# **NXB0102**

# Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 01 — 8 June 2010

**Product data sheet** 

### 1. General description

The NXB0102 is a 2-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two data input-output ports (An and Bn), one output enable input (OE) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied at any voltage between 1.2 V and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between 1.65 V and 5.5 V, making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and OE are referenced to  $V_{CC(A)}$  and pins Bn are referenced to  $V_{CC(B)}$ . A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

#### 2. Features and benefits

- Wide supply voltage range:
  - ◆ V<sub>CC(A)</sub>: 1.2 V to 3.6 V and V<sub>CC(B)</sub>: 1.65 V to 5.5 V
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - ◆ HBM JESD22-A114E Class 2 exceeds 2500 V for A port
  - ◆ HBM JESD22-A114E Class 3B exceeds 15000 V for B port
  - MM JESD22-A115-A exceeds 200 V
  - CDM JESD22-C101E exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C



Dual supply translating transceiver; auto direction sensing; 3-state

# 3. Ordering information

Table 1. Ordering information

Type number	Package								
	Temperature range	Name	Description	Version					
NXB0102DP	-40 °C to +125 °C	TSSOP8	plastic thin shrink small outline package; 8 leads; body width 3 mm; lead length 0.5 mm	SOT505-2					
NXB0102GT	–40 °C to +125 °C	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body 1 $\times$ 1.95 $\times$ 0.5 mm	SOT833-1					
NXB0102GD	–40 °C to +125 °C	XSON8U	plastic extremely thin small outline package; no leads; 8 terminals; UTLP based; body $3\times2\times0.5$ mm	SOT996-2					
NXB0102GF	–40 °C to +125 °C	XSON8	extremely thin small outline package; no leads; 8 terminals; body $1.35 \times 1 \times 0.5$ mm	SOT1089					

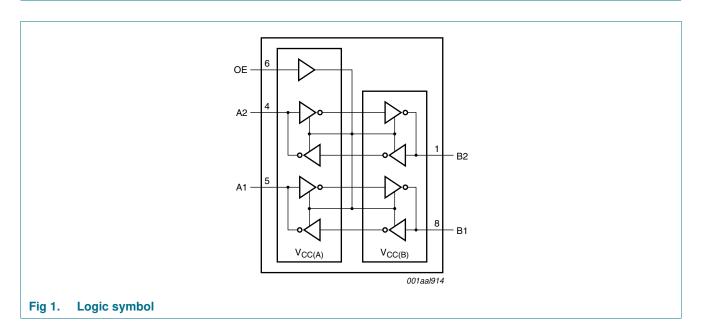
# 4. Marking

Table 2. Marking

Type number	Marking code <sup>[1]</sup>
NXB0102DP	t02
NXB0102GT	t02
NXB0102GD	t02
NXB0102GF	t2

<sup>[1]</sup> The pin 1 indicator is located on the lower left corner of the device, below the marking code.

# 5. Functional diagram

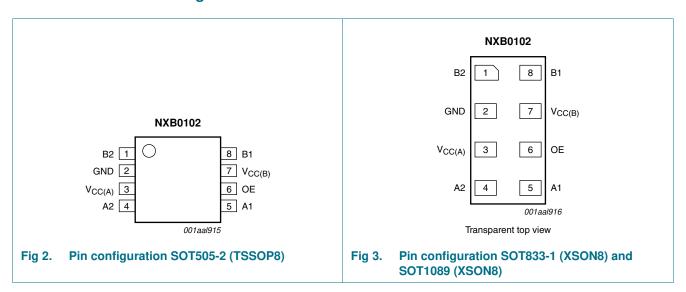


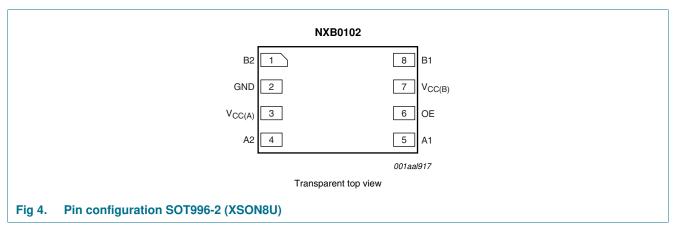
2 of 25

Dual supply translating transceiver; auto direction sensing; 3-state

# 6. Pinning information

#### 6.1 Pinning





# 6.2 Pin description

#### Table 3. Pin description

	•	
Symbol	Pin	Description
B2, B1	1, 8	data input or output (referenced to $V_{\text{CC}(B)}$ )
GND	2	ground (0 V)
V <sub>CC(A)</sub>	3	supply voltage A
A2, A1	4, 5	data input or output (referenced to $V_{\text{CC}(A)}$ )
OE	6	output enable input (active HIGH; referenced to $V_{\text{CC}(A)}$ )
$V_{CC(B)}$	7	supply voltage B

#### Dual supply translating transceiver; auto direction sensing; 3-state

# 7. Functional description

Table 4. Function table[1]

Supply voltage		Input	Input/output			
$V_{CC(A)}$ $V_{CC(B)}$		OE	An	Bn		
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	L	Z	Z		
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	Н	input or output	output or input		
GND[2]	GND[2]	Χ	Z	Z		

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

### 8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

			-		-
Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B		-0.5	+6.5	V
VI	input voltage		<u>[1]</u> –0.5	+6.5	V
Vo	output voltage	Active mode	[1][2][3] -0.5	$V_{CCO} + 0.5$	V
		Power-down or 3-state mode	<u>[1]</u> –0.5	+6.5	V
I <sub>IK</sub>	input clamping current	$V_I < 0 V$	<b>–50</b>	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	<b>–50</b>	-	mA
I <sub>O</sub>	output current	$V_O = 0 V \text{ to } V_{CCO}$	[2] _	±50	mA
I <sub>CC</sub>	supply current	$I_{CC(A)}$ or $I_{CC(B)}$	-	100	mA
I <sub>GND</sub>	ground current		-100	-	mA
T <sub>stg</sub>	storage temperature		<b>–65</b>	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$	<u>[4]</u> _	250	mW

<sup>[1]</sup> The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

<sup>[2]</sup> When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into Power-down mode.

<sup>[2]</sup> V<sub>CCO</sub> is the supply voltage associated with the output.

<sup>[3]</sup>  $V_{CCO} + 0.5 \text{ V}$  should not exceed 6.5 V.

<sup>[4]</sup> For TSSOP8 package: above 55 °C the value of  $P_{tot}$  derates linearly with 2.5 mW/K. For XSON8 and XSON8U packages: above 118 °C the value of  $P_{tot}$  derates linearly with 7.8 mW/K.

Dual supply translating transceiver; auto direction sensing; 3-state

# 9. Recommended operating conditions

Table 6. Recommended operating conditions[1][2]

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		1.2	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
V <sub>O</sub>	output voltage	Power-down or 3-state mode; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$			
		A port	0	3.6	V
		B port	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	40	ns/V

<sup>[1]</sup> The A and B sides of an unused I/O pair must be held in the same state, both at V<sub>CCI</sub> or both at GND.

#### 10. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{OH}$	HIGH-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = -20 \mu\text{A}$	-	1.1	-	V
V <sub>OL</sub>	LOW-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = 20 \mu\text{A}$	-	0.09	-	V
I <sub>I</sub>	input leakage current	OE input; $V_I$ = 0 V to 3.6 V; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	-	±1	μΑ
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O$ = 0 V to $V_{CCO}$ ; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	[1] -	-	±1	μΑ
I <sub>OFF</sub>	power-off leakage current	A port; $V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V	-	-	±1	
		B port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V	-	-	±1	μΑ
I <sub>CC</sub>	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	[2]			
		$I_{CC(A)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	0.05	-	μΑ
		$I_{CC(B)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	3.3	-	μΑ
		$I_{CC(A)} + I_{CC(B)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	3.5	-	μΑ
C <sub>I</sub>	input capacitance	OE input; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	1.0	-	pF
C <sub>I/O</sub>	input/output	A port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	4.0	-	pF
	capacitance	B port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	7.5	-	pF

<sup>[1]</sup>  $V_{\text{CCO}}$  is the supply voltage associated with the output.

NXB0102

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<sup>[2]</sup>  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

<sup>[2]</sup>  $V_{CCI}$  is the supply voltage associated with the input.

**NXB0102 NXP Semiconductors** 

### Dual supply translating transceiver; auto direction sensing; 3-state

Table 8. **Static characteristics** 

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C to	+85 °C	-40 °C to	-40 °C to +125 °C		
				Min	Max	Min	Max		
$V_{IH}$	HIGH-level	A or B port and OE input	[1]						
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V	
$V_{IL}$	LOW-level	A or B port and OE input	[1]						
input voltage		$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V	
V <sub>OH</sub>	HIGH-level	$I_O = -20 \mu A$	[2]						
	output voltage	A port; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V}$		$V_{CCO}-0.4$	-	$V_{\text{CCO}}-0.4$	-	V	
		B port; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V		$V_{CCO}-0.4$	-	$V_{\text{CCO}}-0.4$	-	V	
OL	LOW-level	I <sub>O</sub> = 20 μA	[2]						
	output voltage	A port; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V}$		-	0.4	-	0.4	V	
		B port; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V		-	0.4	-	0.4	V	
I <sub>I</sub>	input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V};$ $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	±2	-	±5	μА	
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±10	μА	
I <sub>OFF</sub>	power-off leakage	A port; $V_1$ or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V		-	±2	-	±10	μА	
	current	B port; $V_I$ or $V_O = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V		-	±2	-	±10	μА	

#### Dual supply translating transceiver; auto direction sensing; 3-state

**Table 8.** Static characteristics ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	–40 °C	to +85 °C	-40 °C to	+125 °C	Unit
			Min	Max	Min	Max	
I <sub>CC</sub>	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	[1]			'	
		I <sub>CC(A)</sub>					
		OE = LOW; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	3	-	15	μА
		OE = HIGH; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	3	-	20	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	2	-	15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$	-	-2	-	-15	μΑ
		I <sub>CC(B)</sub>					
		OE = LOW; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	5	-	15	μΑ
		OE = HIGH; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	5	-	20	μА
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	-2	-	-15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$	-	2	-	15	μΑ
		$I_{CC(A)} + I_{CC(B)}$					
		$V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	8	-	40	μА

<sup>[1]</sup> V<sub>CCI</sub> is the supply voltage associated with the input.

# 11. Dynamic characteristics

Table 9. Typical dynamic characteristics for temperature 25 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for waveforms see Figure 5 and Figure 6.

Symbol	Parameter	Conditions				Unit		
				1.8 V	2.5 V	3.3 V	5.0 V	
$V_{CC(A)} = 1$	1.2 V; T <sub>amb</sub> = 25 °C							
$t_{pd}$	propagation delay	A to B		5.9	4.8	4.4	4.2	ns
		B to A		5.6	4.8	4.5	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		0.5	0.5	0.5	0.5	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	6.9	6.9	6.9	6.9	ns
		OE to B; no external load	[2]	9.5	8.6	8.5	8.0	ns
		OE to A		81	69	83	68	ns
		OE to B		81	69	83	68	ns
t <sub>t</sub>	transition time	A port		4.0	4.0	4.1	4.1	ns
		B port		2.6	2.0	1.7	1.4	ns

<sup>[2]</sup>  $V_{CCO}$  is the supply voltage associated with the output.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 9. Typical dynamic characteristics for temperature 25 °C[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for waveforms see Figure 5 and Figure 6.

Symbol	Parameter	Conditions			V <sub>CC(B)</sub>						
				1.8 V	2.5 V	3.3 V	5.0 V				
$t_{sk(o)}$	output skew time	between channels	[3]	0.2	0.2	0.2	0.2	ns			
t <sub>W</sub>	pulse width	data inputs		15	13	13	13	ns			
f <sub>data</sub>	data rate			70	80	80	80	Mbps			

 $<sup>\</sup>begin{array}{ll} [1] & t_{pd} \text{ is the same as } t_{PLH} \text{ and } t_{PHL}. \\ & t_{en} \text{ is the same as } t_{PZL} \text{ and } t_{PZH}. \\ & t_{dis} \text{ is the same as } t_{PLZ} \text{ and } t_{PHZ}. \\ & t_{t} \text{ is the same as } t_{THL} \text{ and } t_{TLH} \end{array}$ 

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 7</u>; for wave forms see <u>Figure 5</u> and <u>Figure 6</u>.

Symbol Parameter Conditions V <sub>CC(B)</sub>							Unit					
				1.8 V ±	0.15 V	2.5 V	± 0.2 V	3.3 V	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{CC(A)} =$	1.5 V $\pm$ 0.1 V											
t <sub>pd</sub>	propagation	A to B		1.4	12.9	1.2	10.1	1.1	10.0	8.0	9.9	ns
	delay	B to A		0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.9	1.0	11.9	1.0	11.9	1.0	11.9	ns
		OE to B; no external load	[2]	1.0	16.9	1.0	15.2	1.0	14.1	1.0	13.8	ns
		OE to A		-	320	-	260	-	260	-	280	ns
		OE to B		-	-	200	-	200	-	200	-	ns
t <sub>t</sub>	transition	A port		0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
V <sub>CC(A)</sub> =	1.8 V $\pm$ 0.15 V											
t <sub>pd</sub>	propagation	A to B		1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
	delay	B to A		1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.0	1.0	11.0	1.0	11.0	1.0	11.0	ns
		OE to B; no external load	[2]	1.0	15.4	1.0	13.5	1.0	12.4	1.0	12.1	ns
		OE to A		-	260	-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		8.0	4.1	8.0	4.1	0.8	4.1	8.0	4.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns

<sup>[2]</sup> Delay between OE going LOW and when the outputs are actually disabled.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C[1] ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 7</u>; for wave forms see <u>Figure 5</u> and <u>Figure 6</u>.

Symbol	Parameter	Conditions		V <sub>CC(B)</sub>							Unit	
				1.8 V $\pm$ 0.15 V		2.5 V			± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	_
$t_{sk(o)} \\$	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		20	-	17	-	17	-	17	-	ns
f <sub>data</sub>	data rate			-	49	-	60	-	60	-	60	Mbps
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
	delay	B to A		-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	9.2	1.0	9.2	1.0	9.2	ns
		OE to B; no external load	[2]	-	-	1.0	11.9	1.0	10.7	1.0	10.2	ns
		OE to A		-	-	-	200	-	200	-	200	ns
		OE to B		-	-	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
	time	B port		-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	12	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	85	-	100	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation	A to B		-	-	-	-	0.9	4.7	8.0	4.0	ns
	delay	B to A		-	-	-	-	1.0	4.9	0.9	3.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.2	1.0	9.2	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	10.1	1.0	9.6	ns
		OE to A		-	-	-	-	-	260	-	260	ns
		OE to B		-	-	-	-	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	2.5	0.7	2.5	ns
	time	B port		-	-	-	-	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

 $<sup>\</sup>begin{array}{ll} [1] & t_{pd} \text{ is the same as } t_{PLH} \text{ and } t_{PHL}. \\ & t_{en} \text{ is the same as } t_{PZL} \text{ and } t_{PZH}. \\ & t_{dis} \text{ is the same as } t_{PLZ} \text{ and } t_{PHZ}. \end{array}$ 

NXB0102

9 of 25

 $t_{t}$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ .

<sup>[2]</sup> Delay between OE going LOW and when the outputs are actually disabled.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

**NXB0102 NXP Semiconductors** 

### Dual supply translating transceiver; auto direction sensing; 3-state

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C[1] Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 7</u>; for wave forms see <u>Figure 5</u> and <u>Figure 6</u>.

Symbol	Parameter	Conditions	r Conditions		V <sub>CC(B)</sub>							
				1.8 V $\pm$ 0.15 V		2.5 V ±	0.2 V	3.3 V	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V					•						•
t <sub>pd</sub>	propagation	A to B		1.4	15.9	1.2	13.1	1.1	13.0	8.0	12.9	ns
	delay	B to A		0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.5	1.0	12.5	1.0	12.5	1.0	12.5	ns
		OE to B; no external load	[2]	1.0	18.1	1.0	16.2	1.0	14.9	1.0	14.6	ns
		OE to A		-	340	-	280	-	280	-	300	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
	time	B port		0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
V <sub>CC(A)</sub> =	1.8 V $\pm$ 0.15 V											
t <sub>pd</sub>	propagation	A to B		1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns
•	delay	B to A		1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.5	1.0	11.5	1.0	11.5	1.0	11.5	ns
		OE to B; no external load	[2]	1.0	16.5	1.0	14.5	1.0	13.3	1.0	12.7	ns
		OE to A		-	280	-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.8	6.2	8.0	6.1	0.8	6.1	0.8	6.1	ns
	time	B port		0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		22	-	19	-	19	-	19	-	ns
f <sub>data</sub>	data rate			-	45	-	55	-	55	-	55	Mbps
	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
	delay	B to A		-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	9.6	1.0	9.6	1.0	9.6	ns
		OE to B; no external load	[2]	-	-	1.0	12.6	1.0	11.4	1.0	10.8	ns
		OE to A		-	-	-	220	-	220	-	220	ns
		OE to B		-	-	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
time		-										

### Dual supply translating transceiver; auto direction sensing; 3-state

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C[1] ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 7</u>; for wave forms see <u>Figure 5</u> and <u>Figure 6</u>.

Symbol	Parameter	meter Conditions		V <sub>CC(B)</sub>							Unit	
				1.8 V $\pm$ 0.15 V		2.5 V ±	0.2 V	3.3 V	± 0.3 V	5.0 V $\pm$ 0.5 V		
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs;		-	-	14	-	13	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	75	-	80	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation delay	A to B		-	-	-	-	0.9	7.7	0.8	7.0	ns
		B to A		-	-	-	-	1.0	7.9	0.9	6.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.5	1.0	9.5	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	10.7	1.0	9.6	ns
		OE to A		-	-	-	-	-	280	-	280	ns
		OE to B		-	-	-	-	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	4.5	0.7	4.5	ns
	time	B port		-	-	-	-	0.5	4.1	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}.$ 

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_t$  is the same as  $t_{THL}$  and  $t_{TLH.}$ 

<sup>[2]</sup> Delay between OE going LOW and when the outputs are actually disabled.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 12. Typical power dissipation capacitance

Voltages are referenced to GND (ground = 0 V).[1][2]

Symbol	Parameter	Conditions				V <sub>CC(A)</sub>				Unit
				1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V	
				V <sub>CC(B)</sub>						
			1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V	
$T_{amb} = 2$	5 °C		'		•	'	'		'	
$C_{PD}$	power dissipation capacitance	outputs enabled; $OE = V_{CC(A)}$								
		A port: (direction A to B)	5	5	5	5	5	5	5	pF
		A port: (direction B to A)	8	8	8	8	8	8	8	pF
		B port: (direction A to B)	18	18	18	18	18	18	18	pF
		B port: (direction B to A)	13	16	12	12	12	12	13	pF
		outputs disabled; OE = GND								
		A port: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	pF

[1]  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

f<sub>i</sub> = input frequency in MHz;

fo = output frequency in MHz;

C<sub>L</sub> = load capacitance in pF;

 $V_{CC}$  = supply voltage in V;

N = number of inputs switching;

 $\Sigma (C_L \times V_{CC}{}^2 \times f_o)$  = sum of the outputs.

[2]  $f_i = 10$  MHz;  $V_I = GND$  to  $V_{CC}$ ;  $t_f = t_f = 1$  ns;  $C_L = 0$  pF;  $R_L = \infty \Omega$ .

### 12. Waveforms

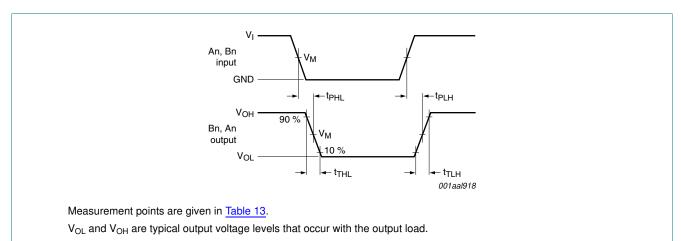


Fig 5. Data input (An, Bn) to data output (Bn, An) propagation delay times

#### Dual supply translating transceiver; auto direction sensing; 3-state

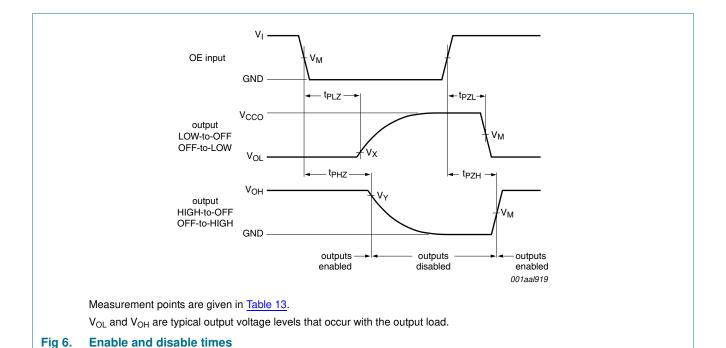
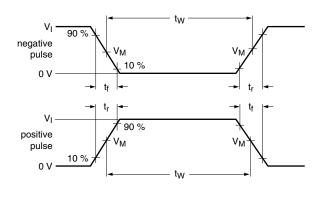


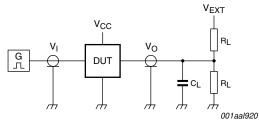
Table 13. Measurement points[1]

Supply voltage	Input	Output		
V <sub>cco</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>
1.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.1 V$	$V_{OH} - 0.1 V$
1.5 V ± 0.1 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.1 V$	V <sub>OH</sub> – 0.1 V
$1.8~V \pm 0.15~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$2.5~\textrm{V} \pm 0.2~\textrm{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$3.3~\textrm{V} \pm 0.3~\textrm{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$
$5.0~V\pm0.5~V$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$

 $<sup>\</sup>label{eq:VCCI} \textbf{[1]} \quad V_{CCI} \text{ is the supply voltage associated with the input and } V_{CCO} \text{ is the supply voltage associated with the output.}$ 

#### Dual supply translating transceiver; auto direction sensing; 3-state





Test data is given in Table 14.

All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  10 MHz;  $Z_{O}$  = 50  $\Omega$ ;  $dV/dt \geq$  1.0 V/ns.

R<sub>L</sub> = Load resistance.

 $C_L$  = Load capacitance including jig and probe capacitance.

 $V_{\text{EXT}}$  = External voltage for measuring switching times.

Fig 7. Test circuit for measuring switching times

Table 14. Test data

Supply voltage	је	Input		Load		V <sub>EXT</sub>		
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	۷ <sub>ا</sub> [1]	Δ <b>t</b> /Δ <b>V</b>	CL	R <sub>L</sub> [2]	t <sub>PLH</sub> , t <sub>PHL</sub>	$t_{PZH}, t_{PHZ}$	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]
1.2 V to 3.6 V	1.65 V to 5.5 V	$V_{CCI}$	$\leq$ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>

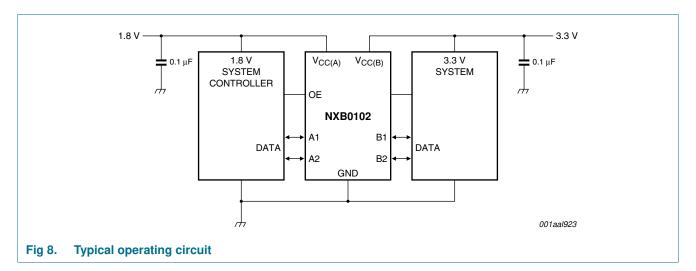
- [1] V<sub>CCI</sub> is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 \text{ M}\Omega$ ; for measuring enable and disable times,  $R_L = 50 \text{ k}\Omega$ .
- [3]  $V_{CCO}$  is the supply voltage associated with the output.

Dual supply translating transceiver; auto direction sensing; 3-state

# 13. Application information

### 13.1 Applications

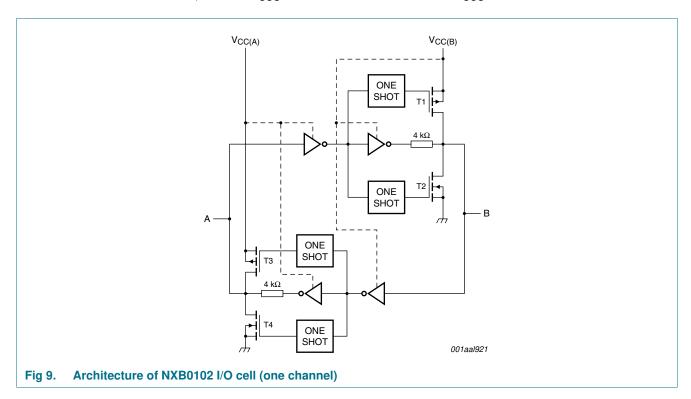
Voltage level-translation applications. The NXB0102 can be used to interface between devices or systems operating at different supply voltages. See <u>Figure 8</u> for a typical operating circuit using the NXB0102.



#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 13.2 Architecture

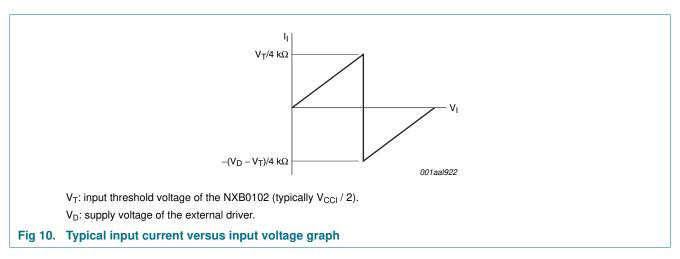
The architecture of the NXB0102 is shown in Figure 9. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NXB0102 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output of one-shot circuits detect rising or falling edges on the A or B ports. During a rising edge, the one-shot circuits turn on the PMOS transistors (T1, T3) for a short duration, accelerating the LOW-to-HIGH transition. Similarly, during a falling edge, the one-shot circuits turn on the NMOS transistors (T2, T4) for a short duration, accelerating the HIGH-to-LOW transition. During output transitions the typical output impedance is 70  $\Omega$  at  $V_{\rm CCO}$  = 1.2 V to 1.8 V, 50  $\Omega$  at  $V_{\rm CCO}$  = 1.8 V to 3.3 V and 40  $\Omega$  at  $V_{\rm CCO}$  = 3.3 V to 5.0 V.



#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 13.3 Input driver requirements

For correct operation, the device driving the data I/Os of the NXB0102 must have a minimum drive capability of  $\pm 2$  mA See Figure 10 for a plot of typical input current versus input voltage.



# 13.4 Power-up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NXB0102 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### 13.5 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

#### 13.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously the NXB0102 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be above 50 k $\Omega$ . For this reason the NXB0102 is not recommended for use in open drain driver applications such as 1-Wire or I<sup>2</sup>C-bus. For these applications, the NXS0102 level translator is recommended.

Dual supply translating transceiver; auto direction sensing; 3-state

# 14. Package outline

TSSOP8: plastic thin shrink small outline package; 8 leads; body width 3 mm; lead length 0.5 mm SOT505-2

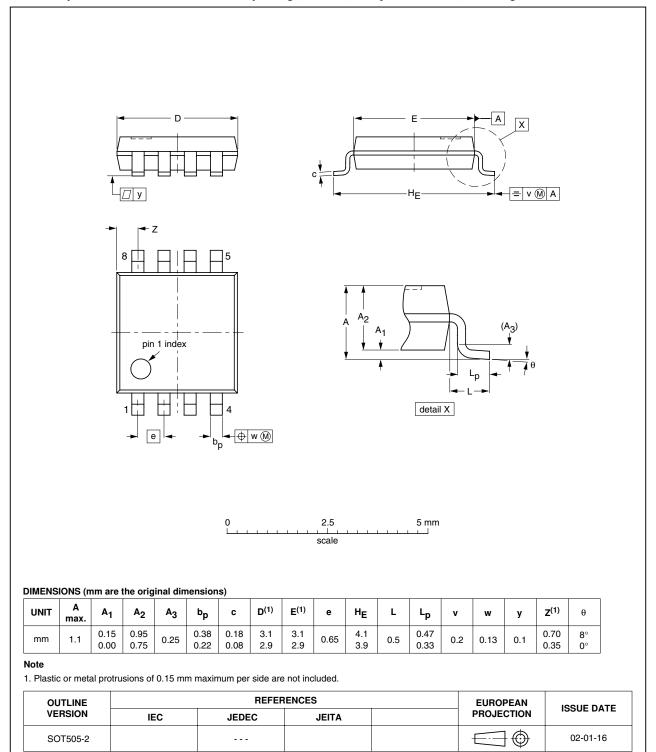


Fig 11. Package outline SOT505-2 (TSSOP8)

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Dual supply translating transceiver; auto direction sensing; 3-state

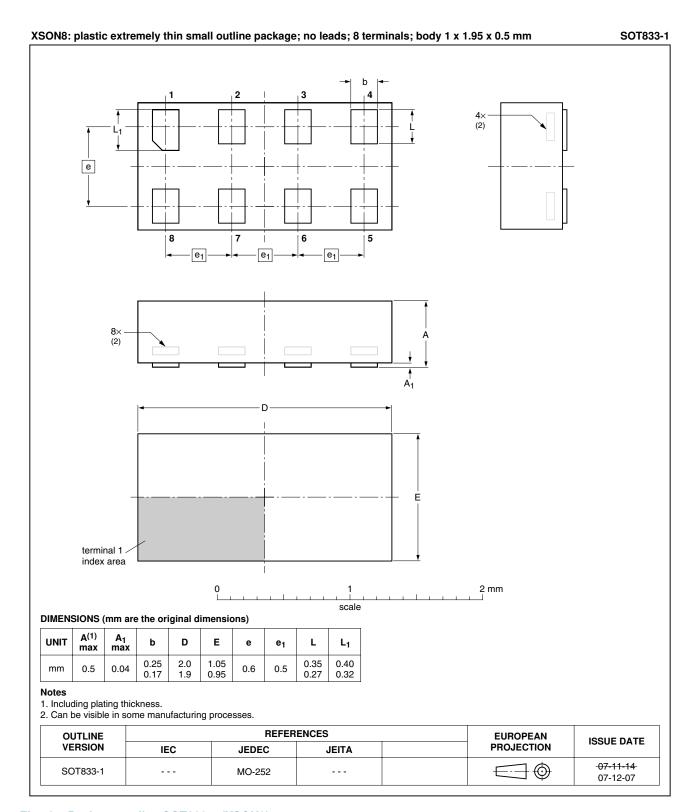


Fig 12. Package outline SOT833-1 (XSON8)

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#### Dual supply translating transceiver; auto direction sensing; 3-state

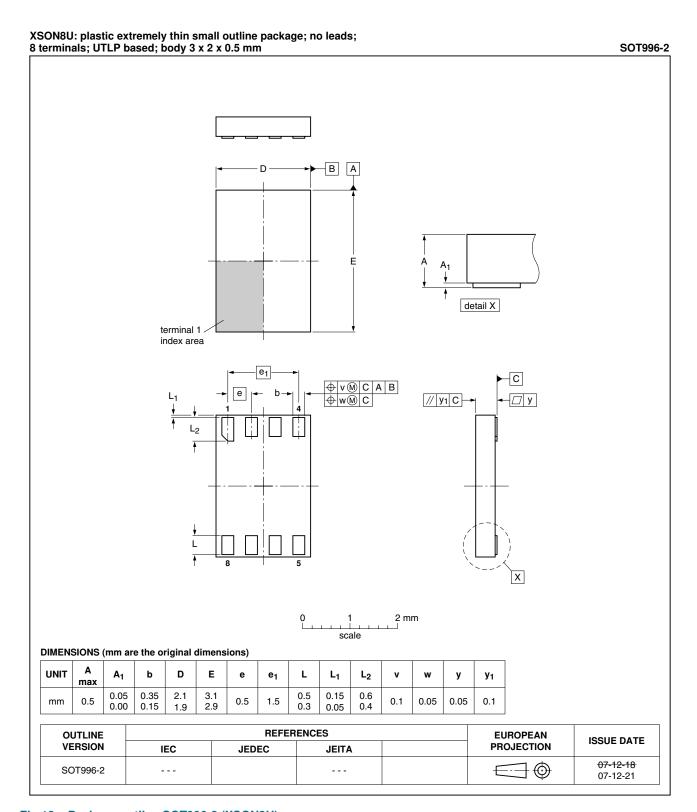


Fig 13. Package outline SOT996-2 (XSON8U)

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#### Dual supply translating transceiver; auto direction sensing; 3-state

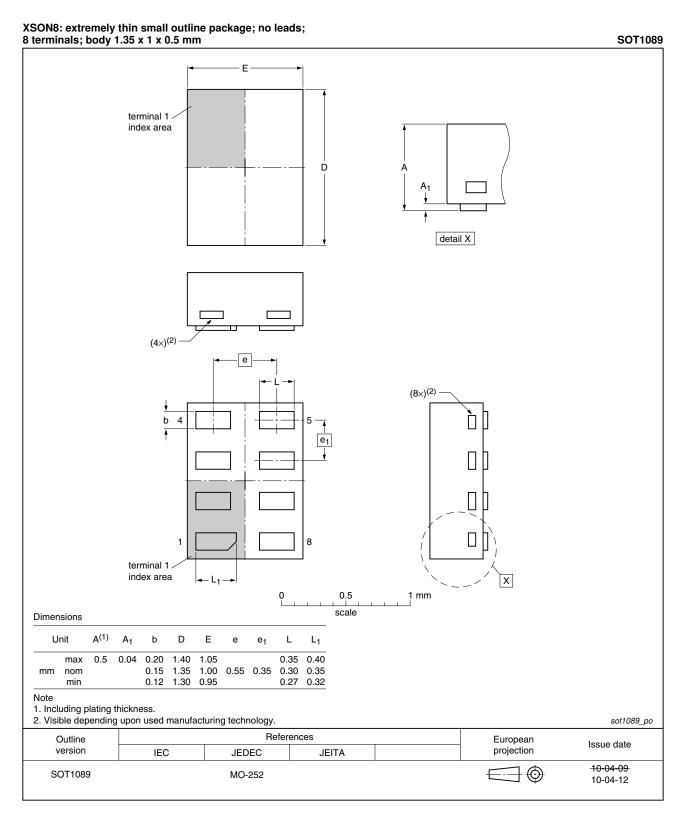


Fig 14. Package outline SOT1089 (XSON8)

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# Dual supply translating transceiver; auto direction sensing; 3-state

# 15. Abbreviations

#### Table 15. Abbreviations

Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model
PRR	Pulse Repetition Rate

# 16. Revision history

#### Table 16. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NXB0102 v.1	20100608	Product data sheet	-	-

#### Dual supply translating transceiver; auto direction sensing; 3-state

# 17. Legal information

#### 17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <a href="http://www.nxp.com">http://www.nxp.com</a>.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

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### Dual supply translating transceiver; auto direction sensing; 3-state

# 19. Contents

1	General description	1
2	Features and benefits	1
3	Ordering information	2
4	Marking	2
5	Functional diagram	2
6	Pinning information	
6.1	Pinning	3
6.2	Pin description	
7	Functional description	4
8	Limiting values	4
9	Recommended operating conditions	
10	Static characteristics	
11	Dynamic characteristics	
12	Waveforms	
13	Application information	. 15
13.1	Applications	
13.2	Architecture	
13.3	Input driver requirements	. 17
13.4	Power up	
13.5	Enable and disable	
13.6	Pull-up or pull-down resistors on I/O lines	. 17
14	Package outline	. 18
15	Abbreviations	. 22
16	Revision history	. 22
17	Legal information	. 23
17.1	Data sheet status	
17.2	Definitions	. 23
17.3	Disclaimers	. 23
17.4	Trademarks	
18	Contact information	. 24
19	Contents	. 25

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