## **Features**

- **FM Double-conversion System**
- **Integrated Second IF Filter with Software-controlled Bandwidth**
- **Completely Integrated FM Demodulator**
- **Soft Mute and Multipath Noise Cancellation**
- **Receiving Condition Analyzer**
- **AM Up/Down-conversion System**
- **AM Preamplifier with AGC and Stereo Capability**
- **3-wire Bus Controlled**
- **Search Stop Signal Generation (AM and FM)**
- **Automatic Alignment Possible**
- **Pin Compatible with ATR4255**
- **World Tuner, US Weatherboard, J-band**
- **Lead-free Package**

Electrostatic sensitive device. Observe precautions for handling.



## **1. Description**

The ATR4258 is a highly integrated AM/FM front-end circuit manufactured using Atmel's advanced BICMOS technology. It represents a complete, automatically adjustable AM/FM front end, containing a double-conversion system for FM and an up/down-conversion receiver for AM with  $IF1 = 10.7$  MHz and  $IF2 = 450$  kHz. The front end is suitable for digital or analog AF-signal processing. Together with the PLL U4256BM, an automatically aligned high-performance AM/FM tuner can be built. These ICs are dedicated for highly sophisticated car radio applications.





**AM/FM Receiver IC**

## **ATR4258**

Rev. 4838B–AUDR–05/05





### **Figure 1-1.** Block Diagram



 **2**

## **2. Pin Configuration**

**Figure 2-1.** Pinning SSO44





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# **ATR4258**





## **3. Pin Description**

 **4**

## **4. Functional Description**

The ATR4258 implements an AM up/down-conversion reception path from the RF input signal to the AM-demodulated audio frequency output signal, and for FM/WB reception a double-conversion reception path from the RF input signal to the FM-demodulated multiplex signal (MPX). A VCO and an LO prescaler for AM are integrated to generate the LO frequency for the  $1<sup>st</sup>$  mixer. Automatic gain control (AGC) circuits are implemented to control the preamplifier and IF stages in the AM and FM reception path.

For improved FM performance, an integrated IF filter with adjustable bandwidth, a softmute feature and an automatic multipath noise cancellation (MNC) circuit are fully integrated. A powerful set of sensors is provided for receiving condition analysis and stop signal generation.

Several register bits (bit 0 to bit 93) are used to control circuit operation and to adapt certain circuit parameters to the specific application. The control bits are organized in two 8-bit and three 24-bit registers that can be programmed by the 3-wire bus protocol. The bus protocol and the bit-to-register mapping is described in the section ["3-wire Bus Description" on page 20](#page-19-0). The meaning of the control bits is mentioned in the following sections.

The integrated VCO has a high frequency range. Additionally the VCO has a special VCO divider which allows (in connection with the VCO) the reception of all analog world bands.

### **4.1 Reception Mode**

The IC can be operated in four different modes. Mode AM, FM, WB, and Standby are selected by means of bit 92 and bit 93 according to [Table 4-1 on page 6](#page-5-0).

Additionally to the operating modes, the signal paths can be set separately. Bit 62 selects the first mixer and AGC, bit 63 selects the  $1<sup>st</sup>$  amplifier stage. The recommended settings of bit 62 and bit 63 are included in [Table 4-1 on page 6](#page-5-0).

In AM mode the AM mixer, the AM RF-AGC and the  $1<sup>st</sup>$  IF AM amplifier at pin 33 are activated. The input of the  $2^{nd}$  IF amplifier is connected to pin 28 and the output of the  $2^{nd}$  IF amplifier is fed to the AM demodulator. The output of the AM demodulator is available at MPX output pin 11.

In FM mode the FM mixer, the FM RF-AGC and the  $1<sup>st</sup>$  IF FM amplifier at pin 38 are activated. The bandwidth of the output tank at pin 23, pin 24 is increased and the input of the  $2<sup>nd</sup>$  IF amplifier can be switched between pin 23 and pin 24 and pin 28. The output of the  $2<sup>nd</sup>$  IF amplifier is fed to the integrated band filter and FM demodulator. The output of the FM demodulator is available at MPX output pin 11.

The WB mode is similar to the FM mode, but to reduce the bandwidth the AM IF amplifier with the AM filter (bit  $63 = 1$ ) can be used. In WB mode the range of the integrated filter bandwidth control is shifted to lower bandwidth and the gain of the FM demodulator is increased.

In standby mode the mixers, IF amplifiers and AGC circuits are deactivated to reduce current consumption.





### <span id="page-5-0"></span>**Table 4-1.** Operating Mode



### **4.2 Test Mode**

A special test mode is implemented for final production test only. This mode is activated by setting bit 9 = 1. **This mode is not intended to be used in customer applications.** For normal operation, bit 9 has to be set to 0. Bit 22 to bit 30 are deactivated in normal operation mode.





### **4.3 VCO/Local Oscillator Prescaler**

An oscillator circuit is implemented to build a VCO as proposed in the application schematic. The VCO frequency is used to generate the LO frequency of the 1<sup>st</sup> mixer stages. The control voltage of the VCO is usually generated by the PLL circuit U4256BM. The VCO frequency has a range of 70 MHZ to 250 MHz to allow the reception of all analog world bands.

A main element of the implemented oscillator circuit is a bipolar NPN transistor. The internally biased base is connected to pin 13 and the emitter to pin 14. An AGC circuit (bit 30) can be activated to increase the emitter current until the appropriate oscillation level is reached. The fundamental emitter current can be changed by bit 52.

**Table 4-3.** Local Oscillator AGC

Local Oscillator (VCO)	<b>Bit 30</b>
AGC off (default)	
AGC on	

### **Table 4-4.** Local Oscillator Gain



In addition (to the AM prescaler) a special VCO prescaler is implemented for all modes (AM, WB and FM). The divider factor of the prescaler buffer provides the signal of the buffered output (at pin 16) and the prescaler VCO provides the signal of the  $1<sup>st</sup> FM$  mixer stage and AM prescaler. Examples of VCO prescaler settings are described in section ["Application Information" on page](#page-28-0)  [29.](#page-28-0) The divider factor of the VCO and buffer prescaler can be selected according [Table 4-5 on](#page-6-0)  [page 7](#page-6-0).

 **6**

<b>Prescaler VCO</b>	<b>Prescaler Buffer</b>	<b>Bit 12</b>	<b>Bit 11</b>	<b>Bit 10</b>
1.5				
۱.5	l .5			

<span id="page-6-0"></span>**Table 4-5.** Local Oscillator Prescaler (VCO/Buffer Divider)

Note: The U4256 FMOSCIN (pin 19) input frequency is limited to 160 MHz.

### **4.4 FM RF-AGC**

The FM RF-AGC circuit includes a wide-band level detector at the input pin 1 of the FM mixer and an in-band level detector at the output of the FM IF amplifier (pin 30). The outputs of these level detectors are used to control the current into the pin diode (see [Figure 4-1\)](#page-6-1) in order to limit the signal level at the FM mixer input and the following stages. The maximum pin diode current is determined by R115 and the time constant of the AGC control loop can be adjusted by changing the value of C111.

The AGC threshold level at the input of the FM mixer can be adjusted by bit 64 and bit 65 according to [Table 4-6](#page-6-2). The in-band AGC threshold refers to the FM mixer input (pin 1, pin 2) depends on the gain of the FM IF amplifier and can be adjusted by bit 89 to bit 91.

<b>FM-AGC Threshold</b>	<b>Bit 65</b>	<b>Bit 64</b>
$100$ dB $\mu$ V	u	
97 dBµV	u	
94 dBµV		
91 $dB\mu V$		

<span id="page-6-2"></span>**Table 4-6.** FM-AGC Threshold

<span id="page-6-1"></span>







### **4.5 AM RF-AGC**

The AM RF-AGC controls the current into the AM pin diodes (pin 7) and the source drain voltage of the MOSFET in the AM preamplifier stage (pin 6) to limit the level at the AM mixer input (pin 3, pin 41). This threshold level can be set by bit 64 and bit 65. If the level at the AM mixer input exceeds the selected threshold, the current into the AM pin diodes is increased. If this step is not sufficient, the source drain voltage of the MOSFET is decreased. The time constant of the AGC control loop can be adjusted by changing the value of the capacitor at pin 8.

### **Table 4-7.** AM-AGC Threshold



### **4.6 FM 1st Mixer**

In the  $1<sup>st</sup>$  FM mixer stage, the FM reception frequency is down converted to the  $1<sup>st</sup>$  IF frequency. The VCO frequency is used as LO frequency for the mixer.

### **4.7 AM 1st Mixer**

The AM 1<sup>st</sup> mixer is used for up-conversion of the AM reception frequency to the 1<sup>st</sup> IF frequency. Therefore, an AM prescaler is implemented to generate the necessary LO frequency from the VCO frequency. The divide factor of the AM prescaler can be selected according to [Table 4-8.](#page-7-0) (The AM prescaler is only active in AM mode).

<b>Divider (AM Prescaler)</b>	<b>Bit 93</b>	<b>Bit 92</b>	<b>Bit 84</b>	<b>Bit 83</b>	<b>Bit 82</b>	<b>Bit 81</b>
Divide by 2		0	0	0		0
Divide by 3		0	0	$\Omega$	0	
Divide by 4		$\Omega$	0	0		O
Divide by 5		0	0	0		
Divide by 6		0	0		0	Ω
Divide by 7		$\Omega$	0		0	
Divide by 8		$\Omega$	0			0
Divide by 9		0	0			
Divide by 10		$\Omega$		X	X	X

<span id="page-7-0"></span>**Table 4-8.** Divide Factor of the AM Prescaler

 **8**

## **4.8 FM 1st IF Amplifier**

A programmable gain amplifier is used in FM (and WB) mode between pin 38 and pin 30 to compensate the loss in the external ceramic band filters. The gain of this amplifier is adjusted by bit 89 to bit 91. The input and the output resistance is 330Ω and fits to external ceramic filters.

Two different temperature coefficients of the FM IF amplifier can be selected by bit 66.

<b>Gain FM IF</b>	<b>Bit 91</b>	<b>Bit 90</b>	<b>Bit 89</b>
19dB			
21 dB			
23 dB			
25 dB			
27 dB			
28 dB			
29 dB			
30 dB			

**Table 4-9.** Gain of the FM IF Amplifier

**Table 4-10.** Temperature Coefficient Setting of FM IF Amplifier



### **4.9 AM 1st IF Amplifier**

In AM and WB mode, the gain of the  $1<sup>st</sup>$  IF amplifier is controlled by the IF-AGC to extend the control range of the IF-AGC.

### **4.10 2nd Mixer**

The  $2^{nd}$  mixer is used in AM, FM and WB mode. The mixer input has 330 $\Omega$  input resistance and can be connected directly to an external ceramic filter.

In FM mode, the high output resistance of the second mixer is reduced to increase the bandwidth of the tank at the mixer output. The output resistance can be selected by bit 60 and bit 61.

In AM and WB mode bit 61 and bit 62 should be set to 0.





The LO frequency of the  $2^{nd}$  mixer (10.25 MHz) has to be applied at pin 22. This signal is usually generated by the PLL circuit U4256BM.





**Table 4-12.** FM Bandwidth Mixer 2



Note: The bandwidth is also dependant on the values of the application circuit.

### **4.11 2nd IF Amplifier**

In AM and WB mode, the input of the second IF amplifier is pin 28, is externally connected to the 2<sup>nd</sup> mixer tank through the AM ceramic filter to achieve channel selectivity. During normal FM operation (bit  $54 = 0$ ), the input of the second IF amplifier is connected to the  $2^{nd}$  mixer output (pin 23, pin 24) and the integrated FM band filter is used for channel selectivity only. It is possible to use an additional external filter between the  $2<sup>nd</sup>$  mixer tank and pin 28 in FM mode by setting bit 54 to 1.

Table 4-13. 2<sup>nd</sup> IF Filter in FM Mode

2nd IF Filter	<b>Bit 54</b>
Internal filter	
External and internal filter	

### **4.12 IF-AGC**

The IF-AGC controls the level of the 2<sup>nd</sup> IF signal that is passed to the AM demodulator input or the integrated FM band filter and to the  $2^{nd}$  IF output, pin 20.

Two different time constants of the IF-AGC can be selected by the capacitors at pin 35 (IFAGCH) and pin 36 (IFAGCL). The short time constant (IFAGCL) is used in FM/WB mode and in AM search mode. The long time constant (IFAGCH) is used for AM reception.

**Table 4-14.** IF-AGC Time Constant

Mode	<b>Bit 92</b>	<b>Bit 88</b>	<b>IF AGC Time Constant</b>
FM/WB			IFAGCL (fast)
AM reception			IFAGCH (slow)
AM search			IFAGCL (fast)

In FM/WB mode, the output signal of the FM demodulator is applied to pin 35 via a series resistor of about 95 kΩ. This low-pass filtered output signal of the FM demodulator is used for the FM demodulator fine adjustment, for muting and as a reference for the deviation sensor.

## **4.13 2nd IF Output**

The 2<sup>nd</sup> IF after the gain-controlled 2<sup>nd</sup> IF amplifier is available at pin 20 (bit 55 = 0). In AM mode, this signal may be used for an external AM stereo decoder. Alternatively, a signal corresponding to the logarithmic field strength after the integrated FM band filter, which is used for multipath detection, can be switched to pin 20 by setting bit  $55 = 1$ .

### **Table 4-15.** Pin 20 Output Setting



### **4.14 Automatic IF Center Frequency Adjustment**

Integrated active filters are used in the FM band filter, FM demodulator and adjacent channel sensor. The center frequency of these filters is automatically adjusted to the second IF frequency of 450 kHz. The frequency of 10.25 MHz at pin 22 is used as a reference for this alignment.





For fine tuning, the center frequency of all these integrated active filters (band filter and demodulator) can be shifted in steps of 6.25 kHz by means of bit 56 to bit 59. Additionally, the center frequency of the band filter can be adjusted separately by means of bit 14 to bit 17.





<b>IF Center</b>	<b>Bit 59</b>	<b>Bit 58</b>	<b>Bit 57</b>	<b>Bit 56</b>
450.00 kHz	0	0	0	0
456.25 kHz	$\Omega$	0	$\Omega$	
462.50 kHz	$\Omega$	$\mathbf 0$		0
468.75 kHz	$\Omega$	$\Omega$		1
475.00 kHz	$\Omega$	1	$\Omega$	$\Omega$
481.25 kHz	$\Omega$		$\Omega$	
487.50 kHz	$\Omega$			0
493.75 kHz	$\Omega$	1		
450.00 kHz		$\mathbf 0$	$\Omega$	$\Omega$
443.75 kHz		$\Omega$	$\Omega$	
437.50 kHz		$\Omega$		O
431.25 kHz		$\mathbf 0$		
425.00 kHz			0	0
418.75 kHz		1	$\Omega$	
412.50 kHz		1		0
406.25 kHz				

Table 4-16. 2<sup>nd</sup> IF Center Frequency

### **Table 4-17.** FM Band Filter Center Frequency Correction



### **4.15 Integrated FM Band Filter**

For FM reception a band filter with variable bandwidth is integrated in front of the demodulator to provide channel selectivity on the 2<sup>nd</sup> IF. The bandwidth of this filter can be adjusted by bit 0 to 3 (see [Table 4-18\)](#page-12-0) to be suitable for the present receiving condition. In WB mode, the bandwidth of the integrated filter is shifted to lower bandwidth values, while the necessary channel selectivity is achieved by an external ceramic filter.

The center frequency of the integrated FM band filter can be adjusted by means of bit 14 to 17. The field strength after the integrated FM band filter that is available at pin 20 (bit  $55 = 1$ ) can be used for this purpose.

	IF Bandwidth FM (kHz) IF Bandwidth WB (kHz)	Bit 3	Bit 2	Bit 1	Bit 0
220	195	$\Omega$	0	0	0
$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$
200	160	$\Omega$	0	1	
$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$
165	120	0		1	0
$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$
130	80		0	0	
$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$	$\cdots$
90	45			0	0
80	Not usable			$\Omega$	
70	Not usable			1	0
60	Not usable				

<span id="page-12-0"></span>**Table 4-18.** Bandwidth of the Integrated Band Filter

### **4.16 FM Demodulator**

For weather band reception, the gain of the FM demodulator is increased and can be adjusted by means of bit 71 and bit 72 in order to increase the output voltage to compensate the low frequency deviation in weather band.

An integrated demodulator fine adjustment allows automatic fine tuning of the demodulator center frequency to the average frequency of the received signal. This feature is implemented for use in weather band mode and can be activated by setting bit 53 to 0.

### **Figure 4-3.** FM Demodulator Automatic Fine Tuning







The center frequency of the FM demodulator can be adjusted by means of bit 56 to 59. At the center frequency, the DC voltage at the MPX output pin 11 is equal to the MPX offset voltage that can be measured at pin 11 while MPX mute is active (bit  $7 = 1$ ). This adjustment will affect the center frequency of all integrated filters as mentioned before.



### **Table 4-19.** Demodulator Gain in Weather Band Mode





### **4.17 Soft Mute**

The soft mute functionality is implemented to reduce the output level of the FM demodulator at low input signal levels to limit the noise at the MPX output in this case. If the input level falls below an adjustable threshold continuously, the output of the FM demodulator is continuously muted with decreasing input level until a maximum mute value is reached. The threshold for the start of soft mute and the maximum mute can be adjusted. The signal level for 3 dB mute can be set by means of bit 68 to bit 70 and the maximum value for soft mute can be selected by bit 67. The steepness and the time constant of the soft mute can be adjusted by the resistor and capacitor between pin 34 and pin 29.

The field strength signal available at pin 9 is used for soft mute. Therefore, the soft mute threshold that referred to the input of the FM mixer depends on the gain from the FM mixer input to the field strength sensor and on the setting of field strength offset (bit 15 to bit 21).

<b>Relative Soft Mute Threshold</b>	<b>Bit 70</b>	<b>Bit 69</b>	<b>Bit 68</b>
Soft mute OFF	υ		
$-18$ dB			
$-15$ dB			
$-12$ dB			
$-9$ dB			
$-6$ dB			
$-3$ dB			
0 dB			

**Table 4-21.** Soft Mute Threshold

## **ATR4258**

### **Table 4-22.** Maximum Soft Mute



**Figure 4-4.** Soft Mute



### **4.18 MPX Output**

The output of the AM demodulator (AM mode) or the output of the FM demodulator (FM/WB mode) are available at the MPX output (pin 11).

The MPX output signal can be muted by setting bit 7 to 1.

The bandwidth of the low-pass filter at the MPX output can be set by means of bit 79 to 90 kHz or 180 kHz.

**Table 4-23.** MPX Output Mute

<b>MPX Output</b>	Bit 7
MPX out, pin 11 normal operation	
Mute ON	

**Table 4-24.** MPX Output Bandwidth



### **4.19 Receiving Condition Analyzer**

The ATR4258 implements several sensors that provide information about the receiving condition of the selected station.





### **4.20 Field Strength Sensor**

The field strength sensor provides a DC voltage at pin 9 which represents the logarithmic field strength of the signal in the reception band.

The field strength information can be retrieved either from a level detector at the input of the 2<sup>nd</sup> mixer (pin 26) or from the IF-AGC depending on the setting of bit 80. The bandwidth of the field strength detection in the AGC is smaller than by using the level detector because of additional selectivity between the  $2^{nd}$  mixer and the  $2^{nd}$  IF amplifier particularly in AM and WB, but the field strength detection in the AGC is limited to the IF AGC range. Usually the field strength from the level detector is used in FM/WB mode and the AGC field strength is used in AM mode.

The field strength output at pin 9 can be adjusted by the bits 18 to 21 in 0.5 dB steps. This offset also has an influence on the soft mute levels.





### **4.21 Field Strength Selection**

Bit 80 and bit 13 allows the switches between narrow-band field strength and wide-band field strength information.





### **4.22 Search Stop Detector**

A search stop detector is available in AM and FM/WB mode. A STOP condition is signaled (with a low level at pin 21) if the frequency of the IF signal is within a window around the center frequency of 450 kHz. The width of this search stop window can be set by bit 85 to bit 87 in the range of 0.5 kHz to 80 kHz. The frequency of the IF signal is measured by counting the number of periods of the IF signal during a measurement time which is determined by bit 73 to bit 78. The inverted STOP signal is available at pin 21 according to [Table 4-29 on page 17](#page-16-0). The frequency of 10.25 MHz at pin 22 is used as a time reference.



### **Table 4-27.** Search Stop Detector Measurement Time

### **Table 4-28.** Search Stop Window

<b>Search Stop Window</b>	<b>Bit 87</b>	<b>Bit 86</b>	<b>Bit 85</b>
$\pm 0.5$ kHz	0		
$±1.1$ kHz	0		
$\pm 2.3$ kHz	0		
$±4.8$ kHz	0		
$±10$ kHz			
$±20$ kHz			
$±40$ kHz			
$±80$ kHz			

<span id="page-16-0"></span>**Table 4-29.** Signals Available at Digital Output Pin 21



Note: MPINT = Multipath interrupt, Stop and MPINT signal are active low

Pin 35 (IFAGCH) is carried along with pin 36 (IFAGCL) to avoid crackles during a change of the search stop mode to the AM reception mode.

### **4.23 Deviation Sensor**

The deviation sensor is active in AM and FM/WB mode and measures the modulation of the signal. It is implemented as a peak detector of the low-pass-filtered MPX signal (see [Figure 4-5](#page-16-1)). The output voltage at pin 31 is proportional to the frequency deviation in FM/WB or the modulation depth in AM respectively.

<span id="page-16-1"></span>**Figure 4-5.** Deviation Sensor







### **4.24 Adjacent Channel Sensor**

The adjacent channel sensor is active in FM mode only and measures the field strength outside the reception band.





### **4.25 MPINT and ADJAC Reset**

Bit 6 allows a resets of the multipath sensor and the adjacent channel sensor by connecting pin 10 and pin 40 internally to ground and so the external capacitors can be discharged very quickly.





### **4.26 Multipath Sensor**

The multipath sensor is active in FM mode only and measures the disturbance due to multipath reception. The multipath sensor detects drops in the field strength after the integrated band filter by calculating the difference between an averaged maximum field strength and the current field strength. The maximum depth of these drops is represented by the voltage of the peak detector at pin 40 (MULTIP). The level of this voltage represents the degree of disturbance in the received signal.

**Figure 4-7.** Multipath Sensor



## **ATR4258**

A Multipath Noise Canceller (MNC) is implemented to reduce disturbance of the received signal in multipath reception conditions. If the difference between the momentary and the averaged field strength falls below a threshold adjustable by bit 81 to 84 (see [Table 4-32](#page-18-0)), the MPX signal may be muted and this situation (MPINT) can be signalized at pin 21 (INT) according to [Table 4-](#page-16-0) [29 on page 17.](#page-16-0) Muting of the MPX signal during multipath disturbances can be activated be setting bit 8.

### **Table 4-31.** Multipath Noise Canceller



### <span id="page-18-0"></span>**Table 4-32.** Sensitivity of the MNC



Note: Valid in FM or WB mode (bit 92 = 1)

The Multipath interrupt can also be switched on/off by bit 4.

### **Table 4-33.** Multipath Interrupt (MPINT)







### **4.27 AM Noise Blanker**

The AM Noise Blanker of the ATR4258 can be activated by bit 5. The noise peak is detected in the field strength of the first IF and if the disturbance exceeds the level defined by the bits 85 to 87, the signal is muted at the second IF.

**Table 4-34.** AM Noise Blanker Activation

<b>AM Noise Blanker</b>	Bit 5
Off	
On	

**Table 4-35.** Sensitivity of AM Noise Blanker



### <span id="page-19-0"></span>**4.28 3-wire Bus Description**

The register settings of the ATR4258 are programmed by a 3-wire bus protocol. The bus protocol consists of separate commands. A defined number of bits are transmitted sequentially during each command.

One command is used to program all bits of one register. The different registers available (see [Table 4-36 on page 22\)](#page-21-0) are addressed by the length of the command (number of transmitted bits) and by three address bits that are unique for each register of a given length. 8-bit registers are programmed by 8-bit commands and 24-bit registers are programmed by 24-bit commands.

Each bus command starts with a rising edge on the enable line (EN) and ends with a falling edge on EN. EN has to be kept HIGH during the bus command.

The sequence of transmitted bits during one command starts with the LSB of the first byte and ends with the MSB of the last byte of the register addressed. The DATA is evaluated at the rising edges of CLK. The number of LOW to HIGH transitions on CLK during the HIGH period of EN is used to determine the length of the command.

The bus protocol and the register addressing of the ATR4258 are compatible to the addressing used in the U4256BM. That means both the ATR4258 and U4256BM can be operated on the same 3-wire bus as shown in the application circuit ([Figure 10-9 on page 36\)](#page-35-0).

### **Figure 4-8.** Pulse Diagram











## **4.29 Data Transfer**

<span id="page-21-0"></span>











## **5. Absolute Maximum Ratings**

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. All voltages are referred to GND (pin 25)



## **6. Thermal Resistance**



## **7. Operating Range**

All voltages are referred to GND (pin 25)



## **8. Electrical Characteristics**

Test conditions (unless otherwise specified):  $\mathsf{V}_\mathsf{S}$  = 8.5V, T $_{\mathsf{amb}}$  = 25°C



 $*$ ) Type means: A =100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter









\*) Type means: A =100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

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Test conditions (unless otherwise specified):  $\mathsf{V}_\mathsf{S}$  = 8.5V,  $\mathsf{T}_{\mathsf{amb}}$  = 25°C

\*) Type means: A =100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter





Test conditions (unless otherwise specified):  $\mathsf{V}_\mathsf{S}$  = 8.5V, T $_{\mathsf{amb}}$  = 25°C



\*) Type means: A =100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

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Test conditions (unless otherwise specified):  $\mathsf{V}_\mathsf{S}$  = 8.5V,  $\mathsf{T}_{\mathsf{amb}}$  = 25°C

\*) Type means: A =100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter





Test conditions (unless otherwise specified):  $\mathsf{V}_\mathsf{S}$  = 8.5V, T $_{\mathsf{amb}}$  = 25°C



\*) Type means: A =100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

## <span id="page-28-0"></span>**9. Application Information**

### **9.1 AM Prescaler (Divider) Settings**

The AM mixer is used for up conversion of the AM reception frequency to the IF frequency. Therefore an AM prescaler is implemented to generate the necessary LO from the VCO frequency. For the reception of the AM band different prescaler (divider) settings are possible.

[Table 9-1](#page-28-1) gives an example for the AM prescaler (divider) settings and the reception frequencies.

e.g.,

 $f_{VCO}$  = 98.2 MHz ... 124 MHz f<sub>IF</sub> = 10.7 MHz

$$
f_{rec} = \left(\frac{f_{VCO}}{\text{AM Prescale}}\right) - f_{IF}
$$



<span id="page-28-1"></span>

Note: Prescaler VCO Divider = 1 in this example.





### **9.2 Local Oscillator and AM Prescaler Settings**

[Table 9-2](#page-29-0) gives an example for the VCO prescaler divider and AM prescaler divider settings and the reception frequencies.

e.g.,

 $f_{VCO}$  = 195.9 MHz ... 237.9 MHz f IF = +10.7 MHz or –10.7 MHz  $f_{VCO} = (f_{rec} + f_{IF}) \times VCO$  Prescaler  $\times$  AM Prescaler

<span id="page-29-0"></span>



### **9.3 U4256 N- and R-divider Calculation**

### **9.3.1 AM Mode**

$$
N = \frac{f_{VCO}}{VCO \text{-divider} \times \text{AM Prescalar} \times f_{step}}
$$

$$
f_{rec} = \left(\frac{f_{VCO}}{VCO \text{-divider} \times AM \, Prescaler}\right) - f_{IF}
$$

### **9.3.2 FM/WB Mode**

$$
N = \frac{f_{VCO}}{VCO\text{-divider} \times f_{step}}
$$

$$
f_{\text{rec}} = \left(\frac{f_{\text{VCO}}}{\text{VCO-divider}}\right) - f_{\text{IF}}
$$

### **9.3.3 All Modes**

$$
R = \frac{f_{ref}}{f_{step}}
$$

f ref = reference oscillator frequency (e.g. 10.25 MHz)

 $f_{VCO}$  = VCO frequency

f rec = reception frequency

 $f_{\text{step}}$  = step frequency (of the PLL)

### **10. Diagrams**

The following data was measured with the application board (see [Figure 10-9\)](#page-35-0).

In the measurement setup, a 50 $\Omega$  generator is terminated by 50 $\Omega$  and connected to the antenna input by a 50 $\Omega$  series resistor to achieve 75 $\Omega$  termination at the antenna input. The generator level specified is the output voltage of this 50Ω generator at 50Ω load. If the application board is replaced by a 75 $\Omega$  resistor, the voltage at this resistor is 6 dB below the specified voltage level of the 50 $\Omega$  generator.





Note: Integrated band-filter BW setting: 120 kHz (bits 0 to  $2 = 0$ , bit  $3 = 1$ ); 1 kHz modulation frequency; 50 µs de-emphasis (THD)





**Figure 10-2.** Multipath Sensor



Note: AM modulation frequency 20 kHz; generator level 40 dBµV

**Figure 10-3.** Multipath Sensor Frequency Response



Note: Generator level 40 dBµV

**Figure 10-4.** Deviation Sensor



Note: FM modulation frequency: 1 kHz; BW setting 2<sup>nd</sup> IF filter = 120 kHz; demodulator fine tuning (bit  $53 = 0$ )

The center frequency of the integrated band filter has to adjusted  $(e.g., IF center frequency = 462.50 kHz).$ 

**Figure 10-5.** Deviation Sensor Frequency Response







**Figure 10-6.** FM Input Level Sweep



Note: Soft mute threshold bits  $68$ ,  $69 = 0$ , bit  $70 = 1$ ; soft mute gain bit  $67 = 0$ gain FM IF amplifier bit 89 to  $91 = 1$ 





Note: Integrated bandfilter BW setting: 120 kHz Desired signal level adjusted to 40 dB S/N without undesired signal Undesired signal level adjusted to 26 dB S/N

**Figure 10-8.** Test Circuit



Test Point





MPX ADJAC METER



<span id="page-35-0"></span>

R407 VS

 $\frac{1}{2}$ 

(+8.5V to 10.5V) MULTIP P<sub>DEV</sub>

**ATR4258** 





비리<br>IF2O대<br>IF2OK<br>INTER SE

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## **11. Ordering Information**



## **12. Package Information**







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