocket on the motor endbell works well for alignment. Recommended pocket is 0.015" to 0.020" deep and 1.191" in diameter.
- Extending the shaft through the optional shaft pass through hole is an easy way to align the encoder housing to the motor shaft and target magnet. Simply position the encoder so that the shaft is centered concentrically in the shaft pass through hole.
- If previous two methods of alignment are not used it is recommended that the encoder be fastened to the motor using #5-40 or M3 mounting screws. The slightly larger diameter of the #5-40 and M3 screws will compensate for some of the tolerance allowed when using the standard recommended #4-40 or M2.5 mounting screws.





Target Magnet Physical Outline - Engineered Polymer Hub (Mounting Style H)

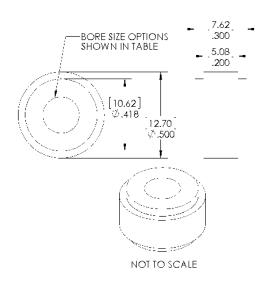


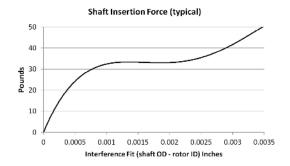
Table 5.1				
Bore Size (.inch)	Motor Shaft OD Size (nominal)	NEMA Guide Shaft Tolerance	Magnet Bore MIN. (inch)	Magnet Bore MAX. (inch)
079	2 mm (.0787")	+0.0000"/-0.0005"	.0727	.0757
118	3 mm (.1181")		.1121	.1151
125	1/8 in (.1250")		.1190	.1220
156	5/32 in (.1563")		.1503	.1533
157	4 mm (.1575")		.1515	.1545
188	3/16 in (.1875")		.1815	.1845
197	5 mm (.1969")		.1909	.1939
236	6 mm (.2364")		.2304	.2334
250	1/4 in (.2500")		.2440	.2470
276	7 mm (.2758")		.2698	.2728
313	5/16 in (.3125")		.3065	.3095
315	8 mm (.3150")		.3090	.3120

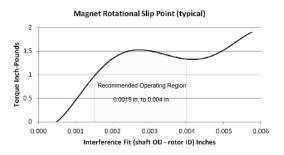
Other bore sizes available upon request. Contact sales@phoenixamerica.com.

Target Magnet Mounting Guidelines - Engineered Polymer Hub (Mounting Style H) For Press Fit Application

- Proper alignment of the target magnet to the encoder sensing element is critical for optimal encoder performance. Insure that the target magnet is mounted to the specified height shown below.
- A machined step on the motor shaft provides a quick and repeatable method for positioning the target magnet. Spacers or other fixturing should be used if no mechanical locating features are on the shaft.
- · A chamfered lead in on the shaft will aid in aligning the target magnet.
- Prior to insertion, the motor shaft should be clean and free of any oils, lubricants, or solvents.
- Proper fixtures and support must be used to ensure the target magnet is pressed on straight and aligned with the motor shaft.
- Opposite end of motor shaft should be supported to avoid undue stress on motor bearings during the pressing operation.
- In applications with high torque or environmental extremes, a retaining compound can be used to enhance the strength of the press fit.







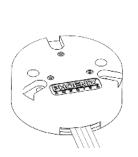
Page 4



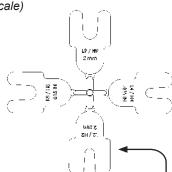
Target Magnet Physical Outline - Universal Hub (Mounting Style U)

A universal hub kit is available to provide a range of bore sizes to fit several popular industry shaft diameters.

Kit contents (not shown to scale)



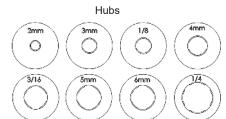




Gap Tool (2 mm needed for H2)

Includes 2 of each size for closed cover option.

Includes 3 of each size for shaft pass through option.





Magnet Insertion Tool



Target Magnet

Assembly Guidelines

Step 1

Attach two of the desired hub size on each side of the target magnet. Make sure the flats are in-line with each other.



Step 2

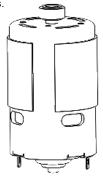
Use the insertion tool to push the target magnet assembly straight onto the shaft until the bottom face of the hub is resting on the 2 mm gap tool.



Without shaft pass-through option

Place the encoder onto the motor and secure with #2 or M2 screws.

Step 3



Step 4

Manually spin the shaft to verify that the shaft/magnet is not interfering with the encoder.

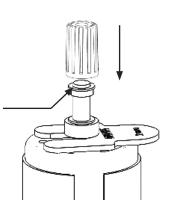


Encoder Cross Section - note the target magnet assembly and shaft are not in contact with the encoder housing or the motor

With shaft pass-through option

Step 2a

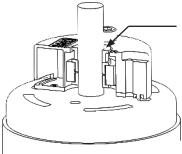
Insert an additional hub piece as shown. This is used as a space filler to match the opening in the encoder housing.



Step 3a

Place the encoder onto the motor and secure with #2 or M2 screws.





Encoder Cross Section - note the top face of the filler hub should be flush with the top face of the encoder housing as shown by the arrow pointer.

Page 5

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Subject to change without notice

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Wiring (Single ended option depicted)

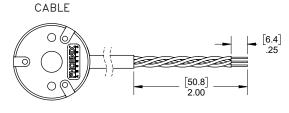
FLYING LEADS

[6.4]

.25

- 24 AWG
- 7x32 Strands, Tinned Copper
 - PVC Insulation
- MIL M16878/1
- Temperature Rating: 105°C

Table 6.1					
Single Ended Wiring					
	Leads	Cable	Connector Pin-Out		
Ch A	Yellow	Brown	1		
Ch B	Blue	Orange	2		
Gnd	Black	Black	3		
Vcc	Red	Red	4		

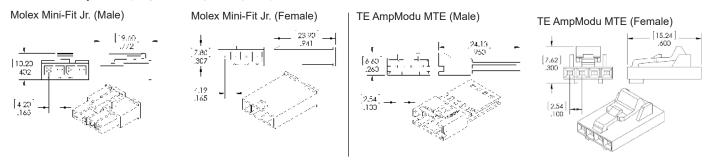


- 24 (or 26) AWG
- 4 (or 6) Conductor with Foil Shield and Drain
- · Stranded Tinned Copper
- PVC Insulation
- Grey PVC Jacket
- UL Style 2464, CSA
- Temperature Rating: 105°C

 ${\it Custom lengths and insulation materials available. Contact sales@phoenix america.com.}$

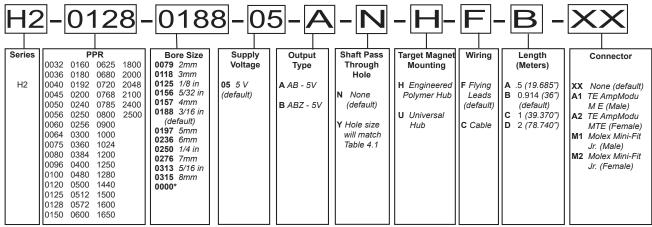
Connector Options (Single ended option depicted)

NOT TO SCALE



Need a different connector? Contact sales@phoenixamerica.com.

Part Number Description



^{*}Use for Universal Hub Option

Example: H2-0128-0188-05-A-N-H-F-B-XX

Page 6