



DEMO MANUAL DC2855A

LTC7818 Triple Output Synchronous Step-Up/Dual Step-Down Supply

DESCRIPTION

Demonstration circuit DC2855A is a triple output synchronous step-up/dual step-down supply featuring the LTC®7818. The demonstration circuit is designed for two buck outputs 5V/10A, 3.3V/10A supplied by a boosted 10V output. Benefiting from this feature, the buck outputs are able to maintain regulation over a wide input voltage range of 4.5V to 36V which is suitable for automotive or other battery fed applications. Also, the demonstration circuit uses a drop-in layout whereas the main buck circuit components fit in an area of 34" by 1½", while the main boost circuit area is 34" by 1¾". The package style for the LTC7818 is a 40-pin exposed pad QFN.

The main features of the board include rail tracking (Buck channels only), an internal 5V linear regulator for bias, separated RUN pins for each output, a PGOOD signal (CH1 only), an overvoltage indicator for CH3 and a Mode selector that allow the converter to run in CCM, Pulse-skipping or Burst Mode operation. Spread Spectrum Mode is availiable for EMI improvement. Synchronization to an external clock is also possible. The LTC7818 data-sheet gives a complete description of these parts, operation and application information. The datasheet must be read in conjunction with this quick start guide for demo circuit 2855A.

Design files for this circuit board are available.

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PERFORMANCE SUMMARY Specifications are at T_A = 25°C

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
V _{IN}	Input Supply Range	Operating (Note 1)	4.5		36	V
		Continuous operation, I _{OUT1} = 0A-10A, I _{OUT2} = 0A-10A, free air	8		16	V
V _{OUT1}	Output1 Voltage		3.2	3.3	3.4	V
V _{OUT2}	Output2 Voltage		4.9	5	5.1	V
V _{OUT3}	Output3 Voltage	V _{IN} = 4.5V-10V (Note 2)	9.8	10	10.2	V
I _{OUT1}	Output1 Current		0		10	А
I _{OUT2}	Output2 Current		0		10	Α
I _{OUT3}	Output3 Current		0		10 (Note 3)	A
f _{SW}	Switching Frequency			2200		kHz
POUT/PIN	Efficiency	V _{IN} = 12V, V _{OUT1} = 3.3V, I _{OUT1} = 10A, RUN2 = 0		88		%
		V _{IN} = 12V, V _{OUT2} = 5V, I _{OUT2} = 10A, RUN1 = 0		91.6		%
		$V_{IN} = 12V$, $V_{OUT1} = 5V$, $V_{OUT2} = 3.3V$, $I_{OUT1} = 10A$, $I_{OUT2} = 10A$		90		%
		V _{IN} = 8V, V _{OUT3} = 10V, I _{OUT3} = 10A, RUN1, 2 = 0		94.6		%

Note 1: When $4.5V < V_{IN} < 8V$ and $16V < V_{IN} < 36V$, only short time operation is allowed at maximum output power (free air). For example, run 10sec when $V_{IN} = 4.5V$, 2min when $V_{IN} = 6V$, 2min when $V_{IN} = 26V$, 10s when $V_{IN} = 36V$ or continuously operate for de-rated output current.

Note 2: V_{OUT3} follows V_{IN} when $V_{IN} > V_{OUT3}$.

Note 3: 10A Maximum output includes the current supplying CH1 and CH2.

QUICK START PROCEDURE

Demonstration circuit DC2855A is easy to set up to evaluate the performance of the LTC7818. Refer to Figure 1 for the proper measurement equipment setup and follow the procedure below:

NOTE: When measuring the output voltage ripple, care must be taken to avoid a long ground lead on the oscilloscope probe. Measure the input or output voltage ripple by touching the probe tip directly across the V_{IN} or V_{OUT} and GND termnals or directly across the relevant capacitor. See Figure 2 for proper scope probe technique.

1. Place jumpers in the following positions:

JP1 ON

JP2 ON

JP3 ON

JP4 SPREAD OFF

JP5 Force Continuous Mode (FCM)

- 2. With power off, connect the input power supply to V_{IN} and GND. With power off, connect loads from V_{OUT} to GND.
- 3. Turn on the power at the input.

NOTE: Make sure that the input voltage does not exceed 36V.

4. Check for the proper output voltages.

 $V_{OUT1} = 3.2V \text{ to } 3.4V$

 $V_{OIIT2} = 4.9V \text{ to } 5.1V$

 $V_{OUT3} = 9.8V$ to 10.2V (V_{OUT3} follows V_{IN} when V_{IN} is higher than 10V)

NOTE: If there is no output, temporarily disconnect the load to make sure that the load is not set too high.

5. Once the proper output voltages are established, adjust the loads within the operating ranges and observe the output voltage regulation, ripple voltage, efficiency, and other parameters.

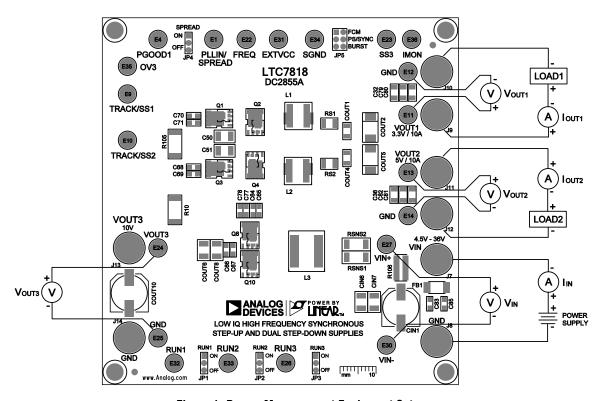


Figure 1. Proper Measurement Equipment Setup

QUICK START PROCEDURE

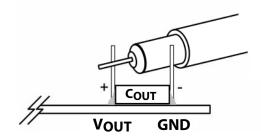


Figure 2. Proper Measurement Equipment Setup

Mode Selection, Spread Spectrum, and Frequency Synchronization

The Demonstration circuit 2855A's Mode selector allows the converter to run in FCM operation, pulse skip operation, and Burst Mode by changing the position of JP5.

Spread Spectrum is enabled by placing JP4 to "ON" position. For synchronizing to an external clock source, JP4 jumper needs to be removed. Apply the external clock from PLLIN/SPREAD turret to GND. Refer to Table 1 and to the datasheet for more details.

Rail Tracking

Demonstration circuit 2855A is configured for an on-board soft-start circuit. The soft-start ramp rate can be adjusted by changing the value of C2 and C47. Demonstration circuit 2855A can also be modified to track an external reference. Refer to Table 2 and Table 3 for tracking options and to the datasheet for more details.

Table 1. Mode Selection and Synchronizing Operation Options

CONFIGURATION	MODE JUMPER
Forced CCM Mode Operation	"FCM"
Pulse Skip Mode Operation	"PS"
Burst Mode Operation	"BURST"
Synchronize to Ext. clock (Ext. clock apply to PLLIN/SPREAD turret)	Remove Jumper JP4
Spread Spectrum Mode	"SPREAD ON"

Table 2. Vout1 Tracking Options

CONFIGURATION	R2	R3	C2	TRK/SS1 CAP
Soft Start Without Tracking (Default)	OPEN	OPEN	0.1uF	OPEN
V _{OUT1} Tracking Scaled V _{OUT2}	Resistor Divider		OPEN	OPEN

Table 3. V_{OUT2} Tracking Options

CONFIGURATION	R34	R37	C47	TRK/SS2 CAP
Soft Start Without Tracking (Default)	ΟΩ	OPEN	0.1uF	OPEN
V _{OUT2} Equals External Ramp	0Ω	OPEN	OPEN	External Ramp
V _{OUT2} Tracking Scaled External Ramp	Resisto	r Divider	OPEN	External Ramp

QUICK START PROCEDURE

Optional Inductor DCR Current Sensing

Demonstration circuit 2855A provides an optional circuit for Inductor DCR Current Sensing. Inductor DCR Current Sensing uses the DC resistance of the inductor to sense the inductor current instead of discrete sense resistors. The advantages of DCR sensing are lower cost, reduced board space, and higher efficiency, but the disadvantage is a less accurate current limit. If DCR sensing is used, be sure to select an inductor with a sufficiently high saturation current.

Refer to Table 4 for Optional Inductor DCR Current Sensing setup and to the datasheet for more details.

Low Quiescent Current Applications

The typical quiescent current (I_Q) of the LTC7818 controller is 14uA in sleep mode as specified in the LTC7818 datasheet. However, the input current of the DC2855A board can be higher than this value because of the additional circuit outside of the IC. Several methods can be adopted to reduce the total input current: (1) Large value FB divider resistors should be used; (2) If 8V or 10V boost output is required, connecting V_{PRG3} to GND or $INTV_{CC}$, with V_{FB3} directly connected to the output can reduce I_Q ; (3) In addition, the optional pull-up resistors should be removed from the board.

Minimum On-Time Causes Channel 2 And Channel 3 To Skip Pulses

The typical minimum on-time Ton(min) of the LTC7818 is 40ns for the Buck channels, and 80ns for the boost channel as specified in the datasheet. Therefore, when the input voltage is higher than 30V the CH2 may start to skip pulses at no load condition. And when the input voltage is higher than 7.5V, the CH3 may start to skip pulses at no load condition.

Thermal Derating Of The Buck Channels

The maximum DC output current of each Buck channel is specified at the nominal input voltage, which is 8V~16V. At higher input voltage, because of the increased power losses, the output currents should be derated. The power devices (Power MOSFETs, inductors) surface temperature must be monitored to ensure safe steady-state operation at higher input voltages.

EXTV_{CC} Supply

With the high switching frequency, the power losses imposed on the LTC7818 on-board gate drivers and LDO become a concern. Apply an external supply voltage to the EXTV_{CC} turret can help reduce LDO loss. On the DC2855A board, by removing R55 and placing zero ohm for R93, 5V (output of channel 2) will be provided for EXTV_{CC}.

Table 4. Optional Inductor DCR Current Sensing

<u> </u>			•					
	CHANNEL1	RS1	R29	R30	C14	R45	R47	R61
CONFIGURATION	CHANNEL2	RS2	R39	R40	C15	R51	R53	R62
	CHANNEL3	RSNS1,2	R80	R81	C56	R89	R90	R91
Current Sense Resistor (Default)		Ref. Sch.	Ref. Sch.	Ref. Sch.	Ref. Sch.	OPEN	OPEN	OPEN
Inductor DCR Current Sensing		0Ω Copper	OPEN	OPEN	Calculated Value from Datasheet		0Ω	

TYPICAL PERFORMANCE CHARACTERISTICS

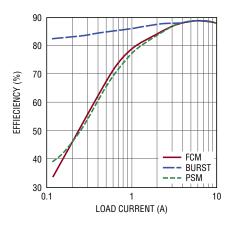


Figure 3. CH1 Efficiency ($V_{IN} = 12V$, $V_{OUT1} = 3.3V$)

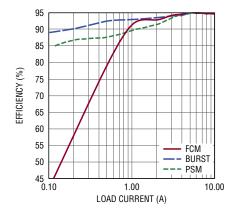


Figure 5. CH3 Efficiency (V_{IN} = 8V, V_{OUT3} = 10V)

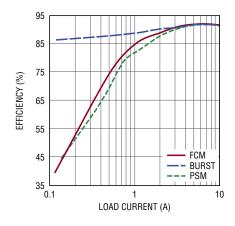


Figure 4. CH2 Efficiency ($V_{IN} = 12V$, $V_{OUT2} = 5V$)

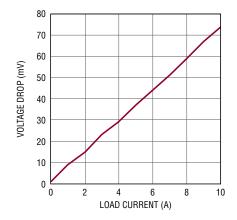


Figure 6. CH3 Voltage Drop in Pass-through Mode

TYPICAL PERFORMANCE CHARACTERISTICS

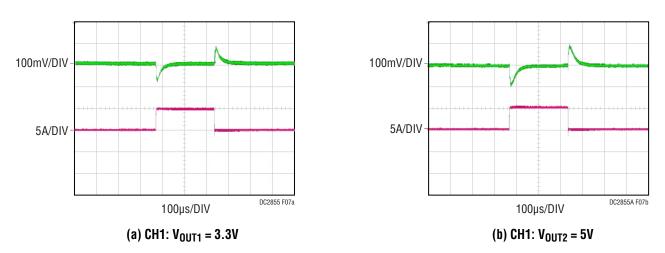


Figure 7. Transient Response Waveform at 12V V_{IN} and 5A – 10A – 5A load current

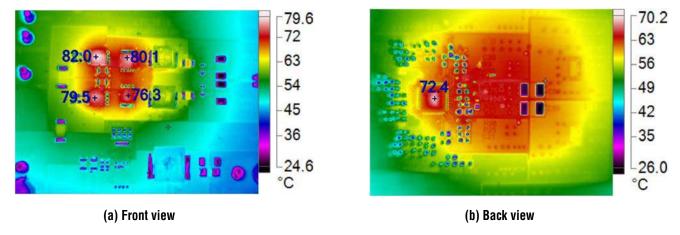


Figure 8. Thermal Image: V_{IN} = 12V, V_{OUT1} = 3.3V, I_{OUT1} = 10A, V_{OUT2} = 5V, I_{OUT2} = 10A, NO AIR FLOW, T_A = 25°C

TYPICAL PERFORMANCE CHARACTERISTICS

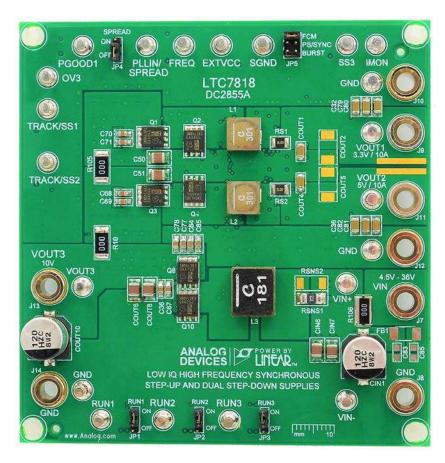


Figure 9. Picture of demo board

DEMO MANUAL DC2855A

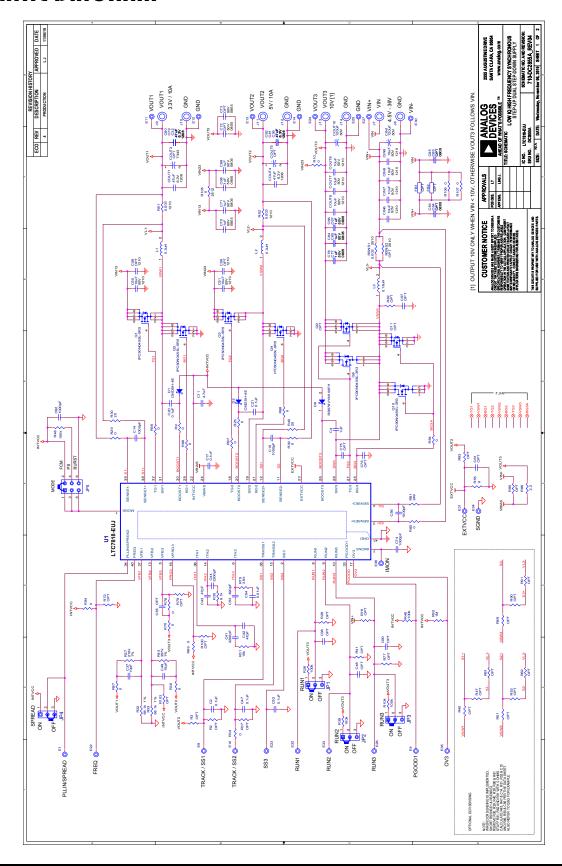
PARTS LIST

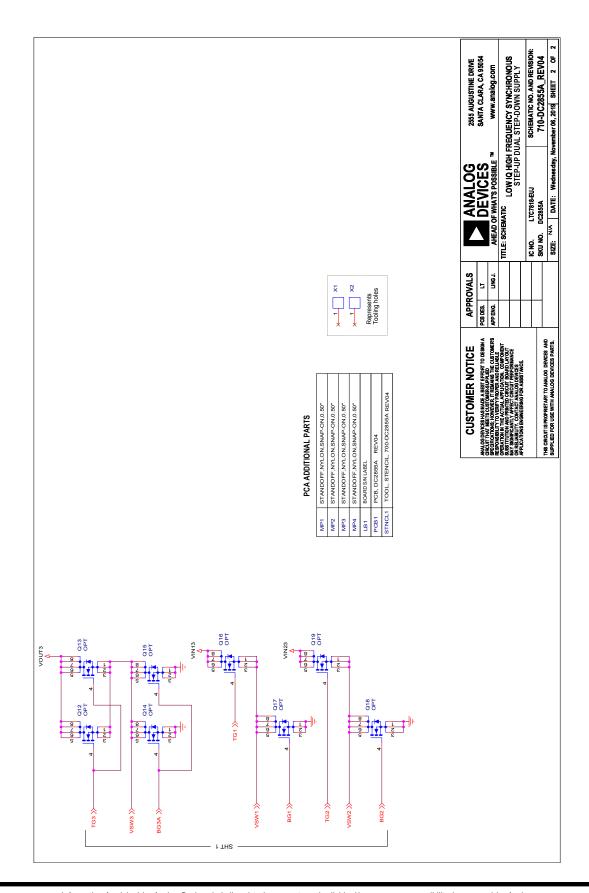
ITEM	QTY	REFERENCE	PART DESCRIPTION	MANUFACTURER/PART, NUMBER
Require	d Circuit	Components		
1	6	C2, C17, C20, C21, C47, C52	CAP., 0.1uF, X7R, 25V, 10%, 0603	AVX, 06033C104KAT2A
2	1	C4	CAP, 1uF, X7R, 16V, 10%, 0603	KEMET, C0603C105K4RAC7867
3	1	C11	CAP., 4.7uF, X5R, 6.3V, 10%, 0805	AVX, 08056D475KAT2A
4	5	C14, C15, C56, C62, C74	CAP, 1000pF, X7R, 50V, 10%, 0603	AVX, 06035C102KAT2A
5	8	C32, C36, C79, C80, C81, C82, COUT1, COUT4	CAP., 47uF, X5R, 6.3V, 20%, 1206	MURATA, GRM31CR60J476ME19L
6	2	C37, C49	CAP, 10pF, X7R, 50V, 10%, 0603	AVX, 06035C100KAT2A
7	1	C41	CAP., 2200pF, X7R, 25V, 10%, 0603	AVX, 06033C222KAT2A
8	2	C42, C43	CAP, 47pF, C0G, 50V, 5%, 0603, AEC-Q200	AVX, 06035A470J4T2A
9	1	C44	CAP., 2200pF, X7R, 50V, 10%, 0603	AVX, 06035C222KAT2A
10	9	C50, C51, CIN6, CIN7, COUT6, COUT7, COUT8, CIN8, CIN9	CAP, 10uF, X7S, 50V, 10%, 1210	TAIYO YUDEN, UMK325C7106KM-T
11	1	C53	CAP, 820pF, COG, 50V, 5%, 0603	AVX, 06035A821JAT2A
12	1	C54	CAP., 0.01uF, X7R, 50V, 10%, 0603	AVX, 06035C103KAT2A
13	10	C64, C65, C66, C67, C68, C69, C70, C71, C77, C78	CAP., 1uF, X7R, 50V, 10%, 0805	TAIYO, YUDEN, UMK212B7105KG-T
14	2	CIN1, COUT10	CAP., 120uF, ALUM. ELECT., 50V, 20%, 10x10.2mm SMD, RADIAL, AEC-Q200	PANASONIC, EEHZC1H121P
15	2	D1, D2	DIODE, SCHOTTKY, 40V, 250mW, SOD-323	CENTRAL SEMI., CMDSH-4E, TR, Lead, Free
16	1	D6	DIODE, SCHOTTKY, 100V, 250mW, SOD-323	ROHM, RB578VYM100FH
17	2	L1, L2	IND., 0.3uH, PWR., 20%, 10A, 21.45mOHMS, SMD 7.5mmX7.5mm, AEC-Q200	COILCRAFT, XAL7030-301ME
18	1	L3	IND., 0.18uH, PWR., 20%, 120A, 11.3x10mm SMD, XAL1060, AEC-Q200	COILCRAFT, XAL1060-181MEC
19	4	Q1, Q2, Q3, Q4	XSTR., MOSET, N-CH, 40V, 50A, PG-TDSON-8-33, AEC-Q101	INFINEON, IPC50N04S5L-5R5
20	2	Q8, Q10	XSTR., MOSFET, N-CH, 40V, 90A, PG-TDSON-8-33, AEC-Q101	INFINEON, IPC90N04S5L-3R3
21	18	R9, R25, R29, R34, R36, R39, R55, R70, R78, R80, R84, R87, R94, R95, R96, R97, R98, R99	RES., 0 OHM, 1/10W, 0603, AEC-Q200	VISHAY, CRCW06030000Z0EA
22	2	R10, R105	RES., 0 OHM, 1W, 2512, 7A, AEC-Q200	VISHAY, CRCW25120000Z0EG
23	2	R30, R40	RES., 20 OHM, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ-3EKF20R0V
24	5	R26, R38, R46, R48, R104	RES., 100k OHMS, 5%, 1/10W, 0603	PANASONIC, ERJ3GEYJ104V
25	2	R106, R107	RES., 0 OHMS, 2W, 2512 LONG SIDE TERM, AEC-Q200	VISHAY, RCL12250000Z0EG
26	1	R27	RES., 210k OHMS, 1%, 1/10W, 0603	NIC, NRC06F2103TRF
27	1	R31	RES., 10k OHMS, 1%, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ3EKF1002V
28	2	R32, R33	RES., 68.1k OHMS, 1%, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ3EKF6812V
29	1	R35	RES., 9.1k OHMS, 1%, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ3EKF9101V

PARTS LIST

ITEM	QTY	REFERENCE	PART DESCRIPTION	MANUFACTURER/PART, NUMBER
30	1	R43	RES., 357k OHMS, 1%, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ3EKF3573V
31	1	R75	RES., 3.6k OHMS, 1%, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ3EKF3601V
32	1	R81	RES., 249 OHMS, 1%, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ3EKF2490V
33	1	R86	RES., 2.2 OHMS, 5%, 1/10W, 0603, AEC-Q200	PANASONIC, ERJ3GEYJ2R2V
34	1	R92	RES., 1M OHM, 1%, 1/10W, 0603, AEC-Q200	VISHAY, CRCW06031M00FKEA
35	2	RS1, RS2	RES., 0.003 OHMS, 5%, 1W, 1210, AEC-Q200	ROHM, PMR25HZPJV3L0
36	1	RSNS1	RES., 0.002 OHMS, SENSE, 1%, 2W, 2010, AEC- Q200, PULSE PROOF	VISHAY, WSLP20102L000FEA
37	1	U1	IC, HIGH FREQ. SYNCHRONOUS STEP UP/DUAL STEP-DOWN POWER SUPPLY, 40QFN	ANALOG DEVICES, LTC7818EUJ#PBF
Addition	al Demo	Board Circuit Components		
1	0	C38, C48, C55, C57, C60, C75, C76	CAP., OPTION, 0603	
2	0	C58, C59	CAP, OPTION, 1210	
3	0	C61, C72, C73, C83, C84, C85, C86	CAP., OPTION, 0805	
4	0	COUT2, COUT5	CAP., OPTION, 7343	
5	0	FB1, FB2	IND., OPTION, 1812	
6	0	Q9, Q11	XSTR., OPTION, MOSFET N-CH, PG-TDSON-8	
7	0	Q12, Q13, Q14, Q15, Q16, Q17, Q18, Q19	XSTR., OPTION, MOSFET N-CH, PPAK SO-8	
8	0	R2, R3, R28, R37, R41, R45, R47, R51, R53, R61, R62, R72, R76, R77, R79, R85, R89, R90, R91, R93, R100, R103	RES., OPTION, 0603	
9	0	R82	RES., OPTION, 1206	
10	0	RSNS2	RES., OPTION, 2010	
Hardwar	e: For D	emo Board Only		
1	21	E1, E4, E9, E10, E11, E12, E13, E14, E22, E23, E24, E25, E26, E27, E30, E31, E32, E33, E34, E35, E36	TEST POINT, TURRET, 0.094" MTG. HOLE, PCB 0.062" THICK	MILL-MAX
2	8	J7, J8, J9, J10, J11, J12, J13, J14	CONN., BANANA JACK, FEMALE, THT, NON- INSULATED, SWAGE, 0.218"	KEYSTONE
3	4	JP1, JP2, JP3, JP4	CONN., HDR, MALE, 1x3, 2mm, VERT, STR, THT, NO SUBS. ALLOWED	WURTH ELEKTRONIK
4	1	JP5	CONN., HDR, MALE, 2x3, 2mm, VERT, STR, THT	WURTH ELEKTRONIK
5	5	XJP1, XJP2, XJP3, XJP4, XJP5	CONN., SHUNT, FEMALE, 2 POS, 2mm	WURTH ELEKTRONIK
6	4	MP1, MP2, MP3, MP4	STANDOFF, NYLON, SNAP-ON, 0.50"	WURTH ELEKTRONIK

SCHEMATIC DIAGRAM





DEMO MANUAL DC2855A



ESD Caution

ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

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