

Digital Power Management IC 2MHz, 600mA DC/DC with Triple 300mA LDOs

General Description

The MIC2811/21 are high performance power management ICs, supporting four output voltage rails with maximum efficiency. The four rails are generated by a single 600mA DC/DC converter and three 300mA LDOs. LDO1 and LDO2 are capable of operating at a low input voltage down to 1.65V useful for post regulating the output voltage of the DC-DC converter. The MIC2811 supports the use of a bypass cap for improved noise performance on LDO1 & LDO2 while the MIC2821 offers a separate enable pin for LDO3.

Featuring an operating frequency of 2MHz, the DC to DC converter uses small values of L and C to reduce board space but still retains operating efficiencies up to 86% at load currents up to 600mA.

The MIC2811/21 feature a µCap design, operating with very small ceramic output capacitors and inductors for stability, reducing required board space and component cost and it is available in fixed output voltages in the 16 pin 3mm × 3mm MLF $^{\circ}$ leadless package.

Data sheets and support documentation can be found on Micrel's web site at: www.micrel.com.

Applications

- Mobile phones / PDAs
- Portable media players
- **Mobile Television Receivers**

__ **Typical Application**

Features

- 2MHz DC/DC converter and 3 LDOs
- Tiny 16-pin 3mm x 3mm MLF $^{\circ}$ package
- **Thermal Shutdown Protection**
- ±2% Output Voltage Accuracy on all outputs
- **Current Limit Protection**

DC/DC Converter

- 2.7V to 5.5V input voltage range
- Output current to 600mA
- 2MHz PWM operation
- Up to 86% efficiency (1.2V output)

LDO 1 & 2

- 1.65V to 5.5V input voltage range
- 300mA output current
- Fixed Output voltage as low as 0.8V
- Low 142mV dropout
- 70dB PSRR at 1kHz

LDO 3

- 2.7V to 5.5V input voltage range
- 300mA output current
- Fixed Output voltage as low as 1.0V

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Ordering Information

Note:

1. Output Voltage of DC/DC, LDO1, LDO2, LDO3 respectively

For additional voltage options, contact Micrel Marketing. Available fixed output voltage range for each output is as follows:

min max
DC/DC 1.0 2.0 1.0 2.0 (Adjustable output also available)
 0.8 3.6

LDO1 0.8 3.6

LDO2 0.8 3.6 $LDO3$

2. MLF is a GREEN RoHS compliant package. Lead finish is NiPdAu. Mold compound is Halogen Free.

Pin Configuration

Pin Description

Absolute Maximum Ratings(1)

Operating Ratings(2)

Electrical Characteristics(5)

 $DV_{IN} = V_{IN} = V_{IN1} = V_{IN2} = V_{OUTMAX} + 1V, L = 2.2 \mu H; C_{OUTDC/DC} = 2.2 \mu F, C_{OUT1} = C_{OUT2} = C_{OUT3} = 2.2 \mu F; I_{OUTDC/DC} = 20 mA;$ I_{OUTLDO1} = I_{OUTLDO2} = I_{OUTLDO2} = 100μA; T_J = 25°C, **bold** values indicate -40°C < T_J < +125°C; unless noted.

Electrical Characteristics - DC/DC Converter

 $DV_{IN} = V_{IN} = V_{EN} = V_{\text{OUTDC/DC}} + 1V$, L = 2.2µH; $C_{\text{OUTDC/DC}} = 2.2\mu$ F, $C_{\text{OUT1}} = C_{\text{OUT2}} = C_{\text{OUT3}} = 2.2\mu$ F; $I_{\text{OUTDC/DC}} = 20\text{mA}$; T_J = 25°C, **bold** values indicate -40° C to + 125°C; unless noted.

Electrical Characteristics - LDO1 and LDO2

VIN = DVIN = VOUTMAX + 1V, VIN1 = VEN1 = VLDO1 + 1V; VIN2 = VEN2 = VLDO2 + 1V ; COUTLDO1 = COUTLDO2 = 2.2µF, ILDO1 = ILDO2 = 100µA; TJ = 25°C, V_{EN} = V_{EN3} = GND, **bold** values indicate –40°C<u>< TJ <</u> +125°C; unless noted.

Electrical Characteristics – LDO3

 $V_{IN} = DV_{IN} = V_{EN3} = V_{LDO3} + 1$ V; $C_{OUT3} = 2.2 \mu F$; $I_{OUTLDO3} = 100 \mu A$; $T_J = 25$ °C, $V_{EN1} = V_{EN2} = GND$

bold values indicate -40° C \leq T_J \leq +125°C; unless noted.

Notes:

1. Exceeding the absolute maximum rating may damage the device.

- 2. The device is not guaranteed to function outside its operating rating.
- 3. The maximum allowable power dissipation of any T_A (ambient temperature) is P_{D(max)} = $(T_{J(max)} T_A) / \theta_{JA}$. Exceeding the maximum allowable power dissipation will result in excessive die temperature, and the regulator will go into thermal shutdown.

4. Devices are ESD sensitive. Handling precautions recommended. Human body model, 1.5k in series with 100pF.

5. Specification for packaged product only.

Typical Characteristics (DC/DC Converter)

Typical Characteristics (LDO)

MIC2811 LDO3 PSRR

MIC2811 LDO3 Output Noise Spectral Density

LDO3

LDO2 Line Regulation

Typical Characteristics (LDO cont.)

Functional Characteristics (DC/DC Converter)

Functional Characteristics (LDO)

TIME (100ps/div)

1mA

Functional Diagram

Block Diagram

Applications Information

The MIC2811 and MIC2821 are power management ICs with a single integrated step-down regulator and three low dropout regulators. LDO1, LDO2, and LDO3 are 300mA low dropout regulators supplied by their own independent input voltage pins. The supply to LDO3 (V_{IN}) also powers the bias circuitry and must be available for any output to be operational. This supply requires an external connection to DVIN. The step-down regulator is a 2MHz 600mA PWM power supply, using small values of L and C operating at over 90% efficiency.

DVIN/VIN/VIN1/VIN2

All four regulators, the switch mode regulator, LDO1, LDO2, and LDO3 have their own unique input voltage supply pin. VIN provides power to LDO3 and internal circuitry shared by all the regulators and therefore must be available for any of the regulators to operate properly. DVIN and VIN must be tied together and have a minimum input voltage of 2.7V. Inputs to LDO1 (VIN1) and LDO2 (VIN2) can go as low as 1.65V, but should never exceed the VIN and DVIN input voltage. Due to the high switching speeds, a 1µF input capacitor is recommended close to the DVIN, decoupled to the PGND pin.

LDO1

Regulated output voltage of LDO1. Power is provided by VIN1 and enabled through EN1. Recommended output capacitance is 2.2µF, decoupled to the SGND pin.

LDO2

Regulated output voltage of LDO2. Power is provided by VIN2 and enabled through EN2. Recommended output capacitance is 2.2µF, decoupled to the SGND pin.

LDO3

Regulated output voltage of LDO3. Power is provided by VIN and enabled through EN (MIC2811) or EN3 (MIC2821). Recommended output capacitance is 2.2µF, decoupled to the SGND pin.

SW

The switch (SW) pin connects directly to the inductor and provides the switching current necessary to operate in PWM mode. Due to the high speed switching on this pin, the switch node should be routed away from sensitive nodes.

DC/DC Output Capacitor

The DC/DC regulator requires an output capacitor for proper operation. Values of greater than 2.2µF improve transient response and noise reduction at high frequency. X7R/X5R dielectric-type ceramic capacitors are recommended because of their superior temperature

performance. X7R-type capacitors change capacitance by 15% over their operating temperature range and are the most stable type of ceramic capacitors. Z5U and Y5V dielectric capacitors change value by as much as 50% to 60% respectively over their operating temperature ranges and for that reason are not recommended. Larger output capacitances can be achieved by placing tantalum or aluminum electrolytics in parallel with the ceramic capacitor. For example, a 100µF electrolytic in parallel with a 10µF ceramic can provide the transient and high frequency noise performance of a 100µF ceramic at a significantly lower cost. Specific undershoot/overshoot performance will depend on both the values and ESR/ESL of the capacitors.

Inductor Selection

Inductor selection will be determined by the following (not necessarily in the order of importance);

- **Inductance**
- Rated current value
- Size requirements
- DC resistance (DCR)

The MIC2811 and MIC2821 are designed for use with a 2.2µH inductor. Maximum current ratings of the inductor are generally given in two methods; permissible DC current and saturation current. Permissible DC current can be rated either for a 40°C temperature rise or a 10% to 20% loss in inductance. Ensure the inductor selected can handle the maximum operating current. When saturation current is specified, make sure that there is enough margin that the peak current will not saturate the inductor. Peak inductor current can be calculated as follows:

$$
I_{PK} = I_{OUT} + \frac{V_{OUT}(1 - \frac{V_{OUT}}{V_N})}{2 \times f \times L}
$$

The size requirements refer to the area and height requirements that are necessary to fit a particular design. Please refer to the inductor dimensions on their datasheet.

DC resistance is also important. While DCR is inversely proportional to size, DCR can represent a significant efficiency loss.

Efficiency Considerations

Efficiency is defined as the amount of useful output power, divided by the amount of power supplied.

$$
Efficiency_{0} = \left(\frac{Vout \times lout}{Vin \times lin}\right) \times 100
$$

Maintaining high efficiency serves two purposes. It reduces power dissipation in the power supply, reducing the need for heat sinks and thermal design considerations and it reduces consumption of current for battery powered applications. Reduced current draw from a battery increases the devices operating time and is critical in hand held devices.

There are two types of losses in switching converters; DC losses and switching losses. DC losses are simply the power dissipation of I^2R . Power is dissipated in the high side switch during the on cycle. Power loss is equal to the high side MOSFET R_{DSON} multiplied by the Switch Current². During the off cycle, the low side N-channel MOSFET conducts, also dissipating power. Device operating current also reduces efficiency. The product of the quiescent (operating) current and the supply voltage is another DC loss.

Over 100mA, efficiency loss is dominated by MOSFET R_{DSON} and inductor losses. Higher input supply voltages will increase the Gate to Source threshold on the internal MOSFETs, reducing the internal R_{DSON} . This improves efficiency by reducing DC losses in the device. All but the inductor losses are inherent to the device. In which case, inductor selection becomes increasingly critical in efficiency calculations. As the inductors are reduced in size, the DC resistance (DCR) can become quite significant. The DCR losses can be calculated as follows:

$$
L_Pd = Iout^2 \times DCR
$$

From that, the loss in efficiency due to inductor resistance can be calculated as follows;

$$
Efficiency_Loss = \left[1 - \left(\frac{Vout \times lout}{Vout \times lout + L_Pd}\right)\right] \times 100
$$

Efficiency loss due to DCR is minimal at light loads and gains significance as the load is increased. Inductor selection becomes a trade-off between efficiency and size in this case.

PGND

Power ground (PGND) is the ground path for the high current PWM mode. The current loop area for the power ground should be as small as possible.

SGND

Signal ground (SGND) is the ground path for the biasing and control circuitry. The current loop for the signal ground should be as small as possible.

BYP (MIC2811 only)

For enhanced noise and PSRR performance on LDO1 & LDO2, the internal reference of the MIC2811 can be bypassed with a capacitor to ground. A quick-start feature allows for quick turn-on of the output voltage. The recommended nominal bypass capacitor is 0.1µF, but it can be increased, which will also result in an increase to the start-up time.

MIC2811 Layout Recommendations

A poor layout of the MIC2811 may cause unwanted voltage and current spikes. This can lead to noise on DC voltages and EMI radiating to nearby devices. The following are recommendations for the MIC2811/21 layout. The evaluation board layout is included as an example.

1. Place the MIC2811/21 with the pad size designated in the "Recommended Land Patterns" page of the Micrel website.

2. When laying out the components, keep the MIC2811, inductor, and filter capacitors physically close to keep traces as short as possible. The traces between these components carry relatively high switching currents and can affect adjacent signals.

3. The input capacitor between DVIN and PGND should be placed right next to the MIC2811/21. This will eliminate trace inductance effects and reduce internal noise for the MIC2811/21 control circuitry. The trace from the DVIN filter capacitor to the MIC2811/21 device should not be routed through any vias. This lessens the chance of noise coupling by the effective antenna of the via.

4. Monitoring the path of the switching currents will help minimize the radiated noise. In the first half of the switching cycle, current flows from the input filter capacitor through the high side switch within the MIC2811, then through the inductor to the output filter capacitor and lastly through ground. In the second half of the switching cycle, current is pulled up from ground through the low side synchronous switch within the MIC2807 by the inductor, to the output filter capacitor and then back through ground, forming a second current loop. Route these loops to ensure the current curls in the same direction, preventing magnetic field reversal between the switching cycles.

5. Connect the Bypass capacitor (MIC2811 Only) to the BYP pin and the AGND pin. AGND and PGND should be connected close to the chip at a single point in order to minimize undesirable behavior due to ground bounce. Input and output filter capacitors should be connected to PGND.

6. Connections between power components and the MIC2811 should have wide traces. It is good practice to use a minimum of 30mils (0.762mm) per Ampere for 1oz copper weight.

7. Route noise sensitive traces such as Feedback (FB), BIAS, and BYP away from the switching traces and the inductor. Noise coupled into these pins can affect the accuracy of the output. The Feedback pin should be connected at point of load for an accurate load regulation.

MIC2811/2821-YML Schematic

Bill of Materials

Notes:

1. AVX: www.avx.com

2. Murata: www.murata.com

3. TDK: www.tdk.com

4. Vishay: www.vishay.com

5. Taiyo Yuden: www.t-yuden.com

6. Sumida: www.sumida.com

7. Coilcraft: www.coilcraft.com

8. Micrel, Inc.: www.micrel.com

PCB Layout Recommendations

Top Layer

Bottom Layer

Package Information

16-Pin 3mm x 3mm MLF® (ML)

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