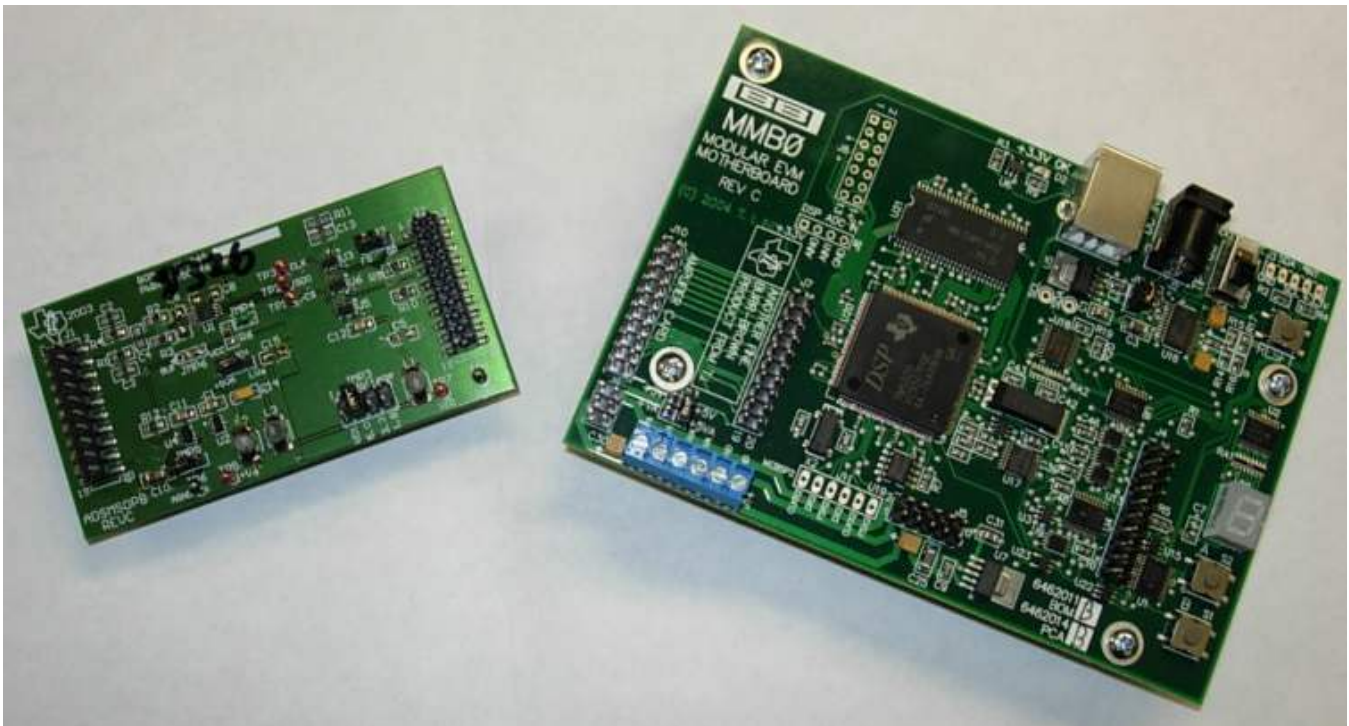


## **MSOP-8EVM and MSOP-8EVM-PDK**



**Figure 1. MSOP-8EVM (Left) and MSOP-8EVM-PDK (Right)**

This user's guide describes the characteristics, operation, and use of the MSOP-8EVM, both by itself and as part of the MSOP-8EVM-PDK. This EVM is an evaluation board for single-channel, 14- to 16-bit, analog-to-digital converter (ADC) devices in an MSOP-8 package. A complete circuit description, schematic diagram, and bill of materials are included with this document.

This manual covers the operation of both the MSOP-8EVM and the MSOP-8EVM-PDK. It does not describe the MMB0 motherboard in detail. Throughout this document, the abbreviation *EVM* and the term *evaluation module* are synonymous with the MSOP-8EVM.

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## 1 EVM Overview

### 1.1 Features

#### MSOP-8EVM Features:

- Full-featured evaluation board for a variety of single-channel, 8-pin, micro-SOP, 14- to 16-bit, serial output, ADCs
- Onboard reference and buffer circuits
- High-speed serial interface
- Modular design for use with a variety of DSP and microcontroller interface boards

For use with a computer, the MSOP-8EVM-PDK is available. This kit combines the MSOP-8EVM board with the DSP-based MMB0 motherboard, and includes [ADCPro™ software](#) for evaluation.

The MMB0 motherboard allows the MSOP-8EVM to be connected to the computer via an available USB port. This manual shows how to use the MMB0 as part of the MSOP-8EVM-PDK, but does not provide technical details on the MMB0 itself.

ADCPro is a program for collecting, recording, and analyzing data from ADC evaluation boards. It is based on a number of plug-in programs, so it can be expanded easily with new test and data collection plug-ins. The MSOP-8EVM-PDK is controlled by a plug-in that is executed in ADCPro.

This manual covers the operation of both the MSOP-8EVM and the MSOP-8EVM-PDK. It does not describe the MMB0 motherboard in detail. Throughout this document, the abbreviation *EVM* and the term *evaluation module* are synonymous with the MSOP-8EVM.

### 1.2 Introduction

The modular MSOP-8 evaluation module is an updated version of the popular Burr-Brown DEM-MSOP-8 evaluation board. The EVM is designed so that a single printed wiring board (PWB) supports a variety of test configurations for high-speed 14- and 16-bit serial ADCs.

The modular EVM form factor allows for direct evaluation of the ADC performance and operating characteristics. This EVM is compatible with the 5-6K Interface Board ([SLAU104](#)), also available from Texas Instruments.

### 1.3 Related Documentation

[Table 1](#) lists documents related to the MSOP-8EVM. To obtain a copy of any of these TI documents, call the Texas Instruments Literature Response Center at (800) 477-8924 or the Product Information Center (PIC) at (972) 644-5580. When ordering, identify this booklet by its title and literature number. Updated documents can also be obtained through our website at [www.ti.com](http://www.ti.com).

**Table 1. Related Documentation**

EVM-Compatible Device Data Sheets	Literature Number
<a href="#">ADS8320</a>	SBAS108
<a href="#">ADS8321</a>	SBAS123
<a href="#">ADS8324</a>	SBAS172
<a href="#">ADS8325</a>	SBAS226
<a href="#">ADS8326</a>	SBAS343
Application Notes/Additional Literature from TI	Literature Number
<a href="#">Op Amps for Everyone</a>	SLOD006
<a href="#">5-6K Interface Board</a>	SLAU104
<a href="#">Single and Bipolar Signal Conditioning Boards</a>	SLAU105

## 2 Analog Interface

For maximum flexibility, the modular MSOP-8EVM is designed for easy interfacing to multiple analog sources. Samtec part numbers SSW-110-22-F-D-VS-K and TSM-110-01-T-DV-P provide a convenient, 10-pin, dual-row header/socket combination at J1. This header/socket provides access to the analog input pins of the ADC. Consult Samtec at <http://www.samtec.com> or call 1-800-SAMTEC-9 for a variety of mating connector options.

**Table 2. J1—Analog Interface Pinout**

Pin Number	Signal	Description
J1.2	AD_IN+	Noninverting input for differential devices, and analog input for single-ended devices
J1.4	AD_IN–	Inverting input for differential devices, and analog ground for single-ended devices
J1.6	Unused	Pins are unused and should be left open for use with future amplifier and sensor input modules
J1.8	Unused	
J1.10	Unused	
J1.12	Unused	
J1.14	Unused	
J1.16	Unused	
J1.18	REF(–)	Unused
J1.20	REF(+)	External reference source input
J1.15	Unused	Unused
J1.1 to J1.19 (odd)	AGND	Analog ground connections (except J1.15)

## 3 Digital Interface

The modular MSOP-8EVM is designed for easy interfacing to multiple control platforms. Samtec part numbers SSW-110-22-F-D-VS-K and TSM-110-01-T-DV-P provide a convenient, 10-pin, dual-row header/socket combination at J2. This header/socket provides access to the digital control and serial data pins of the MSOP-8EVM. Consult Samtec at <http://www.samtec.com> or 1-800-SAMTEC-9 for a variety of mating connector options.

**Table 3. J2—Digital Interface Pinout**

Pin Number	Signal Name	Description
J2.1	$\overline{CS}$	Chip select, active low signal. Enables data transfer, jumper configurable (see the schematic located at the end of this document)
J2.3	SCLK	Serial clock
J2.5	SCLKr	Serial clock return (for DSP host systems)
J2.7	FS	Frame sync for DSP host systems; alternate chip select through JMP2 (see the schematic located at the end of this document)
J2.9	FSr	Frame sync return (for DSP host systems)
J2.11	Unused	Unused
J2.13	SDO	Serial data output
J2.15	Unused	Unused
J2.17	Unused	Unused
J2.19	SPARE	

## 4 Power Supplies

The modular MSOP-8EVM board requires +5V dc for the analog section. This power source supplies the voltage reference (U2), the reference buffer (U4), and optionally, the ADC installed on the EVM (via JMP1). Supply voltages of +1.8V to +5V dc for the digital section are also required. When used in combination with one of the DAP Interface boards, J3 provides connection to the common power bus described in the 5-6 K Interface Board User's Guide, ([SLAU104](#)). [Table 4](#) shows the pinout for J3.

**Table 4. J3 Pinout**

Pin Number	Signal	Pin Number	Signal
1	Unused	6	AGND
2	Unused	7	+1.8VD
3	+5VA	8	+VD1
4	Unused	9	+3.3VD
5	DGND	10	+5VD

When power is supplied to J3, JMP3 allows for one of four different dc voltages to be applied to the digital sections of the ADC. Review the schematic (located at the end of this document) and PWB silkscreen (see [Figure 3](#)) for further details.

#### 4.1 **ADC Power**

The device installed on the modular MSOP-8EVM has several options with regard to its power source. Refer to the schematic shown at the end of this document for details about the following information.

JMP1 and JMP3 allow the user to select the power supply used by the ADC. When JMP1 is in the default factory position (shunt on pins 1-2), power to the ADC comes from J3.3 or TP5. Single gate digital buffers (U3, U5, and U6) are installed on the ADC digital input/output lines to allow operation with low-voltage controllers, such as the MSP430. The supply voltage to these buffers is determined by JMP3 or the voltage applied to TP7.

## 4.2 Standalone Operation

When used as a standalone EVM, the analog power can be applied to TP5 and referenced to TP6. Digital power can be applied to TP7, referenced to TP4. While filters are provided for all power-supply inputs, optimal performance of the EVM requires a clean, well-regulated power source.

### CAUTION

The ADCs that are compatible with this EVM have a variety of power-supply requirements. Check the appropriate data sheet and verify that all power supplies are within the safe operating limits of the ADC before applying power to the EVM.

## 4.3 Reference Voltage

The modular MSOP-8 can be configured to use the onboard reference/buffer circuits (U2 and U4) or an external reference applied to J1.20. Jumpers JMP5 and JMP6 control the reference source. In the factory default position (shunt on JMP5 pins 1-2), a 2.5V reference is supplied by U2. Moving the shunt at JMP5 to positions 2-3 allows an external reference applied to J1.20 to be used.

### CAUTION

The ADCs that are compatible with this EVM have a variety of reference requirements. Check the appropriate data sheet and verify that the external reference sources are within the safe operating limits of the ADC before applying power to the EVM.

JMP6 controls the actual application of the reference source to the ADC. In the factory default position (shunt on pins 1-2), the reference source is the onboard reference/buffer circuit. Moving the shunt to JMP6 to pins 2-3 allows the voltage applied to the ADC ( $+V_{ADC}$ ) to be used as the reference source.

## 5 EVM Operation

This section provides information on the analog input, digital control, and general operating conditions of the MSOP-8EVM.

### 5.1 Analog Input

The analog input source can be applied directly to J1 (top or bottom side) or through optional amplifier and signal conditioning modules. The analog input range depends on the configuration of the EVM and the ADC installed at location U1. Consult the specific device data sheet to determine the maximum analog input range.

### 5.2 Digital Control

The digital control signals can be applied directly to J2 (top or bottom side). The modular MSOP-8EVM can also be connected directly to a DSP or microcontroller interface board. Visit the product folder for the MSOP-8EVM or the installed device for a current list of compatible interfaces and/or recommended accessory boards.

### 5.3 Chip Select (Shutdown)

Jumper JMP2 is provided to allow the selection of the signals applied to the chip select ( $\overline{CS}$ ) or shutdown (SHDN) pin of the ADC installed on the EVM. The factory default condition for the EVM has a shunt jumper placed between pins 1-2 of JMP2. This configuration allows the Frame Sync (FS) signal from a DSP host system to be used as a chip select for the ADC. This signal originates from J2.7. When JMP2 is moved to pins 2-3, the  $\overline{CS}$  (SHDN) signal is applied via J2.1.

### 5.4 Digital I/O Buffers

Single gate buffers U3, U5, and U6 are provided to ensure the safe operation of the modular MSOP-8EVM with low-voltage host controllers. The digital I/O voltage applied to these buffers via JMP3 should be set in accordance with the operating voltage of the host controller.

### 5.5 Default Jumper Locations

Table 5 lists the jumpers found on the EVM and the respective factory default condition of each.

**Table 5. Jumper Descriptions**

Jumper	Shunt Position	Jumper Description
JMP1	Pins 1-2	Controls ADC supply voltage (default is +5V analog source)
JMP2	Pins 1-2	Controls ADC $\overline{CS}$ (SHDN) pin (default is FS from DSP host)
JMP3	Pins 5-6	Controls digital I/O voltage (default is +3.3V digital source)
JMP4	CLOSED	Ties analog and digital grounds together
JMP5	Pins 1-2	Controls external reference source (default is +2.5V from U2)
JMP6	Pins 1-2	Controls reference source to ADC (default is onboard reference/buffer circuit)



## 6 MSOP-8EVM-PDK Kit Operation

This section provides information on using the MSOP-8EVM-PDK, including setup, program installation, and program usage.

To prepare to evaluate the MSOP-8EVM with the MSOP-8EVM-PDK, complete the following steps:

- Step 1. Install the ADCPro software (if not already installed).
- Step 2. Install the MSOP-8EVM-PDK EVM plug-in software.
- Step 3. Set up the MSOP-8EVM-PDK.
- Step 4. Connect a proper power supply or use the included ac adapter.
- Step 5. Run the ADCPro software.
- Step 6. Complete the Microsoft Windows® USB driver installation process.

Each step is described in the subsequent sections of this document.

### 6.1 Installing the ADCPro Software

Do not connect the MSOP-8EVM-PDK before installing the software. Failure to observe this procedure may cause Windows to not recognize the MSOP-8EVM-PDK.

The latest software is available from Texas Instruments' website at <http://www.ti.com/>. The CD-ROM shipped with the MSOP-8EVM may not contain the latest software, but the ADCPro installer will check for updates when run, if connected to the Internet, and then give you the option of downloading and installing the latest version. Refer to the [ADCPro User's Guide](#) for instructions on installing and using ADCPro.

To install the MSOP-8EVM-PDK plug-in, run the file: **adsXXXXevm-pdk-plugin-1.0.0.exe** for the installed device (*1.0.0* is the version number, and increments with software version releases; you may have a different version on your CD). Double-click the file to run it; then follow the instructions shown. You can also use the ADCPro *Update Check* feature to check for newer versions of the MSOP-8EVM-PDK plug-in, once you have installed one version of it.

The software should now be installed, but the USB drivers may not yet have been loaded by the PC operating system. This step completes when the ADCPro software is executed; see the section titled [Running the Software and Completing Driver Installation](#).



## 6.2 Setting Up the MSOP-8EVM-PDK

The MSOP-8EVM-PDK contains both the MSOP-8EVM and the MMB0 motherboard; however, the devices are shipped unconnected. Follow these steps to set up the MSOP-8EVM-PDK:

- Step 1. Unpack the MSOP-8EVM-PDK kit.
- Step 2. Set the jumpers and switches on the MMB0 as shown in [Figure 2](#).
  - (a) Set the Boot Mode switch to USB.
  - (b) Connect +5V and +5VA on jumper block J13 (if +5V is supplied from J14 +5VA).
  - (c) Leave +5V and +VA disconnected on jumper block J13.
  - (d) If the PDK will be powered from an ac adapter, and used in unipolar mode, connect J12. If the PDK will be powered through the terminal block or will be used in bipolar mode, disconnect J12.

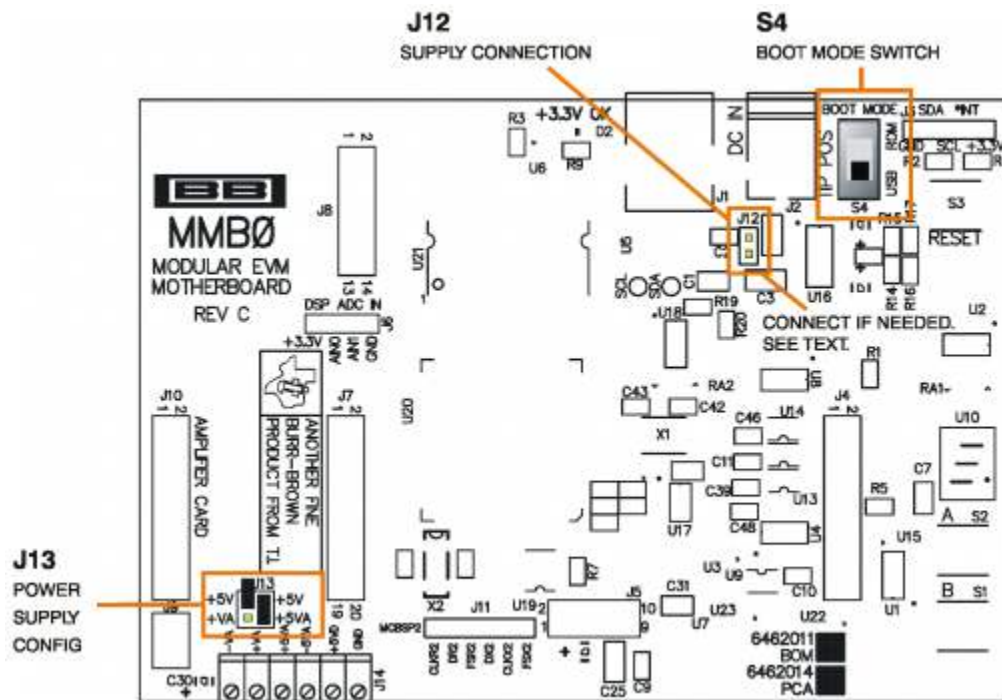


Figure 2. MMB0 Initial Setup

- Step 3. Set the jumpers on the MSOP-8 EVM board as shown in [Figure 3](#) (note that these jumpers are the factory-configured settings for the MSOP-8 EVM):
  - (a) Set I/O Voltage jumper block JMP3 as shown in [Figure 3](#).
  - (b) Set the reference source select jumpers (JMP5 and JMP6) to the onboard/BUF positions.
  - (c) Set the  $\overline{CS}/SHDN$  source select jumper (JMP2) to the FS position.
  - (d) Set up VCC jumper block JMP1 as shown in [Figure 3](#).

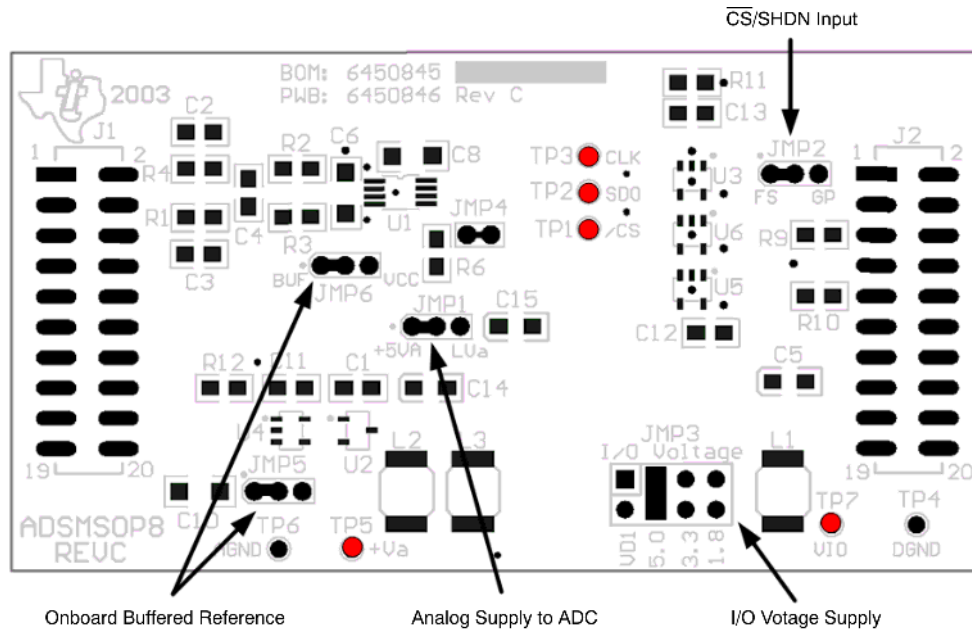


Figure 3. MSOP-8 EVM Board Initial Setup

Step 4. Plug the MSOP-8EVM into the MMB0.



Figure 4. Connecting the MSOP-8EVM to the MMB0 Motherboard

**CAUTION**

Do not misalign the pins when plugging the MSOP-8EVM into the MMB0. Check the pin alignment of J1, J2 and J3 carefully before applying power to the PDK.

**6.2.1 About the MMB0**

The MMB0 is a modular EVM system motherboard. It is designed around the [TMS320VC5507](#), a DSP from Texas Instruments that has an onboard USB interface. The MMB0 also has 16MB of SDRAM installed.

The MMB0 is not sold as a DSP development board, and it is not available separately. TI cannot offer support for the MMB0 except as part of an EVM kit. For schematics or other information about the MMB0, contact Texas Instruments.

### 6.3 Connecting the Power Supply

The MSOP-8EVM-PDK can be operated with a unipolar +5V supply, in which case an external lab power supply can be used via J2 with the included CA-2186 cable or via J14. When the MMB0 DSP is powered properly, LED D2 glows green. The green light indicates that the 3.3V supply for the MMB0 is operating properly; however, it does *not* indicate that the EVM power supplies are operating properly.

#### 6.3.1 Connecting an External Supply

An external supply can be connected to barrel jack J2 on the MMB0 using the included CA-2186 cable. J2 is located next to the USB connector. The adapter must output 6V to 9V dc. The connector must be sleeve-negative, tip-positive. It should have a current rating of at least 500mA. Figure 5 shows the correct connections.

Jumper J12 on the MMB0 connects the external power supply to the board. To use the external power supply, J12 must be shorted.

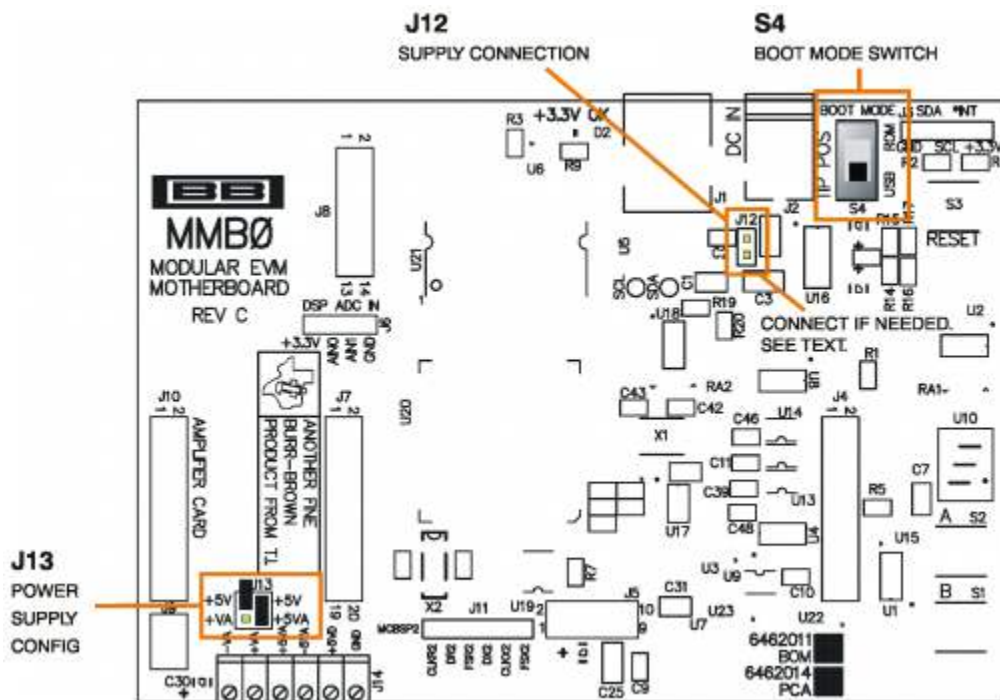


Figure 5. Connecting an AC Adapter

### 6.3.2 Connecting a Laboratory Power Supply

A laboratory power supply can be connected through terminal block J14 on the MMB0, as shown in Figure 6.

To use a unipolar lab power supply configuration:

- Disconnect J12 on the MMB0.
- Connect a +5V dc supply to the +5VD terminal on J14.
- Connect ground of the dc supply to the GND terminal on J14.

It is not necessary to connect a +5V dc supply voltage to the +5VA terminal on J14 if the +5V/+5VA position on J13 is shorted.

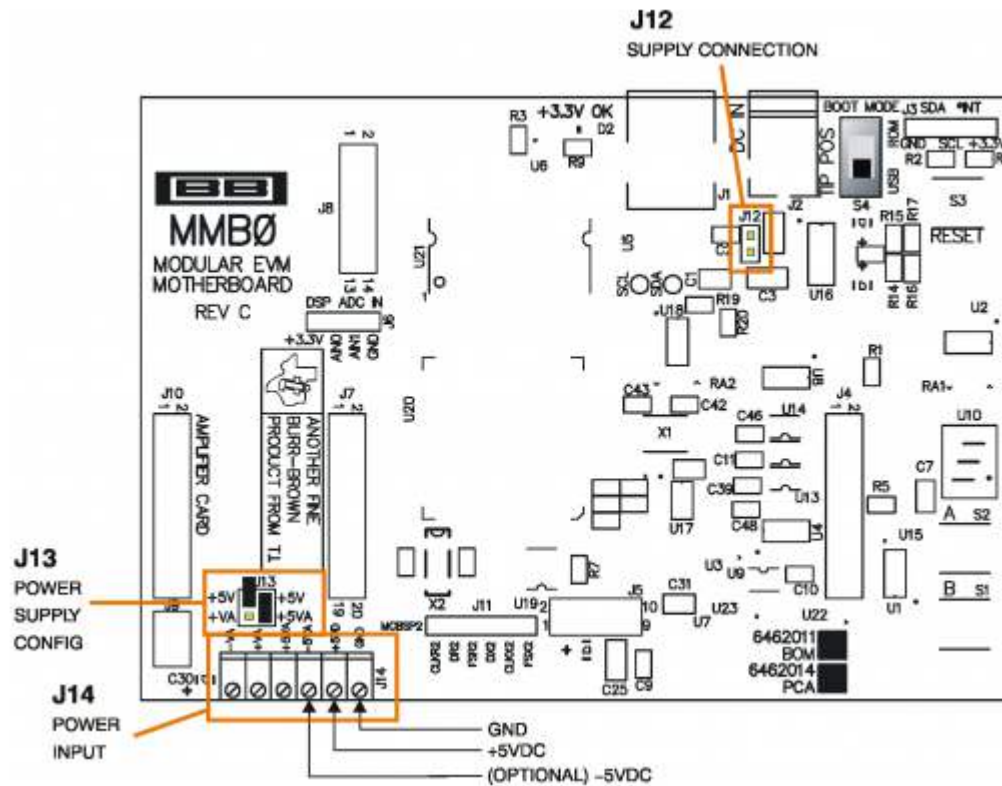


Figure 6. Laboratory Power-Supply Connection

## 6.4 Running the Software and Completing Driver Installation

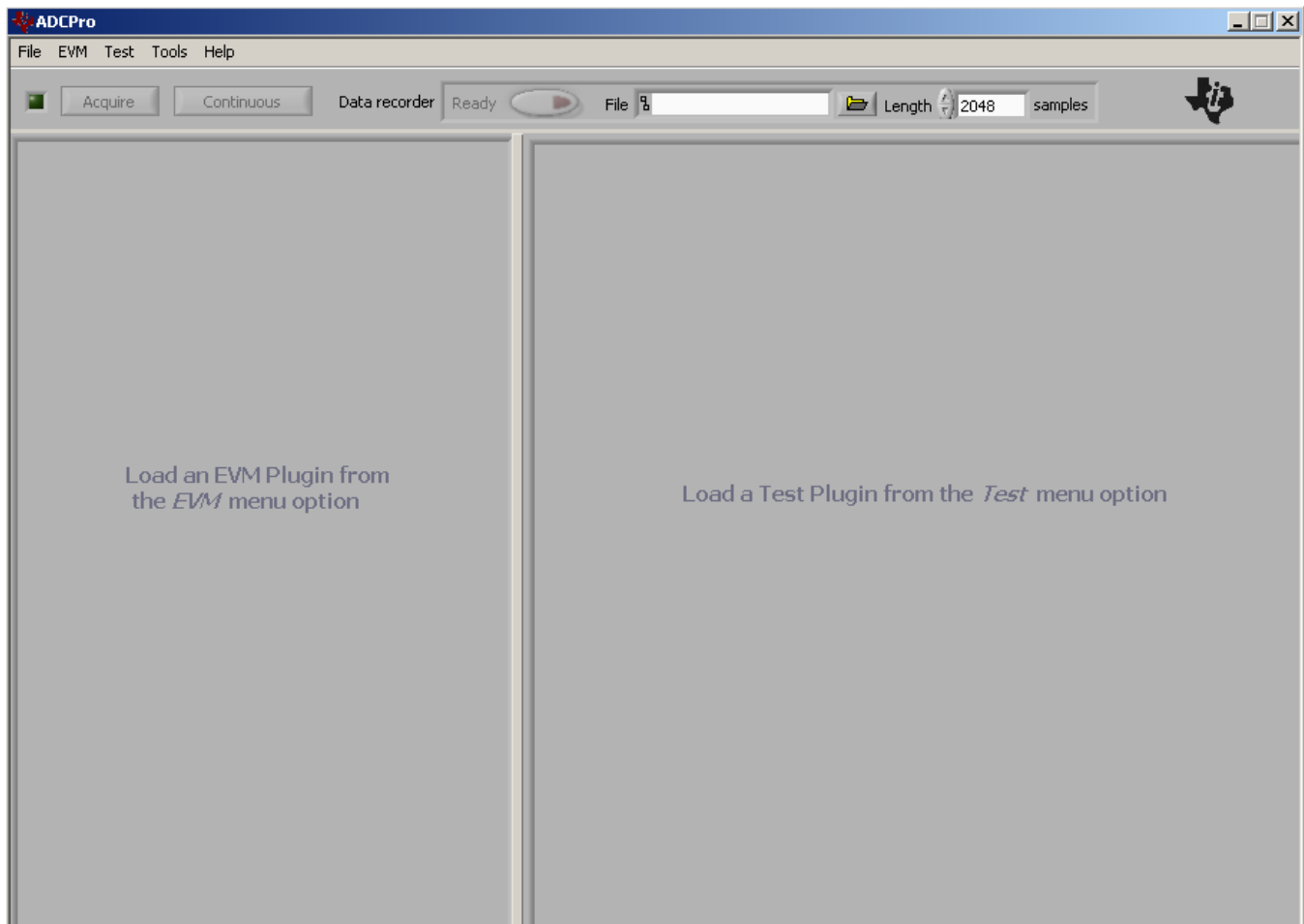
**NOTE:** The software is continually under development. These instructions and screen images are current at the time of this writing, but may not exactly match future releases.

The program for evaluating the MSOP-8EVM-PDK is called ADCPro. This program uses plug-ins to communicate with the EVM. The MSOP-8EVM-PDK plug-in is included in the MSOP-8EVM-PDK package.

The program currently runs only on Windows XP.

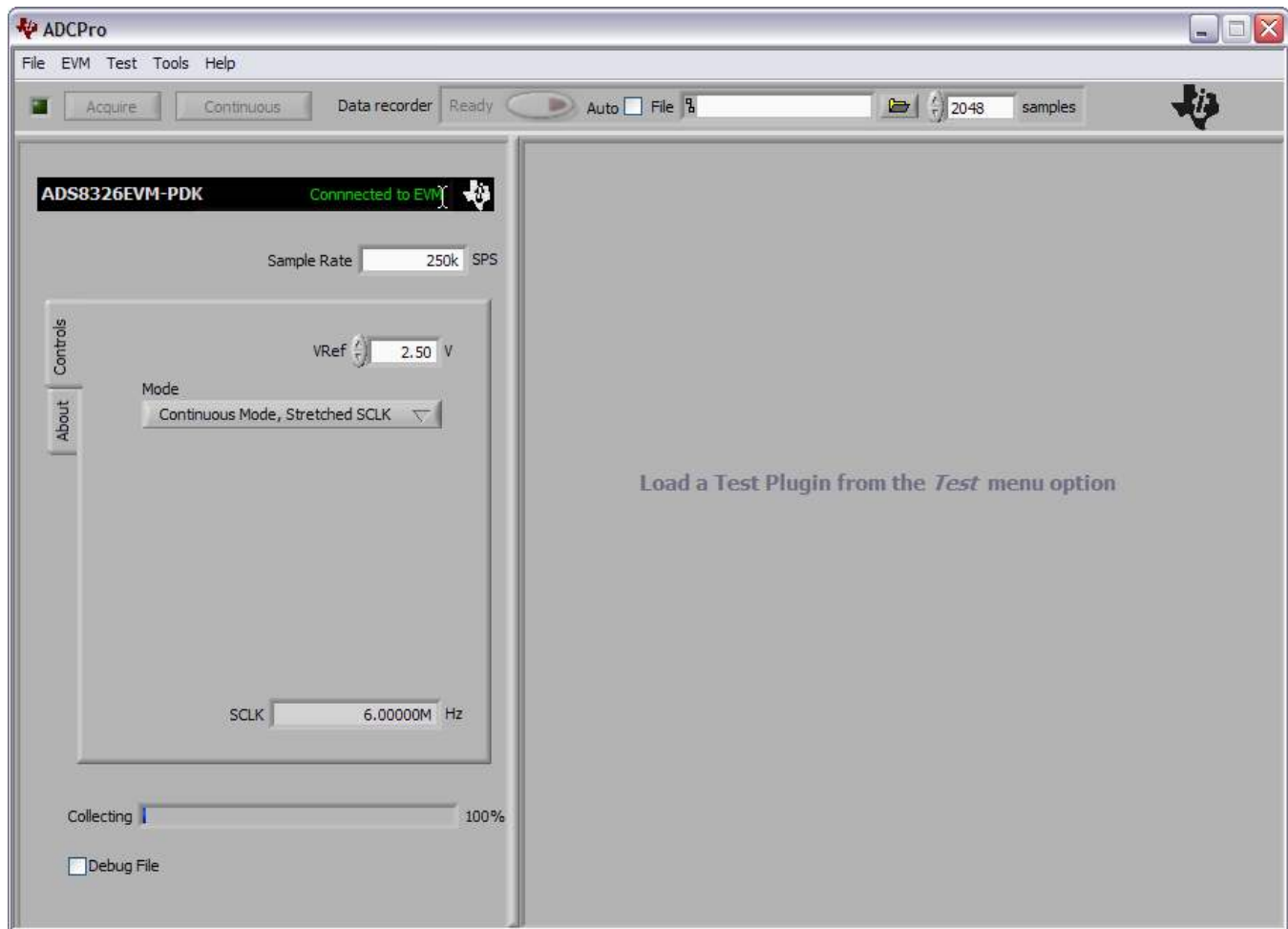
Follow these procedures to run ADCPro and complete the necessary driver installation:

- Step 1. Start the software by selecting *ADCPro* from the Windows Start menu. The screenshot shown in [Figure 7](#) appears.



**Figure 7. ADCPro Software Start-up Display Window**

- Step 2. Select *ADSXXXXEVM* (where *ADSXXXXEVM* is the installed device which is to be evaluated) from the EVM drop-down menu. The *ADSXXXXEVM-PDK* plug-in appears in the left pane, as shown in [Figure 8](#).



**Figure 8. ADS8326EVM-PDK Plug-In Display Window**

- Step 3. The MSOP-8EVM-PDK plug-in window has a status area at the top of the screen. When the plug-in is first loaded, the plug-in searches for the board. You will see a series of messages in the status area indicating this action.
- Step 4. Apply power to the PDK and connect the board to an available PC USB port.
- Step 5. If you have not yet loaded the operating system drivers, Windows will display the *Found New Hardware Wizard* sequence (illustrated in [Figure 9](#) through [Figure 13](#)). Accept the default settings.

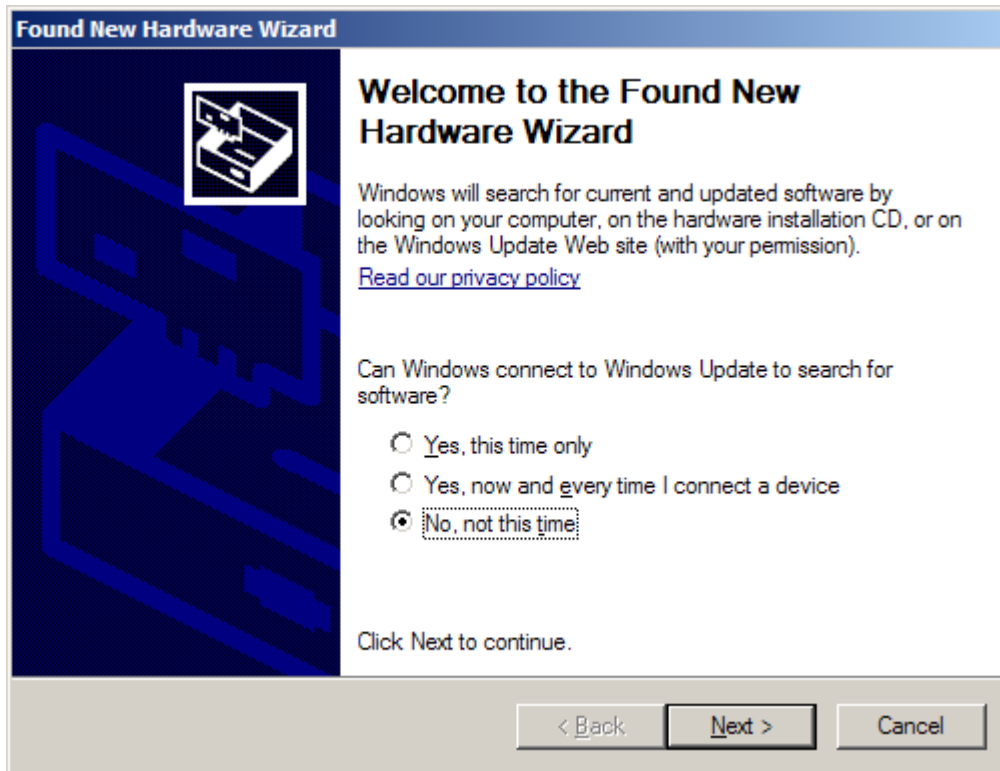


Figure 9. Found New Hardware Wizard, Screen 1

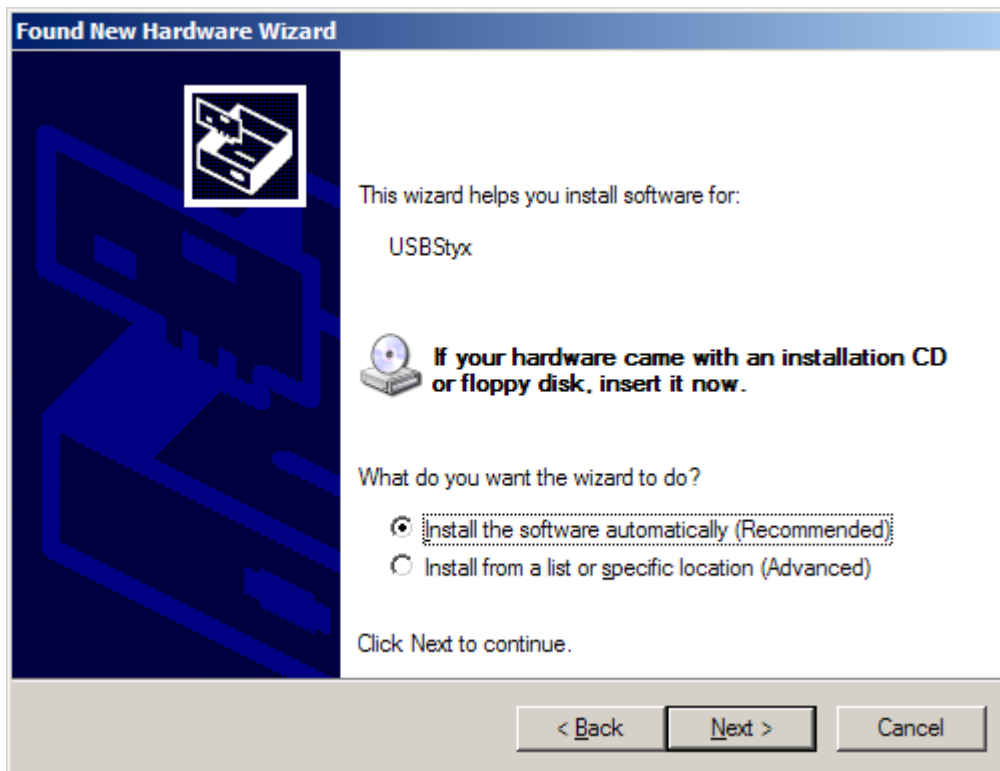


Figure 10. Found New Hardware Wizard, Screen 2





Figure 11. Found New Hardware Wizard, Screen 3

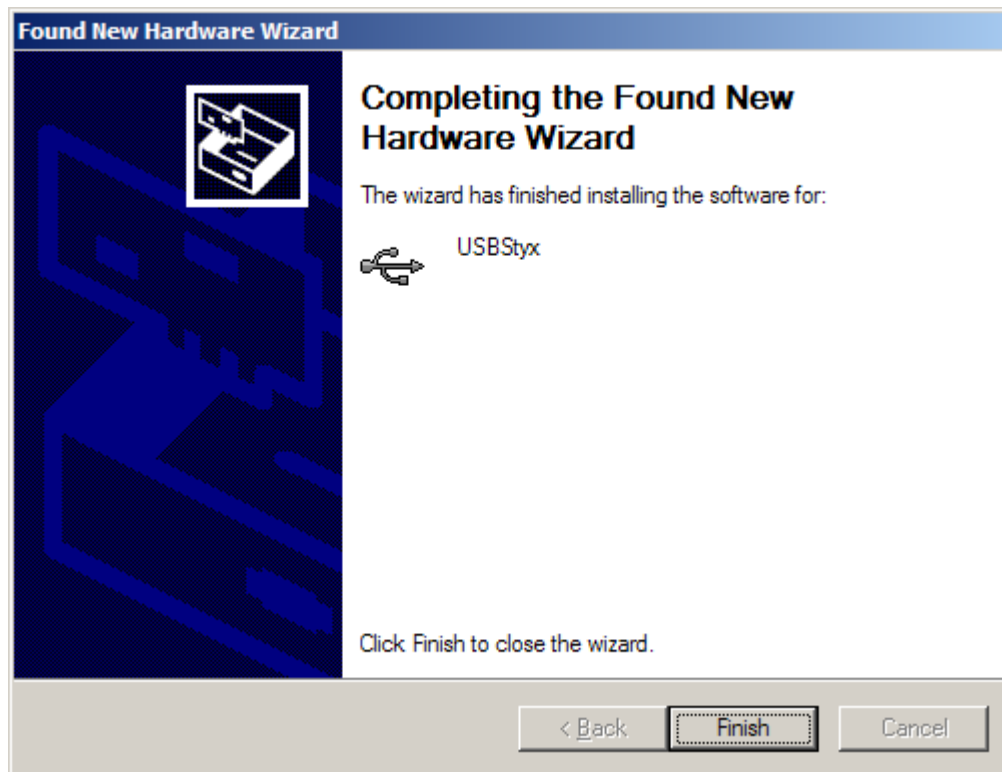
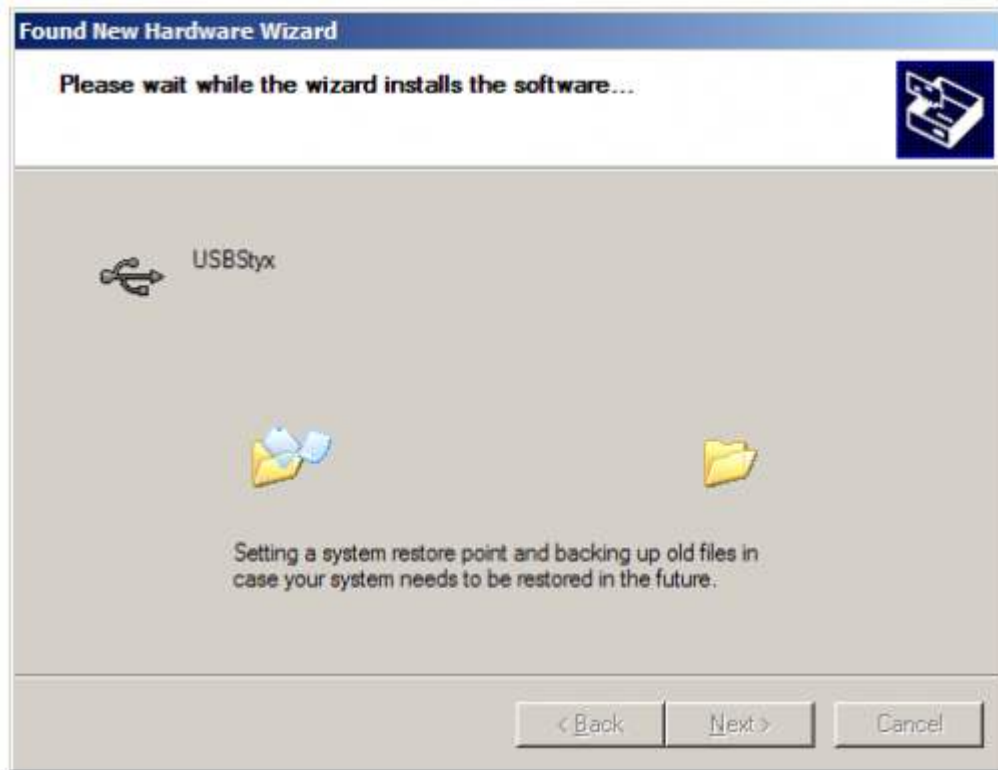


Figure 12. Found New Hardware Wizard, Screen 4



**Figure 13. Found New Hardware Wizard, Screen 5**

- Step 6. When Windows installs the software driver, the plug-in downloads the firmware to the MMB0.
- Step 7. Windows will display the installation wizard a second time. Again, accept the default settings.
- Step 8. The status area displays a connected message. The software is now ready to use.

The driver installation wizard sequence should not appear again, unless you connect the board to a different USB port.

## 7 Evaluating with the ADCPro Software

The evaluation software is based on ADCPro, a program that operates using a variety of plug-ins. (The MSOP-8EVM plug-in is installed as described in the installation section.)

To use ADCPro, load an EVM plug-in and a test plug-in. To load an EVM plug-in, select it from the *EVM* menu. To load a test plug-in, select it from the *Test* menu. To unload a plug-in, select the *Unload* option from the corresponding menu.

Only one of each kind of plug-in can be loaded at a time. If you select a different plug-in, the previous plug-in is unloaded.

### 7.1 Using the MSOP-8EVM-PDK Plug-In

The MSOP-8EVM-PDK plug-ins for ADCPro provide complete control over all settings of the MSOP-8EVM devices. The MSOP-8EVM device settings can be adjusted when not acquiring data. During acquisition, all controls are disabled and settings may not be changed.

When you change a setting on the MSOP-8EVM device plug-in, the setting is immediately updated on the board.

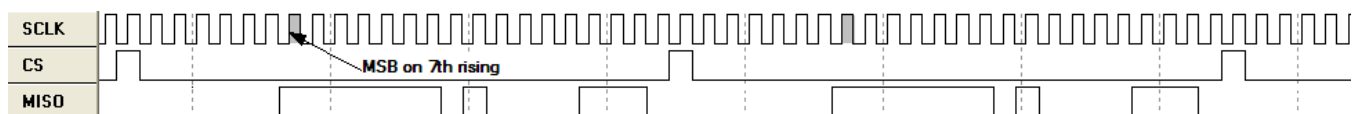
If you unload and reload the plug-in, the software will attempt to load settings from the board.

Settings on the MSOP-8EVM device correspond to the settings described in the particular installed device data sheet. For example, if the installed MSOP-8EVM device is the ADS8326, see the [ADS8326](#) data sheet (available for download at [www.ti.com](http://www.ti.com)) for details.

The user-configurable settings include *Sample Rate*, *Vref* and *Mode*. The sample rate can only be set up to the maximum stipulated sample rate in the device data sheet (that is, 250kHz for the ADS8326) and *Vref* is specified in the device data sheet (that is, 0.1V to 5V for the ADS8326). The three available clock modes are *Continuous Clock—Max SCLK*, *Clockstop Mode—Max SCLK*, and *Continuous Mode—Stretched SCLK*.

#### 7.1.1 Continuous Clock—Max SCLK

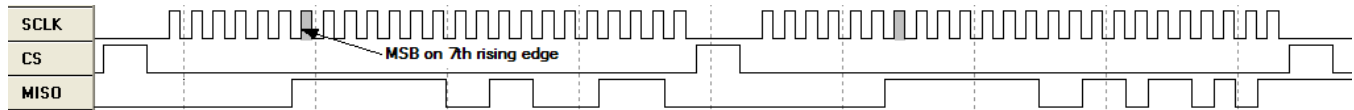
In this mode, SCLK frequency is given as the highest possible serial clock frequency for the data converter under test. The sampling frequency can be adjusted to any desired rate by entering a value in the sampling rate window. The software associated with the MSOP-8 plugin adjusts the number of clock cycles between rising  $\overline{CS}$  pulses to accommodate the requested sampling rate while keeping the serial clock speed constant.



**Figure 14. Continuous Clock—Max SCLK**

### 7.1.2 Clockstop Mode—Max SCLK

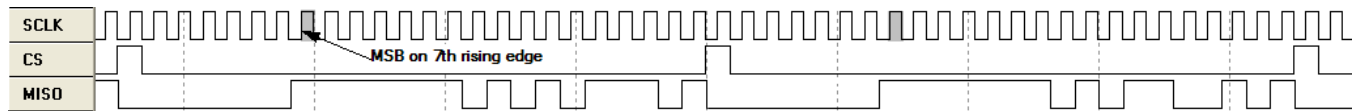
In this mode, SCLK frequency is also the highest possible serial clock frequency for the data converter under test. The sampling frequency can be adjusted to any desired rate by entering a value in the sampling rate window. The primary difference in this mode of operation is that there are 24 cycles of the serial clock applied to the ADC while the CS input is active. Delay time is added between CS to accommodate the desired sampling rate.



**Figure 15. Clockstop Mode—Max SCLK**

### 7.1.3 Continuous Mode—Stretched SCLK

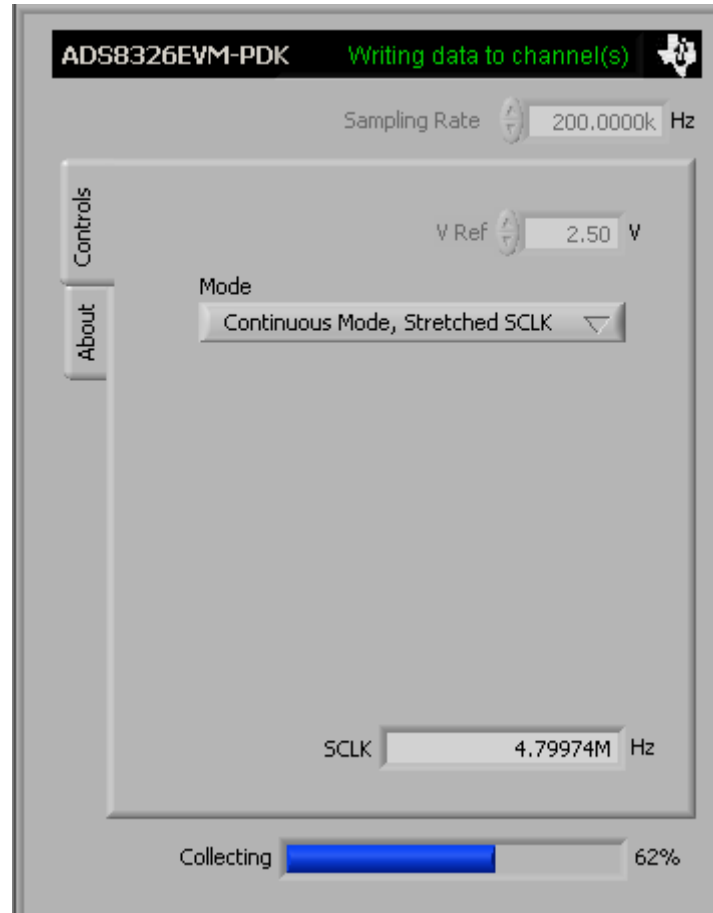
In this mode, SCLK frequency is calculated by the following equation:  $SCLK = \text{sampling rate} \times \text{cycles/sample}$ . The number of clock cycles per sample period depend on the data converter under test (for the ADS8326, this value is 24). Therefore, with the maximum sampling frequency,  $SCLK = 250\text{kHz} \times 24 = 6\text{MHz}$ . The number of SCLK cycles applied to the converter is fixed, and the period of the SCLK automatically scales to reach the desired sampling rate for the given device.



**Figure 16. Continuous Mode—Stretched SCLK**

### 7.1.4 Collecting Data

Once you have configured the ADSXXXXEVM device for your test scenario, pressing the ADCPro *Acquire* button starts the collection of the number of data points specified in the Test plug-in *Block Size* control. The ADSXXXXEVM-PDK plug-in disables all the front panel controls while acquiring and displays a progress bar, as shown in [Figure 17](#).



**Figure 17. Progress Bar While Collecting Data**

For more information on testing ADCs in general and using ADCPro and Test plug-ins, refer to the [ACDPro User's Guide](#).

## 7.2 Troubleshooting

If ADCPro stops responding while the ADSXXXXEVM-PDK is connected, unplug the power supply from the PDK. Unload and reload the plug-in before reapplying power to the PDK.

## **Bill of Materials (BOM) and Schematic**

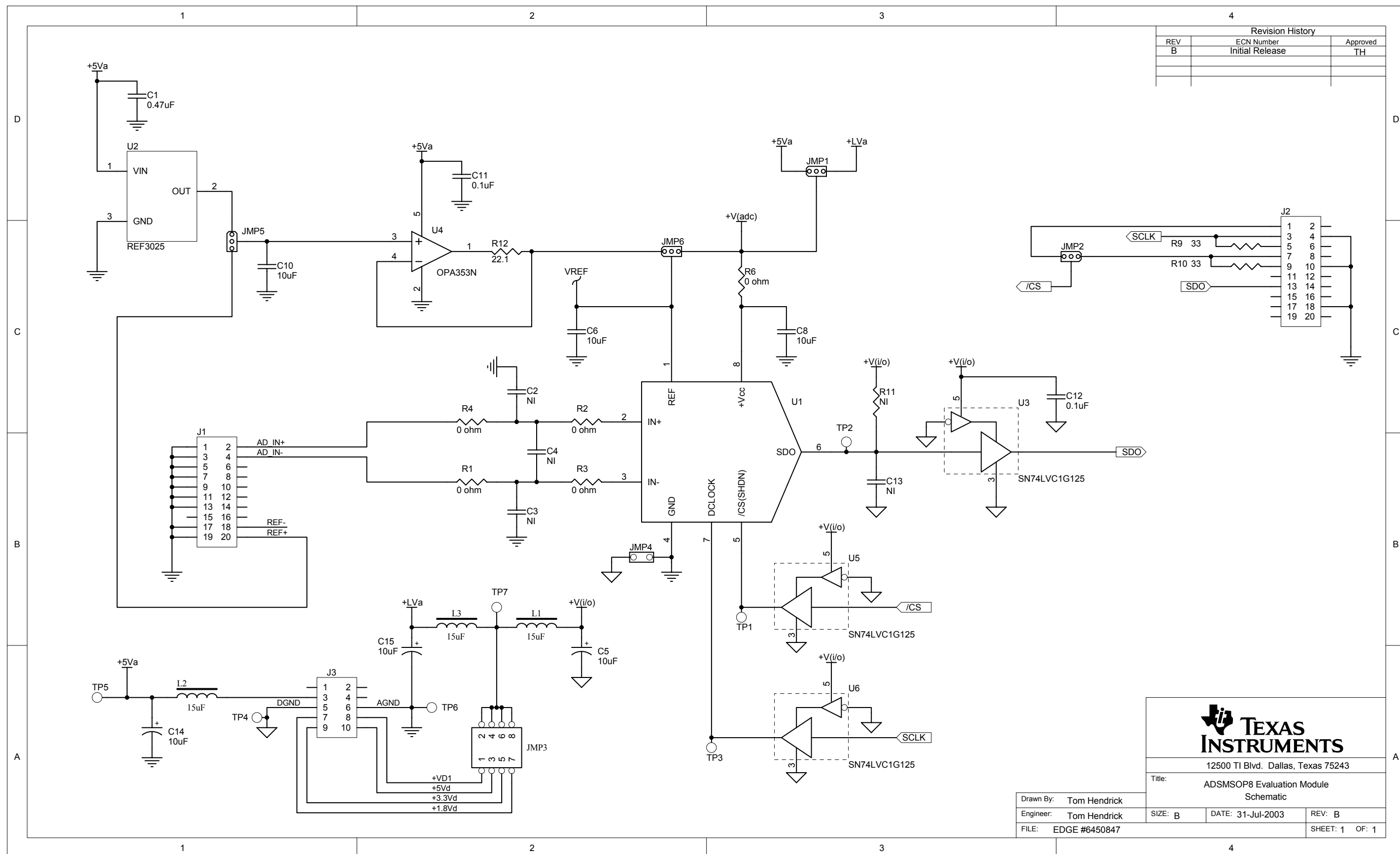
**Table 6** contains a complete bill of materials for the modular MSOP-8EVM. The schematic diagram is also provided.

**Table 6. Bill of Materials**

<b>Designators</b>	<b>Description</b>	<b>Manufacturer</b>	<b>Mfg. Part Number</b>
C2, C3, C4, C13	Not Installed		
R11	Not Installed		
C1	0.47 $\mu$ F, 0805, Ceramic, X7R, 10%	Panasonic	ECJ-2YB1C474K
C11, C12, C14	0.1 $\mu$ F, 0805, Ceramic, X7R, 50V, 10%	Panasonic	ECJ-2YB1H104K
C6, C8, C10	10 $\mu$ F, 1206, Ceramic, Y5V, 10V, 10%	Panasonic	ECJ-3YF1A106Z
C5, C14, C15	10 $\mu$ F, A Case, Tantalum, 10V	Panasonic	ECS-T1AY106R
L1, L2, L3	15 $\mu$ H Inductor, SMT, 1608 Series	Inductors, Inc.	CTDS1608C-153
J1, J2 (top side)	10 Pin, Dual Row, SMT Header (20 Pos.)	Samtec	TSM-110-01-T-DV-P
J1B, J2B (bottom side)	10 Pin, Dual Row, SMT Socket (20 Pos.)	Samtec	SSW-110-22-F-D-VS-K
J3 (bottom side)	5 Pin, Dual Row, SMT Socket (10 Pos.)	Samtec	SSW-105-22-F-D-VS-K
R9, R10	33 $\Omega$ , 0805, 5%, 0.1W Resistor	Yageo America	9C08052A33R0JLHFT
R1, R2, R3, R4, R6	0 $\Omega$ , 0805, 0.1W Resistor	Yageo America	9C08052A0R00JLHFT
TP1, TP2, TP3, TP5, TP7	Red Test Point Loop	Keystone	5001
TP4, TP6	Black Test Point Loop	Keystone	5000
U1	Varies <sup>(1)</sup>		
U2	REF3025	TI	REF3025AIDBZT
U3, U5, U6	SN74LVC1G125	TI	SN74LVC1G125DBVT
U4	OPA353N	TI	OPA353NA/250
JMP1, JMP2, JMP5, JMP6	3 Pin , 2mm Header	Samtec	TMMH-103-C-S-T
JMP3	4 Pin, Dual Row, TH Header (8 Pos.)	Samtec	TSW-104-07-L-D

<sup>(1)</sup> The device installed at location U1 depends on the EVM ordered. This device is soldered to the board for best performance. U1 may be replaced with any device listed in the EVM-compatible device data sheets found in [Table 1](#).

Revision History		
REV	ECN Number	Approved
B	Initial Release	TH



**TEXAS INSTRUMENTS**  
 12500 TI Blvd. Dallas, Texas 75243

Title: **ADSMSOP8 Evaluation Module Schematic**

Drawn By: Tom Hendrick	SIZE: B	DATE: 31-Jul-2003	REV: B
Engineer: Tom Hendrick	FILE: EDGE #6450847	SHEET: 1	OF: 1



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## Revision History

Changes from Original (December 2008) to A Revision	Page
• Modified the <i>MMB0 Initial Setup</i> image. ....	9
• Replaced reference of wall supply to external supply in the <i>Connecting the Power Supply</i> section. ....	11
• Modified the <i>Connecting an AC Adapter</i> image. ....	11
• Modified <i>Laboratory Power-Supply Connection</i> image. ....	12

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NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

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### CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

### FCC Interference Statement for Class A EVM devices

*NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.*

## FCC Interference Statement for Class B EVM devices

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- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

### 3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210

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This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

#### Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

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Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

#### Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

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If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required by Radio Law of Japan to follow the instructions below with respect to EVMs:

1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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