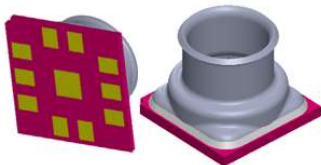


## MEMS pressure sensor: 260-1260 hPa absolute digital output barometer with embedded temperature sensor in water-resistant package



**CCLGA 10L**  
2.7 x 2.7 x 1.7 mm

### Features

- Pressure sensor with water-resistant package
- Potting gel and grounded metal cap
- 260 to 1260 hPa absolute pressure range
- Current consumption down to 4  $\mu$ A
- Absolute pressure accuracy: 0.5 hPa
- Low pressure sensor noise: 0.7 Pa
- Temperature accuracy:  $\pm 1.5$  °C
- Embedded temperature compensation
- 24-bit pressure data output
- ODR from 1 Hz to 200 Hz
- SPI, I<sup>2</sup>C or MIPI I3C<sup>SM</sup> interfaces
- Embedded FIFO
- Interrupt functions: Data-Ready, FIFO flags, pressure thresholds
- Supply voltage: 1.7 to 3.6 V
- **ECOPACK** lead-free compliant

### Applications


- Altimeters and barometers for portable devices
- GPS applications
- Weather station equipment
- [Sport watches](#)
- e-cigarettes
- Water depth monitoring
- [Gas metering](#)

### Description

The **LPS27HHTW** is an ultra-compact piezoresistive absolute pressure sensor which functions as a digital output barometer. The device also embeds a temperature sensor to monitor ambient temperature. The LPS27HHTW comprises a sensing element and an IC interface which communicates through I<sup>2</sup>C, MIPI I3C<sup>SM</sup> or SPI from the sensing element to the application.

The sensing element, which detects absolute pressure, consists of a suspended membrane manufactured using a dedicated process developed by ST.

The LPS27HHTW is available in a ceramic LGA package with metal lid. It is guaranteed to operate over a temperature range extending from -40 °C to +85 °C. The package is holed to allow external pressure to reach the sensing element. Gel inside the IC protects the electrical components from water and the metal cap is grounded electrically for better ESD robustness.

Product status link	
<a href="#">LPS27HHTW</a>	
Product summary	
Order code	LPS27HHTWTR
Temp. range [°C]	-40 to +85°C
Package	CCLGA-10L
Packing	Tape and reel
Product label	
	

# 1 Block diagrams

Figure 1. Device architecture block diagram

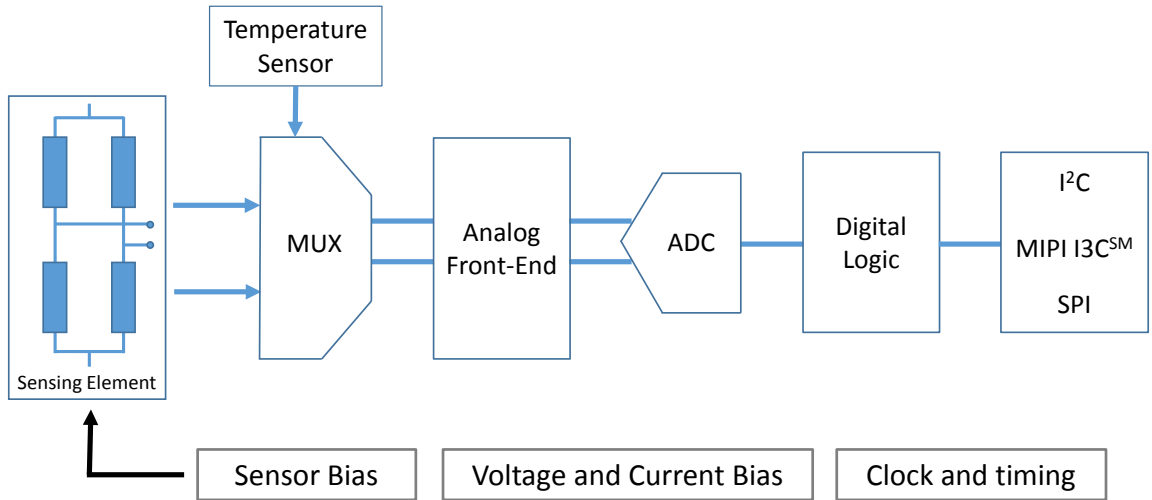
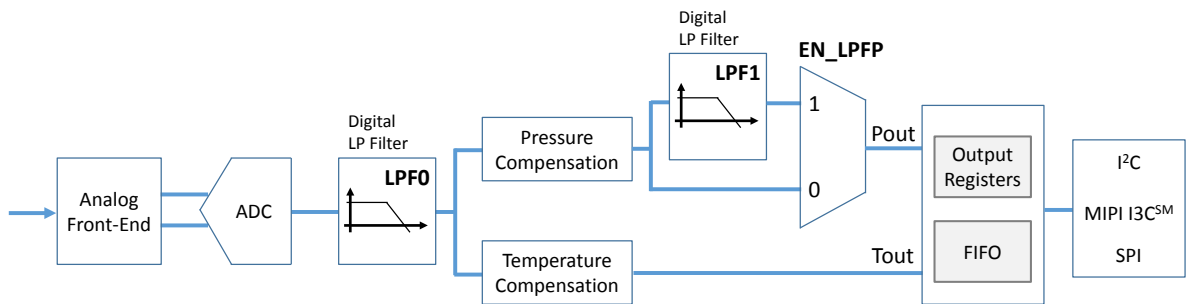


Figure 2. Digital logic



## 2 Pin description

Figure 3. Pin connections (bottom view)

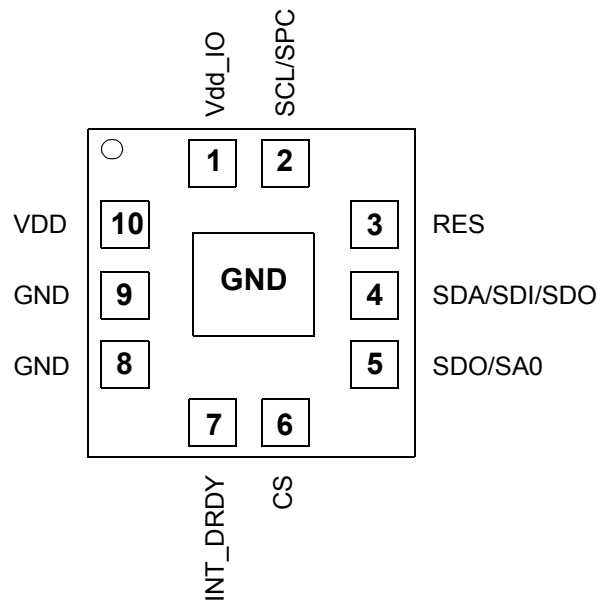


Table 1. Pin description

Pin number	Name	Function
1	Vdd_IO	Power supply for I/O pins
2	SCL SPC	I <sup>2</sup> C / MIPI I3C <sup>SM</sup> serial clock (SCL) SPI serial port clock (SPC)
3	Reserved	Connect to GND
4	SDA SDI SDI/SDO	I <sup>2</sup> C / MIPI I3C <sup>SM</sup> serial data (SDA) 4-wire SPI serial data input (SDI) 3-wire serial data input/output (SDI/SDO)
5	SDO SA0	4-wire SPI serial data output (SDO) I <sup>2</sup> C least significant bit of the device address (SA0) MIPI I3C <sup>SM</sup> least significant bit of the static address (SA0)
6	CS	SPI enable I <sup>2</sup> C and MIPI I3C <sup>SM</sup> / SPI mode selection (1: SPI idle mode / I <sup>2</sup> C and MIPI I3C <sup>SM</sup> communication enabled; 0: SPI communication mode / I <sup>2</sup> C and MIPI I3C <sup>SM</sup> disabled)
7	INT_DRDY	Interrupt or Data-Ready
8	GND	0 V supply
9	GND	0 V supply
10	VDD	Power supply

## 3 Mechanical and electrical specifications

### 3.1 Mechanical characteristics

VDD = 1.8 V, T = 25 °C, unless otherwise noted.

**Table 2. Pressure and temperature sensor characteristics**

Symbol	Parameter	Test condition	Min.	Typ. <sup>(1)</sup>	Max.	Unit
<b>Pressure sensor characteristics</b>						
P <sub>T<sub>op</sub></sub>	Operating temperature range		-40		+85	°C
P <sub>op</sub>	Operating pressure range		260		1260	hPa
P <sub>bits</sub>	Pressure output data			24		bits
P <sub>sens</sub>	Pressure sensitivity			4096		LSB/hPa
P <sub>AccRel</sub>	Relative accuracy over pressure <sup>(2)</sup>	P = 800 - 1100 hPa, T = 25 °C		±0.025		hPa
P <sub>AccT</sub>	Absolute accuracy over temperature	P = 860 ~ 1160 hPa, T = 25 ~ 65°C		±0.5		hPa
		P = 260 ~ 1260 hPa, T = 0 ~ 65 °C		±1		
P <sub>noise</sub>	RMS pressure sensing noise <sup>(3)</sup>	with embedded filter and at T = 25 °C		0.007		hPa RMS
ODR <sub>Pres</sub>	Pressure output data rate <sup>(4)</sup>			1		Hz
				10		
				25		
				50		
				75		
				100		
200						
TCO	Temperature coefficient offset	P = 860 ~ 1160 hPa, T = -20 ~ +65 °C		0.75		Pa/°C
P <sub>longterm</sub>	Pressure accuracy, long-term stability			1		hPa/year
P <sub>drift</sub>	Soldering drift			±0.5		hPa
<b>Temperature sensor characteristics</b>						
T <sub>op</sub>	Operating temperature range		-40		+85	°C
T <sub>acc</sub>	Temperature absolute accuracy	25 ~ 65 °C		±1.5		°C
T <sub>sens</sub>	Temperature sensitivity			100		LSB/°C
ODR <sub>T</sub>	Temperature output data rate			1		Hz
				10		
				25		
				50		
				75		
				100		
200						

1. Typical specifications are not guaranteed.
2. By design, the typ. value is defined based characterization data with 10 hPa pressure interval.
3. Pressure noise RMS evaluated in a controlled environment, based on the average standard deviation of 50 measurements with LOW\_NOISE\_EN = 1, EN\_LPFP = 1, LPFP\_CFG = 1.
4. Output data rate is configured acting on ODR[2:0] in CTRL\_REG1 (10h).

### 3.2 Electrical characteristics

VDD = 1.8 V, T = 25 °C, unless otherwise noted.

**Table 3. Electrical characteristics**

Symbol	Parameter	Test condition	Min.	Typ. <sup>(1)</sup>	Max.	Unit
VDD	Supply voltage		1.7		3.6	V
Vdd_IO	IO supply voltage		1.7		Vdd+0.1	V
Idd	Supply current	@ ODR 1 Hz LOW_NOISE_EN = 0		4		µA
		@ ODR 1 Hz LOW_NOISE_EN = 1		12		
IddPdn	Supply current in power-down mode			0.9		µA

1. Typical specifications are not guaranteed.

**Table 4. DC characteristics**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Unit
<b>DC input characteristics</b>						
Vil	Low-level input voltage (Schmitt buffer)				0.3 * Vdd	V
Vih	High-level input voltage (Schmitt buffer)		0.7 * Vdd			V
<b>DC output characteristics</b>						
Vol	Low-level output voltage				0.2	V
Voh	High-level output voltage		Vdd - 0.2			V

### 3.3 Communication interface characteristics

#### 3.3.1 SPI - serial peripheral interface

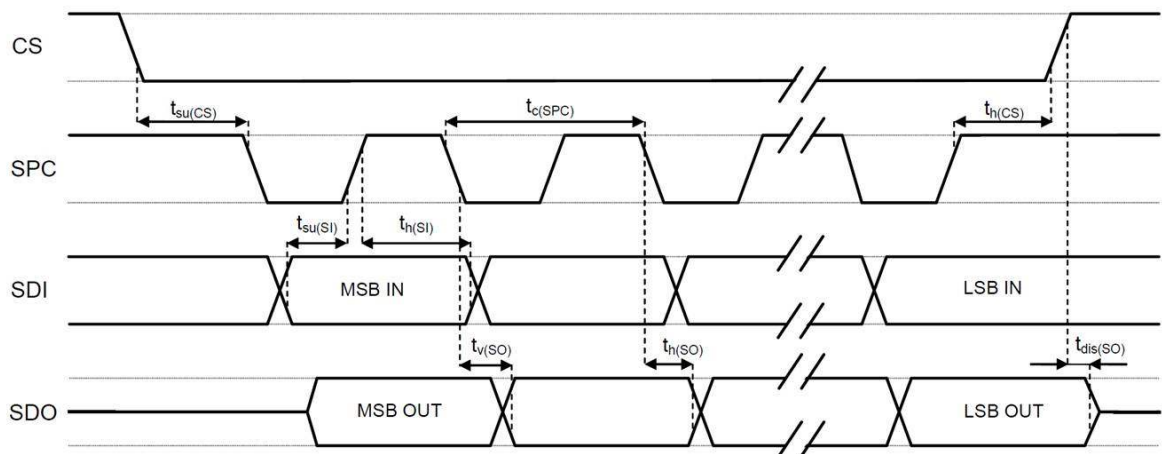
Subject to general operating conditions for V<sub>DD</sub> and T<sub>OP</sub>.

**Table 5. SPI slave timing values**

Symbol	Parameter	Value <sup>(1)</sup>		Unit
		Min.	Max.	
t <sub>c</sub> (SPC)	SPI clock cycle	100		ns
f <sub>c</sub> (SPC)	SPI clock frequency		10 <sup>(2)</sup>	MHz
t <sub>su</sub> (CS)	CS setup time	6		ns
t <sub>h</sub> (CS)	CS hold time	8		
t <sub>su</sub> (SI)	SDI input setup time	5		
t <sub>h</sub> (SI)	SDI input hold time	15		
t <sub>v</sub> (SO)	SDO valid output time		50	
t <sub>h</sub> (SO)	SDO output hold time	9		
t <sub>dis</sub> (SO)	SDO output disable time		50	

1. Values are guaranteed at 10 MHz clock frequency for SPI with both 4 and 3 wires, based on characterization results, not tested in production.
2. Recommended to set max SPI clock 8 MHz to ≤50 Hz ODR.

**Figure 4. SPI slave timing diagram**



Note: Measurement points are done at 0.3·V<sub>DD\_IO</sub> and 0.7·V<sub>DD\_IO</sub> for both ports.

### 3.3.2 I<sup>2</sup>C - inter-IC control interface

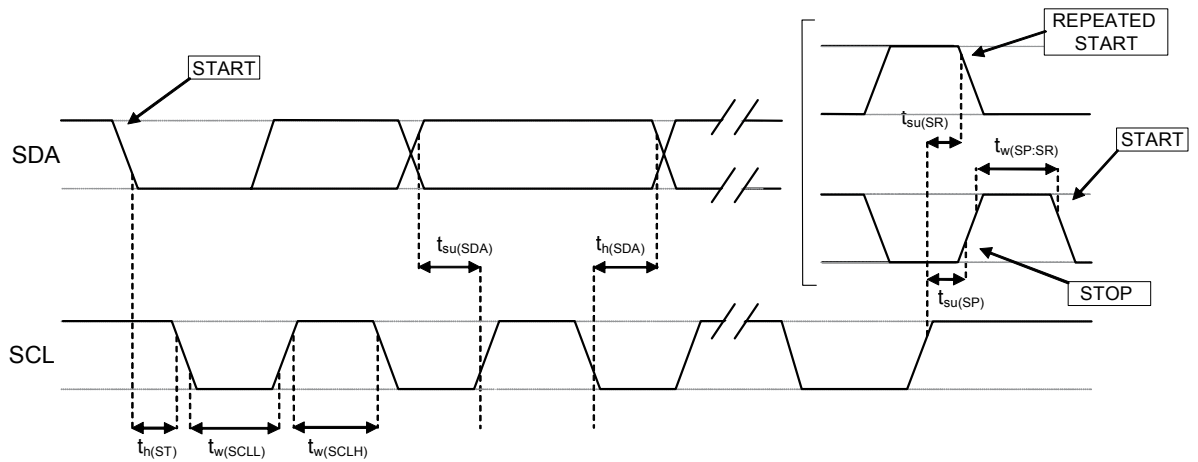
Subject to general operating conditions for V<sub>DD</sub> and T<sub>OP</sub>.

**Table 6. I<sup>2</sup>C slave timing values**

Symbol	Parameter	I <sup>2</sup> C standard mode <sup>(1)</sup>		I <sup>2</sup> C fast mode <sup>(1)</sup>		Unit
		Min.	Max.	Min.	Max.	
f <sub>(SCL)</sub>	SCL clock frequency	0	100	0	400	kHz
t <sub>w(SCLL)</sub>	SCL clock low time	4.7		1.3		μs
t <sub>w(SCLH)</sub>	SCL clock high time	4.0		0.6		
t <sub>su(SDA)</sub>	SDA setup time	250		100		ns
t <sub>h(SDA)</sub>	SDA data hold time	0	3.45	0	0.9	μs
t <sub>h(ST)</sub>	START condition hold time	4		0.6		μs
t <sub>su(SR)</sub>	Repeated START condition setup time	4.7		0.6		
t <sub>su(SP)</sub>	STOP condition setup time	4		0.6		
t <sub>w(SP:SR)</sub>	Bus free time between STOP and START condition	4.7		1.3		

1. Data based on standard I<sup>2</sup>C protocol requirement, not tested in production.

**Figure 5. I<sup>2</sup>C slave timing diagram**



Note: Measurement points are done at 0.3·V<sub>DD\_IO</sub> and 0.7·V<sub>DD\_IO</sub> for both ports.

### 3.4 Absolute maximum ratings

Stress above those listed as “Absolute maximum ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device under these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

**Table 7. Absolute maximum ratings**

Symbol	Ratings	Maximum value	Unit
Vdd	Supply voltage	-0.3 to 4.8	V
Vdd_IO	I/O pins supply voltage	-0.3 to 4.8	V
Vin	Input voltage on any control pin	-0.3 to Vdd_IO +0.3	V
P <sub>(water)</sub>	Overpressure	1	MPa
T <sub>STG</sub>	Storage temperature range	-40 to +125	°C
ESD	Electrostatic discharge protection	2 (HBM)	kV

*Note: Supply voltage on any pin should never exceed 4.8 V.*



This device is sensitive to mechanical shock, improper handling can cause permanent damage to the part.



This device is sensitive to electrostatic discharge (ESD), improper handling can cause permanent damage to the part.



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## 4 Functionality

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The LPS27HHTW is a high-resolution, digital output pressure sensor packaged in a CCLGA package with metal lid. The complete device includes a sensing element based on a piezoresistive Wheatstone bridge approach, and an IC interface which communicates a digital signal from the sensing element to the application.

### 4.1 Sensing element

An ST proprietary process is used to obtain a silicon membrane for MEMS pressure sensors. When pressure is applied, the membrane deflection induces an imbalance in the Wheatstone bridge piezoresistances whose output signal is converted by the IC interface.

### 4.2 IC interface

The complete measurement chain is composed of a low-noise amplifier which converts the resistance unbalance of the MEMS sensors (pressure and temperature) into an analog voltage using an analog-to-digital converter.

The pressure and temperature data may be accessed through an I<sup>2</sup>C/MIPI I3C<sup>SM</sup>/SPI interface thus making the device particularly suitable for direct interfacing with a microcontroller.

The LPS27HHTW features a Data-Ready signal which indicates when a new set of measured pressure and temperature data are available, thus simplifying data synchronization in the digital system that uses the device.

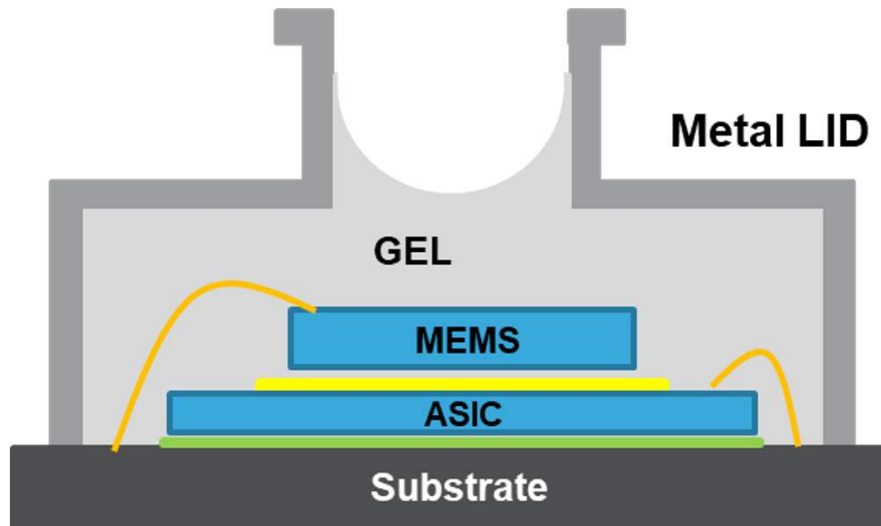
### 4.3 Factory calibration

The trimming values are stored inside the device in a non-volatile structure. When the device is turned on, the trimming parameters are downloaded into the registers to be employed during the normal operation which allows the device to be used without requiring any further calibration.

#### 4.4 Device structure

The LPS27HHTW has a unique cylindrical package solution with a full metal lid assembled on ceramic substrate and this cylindrical package provides an easy assembly with O-rings in the end user's application.

**Figure 6. LPS27HHTW internal structure**



This structure (Figure 6) is designed and verified to resist water pressure up to 10 ATM and the potting gel in the LPS27HHTW has been proven to protect electronic components from long-term exposure to harsh environments such as water mixed with chlorine, bromine, commercial washing detergent and fuels, solvents and chemicals. It also provides excellent low-stress encapsulation performance for sensitive electronic components from severe environmental conditions such as high temperature and humidity, refer to the properties of the gel which are given in the following table.

**Table 8. Potting gel properties**

Properties	Potting gel
Permeability g/m <sup>2</sup> ·24 hr	7
Hardness (penetration) based on ASTM D1403	70
Ultra-low Young's modulus	Less than 0.01 GPa
TCE (Thermal Coefficient of Expansion)	300 ppm/°C

#### 4.5 Interpreting pressure readings

The pressure data are stored in 3 registers: `PRESS_OUT_H` (2Ah), `PRESS_OUT_L` (29h), and `PRESS_OUT_XL` (28h). The value is expressed as a 24-bit signed number (in 2's complement).

To obtain the pressure in hPa, take the complete 24-bit word and then divide by the sensitivity 4096 LSB/hPa. This same interpretation is applied to pressure readings when FIFO is enabled and the pressure data are stored in 3 registers: `FIFO_DATA_OUT_PRESS_XL` (78h), `FIFO_DATA_OUT_PRESS_L` (79h), and `FIFO_DATA_OUT_PRESS_H` (7Ah).

Figure 7. Pressure readings



$$\text{Pressure Value (LSB)} = \text{PRESS\_OUT\_H (2Ah)} \& \text{PRESS\_OUT\_L (29h)} \& \text{PRESS\_OUT\_XL (28h)} = 3FF58Dh = 4191629 \text{ LSB (signed decimal)} \quad (1)$$

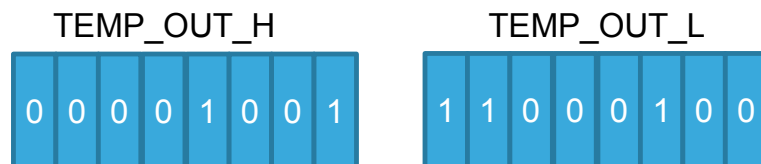
$$\text{Pressure (hPa)} = \frac{\text{Pressure Value (LSB)}}{\text{Sensitivity}} = \frac{4191629 \text{ LSB}}{4096 \text{ LSB/hPa}} = 1023 \text{ hPa} \quad (2)$$

#### 4.6 Interpreting temperature readings

The temperature data are stored in 2 registers: `TEMP_OUT_H` (2Ch) and `TEMP_OUT_L` (2Bh).

The value is expressed as 2's complement. To obtain the temperature in °C, take the two's complement of the complete 16-bit word and then divide by the sensitivity 100 LSB/°C. This same interpretation is applied to temperature readings when FIFO is enabled and the temperature data are stored in 2 registers: `FIFO_DATA_OUT_TEMP_H` (7Ch) and `FIFO_DATA_OUT_TEMP_L` (7Bh).

Figure 8. Temperature readings



$$\text{Temperature Value (LSB)} = \text{TEMP\_OUT\_H (2Ch)} \& \text{TEMP\_OUT\_L (2Bh)} = 09C4 = 2500 \text{ LSB (decimal signed)}$$

$$\text{Temperature (}^\circ\text{C)} = \frac{\text{Temperature Value (LSB)}}{\text{Sensitivity}} = \frac{2500 \text{ LSB}}{100 \text{ LSB/}^\circ\text{C}} = 25.00^\circ\text{C}$$

## 5 FIFO

The LPS27HHTW embeds 128 slots of 40-bit data FIFO to store the pressure and temperature output values. This allows consistent power saving for the system, since the host processor does not need to continuously poll data from the sensor, but it can wake up only when needed and burst the significant data out from the FIFO. This buffer can work according to six different modes:

- Bypass mode
- FIFO mode
- Continuous (Dynamic-Stream) mode
- Continuous (Dynamic-Stream)-to-FIFO mode
- Bypass-to-Continuous (Dynamic-Stream)
- Bypass-to-FIFO mode

The FIFO buffer is enabled when a configuration different from all bits '0' are written in [FIFO\\_CTRL \(13h\)](#) and each mode is selected by the TRIG\_MODES bit and F\_MODE[1:0] bits in [FIFO\\_CTRL \(13h\)](#). Programmable FIFO threshold status, FIFO overrun events and the number of unread samples stored are available in the [FIFO\\_STATUS1 \(25h\)](#) and [FIFO\\_STATUS2 \(26h\)](#) registers and can be set to generate dedicated interrupts on the INT\_DRDY pad using the [CTRL\\_REG3 \(12h\)](#) register.

[FIFO\\_STATUS2 \(26h\)](#)(FIFO\_WTM\_IA) goes to '1' when the number of unread samples ([FIFO\\_STATUS1 \(25h\)](#) (FSS[7:0]) is greater than or equal to WTM[6:0] in [FIFO\\_WTM \(14h\)](#). If [FIFO\\_WTM \(14h\)](#)(WTM[6:0]) is equal to 0, [FIFO\\_STATUS2 \(26h\)](#)(FIFO\_WTM\_IA) stays at '0'.

[FIFO\\_STATUS2 \(26h\)](#)(FIFO\_OVR\_IA) is equal to '1' if a FIFO slot is overwritten.

[FIFO\\_STATUS1 \(25h\)](#)(FSS[7:0]) contains stored data levels of unread samples; when FSS[7:0] is equal to '00000000', FIFO is empty; when FSS[7:0] is equal to '10000000', FIFO is full and the unread samples are 128.

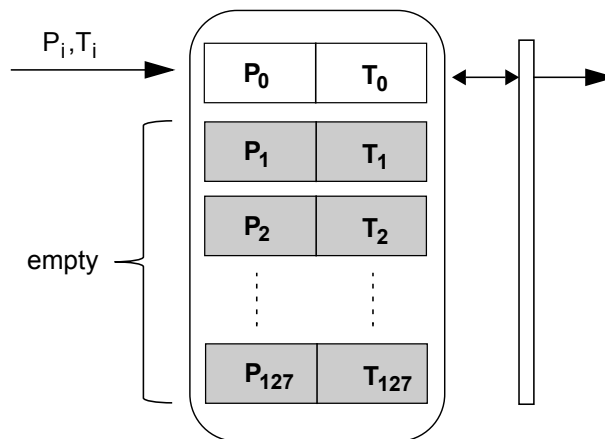
## 5.1 Bypass mode

In Bypass mode (FIFO\_CTRL (13h)(TRIG\_MODES and F\_MODE[1:0] = '000' or '100'), the FIFO is not operational and it remains empty.

Switching to Bypass mode is also used to reset the FIFO. Passing through Bypass mode is mandatory when switching between different FIFO buffer operating modes.

As described in the next figure, for each channel only the first address is used. When new data is available, the older data is overwritten.

Figure 9. Bypass mode



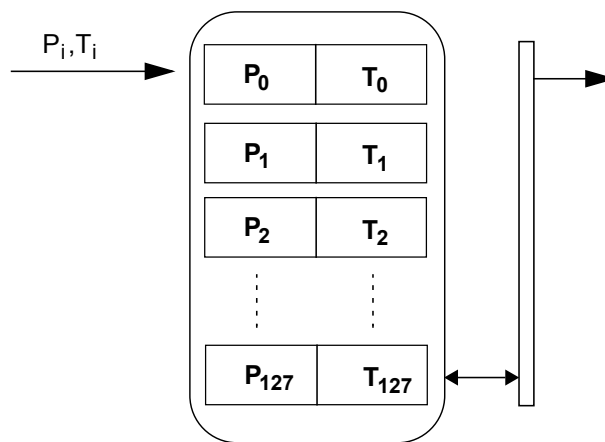
## 5.2 FIFO mode

In FIFO mode (FIFO\_CTRL (13h)(TRIG\_MODES and F\_MODE[1:0] = '001') data from the output PRESS\_OUT\_XL (28h), PRESS\_OUT\_L (29h), PRESS\_OUT\_H (2Ah), TEMP\_OUT\_L (2Bh), and TEMP\_OUT\_H (2Ch) are stored in the FIFO until it is full.

To reset FIFO content, in order to select Bypass mode the value '000' must be written in FIFO\_CTRL (13h) (TRIG\_MODE & F\_MODE[1:0]). After this reset command it is possible to restart FIFO mode by writing the value '001' in FIFO\_CTRL (13h)(TRIG\_MODE & F\_MODE[1:0]).

The FIFO buffer memorizes 128 levels of data, but the depth of the FIFO can be resized/reduced by setting the FIFO\_CTRL (13h)(STOP\_ON\_WTM) bit. If the STOP\_ON\_WTM bit is set to '1', FIFO depth is limited to FIFO\_WTM (14h)(WTM[6:0]) data.

Figure 10. FIFO mode



### 5.3 Continuous (Dynamic-Stream) mode

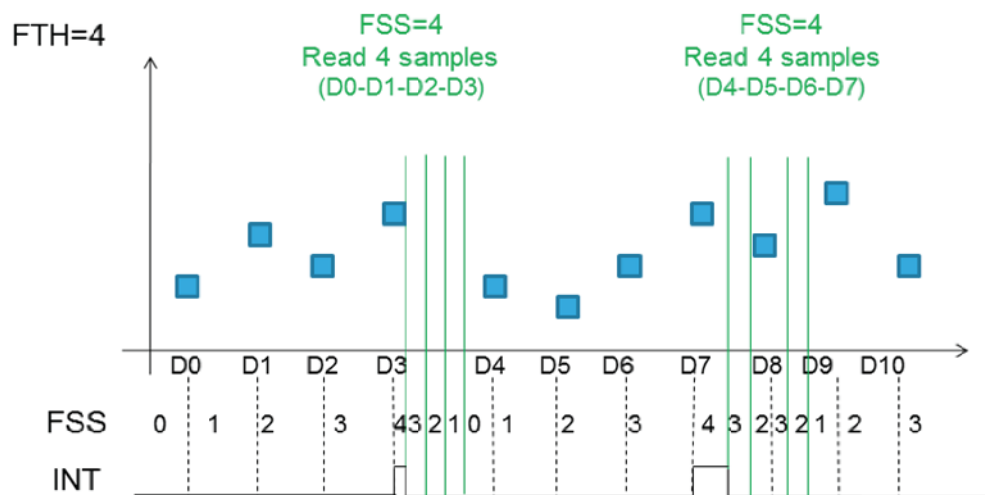
In Continuous (Dynamic-Stream) mode (FIFO\_CTRL (13h)(TRIG\_MODES and F\_MODE[1:0] = '011') after emptying the FIFO, the first new sample that arrives becomes the first to be read in a subsequent read burst. In this way, the number of new data available in FIFO does not depend on the previous read.

In Continuous (Dynamic-Stream) mode FIFO\_STATUS1 (25h)(FSS[7:0]) is the number of new pressure and temperature samples available in the FIFO buffer.

Continuous (Dynamic-Stream) is intended to be used to read FIFO\_STATUS1 (25h)(FSS[7:0]) samples when it is not possible to guarantee reading data within 1/ODR time period.

Also, a FIFO threshold interrupt on the INT\_DRDY pad through CTRL\_REG3 (12h)(INT\_F\_WTM) can be enabled in order to read data from the FIFO and leave free memory slots for incoming data.

Figure 11. Continuous (Dynamic-Stream) mode

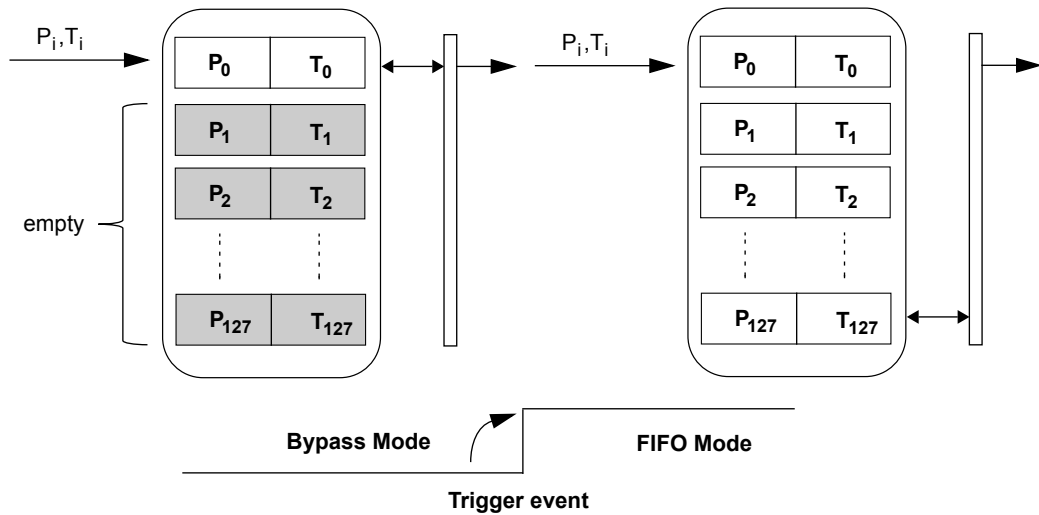


## 5.4 Bypass-to-FIFO mode

In Bypass-to-FIFO mode (FIFO\_CTRL (13h)(TRIG\_MODES and F\_MODE[1:0] = '101'), FIFO behavior switches when the INT\_SOURCE (24h)(IA) bit rises for the first time. When the INT\_SOURCE (24h)(IA) bit is equal to '0', FIFO behaves like in Bypass mode. Once the INT\_SOURCE (24h)(IA) bit rises to '1', FIFO behavior switches and keeps behaving like in FIFO mode.

An interrupt generator has to be set to the desired configuration through INTERRUPT\_CFG (0Bh).

Figure 12. Bypass-to-FIFO mode



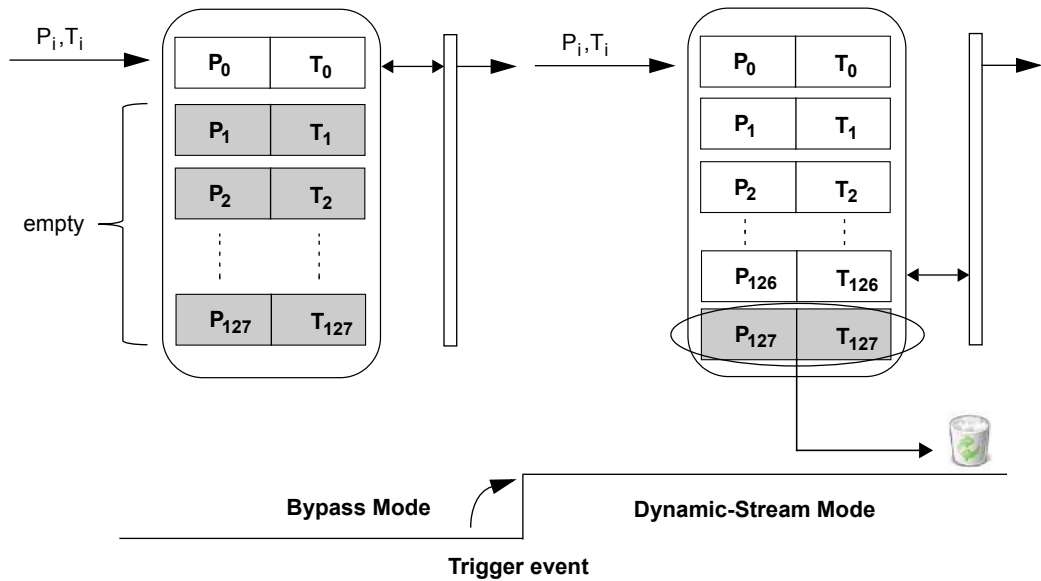


### 5.5 Bypass-to-Continuous (Dynamic-Stream) mode

In Bypass-to-Continuous (Dynamic-Stream) mode (FIFO\_CTRL (13h)(TRIG\_MODES and F\_MODE[1:0] = '110'), FIFO operates in Bypass mode until it switches to Continuous (Dynamic-Stream) mode behavior when INT\_SOURCE (24h)(IA) rises to '1', then FIFO behavior keeps behaving like in Continuous (Dynamic-Stream) mode.

An interrupt generator has to be set to the desired configuration through INTERRUPT\_CFG (0Bh).

Figure 13. Bypass-to-Continuous (Dynamic-Stream) mode

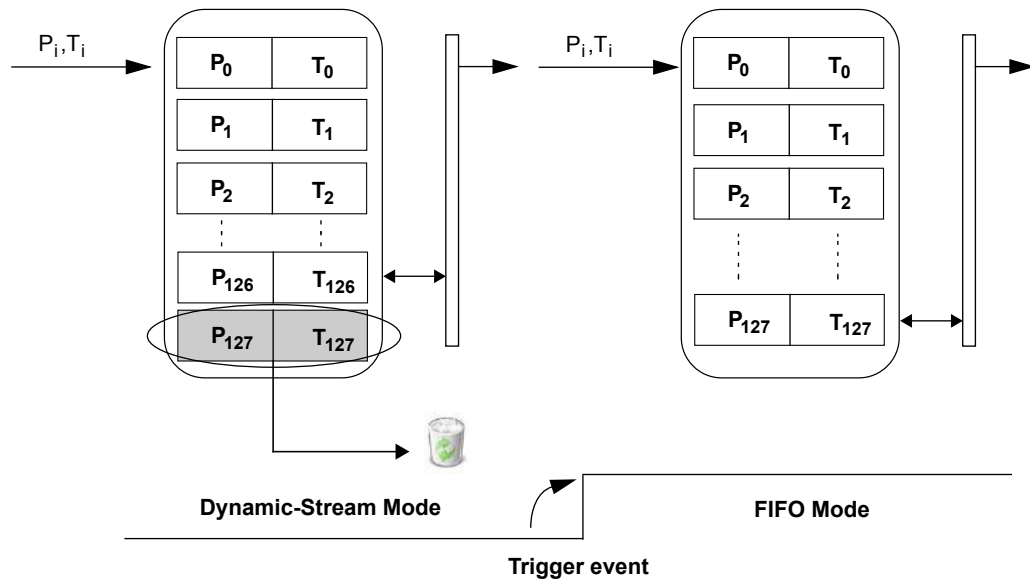


## 5.6 Continuous (Dynamic-Stream)-to-FIFO mode

In Continuous (Dynamic-Stream)-to-FIFO mode (FIFO\_CTRL (13h)(TRIG\_MODES and F\_MODE[1:0] = '111'), data are stored in FIFO and FIFO operates in Continuous (Dynamic-Stream) mode behavior until it switches to FIFO mode behavior when INT\_SOURCE (24h)(IA) rises to '1'.

An interrupt generator has to be set to the desired configuration through INTERRUPT\_CFG (0Bh).

**Figure 14. Continuous (Dynamic-Stream)-to-FIFO mode**



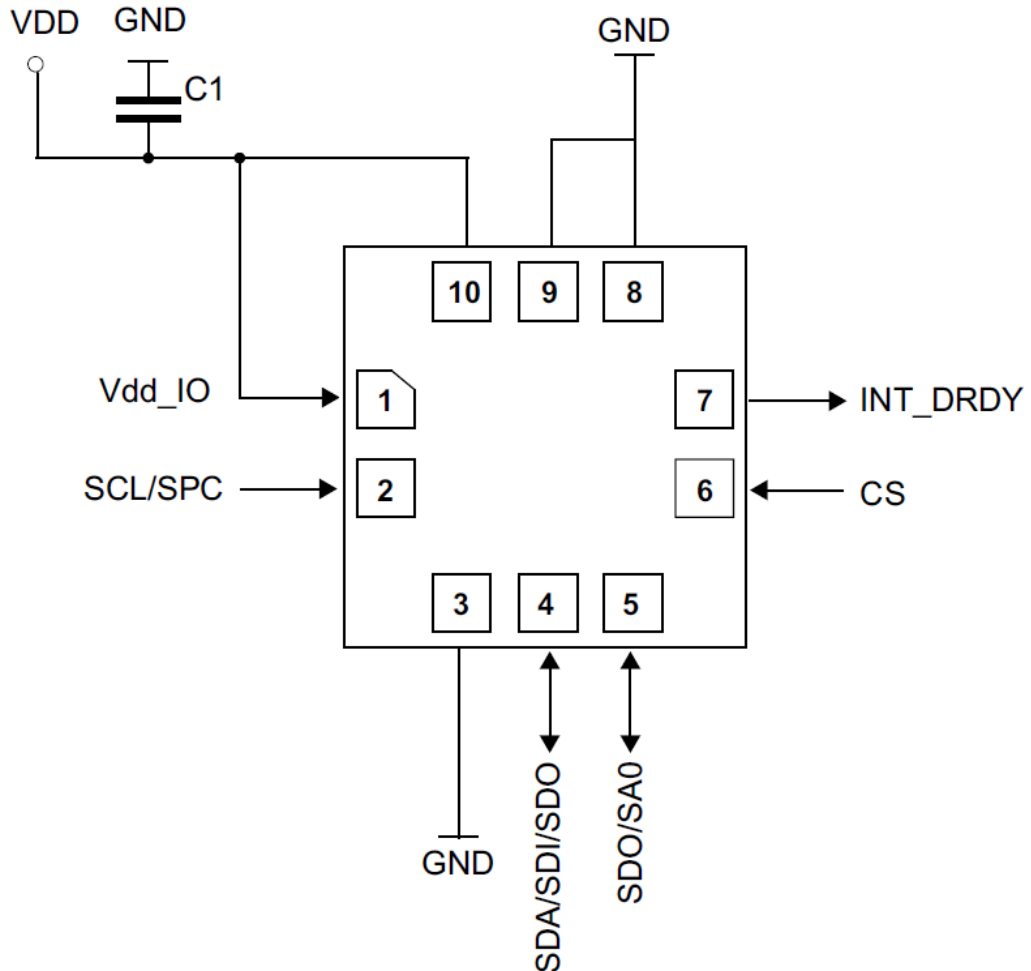
## 5.7 Retrieving data from FIFO

FIFO data is read through FIFO\_DATA\_OUT\_PRESS (78h, 79h and 7Ah) and FIFO\_DATA\_OUT\_TEMP (7Bh, 7Ch).

The read address is automatically updated by the device and it rolls back to 78h when register 7Ch is reached. In order to read all FIFO levels in a multiple byte read, 640 bytes (5 output registers by 128 levels) must be read.

## 6 Application hints

Figure 15. LPS27HHTW electrical connections (top view)



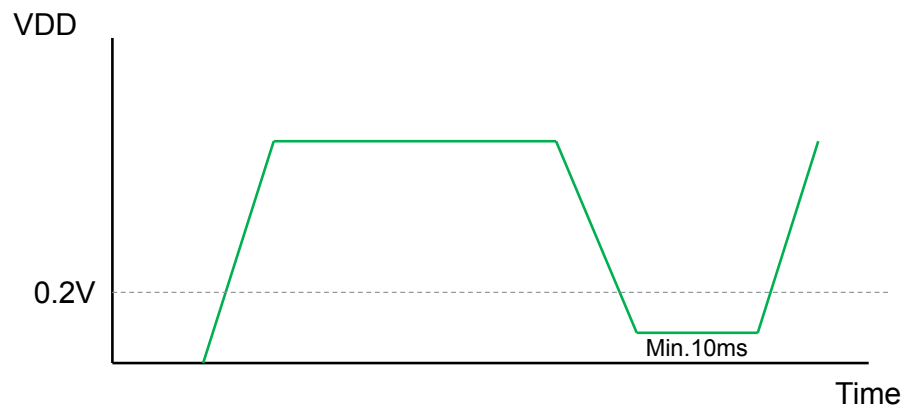
The device power supply must be provided through the VDD line; a power supply decoupling capacitor C1 (100 nF) must be placed as near as possible to the supply pads of the device. The C1 capacitor can be tied to VDD and Vdd\_IO, but it is recommended to use 2 capacitors, one on each VDD and Vdd\_IO line, in case VDD and Vdd\_IO are separate. Depending on the application, an additional capacitor of 4.7  $\mu$ F could be placed on the VDD line.

The functionality of the device and the measured data outputs are selectable and accessible through the I<sup>2</sup>C, MIPI I3C<sup>SM</sup>, SPI interface. When using the I<sup>2</sup>C and MIPI I3C<sup>SM</sup>, CS must be tied to Vdd\_IO.

All the voltage and ground supplies must be present at the same time to have proper behavior of the IC (refer to Figure 15). It is possible to remove VDD while maintaining Vdd\_IO without blocking the communication bus, in this condition the measurement chain is powered off.

*Note: To guarantee proper power-off of the device, it is recommended to maintain the duration of the VDD line to GND for at least 10 ms.*

**Figure 16. LPS27HHTW power-off sequence**



- VDD Rising / Falling time : 10  $\mu$ s ~ 100 ms
- VDD must be lower than 0.2 V for at least 10 ms during power-off sequence for correct POR

## 6.1 Soldering information

The CCLGA package is compliant with the [ECOPACK](#) standard and it is qualified for soldering heat resistance according to JEDEC J-STD-020.

## 7 Digital interfaces

### 7.1 Serial interfaces

The registers embedded in the LPS27HHTW may be accessed through either the I<sup>2</sup>C, MIPI I3C<sup>SM</sup> or SPI serial interfaces. The latter may be SW configured to operate either in 3-wire or 4-wire interface mode.

The serial interfaces are mapped onto the same pads. To select/exploit the I<sup>2</sup>C interface, the CS line must be tied high (i.e. connected to Vdd\_IO).

**Table 9. Serial interface pin description**

Pin name	Pin description
CS	SPI enable I <sup>2</sup> C/SPI mode selection (1: SPI idle mode / I <sup>2</sup> C communication enabled; 0: SPI communication mode / I <sup>2</sup> C disabled)
SCL/SPC	I <sup>2</sup> C serial clock (SCL) SPI serial port clock (SPC)
SDA	I <sup>2</sup> C serial data (SDA)
SDI	4-wire SPI serial data input (SDI)
SDI/SDO	3-wire serial data input /output (SDI/SDO)
SDO	SPI serial data output (SDO)
SA0	I <sup>2</sup> C less significant bit of the device address (SA0)

### 7.2 I<sup>2</sup>C serial interface (CS = high)

The LPS27HHTW I<sup>2</sup>C is a bus slave. The I<sup>2</sup>C is employed to write data into registers whose content can also be read back.

The relevant I<sup>2</sup>C terminology is given in the following table.

**Table 10. I<sup>2</sup>C terminology**

Term	Description
Transmitter	The device which sends data to the bus
Receiver	The device which receives data from the bus
Master	The device which initiates a transfer, generates clock signals and terminates a transfer
Slave	The device addressed by the master

There are two signals associated with the I<sup>2</sup>C bus: the serial clock line (SCL) and the serial data line (SDA). The latter is a bidirectional line used for sending and receiving the data to/from the interface. Both lines have to be connected to Vdd\_IO through pull-up resistors.

The I<sup>2</sup>C interface is compliant with fast mode (400 kHz) I<sup>2</sup>C standards as well as with the normal mode.

### 7.2.1 I<sup>2</sup>C operation

The transaction on the bus is started through a START (ST) signal. A start condition is defined as a HIGH-to-LOW transition on the data line while the SCL line is held HIGH. After the master has transmitted this, the bus is considered busy. The next data byte transmitted after the start condition contains the address of the slave in the first 7 bits and the eighth bit tells whether the master is receiving data from the slave or transmitting data to the slave. When an address is sent, each device in the system compares the first seven bits after a start condition with its address. If they match, the device considers itself addressed by the master.

The 7-bit slave address (SAD) associated to the LPS27HHTW is 101110xb. The **SDO/SA0** pad can be used to modify the less significant bit of the device address. If the SA0 pad is connected to voltage supply, LSb is '1' (7-bit address 1011101b=5Dh), otherwise if the SA0 pad is connected to ground, the LSb value is '0' (7-bit address 1011100b=5Ch). This solution permits connecting and addressing two different LPS27HHTW devices to the same I<sup>2</sup>C lines.

Data transfer with acknowledge is mandatory. The transmitter must release the SDA line during the acknowledge pulse. The receiver must then pull the data line LOW so that it remains stable low during the HIGH period of the acknowledge clock pulse. A receiver which has been addressed is obliged to generate an acknowledge after each byte of data received.

The I<sup>2</sup>C embedded inside the ASIC behaves like a slave device and the following protocol must be adhered to. After the start condition (ST) a slave address is sent, once a slave acknowledge has been returned (SAK), an 8-bit sub-address will be transmitted (SUB): the 7 LSB represent the actual register address while the MSB has no meaning. The IF\_ADD\_INC bit in CTRL\_REG2 (11h) enables sub-address auto increment (IF\_ADD\_INC is '1' by default), so if IF\_ADD\_INC = '1' the SUB (sub-address) will be automatically increased to allow multiple data read/write.

The slave address is completed with a Read/Write bit. If the bit is '1' (Read), a repeated START (SR) condition must be issued after the two sub-address bytes; if the bit is '0' (Write) the master will transmit to the slave with direction unchanged. Table 11 explains how the SAD+read/write bit pattern is composed, listing all the possible configurations.

**Table 11. SAD+Read/Write patterns**

Command	SAD[6:1]	SAD[0] = SA0	R/W	SAD+R/W
Read	101110	0	1	10111001 (B9h)
Write	101110	0	0	10111000 (B8h)
Read	101110	1	1	10111011 (BBh)
Write	101110	1	0	10111010 (BAh)

**Table 12. Transfer when master is writing one byte to slave**

Master	ST	SAD + W		SUB		DATA		SP
Slave			SAK		SAK		SAK	

**Table 13. Transfer when master is writing multiple bytes to slave**

Master	ST	SAD + W		SUB		DATA		DATA		SP
Slave			SAK		SAK		SAK		SAK	

**Table 14. Transfer when master is receiving (reading) one byte of data from slave**

Master	ST	SAD + W		SUB		SR	SAD + R			NMAK	SP
Slave			SAK		SAK			SAK	DATA		

**Table 15. Transfer when master is receiving (reading) multiple bytes of data from slave**

Master	ST	SAD+W		SUB		SR	SAD+R			MAK		MAK		NMAK	SP
Slave			SAK		SAK			SAK	DATA		DATA		DATA		

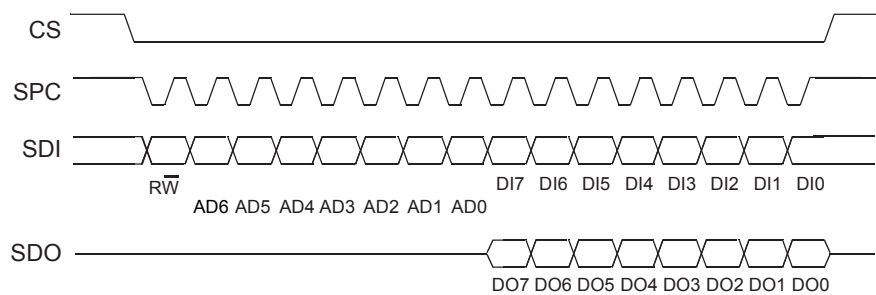
Data are transmitted in byte format (DATA). Each data transfer contains 8 bits. The number of bytes transferred per transfer is unlimited. Data is transferred with the most significant bit (MSb) first. If a slave receiver does not acknowledge the slave address (i.e. it is not able to receive because it is performing some real-time function), the data line must be kept HIGH by the slave. The master can then abort the transfer. A LOW-to-HIGH transition on the SDA line while the SCL line is HIGH is defined as a STOP condition. Each data transfer must be terminated by the generation of a STOP (SP) condition.

In the presented communication format MAK is Master acknowledge and NMAK is no master acknowledge.

### 7.3 SPI bus interface (CS = low)

The LPS27HHTW SPI is a bus slave. The SPI allows writing to and reading from the registers of the device. The serial interface interacts with the application using 4 wires: **CS**, **SPC**, **SDI** and **SDO**.

**Figure 17. Read and write protocol**



**CS** is the serial port enable and it is controlled by the SPI master. It goes low at the start of the transmission and returns to high at the end. **SPC** is the serial port clock and it is controlled by the SPI master. It is stopped high when **CS** is high (no transmission). **SDI** and **SDO** are respectively the serial port data input and output. Those lines are driven at the falling edge of **SPC** and should be captured at the rising edge of **SPC**.

Both the read register and write register commands are completed in 16 clock pulses or multiples of 8 in the case of multiple read/write bytes. Bit duration is the time between two falling edges of **SPC**. The first bit (bit 0) starts at the first falling edge of **SPC** after the falling edge of **CS** while the last bit (bit 15, bit 23,...) starts at the last falling edge of **SPC** just before the rising edge of **CS**.

**bit 0:**  $\overline{RW}$  bit. When 0, the data  $DI(7:0)$  is written into the device. When 1, the data  $DO(7:0)$  from the device is read. In the latter case, the chip will drive **SDO** at the start of bit 8.

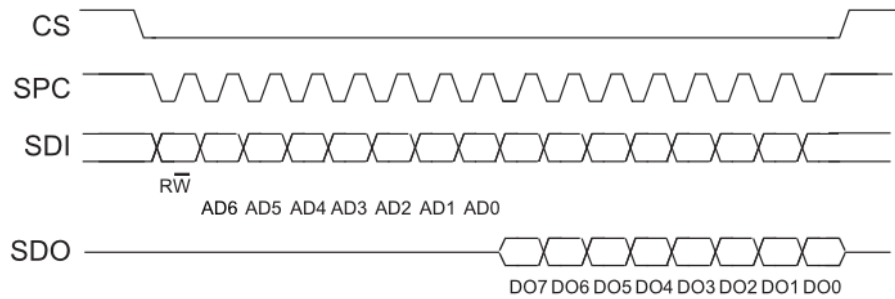
**bit 1-7:** address  $AD(6:0)$ . This is the address field of the indexed register.

**bit 8-15:** data  $DI(7:0)$  (write mode). This is the data that is written into the device (MSb first). bit 8-15: data  $DO(7:0)$  (read mode). This is the data that is read from the device (MSb first). In multiple read/write commands further blocks of 8 clock periods are added. When the  $IF\_ADD\_INC$  bit is 0, the address used to read/write data remains the same for every block. When the  $IF\_ADD\_INC$  bit is 1, the address used to read/write data is incremented at every block.

The function and the behavior of **SDI** and **SDO** remain unchanged.

### 7.3.1 SPI read

Figure 18. SPI read protocol



The SPI read command is performed with 16 clock pulses. The multiple byte read command is performed by adding blocks of 8 clock pulses to the previous one.

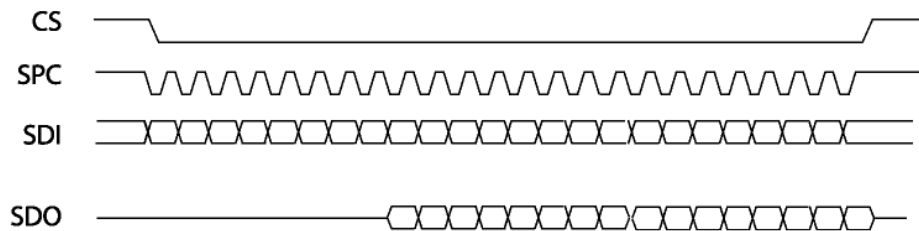
**bit 0:** READ bit. The value is 1.

**bit 1-7:** address AD(6:0). This is the address field of the indexed register.

**bit 8-15:** data DO(7:0) (read mode). This is the data that is read from the device (MSb first).

**bit 16-...:** data DO(...-8). Further data in multiple byte reads.

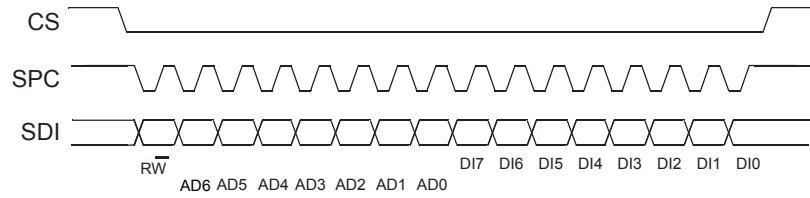
Figure 19. Multiple byte SPI read protocol (2-byte example)





### 7.3.2 SPI write

Figure 20. SPI write protocol



The SPI write command is performed with 16 clock pulses. The multiple byte write command is performed by adding blocks of 8 clock pulses to the previous one.

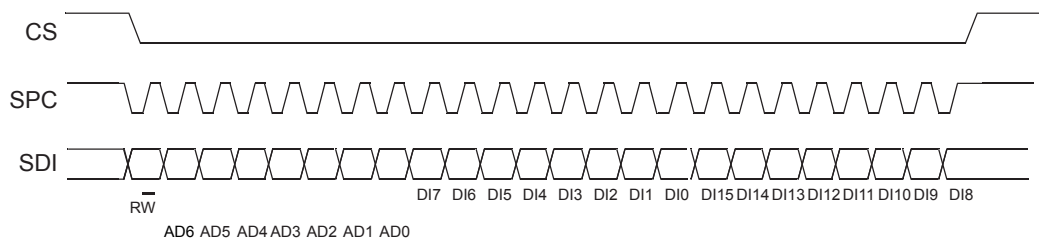
**bit 0:** WRITE bit. The value is 0.

**bit 1-7:** address AD(6:0). This is the address field of the indexed register.

**bit 8-15:** data DI(7:0) (write mode). This is the data that is written in the device (MSb first).

**bit 16-...:** data DI(...-8). Further data in multiple byte writes.

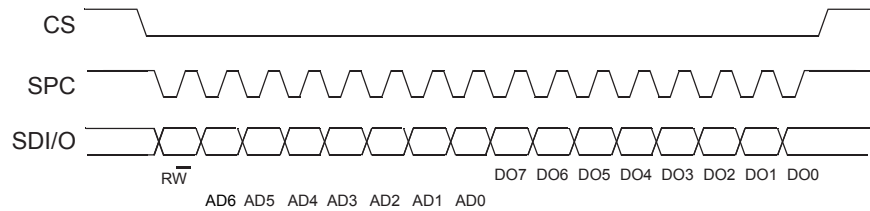
Figure 21. Multiple byte SPI write protocol (2-byte example)



### 7.3.3 SPI read in 3-wire mode

A 3-wire mode is entered by setting bit SIM to '1' (SPI serial interface mode selection) in CTRL\_REG1 (10h).

Figure 22. SPI read protocol in 3-wire mode



The SPI read command is performed with 16 clock pulses:

**bit 0:** READ bit. The value is 1.

**bit 1-7:** address AD(6:0). This is the address field of the indexed register.

**bit 8-15:** data DO(7:0) (read mode). This is the data that is read from the device (MSb first). A multiple read command is also available in 3-wire mode.

## 7.4 MIPI I3C<sup>SM</sup> slave interface

The LPS27HHTW interface includes a MIPI I3C<sup>SM</sup> SDR only slave interface with MIPI I3C<sup>SM</sup> SDR embedded features:

- CCC command
- Direct CCC communication (SET and GET)
- Broadcast CCC communication
- Private communications
- Private read and write for single byte
- Multiple read and write
- In-band interrupt and hot-join requests

### 7.4.1 MIPI I3C<sup>SM</sup> CCC supported commands

The list of MIPI I3C<sup>SM</sup> CCC commands supported by the device is detailed in the following table.

**Table 16. MIPI I3C<sup>SM</sup> CCC commands**

Command	Command code	Default	Description
ENEC	0x80 / 0x00		Slave activity control (direct and broadcast)
RSTDAA	0x86 / 0x06		Reset the assigned dynamic address (direct and broadcast)
DISEC	0x81/ 0x01		Slave activity control (direct and broadcast)
ENTAS0	0x82 / 0x02		Enter activity state (direct and broadcast)
ENTAS1	0x83 / 0x03		Enter activity state (direct and broadcast)
ENTAS2	0x84 / 0x04		Enter activity state (direct and broadcast)
ENTAS3	0x85 / 0x05		Enter activity state (direct and broadcast)
SETMWL	0x89 / 0x08	0x00 0x08	Define maximum write length during private write (direct and broadcast)
SETMRL	0x8A / 0x09	0x00 0x10 0x04	Define maximum read length during private read (direct and broadcast)
SETDASA	0x87		Assign dynamic address using static address (0x5C/0x5D depending on the SDO level)
SETNEWDA	0x88		Change dynamic address
GETMWL	0x8B	0x00 0x08	Get maximum write length during private write
GETMRL	0x8C	0x00 0x10 0x04	Get maximum read length during private read
GETPID	0x8D	0x02 0x08 0x00 0xB3 0x00 0x00	Device ID register
GETBCR	0x8E	0x07	Bus characteristics register
GETDCR	0x8F	0x62	DCR
GETSTATUS	0x90		Status register

Command	Command code	Default	Description
GETMXDS	0x94	0x00 0x20	Return max data speed
GETXTIME	0x99	0x07 0x04 0x0A 0x64	Get exchange time information

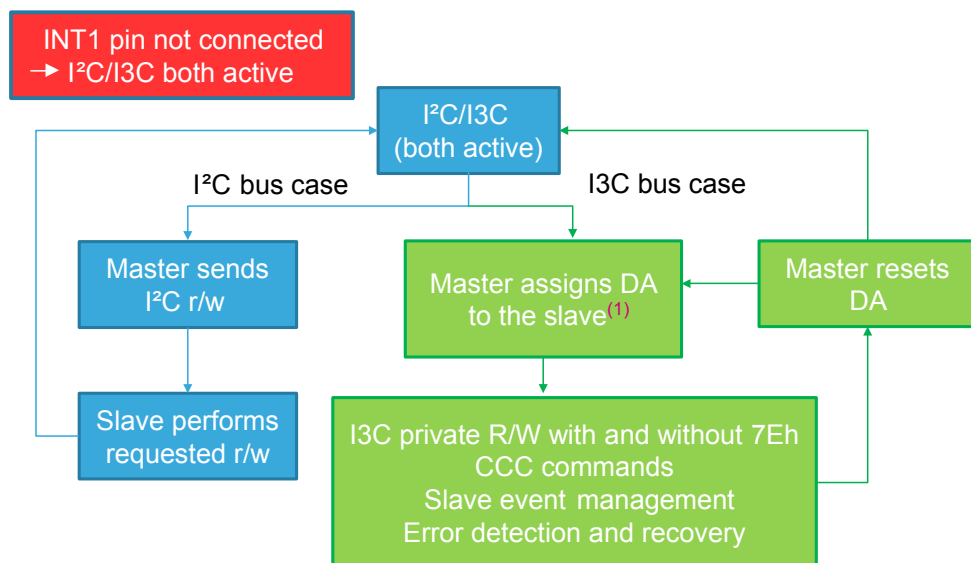
## 7.5 I<sup>2</sup>C/MIPI I3C<sup>SM</sup> coexistence in LPS27HHTW

In the LPS27HHTW, the SDA and SCL lines are common to both I<sup>2</sup>C and MIPI I3C<sup>SM</sup>. The I<sup>2</sup>C bus requires anti-spike filters on the SDA and SCL pins that are not compatible with MIPI I3C<sup>SM</sup> timing.

The device can be connected to both I<sup>2</sup>C and MIPI I3C<sup>SM</sup> or only to the MIPI I3C<sup>SM</sup> bus depending on the connection of the INT1 pin when the device is powered up:

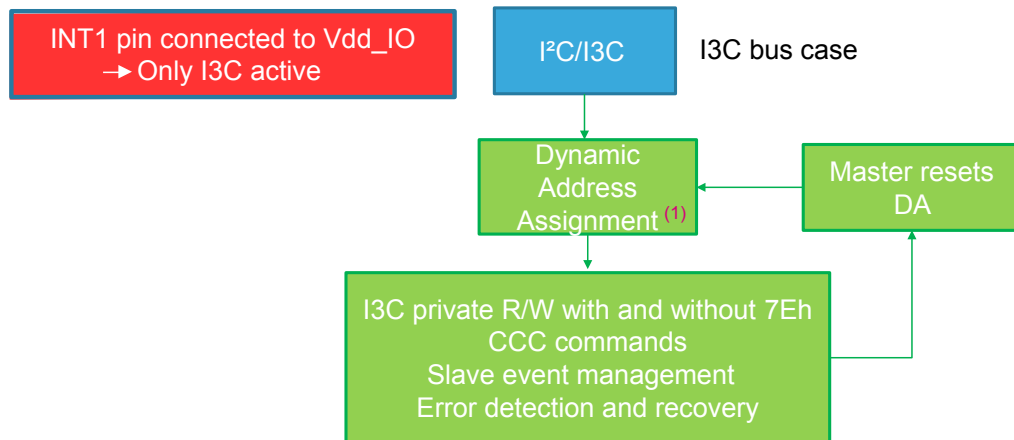
- INT\_DRDY pin floating (internal pull-down): I<sup>2</sup>C/MIPI I3C<sup>SM</sup> both active, see [Figure 23](#)
  - I<sup>2</sup>C case: INT\_DRDY pin is by default an input with pull-down. If I<sup>2</sup>C is used, INT\_DRDY must be left unconnected or eventually pulled down during device initialization. After power-on, during device configuration, the INT\_DRDY pin can be programmed as an interrupt output pin and it is recommended to set bit I3C\_disable to '1'.
  - I3C case: INT\_DRDY pin is by default an input with pull-down. If I3C is used and the INT\_DRDY pin is unconnected, dynamic address assignment must be performed using I<sup>2</sup>C Fast Mode Plus Timing (max 1 MHz clock). After dynamic address assignment, I3C can be used in full speed mode.
- INT\_DRDY pin connected to Vdd\_IO: only MIPI I3C<sup>SM</sup> active, see [Figure 24](#)
  - Only I3C: INT\_DRDY pin is by default an input with pull-down. If INT\_DRDY is set to Vdd\_IO, I3C slave is selected and device can be initialized at full speed through the SETDASA command. If the I3C bus is available for more than 10 msec and the device is not yet addressed, a hot join request is performed (SDA line kept to ground from slave) and the master must manage the request. After device address assignment, a private write can be performed to disconnect the INT\_DRDY pull-down.

**Figure 23. I<sup>2</sup>C and MIPI I3C<sup>SM</sup> both active (INT\_DRDY pin not connected)**



1. Address assignment (SETDASA) must be performed with I<sup>2</sup>C Fast Mode Plus Timing. When the slave is addressed, the I<sup>2</sup>C slave is disabled and the timing is compatible with MIPI I3C<sup>SM</sup> specifications.

Figure 24. Only MIPI I3C<sup>SM</sup> active (INT\_DRDY pin connected to Vdd\_IO)



1. When the slave is MIPI I3C<sup>SM</sup> only, the I<sup>2</sup>C slave is always disabled. The address can be assigned using MIPI I3C<sup>SM</sup> SDR timing.

## 8 Register mapping

The following table provides a quick overview of the 8-bit registers embedded in the device.

**Table 17. Registers address map**

Name	Type	Register Address	Default	Function and comment
		Hex	Binary	
Reserved		00 - 0A	-	Reserved
INTERRUPT_CFG	R/W	0B	00000000	Interrupt register
THS_P_L	R/W	0C	00000000	Pressure threshold registers
THS_P_H	R/W	0D	00000000	
IF_CTRL	R/W	0E	00000000	Interface control register
WHO_AM_I	R	0F	10110011	Who am I
CTRL_REG1	R/W	10	00000000	Control registers
CTRL_REG2	R/W	11	00010000	
CTRL_REG3	R/W	12	00000000	
FIFO_CTRL	R/W	13	00000000	FIFO configuration register
FIFO_WTM	R/W	14	00000000	
REF_P_L	R/W	15	00000000	Reference pressure registers
REF_P_H	R/W	16	00000000	
Reserved		17	-	
RPDS_L	R/W	18	00000000	Pressure offset registers
RPDS_H	R/W	19	00000000	
Reserved		1A - 23	-	Reserved
INT_SOURCE	R	24	Output	Interrupt register
FIFO_STATUS1	R	25	Output	FIFO status registers
FIFO_STATUS2	R	26	Output	
STATUS	R	27	Output	Status register
PRESS_OUT_XL	R	28	Output	Pressure output registers
PRESS_OUT_L	R	29	Output	
PRESS_OUT_H	R	2A	Output	
TEMP_OUT_L	R	2B	Output	Temperature output registers
TEMP_OUT_H	R	2C	Output	
Reserved		2D - 3B	-	Reserved
LPFP_RES	R	3C	Output	Low-pass filter reset register
Reserved		3D - 77	-	Reserved
FIFO_DATA_OUT_PRESS_XL	R	78	Output	FIFO pressure output registers
FIFO_DATA_OUT_PRESS_L	R	79	Output	
FIFO_DATA_OUT_PRESS_H	R	7A	Output	
FIFO_DATA_OUT_TEMP_L	R	7B	Output	FIFO temperature output registers
FIFO_DATA_OUT_TEMP_H	R	7C	Output	

Registers marked as Reserved must not be changed. Writing to those registers may cause permanent damage to the device.

To guarantee the proper behavior of the device, all register addresses not listed in the above table must not be accessed and the content stored in those registers must not be changed.

The content of the registers that are loaded at boot should not be changed. They contain the factory calibration values. Their content is automatically restored when the device is powered up.



## 9 Register description

The device contains a set of registers which are used to control its behavior and to retrieve pressure and temperature data. The register address, made up of 7 bits, is used to identify them and to read/write the data through the serial interface.

### 9.1 INTERRUPT\_CFG (0Bh)

Interrupt mode for pressure acquisition configuration (R/W)

7	6	5	4	3	2	1	0
AUTOREFP	RESET_ARP	AUTOZERO	RESET_AZ	DIFF_EN	LIR	PLE	PHE

AUTOREFP	Enable AUTOREFP function. Default value: 0 (0: normal mode; 1: AUTOREFP enabled)
RESET_ARP	Reset AUTOREFP function. Default value: 0 (0: normal mode; 1: reset AUTOREFP function)
AUTOZERO	Enable AUTOZERO function. Default value: 0 (0: normal mode; 1: AUTOZERO enabled)
RESET_AZ	Reset AUTOZERO function. Default value: 0 (0: normal mode; 1: reset AUTOZERO function)
DIFF_EN	Enable interrupt generation. Default value: 0 (0: interrupt generation disabled; 1: interrupt generation enabled)
LIR	Latch interrupt request to the INT_SOURCE (24h) register. Default value: 0 (0: interrupt request not latched; 1: interrupt request latched)
PLE	Enable interrupt generation on pressure low event. Default value: 0 (0: disable interrupt request; 1: enable interrupt request on pressure value lower than preset threshold)
PHE	Enable interrupt generation on pressure high event. Default value: 0 (0: disable interrupt request; 1: enable interrupt request on pressure value higher than preset threshold)

Referring to [Figure 25. “Threshold-based” interrupt event](#), the LPS27HHTW can be set by the user to support the interrupt function when P\_DIFF\_IN (defined below) is higher or lower than the threshold value stored in THS\_P\_L (0Ch) and THS\_P\_H (0Dh).

It is enabled when the DIFF\_EN bit in the INTERRUPT\_CFG (0Bh) register is set to '1' and either PHE bit or PLE bit (or both bits) = '1'. Then, the differential pressure can be compared to a user-defined threshold stored in the 15-bit THS\_P (0Ch and 0Dh) registers.

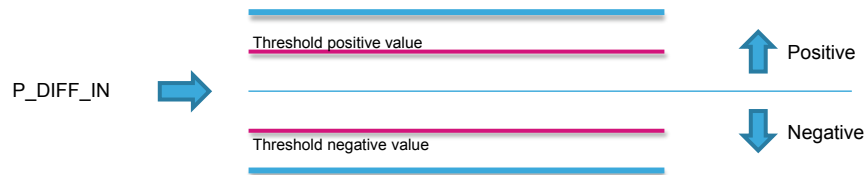
The threshold pressure value defined by the user is a 15-bit unsigned value in the 16-bit register composed of THS\_P\_L (0Ch) and THS\_P\_H (0Dh). The value is:

$$\text{THS\_P (15-bit unsigned)} = \text{Desired Interrupt threshold (hPa)} \times 16$$

The PHE and PLE bits in INTERRUPT\_CFG (0Bh) enable the differential pressure interrupt generation on the positive or negative event respectively.

The differential interrupt must be used with AUTOREFP or AUTOZERO mode.

Figure 25. “Threshold-based” interrupt event



To enable the AUTOZERO mode, the AUTOZERO bit must be set to '1' and then the measured pressure value is used as the reference and stored in the register REF\_P (REF\_P\_L (15h), REF\_P\_H (16h)). From this point on, the output pressure value (PRESS\_OUT\_XL (28h), PRESS\_OUT\_L (29h), PRESS\_OUT\_H (2Ah)) is updated with the difference between the measured pressure and REF\_P.

- $P\_DIFF\_IN = \text{measured pressure} - REF\_P$
- $PRESS\_OUT = \text{measured pressure} - REF\_P$

After the first conversion, the AUTOZERO bit is automatically set back to '0'. In order to return back to normal mode, the RESET\_AZ bit in the INTERRUPT\_CFG (0Bh) register has to be set to '1'. This also resets the content of the REF\_P registers to 0.

**AUTOREFP** mode allows using the pressure differential for the generation of the interrupt keeping the output pressure registers PRESS\_OUT (PRESS\_OUT\_XL (28h), PRESS\_OUT\_L (29h), PRESS\_OUT\_H (2Ah)) without comparing REF\_P. If the AUTOREFP bit is set to '1', the measured output pressure is used as the reference in the register REF\_P (REF\_P\_L (15h), REF\_P\_H (16h)) for interrupt generation with following:

- $P\_DIFF\_IN = \text{measured pressure} - REF\_P$

The output registers PRESS\_OUT (28h, 29h and 2Ah) are not changed by REF\_P and shows as follows.

- $PRESS\_OUT = \text{measured pressure}$

After the first conversion, the AUTOREFP bit is automatically set to '0'. In order to return back to normal mode, the RESET\_ARP bit has to be set to '1'

## 9.2 THS\_P\_L (0Ch)

User-defined threshold value for pressure interrupt event (least significant bits) (R/W)

7	6	5	4	3	2	1	0
THS7	THS6	THS5	THS4	THS3	THS2	THS1	THS0

THS[7:0]	This register contains the low part of threshold value for pressure interrupt generation. Default value: 00h
----------	--

The threshold value for pressure interrupt generation is a 15-bit unsigned right-justified value composed of [THS\\_P\\_H \(0Dh\)](#) and [THS\\_P\\_L \(0Ch\)](#). The value is expressed as:

$THS\_P$  (15-bit unsigned) = Desired interrupt threshold (hPa) x 16

To enable the interrupt event based on this user-defined threshold, the `DIFF_EN` bit in [INTERRUPT\\_CFG \(0Bh\)](#) must be set to '1', the `PHE` bit or `PLE` bit (or both bits) in [INTERRUPT\\_CFG \(0Bh\)](#) has to be enabled.

## 9.3 THS\_P\_H (0Dh)

User-defined threshold value for pressure interrupt event (most significant bits) (R/W)

7	6	5	4	3	2	1	0
-	THS14	THS13	THS12	THS11	THS10	THS9	THS8

THS[14:8]	This register contains the high part of threshold value for pressure interrupt generation. Default value: 00h Refer to <a href="#">THS_P_L (0Ch)</a> .
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## 9.4 IF\_CTRL (0Eh)

Interface control register (R/W)

7	6	5	4	3	2	1	0
INT_EN_I3C	0	0	SDA_PU_EN	SDO_PU_EN	PD_DIS_INT1	I3C_DISABLE	I2C_DISABLE

INT_EN_I3C	Enable INT1 pad with MIPI I3C <sup>SM</sup> . If the INT_EN_I3C bit is set, the INT1 pad is polarized as OUT. Default value: 0 (0: INT1 disabled with MIPI I3C <sup>SM</sup> ; 1: INT1 enabled with MIPI I3C <sup>SM</sup> )
SDA_PU_EN	Enable pull-up on the SDA pin. Default value: 0 (0: SDA pin pull-up disconnected; 1: SDA pin with pull-up)
SDO_PU_EN	Enable pull-up on the SDO pin. Default value: 0 (0: SDO pin pull-up disconnected; 1: SDO pin with pull-up)
PD_DIS_INT1	Disable pull down on the INT1 pin. Default value: 0 (0: INT1 pin with pull-down; 1: INT1 pin pull-down disconnected)
I3C_DISABLE <sup>(1)</sup>	Disable MIPI I3C <sup>SM</sup> interface. Default value: 0 (0: MIPI I3C <sup>SM</sup> enabled; 1: MIPI I3C <sup>SM</sup> disabled)
I2C_DISABLE <sup>(2)</sup>	Disable I <sup>2</sup> C interface. Default value: 0 (0: I <sup>2</sup> C enabled; 1: I <sup>2</sup> C disabled)

1. `I3C_DISABLE` bit disables the MIPI I3C<sup>SM</sup> communication protocol.

2. `I2C_DISABLE` bit disables the I<sup>2</sup>C interface, by default both SPI and I<sup>2</sup>C interfaces are enabled.

## 9.5 WHO\_AM\_I (0Fh)

Device Who am I

7	6	5	4	3	2	1	0
1	0	1	1	0	0	1	1

## 9.6 CTRL\_REG1 (10h)

Control register 1 (R/W)

7	6	5	4	3	2	1	0
0	ODR2	ODR1	ODR0	EN_LPF	LPFP_CFG	BDU	SIM

ODR[2:0]	Output data rate selection. Default value: 000 Refer to <a href="#">Table 18</a> .
EN_LPF	Enable low-pass filter on pressure data when Continuous mode is used. Default value: 0 (0: Low-pass filter disabled; 1: Low-pass filter enabled)
LPFP_CFG	LPFP_CFG: Low-pass configuration register. Default value: 0 Refer to <a href="#">Table 19</a> .
BDU <sup>(1)</sup>	Block data update. Default value: 0 (0: continuous update; 1: output registers not updated until MSB and LSB have been read)
SIM	SPI Serial Interface Mode selection. Default value: 0 (0: 4-wire interface; 1: 3-wire interface)

1. To guarantee the correct behavior of BDU feature, [PRESS\\_OUT\\_H \(2Ah\)](#) must be the last address read.

**Table 18. Output data rate bit configurations**

ODR[2:0]	Temperature, Pressure (Hz)
000	One-shot
001	1 Hz
010	10 Hz
011	25 Hz
100	50 Hz
101	75 Hz
110 <sup>(1)</sup>	100 Hz
111 <sup>(1)</sup>	200 Hz

1. This option disables the low-noise mode automatically.

When the ODR bits are set to '000', the device is in **Power-down mode**. When the device is in power-down mode, almost all internal blocks of the device are switched off to minimize power consumption. The I<sup>2</sup>C interface is still active to allow communication with the device. The content of the configuration registers is preserved and output data registers are not updated, therefore keeping the last data sampled in memory before going into power-down mode.

If the ONE\_SHOT bit in [CTRL\\_REG2 \(11h\)](#) is set to '1', **One-shot mode** is triggered and a new acquisition starts when it is required. Enabling this mode is possible only if the device was previously in power-down mode (ODR bits set to '000'). Once the acquisition is completed and the output registers updated, the device automatically enters in power-down mode. ONE\_SHOT bit self-clears itself.

When the ODR bits are set to a value different than '000', the device is in **Continuous mode** and automatically acquires a set of data (pressure and temperature) at the frequency selected through the ODR[2:0] bits.

Once the additional low-pass filter has been enabled through the EN\_LPFP bit, it is possible to configure the device bandwidth acting on the LPFP\_CFG bit. See [Table 19](#) for low-pass filter configurations.

**Table 19. Low-pass filter configurations**

EN_LPFP	LPFP_CFG	Additional low-pass filter status	Device bandwidth
0	x	Disabled	ODR/2
1	0	Enabled	ODR/9
1	1	Enabled	ODR/20

The BDU bit is used to inhibit the update of the output registers until both upper and lower (and XLOW) register parts are read. In default mode (BDU = '0') the output register values are updated continuously. If for any reason it is not sure to read faster than the output data rate, it is recommended to set the BDU bit to '1'. In this way, the content of the output registers is not updated until MSB, LSB and XLSB have been read which avoids reading values related to different sample times.

## 9.7 CTRL\_REG2 (11h)

Control register 2 (R/W)

7	6	5	4	3	2	1	0
BOOT	INT_H_L	PP_OD	IF_ADD_INC	0	SWRESET	LOW_NOISE_EN	ONE_SHOT

BOOT	Reboots memory content. Default value: 0 (0: normal mode; 1: reboot memory content)
INT_H_L	Interrupt active-high, active-low. Default value: 0 (0: active high; 1: active low)
PP_OD	Push-pull/open-drain selection on interrupt pad. Default value: 0 (0: push-pull; 1: open-drain)
IF_ADD_INC	Register address automatically incremented during a multiple byte access with a serial interface (I <sup>2</sup> C or SPI). Default value: 1 (0: disable; 1: enable)
SWRESET	Software reset. Default value: 0 (0: normal mode; 1: software reset). The bit is self-cleared when the reset is completed.
LOW_NOISE_EN	Enables low noise (used only if ODR is lower than 100 Hz). Default value: 0 (0: low-current mode; 1: low-noise mode)
ONE_SHOT	Enables one-shot. Default value: 0 (0: idle mode; 1: a new dataset is acquired)

The BOOT bit is used to refresh the content of the internal registers stored in the Flash memory block. At device power-up, the content of the Flash memory block is transferred to the internal registers related to the trimming functions to allow correct behavior of the device itself. If for any reason the content of the trimming registers is modified, it is sufficient to use this bit to restore the correct values. When the BOOT bit is set to '1', the content of the internal Flash is copied into the corresponding internal registers and is used to calibrate the device. These values are factory trimmed and they are different for every device. They allow the correct behavior of the device and normally they should not be changed. At the end of the boot process, the BOOT bit is set again to '0' by hardware. The BOOT bit takes effect immediately after it is set to 1.

INT\_H\_L selects an interrupt active-high/low value.

PP\_OD selects push-pull/open-drain on the interrupt pad.

The IF\_ADD\_INC bit enables the address to be automatically incremented during a multiple byte access with a serial interface (SPI or I<sup>2</sup>C).

The SWRESET bit resets the volatile registers to default value '0'. It returns to '0' by hardware.

LOW\_NOISE\_EN is disabled by default and must be changed when the device is in power-down mode. It enables low-noise mode but can be used when the ODR is lower than 100 Hz. If ODR = 100 Hz or ODR = 200 Hz, this option is automatically switched off and the value of the low-noise enable bit is ignored.

LOW\_NOISE\_EN mode is enabled to have less RMS noise and the best performance is achieved with LOW\_NOISE\_EN set to 1 and filter at ODR/20. Depending on the application, the LOW\_NOISE\_EN bit can be enabled (low-noise mode) or disabled (low-current mode) to have less RMS noise or less power consumption (refer to the following table).

**Table 20. RMS noise and power consumption**

Mode	Additional low-pass filter status	Device bandwidth	RMS noise [Pa]	Supply current @ ODR = 1 Hz [μA]
Low noise	Disabled		1.8	12
	Enabled	ODR/9	1	12
	Enabled	ODR/20	0.7	12
Low current	Disabled		5.6	4
	Enabled	ODR/9	3.2	4
	Enabled	ODR/20	2.1	4

The ONE\_SHOT bit is used to start a new conversion when the ODR[2:0] bits in CTRL\_REG1 (10h) are set to '000'. Writing a '1' in ONE\_SHOT triggers a single measurement of pressure and temperature. Once the measurement is done, the ONE\_SHOT bit will self-clear, the new data are available in the output registers, and the STATUS (27h) bits are updated.

### 9.8 CTRL\_REG3 (12h)

Control register 3 - INT\_DRDY pin control register (R/W)

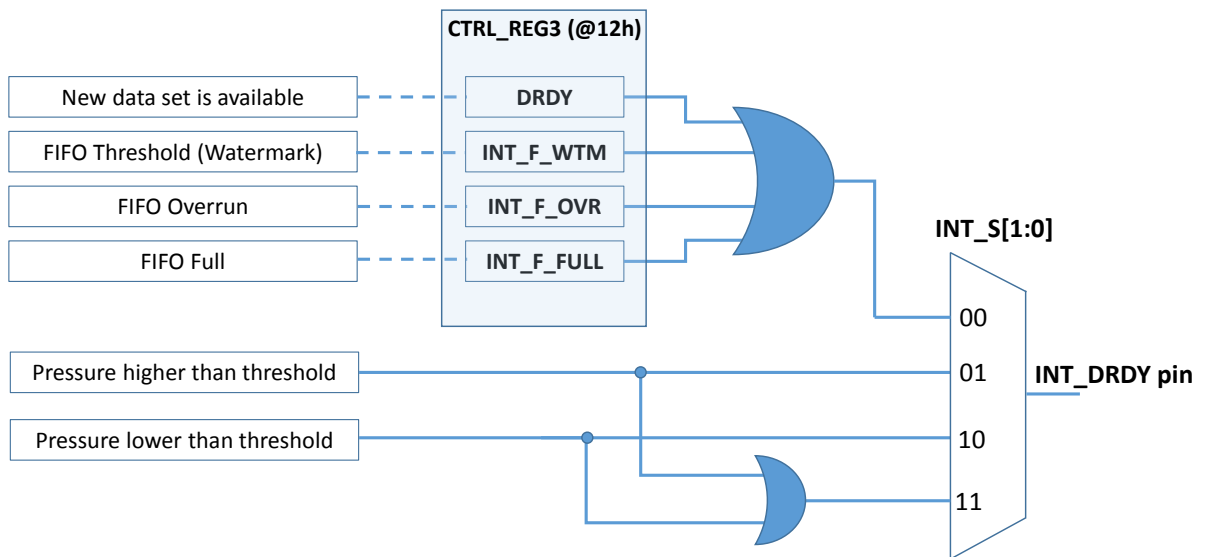
7	6	5	4	3	2	1	0
0	0	INT_F_FULL	INT_F_WTM	INT_F_OVR	DRDY	INT_S1	INT_S0

INT_F_FULL	FIFO full flag on INT_DRDY pin. Default value: 0 (0: FIFO empty; 1: FIFO full - 128 unread samples)
INT_F_WTM	FIFO threshold (watermark) status on INT_DRDY pin. Default value: 0 (0: FIFO is lower than FTH level; 1: FIFO is equal to or higher than FTH level)
INT_F_OVR	FIFO overrun status on INT_DRDY pin. Default value: 0 (0: not overwritten; 1: at least one sample in the FIFO has been overwritten)
DRDY	Data-ready signal on INT_DRDY pin. Default value: 0 (0: disable; 1: enable)
INT_S[1:0]	Data signal on INT_DRDY pin control bits. Default value: 00 Refer to <a href="#">Table 21</a> .

Table 21. Interrupt configurations

INT_S1	INT_S0	INT_DRDY pin configuration
0	0	Data signal (in order of priority: DRDY or INT_F_WTM or INT_F_OVR or INT_F_FULL)
0	1	Pressure high (P_high)
1	0	Pressure low (P_low)
1	1	Pressure low OR high

Figure 26. Interrupt events on INT\_DRDY pin



## 9.9 FIFO\_CTRL (13h)

FIFO control register (R/W)

7	6	5	4	3	2	1	0
0	0	0	0	STOP_ON_WTM	TRIG_MODES	F_MODE1	F_MODE0

STOP_ON_WTM	Stop-on-FIFO watermark. Enables FIFO watermark level use. Default value: 0 (0: disable; 1: enable)
TRIG_MODES	Enables triggered FIFO modes. Default value: 0
F_MODE[1:0]	Selects triggered FIFO modes. Default value: 00 Refer to <a href="#">Table 22</a> .

**Table 22. FIFO mode selection**

TRIG_MODES	F_MODE[1:0]	Mode
x	00	Bypass
0	01	FIFO mode
0	1x	Continuous (Dynamic-Stream)
1	01	Bypass-to-FIFO
1	10	Bypass-to-Continuous (Dynamic-Stream)
1	11	Continuous (Dynamic-Stream)-to-FIFO

The STOP\_ON\_WTM bit enables the use of the FIFO watermark level: when the number of samples in FIFO is equal to the watermark level (set using the WTM[4:0] bits in [FIFO\\_WTM \(14h\)](#)) then FIFO is full.

The TRIG\_MODES bit enables the triggered FIFO modes.

The F\_MODE[1:0] bits select one of the FIFO modes as described in [Table 22](#).

Output data (pressure and temperature) are read through [FIFO\\_DATA\\_OUT\\_PRESS\\_XL \(78h\)](#), [FIFO\\_DATA\\_OUT\\_PRESS\\_L \(79h\)](#), [FIFO\\_DATA\\_OUT\\_PRESS\\_H \(7Ah\)](#), [FIFO\\_DATA\\_OUT\\_TEMP\\_L \(7Bh\)](#) and [FIFO\\_DATA\\_OUT\\_TEMP\\_H \(7Ch\)](#); both single read and multiple read operations can be used.

## 9.10 FIFO\_WTM (14h)

FIFO threshold setting register (R/W)

7	6	5	4	3	2	1	0
0	WTM6	WTM5	WTM4	WTM3	WTM2	WTM1	WTM0

WTM[6:0]	FIFO threshold. Watermark level setting. Default value: 0000000
----------	---



### 9.11 REF\_P\_L (15h)

Reference pressure LSB data (R)

7	6	5	4	3	2	1	0
REFL7	REFL6	REFL5	REFL4	REFL3	REFL2	REFL1	REFL0

REFL[7:0]	This register contains the low part of the reference pressure value. Default value: 00000000
-----------	--

The Reference pressure value is 16-bit data and it is composed of [REF\\_P\\_H \(16h\)](#) and [REF\\_P\\_L \(15h\)](#). The value is expressed as 2's complement.

The reference pressure value is stored and used when the AUTOZERO or AUTOREFP function is enabled. Please refer to the [INTERRUPT\\_CFG \(0Bh\)](#) register description.

### 9.12 REF\_P\_H (16h)

Reference pressure MSB data (R)

7	6	5	4	3	2	1	0
REFL15	REFL14	REFL13	REFL12	REFL11	REFL10	REFL9	REFL8

REFL[15:8]	This register contains the high part of the reference pressure value. Default value: 00000000
------------	---

### 9.13 RPDS\_L (18h)

Pressure offset (LSB data)

7	6	5	4	3	2	1	0
RPDS7	RPDS6	RPDS5	RPDS4	RPDS3	RPDS2	RPDS1	RPDS0

RPDS[7:0]	This register contains the low part of the pressure offset value. Default value: 00000000
-----------	---

The pressure offset value is 16-bit data that can be used to implement one-point calibration (OPC) after soldering. This value is composed of [RPDS\\_H \(19h\)](#) and [RPDS\\_L \(18h\)](#). The value is expressed as 2's complement.

### 9.14 RPDS\_H (19h)

Pressure offset (MSB data)

7	6	5	4	3	2	1	0
RPDS15	RPDS14	RPDS13	RPDS12	RPDS11	RPDS10	RPDS9	RPDS8

RPDS[15:8]	This register contains the high part of the pressure offset value. Default value: 00000000 Refer to <a href="#">RPDS_L (18h)</a> .
------------	---

### 9.15 INT\_SOURCE (24h)

Interrupt source (read only)

7	6	5	4	3	2	1	0
BOOT_ON	0	0	0	0	IA	PL	PH

BOOT_ON	Indication of Boot phase. (0: Boot phase has ended; 1: Boot phase is running).
IA	Interrupt active. (0: no interrupt has been generated; 1: one or more interrupt events have been generated).
PL	Differential pressure Low. (0: no interrupt has been generated; 1: low differential pressure event has occurred).
PH	Differential pressure High. (0: no interrupt has been generated; 1: high differential pressure event has occurred).

### 9.16 FIFO\_STATUS1 (25h)

FIFO status register (read only)

7	6	5	4	3	2	1	0
FSS7	FSS6	FSS5	FSS4	FSS3	FSS2	FSS1	FSS0

FSS[7:0]	FIFO stored data level, number of unread samples stored in FIFO. (00000000: FIFO empty; 10000000: FIFO full, 128 unread samples)
----------	---

### 9.17 FIFO\_STATUS2 (26h)

FIFO status register (read only)

7	6	5	4	3	2	1	0
FIFO_WTM_IA	FIFO_OVR_IA	FIFO_FULL_IA	-	-	-	-	-

FIFO_WTM_IA	FIFO threshold (watermark) status. Default value: 0 (0: FIFO filling is lower than treshold level; 1: FIFO filling is equal or higher than treshold level).
FIFO_OVR_IA	FIFO overrun status. Default value: 0 (0: FIFO is not completely full; 1: FIFO is full and at least one sample in the FIFO has been overwritten).
FIFO_FULL_IA	FIFO full status. Default value: 0 (0: FIFO is not completely filled; 1: FIFO is completely filled, no samples overwritten)

### 9.18 STATUS (27h)

Status register (read only)

7	6	5	4	3	2	1	0
-	-	T_OR	P_OR	-	-	T_DA	P_DA

T_OR	Temperature data overrun. (0: no overrun has occurred; 1: a new data for temperature has overwritten the previous data)
P_OR	Pressure data overrun. (0: no overrun has occurred; 1: new data for pressure has overwritten the previous data)
T_DA	Temperature data available. (0: new data for temperature is not yet available; 1: a new temperature data is generated)
P_DA	Pressure data available. (0: new data for pressure is not yet available; 1: a new pressure data is generated)

This register is updated every ODR cycle.

### 9.19 PRESS\_OUT\_XL (28h)

Pressure output value LSB data (read only)

7	6	5	4	3	2	1	0
POUT7	POUT6	POUT5	POUT4	POUT3	POUT2	POUT1	POUT0

POUT[7:0]	This register contains the low part of the pressure output value.
-----------	---

The pressure output value is a 24-bit data that contains the measured pressure. It is composed of [PRESS\\_OUT\\_H \(2Ah\)](#), [PRESS\\_OUT\\_L \(29h\)](#) and [PRESS\\_OUT\\_XL \(28h\)](#). The value is expressed as 2's complement.

The output pressure register **PRESS\_OUT** is provided as the difference between the measured pressure and the content of the register **RPDS (18h, 19h)\***.

Please refer to [Section 4.5 Interpreting pressure readings](#) for additional info.

\*DIFF\_EN = '0', AUTOZERO = '0', AUTOREFP = '0'

### 9.20 PRESS\_OUT\_L (29h)

Pressure output value middle data (read only)

7	6	5	4	3	2	1	0
POUT15	POUT14	POUT13	POUT12	POUT11	POUT10	POUT9	POUT8

POUT[15:8]	This register contains the mid part of the pressure output value. Refer to <a href="#">PRESS_OUT_XL (28h)</a> .
------------	---

### 9.21 PRESS\_OUT\_H (2Ah)

Pressure output value MSB data (read only)

7	6	5	4	3	2	1	0
POUT23	POUT22	POUT21	POUT20	POUT19	POUT18	POUT7	POUT16

POUT[23:16]	This register contains the high part of the pressure output value. Refer to <a href="#">PRESS_OUT_XL (28h)</a> .
-------------	--

### 9.22 TEMP\_OUT\_L (2Bh)

Temperature output value LSB data (read only)

7	6	5	4	3	2	1	0
TOUT7	TOUT6	TOUT5	TOUT4	TOUT3	TOUT2	TOUT1	TOUT0

TOUT[7:0]	This register contains the low part of the temperature output value.
-----------	--

The temperature output value is 16-bit data that contains the measured temperature. It is composed of [TEMP\\_OUT\\_H \(2Ch\)](#) and [TEMP\\_OUT\\_L \(2Bh\)](#). The value is expressed as 2's complement.

### 9.23 TEMP\_OUT\_H (2Ch)

Temperature output value MSB data (read only)

7	6	5	4	3	2	1	0
TOUT15	TOUT14	TOUT13	TOUT12	TOUT11	TOUT10	TOUT9	TOUT8

TOUT[15:8]	This register contains the high part of the temperature output value.
------------	---

### 9.24 LPFP\_RES (3Ch)

Low-pass filter reset (read only)

If the LPFP is active, in order to avoid the transitory phase, the filter can be reset by reading this register before generating pressure measurements.

### 9.25 FIFO\_DATA\_OUT\_PRESS\_XL (78h)

FIFO pressure output LSB data (read only)

7	6	5	4	3	2	1	0
FIFO_P7	FIFO_P6	FIFO_P5	FIFO_P4	FIFO_P3	FIFO_P2	FIFO_P1	FIFO_P1

FIFO_P[7:0]	Pressure LSB data in FIFO buffer
-------------	----------------------------------

### 9.26 FIFO\_DATA\_OUT\_PRESS\_L (79h)

FIFO pressure output middle data (read only)

7	6	5	4	3	2	1	0
FIFO_P15	FIFO_P14	FIFO_P13	FIFO_P12	FIFO_P11	FIFO_P10	FIFO_P9	FIFO_P8

FIFO_P[15:8]	Pressure middle data in FIFO buffer
--------------	-------------------------------------

### 9.27 FIFO\_DATA\_OUT\_PRESS\_H (7Ah)

FIFO pressure output MSB data (read only)

7	6	5	4	3	2	1	0
FIFO_P23	FIFO_P22	FIFO_P21	FIFO_P20	FIFO_P19	FIFO_P18	FIFO_P17	FIFO_P16

FIFO_P[23:16]	Pressure MSB data in FIFO buffer
---------------	----------------------------------

### 9.28 FIFO\_DATA\_OUT\_TEMP\_L (7Bh)

FIFO temperature output LSB data (read only)

7	6	5	4	3	2	1	0
FIFO_T7	FIFO_T6	FIFO_T5	FIFO_T4	FIFO_T3	FIFO_T2	FIFO_T1	FIFO_T0

FIFO_T[7:0]	Temperature LSB data in FIFO buffer
-------------	-------------------------------------

### 9.29 FIFO\_DATA\_OUT\_TEMP\_H (7Ch)

Temperature LSB data in FIFO buffer

7	6	5	4	3	2	1	0
FIFO_T15	FIFO_T14	FIFO_T13	FIFO_T12	FIFO_T11	FIFO_T10	FIFO_T9	FIFO_T8

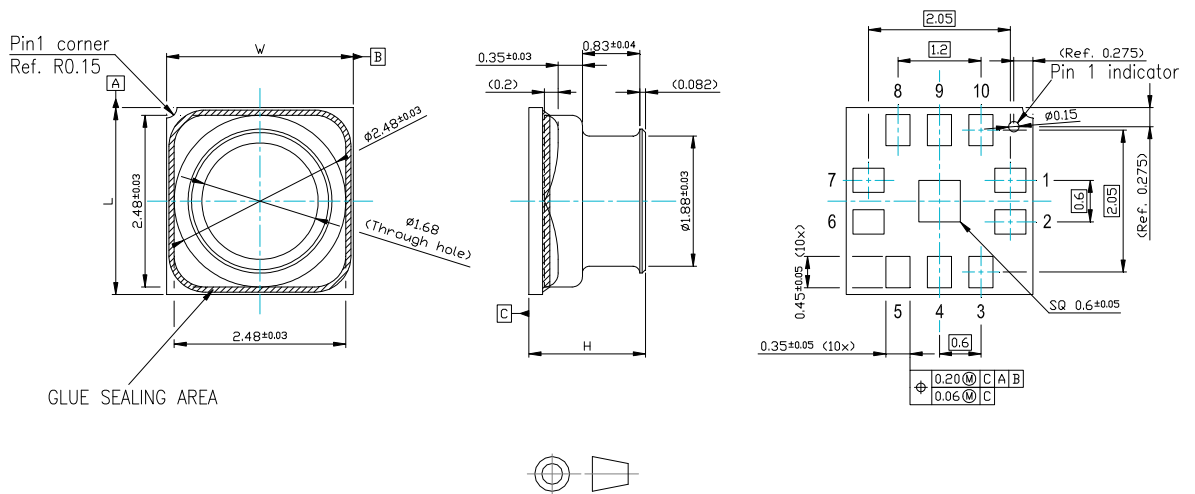
FIFO_T[15:8]	Temperature MSB data in FIFO buffer
--------------	-------------------------------------

## 10 Package information

In order to meet environmental requirements, ST offers these devices in different grades of **ECOPACK** packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com). ECOPACK is an ST trademark.

### 10.1 CCLGA-10L package information

Figure 27. CCLGA - 10L (2.7 x 2.7 x 1.7 typ. mm) package outline and mechanical data



Dimensions are in millimeter unless otherwise specified  
General Tolerance is +/-0.10mm unless otherwise specified

#### OUTER DIMENSIONS

ITEM	DIMENSION [mm]	TOLERANCE [mm]
Length [L]	2.7	±0.15
Width [W]	2.7	±0.15
Height [H]	1.85 MAX	/

DM00492423\_1

## 10.2 CCLGA-10L packing information

Figure 28. Carrier tape information for CCLGA-10L package

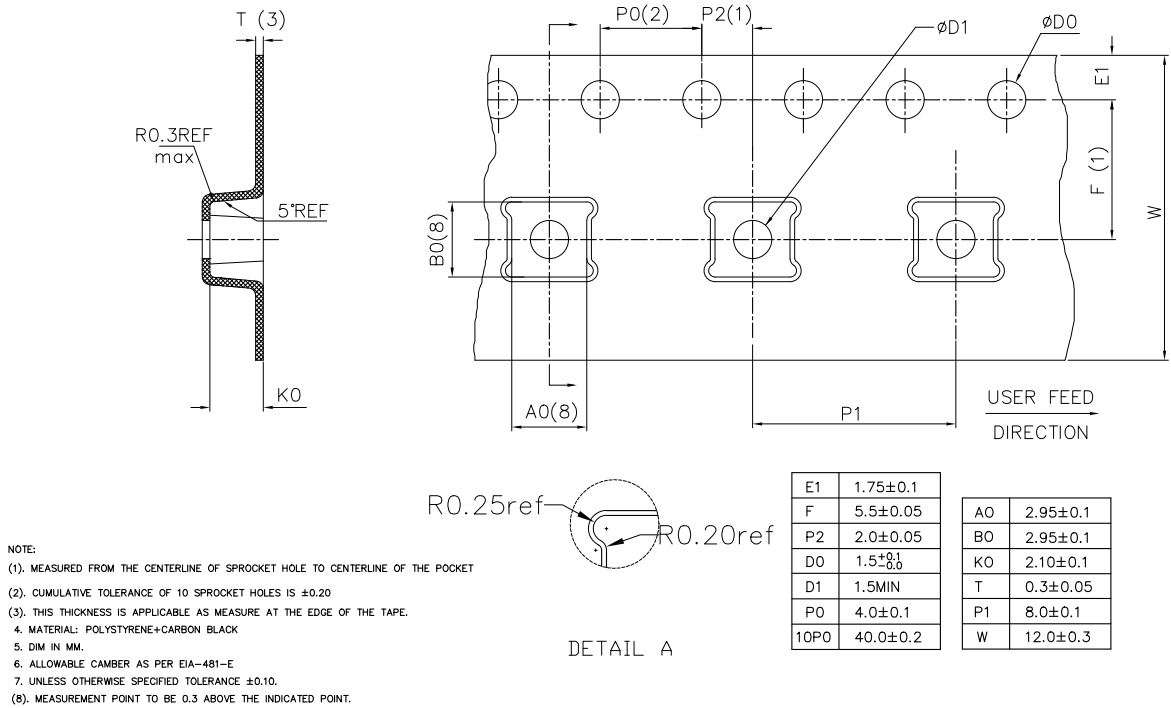


Figure 29. Package orientation in carrier tape



Figure 30. Reel information for carrier tape of CCLGA-10L package

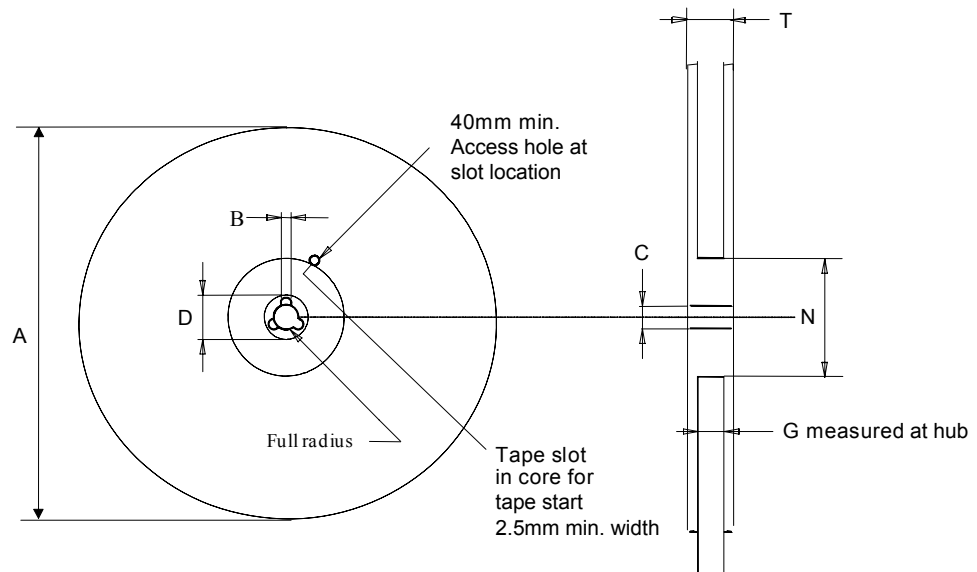


Table 23. Reel dimensions for carrier tape of CCLGA-10L package

Reel dimensions (mm)	
A (max)	330
B (min)	1.5
C	13 ±0.25
D (min)	20.2
N (min)	60
G	12.4 +2/-0
T (max)	18.4



## Contents

<b>1</b>	<b>Block diagrams</b>	<b>2</b>
<b>2</b>	<b>Pin description</b>	<b>3</b>
<b>3</b>	<b>Mechanical and electrical specifications</b>	<b>4</b>
3.1	Mechanical characteristics	4
3.2	Electrical characteristics	5
3.3	Communication interface characteristics	6
3.3.1	SPI - serial peripheral interface	6
3.3.2	I <sup>2</sup> C - inter-IC control interface	7
3.4	Absolute maximum ratings	8
<b>4</b>	<b>Functionality</b>	<b>9</b>
4.1	Sensing element	9
4.2	IC interface	9
4.3	Factory calibration	9
4.4	Device structure	10
4.5	Interpreting pressure readings	11
4.6	Interpreting temperature readings	11
<b>5</b>	<b>FIFO</b>	<b>12</b>
5.1	Bypass mode	13
5.2	FIFO mode	14
5.3	Continuous (Dynamic-Stream) mode	15
5.4	Bypass-to-FIFO mode	16
5.5	Bypass-to-Continuous (Dynamic-Stream) mode	17
5.6	Continuous (Dynamic-Stream)-to-FIFO mode	18
5.7	Retrieving data from FIFO	18
<b>6</b>	<b>Application hints</b>	<b>19</b>
6.1	Soldering information	20
<b>7</b>	<b>Digital interfaces</b>	<b>21</b>
7.1	Serial interfaces	21
7.2	I <sup>2</sup> C serial interface (CS = high)	21

7.2.1	I <sup>2</sup> C operation .....	22
<b>7.3</b>	<b>SPI bus interface (CS = low) .....</b>	<b>23</b>
7.3.1	SPI read .....	24
7.3.2	SPI write .....	25
7.3.3	SPI read in 3-wire mode .....	26
<b>7.4</b>	<b>MIPI I3C<sup>SM</sup> slave interface .....</b>	<b>27</b>
7.4.1	MIPI I3C <sup>SM</sup> CCC supported commands .....	27
<b>7.5</b>	<b>I<sup>2</sup>C/MIPI I3C<sup>SM</sup> coexistence in LPS27HHTW .....</b>	<b>29</b>
<b>8</b>	<b>Register mapping .....</b>	<b>31</b>
<b>9</b>	<b>Register description .....</b>	<b>33</b>
9.1	INTERRUPT_CFG (0Bh) .....	33
9.2	THS_P_L (0Ch) .....	35
9.3	THS_P_H (0Dh) .....	35
9.4	IF_CTRL (0Eh) .....	35
9.5	WHO_AM_I (0Fh) .....	36
9.6	CTRL_REG1 (10h) .....	36
9.7	CTRL_REG2 (11h) .....	37
9.8	CTRL_REG3 (12h) .....	39
9.9	FIFO_CTRL (13h) .....	40
9.10	FIFO_WTM (14h) .....	40
9.11	REF_P_L (15h) .....	41
9.12	REF_P_H (16h) .....	41
9.13	RPDS_L (18h) .....	41
9.14	RPDS_H (19h) .....	41
9.15	INT_SOURCE (24h) .....	42
9.16	FIFO_STATUS1 (25h) .....	42
9.17	FIFO_STATUS2 (26h) .....	42
9.18	STATUS (27h) .....	43
9.19	PRESS_OUT_XL (28h) .....	43
9.20	PRESS_OUT_L (29h) .....	43
9.21	PRESS_OUT_H (2Ah) .....	44

---

9.22	TEMP_OUT_L (2Bh) .....	44
9.23	TEMP_OUT_H (2Ch) .....	44
9.24	LPFP_RES (3Ch) .....	44
9.25	FIFO_DATA_OUT_PRESS_XL (78h) .....	44
9.26	FIFO_DATA_OUT_PRESS_L (79h) .....	45
9.27	FIFO_DATA_OUT_PRESS_H (7Ah).....	45
9.28	FIFO_DATA_OUT_TEMP_L (7Bh).....	45
9.29	FIFO_DATA_OUT_TEMP_H (7Ch).....	45
<b>10</b>	<b>Package information.....</b>	<b>46</b>
10.1	CCLGA-10L package information .....	46
10.2	CCLGA-10L packing information.....	47
<b>Contents .....</b>		<b>49</b>
<b>List of tables .....</b>		<b>52</b>
<b>List of figures.....</b>		<b>53</b>
<b>Revision history .....</b>		<b>54</b>

## List of tables

<b>Table 1.</b>	Pin description . . . . .	3
<b>Table 2.</b>	Pressure and temperature sensor characteristics . . . . .	4
<b>Table 3.</b>	Electrical characteristics . . . . .	5
<b>Table 4.</b>	DC characteristics . . . . .	5
<b>Table 5.</b>	SPI slave timing values . . . . .	6
<b>Table 6.</b>	I <sup>2</sup> C slave timing values . . . . .	7
<b>Table 7.</b>	Absolute maximum ratings . . . . .	8
<b>Table 8.</b>	Potting gel properties . . . . .	10
<b>Table 9.</b>	Serial interface pin description . . . . .	21
<b>Table 10.</b>	I <sup>2</sup> C terminology . . . . .	21
<b>Table 11.</b>	SAD+Read/Write patterns . . . . .	22
<b>Table 12.</b>	Transfer when master is writing one byte to slave . . . . .	22
<b>Table 13.</b>	Transfer when master is writing multiple bytes to slave . . . . .	22
<b>Table 14.</b>	Transfer when master is receiving (reading) one byte of data from slave . . . . .	22
<b>Table 15.</b>	Transfer when master is receiving (reading) multiple bytes of data from slave . . . . .	23
<b>Table 16.</b>	MIPI I3C <sup>SM</sup> CCC commands . . . . .	27
<b>Table 17.</b>	Registers address map . . . . .	31
<b>Table 18.</b>	Output data rate bit configurations . . . . .	36
<b>Table 19.</b>	Low-pass filter configurations . . . . .	37
<b>Table 20.</b>	RMS noise and power consumption . . . . .	38
<b>Table 21.</b>	Interrupt configurations . . . . .	39
<b>Table 22.</b>	FIFO mode selection . . . . .	40
<b>Table 23.</b>	Reel dimensions for carrier tape of CCLGA-10L package . . . . .	48
<b>Table 24.</b>	Document revision history . . . . .	54

## List of figures

<b>Figure 1.</b>	Device architecture block diagram . . . . .	2
<b>Figure 2.</b>	Digital logic . . . . .	2
<b>Figure 3.</b>	Pin connections (bottom view) . . . . .	3
<b>Figure 4.</b>	SPI slave timing diagram . . . . .	6
<b>Figure 5.</b>	I <sup>2</sup> C slave timing diagram . . . . .	7
<b>Figure 6.</b>	LPS27HHTW internal structure . . . . .	10
<b>Figure 7.</b>	Pressure readings . . . . .	11
<b>Figure 8.</b>	Temperature readings . . . . .	11
<b>Figure 9.</b>	Bypass mode . . . . .	13
<b>Figure 10.</b>	FIFO mode . . . . .	14
<b>Figure 11.</b>	Continuous (Dynamic-Stream) mode . . . . .	15
<b>Figure 12.</b>	Bypass-to-FIFO mode . . . . .	16
<b>Figure 13.</b>	Bypass-to-Continuous (Dynamic-Stream) mode . . . . .	17
<b>Figure 14.</b>	Continuous (Dynamic-Stream)-to-FIFO mode . . . . .	18
<b>Figure 15.</b>	LPS27HHTW electrical connections (top view) . . . . .	19
<b>Figure 16.</b>	LPS27HHTW power-off sequence . . . . .	20
<b>Figure 17.</b>	Read and write protocol . . . . .	23
<b>Figure 18.</b>	SPI read protocol . . . . .	24
<b>Figure 19.</b>	Multiple byte SPI read protocol (2-byte example) . . . . .	24
<b>Figure 20.</b>	SPI write protocol . . . . .	25
<b>Figure 21.</b>	Multiple byte SPI write protocol (2-byte example) . . . . .	25
<b>Figure 22.</b>	SPI read protocol in 3-wire mode . . . . .	26
<b>Figure 23.</b>	I <sup>2</sup> C and MIPI I3C <sup>SM</sup> both active (INT_DRDY pin not connected) . . . . .	29
<b>Figure 24.</b>	Only MIPI I3C <sup>SM</sup> active (INT_DRDY pin connected to Vdd_IO) . . . . .	30
<b>Figure 25.</b>	“Threshold-based” interrupt event . . . . .	34
<b>Figure 26.</b>	Interrupt events on INT_DRDY pin . . . . .	39
<b>Figure 27.</b>	CCLGA - 10L (2.7 x 2.7 x 1.7 typ. mm) package outline and mechanical data . . . . .	46
<b>Figure 28.</b>	Carrier tape information for CCLGA-10L package . . . . .	47
<b>Figure 29.</b>	Package orientation in carrier tape . . . . .	47
<b>Figure 30.</b>	Reel information for carrier tape of CCLGA-10L package . . . . .	48

## Revision history

**Table 24. Document revision history**

Date	Version	Changes
12-Jan-2021	1	Initial release

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