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Phase-sequence Phase-loss Relay калары

Three-phase Phase-sequence Phase-loss Relay Using Voltage Detection Method

- Prevents reverse motor rotation due to incorrect wiring.
- Distinguishes between positive phases, reversed phases, and phase loss when power is turned ON.
- Voltage detection method enables application for any load current.
- One SPDT output relay, 6 A at 250 VAC (resistive load).
- Output status can be monitored using LED indicator.



Model Number Structure

■ Model Number Legend



- 1 2 3
- 1. Basic Model
- K8AB: Measuring and Monitoring Relays **2. Functions**
- PH: Phase-sequence Phase-loss Relay
- 3. Rated Input Voltage
- 1: 200 to 500 VAC

Ordering Information

■ List of Models

Phase-sequence Phase-loss Relay	Functions	Rated input voltage (See note.)	Model
	Phase sequence and phase loss monitoring	200 to 500 VAC	K8AB-PH1

Note: The power supply is shared with the rated input voltage.

Ratings and Specifications

■ Ratings

Rated input voltage	Three-phase, three-wire mode, 200 to 500 VAC	
Input load	15 VA max.	
Reversed phase and phase loss operating time	0.1 s max.	
Reset method	Automatic reset	
Indicators	Power (PWR): Green, Relay output (RY): Yellow	
Output relays	One SPDT relay (NC operation)	
Output relay ratings	Rated load Resistive load $6 A at 250 VAC (cos \phi = 1)$ $6 A at 30 VDC (L/R = 0 ms)$ Inductive load $1 A at 250 VAC (cos \phi = 0.4)$ $1 A at 250 VAC (cos \phi = 0.4)$ $1 A at 30 VDC (L/R = 7 ms)$ Maximum contact voltage: 250 VAC Maximum contact current: $6 A AC$ Maximum switching capacity: $1,500 VA$ Minimum load: $10 mA at 5 VDC$ Mechanical life: $10,000,000$ operations Electrical life: Make: 50,000 times, Break: 30,000 times	
Ambient operating temperature	-20 to 60°C (with no condensation or icing)	
Storage temperature	-40 to 70°C (with no condensation or icing)	
Ambient operating humidity	25% to 85% (with no condensation)	
Storage humidity	25% to 85% (with no condensation)	
Altitude	2,000 m max.	
Terminal screw tightening torque	0.49 N·m	
Terminal wiring method	Recommended wire Solid wire: 2.5 mm² Twisted wires: AWG16, AWG18 Note: 1. Ferrules with insulating sleeves must be used with twisted wires. 2. Two wires can be twisted together. Recommended ferrules A1 1,5-8BK (for AWG16) manufactured by Phoenix Contact A1 1,-8RD (for AWG18) manufactured by Phoenix Contact A1 0,75-8GY (for AWG18) manufactured by Phoenix Contact	
Case color	Munsell 5Y8/1	
Case material	ABS resin (self-extinguishing resin) UL94-V0	
Weight	Approx. 110 g	
Mounting	Mounted to DIN Track or via M4 screws (tightening torque: 1.2 N·m)	
Dimensions	22.5 (W) · 90 (H) · 100 (D) mm	

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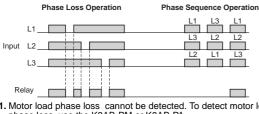
■ Specifications

Input voltage range		200 to 500 VAC	
Input frequency range		45 to 65 Hz	
Overload capacity		Continuous input: 115% of maximum input, 10 s max.: 125% of maximum input	
Temperature influence		Operating time Fluctuation based on measured value at standard temperature: -20°C to standard temperature: ±10% max. Standard temperature to 60°C : ±10% max. (Humidity: 25% to 80%)	
Humidity influence		Operating time Based on ambient room humidity 25% to 80%: ±10% max.	
Influence of po	wer supply voltage	Operating time: $\pm 10\%$ max. Note: The error in the operating value and operating time under standard conditions.	
Influence of power supply frequency		Operating time: ±10% max. (at 45 to 65 Hz) Note: The error in the operating value and operating time under standard conditions.	
Influence of input frequency		At 45 to 65 Hz Operating time ±10% max. Note: The error in the operating value and operating time under standard conditions.	
Applicable standards	Conforming standards	EN60255-5 and EN60255-6 Installation environment (Pollution Degree 2, Overvoltage Category III)	
	EMC	EN61326	
	Safety standards	UL508	
Insulation resistance		20 MΩ min. Between external terminals and case Between input terminals and output terminals	
Dielectric strength		2,000 VAC for one minute Between external terminals and case Between input terminals and output terminals	
Noise immunity		1,500 V power supply terminal common/normal mode Square-wave noise of ±1 ∝s/100 ns pulse width with 1-ns rise time	
Vibration resistance		Frequency 10 to 55 Hz, 0.35-mm single amplitude, acceleration 50 m/s ² 10 sweeps of 5 min each in X, Y, and Z directions	
Shock resistance		100 m/s ² , 3 times each in 6 directions along three axes (up/down, left/right, forward/backward)	
Degree of protection		Terminal section: Finger protection	

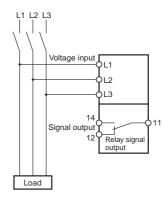
Connections

Wiring Diagram

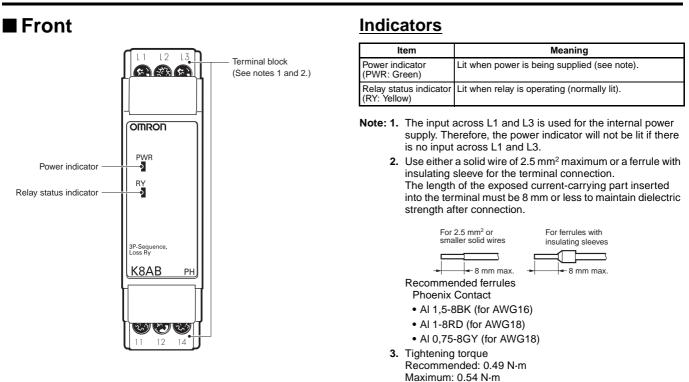
Phase Sequence and Phase Loss Operation Diagram



- Note: 1. Motor load phase loss cannot be detected. To detect motor load phase loss, use the K8AB-PM or K8AB-PA.
 2. The K8AB-PH output relay is normally operative.
 3. L1 and L3 function both as the power supply terminals and as input terminals. If the voltage drops below the minimum input voltage (60%), then the Relay will not operate due to an undervoltage.
 4. Phase loss is detected based on the phase sequence, so phase loss cannot be detected for loads that generate inductive power, e.g., due to monitoring during operation.
 5. Phase loss is detected based on voltage, so phase loss cannot be detected on the load side.



Nomenclature



Operation and Setting Methods

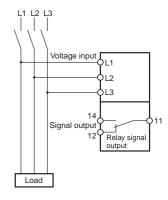
Connections

1. Input

Connect using L1, L2, and L3. Make sure the phase sequence is wired of

Make sure the phase sequence is wired correctly. The Unit will not operate normally if the phase sequence is incorrect.

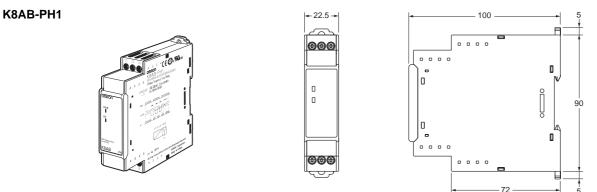
2. Outputs Terminals 11, 12, and 14 are output terminals for SPDT.



(Unit: mm)

Dimensions

Phase-sequence, Phase-loss Relays



Safety Precautions

■ Precautions for Safe Use

Make sure to follow the instructions below to ensure safety.

- 1. Do not use or keep this product in the following environments.
 - Outdoors, or places subject to direct sunlight or wearing weather.
 - Places where dust, iron powder, or corrosive gases (in particular, sulfuric or ammonia gas) exist.
 - Places subject to static electricity or inductive noise.
 - Places where water or oil come in contact with the product.
- 2. Make sure to install this product in the correct direction.
- There is a remote risk of electric shock. Do not touch terminals while electricity is being supplied.
- 4. Make sure to thoroughly understand all instructions in the Instructions Manual before handling this product.
- 5. Make sure to confirm terminal makings and polarity for correct wiring.
- Tighten terminal screws firmly using the following torque. Recommended tightening torque: 0.49 N·m Maximum tightening torque: 0.54 N·m max.
- 7. Operating ambient temperature and humidity for this product must be within the indicated rating when using this product.
- 8. There is a remote risk of explosion. Do not use this product where flammable or explosive gas exists.
- 9. Make sure that no weight rests on the product after installation.
- **10.**To enable an operator to turn off this product easily, install switches or circuit breakers that conform to relevant requirements of IEC60947-1 and IEC60947-3, and label them appropriately.

Precautions for Correct Use

For Proper Use

- 1. Do not use the product in the following locations.
 - Places subject to radiant heat from heat generating devices.
 - Places subject to vibrations or physical shocks.
- 2. Make sure to use setting values appropriate for the controlled object. Failure to do so can cause unintended operation, and may result in accident or corruption of the product.
- 3. Do not use thinner or similar solvent for cleaning. Use commercial alcohol.
- When discarding, properly dispose of the product as industrial waste.
- 5. Only use this product within a board whose structure allows no possibility for fire to escape.

About Installation

- 1. When wiring, use only recommended crimp terminals.
- Do not block areas around the product for proper dissipation of heat. (If you do not secure space for heat dissipation, life cycle of the product will be compromised.)
- **3.** To avoid electrical shocks, make sure that power is not supplied to the product while wiring.
- 4. To avoid electrical shocks, make sure that power is not supplied to the product when performing DIP switch settings.

Noise Countermeasures

- 1. Do not install the product near devices generating strong high frequency waves or surges.
- 2. When using a noise filter, check the voltage and current and install it as close to the product as possible.
- 3. In order to prevent inductive noise, wire the lines connected to the product separately from power lines carrying high voltages or currents. Do not wire in parallel with or on the same cable as power lines.

Other measures for reducing noise include running lines along separate ducts and using shield lines.

<u>To avoid faulty operations,</u> <u>malfunctions, or failure, observe the</u> <u>following operating instructions.</u>

- 1. When turning on the power, make sure to realize rated voltage within 1 second from the time of first supply of electricity.
- 2. Make sure to use power supply for operations, inputs, and transformer with the appropriate capacity and rated burden.
- 3. Maintenance and handling of this product may only be performed by qualified personnel.
- Distortion ratio of input wave forms must be 30% or less. Use of this product with circuits that have large distortion in wave forms may result in unwanted operations.
- 5. Using this product for thyristor controls or inverters will result in errors.
- 6. When setting the volume, adjust the control from the minimum side to the maximum side.

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Questions and Answers

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Α

Checking Operation

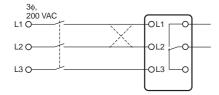
Phase Sequence

Switch the wiring, as shown by the dotted lines in the connection diagram, to reverse the phase sequence and check that the K8AB operates.

Phase Loss

Create a phase loss for any input phase and check that the K8AB operates.

Connection Diagram





Can phase loss be detected on the load side?

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In principle, phase loss cannot be detected on the load side because the K8AB-PH1 measures three-phase voltage to determine phase loss.



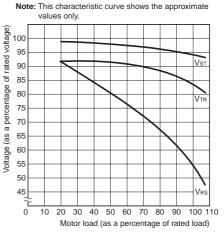
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Motor Load Phase Loss during Operation

Motor load phase loss cannot be detected during operation. It can be used to detect phase loss at startup.

Normally, three-phase motors will continue to rotate even if one phase is open. The three-phase voltage will be induced at the motor terminals. The diagram shows voltage induction at the motor terminals when phase R has been lost with a load applied to a three-phase motor. The horizontal axis shows the motor load as a percentage of the rated load, and the vertical axis shows voltage as a percentage of the rated voltage. The lines in the graph show the voltage induced at the motor terminals for each load when phase loss occurs during operation. As the graph shows, voltage is induced at the motor terminals even if there is phase loss for a motor load, so the K8AB-PH1 cannot detect phase loss for motor loads during operation. Use the K8AB-PH1 to detect phase loss at startup.

Characteristic Curve Diagram



Note: For phase loss of phase R. V_{ST}, V_{TR}, and V_{RS} indicate the motor terminal voltage at phase loss.

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OMRON ELECTRONICS LLC

One Commerce Drive

Schaumburg, IL 60173

847-843-7900

For US technical support or other inquiries: 800-556-6766

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OMRON CANADA, INC.

885 Milner Avenue Toronto, Ontario M1B 5V8 **416-286-6465**

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