

DC MOTOR PULSE WIDTH MODULATOR

Description

The SG1731 is a pulse width modulator circuit designed specifically for DC motor control. It provides a bi-directional pulse train output in response to the magnitude and polarity of an analog error signal input. The device is useful as the control element in motor-driven servo systems for precision positioning and speed control, as well as in audio modulators and amplifiers using carrier frequencies to 350 kHz.

The circuit contains a triangle waveform oscillator, a wideband operational amplifier for error voltage—generation, a summing/ scaling network for level-shifting the triangle waveform, externally programmable PWM comparators and dual ±100 mA, ±22 V totem pole drivers with commutation diodes for full bridge output. A SHUTDOWN terminal forces the drivers into a floating high-impedance state when driven LOW. Supply voltage to the control circuitry and to the output drivers may be from either dual positive and negative supplies, or single-ended.

Features

- ±3.5 V to ±15 V Control Supply
- ±2.5 V to ±22 V Driver Supply
- Dual 100 mA Source/Sink Output Drivers
- 5 kHz to 350 kHz Oscillator Range
- High Slew Rate Error Amplifier
- Adjustable Deadband Operation
- Digital SHUTDOWN Input

High Reliability Features

- Available to MIL-STD-883
- Available to DSCC
 - Standard Microcircuit Drawing (SMD)
- MSC-AMS level "S" Processing Available

Block Diagram

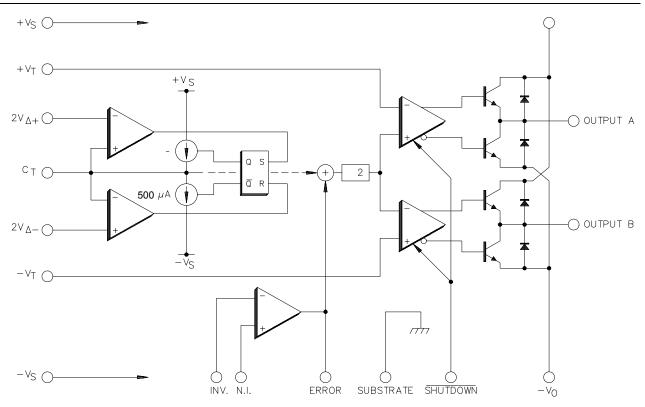


Figure 1 · Block Diagram



Absolute Maximum Ratings (Note 1)

| Supply Voltage (±V _s) | ±18 V |
|---|-----------------|
| Analog Inputs | ±V _s |
| Digital Inputs (SHUTDOWN) | |
| Output Driver Supply Voltage (±V _o) | ±25 V |
| Source/Sink Output Current (continuous) | . 200 mA |
| Source/Sink Output Current (peak, 500 ns) | . 400 mA |
| | |

Note 1. Values beyond which damage may occur. Extended operation at the maximum levels may degrade performance and affect reliability.

| Output Driver Diode Current (continuous) Output Driver Diode Current (peak, 500 ns) | |
|---|----------------|
| Operating Junction Temperature | |
| Hermetic (J - Package) | 150°C |
| Plastic (N - Package) | 150°C |
| Storage Temperature Range | -65°C to 150°C |
| Lead Temperature (Soldering, 10 Seconds) | 300°C |
| RoHS Peak Package Solder Reflow Temp.(40 sec. max. exp.). | 260°C (+0, -5) |
| | |

Thermal Data

J Package:

N Package:

L Package

Note A. Junction Temperature Calculation: $T_J = T_A + (P_D \times \theta_{JA})$. Note B. The above numbers for θ_{JC} are maximums for the limiting thermal resistance of the package in a standard mounting configuration. The θ_{JA} numbers are meant to be guidelines for the thermal performance of the device/pc-board system. All of the above assume no ambient airflow.

Recommended Operating Conditions (Note 2)

Note 2. Range over which the device is functional and parameter limits are guaranteed

Electrical Characteristics

(Unless otherwise specified, these specifications apply over the operating ambient temperatures for SG1731 with -55°C \leq T_A \leq 125°C, SG2731 with -25°C \leq T_A \leq 85°C, SG3731 with 0°C \leq T_A \leq 70°C, V_S = \pm 15 V, and V_O = \pm 22 V. Low duty cycle pulse testing techniques are used which maintains junction and case temperatures equal to the ambient temperature.)

| Parameter | Test Conditions | SG1731/27 | | 1/3731 | Units |
|--------------------------------------|---|-----------|------|--------|--------|
| | | Min. | Тур. | Max. | Ullits |
| Oscillator Section | | | | | |
| C _⊤ Charging Current | $T_A = 25^{\circ}C$ | 450 | 500 | 550 | μΑ |
| | $T_A = T_{MIN}$ to T_{MAX} | 400 | | 600 | μΑ |
| 2V∆± Input Bias Current | $V_{\rm CM} = \pm 5 \text{ V}$ | | | -20 | μΑ |
| Initial Oscillator Frequency | $C_{T} = 1000 \text{ pF}, 2V\Delta \pm = \pm 5 \text{ V}, T_{A} = 25^{\circ}\text{C}$ | 22.5 | 25.0 | 27.5 | kHz |
| Temperature Stability (Note 3) | $C_{T} = 1000 \text{ pF}, 2V\Delta \pm = \pm 5 \text{ V}$ | | | 10 | % |
| Error Amplifier Section (Note 5) | | | | | |
| Input Offset Voltage | | | | 10 | mV |
| Input Bias Current | | | | 3 | μΑ |
| Input Offset Current | | | | 600 | nA |
| Open Loop Voltage Gain | $R_1 = 2 k\Omega$ | 70 | | | dB |
| Output Voltage Swing | $R_{i} = 2 k\Omega$ | ±10 | | | V |
| Common-Mode Rejection Ratio | | 70 | | | dB |
| Slew Rate (Notes 3 and 4) | $T_A = 25^{\circ}C$ | 5 | 10 | | V/μs |
| Unity Gain Bandwidth (Notes 3 and 4) | $T_A = 25^{\circ}C$ | 0.7 | 1 | | MHz |
| PWM Comparators | | | | | |
| Input Bias Current | $\pm V_T = \pm 3 \text{ V}$ | | | 6 | μΑ |



Electrical Characteristics (Continued)

| Parameter | Took Conditions | SG1731/2731/3731 | | | Units | |
|-------------------------------|--|---------------------|-------------|------|--------|--|
| Parameter | Test Conditions | | Typ. M | lax. | Ullits | |
| SHUTDOWN Section | | | | | | |
| Logic Threshold | -V _s = -3.5 V to -15 V | V _s +0.8 | $V_{\rm s}$ | +2.0 | V | |
| SHUTDOWN HIGH Current | $V_{\overline{SHUTDOWN}} = -V_S + 2.4 \text{ V}$ | | | 400 | μΑ | |
| SHUTDOWN LOW Current | $V_{\overline{SHUTDOWN}} = -V_S + 2.4 \text{ V}$ $V_{\overline{SHUTDOWN}} = -V_S$ | | - | 1.0 | mΑ | |
| Output Drivers (Each Output) | | • | <u> </u> | | | |
| HIGH Output Voltage | I _{SOURCE} = 20 mA | 19.2 | | | V | |
| | I _{SOURCE} = 100 mA | 19.0 | | | V | |
| LOW Output Voltage | I _{SINK} = 20 mA | | -1 | 19.2 | V | |
| | I _{SINK} = 100 mA | | -1 | 19.0 | V | |
| Driver Risetime | C _i = 1000 pF | | 3 | 300 | ns | |
| Driver Falltime | $C_{L}^{2} = 1000 \text{ pF}$ | | 3 | 300 | ns | |
| Total Supply Current | | | | | | |
| V _s Supply Current | $V_{SHUTDOWN} = -V_S + 0.8 V$ | | | 14 | mΑ | |
| V _o Supply Current | $\begin{vmatrix} V_{\overline{SHUTDOWN}} = -V_S + 0.8 \text{ V} \\ V_{\overline{SHUTDOWN}} = -V_S + 0.8 \text{ V} \end{vmatrix}$ | | | 6 | mA | |

Note 3. These parameters, although guaranteed, are not tested in production.

Note 5. $V_{CM} = \pm 12 \text{ V}.$

Note 4. Unity Gain Inverting 10 k Ω Feedback Resistance.

Application Information

SUPPLY VOLTAGE

The SG1731 requires a supply voltage for the control circuitry (V_s) and for the power output drivers (V_o). Each supply may be either balanced positive and negative with respect to ground, or single-ended. The only restrictions are:

- 1. The voltage between +V $_{\rm S}$ and -V $_{\rm S}$ must be at least 7.0 V; but no more than 44 V.
- 2. The voltage between +V $_{\rm o}$ and -V $_{\rm o}$ must be at least 5.0 V; but no more than 44 V.
- 3. +V_o must be at least 5 V more positive than -V_s. This eliminates the combination of a single-ended positive control supply with a single-ended negative driver supply.

SUBSTRATE CONNECTION

The substrate connection (Pin 10) must always be connected to either $-V_s$ or $-V_o$, whichever is more negative. The substrate must also be well bypassed to ground with a high quality capacitor.

OSCILLATOR

The triangle oscillator consists of two voltage comparators, a set/reset flip-flop, a bi-directional 500 μA current source, and an external timing capacitor $C_{_T}$. A positive reference voltage $(2V\Delta+)$ applied to Pin 2 determines the positive peak value of the triangle, and a negative reference voltage $(2V\Delta-)$ at Pin 7 sets the negative peak value of the triangle waveform. Since the value of the internal current source is fixed at a nominal $\pm 500~\mu A$, the oscillator period is a function of the selected peak-to-peak voltage excursion and the value of $C_{_T}$. The theoretical expression for the oscillator period is:

$$T_{\rm osc} = \frac{2C_{\rm T} dV}{5 \times 10^{-4}}$$
 (Eq.1)

where \mathbf{C}_{T} is the timing capacitor in Farads and dV is $\mathbf{V}_{\mathsf{OSC}}$ in Volts peak-to-peak.

As a design aid, the solutions to Equation 1 over the recommended range of T_{OSC} and V_{OSC} are given in graphic form in Figure 1. The lower limit on T_{OSC} is 1.85 μs , corresponding to a maximum frequency of 350 kHz. The maximum value of $V_{\text{OSC}},~(2V\Delta +)$ - $(2V\Delta -),~is~10~V$ peak-to-peak for linear waveforms.

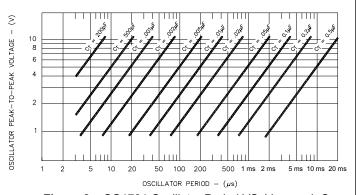


Figure 2 · SG1731 Oscillator Period VS. V_{OSC} and C_T

ERROR AMPLIFIER

The error amplifier of the SG1731 is a conventional internally-compensated operational amplifier with low output impedance. All of the usual feedback and frequency compensation techniques may be use to control the closed-loop gain characteristics. The control supply voltage $\pm V_{\rm S}$ will determine the input common mode range and output voltage swing; both will extend to within 3 V of the $V_{\rm S}$ supply.

PULSE WIDTH MODULATION

Pulse width modulation occurs by comparing the triangle waveform to a fixed upper (+ $V_{\scriptscriptstyle T}$) and lower (- $V_{\scriptscriptstyle T}$) threshold voltage. A crossing above the upper threshold causes Output A to switch to the HIGH state, and a crossing below



Application Information (Continued)

the lower threshold causes Output B to switch to the HIGH state. If $\pm V_s$ is less than ± 8 V then $\pm V_{\tau}$ can be obtained with resistors from $\pm V_s$. If $\pm V_s$ is greater than ± 8 V use zeners.

Threshold crossings are generated by shifting the triangle waveform up and down with the error voltage (Pin 5). A positive error voltage will result in a pulse width modulated output at Driver A (Pin 13). Similarly, a negative error voltage produces a pulse train at Driver B (Pin 12). Figure 2 illustrates this process for the case where $V_{\Delta}+$ is greater than $V_{\tau}.$

It is important to note that the triangle shifting circuit also attenuates the waveform seen at $C_{\scriptscriptstyle T}$ by a factor of 2. This results in a waveform at the PWM comparators with a positive peak of V $\!\Delta +$ and a negative peak of V $\!\Delta -$, and must be taken into account when selecting the values for +V $_{\scriptscriptstyle T}$ and -V $_{\scriptscriptstyle T}$.

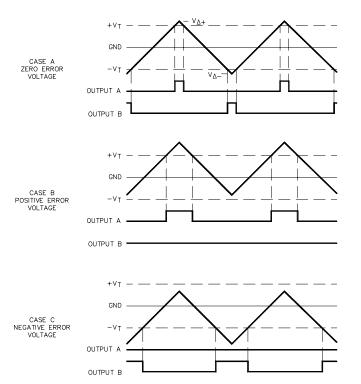
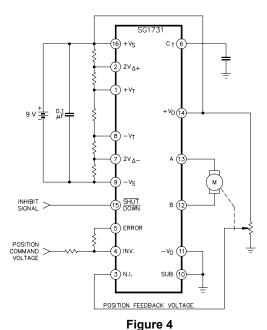


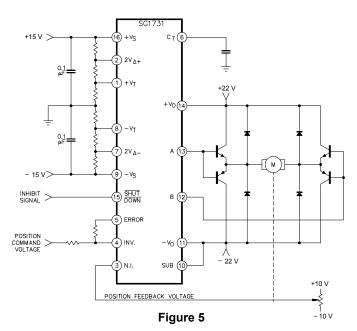
Figure 3 - Pulse Width Modulation with No Deadband

Application Circuits



rigure 4

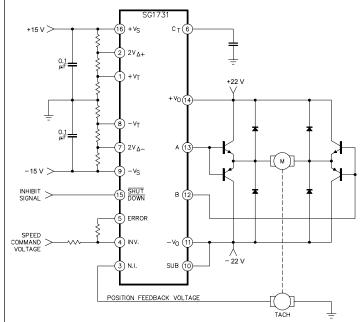
In this simple battery-powered position servo, the control supply and driver supply are both single-ended positive with respect to ground.



A high torque position servo is obtained by buffering the output drivers to obtain higher output current.



Application Circuits (Continued)



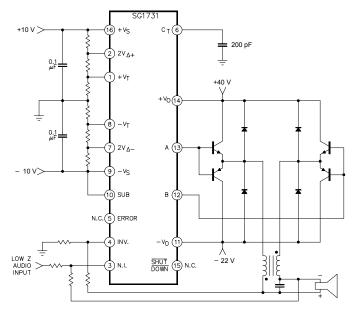


Figure 6

Bi-directional speed control results when the feedback voltage transducer is a tachometer.

Figure 7

The two-quadrant transfer function of the SG1731 is ideal for pulse width modulated audio power amplifiers.

Connection Diagrams & Ordering Information (See Notes Below)

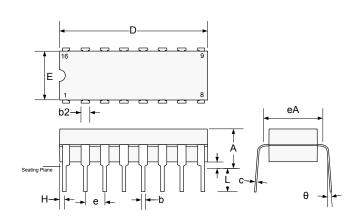
| Package | Part No. | Ambient Temperature Range | Connection Diagram |
|---|--|--|--|
| 16-PIN CERAMIC DIP J - PACKAGE | SG1731J- 883B SG1731J-DESC SG1731J | -55°C to 125°C -55°C to 125°C -55°C to 125°C | $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$ |
| 16-PIN PLASTIC DIP N - PACKAGE | SG3731N 0°C to 70°C N Package: F | | N Package: RoHS Compliant / Pb-free Transition DC: 0503 N Package: RoHS / Pb-free 100% Matte Tin Lead Finish |
| 20-PIN CERAMIC LEADLESS CHIP CARRIER L- PACKAGE | SG1731L SG1731L- 883B | -55°C to 125°C -55°C to 125°C | 1 NC 2 +VT 3 2VΔ+ 4 4 N.I.INPUT 5 5 INV.INPUT 6 6 NC 7 FERROR 8 CT 9 2VΔ- 10 -VT 1 NC 12 -VS 18 13 SUBSTRATE 14 -VO 17 15 OUTPUT B 16 16 NC 15 17 OUTPUT A 14 18 +VO 19 SHUTDOWN 20 +VS |

- Note 1. All packages are viewed from the top.
- Note 2. Contact factory for leadless chip carrier availability.
- Note 3. Hermetic Packages J, L use Sn63/Pb37 hot solder lead finish, Contact factory for availability of RoHS versions.



Package Outline Dimensions

Controlling dimensions are in inches, metric equivalents are shown for general information.

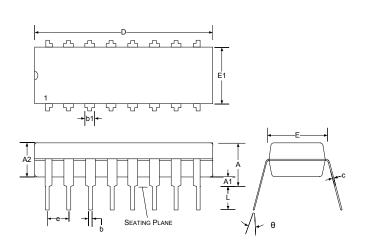


| DIM | MILLIMETERS | | INCHES | | |
|-----|-------------|-------|-----------|-------|--|
| DIN | MIN | MAX | MIN | MAX | |
| Α | - | 5.08 | 1 | 0.200 | |
| b | 0.38 | 0.51 | 0.015 | 0.020 | |
| b2 | 1.04 | 1.65 | 0.045 | 0.065 | |
| С | 0.20 | 0.38 | 0.008 | 0.015 | |
| D | 19.30 | 19.94 | 0.760 | 0.785 | |
| Е | 5.59 | 7.11 | 0.220 | 0.280 | |
| е | 2.54 | BSC | 0.100 BSC | | |
| eA | 7.37 | 7.87 | 0.290 | 0.310 | |
| Н | 0.63 | 1.78 | 0.025 | 0.070 | |
| L | 3.18 | 5.08 | 0.125 | 0.200 | |
| α | - | 15° | - | 15° | |
| Q | 0.51 | 1.02 | 0.020 | 0.040 | |

Note:

Dimensions do not include protrusions; these shall not exceed 0.155mm (.006") on any side. Lead dimension shall not include solder coverage.

Figure 8 · J 16-Pin Ceramic Dual Inline Package Dimensions



| DIM | MILLIMETERS | | INC | HES |
|-----|-------------|-----------|-------|--------|
| DIN | MIN | MAX | MIN | MAX |
| Α | - | 5.33 | - | 0.210 |
| A1 | 0.38 | - | 0.015 | 1 |
| A2 | 3.30 | Тур. | 0.13 | 0 Тур. |
| b | 0.36 | 0.56 | 0.014 | 0.022 |
| b1 | 1.14 | 1.78 | 0.045 | 0.070 |
| С | 0.20 | 0.36 | 0.008 | 0.014 |
| D | 18.67 | 19.69 | 0.735 | 0.775 |
| е | 2.54 | BSC 0.100 | |) BSC |
| E | 7.62 | 8.26 | 0.300 | 0.325 |
| E1 | 6.10 | 7.11 | 0.240 | 0.280 |
| L | 2.92 | 0.381 | 0.115 | 0.150 |
| θ | - | 15° | - | 15° |

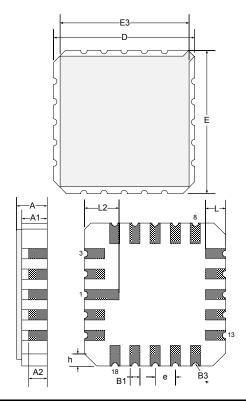
Note:

Dimensions do not include protrusions; these shall not exceed 0.155mm (.006") on any side. Lead dimension shall not include solder coverage.

Figure 9 · N 16-Pin Plastic Dual Inline Package Dimensions



Package Outline Dimensions (Continued)



| DIM | MILLIMETERS | | INCHES | | |
|-------|---------------------|-------|-----------|-------|--|
| DIIVI | MIN | MAX | MIN | MAX | |
| D/E | 8.64 | 9.14 | 0.340 | 0.360 | |
| E3 | - | 8.128 | 1 | 0.320 | |
| е | 1.270 BSC 0.050 BSC | | BSC | | |
| B1 | 0.635 TYP | | 0.025 TYP | | |
| L | 1.02 | 1.52 | 0.040 | 0.060 | |
| Α | 1.626 | 2.286 | 0.064 | 0.090 | |
| h | 1.016 TYP | | 0.040 TYP | | |
| A1 | 1.372 | 1.68 | 0.054 | 0.066 | |
| A2 | - | 1.168 | ī | 0.046 | |
| L2 | 1.91 | 2.41 | 0.075 | 0.95 | |
| В3 | B3 0.203R 0.008 | | 08R | | |

Note:

All exposed metalized area shall be gold plated 60 micro-inch minimum thickness over nickel plated unless otherwise specified in purchase order.

Figure 10 · L 20-Pin Ceramic LCC Package Outline Dimensions



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