

# SANYO Semiconductors **DATA SHEET**

An ON Semiconductor Company

LB1830M

# Monolithic Digital IC Low-Voltage, Low-Saturation Bidirectional Motor Driver

#### Overview

The LB1830M is a low-saturation bidirectional motor driver IC with brake function for use in low-voltage applications. As both of forward and reverse outputs are regulated, it is especially suited for use in portable equipment.

#### **Features**

- Wide operating voltage range: 3.0 to 9.0 V
- Low saturation voltage: 0.2V at  $I_O = 40mA$  (typ)
- Low current drain at standby mode (0.1µA or less)
- Brake function
- Regulated voltage value (forward/reverse) setting available by one variable resistor
- Regulated output/saturation output switching available
- Built-in spark killer diodes
- Small package: MFP10S

#### **Specifications**

#### Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
maximum supply voltage	V <sub>CC</sub> max, V <sub>S</sub> max		10.5	V
Output current	I <sub>M</sub> max		500	mA
Input supply voltage	V <sub>IN</sub>		-0.3 to +10	٧
Allowable power dissipation	Pd max	Independent IC	0.4	W
		Mounted on a specified board *	0.55	W
Operating temperature	Topr		-20 to +80	°C
Storage temperature	Tstg		-40 to +125	°C

 $<sup>^\</sup>star$  Specified board: 30mm  $\times$  30mm  $\times$  1.5mm, glass epoxy board.

Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

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#### LB1830M

#### Allowable Operating Ranges at Ta = 25°C

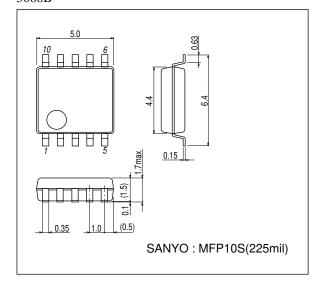
Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>CC</sub> , V <sub>S</sub>		3.0 to 9.0	V
Input high level voltage	V <sub>IH</sub>		2.0 to 9.0	V
Input low level voltage	V <sub>IL</sub>		-0.3 to +0.3	V
Control voltage	V <sub>C</sub>		1.0 to 6.0	V

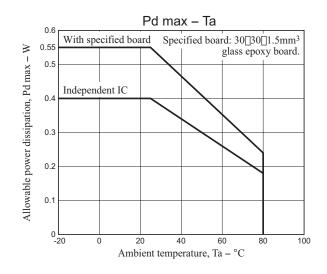
# **Electrical Characteristics** at Ta = 25°C, $V_{CC} = 6V$

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Parameter	Symbol	mbol Conditions		typ	max	Unit	
Current drain	ICC0	IN1 = IN2 = Vm = 0V, V <sub>C</sub> = Vref at standby mode		0.1	10	μА	
I <sub>CC</sub> 1		Forward/reverse, control, load OPEN		2	3	mA	
	I <sub>CC</sub> 2	Forward/reverse, saturation, load OPEN		3	5	mA	
	I <sub>CC</sub> 3	Braking, load OPEN		5	8	mA	
Output saturation voltage	Vsat1	I <sub>O</sub> = 40mA (upper side + lower side)		0.2	0.3	V	
	Vsat2	I <sub>O</sub> = 80mA (upper side + lower side)		0.4	0.6	V	
Reference voltage	Vref	I <sub>Vref</sub> = 1mA	1.85	2.0	2.15	V	
Voltage characteristics of output voltage	$\frac{\Delta V_{O}}{\Delta V_{CC}}$	$V_O = 5V$ , $V_{CC} = 5.5$ to 9V, $I_O = 40$ mA			80	mA	
Current characteristics of output voltage	$\frac{\Delta V_{O}}{\Delta I_{O}}$	$V_O = 5V$ , $V_{CC} = 6V$ , $I_O = 10$ to $80$ mA			50	mA	
Input current	I <sub>IN</sub>	V <sub>IN</sub> = 5V		90	150	μА	
Output voltage	VO	V <sub>C</sub> = 2V	2.3×V <sub>C</sub>		2.5×V <sub>C</sub>	V	

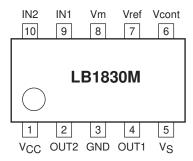
## **Package Dimensions**

unit : mm (typ) 3086B

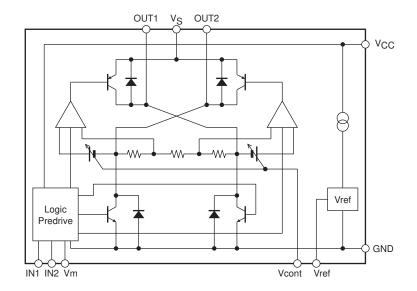




## **Pin Assignment**



# **Block Diagram**



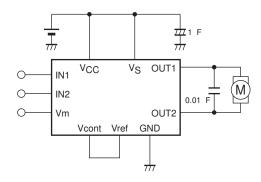
- The constant-voltage drive mode output voltage (the voltage between the output pins)  $V_O$  is determined by the following formula.  $V_O = (V_{CO} + V_{CO} + V_{CO$
- There are no restrictions on the relative magnitudes between the following voltages: V<sub>CC</sub> (control system supply voltage), VS (motor supply voltage), and IN1/IN2/Vm (the input signal voltages).

**Truth Table** 

Input		Output		M. I.		
IN1	IN2	Vm	OUT1	OUT2	Mode	
L	L	L	OFF	OFF	Standby	
Н	L	L	Н	L	Forward (Regulated)	
Н	L	Н	Н	L	Forward (Saturation)	
L	Н	L	L	Н	Reverse (Regulated)	
L	Н	Н	L	Н	Reverse (Saturation)	
Н	Н	*	L	L	Brake	

 $<sup>^{\</sup>star}$  when in saturation mode,  $V_C = VS$  available.

#### **Application Circuit Example**



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