

1. Scope

This document is applied to a magnetic sensor operating to ON/OFF when the sensor detects the magnetic field.

2. Part number

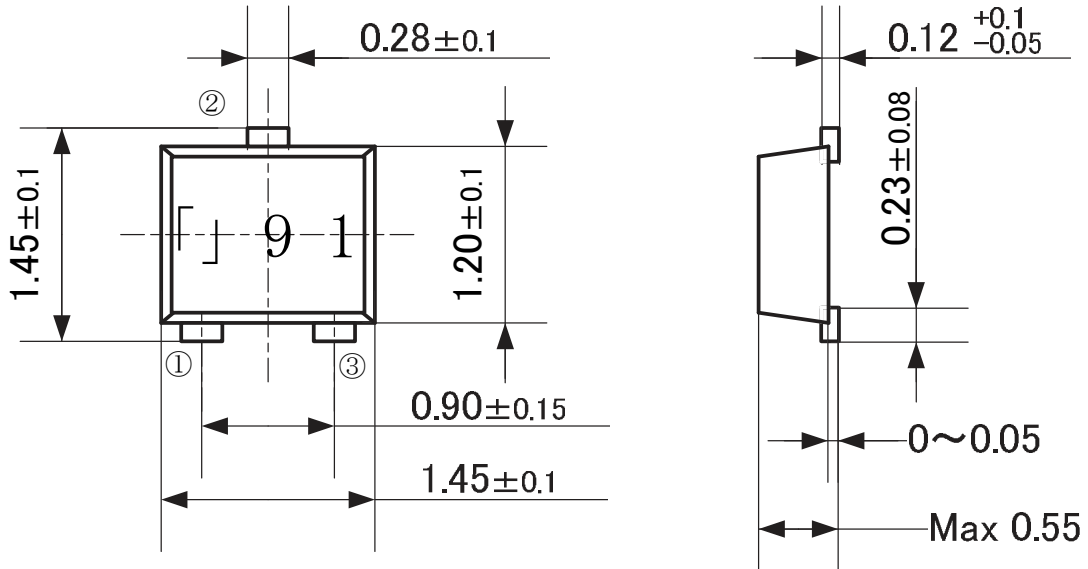
2-1 Part description      Magnetic Sensor

2-2 Murata part number    MRMS591P

3. Dimensions and schematics

3-1 Dimensions

3-1-1 Package outline drawing      (Unit :mm)

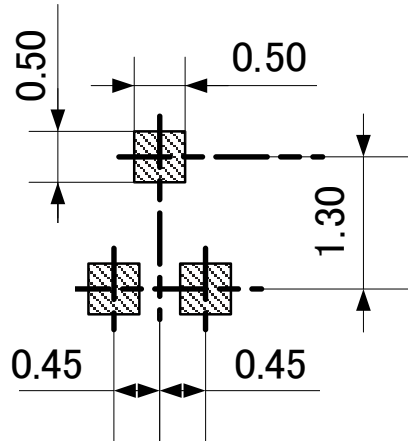


①:Vcc ②:Gnd ③:Out

3-1-2 Marking example

(E.g.) 「」 9 1      I    Control code.  
           ↓↓↓        II    Manufactured year...The last digit of the year  
           I II III     III    Manufactured month..  
                           Jan to Sep : 1 to 9  
                           Oct to Dec : X, Y, Z

3-1-3 Reference mount pad

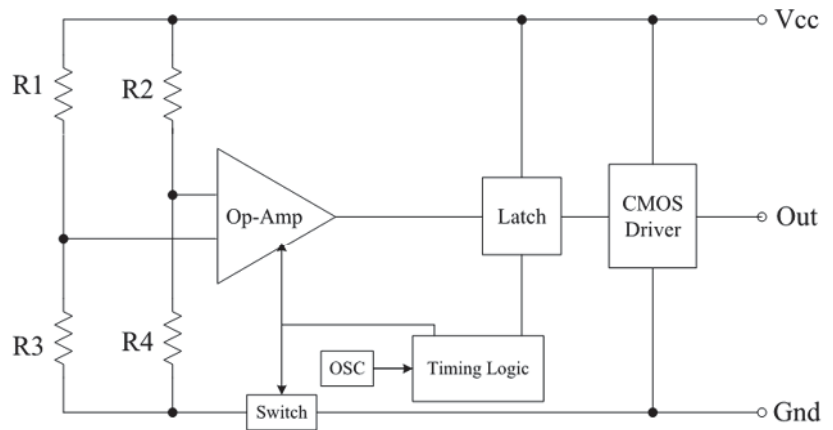
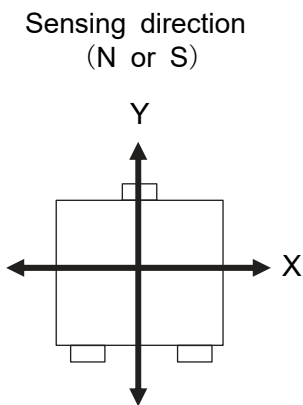


(Unit:mm)

NOTE1) Please evaluate your soldering paset condition and reflow condition with our product being mounted to your product.

NOTE2) Please make sure the sensing direction of the sensor (see the item 3-2) and your magnetic field direction to the sensor.

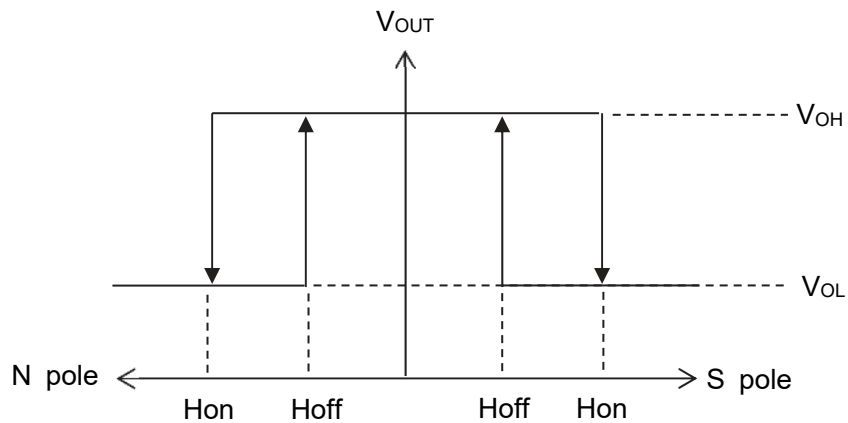
3-2 Block wiring diagram



The intermittent switch circuit inside R1-R4:MR Elements

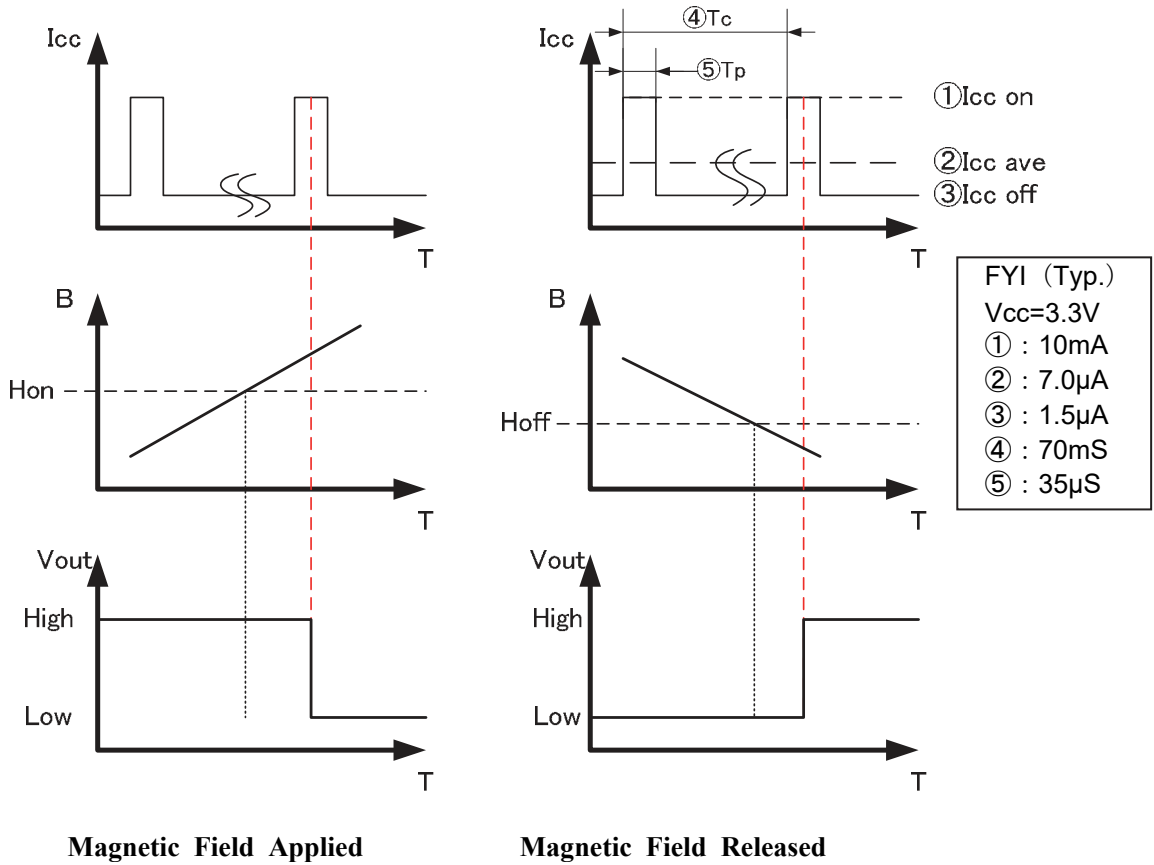
3-3 Magnetic electric conversion characteristic

ON/OFF switched depending on the intensity of the magnetic field.(Negative logic)



3-4 Timing diagram

The sensor has intermittence operating circuit.



NOTE1) AMR element is driven by the intermittent switch circuit shown in item 3-2.

The timing of Vout change is subject to the period of Icc on.

NOTE2) When the change rate Hon and Hoff exceed the speed of intermittent switch, sensor may cause non operation or miss operation.

3-5 Electric Characteristics/ Absolute Maximum Rating (Ta=+25°C±3°C)

	Parameter	Symbol	Conditions	Min.	Typ.	Max.	Unit
1	Supply voltage	V <sub>cc</sub>	—	3.1	3.3	3.5	V
2	Absolute max. supply voltage	—	—	—	—	6.0	V
3	Current consumption	I <sub>AVE</sub>	V <sub>cc</sub> =3.3V No Load Resistance Average Current	—	7	18	uA
4	Operating magnetic field (XY)	H <sub>on</sub>	V <sub>cc</sub> =3.3V No Load Resistance	—	2.3	4.0	mT
		H <sub>off</sub>	V <sub>cc</sub> =3.3V No Load Resistance	0.5	—	—	
5	Hi level output	V <sub>OH</sub>	V <sub>cc</sub> =3.3V No Load Resistance	3.0	—	—	V
6	Lo level output	V <sub>OL</sub>	V <sub>cc</sub> =3.3V No Load Resistance	—	—	0.3	V
7	Operating temp. range	—	—	-40	—	+85	°C
8	Storage temp. range	—	—	-40	—	+125	°C

NOTE1) Each specification is defined by testing above items individually.

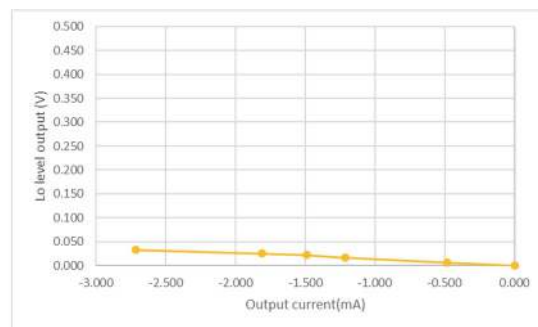
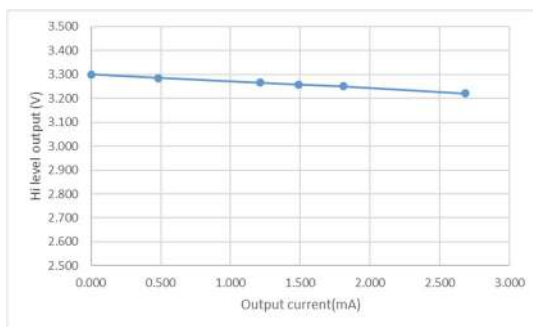
NOTE2) When shifting the sensor output from H to L, please make sure the magnetic field applied to the sensor becomes higher than the above operating magnetic field (H<sub>on</sub>) through your designing.

NOTE3) When shifting the sensor output from L to H, please make sure the magnetic field applied to the sensor becomes lower than the above operating magnetic field (H<sub>off</sub>) through your designing.

NOTE4) Sensitivity selection of this product is performed at V<sub>cc</sub>=3.3V. Operating magnetic field can possibly change when applying the supply voltage other than 3.3V.

NOTE5) In case of applying magnetic field stronger than 40mT, the sensor can possibly be OFF.

Reference) Output current-output voltage relationship



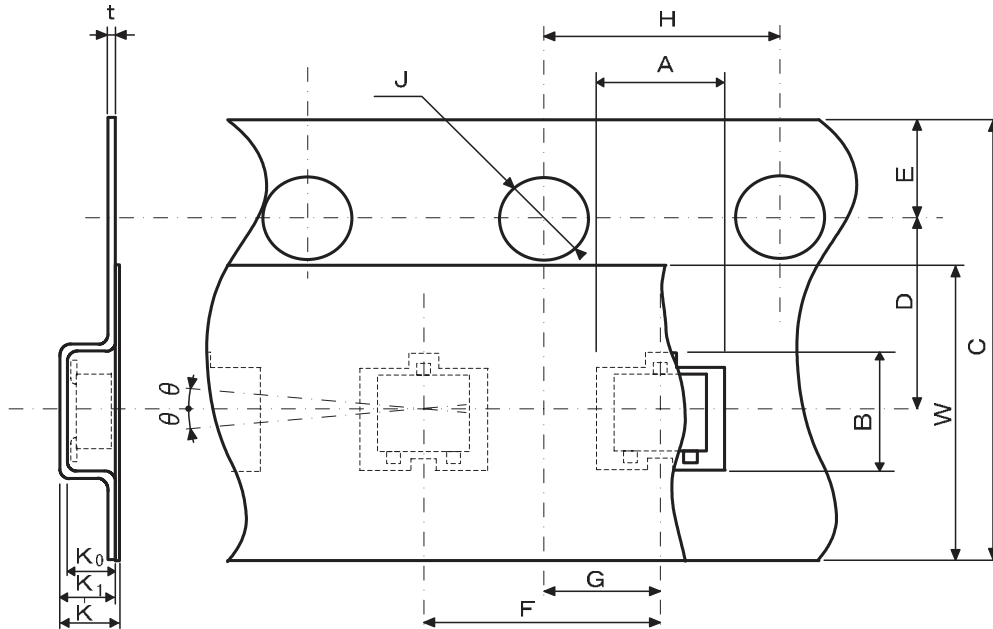
4. Packing specification

4-1 Packing information

Form of packing	Reel dimension	Pcs per reel
Tape & reel	φ180	3000pcs

4-2 Taping specifications

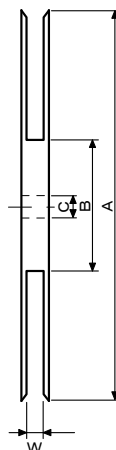
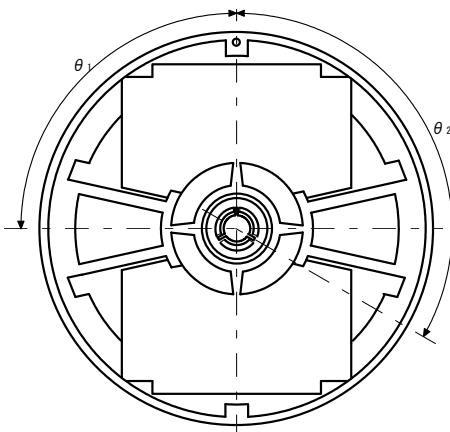
4-2-1 Taping dimensions



Unit:mm

Parameter		Symbol	Size/ Angle	Parameter		Symbol	Size/ Angle
Pocket	Length	A	1.73±0.1	Dist. Between center lines	L direction	G	2.0±0.05
	Width	B	2.17±0.1		W direction	D	3.5±0.05
	Depth	K <sub>0</sub>	0.70±0.05	Carrier tape	Width	W	5.5 <sup>+0.3</sup> <sub>0</sub>
	Pitch	F	4.0±0.1		Width	C	8.0±0.1
Feed hole	Diameter	J	φ1.5 <sup>+0.1</sup> <sub>0</sub>	Device	Thickness	T	0.18±0.05
	Pitch	H	4.0±0.1		Depth	K <sub>1</sub>	0.93±0.1
	Position	E	1.75±0.1	Device	Tilt	θ	10°MAX
Overall thickness		K	0.98±0.1				

4-2-2 Reel dimensions...EIAJ PRV08B compliant

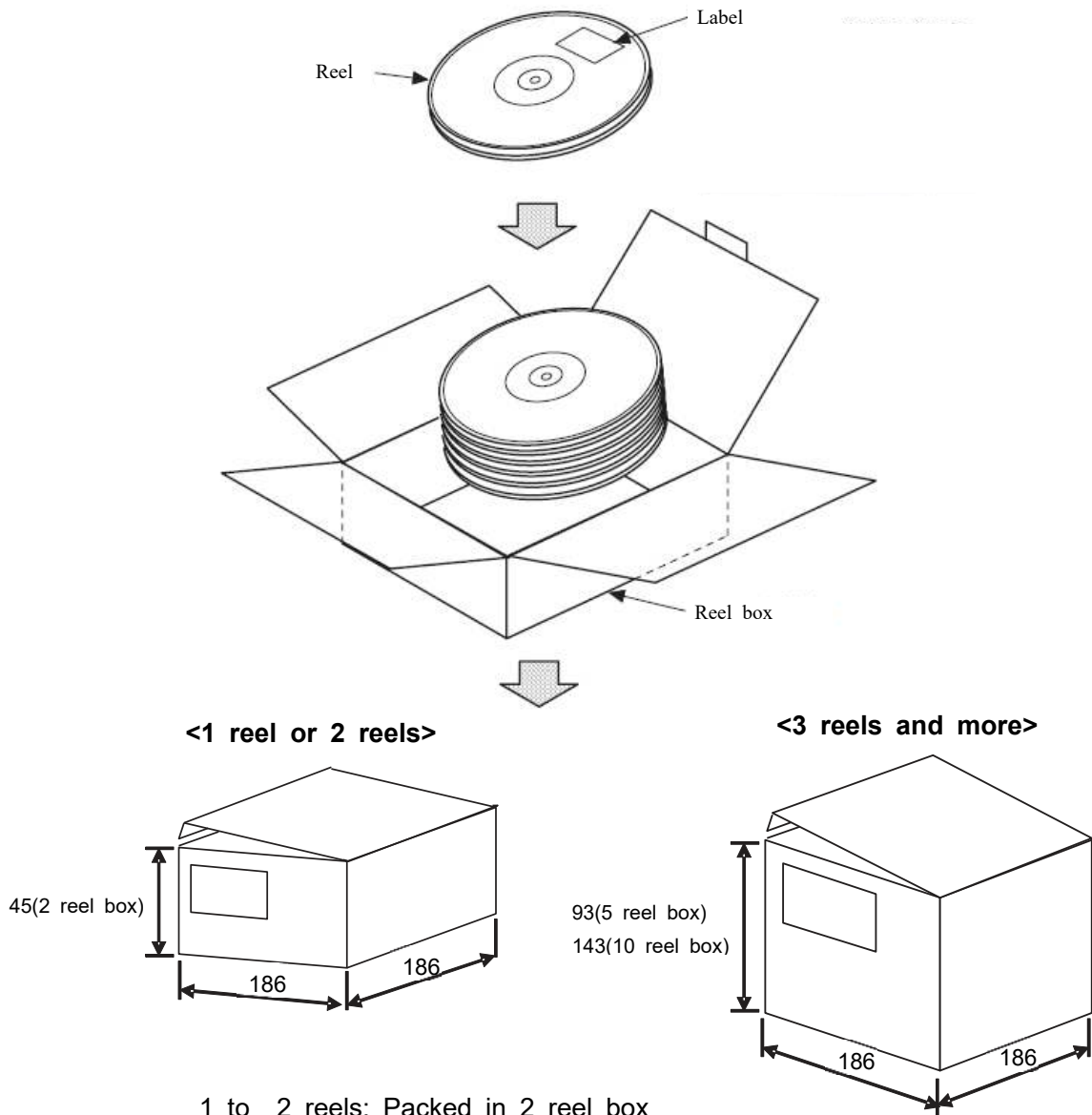


Unit: mm

Item	Symbol	Dim/Angle
Hub	Diameter	A
	Dis. between flanges	W
	Diameter	B
	Hub slit position	θ <sub>1</sub>
	Spindle hole diam.	C
Marking	Key slit position	θ <sub>2</sub>
	Labeled on one side of flange	



4-3 Outer packing specifications



- 1 to 2 reels: Packed in 2 reel box
- 3 to 5 reels: Packed in 5 reel box
- 6 to 10 reels: Packed in 10 reel box

\*When the box is not filled with reels, antistatic buffer material will be used to avoid product from moving inside box.

\*Unit: mm, Tolerance: +/- 5mm

Material

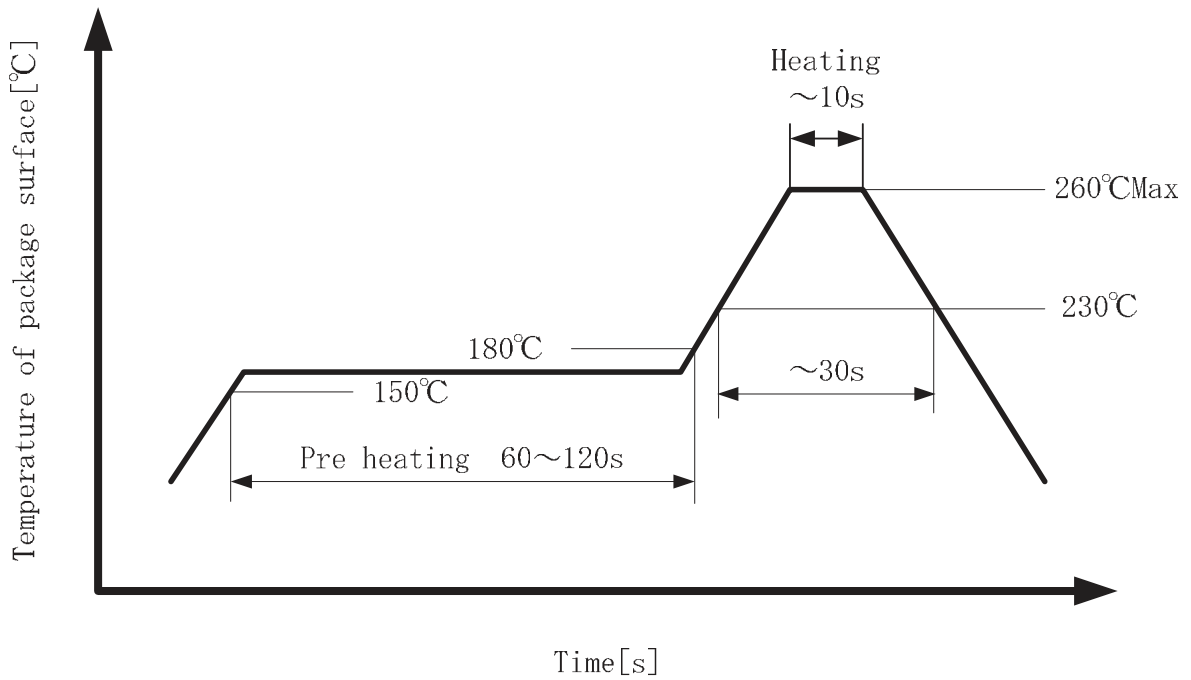
Reel packing box: Cardboard

5. Mounting condition

5-1 Reflow condition

- Below is the maximum reflow condition for the product mounting.
- The temperature mentioned in below table and figure is package surface temperature.
- The absolute maximum package peak temperature is 260°C and time within the temperature of 260°C must not exceed 10 seconds (Requirement).

Profile	Conditions
<b>Pre-heating</b> Temperature Min. Temperature Max. Time from Temperature Min. to Max.	150°C 180°C 60-120s
<b>Heating</b> Liquidus temperature Time maintained over Liquidus temperature Peak Temperature	230°C 30s 260°C/10s max.
Cycle of reflow	3 times max.





## 6. Reliability test

No.	Reliability test	Test conditions	Judgment criteria
1	High temp. storage	+125°C 500h No-load	<p>It shall be tested after being kept in a room over 2hours and Vcc=3.3V.</p> <p>• Output voltage Hi:3.0V or above Lo:0.3V or less</p> <p>• Using current 18 <math>\mu</math> A or less</p> <p>90% and more terminal surface covered with solder</p> <p>No external abnormality found.</p> <p>No terminal fracture, loosening found.</p>
2	High temp. load	+105°C 500h Load voltage 5.5V	
3	Low temp. storage	-40°C 500h No-load	
4	High temp, high humidity load	+85°C 85%RH 500h Load voltage 5.5V	
5	Thermal shock	-55 °C /30 min $\Leftrightarrow$ +125 °C /30min (vapor phase) 500 cycle, no-load	
6	Vibration	Apply vibration [Max amplitude: 1.5mm, frequency: 10 to 55Hz, 1 cycle minute, 3 directions, 2h in each direction (total 6h )]	
7	Shock test	Unpacked condition, X, Y, Z direction, 1470m/s <sup>2</sup> , 5 times/each	
8	Drop test	100g dummy load, Height: 150cm, on the concrete, 6 sides, 10 times/each	
9	Solder heat resistance	Pretreatment: +85°C, 85%RH, 168h Reflow condition: Max. 260°C & 230°C, 30 sec, times of reflow: 3	
10	Electrostatic resistance	Machine Model Condition: 200pF, Resistance: 0 $\Omega$ , +/-200V	
		Human Body Model Condition: 100pF, Resistance: 1.5k $\Omega$ , +/-2kV	
11	Solder ability	Solder temp.: +230°C, Time: 3 sec immersion	
12	Electrode sticking tendency	5N(510gf), 4 directions, 10 sec	
13	Bending cycle	Glass epoxy PCB, t=1.6, Speed: 1mm/s, 90mm span, bending range $\pm$ 1mm, 1500 cycle	
14	Bending limit	Glass epoxy PCB, t=1.6, 90mm span, bending range $\pm$ 4mm.	

## 7. Caution

### 7-1 Limitation of applications

Please avoid using this product for the applications listed below which require especially high reliability in order to prevent defects that might directly cause damage to the third party's life, body, or property.

When this product is used for the applications listed below, we shall not be liable for any claims on the product.

- ① Aircraft equipment
- ② Aerospace equipment
- ③ Undersea equipment
- ④ Generating plant equipment
- ⑤ Medical equipment
- ⑥ Transportation equipment (vehicles, trains, ships, etc.)
- ⑦ Traffic signal equipment
- ⑧ Data processing equipment
- ⑨ Application of similar complexity and/or reliability requirements to the applications listed above.

### 7-2 Fail-safe

Be sure to provide appropriate fail-safe function on your product to prevent a second damage that may be caused by the abnormal function or the failure of our product.

## 8. Caution for use

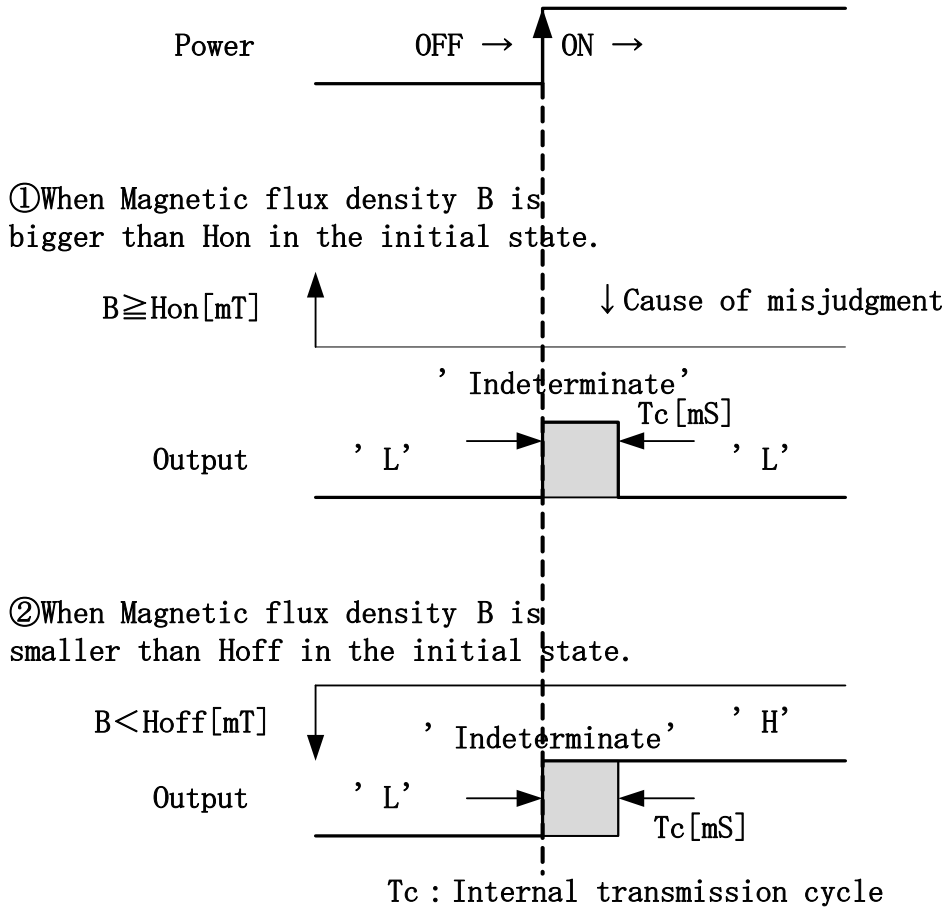
### 8-1 Handling

- This product may be degraded by electrostatic discharge. It is necessary to take anti-static precautions when handling.

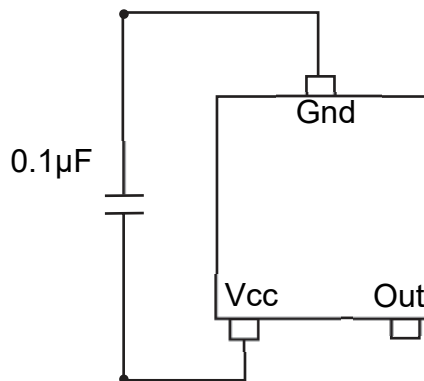
### 8-2 Design

- Please carefully evaluate this product for the magneto-variation of the magnet used along with this product, otherwise this product may result in the miss-operation or the non-operation.
- Sensor miss-operation or non-operation may occur due to the influence of the magnetic noise from surrounding devices such as motor. Please make sure there is no influence of the magneti noise in designing process.
- Please be careful about a magnetic body (Iron, Nickel, etc.) and a magnetic noise immunity that may affect the magnetism of a magnet.
- Please do not supply inverse voltage or excess voltage to this product. If applied, this product may be damaged and electrically destroyed.
- Please design your product not to be affected by stress of the resin due to heat shrink.
- Sensor output (Vout) is not stable at power on to the sensor. After power on, it needs about 4 times of Tc showed on item 3-4 to make it stable.

- Please avoid plugging/unplugging of connector cable while the power is on.



- It is effective to place a bypass capacitor near AMR sensor for power supply noise suppression.



- \*  $0.1\ \mu\text{F}$  is the recommended value and does not guarantee operation. Please select the suitable capacity depending on the usage environment. In addition, when the sensor is used under high noise level, Zener diode is recommended in parallel with a bypass capacitor.

### 8-3 Storage condition

- Recommended storage conditions are listed below.  
Temperature : +5 to +30°C  
Humidity : 70%(RH)% and lower  
\*Desiccator storage or storage in N<sub>2</sub> atmosphere is recommended.
- Allowable storage time of the product is one year from the date of delivery.
- Please take account of the storage conditions listed above. Please also use the product as soon as possible after opening the product packing to avoid the deterioration of solder ability.
- Please avoid the water, chemical solvent, or oil.
- Please avoid the corrosive gas (Cl<sub>2</sub> H<sub>2</sub>S, NH<sub>3</sub> NO<sub>2</sub>, NO<sub>3</sub> etc.)
- Please avoid the strong vibration or shock.

### 8-4 Mounting

- Please mount this product under standard reflow condition. Otherwise this product may be damaged.
- Hand soldering is not allowed for this product.
- Please do not apply excessive load to the terminals. Also, please do not bend the terminals.
- Please do not apply excessive bending stress to the product by bending the PCB or by similar handling as it may change the sensor sensitivity.
- Please make sure the mounting state of the sensor after mounting it. Depend on your application, mounting error may cause the sensor miss operation.

### 9. Note

- Make sure that your product has been evaluated in view of your specifications with our product being mounted to your product.
- Not to use our product deviating from the agreed specification.