### **Microprocessor Supervisory Circuits**

#### **General Description**

The MAX691A/MAX693A/MAX800L/MAX800M microprocessor (μP) supervisory circuits are pin-compatible upgrades to the MAX691, MAX693, and MAX695. They improve performance with 30μA supply current, 200ms typ reset active delay on power-up, and 6ns chip-enable propagation delay. Features include write protection of CMOS RAM or EEPROM, separate watchdog outputs, backup-battery switchover, and a RESET output that is valid with  $V_{CC}$  down to 1V. The MAX691A/ MAX800L have a 4.65V typical reset-threshold voltage, and the MAX693A/MAX800Ms' reset threshold is 4.4V typical. The MAX800L/MAX800M guarantee power-fail accuracies to ±2%.

#### **Applications**

- Computers
- **Controllers**
- Intelligent Instruments
- Critical μP Power Monitoring

### **Typical Operating Circuit**



*MaxCap is a registered trademark of Kanthal Globar, Inc.*

#### **Features**

- 200ms Power-OK/Reset Timeout Period
- 1μA Standby Current, 30μA Operating Current
- On-Board Gating of Chip-Enable Signals, 10ns max Delay
- MaxCap<sup>®</sup> or SuperCap Compatible
- Guaranteed RESET Assertion to  $V_{CC}$  = +1V
- Voltage Monitor for Power-Fail or Low-Battery Warning
- Power-Fail Accuracy Guaranteed to ±2% (MAX800L/M)
- Available in 16-Pin Narrow SO, Plastic DIP, and TSSOP Packages

#### **Ordering Information**



*Ordering Information continued at end of data sheet.*

\**Dice are specified at TA = +25°C, DC parameters only. Devices in PDIP, SO, and TSSOP packages are available in both leaded and lead-free packaging. Specify lead free by adding the + symbol at the end of the part number when ordering. Lead free not available for CERDIP package.*





### **Absolute Maximum Ratings**

Terminal Voltage (with respect to GND)





Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these<br>or any other conditions beyond those in *device reliability.*

#### **Electrical Characteristics**

(MAX691A, MAX800L:  $V_{CC}$  = +4.75V to +5.5V; MAX693A, MAX800M:  $V_{CC}$  = +4.5V to +5.5V;  $V_{VBATT}$  = 2.8V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.



## Microprocessor Supervisory Circuits

### **Electrical Characteristics (continued)**

(MAX691A, MAX800L:  $V_{CC}$  = +4.75V to +5.5V; MAX693A, MAX800M:  $V_{CC}$  = +4.5V to +5.5V;  $V_{VBATT}$  = 2.8V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.



### Microprocessor Supervisory Circuits

### **Electrical Characteristics (continued)**

(MAX691A, MAX800L:  $V_{CC}$  = +4.75V to +5.5V; MAX693A, MAX800M:  $V_{CC}$  = +4.5V to +5.5V;  $V_{VBATT}$  = 2.8V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.



**Note 1:** Either V<sub>CC</sub> or VBATT can go to 0V, if the other is greater than 2.0V.

**Note 2:** The supply current drawn by the MAX691A/MAX800L/MAX800M from the battery excluding I<sub>OUT</sub> typically goes to 10μA when (VBATT - 1V) < V<sub>CC</sub> < VBATT. In most applications, this is a brief period as V<sub>CC</sub> falls through this region. **Note 3:** "+" = battery-discharging current, "--" = battery-charging current.

**Note 4:** Although presented as typical values, the number of clock cycles for the reset and watchdog timeout periods are fixed and do not vary with process or temperature.

**Note 5:** RESET is an open-drain output and sinks current only.

Note 6: WDI is internally connected to a voltage divider between V<sub>OUT</sub> and GND. If unconnected, WDI is driven to 1.6V (typ), disabling the watchdog function.

**Note 7:** The chip-enable resistance is tested with V<sub>CC</sub> = +4.75V for the MAX691A/MAX800L and V<sub>CC</sub> = +4.5V for the MAX693A/ MAX800M.  $\overline{CE}$  IN =  $\overline{CE}$  OUT = V<sub>CC</sub>/2.

**Note 8:** The chip-enable propagation delay is measured from the 50% point at CE IN to the 50% point at CE OUT.

**Typical Operating Characteristics**

(TA = +25°C, unless otherwise noted.)



### Microprocessor Supervisory Circuits

### **Typical Operating Characteristics (continued)**

(TA = +25°C, unless otherwise noted.)



### Microprocessor Supervisory Circuits

### **Pin Description**



#### **Detailed Description**

#### **RESET and RESET Outputs**

The MAX691A/MAX693A/MAX800L/MAX800M's RESET and RESET outputs ensure that the μP (with reset inputs asserted either high or low) powers up in a known state, and prevents code-execution errors during power-down or brownout conditions.

The RESET output is active low, and typically sinks 3.2mA at 0.1V saturation voltage in its active state. When deasserted, RESET sources 1.6mA at typically  $V_{\text{OUT}}$  - 0.5V. RESET output is open drain, active high, and typically sinks 3.2mA with a saturation voltage of 0.1V. When no backup battery is used, RESET output is guaranteed to be valid down to V<sub>CC</sub> = 1V, and an external 10kΩ pulldown resistor on  $\overline{\text{RESET}}$  insures that it will be valid with  $V_{\text{CC}}$ down to GND (Figure 1). As  $V_{CC}$  goes below 1V, the gate drive to the RESET output switch reduces accordingly, increasing the  $R_{DS(ON)}$  and the saturation voltage. The 10kΩ pulldown resistor insures the parallel combination of switch plus resistor is around 10kΩ and the output saturation voltage is below 0.4V while sinking 40μA. When using a 10kΩ external pulldown resistor, the high state for RESET output with  $V_{CC}$  = 4.75V will be 4.5V typical.

# **MAX691A MAX693A** TO µP RESET 1kΩ RESET

*Figure 1. Adding an external pulldown resistor ensures RESET is valid with VCC down to GND.*

For battery voltages  $\geq$  2V connected to VBATT, RESET and  $\overline{\sf{RESET}}$  remain valid for  $V_{CC}$  from 0V to 5.5V.

RESET and  $\overline{\mathsf{RESET}}$  are asserted when  $\mathsf{V_{CC}}$  falls below the reset threshold (4.65V for the MAX691A/MAX800L, 4.4V for the MAX693A/MAX800M) and remain asserted for 200ms typ after  $V_{CC}$  rises above the reset threshold on power-up (Figure 5). The devices' batteryswitchover comparator does not affect reset assertion. However, both reset outputs are asserted in batterybackup mode since  $V_{\rm CC}$  must be below the reset threshold to enter this mode.

#### **Watchdog Function**

The watchdog monitors μP activity via the Watchdog Input (WDI). If the μP becomes inactive, RESET and RESET are asserted. To use the watchdog function, connect WDI to a bus line or μP I/O line. If WDI remains high or low for longer than the watchdog timeout period (1.6s nominal), WDO, RESET, and RESET are asserted (see RESET and RESET Outputs section, and the Watchdog Output discussion on this page).

#### **Watchdog Input**

A change of state (high to low, low to high, or a minimum 100ns pulse) at the WDI during the watchdog period resets the watchdog timer. The watchdog default timeout is 1.6s.

To disable the watchdog function, leave WDI floating. An internal resistor network (100kΩ equivalent impedance at WDI) biases WDI to approximately 1.6V. Internal comparators detect this level and disable the watchdog timer. When  $V_{CC}$  is below the reset threshold, the watchdog





*Figure 2. Watchdog Timeout Period and Reset Active Time*

function is disabled and WDI is disconnected from its internal resistor network, thus becoming high impedance.

#### **Watchdog Output**

The Watchdog Output (WDO) remains high if there is a transition or pulse at WDI during the watchdog timeout period. The watchdog function is disabled and WDO is a logic high when  $V_{CC}$  is below the reset threshold, battery-backup mode is enabled, or WDI is an open circuit. In watchdog mode, if no transition occurs at WDI during the watchdog timeout period, RESET and RESET are asserted for the reset timeout period (200ms typical). WDO goes low and remains low until the next transition at WDI (Figure 2). If WDI is held high or low indefinitely, RESET and RESET will generate 200ms pulses every 1.6s. WDO has a 2 x TTL output characteristic.

#### **Selecting an Alternative Watchdog and Reset Timeout Period**

The OSC SEL and OSC IN inputs control the watchdog and reset timeout periods. Floating OSC SEL and OSC IN or tying them both to  $V_{\Omega I}$  selects the nominal 1.6s watchdog timeout period and 200ms reset timeout period. Connecting OSC IN to GND and floating or connecting OSC SEL to  $V_{\text{OUT}}$  selects the 100ms normal watchdog timeout delay and 1.6s delay immediately after reset. The reset timeout delay remains 200ms (Figure 2). Select alternative timeout periods by connecting OSC SEL to GND and connecting a capacitor between OSC IN and GND, or by externally driving OSC IN (Table 1 and Figure 3). OSC IN is internally connected to a ±100nA (typ) current source that charges and discharges the timing capacitor to create the oscillator frequency, which sets the reset and watch-

### MAX691A/MAX693A/ MAX800L/MAX800M



### **Table 1. Reset Pulse Width and Watchdog Timeout Selections**



*Figure 3. Oscillator Circuits*

dog timeout periods (see Connecting a Timing Capacitor at OSC IN in the Applications Information section).

#### **Chip-Enable Signal Gating**

The MAX691A/MAX693A/MAX800L/MAX800M provide internal gating of chip-enable (CE) signals to prevent erroneous data from being written to CMOS RAM in the event of a power failure. During normal operation, the CE gate is enabled and passes all CE transitions. When reset is asserted, this path becomes disabled, preventing erroneous data from corrupting the CMOS RAM. All these parts use a series transmission gate from  $\overline{CE}$  IN to  $\overline{CE}$ OUT (Figure 4).

The 10ns max CE propagation delay from  $\overline{CE}$  IN to  $\overline{CE}$ OUT enables the parts to be used with most μPs.

#### **Chip-Enable Input**

The Chip-Enable Input  $(\overline{CE}$  IN) is high impedance (disabled mode) while RESET and RESET are asserted.

During a power-down sequence where  $V_{CC}$  falls below the reset threshold or a watchdog fault,  $\overline{CE}$  IN assumes a high-impedance state when the voltage at  $\overline{CE}$  IN goes

high or 15μs after reset is asserted, whichever occurs first (Figure 5).

During a power-up sequence, CE IN remains high impedance, regardless of  $\overline{CE}$  IN activity, until reset is deasserted following the reset timeout period.

In the high-impedance mode, the leakage currents into this terminal are ±1μA max over temperature. In the lowimpedance mode, the impedance of  $\overline{CE}$  IN appears as a 75Ω resistor in series with the load at  $\overline{CE}$  OUT.

The propagation delay through the CE transmission gate depends on both the source impedance of the drive to CE IN and the capacitive loading on the Chip-Enable Output (CE OUT) (see Chip-Enable Propagation Delay vs. CE OUT Load Capacitance in the *Typical Operating Characteristics*). The CE propagation delay is production tested from the 50% point of  $\overline{CE}$  IN to the 50% point of  $\overline{CE}$  OUT using a 50 $\Omega$  driver and 50pF of load capacitance (Figure 6). For minimum propagation delay, minimize the capacitive load at CE OUT, and use a low outputimpedance driver.

#### **Chip-Enable Output**

In the enabled mode, the impedance of  $\overline{CE}$  OUT is equivalent to 75 $\Omega$  in series with the source driving  $\overline{CE}$  IN. In the disabled mode, the  $75\Omega$  transmission gate is off and  $\overline{CE}$  OUT is actively pulled to  $V_{\text{OUT}}$ . This source turns off when the transmission gate is enabled.

#### **LOW LINE Output**

LOW LINE is the buffered output of the reset threshold comparator. LOW LINE typically sinks 3.2mA at 0.1V. For normal operation (V<sub>CC</sub> above the  $\overline{\text{LOW}}$  LINE threshold), LOW LINE is pulled to  $V_{\text{OUT}}$ .

#### **Power-Fail Comparator**

The power-fail comparator is an uncommitted comparator that has no effect on the other functions of the IC. Common uses include low-battery indication (Figure 7), and early power-fail warning (see *Typical Operating Circuit*).

## Microprocessor Supervisory Circuits



*Figure 4. MAX691A/MAX693A/MAX800L/MAX800M Block Diagram*



*Figure 5. Reset and Chip-Enable Timing*



*Figure 6. CE Propagation Delay Test Circuit Figure 7. Low-Battery Indicator*

#### **Table 2. Input and Output Status in Battery-Backup Mode**



*\*VCC must be below the reset threshold to enter battery-backup mode.*

### Microprocessor Supervisory Circuits



#### **Power-Fail Input**

Power-Fail Input (PFI) is the input to the power-fail comparator. It has a guaranteed input leakage of ±25nA max over temperature. The typical comparator delay is 25μs from  $V_{\text{IL}}$  to  $V_{\text{OL}}$  (power failing), and 60µs from  $V_{\text{IH}}$  to  $V<sub>OH</sub>$  (power being restored). If PFI is not used, connect it to ground.

#### **Power-Fail Output**

The Power-Fail Output (PFO) goes low when PFI goes below 1.25V. It typically sinks 3.2mA with a saturation voltage of 0.1V. With PFI above 1.25V, PFO is actively pulled to VOUT.

#### **Battery-Backup Mode**

Two conditions are required to switch to battery-backup mode: 1)  $V_{CC}$  must be below the reset threshold, and 2)  $V_{\text{CC}}$  must be below VBATT. Table 2 lists the status of the inputs and outputs in battery-backup mode.

#### **Battery-On Output**

The Battery-On (BATT ON) output indicates the status of the internal  $V_{CC}/b$ attery-switchover comparator, which controls the internal  $V_{CC}$  and VBATT switches. For V<sub>CC</sub> greater than VBATT (ignoring the small hysteresis effect), BATT ON typically sinks 3.2mA at 0.1V saturation voltage. In battery-backup mode, this terminal sources approximately 10µA from  $V_{\text{OUT}}$ . Use BATT ON to indicate battery-switchover status or to supply base drive to an external pass transistor for higher-current applications (see Typical Operating Circuit).

#### **Input Supply Voltage**

The Input Supply Voltage ( $V_{CC}$ ) should be a regulated 5V. V<sub>CC</sub> connects to V<sub>OUT</sub> via a parallel diode and a large PMOS switch. The switch carries the entire cur-rent

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load for currents less than 250mA. The parallel diode carries any current in excess of 250mA. Both the switch and the diode have impedances less than 1 $\Omega$  each. The maximum continuous current is 250mA, but power-on transients may reach a maximum of 1A.

#### **Battery-Backup Input**

The Battery-Backup Input (VBATT) is similar to the  $V_{CC}$ input except the PMOS switch and parallel diode are much smaller. Accordingly, the on-resistances of the diode and the switch are each approximately 10Ω. Continuous current should be limited to 25mA and peak currents (only during power-up) limited to 250mA. The reverse leakage of this input is less than 1μA over temperature and supply voltage (Figure 8).

#### **Output Supply Voltage**

The Output Supply Voltage ( $V_{\text{OUT}}$ ) pin is internally connected to the substrate of the IC and supplies current to the external system and internal circuitry. All opencircuit outputs will, for example, assume the  $V_{\text{OUT}}$  voltage in their high states rather than the  $V_{CC}$  voltage. At the maximum source current of 250mA,  $V_{OUT}$  will typically be 200mV below  $V_{CC}$ . Decouple this terminal with a 0.1 $\mu$ F capacitor.

#### **Applications Information**

The MAX691A/MAX693A/MAX800L/MAX800M are not short-circuit protected. Shorting  $V_{\text{OUT}}$  to ground, other than power-up transients such as charging a decoupling capacitor, destroys the device.

All open-circuit outputs swing between  $V_{\text{OUT}}$  and GND rather than  $V_{CC}$  and GND.



*Figure 8.* V<sub>CC</sub> and VBATT to VOUT Switch Figure 9. SuperCap or MaxCap on VBATT

If long leads connect to the chip inputs, insure that these leads are free from ringing and other conditions that would forward bias the chip's protection diodes.

There are three distinct modes of operation:

- 1) Normal operating mode with all circuitry powered up. Typical supply current from  $V_{CC}$  is 35 $\mu$ A while only leakage currents flow from the battery.
- 2) Battery-backup mode where  $V_{CC}$  is typically within 0.7V below VBATT. All circuitry is powered up and the supply current from the battery is typically less than 60μA.
- 3) Battery-backup mode where  $V_{CC}$  is less than VBATT by at least 0.7V. VBATT supply current is 1μA max.

#### **Using SuperCap or MaxCap with the MAX691A/MAX693A/MAX800L/MAX800M**

VBATT has the same operating voltage range as  $V_{CC}$ , and the battery switchover threshold voltages are typically ±30mV centered at VBATT, allowing use of a SuperCap and a simple charging circuit as a backup source (Figure 9).

If  $V_{CC}$  is above the reset threshold and VBATT is 0.5V above  $V_{CC}$ , current flows to  $V_{OUT}$  and  $V_{CC}$  from VBATT until the voltage at VBATT is less than 0.5V above  $V_{CC}$ . For example, with a SuperCap connected to VBATT and through a diode to  $V_{CC}$ , if  $V_{CC}$  quickly changes from 5.4V to 4.9V, the capacitor discharges through  $V_{\text{OUT}}$  and  $V_{\text{CC}}$ until VBATT reaches 5.1V typ. Leakage current through the SuperCap charging diode and the internal power diode eventually discharges the SuperCap to  $V_{CC}$ . Also, if  $V_{CC}$  and VBATT start from 0.1V above the reset thresh-





old and power is lost at  $V_{CC}$ , the SuperCap on VBATT discharges through  $V_{CC}$  until VBATT reaches the reset threshold; then the battery-backup mode is initiated and the current through  $V_{CC}$  goes to zero.

#### **Using Separate Power Supplies for VBATT and VCC**

If using separate power supplies for  $V_{CC}$  and VBATT, VBATT must be less than  $0.3V$  above  $V_{CC}$  when  $V_{CC}$  is above the reset threshold. As described in the previous section, if VBATT exceeds this limit and power is lost at  $V_{\text{CC}}$ , current flows continuously from VBATT to  $V_{\text{CC}}$  via the VBATT-to-V<sub>OUT</sub> diode and the V<sub>OUT</sub>-to-V<sub>CC</sub> switch until the circuit is broken (Figure 8).

#### **Alternate Chip-Enable Gating**

Using memory devices with both  $CE$  and  $\overline{CE}$  inputs allows the CE loop to be bypassed. To do this, connect CE IN to ground, pull up  $\overline{\text{CE}}$  OUT to  $V_{\text{OUT}}$ , and connect  $\overline{\text{CE}}$  OUT to the  $\overline{CE}$  input of each memory device (Figure 10). The CE input of each part then connects directly to the chip-select logic, which does not have to be gated.

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Figure10. Alternate CE Gating **Figure 11. Adding Hysteresis to the Power-Fail Comparator** 



*Figure 12. Monitoring a Negative Voltage*

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*Figure 13. Maximum Transient Duration without Causing a Reset Pulse vs. Reset Comparator Overdriv*

#### **Adding Hysteresis to the Power-Fail Comparator**

Hysteresis adds a noise margin to the power-fail comparator and prevents repeated triggering of  $\overline{PFO}$  when  $V_{IN}$  is near the power-fail comparator trip point. Figure 11 shows how to add hysteresis to the power-fail comparator. Select the ratio of R1 and R2 such that PFI sees 1.25V when  $V_{\text{IN}}$  falls to the desired trip point (V<sub>TRIP</sub>). Resistor R3 adds hysteresis. It will typically be an order of magnitude greater than R1 or R2. The current through R1 and R2 should be at least 1μA to ensure that the 25nA (max) PFI input current does not shift the trip point. R3 should be larger than 10kΩ to prevent it from loading down the PFO pin. Capacitor C1 adds noise rejection.

#### **Monitoring a Negative Voltage**

The power-fail comparator can be used to monitor a negative supply voltage using Figure 12's circuit. When the negative supply is valid,  $\overline{PFO}$  is low. When the negative supply voltage drops, PFO goes high. This circuit's

accuracy is affected by the PFI threshold tolerance, the  $V_{\text{CC}}$  voltage, and resistors R1 and R2.

#### **Backup-Battery Replacement**

The backup battery may be disconnected while  $V_{CC}$  is above the reset threshold. No precautions are necessary to avoid spurious reset pulses.

#### **Negative-Going VCC Transients**

While issuing resets to the μP during power-up, powerdown, and brownout conditions, these supervisors are relatively immune to short-duration, negative-going  $V_{CC}$ transients (glitches). It is usually undesirable to reset the μP when  $V_{CC}$  experiences only small glitches.

Figure 13 shows maximum transient duration vs. resetcomparator overdrive, for which reset pulses are **not**  generated. The graph was produced using negativegoing  $V_{\text{CC}}$  pulses, starting at 5V and ending below the reset threshold by the magnitude indicated (reset comparator overdrive). The graph shows the maximum pulse width a negative-going  $V_{CC}$  transient may typically have without causing a reset pulse to be issued. As the amplitude of the transient increases (i.e., goes farther below the reset threshold), the maximum allowable pulse width decreases. Typically, a  $V_{CC}$  transient that goes 100mV below the reset threshold and lasts for 40μs or less will not cause a reset pulse to be issued.

A 100nF bypass capacitor mounted close to the  $V_{CC}$  pin provides additional transient immunity.

#### **Connecting a Timing Capacitor at OSC IN**

When OSC SEL is connected to ground, OSC IN disconnects from its internal 10μA (typ) pullup and is internally connected to a ±100nA current source. When a capacitor is connected from OSC IN to ground (to select alternative reset and watchdog timeout periods), the current source charges and discharges the timing capacitor to create the oscillator that controls the reset and watchdog timeout period. To prevent timing errors or oscillator startup prob-

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lems, minimize external current leakage sources at this pin, and locate the capacitor as close to OSC IN as possible. The sum of PC-board leakage plus OSC capacitor leakage must be small compared to ±100nA.

#### **Maximum V<sub>CC</sub> Fall Time**

The  $V_{CC}$  fall time is limited by the propagation delay of the battery switchover comparator and should not exceed 0.03V/μs. A standard rule of thumb for filter capacitance on most regulators is on the order of 100μF per amp of current. When the power supply is shut off or the main battery is disconnected, the associated initial  $V_{CC}$  fall rate is just the inverse or  $1A/100\mu$ F = 0.01V/ $\mu$ s. The V<sub>CC</sub> fall rate decreases with time as  $V_{CC}$  falls exponentially, which more than satisfies the maximum fall-time requirement.

#### **Watchdog Software Considerations**

A way to help the watchdog timer keep a closer watch on software execution involves setting and resetting the watchdog input at different points in the program, rather than "pulsing" the watchdog input high-low-high or lowhigh-low. This technique avoids a "stuck" loop where the watchdog timer continues to be reset within the loop, keeping the watchdog from timing out. Figure 14 shows an example flow diagram where the I/O driving the watchdog input is set high at the beginning of the program, set low at the beginning of every subroutine or loop, then set high again when the program returns to the beginning. If the program should "hang" in any subroutine, the I/O is continually set low and the watchdog timer is allowed to time out, causing a reset or interrupt to be issued.



*Figure 14. Watchdog Flow Diagram*

### MAX691A/MAX693A/ MAX800L/MAX800M



#### **Chip Topography** Criation (continued) Chip Topography

*\*Dice are specified at TA = +25°C, DC parameters only.*

*\*\*Contact factory for availability and processing to MIL-STD-883B.*

*Devices in PDIP, SO and TSSOP packages are available in both leaded and lead-free packaging. Specify lead free by adding the + symbol at the end of the part number when ordering. Lead free not available for CERDIP package.*



#### **Package Information**

For the latest package outline information and land patterns (footprints), go to **[www.maximintegrated.com/packages](http://www.maximintegrated.com/packages)**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.



### Microprocessor Supervisory Circuits

### **Revision History**



For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at www.maximintegrated.com.

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