

FAN8702/FAN8702B/FAN8702MP

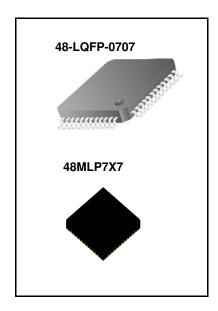
6 Channel DSC Motor Driver

Features

- Independent 6-Channel H-Bridge.
- Output Current up to 600mA (Each Channel)
- Constant Current Control on CH5 and CH6.
- Constant Voltage Control on CH1,2,3 and CH4.
- Built in Brake Function on CH3,4 and CH6.
- Built in Short Through Protection.
- Low Saturation Voltage.
- Low Voltage operation.
- Built in Reference Voltage.
- Built in Thermal Shut Down.

Description

The FAN8702 is designed for portable equipment such as DSC and mobile phone camera. It consists of 2 constant current and 4 constant voltage drive blocks suitable for shutter, auto-focus, iris and zoom motor drive.



Typical Applications

- DSC
- Mobile Phone Camera

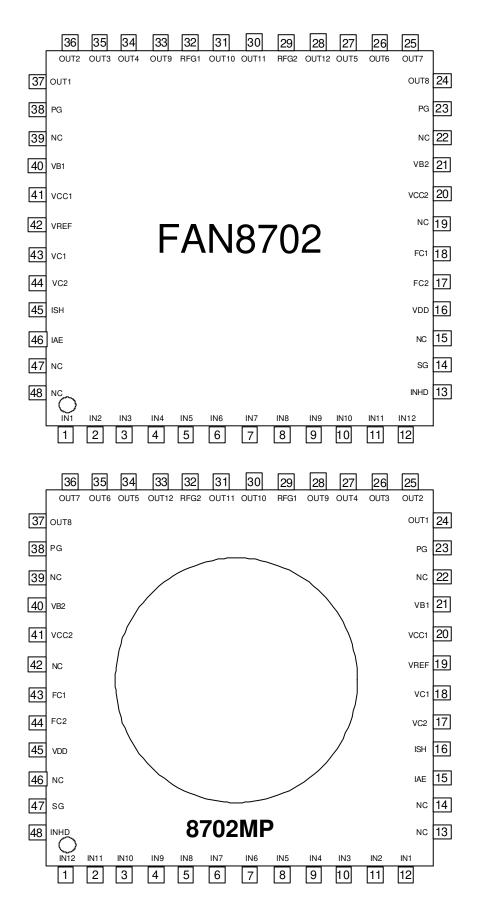
Ordering Information

Device	Package	Operating Temp.
FAN8702MP	48MLP 7X7	-20°C to +80°C
FAN8702MPX	48MLP 7X7	-20°C to +80°C
FAN8702	48-LQFP-0707	-20°C to +80°C
FAN8702B	48-LQFP-0707	-20°C to +80°C

Notes

X: Tape & Reel

Pin Assignments



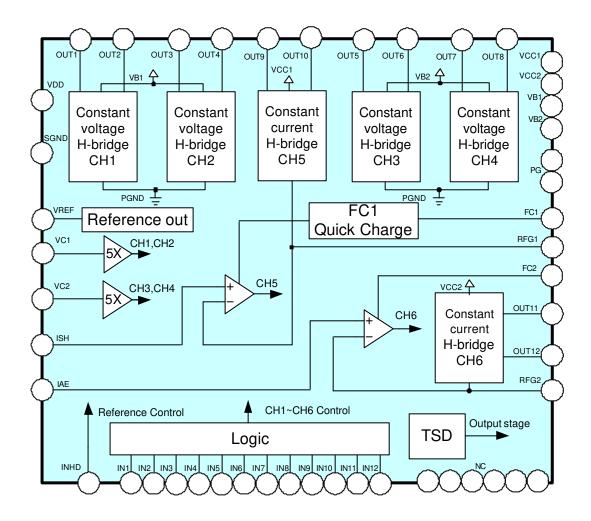
Pin Definitions

Pin Number		D: N	1/0	D. E D	
FAN8702/B	FAN8702MP	Pin Name	I/O	Pin Function Description	Remark
1	12	IN 1	I	Logic Input 1	-
2	11	IN 2	I	Logic Input 2	-
3	10	IN 3	I	Logic Input 3	-
4	9	IN 4	I	Logic Input 4	-
5	8	IN 5	I	Logic Input 5	-
6	7	IN 6	ı	Logic Input 6	-
7	6	IN 7	I	Logic Input 7	-
8	5	IN 8	I	Logic Input 8	-
9	4	IN 9	I	Logic Input 9	-
10	3	IN 10	I	Logic Input 10	-
11	2	IN 11	I	Logic Input 11	-
12	1	IN 12	I	Logic Input 12	-
13	48	INHD	I	Voltage Adjust for Vref	-
14	47	SG	Р	Signal Ground	-
15	46	NC	-	Non Connection	-
16	45	VDD	Р	Supply Voltage (Logic Voltage)	-
17	44	FC2	Α	Compensation 2	-
18	43	FC1	Α	Compensation 1	-
19	42	NC	-	Non Connection	-
20	41	VCC2	Р	Supply Voltage (Current Drive2)	-
21	40	VB2	Р	Supply Voltage (Voltage Drive2)	-
22	39	NC	-	Non Connection	-
23	38	PG	Р	Power Ground	-
24	37	OUT8	Α	Voltage Driver OUT8	-
25	36	OUT7	Α	Voltage Driver OUT7	-
26	35	OUT6	Α	Voltage Driver OUT6	-
27	34	OUT5	Α	Voltage Driver OUT5	-
28	33	OUT12	Α	Current Driver OUT12	-
29	32	RFG2	A	Current Sensing2	-
30	31	OUT11	Α	Current Driver OUT11	-
31	30	OUT10	Α	Current Driver OUT10	-
32	29	RFG1	A	Current Sensing1	-
33	28	OUT9	Α	Current Driver OUT9	-
34	27	OUT4	Α	Voltage Driver OUT4	-
35	26	OUT3	Α	Voltage Driver OUT3	-
36	25	OUT2	Α	Voltage Driver OUT2	-
37	24	OUT1	Α	Voltage Driver OUT1	-
38	23	PG	Р	Power Ground	-
39	22	NC	-	Non Connection	-
40	21	VB1	Р	Supply Voltage (Voltage Drive1)	-

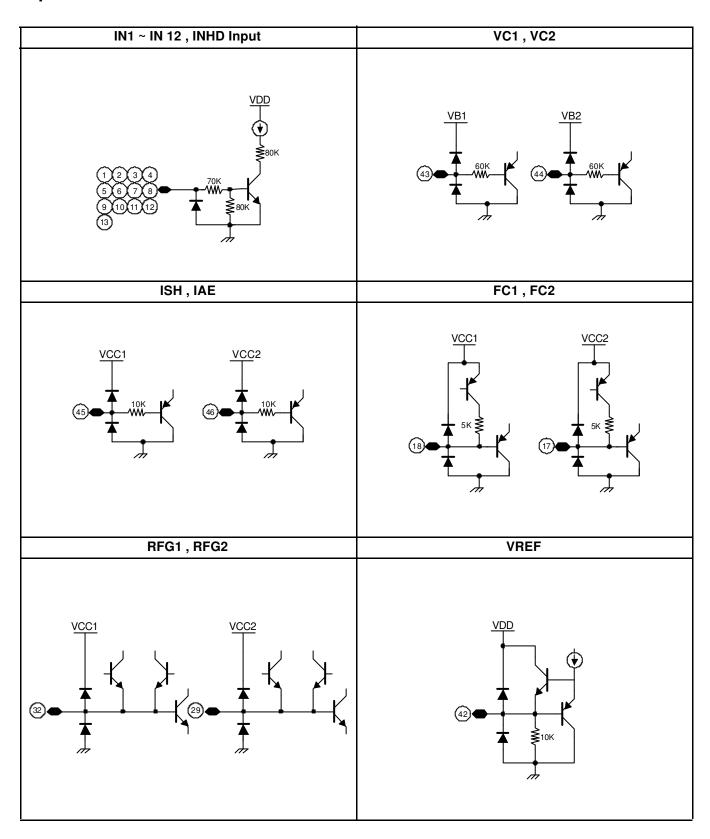
Pin Definitions (Continued)

Pin Nu	umber	Pin Name	Remark		
Pin Number	Pin Number	riii Naiile	I/O	Pin Function Description	Heiliaik
41	20	VCC1	Р	Supply Voltage (Current Drive1)	-
42	19	VREF	Α	Reference Voltage Out	-
43	18	VC1	Α	Voltage Adjust for Out 1~4	-
44	17	VC2	Α	Voltage Adjust for Out 5~8	-
45	16	ISH	A	Voltage Adjust for Shutter(Out9~10)	-
46	15	IAE	Α	Voltage Adjust for IRIS(Out11~12)	-
47	14	NC	-	Non Connection	-
48	13	NC	-	Non Connection	-

Internal Block Diagram

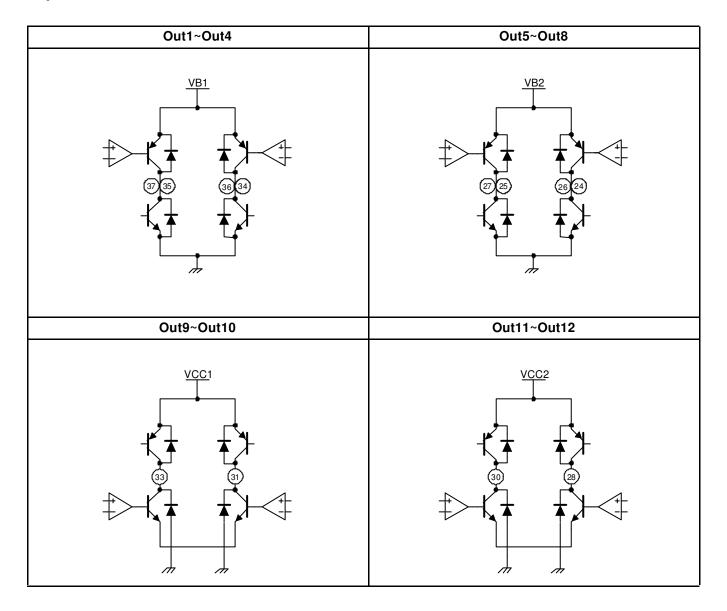


Equivalent Circuits



Notes: Reference of pin number is 48-LQFP-0707

Equivalent Circuits (Continued)



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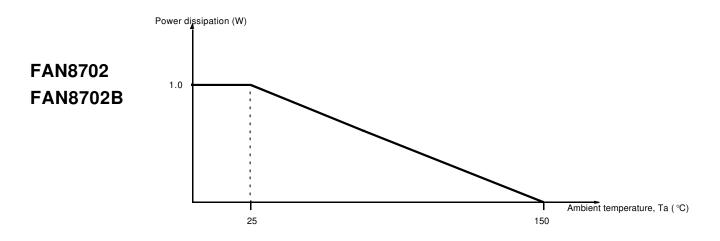
Absolute Maximum Ratings (Ta = 25°C)

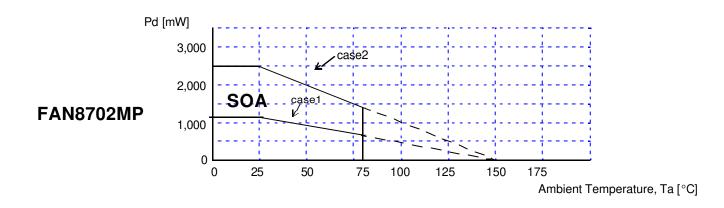
Parameter	Symbol	Value	Unit
Maximum Power Supply Voltage	VBMAX	10.5	V
Maximum Power Supply Voltage	VCCMAX	10.5	V
Maximum Approval Voltage To Input Pin	VINMAX	10.5	V
Maximum Approval Voltage To Output Pin	VOUTMAX	11.5	V
Maximum Output Current	IOUTMAX	600	mA
		1000 (FAN8702/B) ^{Case1}	
Maximum Power Dissipation	PdMAX	1200 (FAN8702MP) ^{Case1}	mW
		2500 (FAN8702MP) Case2	1
Operating Temperature	TOPR	-20 ~ +80	°C
Storage Temperature	TSTG	-55 ~ +150	°C

Note:

- 1. Refer: EIA/JESD 51-2 & EIA/JESD 51-3 & EIA/JESD 51-5 & EIA/JESD 51-7
- 2. Case 1: Single layer PCB with 1 signal plane only, PCB size 76mm × 114mm × 1.6mm.
- 3. Case 2: Multi layer PCB with 1 signal, 1 power and 1 ground planes, PCB size $76\text{mm} \times 114\text{mm} \times 1.6\text{mm}$, Cu plane sizes for power and ground $74\text{mm} \times 74\text{mm} \times 0.035\text{mm}$, thermal via hole pitch 0.9mm, via hole ϕ size 0.3mm, 6 via hole.
- 4. Should not exceed PD or ASO value.

Power Dissipation Curve





Recommended Operating Conditions (Ta = 25°C)

Parameter	Symbol	Min.	Тур.	Max.	Unit
Operating Voltage Range	VB1,2	2.2	-	6.5	V
Operating Voltage Range	VCC1,2	2.2	-	6.5	V
Logic Input High Level	VINH	1.8	-	7.0	V
Logic Input Low Level	VINL	-0.3	-	0.4	V

Electrical Characteristics

(Ta = 25°C, VB1=VB2=VCC1=VCC2=VDD=2.4V)

Block	Parameter	Symbol	Conditions	Min.	Тур.	Max.	Unit
	Stand-by Current	ISTB	VB=VCC=VDD=7.0V	-	-	1.0	μΑ
	Operating Consumption Current 1	ICC1	IN1~,IN8 (1Phase) IOV=200mA, Note1	-	8	11	mA
	Operating Consumption Current 2	ICC2	IN1~IN8(2Phase) IOV=400mA, Note1	-	17	25	mA
	Operating Consumption Current 3	ICC3	IN5~IN8(Brake) Note2	-	16	25	mA
Total	Operating Consumption Current 4	ICC4	IN9~IN12(1 phase) IOI=200mA, Note1	-	6	11	mA
	Operating Consumption Current 5	ICC5	IN11,IN12(Brake)Note2	-	16	25	mΑ
	Reference Voltage Output Voltage 1	VREF1	IREF=-1mA,INHD=L	0.95	1.0	1.05	V
	Reference Voltage Output Voltage 2	VREF2	IREF=-1mA,INHD=H	0.64	0.67	0.70	V
	Logic Input High Current	IINH	VIN=5.0V	-	60	90	μΑ
	Logic Input Low Current	IINL	VIN=0.0V	-1	-	1	μΑ
	Thermal Shutdown	THD	-	-	150	-	°C
Current	Output Current 1	Ю	RFG=1.0 Ω , ISH=0.3V	282	300	318	mA
driver	Output Saturation Voltage (PNP+NPN)	VSAT1	IO=0.3A	-	0.4	0.6	٧
Voltage	Output Voltage 1	VO	VC1, 2 =0.4V	1.9	2.0	2.1	V
driver	Output Saturation Voltage (PNP+NPN)	VSAT2	IO=0.2A	-	0.35	0.50	V

Note:

^{1.} ICC1, ICC2,ICC4 is sum of the current consumption VB1,VB2,VCC1,VCC2 line.

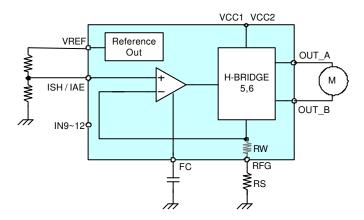
 $^{2.\} ICC3,\ ICC5\ is\ sum\ of\ the\ current\ consumption\ VB1,VB2,VCC1,VCC2\ and\ VDD\ line.$

Operation Truth Table

Input/ Out- put Mo- tor Oper- ation	IN 1	IN 2	IN 3	IN 4	IN 5	IN 6	IN 7	IN 8	IN 9	IN 10	IN 11	IN 12	INHD	О ШТ 1	ОТ 2	OU T3	OUT 4	OUT 5	OUT 6	OUT 7	OUT 8	OUT 9	ОUТ 10	ОUТ 11	OUT 12	Vref
Stan d-by	L	L	L	L	L	L	L	L	L	L	L	L	L	Z	Z	Z	Z	Z	Z	Z	Z	Z	Z	Z	Z	Z
	L	L	L	L	L	L	L	L	L	L	L	L	Н													0.67
	١	Nhe	en c	ne	of in	ıput	of I	N1	to IN	V12 i	s hig	jh	L H													1.0 0.67
Volt age dri- ver 1	L H H	L H L		L H L										Z L H Z	Z H L	Z L H	Z H L									0.07
Volt age dri- ver 2					L H	L H L	L L H	L H L										Z L H L	Z H L	Z L H	Z H L					
Curr ent dri- ver 1									L H H	H L H	L	L		F	AN8		N87 B an			02M	Р	Z L H Inh	Z H L ibit	Z	Z	
Curr ent dri- ver 2											L H H	H L H												L H L	H L L	

Application Information

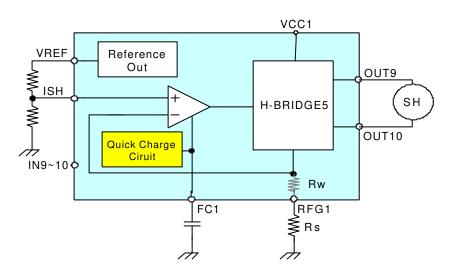
1. Current Drive Output Current Setting



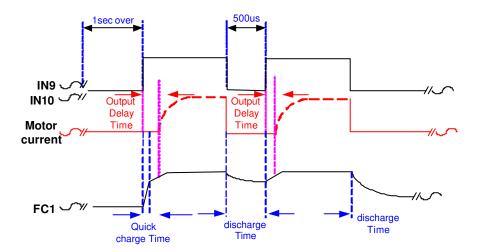
Motor current is determined by ISH/IAE voltage and Rs sensing resistance and calculated by the formula below considering Rw. Generally internal bonding and metal resistance Rw is around 0.05Ω .

$$Motor Current = \frac{ISH \ or \ IAE \ Input \ Voltage}{R_S + R_W}$$

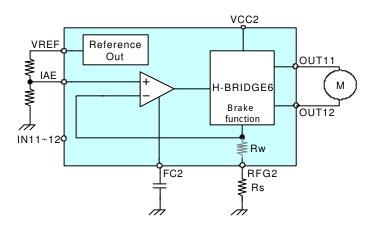
2. Current Drive Block1(CH5)



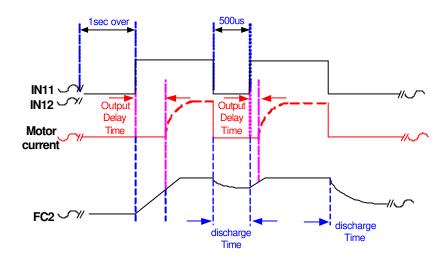
If there is no capacitor on the exterior of the FC terminal or low capacitance is used, it may cause oscillation or overshoot at output terminal. The output stage will not be operating until FC1 terminal voltage reaches around 0.7V (Typical) The output response time depends on the FC1 capacitance and interval of Input signal. Generally, the quick charging time is $10us\sim20us$. To minimize the delay time difference in the output response between high-speed shutter and bulb shutter a quick charging circuit is built in.



3. Current Drive block2(CH6)

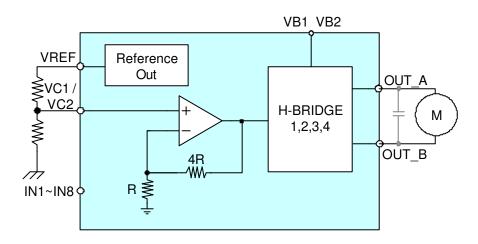


The output response time depends on the FC2 capacitance and interval of Input signal because there is no FC quick charging circuit in current drive2.



4. Voltage Drive Block

The output voltage as much as 5 times the input voltage VC1, VC2 is produced in the range of motor power VB1/VB2. If output oscillation occur during constant voltage drive, then 0.01uF~0.1uF capacitor should be installed on the both sides of the output.

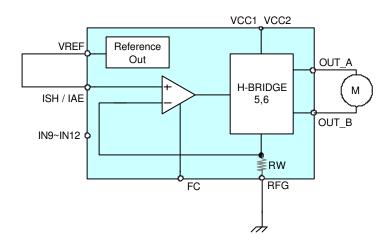


5. H-Bridge Drive Mode

A H-bridge drive mode can be implemented using the current drive block or the voltage drive block.

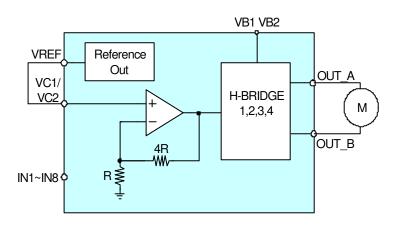
1) H- bridge drive using current drive block

The current drive block using the H-bridge method can be operated with ISH/AE connected to VREF or supply input, with the FC terminal open and sensing terminal connected to ground.



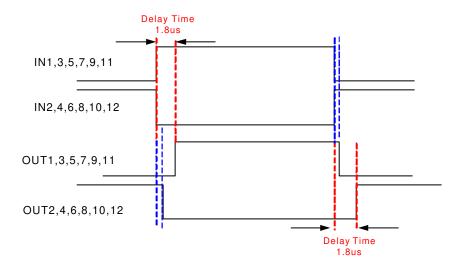
2) H- bridge drive using voltage drive block

When VB1 and VB2 power is less than 5V, VC1/VC2 input should be connected to VREF or motor supply and VB1 and VB2 power is more than 5V, VC1/VC2 input should be connected to motor supply. In H-bridge drive mode, a capacitor to prevent oscillation is not necessary on both sides of the output.



6. Short through protection

When a motor is driven, high/low side TR turn on simultaneously. This range may cause power to be shorted to ground momentarily. To prevent a short through, output is generated with a 1.8us(typical) delay after a high input signal.



7. Brake function

The brake function is built in Ch3,4 and CH6. Using the H/H signal on input, it is designed so that a short brake is operated on output.

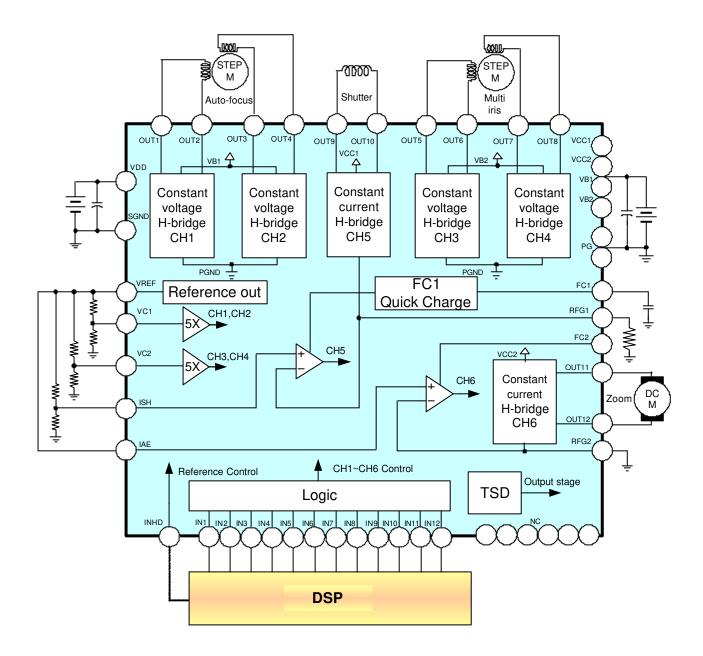
8. Power Supply

VB1,VB2,VCC1 and VCC2 are separated for motor power of FAN8702 and VDD is used for IC logic power. VB1,VB2,VCC1 and VCC2 are correspond to H-bridge 1~2, H-bridge 3~4, H-bridge 5 and H-bridge6.

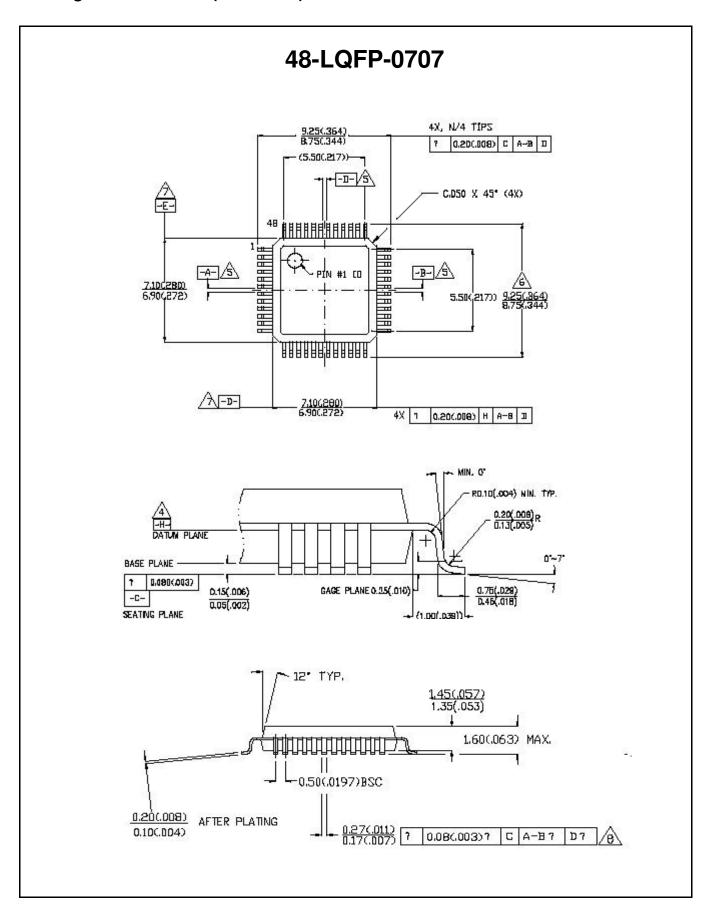
9. Thermal shutdown

When thermal shut down is activated, all the outputs become off except for VREF.

Typical Application Circuits1

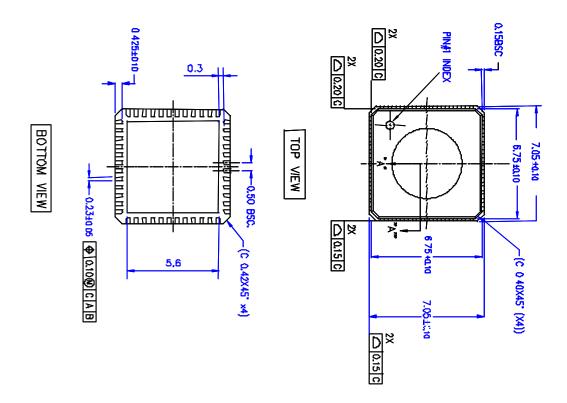


Package Dimensions (Unit: mm)



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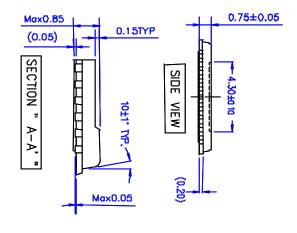
48MLP 7x7



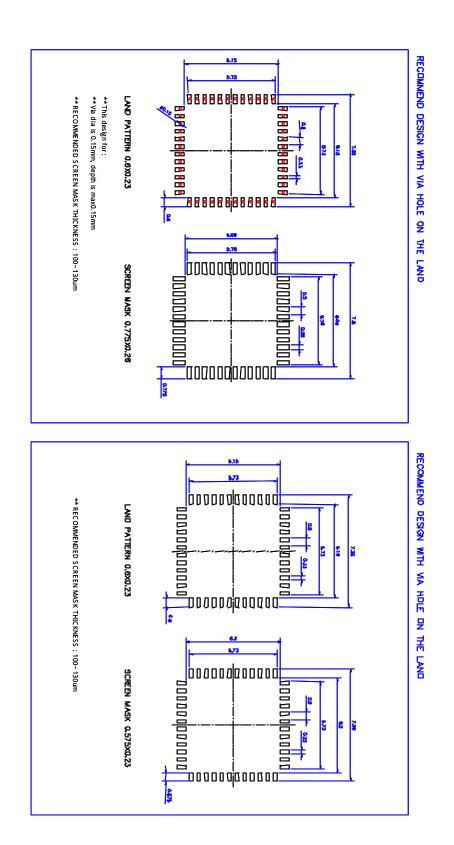
NOTES :

1. PACKAGE DIMENSIONS CONFORM TO JEDEC MG-220 (WKKD-2).
2. DIMENSIONNO AND TOLERANCING CONFORM TO ASSM Y 14.5N ~ 1994.
3 LEAD NUMBERS START WITH THE JI AND CONTINUE
COUNTOLDCKWISE TO LEAD JAB WHEN VIEWED FROM THE TOP.

4. PN // INDEX MUST BE INDICATED BY LASER MARK
5. MAXINUM ALLOWABLE BURR SHALL NOT EXCEED 0.05NM



Recommended PCB Design for FAN8702MP(Unit: mm)



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