# KAI-02150

# 1920 (H) x 1080 (V) Interline CCD Image Sensor

#### **Description**

The KAI–02150 Image Sensor is a 1080p (1920  $\times$  1080) CCD in a 2/3″ optical format. Based on the TRUESENSE 5.5-micron Interline Transfer CCD Platform, the sensor features broad dynamic range, excellent imaging performance, and a flexible readout architecture that enables use of 1, 2, or 4 outputs for full resolution readout up to 64 frames per second. A vertical overflow drain structure suppresses image blooming and enables electronic shuttering for precise exposure control.

## **Table 1. GENERAL SPECIFICATIONS**



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#### **Figure 1. KAI−02150 Interline CCD Image Sensor**

## **Features**

- Bayer Color Pattern, TRUESENSE Sparse Color Filter Pattern, and Monochrome Configurations
- Progressive Scan Readout
- Flexible Readout Architecture
- High Frame Rate
- High Sensitivity
- Low Noise Architecture
- Excellent Smear Performance
- Package Pin Reserved for Device Identification

## **Applications**

- Industrial Imaging
- Medical Imaging
- Security

#### **ORDERING INFORMATION**

See detailed ordering and shipping information on page 2 of this data sheet.

The sensor is available with the TRUESENSE Sparse Color Filter Pattern, a technology which provides a 2x improvement in light sensitivity compared to a standard color Bayer part.

The sensor shares common PGA pin-out and electrical configurations with other devices based on the TRUESENSE 5.5 micron Interline Transfer CCD Platform, allowing a single camera design to support multiple members of this sensor family.

#### **ORDERING INFORMATION**

#### **Standard Devices**

See full datasheet for ordering information associated with devices no longer recommended for new designs.





See the ON Semiconductor *Device Nomenclature* document (TND310/D) for a full description of the naming convention used for image sensors. For reference documentation, including information on evaluation kits, please visit our web site at [www.onsemi.com.](http://onsemi.com)

## **Not Recommended for New Designs**

## **Table 3. ORDERING INFORMATION − NOT RECOMMENDED FOR NEW DESIGNS**



## **DEVICE DESCRIPTION**

#### **Architecture**



**Figure 2. Block Diagram**

#### **Dark Reference Pixels**

There are 12 dark reference rows at the top and 12 dark rows at the bottom of the image sensor. The dark rows are not entirely dark and so should not be used for a dark reference level. Use the 22 dark columns on the left or right side of the image sensor as a dark reference.

Under normal circumstances use only the center 20 columns of the 22 column dark reference due to potential light leakage.

#### **Dummy Pixels**

Within each horizontal shift register there are 11 leading additional shift phases. These pixels are designated as dummy pixels and should not be used to determine a dark reference level.

In addition, there is one dummy row of pixels at the top and bottom of the image.

#### **Active Buffer Pixels**

20 unshielded pixels adjacent to any leading or trailing dark reference regions are classified as active buffer pixels.

These pixels are light sensitive but are not tested for defects and non-uniformities.

#### **Image Acquisition**

An electronic representation of an image is formed when incident photons falling on the sensor plane create electron-hole pairs within the individual silicon photodiodes. These photoelectrons are collected locally by the formation of potential wells at each photosite. Below photodiode saturation, the number of photoelectrons collected at each pixel is linearly dependent upon light level and exposure time and non-linearly dependent on wavelength. When the photodiodes charge capacity is reached, excess electrons are discharged into the substrate to prevent blooming.

#### **ESD Protection**

Adherence to the power-up and power-down sequence is critical. Failure to follow the proper power-up and power-down sequences may cause damage to the sensor. See Power-Up and Power-Down Sequence section.

#### **Bayer Color Filter Pattern**





#### **TRUESENSE Sparse Color Filter Pattern**



#### **Figure 4. TRUESENSE Sparse Color Filter Pattern**

# <span id="page-5-0"></span>**Physical Description**

*Pin Grid Array Pin Description*



**Figure 5. PGA Package Pin Designations − Top View**

### **Table 4. PGA PACKAGE PIN DESCRIPTION**



# **Pin Name Description** 25 Rb Reset Gate, Quadrant b 26 | RDb | Reset Drain, Quadrant b 27 | GND | Ground 28 | VOUTb | Video Output, Quadrant b 29 | VDDb | Output Amplifier Supply, Quadrant b V2B Vertical CCD Clock, Phase 2, Bottom V1B Vertical CCD Clock, Phase 1, Bottom V4B Vertical CCD Clock, Phase 4, Bottom V3B Vertical CCD Clock, Phase 3, Bottom 34 | ESD | ESD Protection Disable V3T Vertical CCD Clock, Phase 3, Top DevID Device Identification V1T Vertical CCD Clock, Phase 1, Top V4T Vertical CCD Clock, Phase 4, Top VDDd Output Amplifier Supply, Quadrant d V2T Vertical CCD Clock, Phase 2, Top GND Ground VOUTd Video Output, Quadrant d 43 Rd Reset Gate, Quadrant d RDd Reset Drain, Quadrant d 45 | H2SLd | Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant d OGd Output Gate, Quadrant d 47 H1Bd Horizontal CCD Clock, Phase 1, Barrier, Quadrant d H2Bd Horizontal CCD Clock, Phase 2, Barrier, Quadrant d H2Sd Horizontal CCD Clock, Phase 2, Storage, Quadrant d H1Sd Horizontal CCD Clock, Phase 1, Storage, Quadrant d 51 | N/C | No Connect SUB Substrate H2Sc Horizontal CCD Clock, Phase 2, Storage, Quadrant c H1Sc Horizontal CCD Clock, Phase 1, Storage, Quadrant c H1Bc Horizontal CCD Clock, Phase 1, Barrier, Quadrant c H2Bc Horizontal CCD Clock, Phase 2, Barrier, Quadrant c H2SLc Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant c OGc Output Gate, Quadrant c 59 Rc Rc Reset Gate, Quadrant c RDc Reset Drain, Quadrant c 61 | GND Ground VOUTc Video Output, Quadrant c 63 VDDc Joutput Amplifier Supply, Quadrant c V2T Vertical CCD Clock, Phase 2, Top V1T Vertical CCD Clock, Phase 1, Top V4T Vertical CCD Clock, Phase 4, Top V3T Vertical CCD Clock, Phase 3, Top 68 | ESD | EDS Protection Disable

#### **Table [4](#page-5-0). PGA PACKAGE PIN DESCRIPTION** (continued)

1. Liked named pins are internally connected and should have a common drive signal.

2. N/C pins (17, 51) should be left floating.

<span id="page-7-0"></span>*Ceramic Leadless Chip Carrier Pin Description*







#### **Table 5. CLCC PACKAGE PIN DESCRIPTION**



## **Table [5](#page-7-0). CLCC PACKAGE PIN DESCRIPTION** (continued)

1. Liked named pins are internally connected and should have a common drive signal.

# <span id="page-9-0"></span>**IMAGING PERFORMANCE**

#### **Typical Operational Conditions**

Unless otherwise noted, the Imaging Performance Specifications are measured using the following conditions.

#### **Table 6. TYPICAL OPERATIONAL CONDITIONS**



1. For monochrome sensor, only green LED used.

#### **Specifications**

### **Table 7. PERFORMANCE SPECIFICATIONS**



## <span id="page-10-0"></span>**Table [7](#page-9-0). PERFORMANCE SPECIFICATIONS** (continued)



3. The operating value of the substrate voltage, V<sub>AB</sub>, will be marked on the shipping container for each device. The value of V<sub>AB</sub> is set such<br>that the photodiode charge capacity is 680 mV.

4. At 40 MHz.

5. Uses 20LOG (P<sub>Ne</sub> / n<sub>e−T</sub>).<br>6. Assumes 5 pF load.

7. This color filter set configuration (Gen1) is not recommended for new designs.

## **TYPICAL PERFORMANCE CURVES**

#### **Quantum Efficiency**

*Monochrome with Microlens*



NOTE: The PGA and CLCC versions have different quantum efficiencies due to differences in the cover glass transmission. See Figure [35:](#page-35-0) Cover Glass Transmission for more details.

**Figure 7. Monochrome with Microlens Quantum Efficiency**



*Monochrome without Microlens*

**Figure 8. Monochrome without Microlens Quantum Efficiency**

*Color (Bayer RGB) with Microlens and MAR Cover Glass (Gen2 and Gen1 CFA)*



**Figure 9. MAR Glass Color (Bayer) with Microlens Quantum Efficiency**

*Color (Bayer RGB) with Microlens and Clear Cover Glass (Gen2 and Gen1 CFA)*



**Figure 10. Clear Glass Color (Bayer) with Microlens Quantum Efficiency**

*Color (TRUESENSE Sparse CFA) with Microlens (Gen2 and Gen1 CFA)*



**Figure 11. Color (TRUESENSE Sparse CFA) with Microlens Quantum Efficiency**

#### **Angular Quantum Efficiency**

For the curves marked "Horizontal", the incident light angle is varied in a plane parallel to the HCCD. For the curves marked "Vertical", the incident light angle is varied in a plane parallel to the VCCD.

*Monochrome with Microlens*



**Figure 12. Monochrome with Microlens Angular Quantum Efficiency**

## **Dark Current vs. Temperature**



**Figure 13. Dark Current vs. Temperature**



**Power-Estimated**

**Figure 14. Power**

# **Frame Rates**



**Figure 15. Frame Rates**

## <span id="page-16-0"></span>**DEFECT DEFINITIONS**

#### Table 8. OPERATION CONDITIONS FOR DEFECT TESTING AT 40°C



1. Horizontal overclocking used.

2. Vertical overclocking used.

3. VCCD Integration  $\overline{\text{Time}} = 572$  lines  $\times$  Line Time, which is the total time a pixel will spend in the VCCD registers.

4. For monochrome sensor, only the green LED is used.

#### Table 9. DEFECT DEFINITIONS FOR TESTING AT 40°C



1. For the color device (KAI−02150−FBA, KAI−02150−CBA, KAI−02150−QBA, or KAI−02150−PBA), a bright field defective pixel deviates by 12% with respect to pixels of the same color.

2. Column and cluster defects are separated by no less than two (2) good pixels in any direction (excluding single pixel defects).

## Table 10. OPERATION CONDITIONS FOR DEFECT TESTING AT 27°C



1. Horizontal overclocking used.

2. Vertical overclocking used.

3. VCCD Integration Time = 572 lines  $\times$  Line Time, which is the total time a pixel will spend in the VCCD registers.

4. For monochrome sensor, only the green LED is used.

#### Table 11. DEFECT DEFINITIONS FOR TESTING AT 40°C



1. For the color device (KAI−02150−FBA, KAI−02150−CBA, KAI−02150−QBA, or KAI−02150−PBA), a bright field defective pixel deviates by 12% with respect to pixels of the same color.

2. Column and cluster defects are separated by no less than two (2) good pixels in any direction (excluding single pixel defects).

## **Defect Map**

The defect map supplied with each sensor is based upon testing at an ambient (27°C) temperature. Minor point defects are not included in the defect map. All defective

pixels are reference to pixel 1, 1 in the defect maps. See Figure [16](#page-18-0): Regions of Interest for the location of pixel 1, 1.

# <span id="page-18-0"></span>**TEST DEFINITIONS**

#### **Test Regions of Interest**



Only the Active Area ROI pixels are used for performance and defect tests.

### **Overclocking**

The test system timing is configured such that the sensor is overclocked in both the vertical and horizontal directions. See Figure 16 for a pictorial representation of the regions of interest.



**Figure 16. Regions of Interest**

#### **Tests**

#### *Dark Field Global Non-Uniformity*

This test is performed under dark field conditions. The sensor is partitioned into 144 sub regions of interest, each of which is 120 by 120 pixels in size. See Figure [17](#page-19-0): Test Sub Regions of Interest. The average signal level of each of the 144 sub regions of interest is calculated. The signal level of each of the sub regions of interest is calculated using the following formula:

- Signal of  $ROI[i] = (ROI Average in Counts -$ 
	- $-$  Horizontal Overclock Average in Counts)  $\cdot$
	- mV per Count

```
Units : mVpp (millivolts Peak to Peak)
```
Where  $i = 1$  to 144. During this calculation on the 144 sub regions of interest, the maximum and minimum signal levels are found. The dark field global uniformity is then calculated as the maximum signal found minus the minimum signal level found.

#### *Global Non-Uniformity*

This test is performed with the imager illuminated to a level such that the output is at 70% of saturation (approximately 476 mV). Prior to this test being performed the substrate

voltage has been set such that the charge capacity of the sensor is 680 mV. Global non-uniformity is defined as

Global Non–Uniformity = 
$$
100 \cdot \left( \frac{\text{Active Area Standard Deviation}}{\text{Active Area Signal}} \right)
$$

\nUnits: % rms

\nLet's large inverse, Red's Solving Average

Active Area Signal = Active Area Average − Dark Column Average

#### *Global Peak to Peak Non-Uniformity*

This test is performed with the imager illuminated to a level such that the output is at 70% of saturation (approximately 476 mV). Prior to this test being performed the substrate voltage has been set such that the charge capacity of the sensor is 680 mV. The sensor is partitioned into 144 sub regions of interest, each of which is 120 by 120 pixels in size. See Figure [17:](#page-19-0) Test Sub Regions of Interest. The average signal level of each of the 144 sub regions of interest (ROI) is calculated. The signal level of each of the sub regions of interest is calculated using the following formula:

Signal of  $ROI[i] = (ROI Average in Counts -$ 

- $-$  Horizontal Overclock Average in Counts)  $\cdot$ 
	- mV per Count

<span id="page-19-0"></span>Where  $i = 1$  to 144. During this calculation on the 144 sub regions of interest, the maximum and minimum signal levels are found. The global peak to peak uniformity is then calculated as:

Global Uniformity = 
$$
100 \cdot \left( \frac{\text{Max. Signal} - \text{Min. Signal}}{\text{Active Area Signal}} \right)
$$
  
 Units : % pp

#### *Center Non-Uniformity*

This test is performed with the imager illuminated to a level such that the output is at 70% of saturation (approximately 476 mV). Prior to this test being performed the substrate voltage has been set such that the charge capacity of the sensor is 680 mV. Defects are excluded for the calculation of this test. This test is performed on the center 100 by 100 pixels of the sensor. Center uniformity is defined as:

Center ROI Uniformity = 100 ·  $\left(\frac{\text{Center ROI Standard Deviation}}{\text{Center ROI Signal}}\right)$ 

Units : % rms

Center ROI Signal = Center ROI Average − Dark Colum Average

#### *Dark Field Defect Test*

This test is performed under dark field conditions. The sensor is partitioned into 144 sub regions of interest, each of which is 120 by 120 pixels in size. In each region of interest, the median value of all pixels is found. For each region of interest, a pixel is marked defective if it is greater than or equal to the median value of that region of interest plus the defect threshold specified in the "Defect Definitions" section.

#### *Bright Field Defect Test*

This test is performed with the imager illuminated to a level such that the output is at approximately 476 mV.

Prior to this test being performed the substrate voltage has been set such that the charge capacity of the sensor is 680 mV. The average signal level of all active pixels is found. The bright and dark thresholds are set as:

Dark Defect Threshold = Active Area Signal  $\cdot$  Threshold

#### Bright Defect Threshold = Active Area Signal  $\cdot$  Threshold

The sensor is then partitioned into 144 sub regions of interest, each of which is 120 by 120 pixels in size. In each region of interest, the average value of all pixels is found. For each region of interest, a pixel is marked defective if it is greater than or equal to the median value of that region of interest plus the bright threshold specified or if it is less than or equal to the median value of that region of interest minus the dark threshold specified.

Example for major bright field defective pixels:

- Average value of all active pixels is found to be 476 mV.
- Dark defect threshold:  $476 \text{ mV} \cdot 12 \% = 57 \text{ mV}$ .
- Bright defect threshold:  $476 \text{ mV} \cdot 12\% = 57 \text{ mV}$ .
- Region of interest #1 selected. This region of interest is pixels 21, 21 to pixels 140, 140.
	- ♦ Median of this region of interest is found to be 470 mV.
	- ♦ Any pixel in this region of interest that is  $\geq$  (470 + 57 mV) 527 mV in intensity will be marked defective.
	- $\triangle$  Any pixel in this region of interest that is  $\leq$  (470 – 57 mV) 413 mV in intensity will be marked defective.
- All remaining 144 sub regions of interest are analyzed for defective pixels in the same manner.

*Test Sub Regions of Interest*

129	130	131	132	133	134	135	136	137	138	139	140	141	142	143	144
113	114	115	116	117	118	119	120	121	122	123	124	125	126	127	128
97	98	99	100	101	102	103	104	105	106	107	108	109	110	111	112
81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96
65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80
49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64
33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48
17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32
1	$\overline{c}$	3	4	5	6	$\overline{7}$	8	9	10	11	12	13	14	15	16
<b>21 21)</b>															

Pixel (1940,1100)

Pixel (21,21) VOUTa

**Figure 17. Test Sub Regions of Interest**

# **OPERATION**

#### **Absolute Maximum Ratings**

Absolute maximum rating is defined as a level or condition that should not be exceeded at any time per the description. If the level or the condition is exceeded, the device will be degraded and may be damaged. Operation at these values will reduce MTTF.

#### **Table 12. ABSOLUTE MAXIMUM RATINGS**



Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. Noise performance will degrade at higher temperatures.

2.  $T = 25^{\circ}$ C. Excessive humidity will degrade MTTF.

3. Total for all outputs. Maximum current is −15 mA for each output. Avoid shorting output pins to ground or any low impedance source during operation. Amplifier bandwidth increases at higher current and lower load capacitance at the expense of reduced gain (sensitivity).

#### **Table 13. ABSOLUTE MAXIMUM VOLTAGE RATINGS BETWEEN PINS AND GROUND**



1.  $\alpha$  denotes a, b, c or d.

2. Refer to Application Note Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions

#### **Power-Up and Power-Down Sequence**

Adherence to the power-up and power-down sequence is critical. Failure to follow the proper power-up and power-down sequences may cause damage to the sensor.



#### Notes:

- 1. Activate all other biases when ESD is stable and SUB is above 3 V.
- 2. Do not pulse the electronic shutter until ESD is stable.
- 3. VDD cannot be +15 V when SUB is 0 V.
- 4. The image sensor can be protected from an accidental improper ESD voltage by current limiting the SUB current to less than 10 mA. SUB and VDD must always be greater than GND. ESD must always be less than GND. Placing diodes between SUB, VDD, ESD and ground will protect the sensor from accidental overshoots of SUB, VDD and ESD during power on and power off. See the figure below.



The VCCD clock waveform must not have a negative overshoot more than 0.4 V below the ESD voltage.



**Figure 19. VCCD Clock Waveform**

Example of external diode protection for SUB, VDD and ESD. $\alpha$  denotes a, b, c or d.





#### **DC Bias Operating Conditions**





1.  $\alpha$  denotes a, b, c or d.

2. The maximum DC current is for one output.  $I_{DD} = I_{OUT} + I_{SS}$ . See Figure 21.

3. The operating value of the substrate voltage, V<sub>AB</sub>, will be marked on the shipping container for each device. The value of V<sub>AB</sub> is set such that the photodiode charge capacity is the nominal  $P_{Ne}$  (see Specifications).

4. An output load sink must be applied to each VOUT pin to activate each output amplifier.

5. Nominal value required for 40 MHz operation per output. May be reduced for slower data rates and lower noise.

6. Adherence to the power-up and power-down sequence is critical. See Power Up and Power Down Sequence section.

7. ESD maximum value must be less than or equal to  $V1_L + 0.4 V$  and  $V2_L + 0.4 V$ .

8. Refer to Application Note Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions.

9. Where Vx\_L is the level set for V1\_L, V2\_L, V3\_L, or V4\_L in the application.



**Figure 21. Output Amplifier**

## **AC Operating Conditions**

#### **Table 15. CLOCK LEVELS**



1.  $\alpha$  denotes a, b, c or d.

2. Capacitance is total for all like named pins.

3. Use separate clock driver for improved speed performance.

4. Reset low should be set to –3 V for signal levels greater than 40,000 electrons.

5. Refer to Application Note Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions.

6. Capacitance values are estimated.

7. If the minimum horizontal clock low level is used (–5.2 V), then the maximum horizontal clock amplitude should be used (5.2 V amplitude) to create a –5.2 V to 0.0 V clock. If a 5 V clock driver is used, the horizontal low level should be set to –5.0 V and the high level should be a set to 0.0 V.

The figure below shows the DC bias (VSUB) and AC clock (VES) applied to the SUB pin. Both the DC bias and AC clock are referenced to ground.



**Figure 22. DC Bias and AC Clock Applied to the SUB Pin**

#### **Device Identification**

The device identification pin (DevID) may be used to determine which Truesense Imaging 5.5 micron pixel interline CCD sensor is being used.

#### **Table 16.**



1. Nominal value subject to verification and/or change during release of preliminary specifications.

2. If the Device Identification is not used, it may be left disconnected.

3. After Device Identification resistance has been read during camera initialization, it is recommended that the circuit be disabled to prevent localized heating of the sensor due to current flow through the R\_DeviceID resistor.

#### *Recommended Circuit*

Note that V1 must be a different value than V2.





## <span id="page-25-0"></span>**TIMING**





1. Refer to timing diagrams as shown in Figure [24,](#page-27-0) Figure [25,](#page-27-0) Figure [26,](#page-28-0) Figure [27](#page-28-0) and Figure [28](#page-28-0).

2. Refer to Figure [28:](#page-28-0) VCCD Clock Edge Alignment.

3. Relative to the pulse width.

#### **Timing Diagrams**

The timing sequence for the clocked device pins may be represented as one of seven patterns (P1−P7) as shown in the table below. The patterns are defined in Figure [24](#page-27-0) and Figure [25](#page-27-0). Contact Truesense Imaging Application Engineering for other readout modes.

#### **Table 18. TIMING DIAGRAMS**



## <span id="page-26-0"></span>**Table [18](#page-25-0). TIMING DIAGRAMS** (continued)





1. For optimal performance of the sensor. May be clocked at a lower frequency. If clocked at a lower frequency, the frequency selected should be a multiple of the frequency used on the a and b register.

2. H2SLx follows the same pattern as H2Sx For optimal speed performance, use a separate clock driver.

3. Off = +5 V. Note that there may be operating conditions (high temperature and/or very bright light sources) that will cause blooming from the unused c/d register into the image area.

#### <span id="page-27-0"></span>*Photodiode Transfer Timing*

A row of charge is transferred to the HCCD on the falling edge of V1 as indicated in the P1 pattern below. Using this timing sequence, the leading dummy row or line is combined with the first dark row in the HCCD. The "Last Line" is dependent on readout mode – either 572 or 1144 minimum counts required. It is important to note that, in

general, the rising edge of a vertical clock (patterns P1−P4) should be coincident or slightly leading a falling edge at the same time interval. This is particularly true at the point where P1 returns from the high (3<sup>rd</sup> level) state to the mid-state when P4 transitions from the low state to the high state.



**Figure 24. Photodiode Transfer Timing**

#### *Line and Pixel Timing*

Each row of charge is transferred to the output, as illustrated below, on the falling edge of H2SL (indicated as

P6 pattern). The number of pixels in a row is dependent on readout mode – either 1013 or 2026 minimum counts required.





<span id="page-28-0"></span>*Pixel Timing Detail*



**Figure 26. Pixel Timing Detail**

## *Frame/Electronic Shutter Timing*

The SUB pin may be optionally clocked to provide electronic shuttering capability as shown below. The

resulting photodiode integration time is defined from the falling edge of SUB to the falling edge of V1 (P1 pattern).



**Figure 27. Frame/Electronic Shutter Timing**

*VCCD Clock Edge Alignment*









#### **STORAGE AND HANDLING**

#### **Table 19. STORAGE CONDITIONS**



1. Long-term storage toward the maximum temperature will accelerate color filter degradation.

2.  $T = 25^{\circ}$ C. Excessive humidity will degrade MTTF.

For information on ESD and cover glass care and cleanliness, please download the *Image Sensor Handling and Best Practices* Application Note (AN52561/D) from [www.onsemi.com.](http://onsemi.com)

For information on environmental exposure, please download the *Using Interline CCD Image Sensors in High Intensity Lighting Conditions* Application Note (AND9183/D) from [www.onsemi.com](http://onsemi.com).

For information on soldering recommendations, please download the Soldering and Mounting Techniques Reference Manual (SOLDERRM/D) from [www.onsemi.com.](http://onsemi.com)

For quality and reliability information, please download the *Quality & Reliability* Handbook (HBD851/D) from [www.onsemi.com.](http://onsemi.com)

For information on device numbering and ordering codes, please download the *Device Nomenclature* technical note (TND310/D) from [www.onsemi.com](http://onsemi.com).

For information on Standard terms and Conditions of Sale, please download [Terms and Conditions](http://www.onsemi.com/site/pdf/ONSEMI_T&C.pdf) from [www.onsemi.com.](http://onsemi.com)

## **MECHANICAL INFORMATION**

#### **PGA Completed Assembly**



Notes:

- 1. See Ordering Information for marking code.
- 2. No materials to interfere with clearance through guide holes.
- 3. The center of the active image is nominally at the center of the package.
- 4. Die rotation < 0.5 degrees.
- 5. Glass rotation < 1.5 degrees with respect to package outer edges for all sealed configurations.
- 
- 6. Internal traces may be exposed on sides of package. Do not allow metal to contact sides of ceramic package. 7. Recommended mounting screws:1.6 × 0.35 mm (ISO Standard); 0–80 (Unified Fine Thread Standard).

8. Units: millimeters.

#### **Figure 30. PGA Completed Assembly**

## **CLCC Completed Assembly**



3. Units: millimeters.

**Figure 31. CLCC Completed Assembly**



Notes:

- 1. Dust/Scratch Count 12 micron maximum
- 2. Units: IN [MM]
- 3. Reflectance Specification
	- a. 420 nm to 435 nm < 2.0%
	- b. 435 nm to 630 nm < 0.8% c. 630 nm to 680 nm < 2.0%



## **CLCC MAR Cover Glass**





Notes:

- 1. Dust/Scratch Count 12 micron maximum
- 2. Units: millimeter
- 3. Reflectance Specification
	- a. 420 nm to 435 nm < 2.0%
	- b. 435 nm to 630 nm < 0.8%
		- c. 630 nm to 680 nm < 2.0%



#### <span id="page-35-0"></span>**PGA Clear Cover Glass**



#### Notes:

1. Dust/Scratch Count – 12 micron maximum

2. Units: IN

**Figure 34. PGA Clear Cover Glass**



## **Cover Glass Transmission**

NOTE: PGA and CLCC MAR transmission data differ due to in-spec differences from glass vendor.

**Figure 35. Cover Glass Transmission**

## **SHIPPING CONFIGURATION**

#### **Cover Glass Protective Tape**

Cover glass protective tape, as shown in Figure 36, is utilized to help ensure the cleanliness of the cover glass during transportation and camera manufacturing. This protective tape is not intended to be optically correct, and

should be removed prior to any image testing. The protective tape should be removed in an ionized air stream to prevent static build-up and the attraction of particles. The following part numbers will have the protective tape applied:

#### **Table 20.**



#### **Table 21.**







# **Tray Packing**

The following part numbers are packed in bricks of 6 trays, each tray containing 32 image sensors, for a total of

192 image sensors per brick. The minimum order and multiple quantities for this configuration are 192 image sensors.

#### **Table 22.**



## *Tray Configuration*

# Pin-Up View



**Figure 37. Tray Pin-Up View**



## Pin-Down View

**Figure 38. Tray Pin-Down View**

## *Brick Configuration*

Bricks consist of 6 full trays and 1 empty tray. Each tray contains 32 image sensors. There are a total of 192 image

sensors in the brick. The ID label is applied to the top of the brick. Tray 1 is at the bottom of the brick and the empty tray is at the top of the brick.



# **Figure 39. Brick**

The Brick ID is Encoded in the Bar Code.



**Figure 40. Brick ID Label**

*Brick in Vacuum Sealed Bag*



**Figure 41. Sealed Brick**

*Shipping Container* Brick Loaded in Shipping Container



**Figure 42. Brick Loaded in Shipping Container**

Open Shipping Container with Parts List

The parts list (see Figure [46](#page-40-0)) details information for each sensor in the brick. The parts list includes the serial number, tray and location, and VAB value for each sensor.



**Figure 43. Open Shipping Container with Parts List**

#### Sealed Shipping Container

The Brick Label (see Figure [45\)](#page-40-0) is applied to both ends of the shipping container.



**Figure 44. Sealed Shipping Container**

## <span id="page-40-0"></span>Brick Label



**Figure 45. Brick Label**

#### *Parts List*

The parts list details information for each sensor in the brick. The parts list includes the serial number, tray and location, and VAB value for each sensor. Additionally, the VAB value and serial number are encoded in the bar code.



**Figure 46. Parts List**

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