

# **Multifunction LCD Segment Driver**

## BU97930MUV MAX 108 segments (SEG27×COM4)

#### Features

- Integrated RAM for display data (DDRAM): 27 x 4 bit (Max 108 Segment)
- LCD drive output:
  - 4 Common output, Max 27 Segment output
- Integrated 1ch LED driver circuit
- Segment /GPO(Max 4port) output mode selectable
- Support PWM generation from ext. or internal clock (Resolution: 8bit)
- Support standby mode
- Integrated Power-on-Reset circuit (POR)
- Integrated Oscillator circuit
- No external component
- Low power consumption design
- Independent power supply for LCD driving
- Support Blink function (Blink frequency 1.6, 2.0, 2.6, 4.0Hz selectable)

#### Applications

- Telephone
- FAX
- Portable equipment (POS, ECR, PDA etc.)
- DSC
- DVC
- Car audio
- Home electrical appliance
- Meter equipment

etc.

### Key Specifications

■ Supply Voltage Range: +1.8V to +3.6V

■ LCD drive power supply Range: +2.7V to +5.5V

■ Operating Temperature Range: -40°C to +85°C

■ Max Segments: 108 Segments

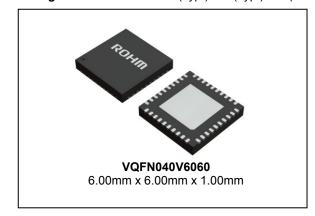
■ Display Duty: Static, 1/3, 1/4 selectable

■ Bias: Static, 1/3

■ Interface: 3wire serial interface

#### Package

W (Typ.) x D (Typ.) x H (Max.)



### ●Typical Application Circuit

LED/GPO using case

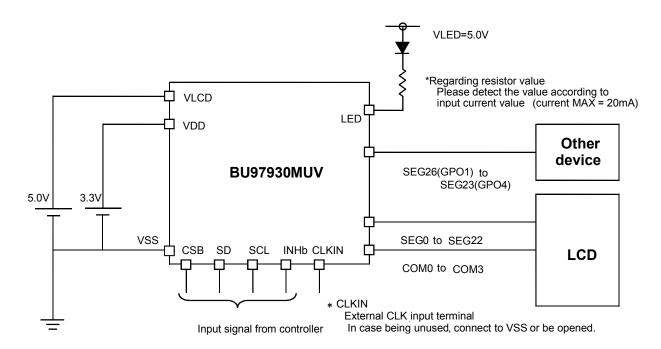


Figure 1. Typical application circuit

OProduct structure: Silicon monolithic integrated circuit OThis product is not designed for protection against radioactive rays.

### ●Block Diagram / Pin Configuration / Pin Description

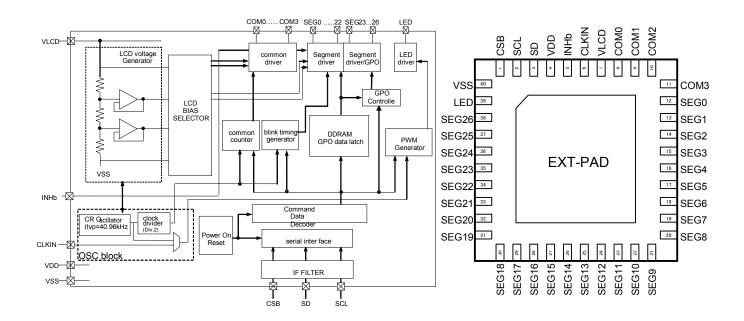


Figure 2. Block Diagram

Figure 3. Pin Configuration (BOTTOM VIEW)

Table 1 Pin Description

	I <u> </u>		T	in Description
Terminal	Terminal number	I/O	unused case	Function
CSB	1	I	-	Chip select: "L" active
SCL	2	-	-	Serial data transfer clock
SD	3	_	-	Input serial data
VDD	4	-	-	Power supply for LOGIC
CLKIN	6	I	OPEN / VSS	External clock input terminal (for display/PWM using selectable); Support Hi-Z input mode at internal clock mode
VSS	40	ı	-	GND
VLCD	7	-	-	Power supply for LCD
INHb	5	I	VDD	Display turning on/off select terminal H: turning on display, L: turning off display  INHb = "L": All SEG/COM terminals : output VSS level GPO terminal : output VSS level LED drive terminal : output Hi-Z
COM0 to 3	8 to 11	0	OPEN	COMMON output for LCD
SEG0 to 22	12 to 34	0	OPEN	SEGMENT output for LCD
SEG23 to 26	35 to 38	0	OPEN	SEGMENT output for LCD/GPO
LED	39	0	OPEN	LED driver output
EXT-PAD	-	-	VSS	substrate

### ● Absolute Maximum Ratings (VSS=0V)

Parameter	Symbol	Ratings	Unit	Remarks
Power supply voltage 1	VDD	-0.3 to +4.5	V	Power supply
Power supply voltage 2	VLCD	-0.5 to +7.0	V	Power supply for LCD
Power Dissipation	Pd	0.8*1	W	
Input voltage range	VIN	-0.5 to VDD+0.5	V	
Operational temperature range	Topr	-40 to +85	°C	
Storage temperature range	Tstg	-55 to +125	°C	
	lout1	5	mA	SEG output
Output current	lout2	5	mA	COM output
	lout3	10	mA	GPO output
	lout4	50	mA	LED output

When operated higher than Ta=25°C, subtract 8.0mW per degree. (using ROHM standard board) (board size: 74.2mm×74.2mm×1.6mm material: FR4 board copper foil: land pattern only).

### ■Recommended Operating Ratings(Ta=-40°C to +85°C,VSS=0V)

Parameter	Symbol	Ratings			Unit	Remarks	
Farameter	Symbol	MIN	TYP	MAX	Offic	Remarks	
Power supply voltage 1	VDD	1.8	-	3.6	V	Power supply	
Power supply voltage 2	VLCD	2.7	-	5.5	V	Power supply for LCD	
Output current	lout4	-	-	20	mA	Per LED port 1ch	

### Electrical Characteristics

DC characteristics (Ta=-40°C to +85°C, VDD=1.8V to 3.6V, VLCD=2.7V to 5.5V, VSS=0)

Parameter	Cumbal	Limit			Unit	Condition	
Parameter	Symbol	MIN	TYP	MAX	Offic	Condition	
"H" level input voltage	VIH	0.8VDD	-	VDD	V	SD, SCL, CSB, CLKIN, INHb	
"L" level input voltage	VIL	VSS	-	0.2VDD	V	SD, SCL, CSB, CLKIN, INHb	
Hysteresis width	VH	-	0.2	-	V	SCL, INHb, VDD=3.3V, Ta=25°C	
"H" level input current	IIH1	-	-	5	μΑ	SD, SCL, CSB, CLKIN, INHb, VI=3.6V	
"L" level input current	IIL1	-5	-	-	μΑ	SD, SCL, CSB, CLKIN, INHb, VI=0V	
	VOH1	VLCD -0.4	-	-	V	lload=-50μA, VLCD=5.0V SEG0 to SEG26	
"H" level output voltage (*2)	VOH2	VLCD -0.4	-	-	V	lload=-50μA, VLCD=5.0V, COM0 to COM3	
	VOH3	VLCD -0.6	-	-	V	lload=-1mA,VLCD=5.0V, SEG23 to SEG26(GPO mode)	
	VOL1	-	-	0.4	V	lload= 50µA, VLCD=5.0V, SEG0 to SEG26	
"L" level output voltage	VOL2	-	-	0.4	V	lload= 50μA, VLCD=5.0V, COM0 to COM3	
(*2)	VOL3	-	-	0.5	V	Iload=1mA, VLCD=5.0V, SEG23 to SEG26(GPO mode)	
	VOL4	-	0.11	0.5	V	lload=20mA, VLCD=5.0V, LED	
	IstVDD	-	3	10	μΑ	Input terminal ALL'L', Display off, Oscillation off	
	IstVLCD	-	0.5	5	μΑ	Input terminal ALL'L', Display off, Oscillation off	
	IVDD1	-	8	15	μΑ	VDD=3.3V, Ta=25°C, 1/3bias, fFR=64Hz, PWM generate off, All output pin open	
Current consumption (*1)	IVDD2	-	30	45	μΑ	VDD=3.3V, Ta=25°C, 1/3bias, fFR=64Hz, PWM Frequency=500Hz setting, All output pin open	
	IVLCD1	-	10	15	μΑ	VLCD=5.0V, Ta=25°C, 1/3bias, fFR=64Hz, LED generate off, All output pin open	
	IVLCD2	-	30	48	μΑ	VLCD=5.0V, Ta=25°C, 1/3bias, fFR=64Hz, PWM Frequency=500Hz setting, All output pin open	

<sup>\*1</sup> Power save mode 1 and frame inversion setting

<sup>\*2</sup> Iload: In this case, load current from only one port

### ● Electrical Characteristics – continued

Oscillation Frequency Characteristics (Ta=-40°C to +85°C, VDD=1.8V to 3.6V, VLCD=2.7V to 5.5V, VSS=0)

Parameter	Symbol	Limit			Unit	Condition	
Farameter	Symbol	MIN	MIN	MIN	Offic	Condition	
Frame frequency 1	fFR1	57.6	64	70.4	Hz	VDD=3.3V, Ta=25°C, fFR=64Hz setting	
Frame frequency 2	fFR2	51.2	64	73.0	Hz	VDD=2.5 to 3.6V fFR=64Hz setting	
Frame frequency 3	fFR3	45.0	-	64	Hz	VDD=1.8 to 2.5V fFR=64Hz setting	

MPU interface Characteristics (Ta=-40°C to +85°C, VDD=1.8V to 3.6V, VLCD=2.7V to 5.5V, VSS=0)

Doromotor	Cumbal	Limit			unit	Condition
Parameter	Symbol	MIN	TYP	MAX	uniit	Condition
Input rise time	tr	-	-	50	ns	
Input fall time	tf	-	-	50	ns	
SCL cycle time	tSCYC	250	-	-	ns	
"H" SCL pulse width	tSHW	50	-	-	ns	
"L" SCL pulse width	tSLW	50	-	-	ns	
SD setup time	tSDS	50	-	-	ns	
SD hold time	tSDH	50	-	-	ns	
CSB setup time	tCSS	50	-	-	ns	
CSB hold time	tCSH	50	-	-	ns	
"H" CSB pulse width	tCHW	50	-	-	ns	

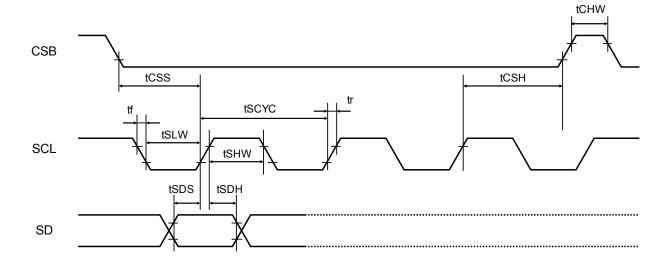


Figure 4. Serial interface timing

### ●I/O equivalent circuit

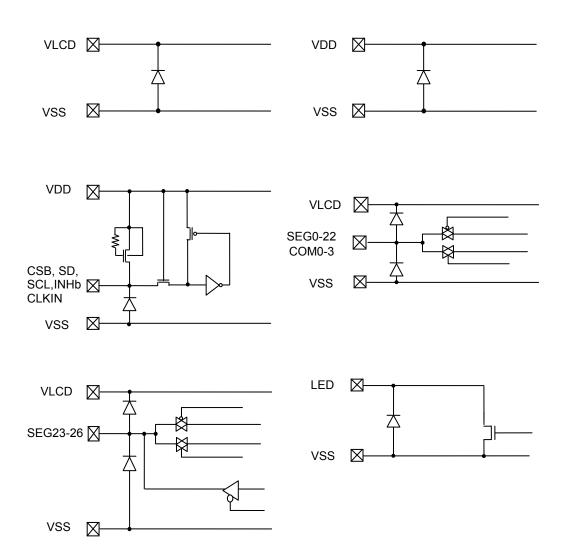
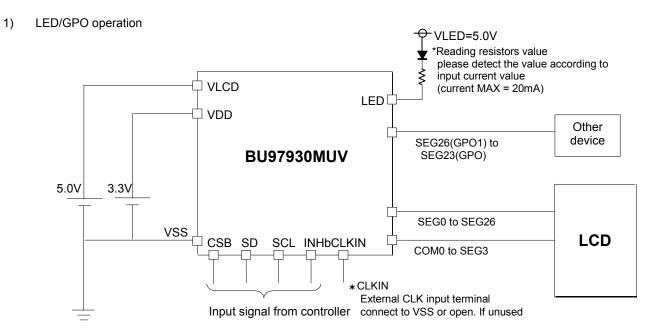


Figure 5. I/O equivalent circuit

### **BU97930MUV**

### ●Example of recommended circuit



#### SEG output only operation 2)

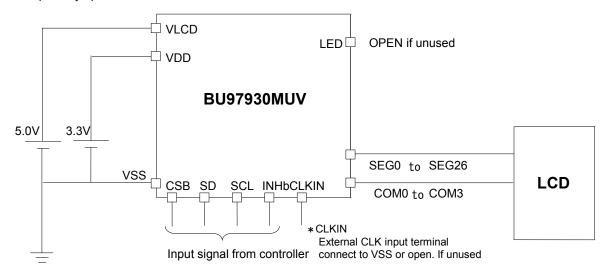


Figure 6. Example of Recommended Circuit

#### Function description

OCommand and data transfer method

O3-SPI (3-wire serial interface)

This device is controlled by a 3-wire signal (CSB, SCL, and SD).

First. Interface counter is initialized with CSB="H".

Setting CSB="L", enables SD and SCL inputs.

The protocol of 3-SPI transfer is as follows.

Each command starts with Command or Data judgment bit (D/C) as MSB data,

followed by data D6 to D0 (this is when CSB ="L").

(Internal data is latched at the rising edge of SCL, serial data is converted to an 8-bit parallel data at the falling edge of the 8th CLK.)

When CSB changes from "L" to "H", and at this time serial commands are less than 8 bits, command and data transfers are cancelled. To start sending command again, please set CSB="L" and send command continuously.

After sending RAMWR or BLKWR or GPOSET command, this device is in the RAM data input mode. Under this mode, device can not accept new commands.

In this case, execute a "H" to "L" transition at CSB, after this sequence, the device is released from RAM data input mode, and can accept new command.

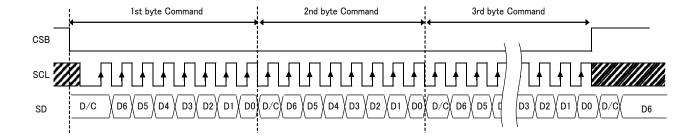


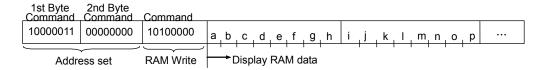
Figure 7. 3-SPI Data transfer Format

- \* 8-bit data, sending after RAMWR command, are display RAM data
- \* 8-bit data, sending after BLKWR command, are blink RAM data
- \* SCL and SD can be set to "H" or cleared to "L" during CSB="H".

OWrite display data and transfer method

This device has Display Data RAM (DDRAM) of 28×4=112bit.

The relationship between data input and display data, DDRAM data and address are as follows.



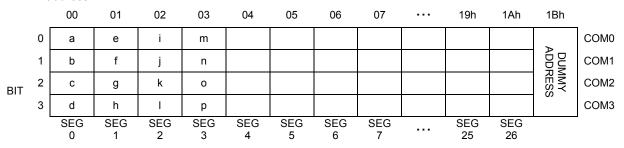
According to this command, an 8-bit binary data will be written to the DDRAM. The starting address of the DDRAM where data will be written is specified by "ADSET" command, and is automatically incremented for every 4 bits of data received..

Writing data to DDRAM can be done by continuously sending data.

(In case data is sent continuously after write date at 1Ah (SEG26), RAM data will be written to 1Bh (dummy address) and return to address 00h (SEG0) automatically.)

In case SEG port assigned to GPO port by OUTSET command, corresponding SEG address do not change and used as dummy address.

### DDRAM address



Display data write to DDRAM every 4 bits.

In case CSB changes from "L" to "H" before 4 bits of data transfer was finished, RAM write is cancelled.

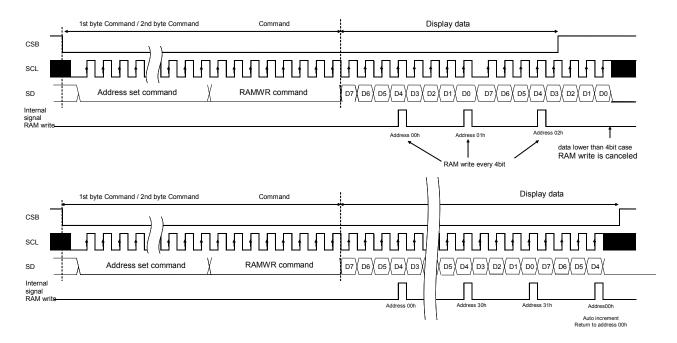


Figure 8. Display Data Transfer Method

#### OBlink function

This device has Blink function. Blink function can set each segment port individually.

Blink ON/OFF and Blink frequency are set by the BLKSET command.

Blink frequency varies according to fCLK characteristics.

Blink setup of each segment is controlled by BLKWR command.

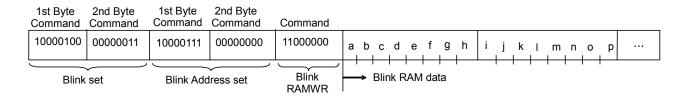
The write start address is specified by "BLKADSET" command. And this address will automatically increment every 4 bits of blink data received. The relation of BLKWR command, blink ram data, and blinking segment port is below.

In case data is "1", segment will blink, on the other hand when data is "0", segment will not blink.

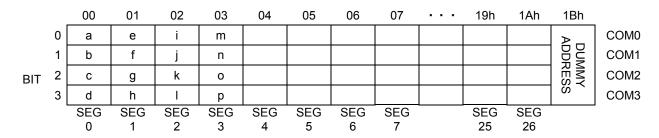
(In case data is written continuously after write data at 1Ah (SEG26), RAM data will be written to 1Bh (dummy address) and return to address 00h (SEG0) automatically.)

Please refer to the following figures about Blink operation of each segment.

In case SEG port assigned to GPO port by OUTSET command, corresponding SEG address does not change and used as dummy address.



#### Blink RAM address



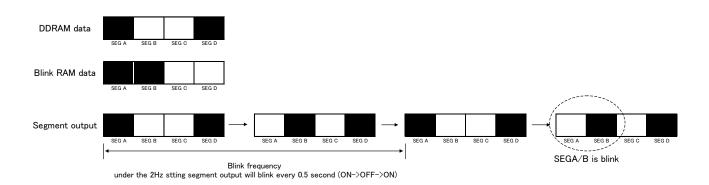


Figure 9. Blink Operation

OLCD Driver Bias/Duty Circuit

BU97930MUV generates LCD driving voltage using an on-chip Buffer AMP.

Also, it can drive LCD with low power consumption

\*Line and frame inversion can be set by MODESET command.

\*1/4duty, 1/3duty and static mode can be set by DISCTL command.

About each LCD driving waveform, please refer to "LCD driving waveform" descriptions.

### Olnitial state

Initial state after SWRST command input

- oDisplay off
- oAll command register values are in Reset state.
- oDDRAM address data and Blink address data are initialized

(DDRAM data and Blink RAM data are not initializing.

Please write DDRAM data and Blink RAM data before Display on.)

### ●Command / Function list

### **Function description table**

NO	Command	Function
1	Mode Set (MODESET)	Sets LCD drive mode (display on/off, current mode)
2	Display control (DISCTL)	Sets LCD drive mode (frame freq., line/frame inversion)
3	Address set (ADSET)	Sets display data RAM address for RAMWR command
4	Blink set (BLKSET)	Sets Blink mode on/off
5	Blink address set (BLKADSET)	Sets Blink data RAM address for BLKWR command
6	SEG/GPO port change (OUTSET)	Selects segment output/general purpose output (GPO)
7	LED drive control (PWMSET) (H piece adjustment of PWM)	Sets PWM1 signal "H" width for LED driving
8	RAM WRITE (RAMWR)	Writes display data to display data RAM
9	Blink RAM WRITE (BLKWR)	Writes Blink data to BLINK data RAM
10	All Pixel ON (APON)	Sets all Pixel display on
11	All Pixel OFF (APOFF)	Sets all Pixel display off
12	All Pixel On/Off mode off (NORON)	Sets normal display mode (APON/APOFF cancel)
13	Software Reset (SWRST)	Software Reset
14	OSC external input (OSCSET)	Enables External clock input
15	GPO output set (GPOSET)	Sets GPO output data

### Command Descriptions

D/C, Data / Command judgment bit (MSB) For more details, please refer to 3wire serial I/F

### OMode Set (MODESET)

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte command	1	0	0	0	0	0	0	1	81h	-
2nd byte command	0	0	0	0	P3	P2	P1	P0	-	00h

Display Set

Condition	P3	Reset state
Display OFF	0	0
Display ON	1	

**MSB** 

Display OFF: No LCD driving mode (Output: VSS Level)

Turn off OSC circuit and LCD power supply circuit. (Synchronized with frame freq)

LSB

Display ON: LCD driving mode

Turn on OSC circuit and LCD power supply circuit. Read data from DDRAM and display to LCD.

LED port and GPO port output states are not affected by a Display on/off state

Output state is determined by command setup (OUTSET GPOSET, PWMSET) and INHb terminal state, respectively. For more details, please refer to each command description.

#### LCD drive mode set

Condition	P2	Reset state
Frame inversion	0	0
Line inversion	1	

### Current mode set

Condition	P1	P0	Reset state
Power save mode1	0	0	0
Power save mode2	0	1	
Normal mode	1	0	
High power mode	1	1	

<sup>\*</sup> Please supply the VLCD voltage larger than 3V at High power mode.

(Reference data of consumption current)

Condition	Current consumption
Power save mode 1	×1.0
Power save mode 2	×1.7
Normal mode	×2.7
High power mode	×5.0

<sup>\*</sup> The value changes according to the panel load.

### ODisplay control (DISCTL)

**MSB** 

LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	0	1	0	82h	-
2nd byte Command	0	0	0	0	P3	P2	P1	P0	-	02h

Duty set

<u> </u>			
Condition	P3	P2	Reset state
1/4duty (1/3bias)	0	0	0
1/3duty (1/3bias)	0	1	
Static (1/1bias)	1	*	

<sup>\*:</sup> Don't care

In 1/3 duty, Display data and Blink data of COM3 are ineffective. COM1 and COM3 output are same data.

Please be careful in transmitting display data and blink data.

The examples of SEG/COM output waveform, under each Bias/Duty set up, are shown at "LCD Driver Bias/Duty Circuit" description.

Frame frequency set

Condition (1/4,1/3,1/1duty)	P1	P0	Reset state
(128Hz, 130Hz, 128Hz)	0	0	
(85Hz, 86hz, 64Hz)	0	1	
(64Hz, 65Hz, 48Hz)	1	0	0
(51Hz, 52Hz, 32Hz)	1	1	

Relation table, between Frame frequencies (FR), integrated oscillator circuit (OSC) and Divide number.

<u> </u>									
DISCTL (P1,P0)		Divide		FR [Hz] ( * 1)					
	Di	uty set (P3,P	2)	Duty set (P3,P2)					
	(0,0) 1/4duty	(0,1) 1/3duty	(1, * ) 1/1duty	(0,0) 1/4duty	(0,1) 1/3duty	(1, * ) 1/1duty			
(0,0)	160	156	160	128	131.3	128			
(0,1)	240	237	320	85.3	86.4	64			
(1,0)	320	315	428	64	65	47.9			
(1,1)	400	393	640	51.2	52.1	32			

<sup>\*1:</sup> FR is frame frequency, in case OSC frequency = 20.48KHz (typ).

The Formula, to calculate OSC frequency from Frame frequency is shown below.

"OSC frequency = Frame frequency (measurement value) x Divide number "Divide number : Please determine by using the value of Frame Frequency Set (P1,P0) and duty setting (P3,P2).

Ex) (P1,P0) = (0,1), (P3,P2) = (0,1) => Divide number = 237

### OAddress set (ADSET)

MSB
-----

LSB

MSB	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	0	1	1	83h	
2nd byte Command	0	0	0	P4	P3	P2	P1	P0	-	00h

Set start address to write DDRAM data.

The address can be set from 00h to 1Ah. (Address 1Bh is used at dummy address)

Do not set other addresses. (Except 00h to 1Bh address is not acceptable.)

In case writing data to DDRAM, make sure to send RAMWR command.

### OBlink set (BLKSET)

**MSB** 

LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	1	0	0	84h	-
2nd byte Command	0	0	0	0	0	P2	P1	P0	-	00h

Set Blink ON/OFF.

For more details, please refer to "Blink function".

#### Blink set

Blink mode(Hz)	P2	P1	P0	Reset state
OFF	0	0 / *	0 / *	0
1.6	1	0	0	
2.0	1	0	1	
2.6	1	1	0	
4.0	1	1	1	

<sup>\*:</sup> Don't care

### OBlink address set (BLKADSET)

MSB

LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	1	1	1	87h	ı
2nd byte Command	0	0	0	P4	P3	P2	P1	P0	-	00h

Set Blink data RAM start write address.

The address can be set from 00h to 1Ah. (Address 1Bh is used at dummy address)

Do not set other addresses. (Except 00h to 1Bh address is not acceptable.)

In case writing data to Blink RAM, make sure to send BLKWR command

### OSEG/GPO port change (OUTSET)

**MSB** 

LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	1	0	0	0	88h	-
2nd byte Command	0	0	0	0	0	P2	P1	*	-	00h

Set output mode, Segment output or GPO output.

P2 to P0: Select changing port number. (SEG23 to SEG26 ports are SEG mode/GPO mode selectable)

In case GPO output is selected, Terminal output data is set by GPOSET command.

Ex) In case SEG 26 port assigned to GPO,

If GPO1 data is "H", GPO1 (SEG26) port outputs "H" (VLCD Level).

If GPO1 data is "L", GPO1 (SEG26) port outputs "L" (VSS level).

Output terminal state under the P2 to P0 set condition is listed below

**Output Terminal state** 

	Conditio	n	SEG T	SEG Terminal state (SEG output/GPO output)							
P2	P1	P0	SEG23 port	SEG24 port	SEG25 port	SEG26 port					
0	0	*	SEG23	SEG24	SEG25	SEG26					
0	1	0	SEG23	SEG24	SEG25	GPO1					
0	1	1	SEG23	SEG24	GPO2	GPO1					
1	0	0	SEG23	GPO3	GPO2	GPO1					
1	0	1	GPO4	GPO3	GPO2	GPO1					
1	1	*	(C	(OUTSET command will be canceled)							

In case SEG port is switched to the GPO port, DDRAM address and Blink RAM address do not change. In this case DDRAM address and Blink RAM address, selected GPO output mode is dummy address.

The output state of GPO and LED port under the INHb H/L, display on/off, and RESET state are listed below.

Control nort	INI	Hb	DISF	PLAY	DESET state	
Control port	Н	H L		OFF	RESET state	
GPO	According to GPOSET command	Low Fix	According to GPOSET command	According to GPOSET command	GPO unselected (All SEG output)	
LED	According to PWMSET command	Hi-Z	According to PWMSET command	According to PWMSET command	LED unselected (All SEG output)	

OLED drive-control (PWM "H" width control) command (PWMSET)

	INIOD				LOB					
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	1	0	1	0	8Ah	-
2nd byte Command	0	0	0	0	0	0	P7	P6	-	00h
3rd byte Command	0	0	P5	P4	P3	P2	P1	P0	-	00h

LOD

2nd and 3rd byte command data are able to set from 00h to 3Fh (described as 8bit binary data).

In case other value is selected, sending command is ignored, and 2nd and 3rd byte command data is set to 3Fh. In default state, 2nd and 3rd byte command data are set to 00h.

In case command is less than 3 bytes, sending command is cancelled.

According to PWMSET command, LED driving signal is adjustable. PWM "H" width is adjustable by 8-bit resolution.

Explanation about P7 to P6 data of 2nd byte command and P5 to P0 data of 3rd byte command are as follows: (The 2nd byte data are used as upper 2bit, and 3rd byte data are used as lower 6 bits.)

8bit mode: P7 data is used as MSB of 8 bits, and P0 data is used LSB.

LED driving period is decided by the "H" width of PWM signal, generated by PWM generator circuit (resolution: 8 bits).

Ex)

In case, external PWM clock 125KHz, parameter setting value is 127 (7Fh)

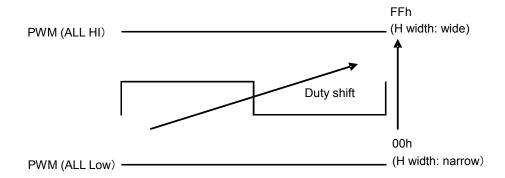
1-bit resolution: 8us

ALL HI set: PWM signal frequency about 500Hz, H width about 2.00msec

ALL LOW set: PWM signal frequency about 500Hz, H width 0usec (in case 8-bit resolution)

This command is reflected, synchronizing with a next PWM frame head.

And, LED port output is as follows. LED port operation does not affect Display ON/OFF state.



(\*) About the PWM frequency and PWM "H" width calculation.

PWM cycle and PWM "H" width, decided by PWM clock cycle are described as follows: (PWM clock cycle is a minimum unit of PWM "H" width)

PWM frequency = PWM clock cycle × (Number of the steps (8bit =256) - 1 ) PWM H width = PWM clock cycle × Parameter set value (8bit: 0 to 255)

PWM Duty = PWM H width/PWM cycle = Parameter set value / Number of the steps

In case PWM is generated from internal clock, the PWM cycle varies according to OSC frequency.

### **ORAM WRITE (RAMWR)**

MSB							LSB
D/C	D6	D5	D4	D3	D2	D1	D0

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	1	0	0	0	0	0	A0h	-
2nd byte Command				Random						
n byte Command					Random					

Input data, sending after 1st byte command, are used as Display data. And display data are sent every 4 bits. Please set this command after the ADSET command.

### **OBlink RAM WRITE (BLKWR)**

MSB				LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	1	0	0	0	0	0	0	C0h	-
2nd byte Command				Random						
n byte Command				Random						

Input data, sending after 1st byte command, are used as Display data. And display data are sent every 4 bits. Please set this command after the BLKADSET command.

### OAII Pixel ON (APON)

MSB				LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	0	1	91h	-

After sending the command, all SEG outputs set display on state regardless of the DDRAM data. (This command affects the SEG output terminals only (except GPO and LED output)

### OAII Pixel OFF (APOFF)

MSB	LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	0	0	90h	-

After sending the command, all SEG outputs set display off state regardless of the DDRAM data. (This command affects the SEG output terminals only (except GPO and LED output)

### OAII Pixel ON/OFF mode off (NORON)

### MSB LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	1	1	93h	-

After sending the command, all SEG outputs are released from APON/APOFF state.

And SEG port output signal follows DDRAM data.

(This command affects the SEG output terminals only (except GPO and LED output)

After reset sequence or SWRESET, all outputs set NORON state.

### OSoftware Reset (SWRST)

MSB	LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	1	0	92h	-

After sending the command, device is set to default state.

OOSC external input command (OSCSET)

MSB				LSB						
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	1	0	0	0	98h	-
2nd byte Command	0	0	0	0	0	P2	P1	P0	-	00h

Sets the type of clock mode. There are 4 selectable modes including external clock input mode. Details of this command function are as follows.

Condition	P2	P1	P0	Reset state
Internal CLK (PWM generation OFF)	0	0	0	0
External CLK input for PWM (PWM generation OFF)	0	0	1	
Internal CLK (PWM generation ON)	0	1	0	
External CLK input for PWM (PWM generation ON)	0	1	1	
External CLK input for Display (ROHM use only)	1	*	*	

(\*: Don't care)

(P2,P1,P0)=(0,0,1): External PWM input mode

CLKIN: external PWM input available.

PWMOUT: "L" Output

\*under the (P2,P1,P0)=(0,0,0) condition PWMOUT into same state

(P2,P1,P0)=(0,1,0): PWM is generated from an internal oscillating frequency

(P2,P1,P0)=(0,1,1): PWM is generated from an External CLK input CLKIN PWM width is set by PWMSET command.

The relation of OSC function control by each command is as follows:

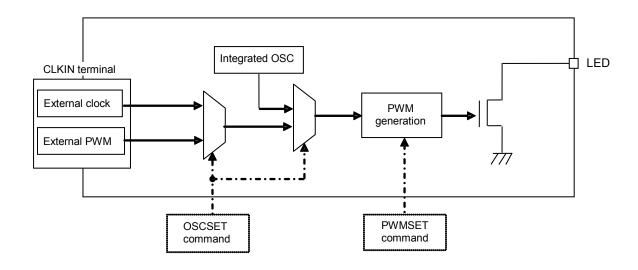


Figure 10. OSC External Input

### OGPO output set command (GPOSET)

MS

LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	1	0	1	0	9Ah	-
2nd byte Command	0	0	0	P4	P3	P2	P1	0	-	00h

<sup>(\*:</sup> Don't care)

Set GPO output data. The relation between SEG port (GPO port) and data is shown below.

GPOSET data	GPO port	SEG port
P1	GPO1	SEG26
P2	GPO2	SEG25
P3	GPO3	SEG24
P4	GPO4	SEG23

GPO data output is asynchronous from frame cycle.

In case INHb="H", GPO output signal follows GPOSET data, on the other hand, in case INHb="L" GPO output is GND level. GPO output is not affected by Display ON/OFF state.

### ●LCD driving waveform

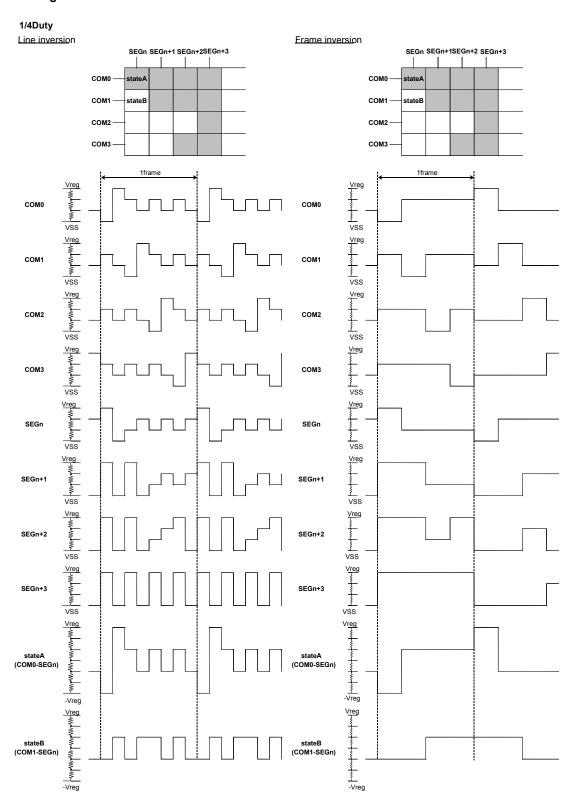


Figure 11. Waveform of Line Inversion

Figure 12. Waveform of Frame Inversion

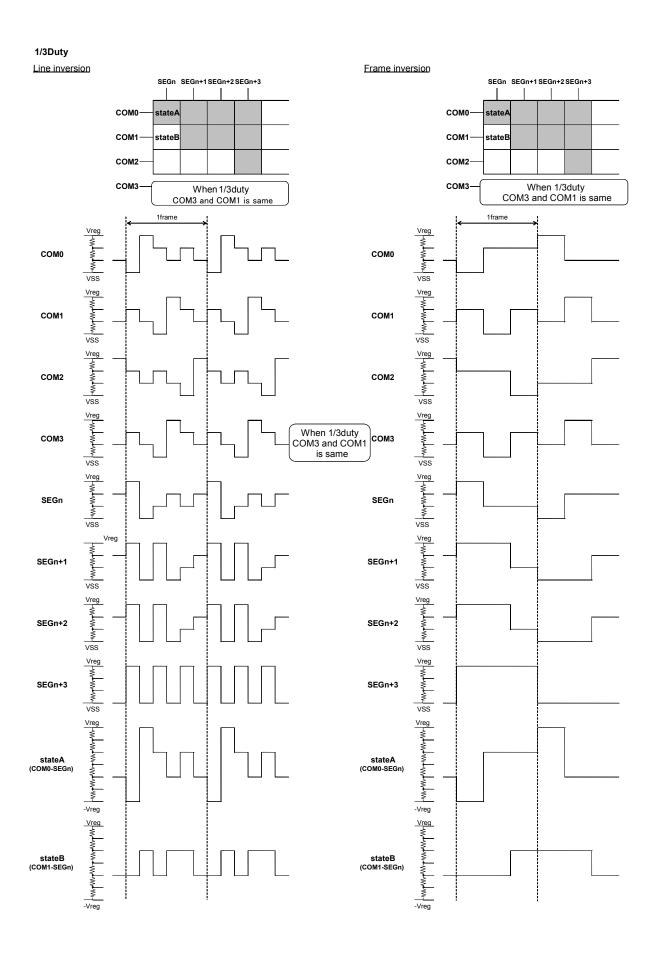


Figure 13. Waveform of Line Inversion

Figure 14. Waveform of Frame Inversion

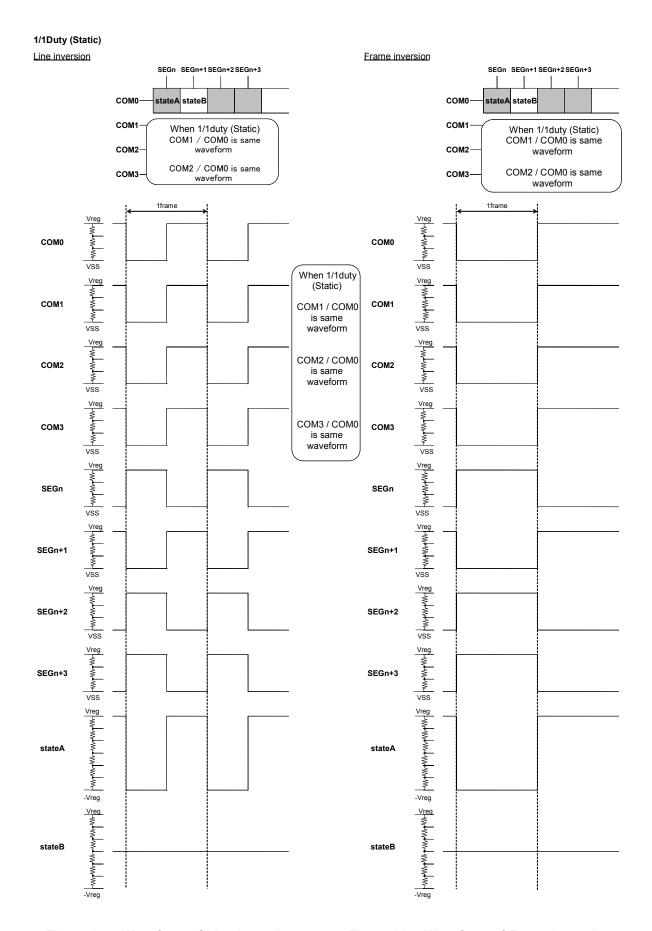


Figure 15. Waveform of Line Inversion

Figure 16. Waveform of Frame Inversion

### ●Initialize Sequence

Recommended input sequence is listed below, before starting LCD driving. (Refer to Power ON/OFF sequence)

Input voltage supply

CSB 'H' ...interface initializing

CSB 'L' ...interface command sending

SWRESET ...software reset

MODESET ...Display off

Various commands setting

RAM WRITE

Blink RAM WRITE

MODESET ...Display on

Start LCD driving

<sup>\*</sup>Before initializing sequence, DDRAM address, DDRAM data, Blink address and Blink data are random.

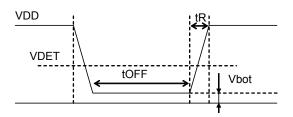
#### ● Cautions on Power-On/ Power-Off condition

#### **OPOR** circuit

BU97930MUV has "P.O.R" (Power-On Reset) circuit and Software Reset function. Please follow the recommended Power-On conditions in order to power up properly.

1, Please set power up conditions, follow the recommended tR, tF, tOFF, and Vbot specification below in order to ensure P.O.R operation.

(\*The detection voltage of POR varies because of environment, etc. To operate POR, please satisfy Vbot lower than 0.5V condition.)



Recommended condition of tR, tF, tOFF, Vbot

tR	tOFF	Vbot	VDET
less than	Over	less than 0.5V	TYP
10ms	1ms		1.2V

\* VDET : POR detect level

Figure 17. Power ON/OFF Waveform

- 2, If it is difficult to meet the above conditions, execute the following sequence after Power-On.
  - (1) CSB="L"→"H" condition
  - (2) After CSB"H"→"L", execute SWRST command.

In addition, in order to the SWRST command certainly, please wait 1ms after a VDD level reaches to 90% and CSB="L" $\rightarrow$ "H".

\*Before SWRST command, input device will be in unstable state, since SWRST command does not operate perfect substitution of a POR function.

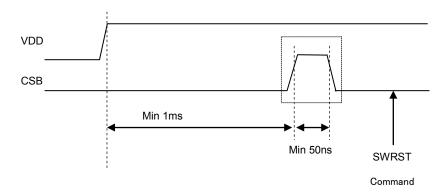


Figure 18. SWRST Command Sequence

### ●Power ON / OFF sequence

Display ON/OFF control by INHb terminal is not asynchronous with frame cycle.

To prevent incorrect display, malfunction and abnormal current,

VDD must be turned on before VLCD in power up sequence.

VDD must be turned off after VLCD in power down sequence.

Please set INHb terminal ="L" during Power ON/OFF sequence.

Please satisfies VLCD Please satisfies VLCD≥VDD, t1>0ns, t2>0ns

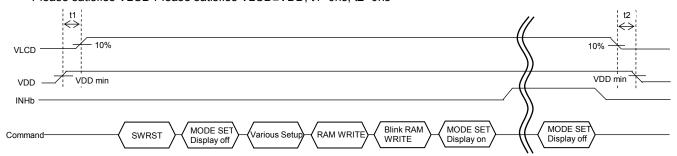


Figure 19. Power On/Off Sequence

### Notes on pull down resistor usage

Satisfy the following sequence if input terminals are pulled down by external resistors (In case MPU output Hi-Z).

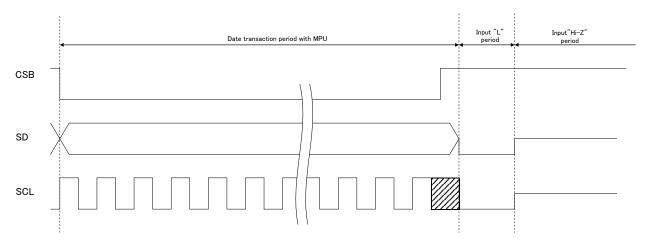


Figure 20. Recommended sequence when input ports are pulled down

BU97930MUV adopts a 5V tolerant I/O for the digital input. This circuit includes a bus-hold function to keep HIGH level. A pull down resistor of below  $10K\Omega$ shall be connected to the input terminals for transitions from HIGH to LOW because the bus-hold transistor turns on during the input's HIGH level. (Refer to the Figure 5; I/O Equivalent Circuit)

A higher resistor than  $10K\Omega$  (approximate) causes input terminals being steady by intermediate potential between HIGH and LOW level so unexpected current is consumed by the system.

The potential depends on the pull down resistance and bus-hold transistor's resistance.

As the bus-hold transistor turns off upon the input level is cleared to LOW, a higher resistor can be used as a pull down resistor if MPU sets SD and SCL lines to LOW before it releases the lines.

The LOW period preceding MPU's bus release shall be at least 50ns as same as a minimum CLK width (tSLW).

### Operational Notes (1) Absolute maximum ratings

Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

### (2) Recommended operating conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

### (3) Reverse connection of power supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply terminals

#### (4) Power supply lines

Design the PCB layout pattern to provide low impedance ground and supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

#### (5) Ground Voltage

The voltage of the ground pin must be the lowest voltage of all pins of the IC at all operating conditions. Ensure that no pins are at a voltage below the ground pin at any time, even during transient condition.

#### (6) Short between pins and mounting errors

Be careful when mounting the IC on printed circuit boards. The IC may be damaged if it is mounted in a wrong orientation or if pins are shorted together. Short circuit may be caused by conductive particles caught between the pins.

### (7) Operation under strong electromagnetic field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

#### (8) Testing on application boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

### (9) Regarding input pins of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the GND voltage should be avoided. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input terminals have voltages within the values specified in the electrical characteristics of this IC.

### (10) GND wiring pattern

When using both small-signal and large-current GND traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the GND traces of external components do not cause variations on the GND voltage. The power supply and ground lines must be as short and thick as possible to reduce line impedance.

#### (11) External Capacitor

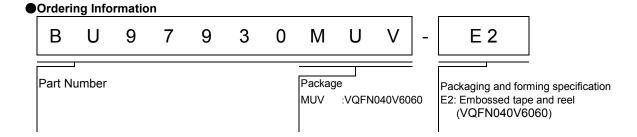
When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

### (12) Unused input terminals

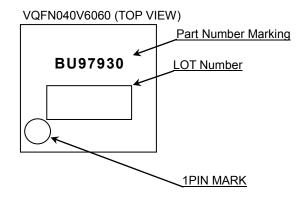
Input terminals of an IC are often connected to the gate of a CMOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of IC. So unless otherwise specified, input terminals not being used should be connected to the power supply or ground line.

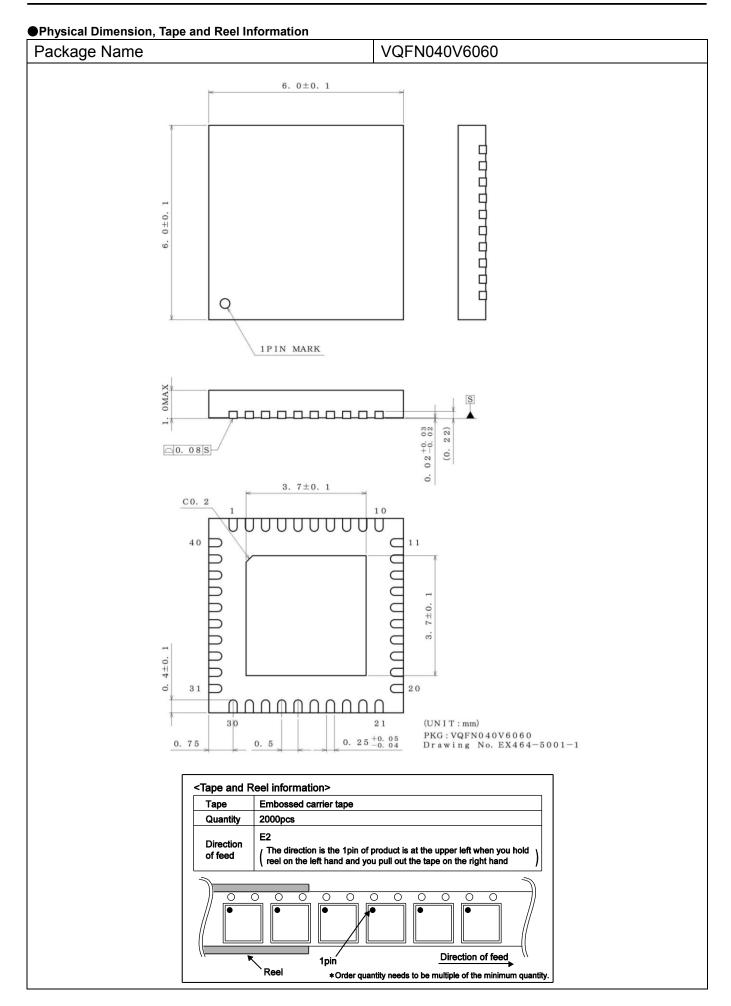
### (13) Rush current

When power is first supplied to the IC, rush current may flow instantaneously. It is possible that the charge current to the parasitic capacitance of internal photo diode or the internal logic may be unstable. Therefore, give special consideration to power coupling capacitance, power wiring, width of GND wiring, and routing of connections.



### Marking Diagram





### Revision History

Date	Revision	Changes				
14.Mar.2012	001	New Release				
8.Jan.2013	002	Improved the statement in all pages. Deleted "Status of this document" in page 26. Changed format of Physical Dimension, Tape and Reel Information.				
26.Jan.2015	003	Add the condition when power supply in page 24.				
10.Apr.2015	004	Modified figure of Power On/Off Sequence in page 24.				

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