MAXM

Calibrated, Quad, 12-Bit Voltage-Output DACs with Serial Interface

_______________General Description

The MAX536/MAX537 combine four 12-bit, voltage-output digital-to-analog converters (DACs) and four precision output amplifiers in a space-saving 16-pin package. Offset, gain, and linearity are factory calibrated to provide the MAX536's ±1LSB total unadjusted error. The MAX537 operates with ±5V supplies, while the MAX536 uses -5V and $+12V$ to $+15V$ supplies.

Each DAC has a double-buffered input, organized as an input register followed by a DAC register. A 16-bit serial word is used to load data into each input/DAC register. The serial interface is compatible with either SPI/QSPI™ or Microwire™, and allows the input and DAC registers to be updated independently or simultaneously with a single software command. The DAC registers can be simultaneously updated with a hardware LDAC pin. All logic inputs are TTL/CMOS compatible.

________________________Applications

Industrial Process Controls

Automatic Test Equipment

Digital Offset and Gain Adjustment

Motion Control Devices

Remote Industrial Controls

Microprocessor-Controlled Systems

________________Functional Diagram

____________________________Features

- ♦ **Four 12-Bit DACs with Output Buffers**
- **Simultaneous or Independent Control of Four DACs via a 3-Wire Serial Interface**
- ♦ **Power-On Reset**
- **SPI/QSPI and Microwire Compatible**
- $±1LSB$ Total Unadjusted Error (MAX536)
- ♦ **Full 12-Bit Performance without Adjustments**
- ♦ **±5V Supply Operation (MAX537)**
- ♦ **Double-Buffered Digital Inputs**
- ♦ **Buffered Voltage Output**
- ♦ **16-Pin DIP/SO Packages**

______________Ordering Information

Ordering Information continued at end of data sheet.

* Contact factory for dice specifications.

** Contact factory for availability and processing to MIL-STD-883.

Pin Configuration

SPI and QSPI are trademarks of Motorola, Inc. Microwire is a trademark of National Semiconductor Corp.

MAXIM

__ Maxim Integrated Products 1

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ABSOLUTE MAXIMUM RATINGS

VDD to AGND or DGND

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS—MAX536

 $(VDD = +15V, VSS = -5V, REFAB/REFCD = 10V, AGND = DGND = 0V, R_L = 5kΩ, C_L = 100pF, TA = T_{MIN} to T_{MAX}, unless$ otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

MAX536/MAX537 MAX536/MAX53

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MAXM

ELECTRICAL CHARACTERISTICS—MAX536 (continued)

 $(V_{DD} = +15V, V_{SS} = -5V, REFAB/REFCD = 10V, AGND = DGND = 0V, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless$ otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

MAXIM

ELECTRICAL CHARACTERISTICS—MAX536 (continued)

 $(V_{DD} = +15V, V_{SS} = -5V, REFAB/REFCD = 10V, AGND = DGND = 0V, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless$ otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

Note 1: TUE is specified with no resistive load.

Note 2: Guaranteed by design.

Note 3: Crosstalk is defined as the glitch energy at any DAC output in response to a full-scale step change on any other DAC.

Note 4: Digital inputs at 2.4V; with digital inputs at CMOS levels, I_{DD} decreases slightly.

Note 5: All input signals are specified with $t_R = t_F \le 5$ ns. Logic input swing is 0V to 5V.

Note 6: Serial data clocked out of SDO on SCK's falling edge. (SDO is an open-drain output for the MAX536. The MAX537's SDO pin has an internal active pull-up.)

Note 7: Serial data clocked out of SDO on SCK's rising edge.

Note 8: SDO changes from High-Z state to 90% of final value.

Note 9: SDO rises 10% toward High-Z state.

MAXM

ELECTRICAL CHARACTERISTICS—MAX537

 $(VDD = +5V, VSS = -5V, REFAB/REFCD = 2.5V, AGND = DGND = 0V, R_L = 5kΩ, C_L = 100pF, TA = T_{M1N} to T_{MAX}, unless$ otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

MAXIM

ELECTRICAL CHARACTERISTICS—MAX537 (continued)

 $(V_{DD} = +5V, V_{SS} = -5V, REFAB/REFCD = 2.5V, AGND = DGND = 0V, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless$ otherwise noted. Typical values are at $TA = +25^{\circ}C$.)

/VI/IXI/VI

ELECTRICAL CHARACTERISTICS—MAX537 (continued)

(V_{DD} = +5V, V_{SS} = -5V, REFAB/REFCD = 2.5V, AGND = DGND = 0V, R_L = 5k Ω , C_L = 100pF, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at $TA = +25^{\circ}C$.)

Note 2: Guaranteed by design.

Note 3: Crosstalk is defined as the glitch energy at any DAC output in response to a full-scale step change on any other DAC.

Note 4: Digital inputs at 2.4V; with digital inputs at CMOS levels, I_{DD} decreases slightly.

Note 5: All input signals are specified with $t_R = t_F \le 5$ ns. Logic input swing is 0V to 5V.

Note 6: Serial data clocked out of SDO on SCK's falling edge. (SDO is an open-drain output for the MAX536. The MAX537's SDO pin has an internal active pull-up.)

Note 7: Serial data clocked out of SDO on SCK's rising edge.

Note 10: When disabled, SDO is internally pulled high.

__Typical Operating Characteristics

50u5

50µs/div

INPUT CODE = ALL 0s

MAXIM

INPUT CODE = ALL 0s

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____________________________Typical Operating Characteristics (continued)

 $(T_A = +25^{\circ}C,$ unless otherwise noted.)

 V_{DD} = +15V, V_{SS} = -5V, REFAB = 5V, C_L = 100pF, R_L = 10k Ω

 V_{DD} = +15V, V_{SS} = -5V, REFAB = 10V, C_L = 100pF, R_L = 10kΩ

MAX536 NEGATIVE FULL-SCALE SETTLING TIME (ALL BITS ON TO ALL BITS OFF)

 $\rm V_{DD}$ = +15V, V_{SS} = -5V, REFAB = 10V, C_L = 100pF, R_L = 10k Ω

MAX536 DIGITAL FEEDTHROUGH

 V_{DD} = +15V, V_{SS} = -5V, REFAB = 10V, \overline{CS} = HIGH, DIN TOGGLING AT $\frac{1}{2}$ THE CLOCK RATE, $OUTA = 5V$

____________________________Typical Operating Characteristics (continued)

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MAX536/MAX537 **MAX536/MAX537**

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____________________________Typical Operating Characteristics (continued)

 $(T_A = +25^{\circ}C,$ unless otherwise noted.)

MAX537

 V_{DD} = +5V, V_{SS} = -5V, REFAB = 2.5V, C_L = 100pF, R_L = 10kΩ

 V_{DD} = +5V, V_{SS} = -5V, REFAB = 2.5V, C_L = 100pF, R_L = 10kΩ

MAX537 POSITIVE FULL-SCALE SETTLING TIME (ALL BITS OFF TO ALL BITS ON)

MAX537 DIGITAL FEEDTHROUGH

 V_{DD} = +5V, V_{SS} = -5V, REFAB = 2.5V, \overline{CS} = HIGH, DIN TOGGLING AT $\frac{1}{2}$ THE CLOCK RATE, OUTA = 1.25V

Pin Description

_______________Detailed Description

The MAX536/MAX537 contain four 12-bit voltage-output DACs that are easily addressed using a simple 3-wire serial interface. They include a 16-bit data-in/data-out shift register, and each DAC has a double-buffered input composed of an input register and a DAC register (see the Functional Diagram on the front page).

The DACs are "inverted" R-2R ladder networks that convert 12-bit digital inputs into equivalent analog output voltages in proportion to the applied reference-voltage inputs. DAC A and DAC B share the REFAB reference input, while DAC C and DAC D share the REFCD reference input. The two reference inputs allow different full-scale output voltage ranges for each pair of DACs. Figure 1 shows a simplified circuit diagram of one of the four DACs.

Reference Inputs

The two reference inputs accept positive DC and AC signals. The voltage at each reference input sets the full-scale output voltage for its two corresponding DACs. The REFAB/REFCD voltage range is 0V to ($V_{DD} - 4V$) for the MAX536 and 0V to ($V_{DD} - 2.2V$) for the MAX537. The output voltages VOUT_are represented by

Figure 1. Simplified DAC Circuit Diagram

a digitally programmable voltage source as:

 $VOUT = NB (VREF) / 4096$

where N_B is the numeric value of the DAC's binary input code (0 to 4095) and VREF is the reference voltage.

MAX536/MAX537 MAX536/MAX537

The input impedance at each reference input is code dependent, ranging from a low value of typically 6kΩ (with an input code of 0101 0101 0101) to a high value of 60kΩ (with an input code of 0000 0000 0000). Since the input impedance at the reference pins is code dependent, load regulation of the reference source is important.

The REFAB and REFCD reference inputs have a $5k\Omega$ guaranteed minimum input impedance. When the two reference inputs are driven from the same source, the effective minimum impedance becomes 2.5kΩ. A voltage reference with a load regulation of 0.001%/mA, such as the MAX674, would typically deviate by 0.164LSB (0.328LSB worst case) when simultaneously driving both MAX536 reference inputs at 10V.

An op amp, such as the MAX400 or OP07, can be used to buffer the reference to increase reference accuracy. The op amp's closed-loop output impedance should be kept below 0.05Ω to ensure an error of less than 0.08LSB. Reference accuracy is also improved by driving the REFAB and REFCD pins separately, or by using a reference with excellent accuracy and superior load regulation, such as the MAX676/MAX677/MAX678.

The reference input capacitance is also code dependent and typically ranges from 125pF to 300pF.

Output Buffer Amplifiers

All MAX536/MAX537 voltage outputs are internally buffered by precision unity-gain followers with a typical slew rate of 5V/us for the MAX536 and 3V/us for the MAX537.

With a full-scale transition at the MAX536 output (0V to 10V or 10V to 0V), the typical settling time to \pm 1/2LSB is 3us when loaded with $5k\Omega$ in parallel with 100pF (loads less than 5kΩ degrade performance).

With a full-scale transition at the MAX537 output (0V to 2.5V or 2.5V to 0V), the typical settling time to \pm 1/2LSB is 5µs when loaded with 5k Ω in parallel with 100pF (loads less than $5k\Omega$ degrade performance).

Output dynamic responses and settling performances of the MAX536/MAX537 output amplifier are shown in the Typical Operating Characteristics.

Serial-Interface Configurations

The MAX536/MAX537's 3-wire or 4-wire serial interface is compatible with both Microwire (Figure 2) and SPI/QSPI (Figure 3). In Figures 2 and 3, LDAC can be tied either high or low for a 3-wire interface, or used as the fourth input with a 4-wire interface. The connection between SDO and the serial-interface port is not necessary, but may be used for data echo. (Data held in the shift register

Figure 5. 4-Wire Serial-Interface Timing Diagram for Asynchronous DAC Updating Using LDAC

/VI/IXI/VI

Figure 6. Detailed Serial-Interface Timing Diagram

of the MAX536/MAX537 can be shifted out of SDO and returned to the microprocessor for data verification; data in the MAX536/MAX537 input/DAC registers cannot be read.)

With a 3-wire interface (CS, SCK, SDI) and LDAC tied high, the DACs are double-buffered. In this mode, depending on the command issued through the serial interface, the input register(s) may be loaded without affecting the DAC register(s), the DAC register(s) can be loaded directly, or all four DAC registers may be simultaneously updated from the input registers. With a 3 wire interface $(\overline{CS}, \overline{SCK}, \overline{SDI})$ and \overline{LDAC} tied low (Figure 4), the DAC registers remain transparent. Any time an input register is updated, the change appears at the DAC output with the rising edge of CS.

The 4-wire interface $(\overline{CS}, \overline{SCK}, \overline{SDI}, \overline{LDAC})$ is similar to the 3-wire interface with \overline{LDAC} tied high, except \overline{LDAC} is a hardware input that simultaneously and asynchronously loads all DAC registers from their respective input registers when driven low (Figure 5).

Serial-Interface Description

The MAX536/MAX537 require 16 bits of serial data. Data is sent MSB first and can be sent in two 8-bit packets or one 16-bit word $(\overline{CS}$ must remain low until 16 bits are transferred). The serial data is composed of two DAC address bits (A1, A0), two control bits (C1, C0), and the 12 data bits D11...D0 (Figure 7). The 4-bit address/control code determines the following: 1) the register(s) to be updated and/or the status of the input and DAC registers (i.e., whether they are in transparent or latch mode), and 2) the edge on which data is clocked out of SDO.

MSB I SB							
———————16 Bits of Serial Data ——————							
Address		Control		Data Bits			
Bits		Bits		MSB. I SB			
A1	A0	C ₁	C0				
4 Address/ Control Bits				12 Data Bits			

Figure 7. Serial-Data Format (MSB Sent First)

Figure 6 shows the serial-interface timing requirements. The chip-select pin (\overline{CS}) must be low to enable the DAC's serial interface. When \overline{CS} is high, the interface control circuitry is disabled and the serial data output pin (SDO) is driven high (MAX537) or is a high-impedance open drain (MAX536). $\overline{\text{CS}}$ must go low at least t_{CSS} before the rising serial clock (SCK) edge to properly clock in the first bit. When \overline{CS} is low, data is clocked into the internal shift register via the serial data input pin (SDI) on SCK's rising edge. The maximum guaranteed clock frequency is 10MHz. Data is latched into the appropriate MAX536/MAX537 input/DAC registers on \overline{CS} 's rising edge.

Interface timing is optimized when serial data is clocked out of the microcontroller/microprocessor on one clock edge and clocked into the MAX536/MAX537 on the other edge. Table 1 lists the serial-interface programming commands. For certain commands, the 12 data bits are "don't cares".

The programming command Load-All-DACs-From-Shift-Register allows all input and DAC registers to be simultaneously loaded with the same digital code from the input shift register. The NOP (no operation) command allows the register contents to be unaffected and is useful when the MAX536/MAX537 are configured in a daisy-chain (see the Daisy-Chaining Devices section). The command to change the clock edge on which serial data is shifted out of the MAX536/MAX537 SDO pin also loads data from all input registers to their respective DAC registers.

Serial-Data Output

The serial-data output, SDO, is the internal shift register's output. The MAX536/MAX537 can be programmed so that data is clocked out of SDO on SCK's rising (Mode 1) or falling (Mode 0) edge . In Mode 0, output data at SDO lags input data at SDI by 16.5 clock cycles, maintaining compatibility with Microwire, SPI/QSPI, and other serial interfaces. In Mode 1, output data lags input data by 16 clock cycles. On power-up, SDO defaults to Mode 1 timing.

For the MAX536, SDO is an open-drain output that should be pulled up to +5V. The data sheet timing specifications for SDO use a 1kΩ pull-up resistor. For the MAX537, SDO is a complementary output and does not require an external pull-up.

Test Pin

The test pin (TP) is used for pre-production analysis of the IC. **Connect TP to VDD for proper MAX536/MAX537 operation. Failure to do so affects DAC operation**.

Daisy-Chaining Devices

Any number of MAX536/MAX537s can be daisy-chained by connecting the SDO pin of one device (with a pull-up resistor, if appropriate) to the SDI pin of the following device in the chain (Figure 8).

Since the MAX537's SDO pin has an internal active pull-up, the SDO sink/source capability determines the time required to discharge/charge a capacitive load. Refer to the serial data out V_{OH} and V_{OL} specifications in the Electrical Characteristics.

Table 1. Serial-Interface Programming Commands

"X" = Don't Care. LDAC provides true latch control: when \overline{LDAC} is low, the DAC registers are transparent; when \overline{LDAC} is high, the DAC registers are latched.

When daisy-chaining MAX536s, the delay from $\overline{\text{CS}}$ low to SCK high (tcss) must be the greater of:

t _D $V + t$ _{DS} or

tTR + tRC + tDS - tCSW

where t_{RC} is the time constant of the external pull-up resistor (R_D) and the load capacitance (C) at SDO. For t_{RC} < 20ns, tCSS is simply tDV + tDS. Calculate tRC from the following equation:

$$
tr_{\text{RC}} = R_{p}(C) \quad \left[\ln \left(\frac{V_{\text{PULL-UP}}}{V_{\text{PULL-UP} - 2.4V}} \right) \right]
$$

where VPULL-UP is the voltage to which the pull-up resistor is connected.

Additionally, when daisy-chaining devices, the maximum clock frequency is limited to:

$$
f_{SCK}(max) = \frac{1}{2 (top + tr_{BC} - 38ns + tr_{DS})}
$$

For example, with t_{RC} = 23ns (5V \pm 10% supply with $R_p = 1k\Omega$ and C = 30pF), the maximum clock frequency is 8.7MHz.

Figure 9 shows an alternate method of connecting several MAX536/MAX537s. In this configuration, the data bus is common to all devices; data is not shifted through a daisy-chain. More I/O lines are required in this configuration because a dedicated chip-select input (CS) is required for each IC.

Figure 8. Daisy-Chaining MAX536/MAX537s with a 3-Wire Serial Interface

Figure 9. Multiple devices sharing a common DIN line may be simultaneously updated by bringing LDAC low. CS1, CS2, CS3... are driven separately, thus controlling which data are written to devices 1, 2, 3...

__________Applications Information

Interfacing to the M68HC11*

PORT D of the 68HC11 supports SPI. The four registers used for SPI operation are the Serial Peripheral Control Register, the Serial Peripheral Status Register, the Serial Peripheral Data I/O Register, and PORT D's Data Direction Register. These registers have a default starting location of \$1000.

On reset, the PORT D register (memory location \$1008) is cleared and bits 5-0 are configured as general-purpose inputs. Setting bit 6 (SPE) of the Serial Peripheral Control Register (SPCR) configures PORT D for SPI as follows:

Bits 6 and 7 are not used. Writes to these bits are ignored. The PORT D Data Direction Register (DDRD) determines whether the port bits are inputs or outputs. Its configuration is shown below:

Setting $DDD = 0$ configures the port bit as an input, while setting DDD_ = 1 configures the port bit as an output. Writes to bits 6 and 7 have no effect.

In SPI mode with $MSTR = 1$, when a PORT D bit is expected to be an input $($ \overline{SS} , MISO, RXD), the corresponding DDRD bit (DDD_) is ignored. If the bit is expected to be an output (SCK, MOSI, TXD), the corresponding DDRD bit must be set for the bit to be an output.

MAXM

Table 2. Serial Peripheral Control-Register Definitions

Table 3. Serial Peripheral Status-Register Definitions

*M68HC11 is a Motorola microcontroller. General information about the device was obtained from M68HC11 technical manuals.

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Table 4. M68HC11 Programming Code

```
* 68HC11 Programming Code for interfacing to the MAX536/MAX537 DACs.
\starData for the MAX536/MAX537 is stored in memory locations $0100 and $0101.
\starRelease Date February 24, 1994
 Revision 0
 Technical support provided by Motorola
* Additional assistance provided by Diane Scott
    68HC11 Code
                                  Instruction
\ddot{\phantom{0}}FOU
             $0000
                         ; Memory location for beginning of program
STRT
REGBLK EQU
             $1000
                         ; Starting address for 68HC11 register block
  The following registers will be addressed relative to the start of the
\starregister block (REGBLK) using indexed addressing mode.
\starThe effective address = contents of Index Register X + offset.
                         ; PORT D memory location
PORTD
             $08
       EQU
DDRD
       EQU
            $09
                         ; PORT D Data Direction Register memory location
                         ; SPCR memory location
SPCR
       FOU
            $28
                         ; SPSR memory location
SPSR
       EQU
            $29
SPDR
       EQU
            $2A
                         ; SPDR memory location
\starStart of main program
MAIN
       ORG
            STRT
                         ; an arbitrary MAX536/MAX537 DAC code (load input
       LDAA #$74
       STAA $0100
                         ; register B with 1/4 of full-scale value; all DAC
                         ; registers updated) is loaded into data memory
       LDAA #$00
       STAA $0101
                         ; locations $0100 and $0101.
                         ; load Index Register X with starting address of register block
       LDX
             #REGBLK
       LDAA #$38
                         ; SPI outputs (SCK, MOSI, and /SS configured as an output)
                         ; configured by setting the Data Direction Register bits
                         ; load data into the Data Direction Register
       STAA DDRD, X
       LDAA #$2F
                        ; set /SS and MOSI high; set SCK low
       STAA PORTD, X
                         ; load data into PORTD to set-up SPI control lines
                         ; set data for SPCR
       LDAA #$51
                         ; load data into the SPCR
       STAA SPCR.X
       BCLR PORTD, X $20 ; bring /CS low
                         ; load high byte of digital data into Accumulator(A)
       LDAA $0100
                          load high byte of MAX536/MAX537 data into SPDR
       STAA SPDR, X
WAIT1
       LDAA SPSR, X
                        ; beginning of loop to poll the SPSR
       BITA #$80
                        ; mask all bits except SPIF (transfer complete) flag
       BEQ
             WAIT1
                        ; branch if SPIF is not set to beginning of loop
                         ; load low byte of digital data into Accumulator(A)
       LDAA $0101
                           load low byte of MAX536/MAX537 data into SPDR
       STAA SPDR, X
       LDAA SPSR.X
WAIT2
                         ; beginning of loop to poll the SPSR
                         ; mask all bits except SPIF (transfer complete) flag
       BITA #$80
                         ; branch if SPIF is not set to beginning of loop
       BEQ
             WAIT2
       LDAA SPDR, X ; read the SPDR to clear the SPIF bit in the SPSR<br>BSET PORTD, X $20; bring / CS high to latch data into the MAX536/MAX537
 The MAX536/MAX537 is now configured to have V_{\text{OUTB}} = V_{\text{REF}} (1024/4096)
```
MAXIM

 \overline{SS} is an input intended for use in a multimaster environment. However, \overline{SS} or unused PORT D bit RXD, TXD, or possibly MISO (if DAC readback is not used) should be configured as a general-purpose output and used as $\overline{\text{CS}}$ by setting the appropriate Data Direction Register bit.

The SPCR configuration (memory location \$1028) is shown below:

*U = Unknown

**Depends on µP clock frequency.

Always configure the 68HC11 as the "master" controller and the MAX536/MAX537 as the "slave" device.

When $MSTR = 1$ in the SPCR, a write to the Serial Peripheral Data I/O Register (SPDR), located at memory location \$102A, initiates the transmission/reception of data. The data transfer is monitored and the appropriate flags are set in the Serial Peripheral Status Register (SPSR).

The SPSR configuration is shown below:

An example of 68HC11 programming code for a two-byte SPI transfer to the MAX536/MAX537 is given in Table 4. \overline{SS} is used for \overline{CS} , the high byte of MAX536/ MAX537 digital data is stored in memory location \$0100, and the low byte is stored in memory location \$0101.

Interfacing to Other Controllers

When using Microwire, refer to the section on Interfacing to the M68HC11 for guidance, since Microwire can be considered similar to SPI when CPOL $= 0$ and CPHA = 0. When interfacing to Intel's 80C51/80C31 microcontroller family, use bit-pushing to configure a desired port as the MAX536/MAX537 interface port. Bitpushing involves arbitrarily assigning I/O port bits as interface control lines, and then writing to the port each time a signal transition is required.

Unipolar Output

For a unipolar output, the output voltages and the reference inputs are the same polarity. Figure 10 shows the MAX536/MAX537 unipolar output circuit, which is also the typical operating circuit. Table 5 lists the unipolar output codes.

Bipolar Output

The MAX536/MAX537 outputs can be configured for bipolar operation using Figure 11's circuit. One op amp and two resistors are required per DAC. With $R1 = R2$:

$$
V_{OUT} = V_{REF} [(2N_B / 4096) - 1]
$$

where N_B is the numeric value of the DAC's binary input code. Table 6 shows digital codes and corresponding output voltages for Figure 11's circuit.

Table 5. Unipolar Code Table

MSB	DAC CONTENTS	LSB	ANALOG OUTPUT
	1111 1111 1111		+ VREF $(\frac{4095}{4096})$
1000	0000	0001	+ VREF $(\frac{2049}{4096})$
1000	0000	0000	+ VREF $\left(\frac{2048}{4096}\right) = \frac{+ \text{VREF}}{2}$
	0111 1111 1111		+ VREF $(\frac{2047}{4096})$
0000	0000	0001	+ VREF $(\frac{1}{4096})$
0000	0000	0000	0V

Table 6. Bipolar Code Table

NOTE: 1LSB = (V_{REF}) $(\frac{1}{4096})$

Figure 10. Unipolar Output Circuit Figure 11. Bipolar Output Circuit

Figure 12. AC Reference Input Circuit Figure 13. AGND Bias Circuit

$$
WIXIN
$$

MAX536/MAX537 MAX536/MAX537

Figure 14. When V_{SS} and V_{DD} cannot be sequenced, tie a Schottky diode between V_{SS} and AGND.

Using an AC Reference

In applications where the reference has AC signal components, the MAX536/MAX537 have multiplying capability within the reference input range specifications. Figure 12 shows a technique for applying a sine-wave signal to the reference input where the AC signal is offset before being applied to REFAB/REFCD. The reference voltage must never be more negative than DGND.

The MAX536's total harmonic distortion plus noise $(THD + N)$ is typically less than 0.012%, given a 5V_{p-p} signal swing and input frequencies up to 35kHz, or given a 2Vp-p swing and input frequencies up to 50kHz. The typical -3dB frequency is 700kHz as shown in the Typical Operating Characteristics graphs.

For the MAX537, with an input signal amplitude of 0.85 mV_{p-p}, THD + N is typically less than 0.024% with a 5kΩ load in parallel with 100pF and input frequencies up to 100kHz, or with a 2kΩ load in parallel with 100pF and input frequencies up to 95kHz.

Offsetting AGND

AGND can be biased from DGND to the reference voltage to provide an arbitrary nonzero output voltage for a zero input code (Figure 13). The output voltage VOUTA is:

$V_{\text{OUTA}} = V_{\text{BIAS}} + N_{\text{B}} (V_{\text{IN}})$

where VBIAS is the positive offset voltage (with respect to DGND) applied to AGND, and NB is the numeric value of the DAC's binary input code. Since AGND is common to all four DACs, all outputs will be offset by VBIAS in the same manner. As the voltage at AGND increases, the DAC's resolution decreases because its full-scale voltage swing is effectively reduced. AGND should not be biased more negative than DGND.

Pow er-Supply Considerations

On power-up, V_{SS} should come up first, V_{DD} next, then REFAB or REFCD. If supply sequencing is not possible, tie an external Schottky diode between V_{SS} and AGND as shown in Figure 14. On power-up, all input and DAC registers are cleared (set to zero code) and SDO is in Mode 0 (serial data is shifted out of SDO on the clock's rising edge).

For rated MAX536 performance, V_{DD} should be 4V higher than REFAB/REFCD and should be between 10.8V and 16.5V. When using the MAX537, V_{DD} should be at least 2.2V higher than REFAB/REFCD and should be between 4.75V and 5.5V. Bypass both V_{DD} and V_{SS} with a 4.7µF capacitor in parallel with a 0.1µF capacitor to AGND. Use short lead lengths and place the bypass capacitors as close to the supply pins as possible.

Grounding and Layout Considerations

Digital or AC transient signals between AGND and DGND can create noise at the analog outputs. Tie AGND and DGND together at the DAC, then tie this point to the highest quality ground available.

Good printed circuit board ground layout minimizes crosstalk between DAC outputs, reference inputs, and digital inputs. Reduce crosstalk by keeping analog lines away from digital lines. Wire-wrapped boards are not recommended.

_Ordering Information (continued)

* Contact factory for dice specifications.

** Contact factory for availability and processing to MIL-STD-883.

___________________Chip Topography

MAX536/MAX537

MAX536/MAX537

TRANSISTOR COUNT: 5034 SUBSTRATE CONNECTED TO V_{DD}

Package Information

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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