Part Number

Step Angle

Frame Size

Current

Holding Torque

Resistance

Rotor Inertia

Connection

Weight

Number of Leads

Body Length (Dim. A)



WO-4118L-07P

1.89 in (48 mm)

2.1 Amps/Phase

0.37 oz-in²

Parallel

0.7 lbs (0.32 kg)

4

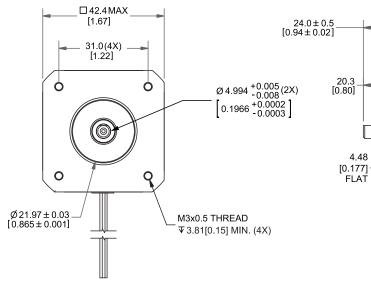
83 oz-in (0.59 Nm) 1.3 Ohms/Phase

1.8°

NEMA 17



DIMENSIONS



Torque (oz-in)

20.3 20.94±0.02] 20.3 [2.0] 20.3 [2.0] 4.48 [0.177] FLAT

PERFORMANCE CURVE

4118L-07P 24VDC, 2.1 Amps/Phase, Bipolar, 1/2 Stepping 70 0.5 60 Torque (N-m) 0.4 40 0.3 30 0.2 20 0.1 10 8000 14000 4000 10000 12000 Speed (pps) 10 20 25 35 40 Speed (rps)

OPERATING SPECIFICATIONS

Radial Play	0.001" max @ 1 lbs load
End Play	0.003" max @ 2 lbs load
Shaft Run Out	0.002" TIR
Concentricity of Mounting Pilot to Shaft	0.003" TIR
Perpendicularity of Shaft to Mounting Face	0.003" TIR
Max Axial Load	6 lbs
Maximum Case Temperature	80 C
Ambient Temperature	-20° to 50° C
Storage Temperature	-20° to 100° C
Humidity Range	85% or less, non-condensing
Magnet Wire Insulation	Class B 130° C
Insulation Resistance	100MΩ at 500 VDC
Dielectric Strength	500 VAC for 1 minute

WIRING TABLE

COLOR	FUNCTION
Red	A+ Phase
Blue	A- Phase
Green	B + Phase
Black	B- Phase

OPERATION & USAGE TIPS



Do not disassemble motors; a significant reduction in motor performance will occur.



Do not machine shafts; this will have a negative effect on shaft run out and perpendicularity.



Do not disconnect motor from drive while in operation.



Do not use holding torque/detent torque of motor as a fail safe brake.



Do not hold motor by lead wires.



Do not exceed the rated current; this will burn the motor.

FAILURE TO COMPLY WITH THESE RECOMMENDATIONS WILL VOID ALL WARRANTY TERMS

RECOMMENDED



Microstepping Driver R701P-RO



Single Axis Controller+Driver **R356**

Motion Control, Solved.

MOTOR ENGINEERING & MANUFACTURING







Small Batch to OEM Volume Production

