

ACS711

Hall-Effect Linear Current Sensor with Overcurrent Fault Output for <100 V Isolation Applications

FEATURES AND BENEFITS

- No external sense resistor required; single package solution
- Reduced power loss: \Box 0.6 m Ω internal conductor resistance on EX package \Box 1.2 m Ω internal conductor resistance on LC package
- Economical low- and high-side current sensing
- Output voltage proportional to AC or DC currents
- \pm 12.5 A and \pm 25 A full-scale sensing ranges on LC package
- \pm 15.5 A and \pm 31 A full-scale sensing ranges on EX package
- Overcurrent \overline{FAULT} trips and latches at 100% of full-scale current
- Low-noise analog signal path
- 100 kHz bandwidth
- Small footprint, low-profile SOIC8 and QFN packages
- 3 to 5.5 V single supply operation
- Integrated electrostatic shield for output stability
- Factory-trimmed for accuracy
- Extremely stable output offset voltage
- Zero magnetic hysteresis
- Ratiometric output from supply voltage

PACKAGES:

8-pin SOICN with internally fused path (LC package)

Not to scale

12-contact QFN 3 mm \times 3 mm \times 0.75 mm (EX package)

DESCRIPTION

The Allegro™ ACS711 provides economical and precise solutions for AC or DC current sensing in <100 V audio, communications systems, and white goods. The device package allows for easy implementation by the customer. Typical applications include circuit protection, current monitoring, and motor and inverter control.

The device consists of a linear Hall sensor circuit with a copper conduction path located near the surface of the die. Applied current flowing through this copper conduction path generates a magnetic field which is sensed by the integrated Hall IC and converted into a proportional voltage. Device accuracy is optimized through the close proximity of the magnetic signal to the Hall transducer.

The output of the device has a positive slope proportional to the current flow from IP+ to IP– (pins 1 and 2, to pins 3 and 4). The internal resistance of this conductive path is $0.6 \text{ m}\Omega$ for the EX package, and $1.2 \text{ m}\Omega$ for the LC package, providing a non-intrusive measurement interface that saves power in applications that require energy efficiency.

The ACS711 is optimized for low-side current sensing applications, although the terminals of the conductive path are electrically isolated from the sensor IC leads, providing sufficient internal creepage and clearance dimensions for a low AC or DC working voltage applications. The thickness of the copper conductor allows survival of the device at up to

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Typical Application

Application 1. The ACS711 outputs an analog signal, V_{IOUT} , that varies linearly with the bi-directional AC or DC primary current, I_P , within the range specified. The FAULT pin trips when I_P reaches $\pm 100\%$ of its fullscale current.

DESCRIPTION (CONTINUED)

5× overcurrent conditions.

The ACS711 is provided in small, surface-mount packages: SOIC8 and QFN12. The leadframe is plated with 100% matte tin, which is compatible with standard lead (Pb) free printed circuit board assembly processes. Internally, the device is Pb-free, except for flip-chip high-temperature Pb-based solder balls, currently exempt from RoHS. The device is fully calibrated prior to shipment from the factory.

SELECTION GUIDE

[1] Contact Allegro for additional packing options.

^[2] Sensitivity measured with V_{CC} = 3.3 V.

[3] QFN package not qualified for automotive applications.

[4] Variants ACS711EEXLT-15AB-T and ACS711EEXLT-31AB-T are Pre-End-of-Life. These device variants are approaching end of life. Within a minimum of 6 months, these device variants will enter their final, Last Time Buy, order phase. Date of status change: June 5, 2017. Suggested replacements include ACS711KEXLT-15AB-T and ACS711KEXLT-31AB-T, respectively.

ABSOLUTE MAXIMUM RATINGS

Functional Block Diagram

PINOUT DIAGRAMS

EX Package LC Package

TERMINAL LIST TABLE

COMMON OPERATING CHARACTERISTICS: Valid across the full range of T_A for the LC package and at $T_A = 25^\circ$ C for the EX package,

 $^{[1]}$ Devices are programmed for maximum accuracy at 3.3 V V_{CC} levels. The device contains ratiometry circuits that accurately alter the 0 A Output Voltage and Sensitivity level of the device in proportion to the applied V_{CC} level. However, as a result of minor nonlinearities in the ratiometry circuit additional output error will result when V_{CC} varies from the 3.3 V V_{CC} level. Customers that plan to operate the device from a 5 V regulated supply should contact their local Allegro sales representative regarding expected device accuracy levels under these bias conditions.

^[2] Calculated using the formula BW_I = 0.35 / t_r.

[3] After the $\overline{\text{FAULT}}$ pin is latched low, the only way to reset it is through a power-off and power-on cycle on the VCC pin. For fault reset, V_{CC} must stay below V_{CCFR} for a period greater than t_{CCFR} before settling to the normal operation voltage (3 to 5.5 V).

x12AB PERFORMANCE CHARACTERISTICS for LC package and E Temperature Range [1]

 T_A = 25°C and V_{CC} = 3.3 V, unless otherwise specified

[1] See Characteristic Performance Data for parameter distributions over temperature.

[2] ±3 sigma noise voltage.

[3] Percentage of I_P , with $I_P = \pm 12.5$ A.

x12AB PERFORMANCE CHARACTERISTICS for LC package and K Temperature Range [1]

 T_A = 25°C and V_{CC} = 3.3 V, unless otherwise specified

[1] See Characteristic Performance Data for parameter distributions over temperature.

[2] ±3 sigma noise voltage.

[3] Percentage of I_P , with $I_P = \pm 12.5$ A.

x15AB PERFORMANCE CHARACTERISTICS [1]

 T_A = 25°C and V_{CC} = 3.3 V, unless otherwise specified

[1] See Characteristic Performance Data for parameter distributions across the full temperature range.

[2] ±3 sigma noise voltage.

[3] Percentage of I_P , with $I_P = \pm 15.5$ A.

x25AB PERFORMANCE CHARACTERISTICS for for LC package and E Temperature Range [1]

 T_A = 25°C and V_{CC} = 3.3 V, unless otherwise specified

[1] See Characteristic Performance Data for parameter distributions over temperature.

[2] ±3 sigma noise voltage.

[3] Percentage of I_P , with $I_P = \pm 25$ A.

x25AB PERFORMANCE CHARACTERISTICS for LC package and K Temperature Range [1]

 T_A = 25°C and V_{CC} = 3.3 V, unless otherwise specified

[1] See Characteristic Performance Data for parameter distributions over temperature.

[2] ±3 sigma noise voltage.

[3] Percentage of I_P , with $I_P = \pm 25$ A.

x31AB PERFORMANCE CHARACTERISTICS [1]

 T_A = 25°C and V_{CC} = 3.3 V, unless otherwise specified

[1] See Characteristic Performance Data for parameter distributions across the full temperature range.

[2] ±3 sigma noise voltage.

[3] Percentage of I_P , with $I_P = \pm 31$ A.

THERMAL CHARACTERISTICS

[1] Additional thermal information available on the Allegro website.

[2] The Allegro evaluation board has 1500 mm2 of 2 oz. copper on each side, connected to pins 1 and 2, and to pins 3 and 4, with thermal vias connecting the layers. Performance values include the power consumed by the PCB. Further details on the board are available from the Frequently Asked Questions document on our website.

-60 -40 -20 0 20 40 60 -60 -40 -20 0 20 40 60 80 100 120 140 VOE (mV) T^A (°C)

QVO Error versus Ambient Temperature

Total Error versus Ambient Temperature

Characteristic Performance Data

Data taken using the ACS711KEX-31AB, V_{CC} = 3.3 V

Sensitivity versus Ambient Temperature

Symmetry versus Ambient Temperature

Nonlinearity versus Ambient Temperature

Characteristic Performance Data

Data taken using the ACS711KLC-12A, V_{CC} = 3.3 V

Accuracy Data

Sensitivity versus Ambient Temperature

Nonlinearity versus Ambient Temperature

Symmetry versus Ambient Temperature

Total Output Error versus Ambient Temperature Fault Operating Point versus Ambient Temperature

Characteristic Performance Data

Data taken using the ACS711KLC-25A, V_{CC} = 3.3 V

Accuracy Data

Sensitivity versus Ambient Temperature

Nonlinearity versus Ambient Temperature

Symmetry versus Ambient Temperature

Characteristic Performance Data

Data taken using the ACS711KLC-25A

Timing Data

DEFINITIONS OF ACCURACY CHARACTERISTICS

Sensitivity (Sens). The change in sensor output in response to a 1 A change through the primary conductor. The sensitivity is the product of the magnetic circuit sensitivity (G/A) and the linear IC amplifier gain (mV/G). The linear IC amplifier gain is programmed at the factory to optimize the sensitivity (mV/A) for the full-scale current of the device.

Noise (V_{NOISE} **). The product of the linear IC amplifier gain (mV)** and the noise floor for the Allegro Hall effect linear IC. The noise floor is derived from the thermal and shot noise observed in Hall elements. Dividing the noise (mV) by the sensitivity (mV/A) provides the smallest current that the device is able to resolve.

Linearity (E_{LIN} **). The degree to which the voltage output from** the sensor varies in direct proportion to the primary current through its full-scale amplitude. Nonlinearity in the output can be attributed to the saturation of the flux concentrator approaching the full-scale current. The following equation is used to derive the linearity:

$$
100\left\{1-\left[\frac{\Delta \text{ gain} \times \% \text{ sat } (V_{\text{IOUT_full-scale amperes}} - V_{\text{IOUT(Q)}})}{2 (V_{\text{IOUT_half-scale amperes}} - V_{\text{IOUT(Q)}})}\right]\right\}
$$

where $V_{\text{IOUT_full-scale amperes}}$ = the output voltage (V) when the sensed current approximates full-scale $\pm I_p$.

Symmetry (E_{SYM} **). The degree to which the absolute voltage** output from the sensor varies in proportion to either a positive or negative full-scale primary current. The following formula is used to derive symmetry:

$$
100 \left(\frac{V_{\text{IOUT_}} + \text{full-scale amperes} - V_{\text{IOUT(Q)}}}{V_{\text{IOUT/O}} - V_{\text{IOUT}} - \text{full-scale amperes}} \right)
$$

Quiescent output voltage ($V_{\text{IOUT(O)}}$ **). The output of the sensor** when the primary current is zero. For a unipolar supply voltage, it nominally remains at $V_{CC}/2$. Thus, $V_{CC} = 3.3$ V translates into $V_{\text{IOUT(O)}} = 1.65$ V. Variation in $V_{\text{IOUT(Q)}}$ can be attributed to the resolution of the Allegro linear IC quiescent voltage trim and thermal drift.

Electrical offset voltage (V_{OE} **). The deviation of the device out**put from its ideal quiescent value of $V_{CC}/2$ due to nonmagnetic causes. To convert this voltage to amperes, divide by the device sensitivity, Sens.

Accuracy (E_{TOT} **). The accuracy represents the maximum devia**tion of the actual output from its ideal value. This is also known as the total ouput error. The accuracy is illustrated graphically in the output voltage versus current chart below.

Ratiometry. The ratiometric feature means that its 0 A output, $V_{\text{IOUT(0)}}$, (nominally equal to $V_{\text{CC}}/2$) and sensitivity, Sens, are proportional to its supply voltage, V_{CC} . The following formula is used to derive the ratiometric change in 0 A output voltage, $\Delta V_{\text{IOUT}(\text{O)RAT}}(\%)$:

The ratiometric change in sensitivity, Δ Sens $_{RAT}$ (%), is defined as:

$$
100 \left(\frac{V_{\text{IOUT(Q)VCC}}/V_{\text{IOUT(Q)3.3V}}}{V_{\text{CC}}/3.3 \text{ V}} \right)
$$

$$
100 \left(\frac{Sens_{\rm VCC} / Sens_{3.3V}}{V_{\rm CC} / 3.3 \text{ V}} \right)
$$

Output Voltage versus Sensed Current Accuracy at 0 A and at Full-Scale Current

DEFINITIONS OF DYNAMIC RESPONSE CHARACTERISTICS

Power-On Time (t_{PO}) **. When the supply is ramped to its operat**ing voltage, the device requires a finite time to power its internal components before responding to an input magnetic field. Power-On Time, t_{PO} , is defined as the time it takes for the output voltage to settle within $\pm 10\%$ of its steady state value under an applied magnetic field, after the power supply has reached its minimum specified operating voltage, $V_{CC}(min)$, as shown in the chart at right.

Rise time (t^r). The time interval between a) when the sensor reaches 10% of its full scale value, and b) when it reaches 90% of its full scale value. The rise time to a step response is used to derive the bandwidth of the current sensor, in which $f(-3 dB) =$ $0.35/t_r$. Both t_r and $t_{RESPONSE}$ are detrimentally affected by eddy current losses observed in the conductive IC ground plane.

APPLICATION INFORMATION

Layout

To optimize thermal and electrical performance, the following features should be included in the printed circuit board:

- The primary leads should be connected to as much copper area as is available.
- The copper should be 2 oz. or heavier.
- Additional layers of the board should be used for conducting the primary current if possible, and should be connected using the arrangement of vias shown below.
- The two solder pads at the ends of the exposed pad loop should be placed directly on the copper trace that conducts the primary current.
- When using vias under exposed pads, such as with the EX package, using plugged vias prevents wicking of the solder from the pad into the via during reflow. Whether or not to use plugged vias should be evaluated in the application.

Suggested Layout. EX package shown.

Package LC, 8-pin SOIC

requirements and PCB layout tolerances

Package EX, 12-Contact QFN With Fused Sensed Current Loop

 \sqrt{D} Coplanarity includes exposed current path and terminals

E Branding scale and appearance at supplier discretion

Revision History

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