

General Description

The MAX5873 is an advanced 12-bit, 200Msps, dual digital-to-analog converter (DAC). This DAC meets the demanding performance requirements of signal synthesis applications found in wireless base stations and other communications applications. Operating from +3.3V and +1.8V supplies, this dual DAC offers exceptional dynamic performance such as 78dBc spurious-free dynamic range (SFDR) at $f_{OUT} = 16$ MHz and supports update rates of 200Msps, with a power dissipation of only 255mW.

The MAX5873 utilizes a current-steering architecture that supports a 2mA to 20mA full-scale output current range, and allows a 0.1VP-P to 1VP-P differential output voltage swing. The MAX5873 features an integrated +1.2V bandgap reference and control amplifier to ensure high-accuracy and low-noise performance. A separate reference input (REFIO) allows for the use of an external reference source for optimum flexibility and improved gain accuracy.

The digital and clock inputs of the MAX5873 accept 3.3V CMOS voltage levels. The MAX5873 features a flexible input data bus that allows for dual-port input or a single-interleaved data port. The MAX5873 is available in a 68-pin QFN package with an exposed paddle (EP) and is specified for the extended temperature range (-40°C to +85°C).

Refer to the MAX5874 and MAX5875 data sheets for pin-compatible 14-bit and 16-bit versions of the MAX5873, respectively. Refer to the MAX5876 for an LVDS-compatible version of the MAX5873.

> **Applications** Base Stations: Single-Carrier UMTS, CDMA, GSM **Communications: Fixed Broadband Wireless** Access, Point-to-Point Microwave

Direct Digital Synthesis (DDS)

Cable Modem Termination System (CMTS)

Automated Test Equipment (ATE)

Instrumentation

Selector Guide

PART	RESOLUTION (BITS)	UPDATE RATE	LOGIC INPUTS
MAX5873	12	200Msps	CMOS
MAX5874	14	200Msps	CMOS
MAX5875	16	200Msps	CMOS
MAX5876**	12	250Msps	LVDS
MAX5877**	14	250Msps	LVDS
MAX5878	16	250Msps	LVDS

**Future product—contact factory for availability.

Features

- 200Msps Output Update Rate
- Noise Spectral Density = -152dBFS/Hz at four = 16MHz
- Excellent SFDR and IMD SFDR = 78dBc at four = 16MHz (to Nyquist) SFDR = 73dBc at four = 80MHz (to Nyquist) IMD = -85dBc at four = 10MHz IMD = -74dBc at four = 80MHz

ИЛХГИ

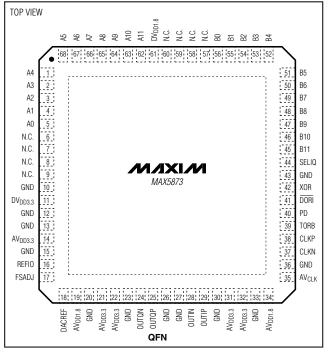
- ACLR = 74dB at four = 61MHz
- 2mA to 20mA Full-Scale Output Current
- CMOS-Compatible Digital and Clock Inputs
- On-Chip +1.20V Bandgap Reference
- Low 255mW Power Dissipation
- 68-Lead QFN-EP Package
- Evaluation Kit Available (MAX5875EVKIT)

Ordering Information

PART	TEMP RANGE	PIN- PACKAGE	PKG CODE
MAX5873EGK	-40°C to +85°C	68 QFN-EP*	G6800-4

*EP = Exposed pad.

Pin Configuration



Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

 $\begin{array}{l} {\sf AV}_{DD1.8}, \, {\sf DV}_{DD1.8} \text{ to } {\sf GND}.....-0.3V \ \text{to } +2.16V \\ {\sf AV}_{DD3.3}, \, {\sf DV}_{DD3.3}, \, {\sf AV}_{CLK} \ \text{to } {\sf GND}....-0.3V \ \text{to } +3.9V \\ {\sf DACREF}, \ {\sf REFIO}, \ {\sf FSADJ} \ \text{to } {\sf GND}...-0.3V \ \text{to } ({\sf AV}_{DD3.3} + 0.3V) \\ {\sf OUTIP}, \ {\sf OUTIN}, \ {\sf OUTQP}, \ {\sf OUTQN} \ \text{to } {\sf GND}...-1V \ \text{to } ({\sf AV}_{DD3.3} + 0.3V) \\ {\sf CLKP}, \ {\sf CLKN} \ \text{to } \ {\sf GND}....-0.3V \ \text{to } ({\sf AV}_{CLK} + 0.3V) \\ {\sf A11/B11}-{\sf A0/B0}, \ {\sf XOR}, \ {\sf SELIQ} \ \text{to } \ {\sf GND} \-0.3V \ \text{to } ({\sf DV}_{DD3.3} + 0.3V) \\ {\sf TORB}, \ \overline{{\sf DORI}}, \ {\sf PD} \ \text{to } \ {\sf GND} \-0.3V \ \text{to } ({\sf DV}_{DD3.3} + 0.3V) \\ \end{array}$

Note 1: Themal resistors based on a multilayer board with 4 x 4 via array in exposed paddle area.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(AV_{DD3.3} = DV_{DD3.3} = AV_{CLK} = +3.3V, AV_{DD1.8} = DV_{DD1.8} = +1.8V, GND = 0, f_{CLK} = f_{DAC}$, external reference $V_{REFIO} = +1.25V$, output load 50Ω double terminated, transformer-coupled output, $I_{OUTFS} = 20$ mA, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.) (Note 2)

PARAMETER	SYMBOL	CC	ONDITIONS	MIN	ТҮР	MAX	UNITS
STATIC PERFORMANCE		·		•			
Resolution					12		Bits
Integral Nonlinearity	INL	Measured differer	ntially		±0.2		LSB
Differential Nonlinearity	DNL	Measured differer	ntially		±0.13		LSB
Offset Error	OS			-0.025	±0.001	+0.025	%FS
Offset Drift Tempco					±10		ppm/°C
Full-Scale Gain Error	GE _{FS}	External reference	9		±1		%FS
Gain Drift Tempco		Internal reference			±100		ppm/°C
		External reference			±50		
Full-Scale Output Current	IOUT	(Note 3)		2		20	mA
Output Compliance		Single ended		-0.5		+1.1	V
Output Resistance	Rout				1		MΩ
Output Capacitance	Cout				5		рF
DYNAMIC PERFORMANCE							
Clock Frequency	fCLK			1		200	MHz
	<i>f</i>	$f_{DAC} = f_{CLK}/2$, sin	gle-port mode	1		100	Mana
Output Update Rate	fdac	fDAC = fCLK, dual-	-port mode	1		200	Msps
Noise Spectral Density		$f_{DAC} = 100MHz$	f _{OUT} = 16MHz, -12dBFS		-152		
		$f_{DAC} = 200MHz$	f _{OUT} = 80MHz, -12dBFS		-153		dBFS/Hz

ELECTRICAL CHARACTERISTICS (continued)

 $(AV_{DD3.3} = DV_{DD3.3} = AV_{CLK} = +3.3V, \\ AV_{DD1.8} = DV_{DD1.8} = +1.8V, \\ GND = 0, \\ f_{CLK} = f_{DAC}, \\ external reference \\ V_{REFIO} = +1.25V, \\ output \\ load \\ 50\Omega \\ double terminated, \\ transformer-coupled \\ output, \\ I_{OUTFS} = 20mA, \\ T_A = T_{MIN} \\ to \\ T_{MAX}, \\ unless \\ otherwise \\ noted. \\ Typical \\ values \\ are \\ at \\ T_A = +25^\circC.) \\ (Note 2)$

PARAMETER	SYMBOL	С	ONDITIONS	MIN	ТҮР	MAX	UNITS
			f _{OUT} = 1MHz, 0dBFS		86		
		f _{DAC} = 100MHz	fout = 1MHz, -6dBFS		82		
			fout = 1MHz, -12dBFS		80		
			f _{OUT} = 10MHz, -12dBFS		85		
			fout = 30MHz, -12dBFS		80		
Spurious-Free Dynamic Range to Nyquist	SFDR		fout = 10MHz, -12dBFS		80		dBc
to nyquist		<i>.</i>	$f_{OUT} = 16MHz$, -12dBFS, $T_A \ge +25^{\circ}C$	72	78		
		$f_{DAC} = 200MHz$	fout = 16MHz, -12dBFS	68	78		-
			$f_{OUT} = 50 MHz, -12 dBFS$		77		-
			f _{OUT} = 80MHz, -12dBFS		73		-
Spurious-Free Dynamic Range, 25MHz Bandwidth	SFDR	f _{DAC} = 150MHz	$f_{OUT} = 16MHz, -12dBFS$		85		dBc
Two-Tone IMD	TTU 45	$f_{DAC} = 100MHz$	$f_{OUT1} = 9MHz$, -7dBFS; $f_{OUT2} = 10MHz$, -7dBFS		-85		
	TTIMD	f _{DAC} = 200MHz	$f_{OUT1} = 79MHz$, -7dBFS; $f_{OUT2} = 80MHz$, -7dBFS		-74		dBc
Four-Tone IMD, 1MHz Frequency Spacing, GSM Model	FTIMD	f _{DAC} = 150MHz	$f_{OUT} = 16MHz, -12dBFS$		-82		dBc
Adjacent Channel Leakage Power Ratio 3.84MHz Bandwidth, W-CDMA Model	ACLR	f _{DAC} = 184.32MHz	f _{OUT} = 61.44MHz		74		dB
Output Bandwidth	BW-1dB	(Note 4)	•		240		MHz
INTER-DAC CHARACTERISTICS							
Gain Matching	∆Gain	fout = DC - 80MH	łz		±0.2		dB
Gain-Matching Tempco	∆Gain/°C				±20		ppm/°C
Phase Matching	∆Phase	$f_{OUT} = 60MHz$			±0.25		Degrees
Phase-Matching Tempco	∆Phase/°C				±0.002		Degrees/ °C
Channel-to-Channel Crosstalk		$f_{CLK} = 200MHz, f_{CLK}$	DUT = 50MHz		-70		dB
REFERENCE							
Internal Reference Voltage Range	VREFIO			1.14	1.2	1.26	V
Reference Input Compliance Range	VREFIOCR			0.125		1.250	V
Reference Input Resistance	R _{REFIO}				10		kΩ
Reference Voltage Drift	TCOREF				±25		ppm/°C
	1			1			

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ELECTRICAL CHARACTERISTICS (continued)

 $(AV_{DD3.3} = DV_{DD3.3} = AV_{CLK} = +3.3V, AV_{DD1.8} = DV_{DD1.8} = +1.8V, GND = 0, f_{CLK} = f_{DAC}$, external reference $V_{REFIO} = +1.25V$, output load 50Ω double terminated, transformer-coupled output, $I_{OUTFS} = 20$ mA, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}$ C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
ANALOG OUTPUT TIMING (See F	igure 4)	•				•
Output Fall Time	t _{FALL}	90% to 10% (Note 5)		0.7		ns
Output Rise Time	t RISE	10 % to 90% (Note 5)		0.7		ns
Output Propagation Delay	tPD	Excluding data latency (Note 5)		1.1		ns
Glitch Impulse		Measured differentially		1		pV•s
Output Noise	Nout	I _{OUTFS} = 2mA		30		pA/√Hz
	1001	Ioutfs = 20mA		30		
TIMING CHARACTERISTICS	1					•
Data to Clock Setup Time	t SETUP	Referenced to rising edge of clock (Note 6)	-0.6	-1.2		ns
Data to Clock Hold Time	thold	Referenced to rising edge of clock (Note 6)	2.1	1.5		ns
Single-Port (Interleaved Mode)		Latency to I output		9		Clock
Data Latency		Latency to Q output		8		cycles
Dual-Port (Parallel Mode) Data Latency				5.5		Clock cycles
Minimum Clock Pulse-Width High	tсн	CLKP, CLKN		2.4		ns
Minimum Clock Pulse-Width Low	tCL	CLKP, CLKN		2.4		ns
CMOS LOGIC INPUTS (A11/B11-	A0/B0, XOR	, SELIQ, PD, TORB, DORI)				
Input Logic High	VIH		0.7 x DV _{DD3.3}			V
Input Logic Low	VIL				0.3 x DV _{DD3.3}	V
Input Leakage Current	I _{IN}			1	20	μA
PD, TORB, DORI Internal Pulldown Resistance		VPD = VTORB = VDORI = 3.3V		1.5		MΩ
Input Capacitance	CIN			2.5		pF
CLOCK INPUTS (CLKP, CLKN)						
Differential Input	A)/	Sine wave		>1.5		\/
Voltage Swing	AV _{CLK}	Square wave		>0.5		Vp-p
Differential Input Slew Rate	SRCLK	(Note 7)		>100		V/µs
External Common-Mode Voltage Range	Vсом			AV _{CLK} / 2 ±0.3	2	V
Input Resistance	RCLK			5		kΩ
Input Capacitance	CCLK			2.5		pF
POWER SUPPLIES						
Analog Supply Voltage Deser	AV _{DD3.3}		3.135	3.3	3.465	V
Analog Supply Voltage Range	AV _{DD1.8}		1.710	1.8	1.890	V
Digital Supply Valtage Passa	DV _{DD3.3}		3.135	3.3	3.465	V
Digital Supply Voltage Range	DVDD1.8		1.710	1.8	1.890	v



ELECTRICAL CHARACTERISTICS (continued)

(AVDD3.3 = DVDD3.3 = AVCLK = +3.3V, AVDD1.8 = DVDD1.8 = +1.8V, GND = 0, fCLK = fDAC, external reference VREFIO = +1.25V, output load 50 Ω double terminated, transformer-coupled output, I_{OUTES} = 20mA, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at $T_A = +25^{\circ}C.$) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
		$f_{DAC} = 200Msps, f_{OUT} = 1MHz$		52	56	~^^
Analog Supply	IAVDD3.3	Power-down		0.001		mA
Current	1	$f_{DAC} = 200Msps, f_{OUT} = 1MHz$		24	32	
	IAVDD1.8	Power-down		0.001		mA
		f _{DAC} = 200Msps, f _{OUT} = 1MHz		1.5	3	mA
Digital Supply	IDVDD3.3	Power-down	1		- IIIA	
Current		$f_{DAC} = 200Msps, f_{OUT} = 1MHz$		20	25	~^^
	DVDD1.8	Power-down		0.001		mA
Power Dissipation	Davas	$f_{DAC} = 200Msps, f_{OUT} = 1MHz$		255	300	mW
Power Dissipation	PDISS	Power-down		3.3		TTIVV
Power-Supply Rejection Ratio	PSRR	AV _{DD3.3} = AV _{CLK} = DV _{DD3.3} = +3.3V ±5% (Notes 7, 8)	-0.1		+0.1	%FS/V

Note 2: Specifications at $T_A \ge +25^{\circ}C$ are guaranteed by production testing. Specifications at $T_A < +25^{\circ}C$ are guaranteed by design and characterization data.

Note 3: Nominal full-scale current IOUTFS = 32 x IREF.

Note 4: This parameter does not include update-rate depending effects of sin(x)/x filtering inherent in the MAX5873.

Note 5: Parameter measured single-ended into a 50Ω termination resistor.

-6dBFS

20

25

Note 6: Not production tested. Guaranteed by design and characterization data.

Note 7: A differential clock input slew rate of >100V/µs is required to achieve the specified dynamic performance.

60

40

20

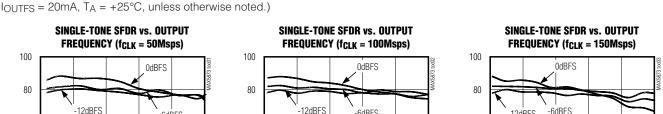
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0

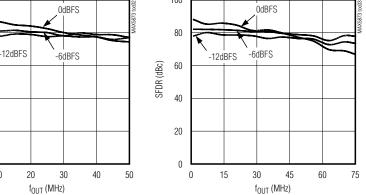
10

SFDR (dBc)

Note 8: Parameter defined as the change in midscale output caused by a $\pm 5\%$ variation in the nominal supply voltage.



Typical Operating Characteristics (AV_{DD3.3} = DV_{DD3.3} = AV_{CLK} = +3.3V, AV_{DD1.8} = DV_{DD1.8} = +1.8V, external reference, V_{REFIO} = +1.25V, R_L = 50Ω double-terminated,



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///XI///

60

40

20

0

0

5

10

15

f_{OUT} (MHz)

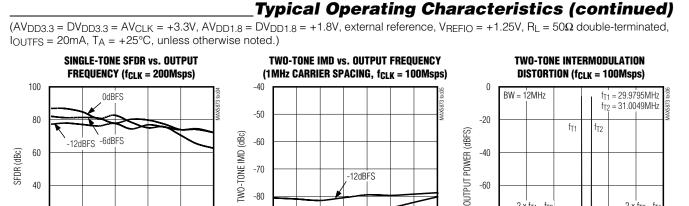
SFDR (dBc)



SFDR (dBc)

40

20



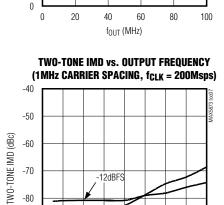
-70

-80

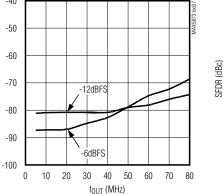
-90

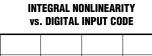
-100

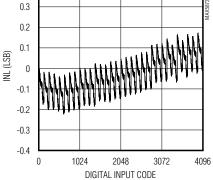
5 10 15 20 25 30



0.4







SFDR vs. FULL-SCALE OUTPUT CURRENT (f_{CLK} = 200MHz)

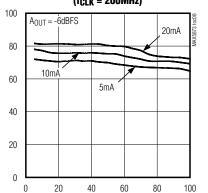
four (MHz)

-12dBFS

-6dBFS

35

40



four (MHz)



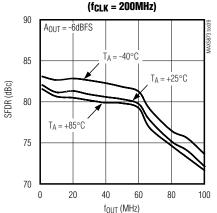
30

32

2 x f_{T2} - f_T

34

36



DIFFERENTIAL NONLINEARITY vs. DIGITAL INPUT CODE

-60

-80

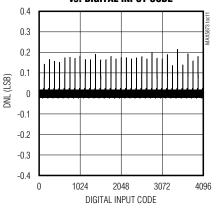
-100

24

2 x f_{T1} - f_{T2}

26

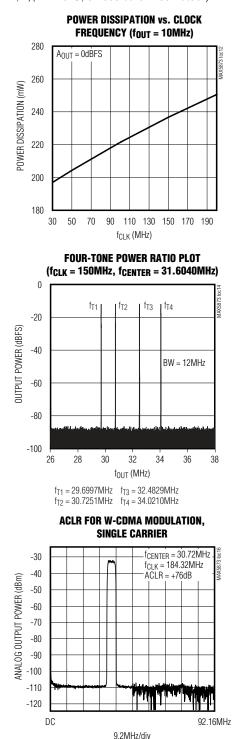
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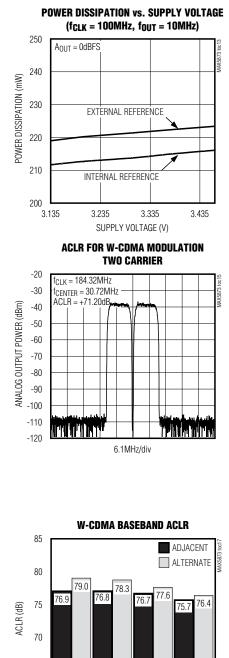
/N/IXI/N

Typical Operating Characteristics (continued)

 $(AV_{DD3.3} = DV_{DD3.3} = AV_{CLK} = +3.3V, AV_{DD1.8} = DV_{DD1.8} = +1.8V$, external reference, $V_{REFIO} = +1.25V$, $R_L = 50\Omega$ double-terminated, $I_{OUTFS} = 20$ mA, $T_A = +25^{\circ}$ C, unless otherwise noted.)



MIXI/M



65

60

1

2

NUMBER OF CARRIERS

3

4

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7

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PIN	NAME	FUNCTION
1–5	A4, A3, A2, A1, A0	Data Bits A4–A0. In dual-port mode, data is directed to the Q-DAC. In single-port mode, data bits are not used. Connect bits A4–A0 to GND in single-port mode.
6–9, 57–60	N.C.	No Connection. Leave floating or connect to GND.
10, 12, 13, 15, 20, 23, 26, 27, 30, 33, 36, 43	GND	Ground
11	DV _{DD3.3}	Digital Supply Voltage. Accepts a 3.135V to 3.465V supply voltage range. Bypass with a $0.1\mu\text{F}$ capacitor to GND.
14, 21, 22, 31, 32	AV _{DD3.3}	Analog Supply Voltage. Accepts a 3.135V to 3.465V supply voltage range. Bypass each pin with a 0.1 μ F capacitor to GND.
16	REFIO	Reference I/O. Output of the internal 1.2V precision bandgap reference. Bypass with a 1µF capacitor to GND. REFIO can be driven with an external reference source.
17	FSADJ	Full-Scale Adjust Input. This input sets the full-scale output current of the DAC. For a 20mA full-scale output current, connect a $2k\Omega$ resistor between FSADJ and DACREF.
18	DACREF	Current-Set Resistor Return Path. For a 20mA full-scale output current, connect a 2k Ω resistor between FSADJ and DACREF.
19, 34	AVDD1.8	Analog Supply Voltage. Accepts a 1.71V to 1.89V supply voltage range. Bypass each pin with a 0.1µF capacitor to GND.
24	OUTQN	Complementary Q-DAC Output. Negative terminal for current output.
25	OUTQP	Q-DAC Output. Positive terminal for current output.
28	OUTIN	Complementary I-DAC Output. Negative terminal for current output.
29	OUTIP	I-DAC Output. Positive terminal for current output.
35	AV _{CLK}	Clock Supply Voltage. Accepts a 3.135V to 3.465V supply voltage range. Bypass with a 0.1 μF capacitor to GND.
37	CLKN	Complementary Converter Clock Input. Negative input terminal for differential converter clock. Internally biased to AV _{CLK} / 2.
38	CLKP	Converter Clock Input. Positive input terminal for differential converter clock. Internally biased to AV _{CLK} / 2.
39	TORB	Two's-Complement/Binary Select Input. Set TORB to a CMOS-logic-high level to indicate a two's- complement input format. Set TORB to a CMOS-logic-low level to indicate a binary input format. TORB has an internal pulldown resistor.
40	PD	Power-Down Input. Set PD high to force the DAC into power-down mode. Set PD low for normal operation. PD has an internal pulldown resistor.
41	DORI	Dual (Parallel)/Single (Interleaved) Port Select Input. Set DORI high to configure as a dual-port DAC. Set DORI low to configure as a single interleaved-port DAC. DORI has an internal pulldown resistor.





Pin Description (continued)

PIN	NAME	FUNCTION
42	XOR	DAC Exclusive-OR Select Input. Set XOR low to allow the data stream to pass unchanged to the DAC input. Set XOR high to invert the input data into the DAC. If unused, connect XOR to GND.
44	44 SELIQ DAC Select Input. Set SELIQ low to direct data into the Q-DAC inputs. Set SELIQ high data into the I-DAC inputs. If unused, connect SELIQ to GND. SELIQ's logic state is o single-port (interleaved) mode.	
45–56	B11, B10, B9, B8, B7, B6, B5, B4, B3, B2, B1, B0	Data Bits B11–B0. In dual-port mode, data is directed to the I-DAC. In single-port mode, the state of SELIQ determines where the data bits are directed.
61	DV _{DD1.8}	Digital Supply Voltage. Accepts a supply voltage range of 1.71V to 1.89V. Bypass with a 0.1 μ F capacitor to GND.
62–68	A11, A10, A9 A8, A7, A6, A5	Data Bits A11–A5. In dual-port mode, data is directed to the Q-DAC. In single-port mode, data bits are not used. Connect bits A11–A5 to GND in single-port mode.
	EP	Exposed Pad. Must be connected to GND through a low-impedance path.

Detailed Description

Architecture

The MAX5873 high-performance, 12-bit, dual currentsteering DAC (Figure 1) operates with DAC update rates up to 200Msps. The converter consists of input registers and a demultiplexer for single-port (interleaved) mode, followed by a current-steering array. During operation in interleaved mode, the input data registers demultiplex the single-port data bus. The current-steering array generates differential full-scale currents in the 2mA to 20mA range. An internal current-switching network, in combination with external 50 Ω termination resistors, converts the differential output currents into dual differential output voltages with a 0.1V to 1V peak-to-peak output voltage range. An integrated +1.2V bandgap reference, control amplifier, and user-selectable external resistor determine the data converter's full-scale output range.

Reference Architecture and Operation The MAX5873 supports operation with the internal +1.2V bandgap reference or an external reference voltage source. REFIO serves as the input for an external, low-impedance reference source. REFIO also serves as a reference output when the DAC operates in internal reference mode. For stable operation with the internal reference, decouple REFIO to GND with a 1µF capacitor. Due to its limited output drive capability, buffer REFIO with an external amplifier when driving large external loads. The MAX5873's reference circuit (Figure 2) employs a control amplifier to regulate the full-scale current IOUTFS for the differential current outputs of the DAC. Configured as a voltage-to-current amplifier, calculate the output current as follows:

$$I_{OUTFS} = 32 \times \frac{V_{REFIO}}{R_{SET}} \times \left(1 - \frac{1}{2^{12}}\right)$$

where I_{OUTFS} is the full-scale output current of the DAC. R_{SET} (located between FSADJ and DACREF) determines the amplifier's full-scale output current for the DAC. See Table 1 for a matrix of different I_{OUTFS} and R_{SET} selections.

Table 1. IOUTFS and RSET SelectionMatrix Based on a Typical +1.200VReference Voltage

FULL-SCALE	R_{SET} (Ω)			
CURRENT IOUTFS (mA)	CALCULATED	1% EIA STD		
2	19.2k	19.1k		
5	7.68k	7.5k		
10	3.84k	3.83k		
15	2.56k	2.55k		
20	1.92k	1.91k		

MAX5873



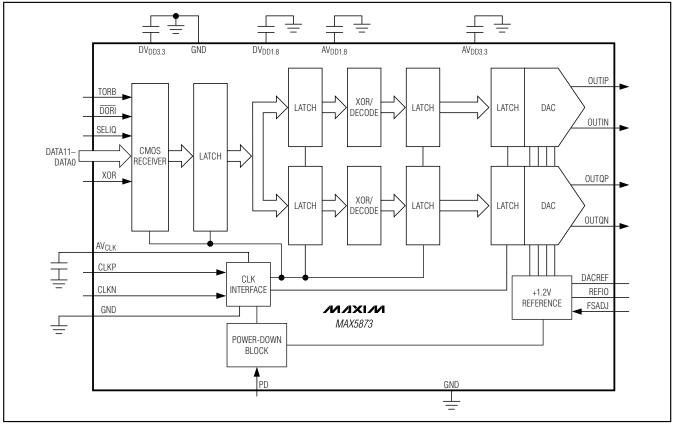


Figure 1. MAX5873 High-Performance, 12-Bit, Dual Current-Steering DAC

Analog Outputs (OUTIP, OUTIN, OUTQP, OUTQN)

Each MAX5873 DAC outputs two complementary currents (OUTIP/N, OUTQP/N) that operate in a singleended or differential configuration. A load resistor converts these two output currents into complementary single-ended output voltages. A transformer or a differential amplifier configuration converts the differential voltage existing between OUTIP (OUTQP) and OUTIN (OUTQN) to a single-ended voltage. If not using a transformer, the recommended termination from the output is a 25Ω termination resistor to ground and a 50Ω resistor between the outputs.

To generate a single-ended output, select OUTIP (or OUTQP) as the output and connect OUTIN (or OUTQN) to GND. SFDR degrades with single-ended operation. Figure 3 displays a simplified diagram of the internal output structure of the MAX5873.

Clock Inputs (CLKP, CLKN)

The MAX5873 features flexible differential clock inputs (CLKP, CLKN) operating from a separate supply

 (AV_{CLK}) to achieve the lowest possible jitter performance. Drive the differential clock inputs from a singleended or a differential clock source. For single-ended operation, drive CLKP with a logic source and bypass CLKN to GND with a 0.1µF capacitor.

CLKP and CLKN are internally biased to AV_{CLK} / 2. This facilitates the AC-coupling of clock sources directly to the device without external resistors to define the DC level. The dynamic input resistance from CLKP and CLKN to ground is $>5k\Omega$.

Data Timing Relationship

Figure 4 displays the timing relationship between digital CMOS data, clock, and output signals. The MAX5873 features a 1.5ns hold, a -1.2ns setup, and a 1.1ns propagation delay time. A nine (eight)-clock-cycle latency exists between CLKP/CLKN, and OUTIP/OUTIN (OUTQP/OUTQN) when operating in single-port (interleaved) mode. In dual-port (parallel) mode, the clock latency is 5.5 clock cycles for both channels.



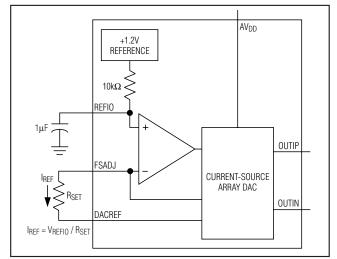


Figure 2. Reference Architecture, Internal Reference Configuration

Table 2. DAC Output Code Table

DIGITAL IN			
OFFSET BINARY TWO'S COMPLEMENT		OUT+	OUT-
0000 0000 0000	1000 0000 0000	0	IOUTFS
0111 1111 1111	0000 0000 0000	I _{OUTFS} / 2	I _{OUTFS} / 2
1111 1111 1111	0111 1111 1111	IOUTFS	0

CMOS-Compatible Digital Inputs Input Data Format Select (TORB, DORI)

The TORB input selects between two's-complement or binary digital input data. Set TORB to a CMOS-logichigh level to indicate a two's-complement input format. Set TORB to a CMOS-logic-low level to indicate a binary input format.

The DORI input selects between a dual-port (parallel) or single-port (interleaved) DAC. Set DORI high to configure the MAX5873 as a dual-port DAC. Set DORI low to configure the MAX5873 as a single-port DAC. In dual-port mode, connect SELIQ to ground.

CMOS DAC Inputs (A11/B11–A0/B0, XOR, SELIQ)

The MAX5873 latches input data on the rising edge of the clock in a user-selectable two's-complement or binary format. A logic-high voltage on TORB selects two'scomplement and a logic-low selects offset binary format.

The MAX5873 includes a single-ended, CMOS-compatible XOR input. Input data (all bits) are compared with the

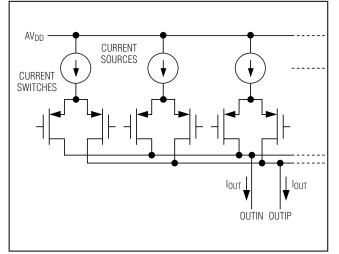


Figure 3. Simplified Analog Output Structure

bit applied to XOR through exclusive-OR gates. Pulling XOR high inverts the input data. Pulling XOR low leaves the input data noninverted. By applying a previously encoded pseudo-random bit stream to the data input and applying decoding to XOR, the digital input data can be decorrelated from the DAC output, allowing for the troubleshooting of possible spurious or harmonic distortion degradation due to digital feedthrough on the PC board.

A11/B11–A0/B0, XOR, and SELIQ are latched on the rising edge of the clock. In single-port mode (DORI pulled low) a logic-high signal on SELIQ directs the B11–B0 data onto the I-DAC inputs. A logic-low signal at SELIQ directs data to the Q-DAC inputs. In dual-port (parallel) mode (DORI pulled high), data on pins A11–A0 are directed onto the Q-DAC inputs and B11–B0 are directed onto the I-DAC inputs.

Power-Down Operation (PD)

The MAX5873 also features an active-high power-down mode that reduces the DAC's digital current consumption from 21.5mA to less than 1mA and the analog current consumption from 76mA to less than 2μ A. Set PD high to power down the MAX5873. Set PD low for normal operation.

When powered down, the MAX5873 reduces the overall power consumption to less than 3.3mW. The MAX5873 requires 10ms to wake up from power-down and enter a fully operational state. The PD integrated pulldown resistor activates the MAX5873 if PD is left floating.



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MAX5873

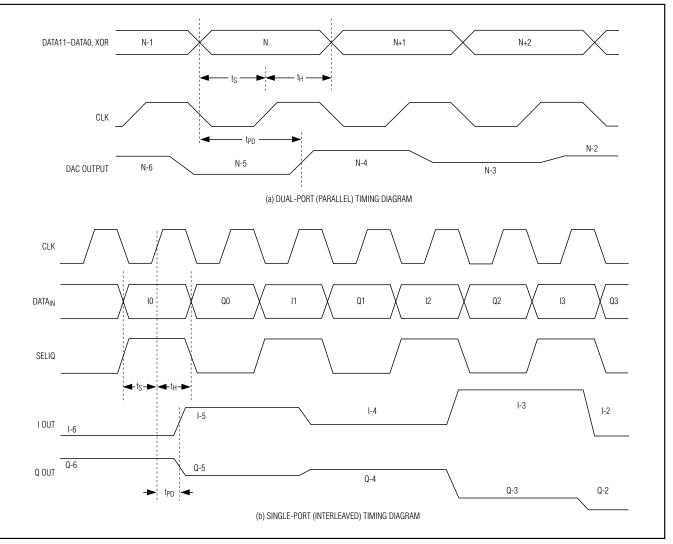


Figure 4. Timing Relationships Between Clock and Input Data for (a) Dual-Port (Parallel) Mode and (b) Single-Port (Interleaved) Mode

Applications Information

CLK Interface

The MAX5873 features a flexible differential clock input (CLKP, CLKN) with a separate supply (AV_{CLK}) to achieve optimum jitter performance. Use an ultra-low jitter clock to achieve the required noise density. Clock jitter must be less than 0.5ps_{RMS} for meeting the specified noise density. For that reason, the CLKP/CLKN input source must be designed carefully. The differential clock (CLKN and CLKP) input can be driven from a single-ended or a differential clock source. Differential

clock drive is required to achieve the best dynamic performance from the DAC. For single-ended operation, drive CLKP with a low noise source and bypass CLKN to GND with a 0.1μ F capacitor.

Figure 5 shows a convenient and quick way to apply a differential signal created from a single-ended source (e.g., HP 8662A signal generator) and a wideband transformer. Alternatively, these inputs can be driven from a CMOS-compatible clock source; however, it is recommended to use sinewave or AC-coupled differential ECL/PECL drive for best dynamic performance.



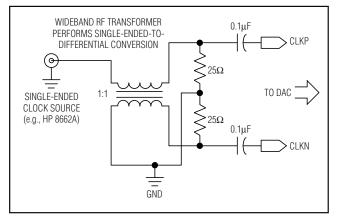


Figure 5. Differential Clock-Signal Generation

Differential Coupling Using a Wideband RF Transformer

Use a pair of transformers (Figure 6) or a differential amplifier configuration to convert the differential voltage existing between OUTIP/OUTQP and OUTIN/OUTQN to a single-ended voltage. Optimize the dynamic performance by using a differential transformer-coupled output to limit the output power to <0dBm full scale. Pay close attention to the transformer core saturation characteristics when selecting a transformer for the MAX5873. Transformer core saturation can introduce strong 2nd-order harmonic distortion especially at low output frequencies and high signal amplitudes. For best results, center tap the transformer to ground. When not using a transformer, terminate each DAC output to ground with a 25Ω resistor. Additionally, place a 50Ω resistor between the outputs (Figure 7).

For a single-ended unipolar output, select OUTIP (OUTQP) as the output and ground OUTIN (OUTQN) to GND. Driving the MAX5873 single-ended is not recom-

mended since additional noise and distortion will be added.

The distortion performance of the DAC depends on the load impedance. The MAX5873 is optimized for 50Ω differential double termination. It can be used with a transformer output as shown in Figure 6 or just one 25Ω resistor from each output to ground and one 50Ω resistor between the outputs (Figure 7). This produces a full-scale output power of up to -2dBm, depending on the output current setting. Higher termination impedance can be used at the cost of degraded distortion performance and increased output noise voltage.

Grounding, Bypassing, and Power-Supply Considerations

Grounding and power-supply decoupling can strongly influence the MAX5873 performance. Unwanted digital crosstalk couples through the input, reference, power supply, and ground connections, and affects dynamic performance. High-speed, high-frequency applications require closely followed proper grounding and powersupply decoupling. These techniques reduce EMI and internal crosstalk that can significantly affect the MAX5873 dynamic performance.

Use a multilayer printed circuit (PC) board with separate ground and power-supply planes. Run high-speed signals on lines directly above the ground plane. Keep digital signals as far away from sensitive analog inputs and outputs, reference input sense lines, commonmode input, and clock inputs as practical. Use a symmetric design of clock input and the analog output lines to minimize 2nd-order harmonic distortion components, thus optimizing the DAC's dynamic performance. Keep digital signal paths short and run lengths matched to avoid propagation delay and data skew mismatches.

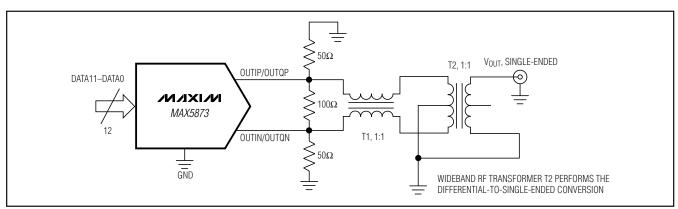


Figure 6. Differential-to-Single-Ended Conversion Using a Wideband RF Transformer

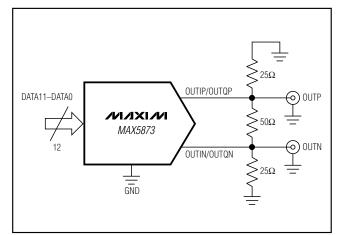


Figure 7. Differential Output Configuration

The MAX5873 requires five separate power-supply inputs for analog (AV_{DD1.8} and AV_{DD3.3}), digital (DV_{DD1.8} and DV_{DD3.3}), and clock (AV_{CLK}) circuitry. Decouple each AV_{DD}, DV_{DD}, and AV_{CLK} input pin with a separate 0.1 μ F capacitor as close to the device as possible with the shortest possible connection to the ground plane (Figure 8). Minimize the analog and digital load capacitances for optimized operation. Decouple all three power-supply voltages at the point they enter the PC board with tantalum or electrolytic capacitors. Ferrite beads with additional decoupling capacitors forming a pi-network could also improve performance.

The analog and digital power-supply inputs AV_{DD3.3}, AV_{CLK}, and DV_{DD3.3} allow a +3.135V to +3.465V supply voltage range. The analog and digital power-supply inputs AV_{DD1.8} and DV_{DD1.8} allow a +1.71V to +1.89V supply voltage range.

The MAX5873 is packaged in a 68-pin QFN-EP package, providing greater design flexibility, increased thermal efficiency, and optimized DAC AC performance. The EP enables the use of necessary grounding techniques to ensure highest performance operation. Thermal efficiency is not the key factor, since the MAX5873 features low-power operation. The exposed pad ensures a solid ground connection between the DAC and the PC board's ground layer.

The data converter die attaches to an EP lead frame with the back of this frame exposed at the package bottom surface, facing the PC board side of the package. This allows for a solid attachment of the package to the PC board with standard infrared (IR) flow soldering techniques. A specially created land pattern on the PC board, matching the size of the EP (6mm x 6mm), ensures the proper attachment and grounding of the DAC. Refer to the MAX5875 EV kit data sheet. Designing vias into the land area and implementing large ground planes in the PC board design allow for the highest performance operation of the DAC. Use an array of at least 4 x 4 vias (≤0.3mm diameter per via hole and 1.2mm pitch between via holes) for this 68-pin QFN-EP package. **Connect the MAX5873 exposed paddle to GND.** Vias connect the land pattern to internal or external copper planes. Use as many vias as possible to the ground plane to minimize inductance.

Static Performance Parameter Definitions Integral Nonlinearity (INL)

Integral nonlinearity is the deviation of the values on an actual transfer function from either a best straight-line fit (closest approximation to the actual transfer curve) or a line drawn between the end points of the transfer function, once offset and gain errors have been nullified. For a DAC, the deviations are measured at every individual step.

Differential Nonlinearity (DNL)

Differential nonlinearity is the difference between an actual step height and the ideal value of 1 LSB. A DNL error specification of less than 1 LSB guarantees a monotonic transfer function.

Offset Error

The offset error is the difference between the ideal and the actual offset current. For a DAC, the offset point is the average value at the output for the two midscale digital input codes with respect to the full scale of the DAC. This error affects all codes by the same amount.

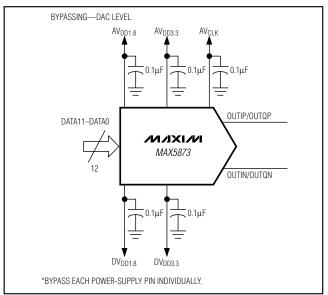


Figure 8. Recommended Power-Supply Decoupling and Bypassing Circuitry



Gain Error

A gain error is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

Dynamic Performance Parameter Definitions Signal-to-Noise Ratio (SNR)

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of the fullscale analog output (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum can be derived from the DAC's resolution (N bits):

$$SNR_{dB} = 6.02_{dB} \times N + 1.76_{dB}$$

However, noise sources such as thermal noise, reference noise, clock jitter, etc., affect the ideal reading; therefore, SNR is computed by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first four harmonics, and the DC offset.

Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of RMS amplitude of the carrier frequency (maximum signal components) to the RMS value of their next-largest distortion component. SFDR is usually measured in dBc and with respect to the carrier frequency amplitude or in dBFS with respect to the DAC's full-scale range. Depending on its test condition, SFDR is observed within a predefined window or to Nyquist. **Two-/Four-Tone Intermodulation Distortion (IMD)** The two-tone IMD is the ratio expressed in dBc (or dBFS) of the worst 3rd-order (or higher) IMD product(s) to either input tone; 2nd-order IMD products usually fall at frequencies that digital filtering easily removes. Therefore, they are not as critical as 3rd-order IMDs. The two-tone IMD performance of the MAX5873 is tested with the two individual input tone levels set to at least -6dBFS and the four-tone performance was tested according to the GSM model at an output frequency of 16MHz and amplitude of -12dBFS.

Adjacent Channel Leakage Power Ratio (ACLR)

Commonly used in combination with wideband codedivision multiple-access (W-CDMA), ACLR reflects the leakage power ratio in dB between the measured power within a channel relative to its adjacent channel. ACLR provides a quantifiable method of determining out-of-band spectral energy and its influence on an adjacent channel when a bandwidth-limited RF signal passes through a nonlinear device.

Settling Time

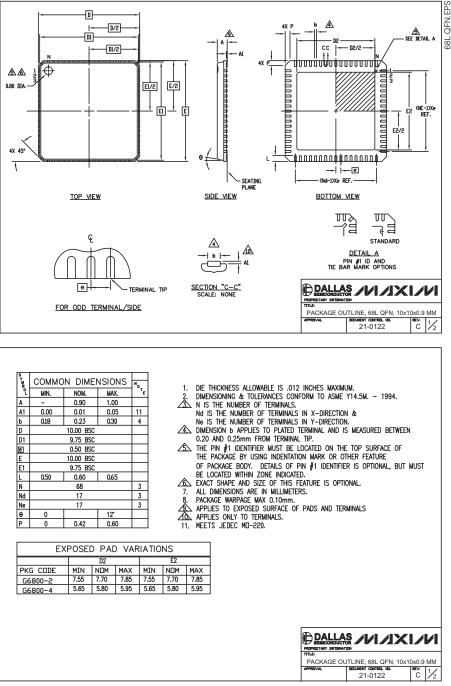
The settling time is the amount of time required from the start of a transition until the DAC output settles its new output value to within the converter's specified accuracy.

Glitch Impulse

A glitch is generated when a DAC switches between two codes. The largest glitch is usually generated around the midscale transition, when the input pattern transitions from 011...111 to 100...000. The glitch impulse is found by integrating the voltage of the glitch at the midscale transition over time. The glitch impulse is usually specified in pV•s.

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to **www.maxim-ic.com/packages**.)



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