

# Low Cost DDR Phase Lock Loop Zero Delay Buffer

93722

### Description

DDR Zero Delay Clock Buffer

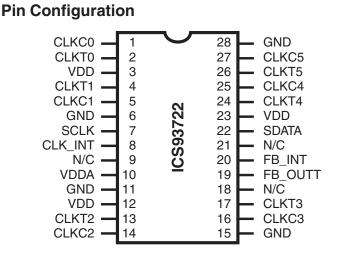
#### **Output Features**

- Low skew, low jitter PLL clock driver
- I<sup>2</sup>C for functional and output control
- Feedback pins for input to output synchronization
- Spread Spectrum tolerant inputs
- 3.3V tolerant CLK\_INT input

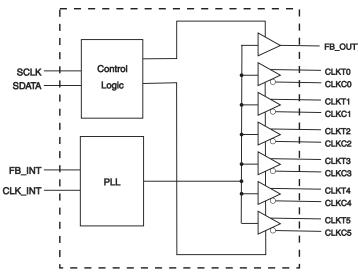
## **Key Specifications**

- PEAK PEAK jitter (66MHz): <120ps
- PEAK PEAK jitter (>100MHz): <75ps</li>
- CYCLE CYCLE jitter (66MHz):<110ps</li>
- CYCLE CYCLE jitter (>100MHz):<65ps
- OUTPUT OUTPUT skew: <100ps
- Output Rise and Fall Time: 650ps 950ps
- DUTY CYCLE: 49.5% 50.5%

Functional Block Diagram



#### 28-Pin SSOP



#### **Functionality Table**

	IN	INPUTS		OUTPUT	PLL State	
	AVDD	CLK_INT	CLKT	CLKC	FB_OUT	PLL State
лт	2.5V (nom)	L	L	н	L	on
)	2.5V (nom)	Н	Н	L	Н	on
	2.5V (nom)	<20MHz	Z	Z	Z	off
	GND	L	L	Н	L	Bypassed/off
2	GND	Н	Н	L	Н	Bypassed/off

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## **Pin Description**

PIN NUMBER	PIN NAME	ТҮРЕ	DESCRIPTION	
6, 11, 15, 28	GND	PWR	Ground	
27, 25, 16, 14, 5, 1	CLKC(5:0)	OUT	"Complementary" clocks of differential pair outputs.	
26, 24, 17, 13, 4, 2	CLKT(5:0)	OUT	"True" Clock of differential pair outputs.	
3, 12, 23	VDD	PWR	Power supply 2.5V	
7	SCLK	IN	Clock input of I <sup>2</sup> C input, 5V tolerant input	
8	CLK_INT	IN	"True" reference clock input	
9, 18, 21	N/C	-	Not connected	
10	VDDA	PWR	Analog power supply, 2.5V	
19 ·	FB_OUTT	OUT	"True" Feedback output, dedicated for external feedback. It switches at the same frequency as the CLK. This output must be wired to FB_INT.	
20	FB_INT	IN	"True" Feedback input, provides feedback signal to the internal PLL for synchronization with CLK_INT to eliminate phase error.	
22	SDATA	IN	Data input for I <sup>2</sup> C serial input, 5V tolerant input	

Bytes 0 to 4 are reserved power up default = 1.

Byte 5: Output Control (1= enable, 0 = disable)

Bit	PIN#	PWD	DESCRIPTION
Bit7	2, 1	1	CLK0 (T&C)
Bit6	4, 5	1	CLK1 (T&C)
Bit5		1	Reserved
Bit4		1	Reserved
Bit3	13, 14	1	CLK2 (T&C)
Bit2	17, 16	1	CLK3 (T&C)
Bit1		1	Reserved
Bit0		1	Reserved

Note: PWD = Power Up Default

# Byte 6: Output Control (1= enable, 0 = disable)

Bit	PIN#	PWD	DESCRIPTION
Bit7		1	Reserved
Bit6		1	Reserved
Bit5		1	Reserved
Bit4		1	Reserved
Bit3	24, 25	1	CLK4 (T&C)
Bit2		1	Reserved
Bit1	26, 27	1	CLK5 (T&C)
Bit0		1	Reserved

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### **Absolute Max**

Supply Voltage (VDD & AVDD)	-0.5V to 3.6V
Logic Inputs	GND –0.5 V to $V_{DD}$ +0.5 V
Ambient Operating Temperature	0°C to +85°C
Case Temperature	115°C
Storage Temperature	–65°C to +150°C

Stresses above those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These ratings are stress specifications only and functional operation of the device at these or any other conditions above those listed in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

## Electrical Characteristics - Input / Supply / Common Output Parameters

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input High Current	I <sub>IH</sub>	$V_{IN} = V_{DD}$ or GND		1	10	μA
Input Low Current	I <sub>IL</sub>	$V_{IN} = V_{DD}$ or GND	-100	-20		μA
Operating Supply Current	I <sub>DD2.5</sub>	C∟ = 0 pF at 133 MHz		275	325	mA
Operating Supply Current	IDDPD	$C_L = 0 \text{ pF}$			100	μA
Output High Current	I <sub>он</sub>	$V_{DD} = 2.3V, V_{OUT} = 1V$		-43	-18	mA
Output High Current	I <sub>OL</sub>	$V_{DD} = 2.3V, V_{OUT} = 1.2V$	26	43		mA
High Impedance Output Current	l <sub>oz</sub>	$V_{DD} = 2.7V, V_{OUT} = V_{DD} \text{ or } GND$			10	μA
Input Clamp Voltage	V <sub>IK</sub>	l <sub>IN</sub> = -18 mA;				V
Lligh Joyal Output Valtage	V	$V_{DD}$ = min to max, $I_{OH}$ = -1 mA	2.1	2.42		V
High-level Output Voltage	V <sub>OH</sub>	$V_{DD} = 2.3V, I_{OH} = -12mA$		1.87		V
Low lovel Output Valtage	V <sub>OL</sub>	$V_{DD}$ = min to max, $I_{OH}$ = 1mA		0.04	0.1	V
Low-level Output Voltage		$V_{DD} = 2.3V, I_{OH} = 12mA$		0.35	0.6	V
Input Capacitance <sup>1</sup>	C <sub>IN</sub>	$V_{IN} = V_{DD}$ or GND		2		pF
Output Capacitance <sup>1</sup>	C <sub>OUT</sub>	$V_{OUT} = V_{DD}$ or GND		3		pF

 $T_A = 0 - 70^{\circ}$ C; Supply Voltage  $V_{DD} = 2.5 V + -0.2 V$  (unless otherwise stated)

1. Guaranteed by design, not 100% tested in production.

## Recommended Operating Condition (see note 1)

 $T_A = 0 - 70^{\circ}C$ ; Supply Voltage AV<sub>DD</sub>,  $V_{DD} = 2.5 V + -0.2V$  (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Analog / Core Supply Voltage	$V_{DD}, AV_{DD}$		2.3	2.5	2.7	V
Input Valtaga Laval	V <sub>IL</sub>				V <sub>DD</sub> /2 - 0.5V	V
Input Voltage Level	V <sub>IH</sub>		$V_{DD}/2 + 0.5V$			V
Inpu Duty Cycle	I <sub>DC</sub>		40		60	
Input max jitter	I <sub>TCYC</sub>				500	ps

## **Timing Requirements**

 $T_A = 0 - 70^{\circ}C$ ; Supply Voltage AV<sub>DD</sub>,  $V_{DD} = 2.5 V + -0.2V$  (unless otherwise stated)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Operating Clock Frequency <sup>1</sup>	freq <sub>op</sub>		66		200	MHz
Input Clock Duty Cycle <sup>1</sup>	d <sub>tin</sub>		40		60	%
Clock Stabilization <sup>1</sup>	t <sub>STAB</sub>	from V <sub>DD</sub> = 2.5V to 1% target frequency			100	s

1. Guaranteed by design, not 100% tested in production.

### **Switching Characteristics**

 $T_A = 0 - 70^{\circ}C$ ; Supply Voltage  $V_{DD} = 2.5 V + -0.2V$  (unless otherwise stated)

PARAMETER	SYMBOL	IBOL CONDITIONS		TYP	MAX	UNITS
Absolute Jitter <sup>1</sup>	T <sub>jabs</sub>	66 MHz			120	00
Adsolute Jitter	' jabs	100 - 200 MHz			75	ps
Ovele to evele litter <sup>1,2</sup>	т	66 MHz		50	110	20
Cycle to cycle Jitter <sup>1,2</sup>	T <sub>cyc-cyc</sub>	100 - 200 MHz		25	65	ps
Phase Error <sup>1</sup>	t <sub>(phase error)</sub>	CLK_INT to FB_INT	-150	50	150	ps
Output to output Skew <sup>1</sup>	T <sub>skew</sub>	V <sub>T</sub> = 50%		70	100	ps
Pulse Skew <sup>1</sup>	T <sub>skewp</sub>				100	ps
Duty Ovela (differential) <sup>1,3</sup>	D	$V_{T} = 50\%$ , 66 MHz to 100 MHz	49.5	50	50.5	%
Duty Cycle (differential) <sup>1,3</sup>	D <sub>C</sub>	$V_{T} = 50\%$ , 101 MHz to 167 MHz	49	49 50 51		/0
Rise Time, Fall Time <sup>1</sup>	t <sub>R</sub> , t <sub>F</sub>	Single-ended 20 - 80 %	450	550	950	ne
	۲R, ۴	Load = 120 <sup>-/</sup> 12 pF	430			ps

1. Guaranteed by design, not 100% tested in production.

2. Refers to transistion on non-inverting output.

3. While the pulse skew is almost constant over frequency, the duty cycle error increases at higher frequencies.

This is due to the formula: duty cycle =  $t_{wH} / t_C$ , where the cycle time ( $t_C$ ) decreases as the frequency increases.

# General I<sup>2</sup>C serial interface information

The information in this section assumes familiarity with  $I^2C$  programming. For more information, contact IDT for an  $I^2C$  programming application note.

## How to Write:

- Controller (host) sends a start bit.
- Controller (host) sends the write address D4(H)
- IDT clock will acknowledge
- Controller (host) sends a dummy command code
- IDT clock will acknowledge
- · Controller (host) sends a dummy byte count
- IDT clock will acknowledge
- Controller (host) starts sending first byte (Byte 0) through byte 6
- IDT clock will acknowledge each byte one at a

#### time.

• Controller (host) sends a Stop bit

How to Write:					
Controller (Host)	IDT (Slave/Receiver)				
Start Bit					
Address					
D4 <sub>(H)</sub>					
	ACK				
Dummy Command Code					
	ACK				
Dummy Byte Count					
	ACK				
Byte 0					
	ACK				
Byte 1					
	ACK				
Byte 2					
	ACK				
Byte 3	1.0%				
Durbs 4	ACK				
Byte 4	ACK				
Byto 5	ACK				
Byte 5	ACK				
Byte 6	ACK				
Dyte 0	АСК				
Byte 7					
	ACK				
Stop Bit					

#### Notes:

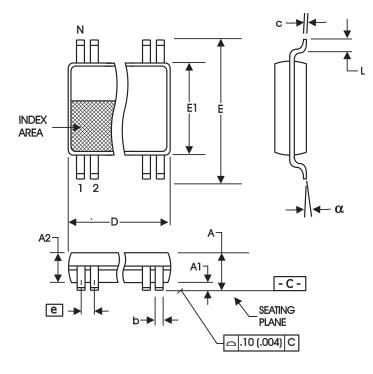
- 1. The IDT clock generator is a slave/receiver, I<sup>2</sup>C component. It can read back the data stored in the latches for verification. **Read-Back will support Intel PIIX4 "Block-Read" protocol**.
- 2. The data transfer rate supported by this clock generator is 100K bits/sec or less (standard mode)
- 3. The input is operating at 3.3V logic levels.
- 4. The data byte format is 8 bit bytes.
- 5. To simplify the clock generator I<sup>2</sup>C interface, the protocol is set to use only "**Block-Writes**" from the controller. The bytes must be accessed in sequential order from lowest to highest byte with the ability to stop after any complete byte has been transferred. The Command code and Byte count shown above must be sent, but the data is ignored for those two bytes. The data is loaded until a Stop sequence is issued.
- 6. At power-on, all registers are set to a default condition, as shown.

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# How to Read:

- Controller (host) will send start bit.
- Controller (host) sends the read address D5 (H)
- IDT clock will *acknowledge*
- IDT clock will send the byte count
- Controller (host) acknowledges
- IDT clock sends first byte (Byte 0) through byte 7
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a stop bit

How to Read:					
Controller (Host)	IDT (Slave/Receiver)				
Start Bit					
Address					
D5(H)					
	ACK				
	Byte Count				
ACK					
	Byte 0				
ACK					
	Byte 1				
ACK					
	Byte 2				
ACK					
	Byte 3				
ACK					
	Byte 4				
ACK					
	Byte 5				
ACK					
	Byte 6				
ACK					
	Byte 7				
Stop Bit					



SYMBOL	In Millimeters COMMON DIMENSIONS		In In COMMON D	ches IMENSIONS
	MIN	MAX	MIN	MAX
А	-	2.00	-	.079
A1	0.05	-	.002	-
A2	1.65	1.85	.065	.073
b	0.22	0.38	.009	.015
С	0.09	0.25	.0035	.010
D	SEE VARIATIONS		SEE VAF	RIATIONS
E	7.40	8.20	.291	.323
E1	5.00	5.60	.197	.220
е	0.65 E	BASIC	0.0256 BASIC	
L	0.55	0.95	.022	.037
Ν	SEE VARIATIONS		SEE VARIATIONS	
α	0°	8°	0°	8°

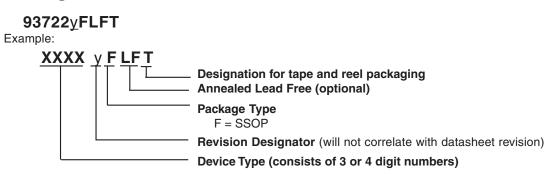
#### VARIATIONS

N	D mm.		D (inch)	
	MIN	MAX	MIN	MAX
28	9.90	10.50	.390	.413
			MO-150 JEDEC	6/1/00 Rev B

MO-150 JEDEC Doc.# 10-0033

209 mil SSOP

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