

MC9S08LH64 Rev. 6.1, 08/2012

MC9S08LH64 Series Data Sheet

by: Automotive and Industrial Solutions Group

This is the MC9S08LH64 Series Data Sheet set consisting of the following files:

- MC9S08LH64 Data Sheet Addendum, Rev 1
- MC9S08LH64 Series Data Sheet, Rev 6





Freescale Semiconductor Data Sheet Addendum

MC9S08LH64AD Rev. 1, 08/2012

MC9S08LH64 Data Sheet Addendum

by: Automotive and Industrial Solutions Group

This document describes corrections to the *MC9S08LH64 Series Data Sheet*, order number MC9S08LH64. For convenience, the addenda items are grouped by revision. Please check our website at http://www.freescale.com for the latest updates.

The current available version of the MC9S08LH64 Series Data Sheet is Revision 6.

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Addendum for Revision 6

1 Addendum for Revision 6

Table 1. MC9S08LH64 Data Sheet Rev 6 Addendum

Location	Description
Section 3.7, "Supply Current Characteristics"/Table 9/Page 23	In the table, for numbers 3 and 4, change "LPS" to "LPR".
25	

2 Revision History

Table 2 provides a revision history for this document.

Table 2. Revision History Table

Rev. Number	Substantive Changes	Date of Release
1.0	Initial release. Correct errors in the following sections: • Section 3.7, "Supply Current Characteristics"	07/2012

MC9S08LH64 Data Sheet Addendum, Rev. 1



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MC9S08LH64AD Rev. 1 08/2012



Freescale Semiconductor Data Sheet: Advanced Information

An Energy Efficient Solution by Freescale

MC9S08LH64 Series

Covers: MC9S08LH64 and MC9S08LH36

- 8-bit HCS08 Central Processor Unit (CPU)
 - Up to 40 MHz CPU at 3.6 V to 2.1 V across temperature range of –40 °C to 85 °C
 - Up to 20 MHz at 2.1 V to 1.8 V across temperature range of -40 °C to 85 °C
 - HC08 instruction set with added BGND instruction
 - Support for up to 32 interrupt/reset sources
- · On-Chip Memory
 - Dual array flash read/program/erase over full operating voltage and temperature
 - Random-access memory (RAM)
 - Security circuitry to prevent unauthorized access to RAM and flash contents
- · Power-Saving Modes
 - Two low-power stop modes
 - Reduced-power wait mode
 - Low-power run and wait modes allow peripherals to run while voltage regulator is in standby
 - Peripheral clock gating register can disable clocks to unused modules, thereby reducing currents
 - Very low-power external oscillator that can be used in stop2 or stop3 modes to provide accurate clock source to time-of-day (TOD) module
 - 6 μs typical wakeup time from stop3 mode
- Clock Source Options
 - Oscillator (XOSC) Loop-control Pierce oscillator; crystal or ceramic resonator range of 31.25 kHz to 38.4 kHz or 1 MHz to 16 MHz
 - Internal Clock Source (ICS) Internal clock source module containing a frequency-locked-loop (FLL) controlled by internal or external reference; precision trimming of internal reference allows 0.2% resolution and 2% deviation over temperature and voltage; supporting bus frequencies from 1 MHz to 20 MHz
- · System Protection
 - Watchdog computer operating properly (COP) reset with option to run from dedicated 1 kHz internal clock source or bus clock
 - Low-voltage warning with interrupt
 - Low-voltage detection with reset or interrupt
 - Illegal opcode detection with reset; illegal address detection with reset
 - Flash block protection
- · Development Support
 - Single-wire background debug interface

Document Number: MC9S08LH64

Rev. 6, 4/2012





64-LQFP Case 840F



80-LQFP Case 917A

- Breakpoint capability to allow single breakpoint setting during in-circuit debugging (plus two more breakpoints in on-chip debug module)
- On-chip in-circuit emulator (ICE) debug module containing three comparators and nine trigger modes

Peripherals

- LCD Up to 8×36 or 4×40 LCD driver with internal charge pump and option to provide an internally-regulated LCD reference that can be trimmed for contrast control
- ADC —16-bit resolution; with a dedicated differential ADC input, and 8 single-ended ADC inputs; up to 2.5 μs conversion time; hardware averaging; calibration registers, automatic compare function; temperature sensor; operation in stop3; fully functional from 3.6 V to 1.8 V
- IIC Inter-integrated circuit bus module to operate at up to 100 kbps with maximum bus loading; multi-master operation; programmable slave address; interrupt-driven byte-by-byte data transfer; broadcast mode; 10-bit addressing
- ACMP Analog comparator with selectable interrupt on rising, falling, or either edge of comparator output; compare option to fixed internal reference voltage; outputs can be optionally routed to TPM module; operation in stop3
- SCIx Two full-duplex non-return to zero (NRZ) modules (SCI1 and SCI2); LIN master extended break generation; LIN slave extended break detection; wakeup on active edge
- SPI Full-duplex or single-wire bidirectional;
 double-buffered transmit and receive; master or slave mode;
 MSB-first or LSB-first shifting
- TPMx Two 2-channel (TPM1 and TPM2); selectable input capture, output compare, or buffered edge- or center-aligned PWM on each channel
- TOD (Time-of-day) 8-bit, quarter second counter with match register; external clock source for precise time base, time-of-day, calendar, or task scheduling functions
- VREFx Trimmable via an 8-bit register in 0.5 mV steps; automatically loaded with room temperature value upon reset; can be enabled to operate in stop3 mode; trim register is not available in stop modes
- Input/Output
 - Dedicated accurate voltage reference output pin, 1.15 V output (VREFOx); trimmable with 0.5 mV resolution
 - Up to 39 GPIOs, two output-only pins
 - Hysteresis and configurable pullup device on all input pins; configurable slew rate and drive strength on all output pins
- Package Options
 - 14mm × 14mm 80-pin LQFP, 10 mm × 10 mm 64-pin LQFP





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Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

http://www.freescale.com/

The following revision history table summarizes changes contained in this document.

Rev	Date	Description of Changes
3	1/2009	Refreshed the draft to include the new VREF module and the latest revisions.
4	4/8/2010	Completed RIDD in the Table 9; updated EREFSTEN in the Table 10; changed all V_{DDAD} to V_{DDA} , V_{SSAD} to V_{SSA} ; updated the min. of V_{REFH} ; Added 64-pin LQFP package information for LH36 MCU; Updated V Room Temp in the Table 20. Updated S2I $_{DD}$ at V_{DD} = 2 and Temp at –40 to 25 °C Added 64-pin LQFP package for LH36. Updated ADC data in the 3.12/33
5	6/20/2011	Added t _{extrst} in the Table 13; changed the ERREFSTEN to EREFSTEN; updated the VREFOX to 1.15 V. Added LCD specification in the Table 10.
6	4/11/2012	Updated IIInl in the Table 8.

Related Documentation

Find the most current versions of all documents at: http://www.freescale.com

Reference Manual —MC9S08LH64RM

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.





1 Devices in the MC9S08LH64 Series

Table 1 summarizes the feature set available in the MC9S08LH64 Series of MCUs.

Table 1. MC9S08LH64 Series Features by MCU and Package

Feature	MC9S0	08LH64	MC9S08LH36		
Package	80-pin LQFP	64-pin LQFP	80-pin LQFP	64-pin LQFP	
FLASH		KB 32,768 Arrays)		KB 2,288 Arrays)	
RAM	40	00	40	00	
ACMP	ує	es	ye	es	
ADC Single-ended Channels	8-ch	8-ch	8-ch	8-ch	
ADC Differential Channels ¹	1	0	1	0	
IIC	ує	es	yes		
IRQ	ує	es	ye	es	
KBI	3	3		3	
SCI1	ує	es	ye	es	
SCI2	ує	es	ye	es	
SPI	ує	es	ye	es	
TPM1	2-	ch	2-	ch	
TPM2	2-	2-ch		ch	
TOD	ує	es	yes		
LCD	8×36 4×40	8×24 4×28	8×36 4×40	8×24 4×28	
VREFO1	yes	no	yes	no	
VREFO2	no	yes	no	yes	
I/O pins ²	39	37	39	37	

¹ Each differential channel consists of two pins (DADPx and DADMx).

The block diagram in Figure 1 shows the structure of the MC9S08LH64 Series MCU.

 $^{^{2}\,}$ The 39 I/O pins include two output-only pins and 18 LCD GPIO.



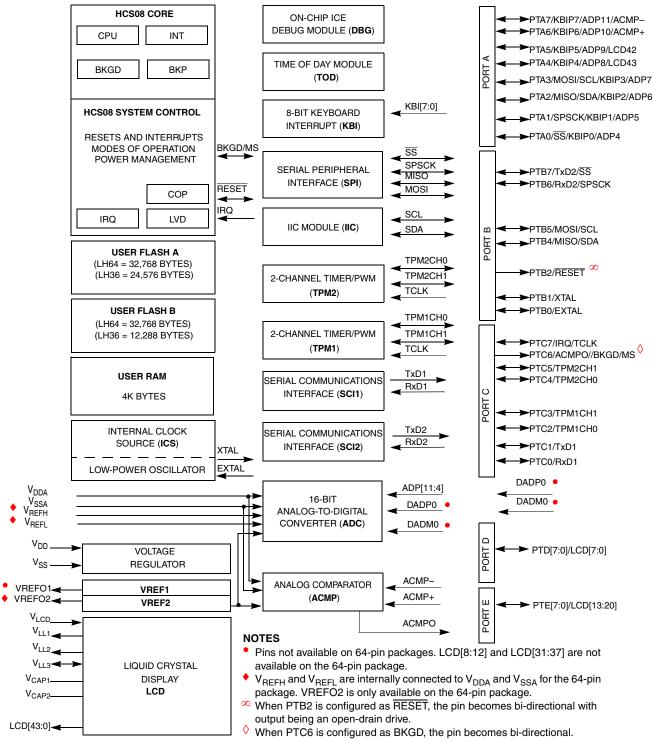


Figure 1. MC9S08LH64 Series Block Diagram

2 Pin Assignments

This section shows the pin assignments for the MC9S08LH64 Series devices.



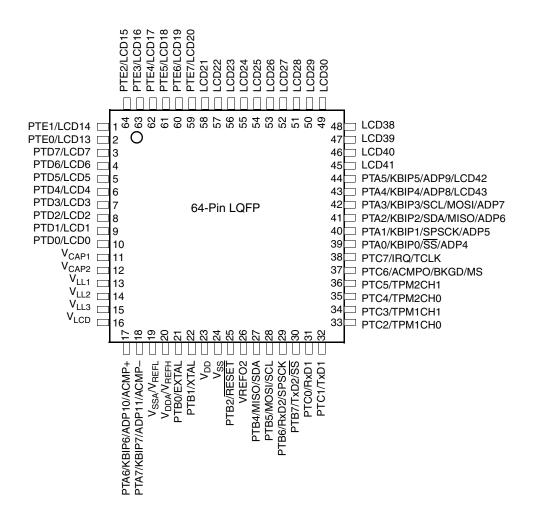


Figure 2. 64-Pin LQFP

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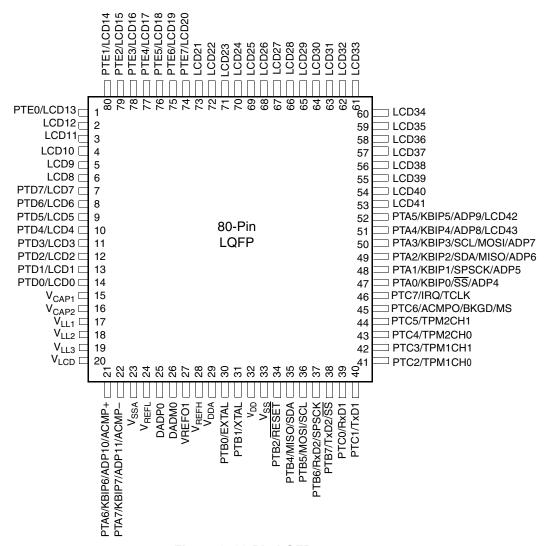


Figure 3. 80-Pin LQFP

Table 2. Pin Availability by Package Pin-Count

		< Lowest Priority > Highest							
80	64	Port Pin	Alt 1	Alt 2	Alt3	Alt4			
1	2	PTE0	LCD13						
2		LCD12							
3		LCD11							
4		LCD10							
5		LCD9							
6		LCD8							
7	3	PTD7	LCD7						
8	4	PTD6	LCD6						

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Table 2. Pin Availability by Package Pin-Count (continued)

			< Low	est Priority>	Highest	
80	64	Port Pin	Alt 1	Alt 2	Alt3	Alt4
9	5	PTD5	LCD5			
10	6	PTD4	LCD4			
11	7	PTD3	LCD3			
12	8	PTD2	LCD2			
13	9	PTD1	LCD1			
14	10	PTD0	LCD0			
15	11	V _{CAP1}				
16	12	V _{CAP2}				
17	13	V _{LL1}				
18	14	V_{LL2}				
19	15	V _{LL3}				
20	16	V_{LCD}				
21	17	PTA6	KBIP6	ADP10	ACMP+	
22	18	PTA7	KBIP7	ADP11	ACMP-	
23	19	V_{SSA}				
24	19	V_{REFL}				
25		DADP0				
26		DADM0				
27		VREFO1				
28	20	V _{REFH}				
29	20	V_{DDA}				
30	21	PTB0		EXTAL		
31	22	PTB1		XTAL		
32	23	V_{DD}				
33	24	V_{SS}				
34	25	PTB2	RESET			
	26	VREFO2				
35	27	PTB4	MISO	SDA		
36	28	PTB5	MOSI	SCL		
37	29	PTB6	RxD2	SPSCK		
38	30	PTB7	TxD2	SS		
39	31	PTC0	RxD1			
40	32	PTC1	TxD1			
41	33	PTC2	TPM1CH0			
42	34	PTC3	TPM1CH1			
43	35	PTC4	TPM2CH0			
44	36	PTC5	TPM2CH1			
45	37	PTC6	ACMPO	BKGD	MS	



Table 2. Pin Availability by Package Pin-Count (continued)

			< Lov	vest Priority>	Highest	
80	64	Port Pin	Alt 1	Alt 2	Alt3	Alt4
46	38	PTC7	IRQ	TCLK		
47	39	PTA0	KBIP0		SS	ADP4
48	40	PTA1	KBIP1		SPSCK	ADP5
49	41	PTA2	KBIP2	SDA	MISO	ADP6
50	42	PTA3	KBIP3	SCL	MOSI	ADP7
51	43	PTA4	KBIP4	ADP8	LCD43	
52	44	PTA5	KBIP5	ADP9	LCD42	
53	45	LCD41				
54	46	LCD40				
55	47	LCD39				
56	48	LCD38				
57		LCD37				
58		LCD36				
59		LCD35				
60		LCD34				
61		LCD33				
62		LCD32				
63		LCD31				
64	49	LCD30				
65	50	LCD29				
66	51	LCD28				
67	52	LCD27				
68	53	LCD26				
69	54	LCD25				
70	55	LCD24				
71	56	LCD23				
72	57	LCD22				
73	58	LCD21				
74	59	PTE7	LCD20			
75	60	PTE6	LCD19			
76	61	PTE5	LCD18			
77	62	PTE4	LCD17			
78	63	PTE3	LCD16			
79	64	PTE2	LCD15			
80	1	PTE1	LCD14			



3 Electrical Characteristics

3.1 Introduction

This section contains electrical and timing specifications for the MC9S08LH64 Series of microcontrollers available at the time of publication.

3.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding, the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

Table 3. Parameter Classifications

Р	Those parameters are guaranteed during production testing on each individual device.
С	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
Т	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
D	Those parameters are derived mainly from simulations.

NOTE

The classification is shown in the column labeled "C" in the parameter tables where appropriate.

3.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in Table 4 may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high-static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either V_{SS} or V_{DD}) or the programmable pullup resistor associated with the pin is enabled.

Thermal Characteristics

Table 4. Absolute Maximum Ratings

Rating	Symbol	Value	Unit
Supply voltage	V_{DD}	-0.3 to +3.8	٧
Maximum current into V _{DD}	I _{DD}	120	mA
Digital input voltage	V _{In}	-0.3 to $V_{DD} + 0.3$	V
Instantaneous maximum current Single pin limit (applies to all port pins) ^{1, 2, 3}	I _D	± 25	mA
Storage temperature range	T _{stg}	-55 to 150	°C

Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V_{DD}) and negative (V_{SS}) clamp voltages, then use the larger of the two resistance values.

3.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

Table 5. Thermal Characteristics

Rating	Symbol	Value	Unit	
Operating temperature range (packaged)	T _A	T _L to T _H -40 to 85	°C	
Maximum junction temperature	T_J	95	°C	
Thermal resistance Single-layer board				
80-pin LQFP	Δ	55	°C/W	
64-pin LQFP	$\theta_{\sf JA}$	73	O/VV	
Thermal resistance Four-layer board				
80-pin LQFP	0	42	°C/W	
64-pin LQFP	$\theta_{\sf JA}$	54	C/VV	

The average chip-junction temperature (T_I) in °C can be obtained from:

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 $^{^2}$ All functional non-supply pins, except for PTB2 are internally clamped to $\rm V_{SS}$ and $\rm V_{DD}$

Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current (V_{In} > V_{DD}) is greater than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).



$$T_{J} = T_{A} + (P_{D} \times \theta_{JA})$$
 Eqn. 1

where:

 $T_A = Ambient temperature, °C$

 θ_{JA} = Package thermal resistance, junction-to-ambient, °C/W

 $P_D = P_{int} + P_{I/O}$

 $P_{int} = I_{DD} \times V_{DD}$, Watts — chip internal power

 $P_{I/O}$ = Power dissipation on input and output pins — user determined

For most applications, $P_{I/O} \ll P_{int}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$$P_D = K \div (T_{.1} + 273 \,^{\circ}C)$$
 Eqn. 2

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_\Delta + 273 \, ^{\circ}C) + \theta_{A\Delta} \times (P_D)^2$$
 Eqn. 3

where K is a constant pertaining to the particular part. K can be determined from Equation 3 by measuring P_D (at equilibrium) for a known T_A . Using this value of K, the values of P_D and T_J can be obtained by solving Equation 1 and Equation 2 iteratively for any value of T_A .

3.5 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions should be taken to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits. During the device qualification, ESD stresses were performed for the human body model (HBM), the machine model (MM) and the charge device model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless instructed otherwise in the device specification.

Table 6. ESD and Latch-up Test Conditions

Model Description Symbol Va

Model	Description	Symbol	Value	Unit
	Series resistance	R1	1500	Ω
Human Body Model	Storage capacitance	С	100	pF
	Number of pulses per pin	_	3	
Charge	Series resistance	R1	0	Ω
Device	Storage capacitance	С	200	pF
Model	Number of pulses per pin	_	3	

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DC Characteristics

Table 6. ESD and Latch-up Test Conditions (continued)

Latch-up	Minimum input voltage limit	-2.5	V
Laterrup	Maximum input voltage limit	7.5	V

Table 7. ESD and Latch-Up Protection Characteristics

No.	Rating ¹	Symbol	Min	Max	Unit
1	Human body model (HBM)	V_{HBM}	±2000	_	V
2	Charge device model (CDM) V _{CDM}		±500	_	V
3	Latch-up current at T _A = 85 °C	I _{LAT}	±100	_	mA

Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

3.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 8. DC Characteristics

Num	С	C	Characteristic	Symbol	Condition	Min	Typ ¹	Max	Unit
1		Operating Vol	tage			1.8		3.6	V
	С	Outra de la imb	PTA[0:3], PTA[6:7], PTB[0:7], PTC[0:7] ² , low-drive strength		V_{DD} >1.8 V I_{Load} = -0.6 mA	V _{DD} – 0.5	_	_	
2	Р	1 1/[0.0],	PTA[0:3], PTA[6:7], PTB[0:7], PTC[0:7] ² ,		$V_{DD} > 2.7 \text{ V}$ $I_{Load} = -10 \text{ mA}$	V _{DD} – 0.5	_	_	V
	С		high-drive strength		$V_{DD} > 1.8 V$ $I_{Load} = -3 \text{ mA}$	V _{DD} – 0.5		1	
	С		PTA[4:5], PTD[0:7],		$V_{DD} > 1.8 \text{ V}$ $I_{Load} = -0.5 \text{ mA}$	V _{DD} - 0.5		-	
3	Р	voltage			$V_{DD} > 2.7 \text{ V}$ $I_{Load} = -2.5 \text{ mA}$	V _{DD} – 0.5	_	_	V
	С	high-drive strength		$V_{DD} > 1.8 \text{ V}$ $I_{Load} = -1 \text{ mA}$	V _{DD} – 0.5		_		
4	D	Output high current	Max total I _{OH} for all ports	I _{OHT}			l	100	mA
	С	0.11	PTA[0:3], PTA[6:7], PTB[0:7], PTC[0:7], low-drive strength		$V_{DD} > 1.8 \text{ V}$ $I_{Load} = 0.6 \text{ mA}$			0.5	
5	Р	Output low			$V_{DD} > 2.7 \text{ V}$ $I_{Load} = 10 \text{ mA}$	_	_	0.5	V
	С			$V_{DD} > 1.8 \text{ V}$ $I_{Load} = 3 \text{ mA}$	_	_	0.5		



Table 8. DC Characteristics (continued)

Num	С		Characteristic	Symbol	Condition	Min	Typ ¹	Max	Unit
	С	Outrout law	PTA[4:5], PTD[0:7], PTE[0:7], low-drive strength		V _{DD} > 1.8 V I _{Load} = 0.5 mA	_	_	0.5	
6	Р	Output low voltage	PTA[4:5], PTD[0:7], PTE[0:7],	V_{OL}	$V_{DD} > 2.7 V$ $I_{Load} = 3 \text{ mA}$	_	_	0.5	V
	С		high-drive strength		$V_{DD} > 1.8 V$ $I_{Load} = 1 \text{ mA}$	_	_	0.5	
7	D	Output low current	Max total I _{OL} for all ports	I _{OLT}		_	_	100	mA
8	Р	Input high	all digital inputs	V _{IH}	V _{DD} > 2.7 V	0.70 x V _{DD}	_	_	
	С	voltage	an angitan mpato	, 111	V _{DD} > 1.8 V	0.85 x V _{DD}		_	V
9	Р	Input low	all digital inputs	V_{IL}	V _{DD} > 2.7 V	_		0.35 x V _{DD}	-
	С	voltage	an angital impato	· IL	V _{DD} > 1.8 V	_	_	0.30 x V _{DD}	
10	С	Input hysteresis	all digital inputs	V_{hys}		0.06 x V _{DD}	_	_	mV
			all input only pins except for		$V_{In} = V_{DD}$	_	0.025	1	μΑ
11	Р	Input leakage	LCD only pins (LCD 8-12, 21-41)	ll _{ln} l	$V_{In} = V_{SS}$	_	0.025	1	μΑ
	•	current	LOD only ning /LOD 0.10	··In·	$V_{In} = V_{DD}$	_	100	150	μΑ
			LCD only pins (LCD 8-12, 21-41)		$V_{In} = V_{SS}$	_	0.025	1	μА
12	Р	Hi-Z (off-state) leakage current	all input/output (per pin)	ll _{OZ} l	$V_{In} = V_{DD}$ or V_{SS}	_	0.025	1	μΑ
13	Р	Total leakage current ³	Total leakage current for all pins	I _{InT}	$V_{In} = V_{DD}$ or V_{SS}	_	_	3	μΑ
14	Р	Pullup, Pulldown resistors	all non-LCD pins when enabled	R _{PU,} R _{PD}		17.5	_	52.5	kΩ
15	Р	Pullup, Pulldown resistors	LCD/GPIO pins when enabled	R _{PU,} R _{PD}		35	_	77	kΩ
		DC injection	Single pin limit			-0.2	_	0.2	mA
16	D	current ^{4, 5,}	Total MCU limit, includes sum of all stressed pins	I _{IC}	$V_{IN} < V_{SS}, V_{IN} > V_{DD}$	- 5	_	5	mA
17	С	Input Capac	itance, all pins	C _{In}		_	_	8	pF
18	С	RAM retention	on voltage	V _{RAM}		_	0.6	1.0	V
19	С	POR re-arm	voltage ⁷	V _{POR}		0.9	1.4	2.0	V
20	D	POR re-arm	time	t _{POR}		10	_	_	μS
21	Р	Low-voltage	detection threshold	V_{LVD}	V _{DD} falling V _{DD} rising		1.84 1.92	1.88 1.96	V



DC Characteristics

Num	С	Characteristic	Symbol	Condition	Min	Typ ¹	Max	Unit
22	Р	Low-voltage warning threshold	V_{LVW}	V _{DD} falling V _{DD} rising		2.14	2.2	V
23	Р.	Low-voltage inhibit reset/recover hysteresis	V _{hys}		_	80	_	mV
24	Р	Bandgap Voltage Reference ⁸	V_{BG}		1.15	1.17	1.18	V

Typical values are measured at 25 °C. Characterized, not tested

- POR will occur below the minimum voltage.
- ⁸ Factory trimmed at V_{DD} = 3.0 V, Temp = 25 °C

PULLUP RESISTOR TYPICALS - Non LCD pins

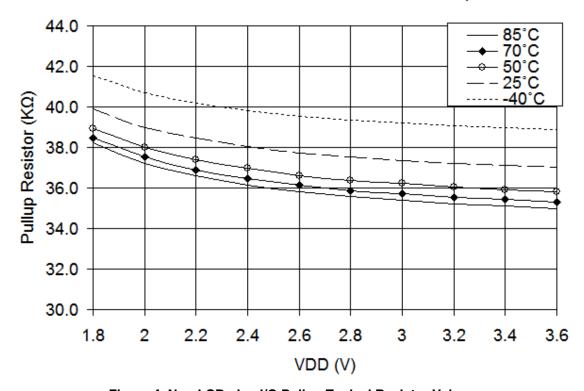


Figure 4. Non LCD pins I/O Pullup Typical Resistor Values

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² All I/O pins except for LCD pins in Open Drain mode.

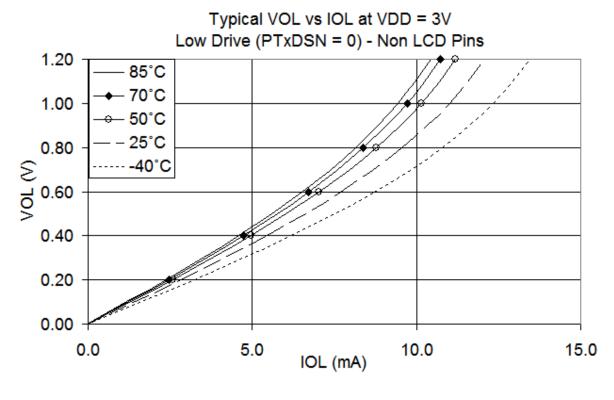
³ Total leakage current is the sum value for all GPIO pins. This leakage current is not distributed evenly across all pins but characterization data shows that individual pin leakage current maximums are less than 250 nA.

 $^{^4}$ All functional non-supply pins, except for PTB2 are internally clamped to V_{SS} and V_{DD} .

Input current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.

Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If the positive injection current (V_{In} > V_{DD}) is greater than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure that external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).





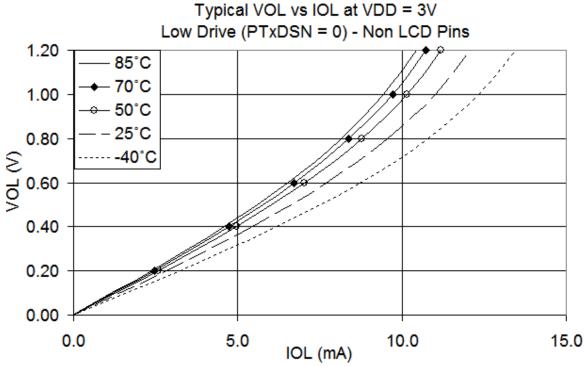


Figure 5. Typical Low-Side Driver (Sink) Characteristics (Non LCD Pins) — Low Drive (PTxDSn = 0)



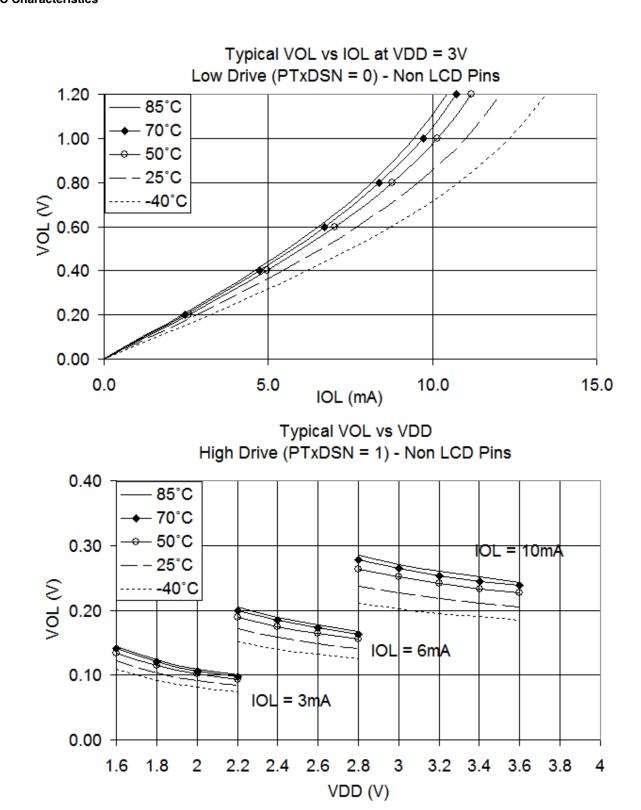


Figure 6. Typical Low-Side Driver (Sink) Characteristics(Non LCD Pins) — High Drive (PTxDSn = 1)



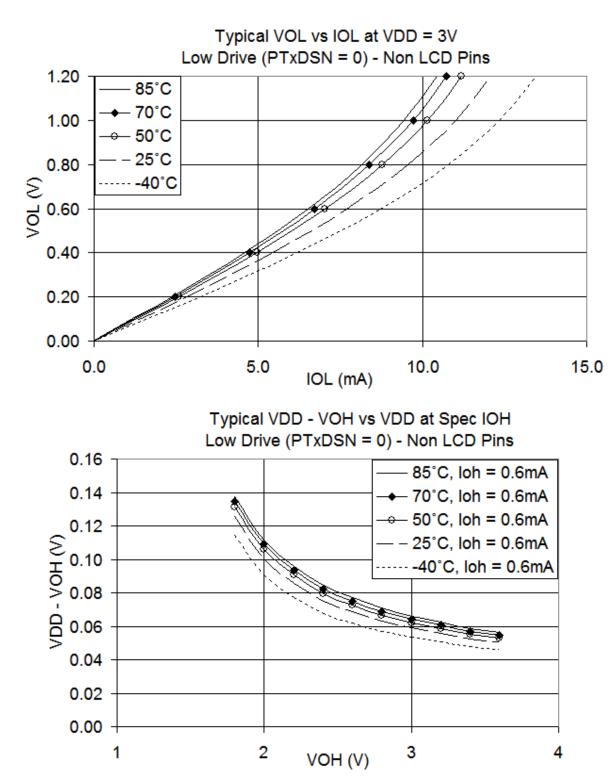
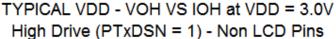
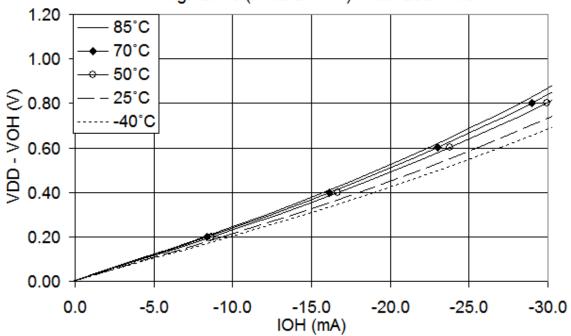


Figure 7. Typical High-Side (Source) Characteristics (Non LCD Pins)— Low Drive (PTxDSn = 0)









Typical VOh vs VDD High Drive (PTxDSN = 1) - Non LCD Pins

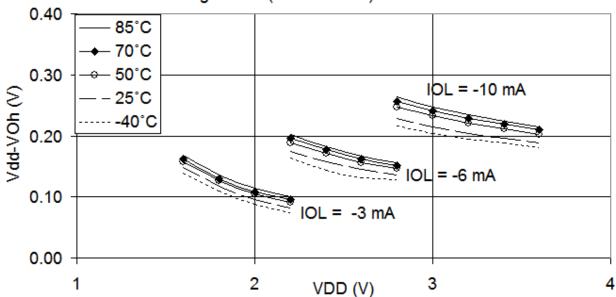


Figure 8. Typical High-Side (Source) Characteristics(Non LCD Pins) — High Drive (PTxDSn = 1)



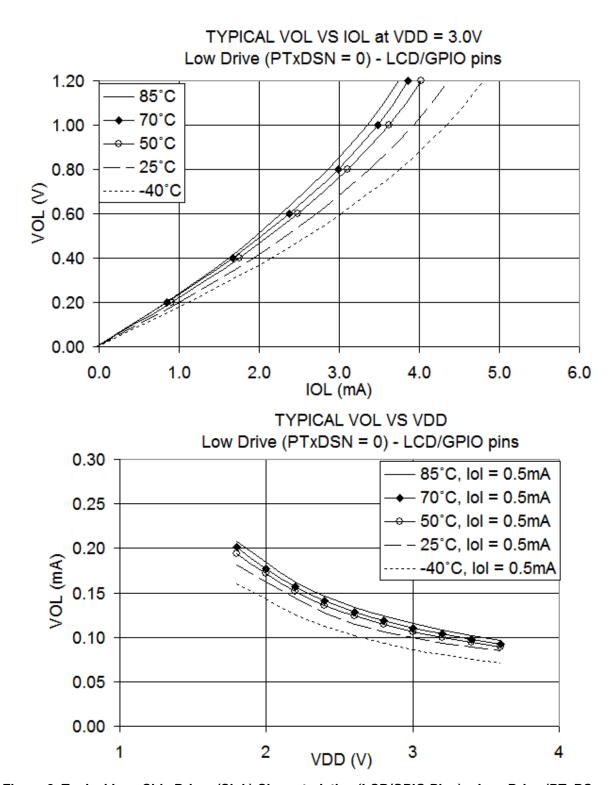
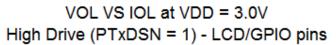
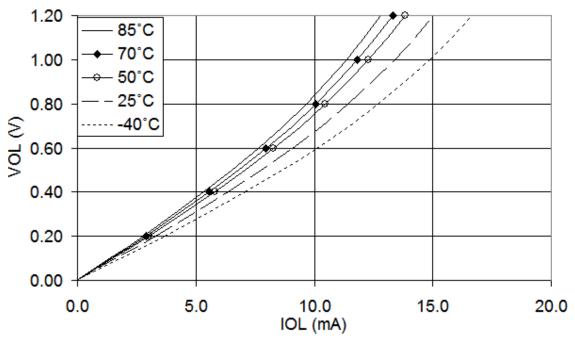


Figure 9. Typical Low-Side Driver (Sink) Characteristics (LCD/GPIO Pins)— Low Drive (PTxDSn = 0)







TYPICAL VOL VS VDD High Drive (PTxDSN = 1) - LCD/GPIO pins 0.30 85°C 0.25 10L = 3 mA

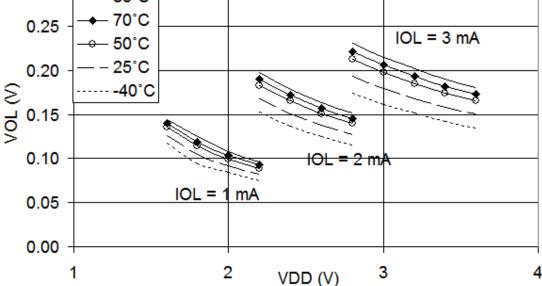
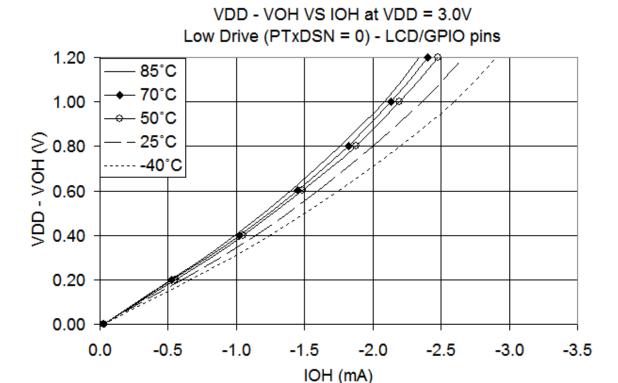


Figure 10. Typical Low-Side Driver (Sink) Characteristics (LCD/GPIO Pins) — High Drive (PTxDSn = 1)





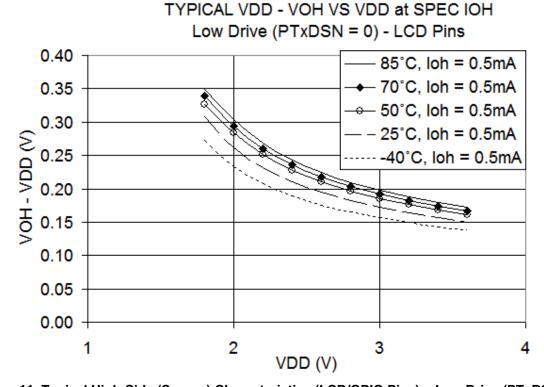
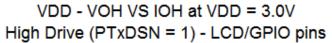
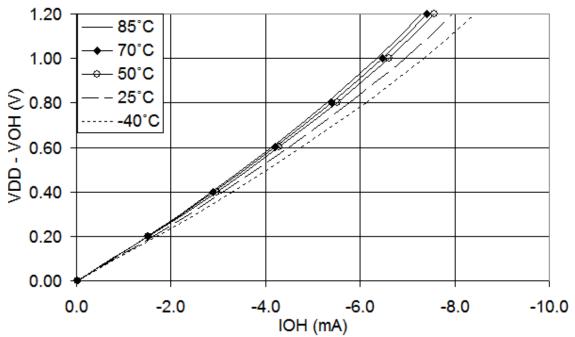


Figure 11. Typical High-Side (Source) Characteristics (LCD/GPIO Pins)— Low Drive (PTxDSn = 0)









VOH - VDD VS VDD at SPEC IOH High Drive (PTxDSN = 1) - LCD Pins

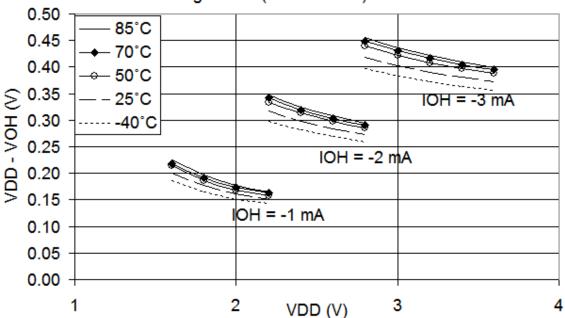


Figure 12. Typical High-Side (Source) Characteristics (LCD/GPIO Pins) — High Drive (PTxDSn = 1)



3.7 Supply Current Characteristics

This section includes information about power supply current in various operating modes.

Table 9. Supply Current Characteristics

Num	С	Parameter	Symbol	Bus Freq	V _{DD} (V)	Typ ¹	Max	Unit	Temp (°C)
	T			20 MHz		13.75	17.9		
1	T	Run supply current FEI mode, all modules on	RI_{DD}	8 MHz	3	7		mA	-40 to 85
	Т			1 MHz		2	1		
	Т	Run supply current		20 MHz		8.9	1		
2	T	FEI mode, all modules off	RI_{DD}	8 MHz	3	5.5	1	mA	-40 to 85
	T			1 MHz		0.9	_		
3	Т	Run supply current	DI	32 kHz FBILP	3	185		μА	40 to 85
3	Т	LPS=0, all modules off	RI _{DD}	16 kHz FBELP		115	_	μΑ	40 10 65
	т	Run supply current				21.9			0 to 70
4	ı	LPS=1, all modules off, running from Flash	DI	16 kHz	3	21.9	_		-40 to 85
4	Т	Run supply current LPS=1, all modules off, running from	- RI _{DD}	FBELP	3	7.3	_	μΑ	0 to 70
	'	RAM				7.5	_		-40 to 85
	T	Wait mode supply current FEI mode, all modules off	WI _{DD}	20 MHz	3	4.57	6	mA	
5	T			8 MHz		2			-40 to 85
	T			1 MHz		0.73			
	Р	Stop2 mode supply current				0.4	1.3		-40 to 25
	С				3	4	6		70
6	Р		S2I _{DD}	n/a		8.5	13	μΑ	85
	С		ODD			0.35	1.0	μ	-40 to 25
	С				2	3.9	5		70
	С					7.7	10		85
	Р	Stop3 mode supply current				0.65	1.8		-40 to 25
	С	No clocks active			3	5.7	8.0		70
7	Р		S3I _{DD}	n/a		12.2	20	μΑ	85
	С		00	-		0.6	1.5		-40 to 25
	С				2	5	6.8		70
	С					11.5	14		85

¹ Typical values are measured at 25 °C. Characterized, not tested



Supply Current Characteristics

Table 10. Stop Mode Adders

Num	_	C Parameter	Condition		Tempera	nture (°C)		Units
Nulli			Condition	-40	25	70	85	Ullits
1	Т	LPO		100	100	150	175	nA
2	Т	EREFSTEN	RANGE = HGO = 0	750	750	800	850	nA
3	Т	IREFSTEN ¹		63	70	77	81	μА
4	Т	TOD	Does not include clock source current	50	50	75	100	nA
5	Т	LVD ¹	LVDSE = 1	110	110	112	115	μА
6	Т	ACMP ¹	Not using the bandgap (BGBE = 0)	12	12	20	23	μА
7	Т	ADC ¹	ADLPC = ADLSMP = 1 Not using the bandgap (BGBE = 0)	95	95	101	120	μА
8	Т	LCD	VIREG enabled for Contrast control, 1/8 Duty cycle, 8x24 configuration for driving 192 segments, 32 Hz frame rate, No LCD glass connected.	1	1	6	13	μА
9	Т	LCD	LCD configured for 1/8 duty cycle, 8x24 configuration for driving 192 segments, 32 Hz frame rate, no LCD glass connected.	0.2	0.24	0.5	0.65	μΑ

Not available in stop2 mode.

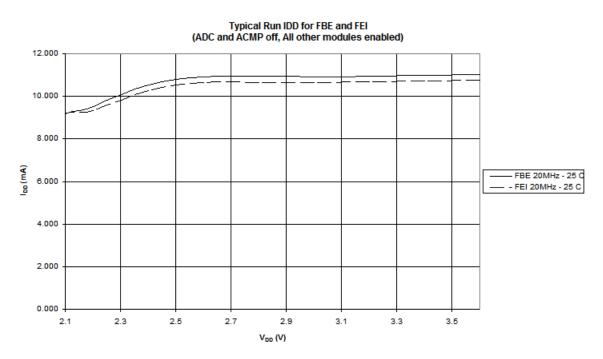


Figure 13. Typical Run I_{DD} for FBE and FEI, I_{DD} vs. V_{DD} (ACMP and ADC off, All Other Modules Enabled)

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3.8 External Oscillator (XOSCVLP) Characteristics

See Figure 14 and Figure 15 for crystal or resonator circuits.

Table 11. XOSCVLP and ICS Specifications (Temperature Range = −40 to 85°C Ambient)

Num	С	Characteristic	Symbol	Min	Typ ¹	Max	Unit
1	С	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0) High range (RANGE = 1), high gain (HGO = 1) High range (RANGE = 1), low power (HGO = 0)	f _{lo} f _{hi} f _{hi}	32 1 1	_ _ _	38.4 16 8	kHz MHz MHz
2	D	Load capacitors Low range (RANGE=0), low power (HGO=0) Other oscillator settings	C _{1,} C ₂		See No		
3	D	Feedback resistor Low range, low power (RANGE=0, HGO=0) ² Low range, high gain (RANGE=0, HGO=1) High range (RANGE=1, HGO=X)	R _F		— 10 1	_ _ _	ΜΩ
4	D	Series resistor — Low range, low power (RANGE = 0, HGO = 0) ² Low range, high gain (RANGE = 0, HGO = 1) High range, low power (RANGE = 1, HGO = 0) High range, high gain (RANGE = 1, HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	R _S	111 111			kΩ
5	С	Crystal start-up time ⁴ Low range, low power Low range, high gain High range, low power High range, high gain	t CSTL t CSTH	_ _ _ _	600 400 5 15	_ _ _ _	ms
6	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE mode FBE or FBELP mode	f _{extal}	0.03125 0	_ _	20 20	MHz MHz

Data in Typical column was characterized at 3.0 V, 25 °C or is typical recommended value.

² Load capacitors (C₁,C₂), feedback resistor (R_F) and series resistor (R_S) are incorporated internally when RANGE=HGO=0.

³ See crystal or resonator manufacturer's recommendation.

⁴ Proper PC board layout procedures must be followed to achieve specifications.



Internal Clock Source (ICS) Characteristics

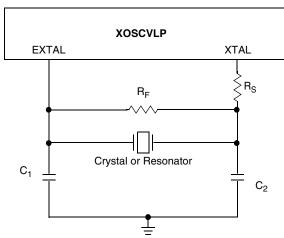


Figure 14. Typical Crystal or Resonator Circuit: High Range and Low Range/High Gain

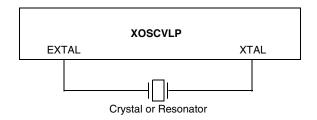


Figure 15. Typical Crystal or Resonator Circuit: Low Range/Low Power

3.9 Internal Clock Source (ICS) Characteristics

Table 12. ICS Frequency Specifications (Temperature Range = −40 to 85 °C Ambient)

Num	С	Chara	acteristic	Symbol	Min	Typ ¹	Max	Unit
1	С	Average internal reference f	requency — untrimmed	f _{int_ut}	25	32.7	41.66	kHz
2	Р	Average internal reference f	requency — user-trimmed	f _{int_t}	31.25	_	39.06	kHz
3	Р	Average internal reference f	requency — factory-trimmed	f _{int_t}	_	32.7	_	kHz
4	Т	Internal reference start-up ti	al reference start-up time		_	60	100	μS
5	Р	DCO output frequency	Low range (DFR = 00)	f _{dco_ut}	12.8	16.8	21.33	MHz
	C	range — untrimmed	Mid range (DFR = 01)		25.6	33.6	42.67	
6	Р	DCO output frequency	Low range (DFR = 00)	f _{dco_t}	16	_	20	MHz
	Р	range — trimmed	Mid range (DFR = 01)	'dco_t	32	_	40	IVII IZ
7	С	Resolution of trimmed DCO output frequency at fixed voltage and temperature (using FTRIM)		$\Delta f_{dco_res_t}$	_	±0.1	±0.2	%f _{dco}
8	С	Resolution of trimmed DCO voltage and temperature (no		$\Delta f_{dco_res_t}$	_	±0.2	±0.4	%f _{dco}

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Table 12. ICS Frequency Specifications (Temperature Range = −40 to 85 °C Ambient) (or	continued)

Num	С	Characteristic	Symbol	Min	Typ ¹	Max	Unit
9	С	Total deviation of trimmed DCO output frequency over voltage and temperature	Δf_{dco_t}	_	+0.5 -1.0	±2	%f _{dco}
10	С	Total deviation of trimmed DCO output frequency over fixed voltage and temperature range of 0 °C to 70 °C	Δf _{dco_t}	_	±0.5	±1	%f _{dco}
11	С	FLL acquisition time ²	t _{Acquire}	_	_	1	ms
12	С	Long term jitter of DCO output clock (averaged over 2-ms interval) ³	C _{Jitter}	_	0.02	0.2	%f _{dco}

¹ Data in Typical column was characterized at 3.0 V, 25 °C or is typical recommended value.

Deviation of DCO Output from Trimmed Frequency

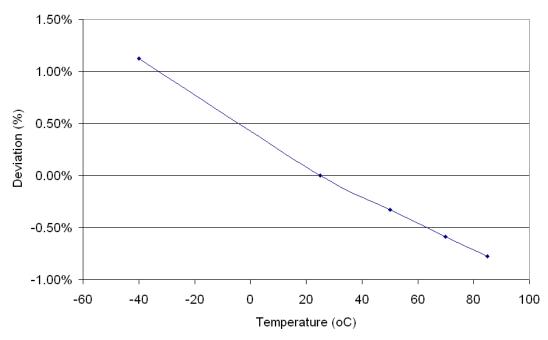


Figure 16. Deviation of DCO Output from Trimmed Frequency (20 MHz, 3.0 V)

3.10 AC Characteristics

This section describes timing characteristics for each peripheral system.

² This specification applies to any time the FLL reference source or reference divider is changed, trim value changed or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{Bus}. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DD} and V_{SS} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.



AC Characteristics

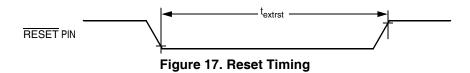
3.10.1 Control Timing

Table 13. Control Timing

Num	С	Rating	Symbol	Min	Typ ¹	Max	Unit
1	D	Bus frequency ($t_{cyc} = 1/f_{Bus}$) $V_{DD} \le 2.1V$ $V_{DD} > 2.1V$	f _{Bus}	dc dc	_ _	10 20	MHz
2	D	Internal low power oscillator period	t _{LPO}	700	_	1300	μS
3	D	External reset pulse width ²	t _{extrst}	100	_	_	ns
4	D	Reset low drive	t _{rstdrv}	34 x t _{cyc}	_	_	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	t _{MSSU}	500	_	_	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes ³	t _{MSH}	100	_	_	μS
7	D	IRQ pulse width Asynchronous path ² Synchronous path ⁴	t _{ILIH,} t _{IHIL}	100 1.5 × t _{cyc}		_	ns
8	D	Keyboard interrupt pulse width Asynchronous path ² Synchronous path ⁴	t _{ILIH} , t _{IHIL}	100 1.5 × t _{cyc}		_	ns
9	С	Port rise and fall time — Low output drive (PTxDS = 0) (load = 50 pF) ^{5, 6} Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t _{Rise} , t _{Fall}	_	16 23		ns
9		Port rise and fall time — High output drive (PTxDS = 1) (load = 50 pF) ^{5, 6} Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t _{Rise} , t _{Fall}		5 9		ns
10	Р	Reset pulse width with digital filter	t _{extrst}		2	_	ms

¹ Typical values are based on characterization data at V_{DD} = 3.0 V, 25 °C unless otherwise stated.

⁶ Except for LCD pins in Open Drain mode.



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² This is the shortest pulse that is guaranteed to be recognized as a reset pin request.

To enter BDM mode following a POR, BKGD/MS should be held low during the power-up and for a hold time of t_{MSH} after V_{DD} rises above V_{LVD}.

⁴ This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized.

 $^{^5}$ Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range –40 °C to 85 °C.



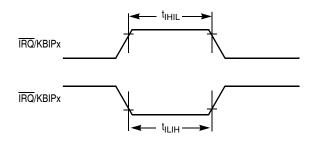


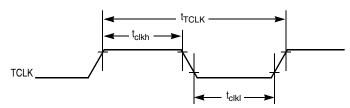
Figure 18. IRQ/KBIPx Timing

3.10.2 **TPM Module Timing**

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

No. C **Function Symbol** Min Max Unit 1 D External clock frequency 0 f_{Bus}/4 Hz f_{TCLK} 2 D External clock period 4 t_{TCLK} $t_{\rm cyc}$ 3 D External clock high time 1.5 t_{clkh} t_{cyc} 4 D External clock low time 1.5 t_{clkl} t_{cyc} 5 D Input capture pulse width 1.5 $\rm t_{\rm cyc}$

Table 14. TPM Input Timing



t_{ICPW}

Figure 19. Timer External Clock

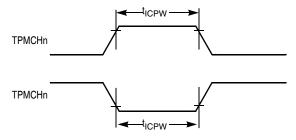


Figure 20. Timer Input Capture Pulse

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AC Characteristics

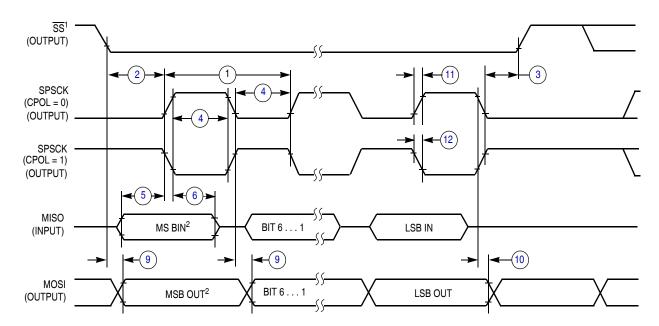
3.10.3 SPI Timing

Table 15 and Figure 21 through Figure 24 describe the timing requirements for the SPI system.

Table 15. SPI Timing

No.	С	Function	Symbol	Min	Max	Unit
_	D	Operating frequency Master Slave	f _{op}	f _{Bus} /2048	f _{Bus} /2 f _{Bus} /4	Hz
1	D	SPSCK period Master Slave	t _{SPSCK}	2 4	2048 —	t _{cyc} t _{cyc}
2	D	Enable lead time Master Slave	t _{Lead}	1/2 1		t _{SPSCK} t _{cyc}
3	D	Enable lag time Master Slave	t _{Lag}	1/2 1	_ _	t _{SPSCK} t _{cyc}
4	D	Clock (SPSCK) high or low time Master Slave	^t wspsck	t _{cyc} – 30 t _{cyc} – 30	1024 t _{cyc} —	ns ns
5	D	Data setup time (inputs) Master Slave	t _{SU}	15 15		ns ns
6	D	Data hold time (inputs) Master Slave	t _{HI}	0 25		ns ns
7	D	Slave access time	t _a	_	1	t _{cyc}
8	D	Slave MISO disable time	t _{dis}	_	1	t _{cyc}
9	D	Data valid (after SPSCK edge) Master Slave	t _v		25 25	ns ns
10	D	Data hold time (outputs) Master Slave	t _{HO}	0 0	_	ns ns
11)	D	Rise time Input Output	t _{RI} t _{RO}	_	t _{cyc} – 25 25	ns ns
(12)	D	Fall time Input Output	t _{FI}	_	t _{cyc} – 25 25	ns ns

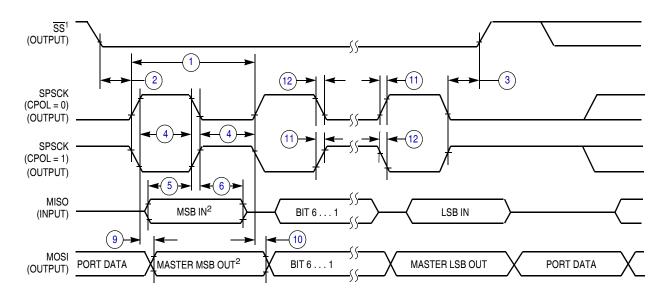




NOTES:

- 1. SS output mode (DDS7 = 1, SSOE = 1).
- 2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 21. SPI Master Timing (CPHA = 0)



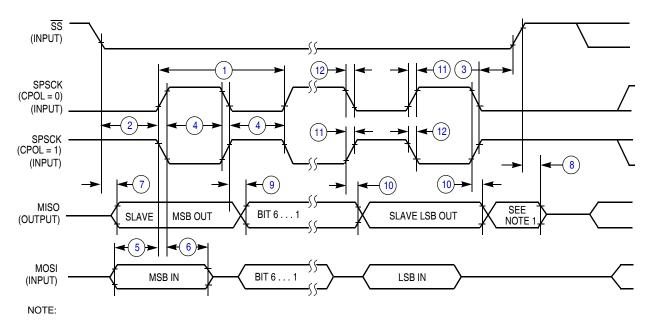
NOTES:

- 1. \overline{SS} output mode (DDS7 = 1, SSOE = 1).
- 2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

Figure 22. SPI Master Timing (CPHA =1)

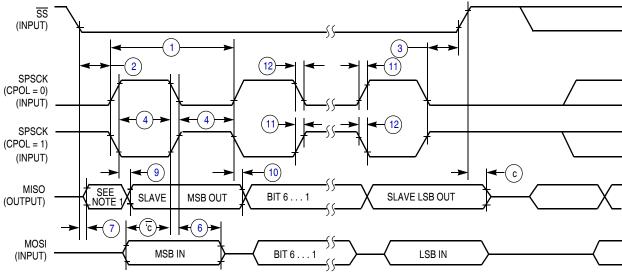


AC Characteristics



1. Not defined but normally MSB of character just received.

Figure 23. SPI Slave Timing (CPHA = 0)



NOTE:

1. Not defined but normally LSB of character just received

Figure 24. SPI Slave Timing (CPHA = 1)



3.11 Analog Comparator (ACMP) Electricals

Table 16. Analog Comparator Electrical Specifications

С	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage	V_{DD}	1.8	_	3.6	V
Р	Supply current (active)	I _{DDAC}	_	20	35	μА
D	Analog input voltage	V _{AIN}	$V_{SS} - 0.3$	_	V_{DD}	V
Р	Analog input offset voltage	V _{AIO}		20	40	mV
С	Analog comparator hysteresis	V _H	3.0	9.0	15.0	mV
Р	Analog input leakage current	I _{ALKG}	_	_	1.0	μΑ
С	Analog comparator initialization delay	t _{AINIT}	_	_	1.0	μS

3.12 ADC Characteristics

Table 17. 16-bit ADC Operating Conditions

Num	Characteris tic	Conditions	Symb	Min	Typ ¹	Max	Unit	Comment
1	Supply	Absolute	V_{DDA}	1.8	_	3.6	٧	
2	voltage	Delta to V _{DD} (V _{DD} -V _{DDA}) ²	ΔV_{DDA}	-100	0	100	mV	
3	Ground voltage	Delta to V _{SS} (V _{SS} -V _{SSA}) ²	ΔV_{SSA}	-100	0	100	mV	
4	Ref Voltage High		V _{REFH}	1.15	V_{DDA}	V _{DDA}	V	
5	Ref Voltage Low		V _{REFL}	V_{SSA}	V _{SSA}	V _{SSA}	V	
6	Input Voltage		V _{ADIN}	V _{REFL}	_	V _{REFH}	٧	
7	Input Capacitance	16-bit modes 8/10/12-bit modes	C _{ADIN}	_	8 4	10 5	pF	
8	Input Resistance		R _{ADIN}	_	2	5	kΩ	



ADC Characteristics

Table 17. 16-bit ADC Operating Conditions

Num	Characteris tic	Conditions	Symb	Min	Typ ¹	Max	Unit	Comment
9		16 bit modes f _{ADCK} > 8MHz 4MHz < f _{ADCK} < 8MHz f _{ADCK} < 4MHz		_ _ _		0.5 1 2		
10	Analog Source	13/12 bit modes f _{ADCK} > 8MHz 4MHz < f _{ADCK} < 8MHz f _{ADCK} < 4MHz	R _{AS}	 	_ _ _	1 2 5	kΩ	External to MCU
11	Resistance	11/10 bit modes f _{ADCK} > 8MHz 4MHz < f _{ADCK} < 8MHz f _{ADCK} < 4MHz		_ _ _	_ _ _	2 5 10		Assumes ADLSMP=0
12		9/8 bit modes f _{ADCK} > 8MHz f _{ADCK} < 8MHz			_	5 10		
13		ADLPC = 0, ADHSC = 1		1.0	_	8		
14	ADC Conversion Clock Freq.	ADLPC = 0, ADHSC = 0	f _{ADCK}	1.0	_	5	MHz	
15	, '	ADLPC = 1, ADHSC = 0		1.0	_	2.5		

Typical values assume V_{DDA} = 3.0 V, Temp = 25 °C, f_{ADCK} = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

² DC potential difference.



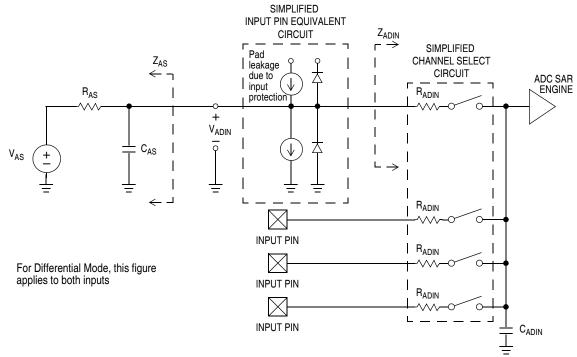


Figure 25. ADC Input Impedance Equivalency Diagram

Table 18. 16-bit ADC Characteristics full operating range($V_{REFH} = V_{DDA} > 1.8$, $V_{REFL} = V_{SSA}$, $F_{ADCK} \le 8MHz$)

Characteristic	Conditions ¹	С	Symb	Min	Typ ²	Max	Unit	Comment
Supply Current	ADLPC = 1, ADHSC = 0			_	215	_		ADLOMD O
	ADLPC = 0, ADHSC = 0	Т	I _{DDA}	_	470	_	μΑ	ADLSMP = 0 ADCO = 1
	ADLPC=0, ADHSC=1			_	610	_		
Supply Current	Stop, Reset, Module Off	С	I _{DDA}	_	0.01	_	μΑ	
ADC	ADLPC = 1, ADHSC = 0			_	2.4	_		
Asynchronous Clock Source	ADLPC = 0, ADHSC = 0	Р	f _{ADACK}	_	5.2	_	MHz	t _{ADACK} =
	ADLPC = 0, ADHSC = 1			_	6.2	_		1/f _{ADACK}
Sample Time	See reference manual for sa	ımple t	times					
Conversion Time	See reference manual for co	nversi	on times					



ADC Characteristics

Table 18. 16-bit ADC Characteristics full operating range($V_{REFH} = V_{DDA} > 1.8$, $V_{REFL} = V_{SSA}$, $F_{ADCK} \le 8MHz$)

Characteristic	Conditions ¹	С	Symb	Min	Typ ²	Max	Unit	Comment
Total Unadjusted	16-bit differential mode 16-bit single-ended mode	Т	TUE		±16 ±20	+48/-40 +56/-28	LSB ³	32x Hardware
Error	13-bit differential mode 12-bit single-ended mode	Т		_	±1.5 ±1.75	±3.0 ±3.5		Averaging (AVGE = %1 AVGS = %11)
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.7 ±0.8	±1.5 ±1.5		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.5 ±0.5	±1.0 ±1.0		
Differential Non-Linearity	16-bit differential mode 16-bit single-ended mode	Т	DNL	_	±2.5 ±2.5	+5/-3 +5/-3	LSB ²	
	13-bit differential mode 12-bit single-ended mode	Т			±0.7 ±0.7	±1 ±1		
	11-bit differential mode 10-bit single-ended mode	Т			±0.5 ±0.5	±0.75 ±0.75		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.2 ±0.2	±0.5 ±0.5		
Integral Non-Linearity	16-bit differential mode 16-bit single-ended mode	Т	INL	_	±6.0 ±10.0	±16.0 ±20.0	LSB ²	
	13-bit differential mode 12-bit single-ended mode	Т		_	±1.0 ±1.0	±2.5 ±2.5		
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.5 ±0.5	±1.0 ±1.0		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.3 ±0.3	±0.5 ±0.5		
Zero-Scale Error	16-bit differential mode 16-bit single-ended mode	Т	E _{ZS}		±4.0 ±4.0	+32/-24 +24/-16	LSB ²	$V_{ADIN} = V_{SSA}$
	13-bit differential mode 12-bit single-ended mode	Т		_	±0.7 ±0.7	±2.5 ±2.0		
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.4 ±0.4	±1.0 ±1.0		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.2 ±0.2	±0.5 ±0.5		



Table 18. 16-bit ADC Characteristics full operating range($V_{REFH} = V_{DDA} > 1.8$, $V_{REFL} = V_{SSA}$, $F_{ADCK} \le 8MHz$)

	T			1	- DDA	, - NEFL		
Characteristic	Conditions ¹	С	Symb	Min	Typ ²	Max	Unit	Comment
Full-Scale Error	16-bit differential mode 16-bit single-ended mode	Т	E _{FS}		+10/0 +14/0	+42/-2 +46/-2	LSB ²	$V_{ADIN} = V_{DDA}$
	13-bit differential mode 12-bit single-ended mode	Т			±1.0 ±1.0	±3.5 ±3.5		
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.4 ±0.4	±1.5 ±1.5		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.2 ±0.2	±0.5 ±0.5		
Quantization	16-bit modes	D	EQ	_	-1 to 0	_	LSB ²	
Error	≤13-bit modes			_	_	±0.5		
Effective Number of Bits	16-bit differential mode Avg = 32 Avg = 16 Avg = 8 Avg = 4 Avg = 1	С	ENOB	12.8 12.7 12.6 12.5 11.9	14.2 13.8 13.6 13.3 12.5	1111	Bits	F _{in} = F _{sample} /100
	16-bit single-ended mode Avg = 32 Avg = 16 Avg = 8 Avg = 4 Avg = 1	D			13.2 12.8 12.6 12.3 11.5			
Signal to Noise plus Distortion	See ENOB		SINAD	SINAD =	= 6.02 · ENG	<i>OB</i> + 1. 76	dB	
Total Harmonic Distortion	16-bit differential mode Avg = 32	С	THD	_	-91.5	-74.3	dB	F _{in} = F _{sample} /100
	16-bit single-ended mode Avg = 32	D		_	-85.5	_		
Spurious Free Dynamic	16-bit differential mode Avg = 32	С	SFDR	75.0	92.2	_	dB	F _{in} = F _{sample} /100
Range	16-bit single-ended mode Avg = 32	D		_	86.2	_		
Input Leakage Error	all modes	D	E _{IL}		I _{In} * R _{AS}		mV	I _{In} = leakage current (refer to DC characteristics)
Temp Sensor	-40 °C– 25 °C	С	m	_	1.646	_	mV/°C	
Slope	25 °C– 125 °C			_	1.769			
Temp Sensor Voltage	25 °C	С	V _{TEMP25}		701.2	_	mV	



ADC Characteristics

- $^{\rm 1}~$ All accuracy numbers assume the ADC is calibrated with $\rm V_{REFH}\!\!=\!\!V_{DDA}$
- Typical values assume V_{DDA} = 3.0 V, Temp = 25 °C, f_{ADCK}=2.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
- 3 1 LSB = $(V_{REFH} V_{REFL})/2^N$

Table 19. 16-bit ADC Characteristics($V_{REFH} = V_{DDA} \ge 2.7V$, $V_{REFL} = V_{SSA}$, $F_{ADCK} \le 4MHz$, ADHSC=1)

Characteristic	Conditions ¹	С	Symb	Min	Typ ²	Max	Unit	Comment
Total Unadjusted Error	16-bit differential mode 16-bit single-ended mode	Т	TUE	_	±16 ±20	+24/-24 +32/-20	LSB ³	32x Hardware
LIIOI	13-bit differential mode 12-bit single-ended mode	Т		_	±1.5 ±1.75	±2.0 ±2.5		Averaging (AVGE = %1 AVGS = %11)
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.7 ±0.8	±1.0 ±1.25		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.5 ±0.5	±1.0 ±1.0		
Differential Non-Linearity	16-bit differential mode 16-bit single-ended mode	Т	DNL	_	±2.5 ±2.5	±3 ±3	LSB ²	
	13-bit differential mode 12-bit single-ended mode	Т		_	±0.7 ±0.7	±1 ±1		
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.5 ±0.5	±0.75 ±0.75		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.2 ±0.2	±0.5 ±0.5		
Integral Non-Linearity	16-bit differential mode 16-bit single-ended mode	Т	INL	_	±6.0 ±10.0	±12.0 ±16.0	LSB ²	
	13-bit differential mode 12-bit single-ended mode	Т		_	±1.0 ±1.0	±2.0 ±2.0		
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.5 ±0.5	±1.0 ±1.0		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.3 ±0.3	±0.5 ±0.5		
Zero-Scale Error	16-bit differential mode 16-bit single-ended mode	Т	E _{ZS}	_	±4.0 ±4.0	+16/0 +16/-8	LSB ²	$V_{ADIN} = V_{SSA}$
	13-bit differential mode 12-bit single-ended mode	Т			±0.7 ±0.7	±2.0 ±2.0		
	11-bit differential mode 10-bit single-ended mode	Т			±0.4 ±0.4	±1.0 ±1.0		
	9-bit differential mode 8-bit single-ended mode	Т		_	±0.2 ±0.2	±0.5 ±0.5		



Table 19. 16-bit ADC Characteristics(V_{REFH} = V_{DDA} \geq 2.7V, V_{REFL} = V_{SSA}, F_{ADCK} \leq 4MHz, ADHSC=1)

Characteristic	Conditions ¹	С	Symb	Min	Typ ²	Max	Unit	Comment
Full-Scale Error	16-bit differential mode 16-bit single-ended mode	Т	E _{FS}		+8/0 +12/0	+24/0 +24/0	LSB ²	$V_{ADIN} = V_{DDA}$
	13-bit differential mode 12-bit single-ended mode	Т			±0.7 ±0.7	±2.0 ±2.5		
	11-bit differential mode 10-bit single-ended mode	Т		_	±0.4 ±0.4	±1.0 ±1.0		
	9-bit differential mode 8-bit single-ended mode	Т			±0.2 ±0.2	±0.5 ±0.5		
Quantization	16 bit modes	D	EQ	_	-1 to 0	_	LSB ²	
Error	≤13 bit modes	1		_	_	±0.5		
Effective Number of Bits	16 bit differential mode Avg=32 Avg=16 Avg=8 Avg=4 Avg=1	С	ENOB	14.3 13.8 13.4 13.1 12.4	14.5 14.0 13.7 13.4 12.6		Bits	F _{in} = F _{sample} /100
	16 bit single-ended mode Avg=32 Avg=16 Avg=8 Avg=4 Avg=1			TBD TBD TBD TBD TBD	13.5 13.0 12.7 12.4 11.6	 - - -		
Signal to Noise plus Distortion	See ENOB		SINAD	SINAD =	= 6.02 *ENC	OB +1.76	dB	
Total Harmonic Distortion	16 bit differential mode Avg=32	С	THD	_	-95.8	-90.4	dB	F _{in} = F _{sample} /100
	16 bit single-ended mode Avg=32	D		_	_	l		
Spurious Free Dynamic	16 bit differential mode Avg=32	С	SFDR	91.0	96.5	ı	dB	F _{in} = F _{sample} /100
Range	16 bit single-ended mode Avg=32	D		_				
Input Leakage Error	all modes	D	E _{IL}		I _{In} * R _{AS}		mV	I _{In} = leakage current (refer to DC characteristics)
Temp Sensor	-40 °C– 25 °C	D	m	_	1.646	_	mV/°C	
Slope	25 °C– 125 °C			_	1.769	_		
Temp Sensor Voltage	25 °C	D	V _{TEMP25}	_	701.2	_	mV	

¹ All accuracy numbers assume the ADC is calibrated with V_{REFH}=V_{DDA}

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VREF Specifications

3.13 VREF Specifications

Table 20. VREF Electrical Specifications

Num	Characteristic	Symbol	Min	Max	Unit						
1	Supply voltage	V_{DD}	1.80	3.60	V						
2	Operating temperature range	T _{op}	-40	105	С						
3	Maximum Load	_	_	10	mA						
	Operation across Temperature										
4	V Room Temp	V Room Temp	1.135	1.165	V						
5	Untrimmed –40 °C	Untrimmed –40 °C	−2 to −6 from Volt	·	mV						
6	Trimmed –40 °C	Trimmed –40 °C	± 1 from Room	Temp Voltage	mV						
7	Untrimmed 0 °C	Untrimmed 0 °C	+1 to -2 from Volt	•	mV						
	Trimmed 0 °C	Trimmed 0 °C	± 0.5 from Rooi	m Temp Voltage	mV						
8	Untrimmed 50 °C	Untrimmed 50 °C	+1 to -2 from Volt	•	mV						
9	Trimmed 50 °C	Trimmed 50 °C	± 0.5 from Rooi	m Temp Voltage	mV						
10	Untrimmed 85 °C	Untrimmed 85 °C	0 to -4 from Roc	m Temp Voltage	mV						
11	Trimmed 85 °C	Trimmed 85 °C	± 0.5 from Rooi	m Temp Voltage	mV						
12	Untrimmed 125 °C	Untrimmed 125 °C	−2 to −6 from Volt	-	mV						
13	Trimmed 125 °C	Trimmed 125 °C	± 1 from Room	Temp Voltage	mV						
14	Load Bandwidth	_	_	_	_						
15	Load Regulation Mode = 10 at 1mA load	Mode = 10	20	100	μV/mA						
16	Line Regulation (Power Supply	DC	± 0.1 from Rooi	m Temp Voltage	mV						
10	Rejection)	AC	-6	60	dB						
	F	Power Consumption	n								
17	Powered down Current (Stop Mode, VREFEN = 0, VRSTEN = 0)	I	_	.100	μΑ						
18	Bandgap only (Mode[1:0] 00)	I	_	75	μА						
19	Low-Power buffer (Mode[1:0] 01)	I	_	125	μА						
20	Tight-Regulation buffer (Mode[1:0] 10)	I	_	1.1	mA						
21	Reserved (Mode[1:0] 11)	_	_	_	_						

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 $^{^2}$ Typical values assume V_{DDA} = 3.0 V, Temp = 25 °C, f_{ADCK} = 2.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

 $^{^{3}}$ 1 LSB = $(V_{REFH} - V_{REFL})/2^{N}$



LCD Specifications 3.14

Table 21. LCD Electricals, 3-V Glass

#	С	Characteristic	Symbol	Min	Тур	Max	Unit
1	D	LCD Supply Voltage	V_{LCD}	0.9	1.5	1.8	V
2	D	LCD Frame Frequency	f _{Frame}	28	30	58	Hz
3	D	LCD Charge Pump Capacitance	C _{LCD}	_	100	100	nF
4	D	LCD Bypass Capacitance	C _{BYLCD}	_	100	100	nF
5	D	LCD Glass Capacitance	C _{glass}	_	2000	8000	pF
6	D	HRefSel = 0	V	0.89	1.00	1.15	V
7	D	V _{IREG} HRefSel = 1	V _{IREG}	1.49	1.67	1.85 ¹	V
8	D	V _{IREG} TRIM Resolution	Δ_{RTRIM}	1.5	_	_	% V _{IREG}
9	D	V_{IREG} Ripple HRefSel = 0	_	_	_	0.1	V
10	ט	HRefSel = 1	_	_	_	0.15	\ \ \
11	D	V _{LCD} Buffered Adder ²	I _{Buff}	_	1		μА

V_{IREG} Max can not exceed V_{DD} – 0.15 V
 VSUPPLY = 10, BYPASS = 0

3.15 Flash Specifications

This section provides details about program/erase times and program-erase endurance for the flash memory.

Program and erase operations do not require any special power sources other than the normal V_{DD} supply. For more detailed information about program/erase operations, see the Memory section of the reference manual.

Table 22. Flash Characteristics

#	С	Characteristic	Symbol	Min	Typical	Max	Unit
1	D	Supply voltage for program/erase -40 °C to 85 °C	V _{prog/erase}	1.8	_	3.6	V
2	D	Supply voltage for read operation	V _{Read}	1.8	_	3.6	V
3	D	Internal FCLK frequency ¹	f _{FCLK}	150	_	200	kHz
4	D	Internal FCLK period (1/FCLK)	t _{Fcyc}	5	_	6.67	μS
5	Р	Byte program time (random location) ²	t _{prog}		9		t _{Fcyc}
6	Р	Byte program time (burst mode) ²	t _{Burst}		4		t _{Fcyc}
7	Р	Page erase time ²	t _{Page}		4000		t _{Fcyc}
8	Р	Mass erase time ²	t _{Mass}		20,000		t _{Fcyc}
9	D	Byte program current ³	R _{IDDBP}	_	4	_	mA

¹ The frequency of this clock is controlled by a software setting.



EMC Performance

- ² These values are hardware state machine controlled. User code does not need to count cycles. This information supplied for calculating approximate time to program and erase.
- ³ The program and erase currents are additional to the standard run I_{DD} . These values are measured at room temperatures with $V_{DD} = 3.0 \text{ V}$, bus frequency = 4.0 MHz.

3.16 EMC Performance

Electromagnetic compatibility (EMC) performance is highly dependent on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 available on www.freescale.com for advice and guidance specifically targeted at optimizing EMC performance.

3.16.1 Radiated Emissions

Microcontroller radiated RF emissions are measured from 150 kHz to 1 GHz using the TEM/GTEM Cell method in accordance with the IEC 61967-2 and SAE J1752/3 standards. The measurement is performed with the microcontroller installed on a custom EMC evaluation board while running specialized EMC test software. The radiated emissions from the microcontroller are measured in a TEM cell in two package orientations (North and East).

4 Ordering Information

This appendix contains ordering information for the device numbering system.

Memory Device Number¹ Available Packages² Flash RAM 64 KB 4000 80-pin LQFP MC9S08LH64 64 KB 4000 64-pin LQFP 36 KB 4000 80-pin LQFP MC9S08LH36 64-pin LQFP 36 KB 4000

Table 23. Device Numbering System

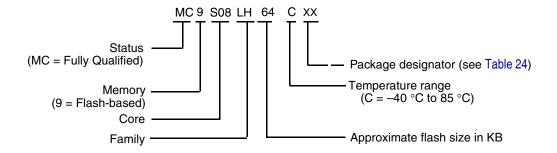
4.1 Device Numbering System

Example of the device numbering system:

See Table 1 for a complete description of modules included on each device.

² See Table 24 for package information.





4.2 Package Information

Table 24. Package Descriptions

Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
80	Low Quad Flat Package	LQFP	LK	917A	98ASS23237W
64	Low Quad Flat Package	LQFP	LH	840F	98ASS23234W

4.3 Mechanical Drawings

Table 24 provides the available package types and their document numbers. The latest package outline/mechanical drawings are available on the MC9S08LH64 Series Product Summary pages at http://www.freescale.com.

To view the latest drawing, either:

- Click on the appropriate link in Table 24, or
- Open a browser to the Freescale website (http://www.freescale.com), and enter the appropriate document number (from Table 24) in the "Enter Keyword" search box at the top of the page.



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