

# CMOS 220 MHz True-Color Graphics Triple 10-Bit Video RAM-DAC

# ADV7152

#### FEATURES



**APPLICATIONS** 



#### REV. B

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# $\begin{array}{l} \textbf{ADV7152-SPECIFICATIONS}_{(V_{AA}^{1}=\ +\ 5\ V;\ V_{REF}=\ +\ 1.235\ V;\ R_{SET}=\ 280\ \Omega.\ \text{IOR, IOG, IOB}\ (R_{L}=\ 37.5\ \Omega, C_{L}=\ 10\ \text{pF}); \\ \hline \textbf{IOR, IOG, IOB}=\ \text{GND. All specifications}\ T_{MIN}\ \text{to}\ T_{MAX}^{2}\ \text{unless otherwise noted.}) \end{array}$

Parameter	All Versions	Unit	Test Conditions/Comments
STATIC PERFORMANCE			
Resolution (Each DAC)	10	Bits	
Accuracy (Each DAC)			
Integral Nonlinearity	±1	LSB max	
Differential Nonlinearity	±1	LSB max	Guaranteed Monotonic
Gray Scale Error	±5	% Gray Scale max	
Coding		Binary	
DIGITAL INPUTS (Excluding CLOCK, CLOCK)			
Input High Voltage, V <sub>INH</sub>	2	V min	
Input Low Voltage, VINI	0.8	V max	
Input Current, I <sub>IN</sub>	±10	uA max	$V_{IN} = 0.4 V \text{ or } 2.4 V$
Input Capacitance, $C_{IN}$	10	pF typ	
$\frac{1}{CLOCK}$			
Input High Voltage	V. 10	Vmin	
Input I ow Voltage Vous	$V_{AA} = 1.0$ $V_{AA} = 1.6$	V max	
Input Current Inc	+10		$V_{\rm res} = 0.4 \mathrm{V}$ or $2.4 \mathrm{V}$
Input Canacitance Car	10	nF typ	$v_{\rm IN} = 0.4$ v or 2.4 v
		prtyp	
DIGITAL OUTPUTS	$ \langle \rangle \rangle$		L 400 A
Output High Voltage, Volt	$\left  \right ^{2.4} $	V <sup>m</sup>	$I_{\text{SOURCE}} = 400 \mu\text{A}$
Output Low Voltage, Vol	$\left  \left( \begin{array}{c} 0.4 \\ 2d \end{array} \right) \right $	max	$I_{\text{SINK}} = 3.2 \text{ mA}$
Floating-State Leakage Current		$\mu A max$	
Floating-State Output Capacitance		pF/typ	
ANALOG OUTPUTS			
Gray Scale Current Range	15/22	mA min/max	
Output Current			
White Level Relative to Blank	17.69/20.40	mA min/max	Typically 19.05 mA
White Level Relative to Black	16.74/18.50	mA min/max	Typically 17.62 mA
Black Level Relative to Blank	0.95/1.90	mA min/max	Typically 1.44 m.4
Blank Level on IOR, IOB	0/50	μA min	Typically 5 μA
Blank Level on IOG	6.29/8.96	mA min/max	Typically 7.62 mA
Sync Level on IOG	0/50	$\mu A m n/m ax$	Typically 5 $\mu$ A
LSB Size	17.22	μA typ	
DAC-to-DAC Matching	3	% max	Typically 1%
Output Compliance, V <sub>OC</sub>	0/+1.4	V min/V max	
Output Impedance, R <sub>OUT</sub>	100	$k\Omega$ typ	
Output Capacitance, C <sub>OUT</sub>	30	pFmax	$I_{OUT} = 0 \text{ mA}$
VOLTAGE REFERENCE			
Voltage Reference Range, V <sub>REF</sub>	1.14/1.26	V min/V max	$V_{REF} = 1.235$ V for Specified Performance
Input Current, I <sub>VREF</sub>	+5	μA typ	
POWER REQUIREMENTS			
$V_{AA}$	5	V nom	
$I_{AA}{}^3$	400	mA max	220 MHz Parts
I <sub>AA</sub>	370	mA max	170 MHz Parts
I <sub>AA</sub>	350	mA max	135 MHz Parts
I <sub>AA</sub>	330	mA max	110 MHz Parts
I <sub>AA</sub>	315	mA max	85 MHz Parts
Power Supply Rejection Ratio	0.5	%/% max	Typically $0.12\%$ /%, COMP = $0.1 \mu$ F
DYNAMIC PERFORMANCE			
Clock and Data Feedthrough <sup>4, 5</sup>	-30	dB typ	
Glitch Impulse	50	pV secs typ	
DAC-to-DAC Crosstalk <sup>6</sup>	-23	dB typ	

NOTES

 $^{1}\pm5\%$  for all versions.

<sup>2</sup>Temperature range (T<sub>MIN</sub> to T<sub>MAX</sub>): 0°C to +70°C; T<sub>J</sub> (Silicon Junction Temperature)  $\leq 100$ °C. <sup>3</sup>Pixel Port is continuously clocked with data corresponding to a linear ramp. T<sub>J</sub> = 100°C.

<sup>4</sup>Clock and data feedthrough is a function of the amount of overshoot and undershoot on the digital inputs. Glitch impulse includes clock and data feedthrough. <sup>5</sup>TTL input values are 0 to 3 volts, with input rise/fall times ≤ 3 ns, measured the 10% and 90% points. Timing reference points at 50% for inputs and outputs.

<sup>6</sup>DAC-to-DAC crosstalk is measured by holding one DAC high while the other two are making low-to-high and high-to-low transitions.

Specifications subject to change without notice.

**TIMING CHARACTERISTICS**<sup>1</sup>  $(V_{AA}^2 = +5 \text{ V}; V_{REF} = +1.235 \text{ V}; R_{SET} = 280 \Omega. \text{ IOR, IOG, IOB} (R_L = 37.5 \Omega, C_L = 10 \text{ pF});$  $\overline{IOR}$ ,  $\overline{IOB}$  = GND. All specifications T<sub>MIN</sub> to T<sub>MAX</sub><sup>3</sup> unless otherwise noted.)

#### **CLOCK CONTROL AND PIXEL PORT<sup>4</sup>** 220 MHz 170 MHz 135 MHz 110 MHz 85 MHz Version Parameter Version Version Version Version Units Conditions/Comments 170 135 MHz max 220 110 85 Pixel CLOCK Rate **f**CLOCK 4.55 5.88 7.4 9.1 11.77 ns min Pixel CLOCK Cycle Time $t_1$ $t_2$ 2 2.5 3 4 4 ns min Pixel CLOCK High Time 2 2.5 3.2 4 4 Pixel CLOCK Low Time t<sub>3</sub> ns min 10 10 10 10 10 ns max Pixel CLOCK to LOADOUT Delay $t_4$ LOADIN Clocking Rate f<sub>loadin</sub> 1:1 Multiplexing 110 110 110 110 85 MHz max 2:1 Multiplexing 110 85 67.5 55 42.5 MHz max LOADIN Cycle Time 1:1 Multiplexing 9.1 9.1 9.1 11.76 ns min 2:1 Multiplexing 9.1 11.76 14.8 18.18 23.53 ns min LOADIN High Time $t_6$ 1:1 Multiplexing 4 4 4 ns min 2:1 Multiplexin 5 8 9 6 ns min LOADIN Low Time 1:1 Multiplexing 4 4 4 4 ns m/in 8 9 2:1 Multiplexing 4 ns m/in Pixel Data Setup Time 0 0 d 0 ns min $t_8$ 5 5 Pixel Data Hold Time 5 t9 5 ns/min 0 LØADOUT to LOADIN Delay 0 0 n¢ min $t_{10}$ $\tau - t_{11}^{5}$ ns max LOADOUT to LOAD IN τ-5 τ-5 τ-5 τ-5 -5 Delay Pipeline IØelak∕ t<sub>PD</sub><sup>6</sup> CLOCK $\times CL \phi C \mathbf{k} = t_1$ 1:1 Multiplexing 5 5 5 5 5 2:1 Multiplexing 6 6 6 6 **CLOCKs** 6 Pixel CLOCK to PRGCROUT Delay 10 10 10 10 10 ns max $t_{12}$ 5 5 5 5 5 ns max SCKIN to SCKOUT Delay t<sub>13</sub> 5 5 5 5 5 ns min BLANK to SCKIN Setup Time $t_{14}$ 1 1 1 1 1 ns min BLANK to SCKIN Hold Time $t_{15}$

### **ANALOG OUTPUTS<sup>7</sup>**

Parameter	220 MHz Version	170 MHz Version	135 MHz Version	110 MHz Version	85 MHz Version	Units	Conditions/Comments
t <sub>16</sub>	15	15	15	15	15	ns typ	Analog Output Delay
t <sub>17</sub>	1	1	1	1	1	ns typ	Analog Output Rise/Fall Time
t <sub>18</sub>	15	15	15	15	15	ns typ	Analog Output Transition Time
t <sub>SK</sub>	2	2	2	2	2	ns max	Analog Output Skew (IOR, IOG, IOB)
	0	0	0	0	0	ns typ	

#### MPU PORTS<sup>8,9</sup>

Parameter	220 MHz Version	170 MHz Version	135 MHz Version	110 MHz Version	85 MHz Version	Units	Conditions/Comments
t <sub>19</sub>	3	3	3	3	3	ns min	$R/\overline{W}$ , C0, C1 to $\overline{CE}$ Setup Time
t <sub>20</sub>	10	10	10	10	10	ns min	$R/\overline{W}$ , C0, C1 to $\overline{CE}$ Hold Time
t <sub>21</sub>	45	45	45	45	45	ns min	$\overline{\text{CE}}$ Low Time
t <sub>22</sub>	25	25	25	25	25	ns min	CE High Time
$t_{23}^{8}$	5	5	5	5	5	ns min	$\overline{CE}$ Asserted to Databus Driven
$t_{24}^{9}$	45	45	45	45	45	ns max	$\overline{\text{CE}}$ Asserted to Data Valid
$t_{25}^{9}$	20	20	20	20	20	ns max	$\overline{CE}$ Disabled to Databus Three-Stated
	5	5	5	5	5	ns min	
t <sub>26</sub>	20	20	20	20	20	ns min	Write Data (D0–D9) Setup Time
t <sub>27</sub>	5	5	5	5	5	ns min	Write Data (D0–D9) Hold Time

NOTES

<sup>1</sup>TTL input values are 0 to 3 volts, with input rise/fall times  $\leq$  3 ns, measured between the 10% and 90% points. ECL inputs (CLOCK, <u>CLOCK</u>) are V<sub>AA</sub>-0.8 V to V<sub>AA</sub>-1.8 V, with input rise/fall times  $\leq$  2 ns, measured between the 10% and 90% points. Timing reference points at 50% for inputs and outputs. Analog output load  $\leq$  10 pF. Databus (D0-D9) loaded as shown in Figure 1. Digital output load for LOADOUT, PRGCKOUT, SCKOUT, I<sub>PLL</sub> and SYNCOUT  $\leq$  30 pF.

 $^{2}\pm5\%$  for all versions.

<sup>3</sup>Temperature range (T<sub>MIN</sub> to T<sub>MAX</sub>): 0°C to +70°C; T<sub>J</sub> (Silicon Junction Temperature)  $\leq 100$ °C.

<sup>4</sup>Pixel Port consists of the following inputs: Pixel Inputs: RED [A, B]; GREEN [A, B]; BLUE [A, B], Palette Selects: PS0 [A, B]; PS1 [A, B]; Pixel Controls:

 $\overline{\text{SYNC}}$ ,  $\overline{\text{BLANK}}$ ; Clock Inputs: CLOCK,  $\overline{\text{CLOCK}}$ , LOADIN, SCKIN; Clock Outputs: LOADOUT, PRGCKOUT, SCKOUT. <sup>5</sup> $\tau$  is the LOADOUT Cycle Time and is a function of the Pixel CLOCK Rate and the Multiplexing Mode: 1:1 multiplexing;  $\tau = \text{CLOCK} = t_1$  ns; 2:1 multiplexing,  $\tau = \text{CLOCK} \times 2 = 2 \times t_1$  ns.

<sup>6</sup>These fixed values for Pipeline Delay are valid under conditions where  $t_{10}$  and  $\tau_{-}t_{11}$  are met. If either  $t_{10}$  or  $\tau_{-}t_{11}$  are not met, the part will operate but the Pipeline Delay is increased by 2 clock cycles for 2:1 mode after calibration cycle is performed.

<sup>7</sup>Output delay measured from the 50% point of the rising edge of CLOCK to the 50% point of full-scale transition. Output rise/fall time measured between the 10% and 90% points of full-scale transition. Settling time measured from the 50% point of full-scale transition to the output remaining within  $\pm 1$  LSB. (Settling time does not include clock and data feedthrough.)

 ${}^{8}t_{23}$  and  $t_{24}$  are measured with the load circuit of Figure 1 and defined as the time required for an output to cross 0.4 V or 2.4 V.

 $^{9}t_{25}$  is derived from the measured time taken by the data outputs to change by 0.5 V when loaded with the circuit of Figure 1. The measured number is then extrapolated back to remove the effects of charging the 100 pF capacitor. This means that the time,  $t_{25}$ , quoted in the Timing Characteristics is the true value for the device and as such is independent of external databus loading capacitances.



Figure 3. LOADIN vs. Pixel Input Data



\*INCLUDES PIXEL DATA (R0-R7, G0-G7, B0-B7); PALETTE SELECT INPUTS (PS0-PS1); SYNC; BLANK

Figure 5. Pixel Input to Analog Output Pipeline with Maximum LOADOUT to LOADIN Delay (2:1 Multiplex Mode)



\*INLCUDES PIXEL DATA (R0-R7, G0-G7, B0-B7); PALETTE SELECT INPUTS (PS0-PS1); SYNC; BLANK





Figure 7. Video Data Shift Clock Input (SCKIN) & BLANK vs. Video Data Shift Clock Output (SCKOUT)





Figure 9. Microprocessor Port (MPU) Interface Timing

# RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Min	Тур	Max	Units
Power Supply Ambient Operating Temperature		4.75	5.00	5.25 +70	Volts °C
Reference Voltage	V <sub>REF</sub>	1.14	1.235	1.26	Volts
Output Load	R <sub>L</sub>		37.5		Ω

#### CAUTION\_

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the ADV7152 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.





NC = NO CONNECT.

# PIN FUNCTION DESCRIPTION

Mnemonic	Function				
$\begin{array}{c} \hline RED \ (R0_A \ldots R0_B - R7_A \ldots R7_B), \\ GREEN \ (G0_A \ldots G0_B - G7_A \ldots G7_B), \\ BLUE \ (B0_A \ldots B0_B - B7_A \ldots B7_B) \end{array}$	Pixel Port (TTL Compatible Inputs). 48 pixel select inputs, with 8 bits each for Red, 8 bits for Green and 8 bits for Blue. Each bit is multiplexed [A-B] 2:1 or 1:1. It can be configured for 24-Bit True-Color Data, 8-Bit Pseudo-Color Data and 15-Bit True-Color Data formats. Pixel Data is latched into the device on the rising edge of LOADIN.				
$PS0_A \dots PS0_B, PS1_A \dots PS1_B$	Palette Priority Selects (TTL Compatible Inputs): These pixel port select inputs deter- mine whether or not the device's pixel data port is selected on a pixel by pixel basis. The palette selects allow switching between multiple palette devices. The device can be pre- programmed to completely shut off the DAC analog outputs. If the values of PS0 and PS1 match the values programmed into bits MR16 and MR17 of the Mode Register, then the device is selected. Each bit is multiplexed [A-B] 2:1 or 1:1. PS0 and PS1 are latched into the device on the rising edge of LOADIN				
LOADIN	Pixel Data Load Input (TTL Compatible Input). This input latches the multiplexed pixel data, including PS0–PS1, BLANK and SYNC into the device.				
	Pixel Data Load Output (TTL Compatible Output). This output control signal runs at a divided down frequency of the pixel CLOCK input. Its frequency is a function of the multiplex rate. It can be used to directly or indirectly drive LOADIN				
	where $M = 1$ for 1:1 Multiplek Mode) (M = 2 for 2:1 Multiplex Mode).				
PRGCKOUT	Programmable Clock Ou/put (TIL Compatible Output). This output control signal runs at a divided down frequency of the pixel CLOCK input. Its frequency is user programmable and is determined by bits CK30 and CR31 of Command Register/3				
	$f_{PRGCKOU} = f_{CLOCK}$ where $N = 4, 8, 16$ and 32.				
SCKIN	Video Shift Clock Input (TTL Compatible Input). The signal on this input is internally gated synchronously with the BLANK signal. The resultant output, SCKOUT, is a video clocking signal that is stopped during video blanking periods.				
SCKOUT	Video Shift Clock Output (TTL Compatible Output). This output is a synchronously gated version of SCKIN and BLANK. SCKOUT, is a video clocking signal that is stopped during video blanking periods.				
CLOCK, <u>CLOCK</u>	Clock Inputs (ECL Compatible Inputs). These differential clock inputs are designed to be driven by ECL logic levels configured for single supply (+5 V) operation. The clock rate is normally the pixel clock rate of the system.				
BLANK	Composite Blank (TTL Compatible Input). This video control signal drives the analog outputs to the blanking level.				
SYNC	Composite-Sync Input (TTL Compatible Input). This video control signal drives the IOG analog output to the SYNC level. It is only asserted during the blanking period. CR22 in Command Register 2 must be set if SYNC is to be decoded onto the analog output, otherwise the SYNC input is ignored.				
SYNCOUT	Composite SYNC O/P (TTL Compatible Output). This video output is a delayed version of SYNC. The delay corresponds to the number of pipeline stages of the device.				
D0-D9	Databus (TTL Compatible Input/Output Bus). Data, including color palette values and device control information is written to and read from the device over this 10-bit, bidirectional databus. 10-bit data or 8-bit data can be used. The databus can be configured for either 10-bit parallel data or byte data (8+2) as well as standard 8-bit data. Any unused bits of the databus should be terminated through a resistor to either he digital power plane ( $V_{CC}$ ) or GND.				
CE	Chip Enable (TTL Compatible Input). This input must be at Logic "0" when writing to or reading from the device over the databus (D0–D9). Internally, data is latched on the rising edge of $\overline{CE}$ .				

Mnemonic	Function
R/W	Read/Write Control (TTL Compatible Input). This input determines whether data is written to or read from the device's registers and color palette RAM. $R/\overline{W}$ and $\overline{CE}$ must be at Logic "0" to write data to the part. $R/\overline{W}$ must be at Logic "1" and $\overline{CE}$ at Logic "0" to read from the device.
C0, C1	Command Controls (TTL Compatible Inputs). These inputs determine the type of read or write operation being performed on the device over the databus (see Interface Truth Table). Data on these inputs is latched on the falling edge of $\overline{CE}$ .
$\frac{\text{IOR}}{\text{IOB}}; \overline{\text{IOR}}, \text{IOG}; \overline{\text{IOG}}, \text{IOB}; \overline{\text{IOB}}$	Red, Green and Blue Current Outputs (High Impedance Current Sources). These RGB video outputs are specified to directly drive RS-343A and RS-170 video levels into doubly terminated 75 $\Omega$ loads.
$\frown$	$\overline{IOR}$ , $\overline{IOG}$ and $\overline{IOB}$ are the complementary outputs of IOR, IOG and IOB. These outputs can be tied to GND if it is not required to use differential outputs.
	Voltage Reference Input (Analog Input). An external 1.235 V voltage reference is re- quired to drive this input. An AD589 (2-terminal voltage reference) or equivalent is rec- ommended. (Note: It is not recommended to use a resistor network to generate the voltage reference.)
R <sub>SET</sub>	output Full-Scale Adjust Control (Analog Input). A resistor connected between this pin and analog ground controls the absolute amplitude of the output video signal. The value of R <sub>SET</sub> is derived from the full-scale output current on IOG according to the following equations:
	$R_{SET}(\Omega) = C1 \times R_{REF}/IOG(mA); SYNC \text{ on } GREEN$ $R_{SET}(\Omega) = C2 \times R_{REF}/IOG(mA); No SYNC \text{ on } GREEN.$
	Full-Scale output currents on IOR and IOB for a particular value of R <sub>SER</sub> are given by
	and $IOR (mA) = C2 \times R_{REE}(V)/R_{SET}(\Omega)$ $IOR (mA) = C2 \times R_{REE}(V)/R_{SET}(\Omega)$
	where $C1 = 6,050$ : PEDESTAL = 7.5 IRE = 5,723: PEDESTAL = 0 IRE
	and
	C2 = 4,323: PEDESTAL = 7.5 IRE = 3,996: PEDESTAL = 0 IRE.
СОМР	Compensation Pin. A 0.1 $\mu$ F capacitor should be connected between this pin and V <sub>AA</sub> .
I <sub>PLL</sub>	Phase Lock Loop Output Current (High Impedance Current Source). This output is used to enable multiple ADV7150/ADV7152s along with ADV7151s to be synchronized together with subpixel resolution when using an external PLL. This output is triggered either from the falling edge of SYNC or BLANK as determined by bit CR21 of Com- mand Register 2. When activated, it supplies a current corresponding to
	$I_{PLL}(mA) = 1,728 \times R_{REF}(V)/R_{SET}(\Omega)$
	When not using the $I_{PLL}$ function, this output pin should be tied to GND.
V <sub>AA</sub>	Power Supply (+5 V $\pm$ 5%). The part contains multiple power supply pins, all should be connected together to one common +5 V filtered analog power supply.
GND	Analog Ground. The part contains multiple ground pins, all should be connected together to the system's ground plane.

#### (Continued from page 1)

applications. The part is controlled and programmed through the microprocessor (MPU) port. The part also contains a number of onboard test registers, associated with self diagnostic testing of the device.

The individual Red, Green and Blue pixel input ports allow True-Color, image rendition. True-Color image rendition, at speeds of up to 220 MHz, is achieved through the use of the onboard data multiplexer/serializer. The pixel input ports flexibility allows for direct interface to most standard frame buffer memory configurations.

The 30 bits of resolution, associated with the color look-up table and triple 10-bit DAC, realizes 24-bit True-Color resolution, while also allowing for the onboard implementation of linearization algorithms, such as Gamma-Correction. This allows offective 30-bit True-Color operation.

The on-chip yideo clock controller circuit generates all the internal clocking and some additional external clocking signals.

# CIRCUIT DETAILS AND ORERATIO

Digital video or pixel data is latched into the AD V715 over the devices Pixel Port. This data acts as a pointer to the onboard Color Palette RAM. The data at the RAM address pointed to is latched into the digital-to-analog converters (DACs) and output as an RGB analog video signal.

For the purposes of clarity of description, the AD V7152 is broken down into three separate functional blocks. These are:

- 1. Pixel port and clock control circuit
- 2. MPU port, registers and color palette
- 3. Digital-to-analog converters and video outputs

Table I shows the architectural and packaging differences between other devices in the AD V715x series of workstation parts. (For more details consult the relevant data sheets.)

# Table I. Architectural and Packaging Differences of the ADV715x Series

Description	AD V7150*	AD V7152	AD V7151*
24-Bit "Gamma" True Color	•	•	
24-Bit "Standard" True Color	•	•	
8-Bit "Gamma" Pseudo Color	•	•	•
8-Bit "Standard" Pseudo Color	•	•	•
15-Bit True Color	•	•	
220 MHz – True Color	•	•	
220 MHz – Pseudo Color	•	•	•
Triple 10-Bit DACs	•	•	•
4:1 Multiplexing	•		•
2:1 Multiplexing	•	•	•
1:1 Multiplexing	•	•	•
160-Lead QFP	•		
100-Lead QFP		•	•

\*See ADV7151 and ADV7150 data sheets for more information on these parts.

An external ECL oscillator source with differential outputs is all that is required to drive the CLOCK and  $\overline{\text{CLOCK}}$  inputs of the ADV7152. The part can also be driven by an external clock generator chip circuit, such as the AD730.

The ADV7152 is capable of generating RGB video output signals which are compatible with RS-343A and RS-170 video standards, without requiring external buffering.

Test diagnostic circuitry has been included to complement the users system level debugging.

The ADV7152 is fabricated in a +5 V CMOS process. Its monolithic CMOS construction ensures greater functionality with low power dissipation.

The ADV7152 is packaged in a plastic 100-pin power quad flatpack (QFP). Superior thermal dissipation is achieved by inclusion of a copper heatslug, within the standard package outline to which the die is attached.

# Pixel Port and Clock Control Circuit

The Pixel Port of the AD V7152 is directly interfaced to the video/graphics pipeline of a computer graphics subsystem. It is connected directly or through a gate array to the video RAM of the systems Frame Buffer (video memory). The pixel port on

the device consists of: Color Data RED, GREEN, BLUE Pixel Controls SYNC, BLANK Palette Selects PS0–PS1 The associated electric signals for the pixel part installer

The associated clocking signals for the pixel port include:

Clock Inputs

Clock Outputs

CLOCK, CLOCK, LOADIN, SCKIN LOADOUT, PRGCKOUT, SCKOUT

These onboard clock control signals are included to simplify interfacing between the part and the frame buffer. Only two control input signals are necessary to get the part operational, CLOCK and CLOCK (ECL Levels). No additional signals or external glue logic are required to get the *Pixel Port & Clock Control Circuit of the part operational.* 

### Pixel Port (Color Data)

The ADV7152 has 48 color data inputs. The part has two (for 2:1 multiplexing) 24-bit wide direct color data inputs. These are user programmed to support a number of color data formats including 24-Bit True Color, 15-Bit True Color and 8-Bit Pseudo Color (see "Color Data Formats" section) in 2:1 and 1:1 multiplex modes.



Figure 10. Multiplexed Color Inputs for the ADV7152

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Color data is latched into the parts pixel port on every rising edge of LOADIN (see Timing Waveform, Figure 3). The required frequency of LOADIN is determined by the multiplex rate, where

$f_{LOADIN} = f_{CLOCK}/2$	2:1 Multiplex Mode
$f_{LOADIN} = f_{CLOCK}$	1:1 Multiplex Mode

Other pixel data signals latched into the device by LOADIN include SYNC, BLANK and PS0–PS1.

Internally, data is pipelined through the part by the differential pixel clock inputs, CLOCK and CLOCK. The LOADIN control signal needs only have a frequency synchronous relationship to the pixel CLOCK (see "Pipeline Delay & Onboard Calibration" section). A completely phase independent LOADIN signal can be used with the ADV7152, allowing the CLOCK to occur apywhere during the LOADIN cycle.

Alternatively, the LOADOUT signal of the ADV7152 can be used. LOADDUT can be connected either directly or indirectly to LOADIN. Its frequency is automatically set to the correct LOADIN requirement.

# SYNC, BLANK

The BLANK and SYNC video control signals drive the analog outputs to the blanking and SYNC levels respectively. These signals are latched into the part on the rising edge of LOADIV. The SYNC information is encoded onto the IOG analog signal when bit CR22 of Command Register 2 is set to a Logic "1." The SYNC input is ignored if CR22 is set to "0."

### **SYNCOUT**

In some applications where it is not permissible to encode SYNC on green (IOG), SYNCOUT can be used as a separate TTL digital SYNC output. This has the advantage over an independent (of the AD V7150) SYNC in that it does not necessitate knowing the absolute pipeline delay of the part. This allows complete independence between LOADIN/Pixel Data and CLOCK. The SYNC input is connected to the device as normal with Bit CR22 of Command Register 2 set to "0" thereby preventing SYNC from being encoded onto IOG. Bit CR12 of Command Register 1 is set to "1," enabling SYNCOUT. The output signal generates a TTL SYNCOUT with correct pipeline delay that is capable of directly driving the composite SYNC signal of a computer monitor.

### PS0-PS1 (Palette Priority Select Inputs)

These pixel port select inputs determine whether or not the device is selected. These controls effectively determine whether the devices RGB analog outputs are turned-on or shut down. When the analog outputs are shut down, IOR, IOG and IOB are forced to 0 mA regardless of the state of the pixel and control data inputs. This state is determined on a pixel by pixel basis as the PS0–PS1 inputs are multiplexed in exactly the same format as the pixel port color data. These controls allow for switching between multiple palette devices (see Appendix 4). If the values of PS0 and PSI match the values programmed into bits MR16 and MR17 of the Mode Register, then the device is selected, if there is no match the device is effectively shut down.

### Multiplexing

The onboard multiplexers of the ADV7152 eliminate the need for external data serializer circuits. Multiple video memory devices can be connected, in parallel, directly to the device. Figure 11 shows two memory banks of 50 MHz memory connected to the ADV7152, running in 2:1 multiplex mode, giving a resultant pixel or dot clock rate of 100 MHz. As mentioned in the previous section, the ADV7152 supports a number of color data formats in 2:1 and 1:1 multiplex modes.

In 1:1 multiplex mode, the ADV7152 is clocked using the LOADIN signal. This means that there is no requirement for differential ECL inputs on CLOCK and CLOCK. The pixel clock is connected directly to LOADIN. (Note: The ECL CLOCK can still be used to generate LOADOUT PRGCKOUT, etc.)



CLOCK CONTROL CIRCUIT The ADV7152 has an integrated Clock Control Circuit (Figure 12). This circuit is capable of both generating the ADV7152's internal clocking signals as well as external graphics subsystem clocking signals. Total system synchronization can be attained by using the parts output clocking signals to drive the controlling graphics processor's master clock as well as the video frame buffers shift clock signals.

### CLOCK, CLOCK Inputs

The Clock Control Circuit is driven by the pixel clock inputs, CLOCK and  $\overline{\text{CLOCK}}$ . These inputs can be driven by a differential ECL oscillator running from a +5 V supply.



Figure 12. Clock Control Circuit of the ADV7152

Alternatively, the ADV7152 CLOCK inputs can be driven by a Programmable Clock Generator (Figure 13), such as the ICS1562. The ICS1562 is a monolithic, phase-locked-loop, clock generator chip. It is capable of synthesizing differential ECL output frequencies in a range up to 220 MHz from a single low frequency reference crystal.



Figure 13. PLL Generator Driving CLOCK, CLOCK of the ADV7152

# **CLOCK CONTROL SIGNALS LOADOUT**

The ADV7152 generates a LOADOUT control signal which runs at a divided down frequency of the pixel CLOCK. The frequency is automatically set to the programmed multiplex rate, controlled by CR36 of Command Register 3.

$f_{LOADOUT} = f_{CLOCK}/2$	2:1 Multiplex Mode
$f_{LOADOUT} = f_{CLOCK}$	1:1 Multiplex Mode

The LOADOUT signal is used to directly drive the LOADIN pixel latch signal of the ADV7152. This is most simply achieved by tying the LOADOUT and LOADIN pins together. Alternatively, the LOADOUT signal can be used to drive the frame buffer's shift clock signals, returning to the LOADIN input delayed with respect to LOADOUT.



Figure 14. LOADOUT vs. Pixel Clock Input (CLOCK, CLOCK)

If it is not necessary to have a known fixed number of pipeline delays, then there is no limitation on the delay between LOAD-OUT and LOADIN (LOADOUT(1) and LOADOUT(2)). LOADIN and Pixel Data must conform to the setup and hold times ( $t_8$  and  $t_9$ ).

If however, it is required that the ADV7152 has a fixed number of pipeline delays ( $t_{PD}$ ), LOADOUT and LOADIN must conform to timing specifications  $t_{10}$  and  $\tau$ - $t_{11}$  as illustrated in Figures 4 and 5.

### PRGCKOUT

The PRGCKOUT control signal outputs a user programmable clock frequency. It is a divided down frequency of the pixel CLOCK (see Figure 8). The rising edge of PRGCKOUT is synchronous to the rising edge of LOADOUT

$$f_{PRGCKOUT} = f_{CLOCK}/N$$

where N = 4, 8, 16 or 32.

One application of the PRGCKOUT is to use it as the master clock frequency of the graphics subsystems processor or controller.

# SCKIN, SCKOUT

These video memory signals are used to minimize external support chips. Figure 15 illustrates the function that is provided. An input signal applied to SCKIN is synchronously AND-ed with the video blanking signal (BLANK). The resulting signal is output on SCKOUT. Figure 7 of the Timing Waveform section shows the relationship between SCKOUT, SCKIN and BLANK.





The SCKOUT signal is essentially the video memory shift control signal. It is stopped during the screen retrace. Figure 16 shows a suggested frame buffer to ADV7152 interface. This is a minimum chip solution and allows the ADV7152 control the overall graphics system clocking and synchronization.



Figure 16. ADV7152 Interface Using SCKIN and SCKOUT

### Pipeline Delay and On-Board Calibration

The AD V7152 has a fixed number of pipeline delays ( $t_{PD}$ ), so long as timings  $t_{10}$  and  $\tau$ - $t_{11}$  are met. However, if a fixed pipeline delay is not a requirement, timings  $t_{10}$  and  $\tau$ - $t_{11}$  can be ignored, a calibration cycle must be run and there is no restriction on LOADIN to LOADOUT timing. If timings  $t_{10}$  and  $\tau$ - $t_{11}$  are not met, the part will function correctly though with an increased number of pipeline delays,  $t_{PD}$  + N CLOCKS (for 2:1 mode N = 2, for 1:1 mode N = 0). The ADV7152 has onboard calibration circuitry which synchronizes pixel data and LOADIN with the internal ADV7152 clocking signals. Calibration can be performed in two ways: during the devices initialization sequence by toggling two bits of the Mode Register, MR10 followed by MR15, or by writing a "1" to Bit CR10 of Command Register 1 which executes a calibration on every Vertical Sync.

# COLOR VIDEO MODES

The AD V7152 supports a number of color video modes all at the maximum video rate. Command bits CR24-CR27 of Command Begister 2 along with Bit MR11 of Mode Register 1 determine the color mode.

#### 24-Bit "Gamma" True Color (CR25, CR26, CR27 - 1, 1, 1 and MR11 =)1)

The part is set to 24-bit/30-bit True-Color operation The pixel port accepts 24 bits of color data which is directly mapped to the Look-Up Table RAM. The Look-Up Table is configured as a 256 location by 30 bits deep RAM (10 bits each for Red, Green and Blue). The output of the RAM drives the DACs with 30-bit data (10 bits each for Red, Green and Blue). The RAM is preloaded with a user determined, nonlinear function, such as a gamma correction curve.





This mode allows for the display of full 24-bit, Gamma-Corrected True-Color Images.

#### 24-Bit "Standard" True Color (CR25, CR26, CR27 = 1, 1, 1 and MR11 = 0)

This mode sets the part into direct 24-bit True-Color operation. The pixel port accepts 24 bits of color data which is directly mapped to Look-Up Table RAM. The Look-Up Table is configured as a 256 location by 24 bits deep RAM (8 bits each for Red, Green and Blue) and essentially acts as a bypass RAM. The output of the RAM drives the DACs with 24-bit data (8 bits each for Red, Green and Blue). The RAM is preloaded with a linear function.

This mode allows for the display of full 24-bit True-Color Images.



#### Figure 18. 24-Bit to 24-Bit Direct True-Color Configuration

# 8-Bit "Gamma" Pseudo Color

# (CR25, CR26, CR27 = X, 0, 0 or X, 1, 0 or X, 0, 1 and MR11 = 1)

This mode sets the part into 8-bit Pseudo-Color operation. The pixel port accepts 8 bits of pixel data which indexes a 30-bit word in the Look-Up Table RAM. The Look-Up Table is configured as a 256 location by 30 bits deep RAM (10 bits each for Red, Green and Blue). The output of the RAM drives the DACs with 30-bit data (10 bits each for Red, Green and Blue).



Figure 19. 8-Bit to 30-Bit Pseudo-Color Configuration

This mode allows for the display of 256 simultaneous colors out of a total palette of millions of addressable colors.

#### 8-Bit "Standard" Pseudo Color

# (CR25, CR26, CR27 = X, 0, 0 or X, 1, 0 or X, 0, 1 and MR11 = 0)

This mode sets the part into 8-bit Pseudo-Color operation. The pixel port accepts 8 bits of pixel data which indexes a 24-bit word in the Look-Up Table RAM. The Look-Up Table is configured as a 256 location by 24 bits deep RAM (10 bits each for Red, Green and Blue). The output of the RAM drives the DACs with 24-bit data (8 bits each for Red, Green and Blue).



Figure 20. 8-Bit to 24-Bit Pseudo-Color Configuration

This mode allows for the display of 256 simultaneous colors out of a total palette of millions of addressable colors.

#### 15-Bit "Gamma" True Color (CR24, CR25, CR26, CR27 = 0, 0, 1, 1 or 1, 0, 1, 1 and MR11 = 1)

The part is set to 15-bit True-Color operation. The pixel port accepts 15 bits of color data which is mapped to the 5 LSBs of each of the red, green and blue palettes of the Look-Up Table RAM. The Look-Up Table is configured as a 32 location by 30 bits deep RAM (10 bits each for Red, Green and Blue). The output of the RAM drives the DACs with 30-bit data (10 bits each for Red, Green and Blue).



This mode allows for the display of 15-bit, Gamma-Corrected True-Color Images.

#### 15-Bit "Standard" True Color (CR24, CR25, CR26, CR27 = 0, 0, 1, 1 or 1, 0, 1, 1 and MR11 = 0)

The part is set to 15-bit True-Color operation. The pixel port accepts 15 bits of color data which is mapped to the 5 LSBs of each of the red, green and blue palettes of the Look-Up Table RAM. The Look-Up Table is configured as a 32 location by 24 bits deep RAM (8 bits each for Red, Green and Blue). The output of the RAM drives the DACs with 24-bit data (8 bits each for Red, Green and Blue).



*Figure 22. 15-Bit to 24-Bit True-Color Configuration* This mode allows for the display of 15-bit True-Color Images.

# PIXEL PORT MAPPING

The pixel data to the ADV7152 is automatically mapped in the parts pixel port as determined by the pixel data mode programmed (Bits CR24–CR27 of Command Register 2).

Pixel data in the 24-bit True-Color modes is directly mapped to the 24 color inputs R0–R7, G0–G7 and B0–B7.



Figure 23. 15-Bit True-Color Mapping Using R3–R7, G3–G7 and B3–B7

There are three modes of operation for 8-bit Pseudo Color. Each mode maps the input pixel data differently. Data can be input one of the three color channels, R0–R7 or G0–G7 or B0–B7.

The part has two modes of operation for 15-bit True Color. In the first mode, data is input to the device over the red, green and blue channel (R3–R7, G3–G7 and B3–B7) and is internally mapped to locations 0 to 31 of the Look-Up Table (LUT) according to Figure 23. In the second mode, data is input to the device over just two of the color ports, red and green (R0–R7 and G0–G6) and is internally mapped to LUT locations 0 to 31 according to Figure 24. (Note: Data on unused pixel inputs is ignored.)



Figure 24. 15-Bit True-Color Mapping Using R0–R7 and G0–G6

# **MICROPROCESSOR (MPU) PORT**

The ADV7152 supports a standard MPU Interface. All the functions of the part are controlled via this MPU port. Direct access is gained to the Address Register, Mode Register and all the Control Registers as well as the Color Palette. The following sections describe the setup for reading and writing to all of the devices registers.

### **MPU Interface**

The MPU interface (Figure 25) consists of a bidirectional, 10-bit wide databus and interface control signals  $\overline{CE}$ , C0, C1 and  $R/\overline{W}$ . The 10-bit wide databus is user configurable as illustrated.

 Table II. Databus Width Table

Databus Width	RAM/DAC Resolution	Read/Write Mode
10 Bit	10 Bit	10-Bit Parallel
10 Bit 8 Bit	8 Bit	8-Bit Parallel 8+2 Byte
8 Bit	8 Bit	8-Bit Parallel

#### **Register Mapping**

The ADV7152 contains a number of onboard registers including the Mode Register (MR17–MR10), Address Register (A7– A0) and nine Control Registers as well as Red (R9–R0), Green (G9–G0) and Blue (B9–B0) Color Registers. These registers control the entire operation of the part. Figure 26 shows the internal register configuration.

Control lines C1 and C0 determine which register the MPU is accessing. C1 and C0 also determine whether the Address Register is pointing to the color registers and look-up table RAM or the control registers. If C1, C0 = 1, 0, the MPU has access to whatever control register is pointed to by the Address Register (A7-A0). If C1, C0 = 0, 1, the MPU has access to the Look-Up Table RAM (Color Palette) through the associated color regisers. The  $\overline{CE}$  input latches data to or from the part.

The R/W control input determines between read or write accesses. The Truth Tables III and IV show all modes of access to the various registers and color paletie for both the 8-bit wide databus configuration and 10-bit wide databus configuration. It should be noted that after power-up, the devices MPU port is automatically set to 10-bit wide operation (see Power-On Reset section).

# **Color Palette Accesses**

Data is written to the color palette by first writing to the address register of the color palette location to be modified. The MPU performs three successive write cycles for each of the red, green and blue registers (10 bit or 8 bit). An internal pointer moves from red to green to blue after each write is completed. This pointer is reset to red after a blue write or whenever the address register is written. During the blue write cycle, the three bytes of red, green and blue are concatenated into a single 30-bit/24-bit word and written to the RAM location as specified in the address register (A7–A0). The address register then automatically increments to point to the next RAM location and a similar red, green and blue palette write sequence is performed. The address register resets to 00H following a blue write cycle to color palette RAM location FFH.



Figure 25. MPU Port and Register Configuration

Data is read from the color palette by first writing to the address register of the color palette location to be read. The MPU performs three successive read cycles from each of the red, green and blue locations (10-bit or 8-bit) of the RAM. An internal pointer moves from red to green to blue after each read is completed. This pointer is reset to red after a blue read or whenever the address register is written. The address register then automatically increments to point to the next RAM location, and a similar red, green and blue palette read sequence is performed. The address register resets to 00H following a blue read cycle of color palette RAM location FFH.

#### **Register Accesses**

The MPU can write to or read from all of the ADV7152s registers. C0 and C1 determine whether the Mode Register or Address Register is being accessed. Access to these registers is direct. The Control Registers are accessed indirectly. The Address Register must point to the desired Control Register. Figure 28 along with the 8-bit and 10-bit Interface Truth T ables illustrate the structure and protocol for device communication over the MPU port.



Figure 26. Internal Register Configuration and Address Decoding

R/W	C1	C0	Databus (D9–D0)	Operation	Result
0 0 0	1 0 1	1 0 0	DB7–DB0 DB7–DB0 DB7–DB0	Write to Mode Register Write to Address Register Write to Control Registers (Particular Control Register Determined by Address	$DB7-DB0 \rightarrow MR17-MR10$ $DB7-DB0 \rightarrow A7-A0$ $DB7-DB0 \rightarrow Control Register$ <i>s Register</i> )
0 0 0	0 0 0	1 1 1	DB9–DB0 DB9–DB0 DB9–DB0	Write to RED Register Write to GREEN Register Write to BLUE Register Write RGB Data to RAM Location Pointed to Address Register = Address Register + 1	DB9-DB0 → R9-R0 DB9-DB0 → G9-G0 DB9-DB0 → B9-B0 by Address Register (A7-A0)
1 1 1	1 0 1	1 0 0	DB7–DB0 DB7–DB0 DB7–DB0	Read Mode Register Read Address Register Read Control Registers (Particular Control Register Determined by Address	$MR17-MR10 \rightarrow DB7-DB0$ $A7-A0 \rightarrow DB7-DB0$ Register Data $\rightarrow DB7-DB0$ <i>s Register</i> )
1 1 1	0 0 0	1 1 1	DB9–DB0 DB9–DB0 DB9–DB0	Read RED RAM Location Read GREEN RAM Location Read BLUE RAM Location (RAM Location Pointed to by Address Reg (A7–A Address Register = Address Register + 1	$R9-R0 \rightarrow DB9-DB0$ $G9-G0 \rightarrow DB9-DB0$ $B9-B0 \rightarrow DB9-DB0$ 0))

Table III. Interface Truth Table (10-Bit Databus Mode)

R/W	C1	C0	D atabus (D 9–D 0)	Operation	Result
0	1	1	DB7–DB0	Write to Mode Register	$DB7-DB0 \rightarrow MR17-MR10$
0	0	0	DB7–DB0	Write to Address Register	$DB7-DB0 \rightarrow A7-A0$
0	1	0	DB7-DB0	Write to Control Registers	$DB7-DB0 \rightarrow Control Registers$
				(Particular Control Register Determined by Addres	s Register $(A7 - A0))$
0	0	1	DB9–DB2	Write to RED Register	$DB9-DB2 \rightarrow R9-R2$
0	0	1	DB1-DB0	Write to RED Register	$DB1-DB0 \rightarrow R1-R0$
0	0	1	DB9–DB2	Write to GREEN Register	$DB9-DB2 \rightarrow G9-G2$
0	0	1	DB1-DB0	Write to GREEN Register	$DB1-DB0 \rightarrow G1-G0$
0	0	1	DB9–DB2	Write to BLUE Register	$DB9-DB2 \rightarrow B9-B2$
0	R	1	DB1-DB0	Write to BLUE Register	$DB1-DB0 \rightarrow B1-B0$
$\frown$	$\land$			Write RGB Data to RAM Location Pointed to	by Address Register (A7-A0)
		/ /~		Address Register = Address Register + 1	
1	$/_{1}/$	$/_1$		Read Mode Register	$MR17 - MR10 \rightarrow DB7 - DB0$
$\sim$	0/		<b>√</b> B7- <b>1</b> 0B0	Read Address Register	$A7-A0 \rightarrow DB7-DB0$
$\leftarrow$	$\downarrow_1$	0	DB7-DB0	Read Control Registers	Register Data $\rightarrow$ DB7–DB0
	L	$\sim$		Particular Control Register Determined by Addres	ss Register)
1	0	1	DB9DB2	Read RED RAM Location	$R \mathfrak{H} = \mathbb{R}^2 \to \mathbb{D} \mathbb{B} \mathfrak{H} = \mathbb{D} \mathbb{B} \mathfrak{H}^2$
1	0	1	DB1-DB0-	Read RED RAM Location	$R \rightarrow DB \rightarrow DB $
1	0	1	DB9-DB2	Read GREEN RAM Location	$G9-G2 \neq DB9-DB2$
1	0	1	DB1-DB0	Read GREEN RAM Location	$/G1-G0 \not\rightarrow DB1-DB0$
1	0	1	DB9-DB2	Read BLUE RAM Location	$B9-B2 \rightarrow DB9-DB2$
1	0	1	DB1-DB0	Read BLUE RAM Location	$\rightarrow$ B1-B0/ $\rightarrow$ // B1-D // 0
				(RAM Location Pointed to by Address Register (A	$(z_A 0))                                    $
				Address Register = Address Register + 1	

Table IV. Interface Truth Table (8-Bit Databus Mode)\*

\*Writing or reading 10-bit data (DB9–DB0) over an 8-bit databus (D7–D0) requires two write or two read cycles. :DB9–DB2 is mapped to D7–D0 on the first cycle.

:DB1-DB0 is mapped to D1-D0 on the second cycle.

DB = Data Bit.

#### **Power-On Reset**

On power-up of the ADV7152 executes a power-on reset operation. This initializes the pixel port such that the pixel sequence AB starts at A. The Mode Register (MR17–MR10), Command Register 2 (CR27–CR20) and Command Register 3 (CR37– CR30) have all bits set to a Logic "1." Command Register 1 (CR17–CR10) has all bits set to a Logic "0." The output clocking signals are also set during this reset period. PRGCKOUT = CLOCK/22

$$PRGCKOUT = CLOCK/32$$
  
LOADOUT = CLOCK/2

The power-on reset is activated when  $V_{AA}$  goes from 0 V to 5 V. This reset is active for 1 µs. The ADV7152 should not be accessed during this reset period. The pixel clock should be applied at power-up.

### **REGISTER PROGRAMMING**

The following section describes each register, including Address Register, Mode Register and each of the nine Control Registers in terms of its configuration.

#### Address Register (A7–A0)

As illustrated in the previous tables, the C0 and C1 control inputs, in conjunction with this address register specify which control register, or color palette location is accessed by the MPU port. The address register is 8-bits wide and can be read from as well as written to. When writing to or reading from the color palette on a sequential basis, only the start address needs to be written. After a red, green and blue write sequence, the address register is automatically incremented.

### MODE REGISTER MR1 (MR19-MR10)

The mode register is a 10-bit wide register. However for programming purposes, it may be considered as an 8-bit wide register (MR18 and MR19 are both reserved). It is denoted as MR17-MR10 for simplification purposes.

The diagram shows the various operations under the control of the mode register. This register can be read from as well written to. In read mode, if MR18 and MR 19 are read back, they are both returned as zeros.

# MODE REGISTER (MR17–MR10) BIT DESCRIPTION Reset Control (MR10)

This bit is used to reset the pixel port sampling sequence. This ensures that the pixel sequence AB starts at A. It is reset by writing a "1" followed by a "0" followed by a "1." This bit must be run through this cycle during the initialization sequence.

### **RAM-DAC Resolution Control (MR11)**

When this is programmed with a "1," the RAM is 30 bits deep (10 bits each for red, green and blue) and each of the three DACs is configured for 10-bit resolution. When MR11 is programmed with a "0," the RAM is 24 bits deep (8 bits each for red, green and blue) and the DACs are configured for 8-bit resolution. The two LSBs of the 10-bit DACs are pulled down to zero in 8-bit RAM-DAC mode.

### MPU Databus Width (MR12)

This bit determines the width of the MPU port. It is configured as either a 10-bit wide (D9–D0) or 8-bit wide (D7–D0) bus. 10-bit data can be written to the device when configured in 8-bit wide mode. The 8 MSBs are first written on D7–D0, then the two LSBs are written over D1–D0. Bits D9–D8 are zeros in 8-bit mode.

#### **Operational Mode Control (MR14-MR13)**

When MR14 is "0" and MR13 is "1," the part operates in normal mode.

#### Calibrate LOADIN (MR15)

This bit automatically calibrates the onboard LOADIN/ LOADOUT synchronization circuit. A "0" to "1" transition initiates calibration. This bit is set to "0" in normal operation. See "Pipeline Delay and Calibration" section. This bit must be run through this cycle during the initialization sequence.

### Palette Select Match Bits Control (MR17-MR16)

These bits allow multiple palette devices to work together. When bits PSI and PS0 match MR17 and MR16 respectively, the device is selected. If these bits do not match, the device is not selected and the analog video outputs drive 0 mA, see "Palette Priority Select Inputs" section.

### Control Registers The ADN7152 has 9 control registers. To access each register, two write operations must be performed. The first write to the address register specifies which of the 9 registers is to be accessed. The second access determines the value written to that particular control register.

#### Pixel Test Register (Address Reg (A7–A0) = 00H)

This register is used when the device is in test/diagnostic mode. It is a 24-bit (8 bits each for RED, GREEN and BLUE) wide read-only register which allows the MPU to read data on the pixel port, see "Test Diagnostic" section.



Mode Register 1 (MR1) (MR19–MR10)

# DAC Test Register

# (Address Reg (A7–A0) = 01H)

This register is used when the device is in test/diagnostic mode. It is a 30-bit (10 bits each for RED, GREEN and BLUE) wide read-only register which allows MPU access to the DAC port, see "Test Diagnostic" section.

# **SYNC**, **BLANK** and $I_{PLL}$ Test Register (Address Reg (A7-A0) = 02H)

#### (Address Reg (A7-A0) = 02H) This register is used when the device

This register is used when the device is in test/diagnostic mode. It is a 3-bit wide (3 LSBs) read/write register which allows MPU access to these particular pixel control bits, see "Test Diagnostic" section.

# ID Register

# (Address Reg (A7–A0) = 03H)

This is an 8-bit wide "Identification" read-only register. For the ADV7152 it will always return the hexadecimal value 8CH.

# Pixel Mask Register (Address Reg (A7-A0) = 04H)

The convents of the pixel plass register are individually bit-wise logically AND-ed with the Red, Green and Blue pixel input stream of data. It is an 8-bit nead/write register with D0 corresponding to R0, G0 and B0. For normal operation, this register is set with FFH.

# **COMMAND REGISTER 1 (CR1)**

# (Address Reg (A7–A0) = 05H)

This register contains a number of control bits as shown in the diagram. CR1 is a 10-bit wide register. However for programming purposes, it may be considered as an 8-bit wide register (CR18 to CR19 are reserved).

The diagram below shows the various operations under the control of CR1. This register can be read from as well as written to. In write mode, "0" should be written to CR11 and CR13–CR17. In read mode, CR11 and CR13–CR19 are returned as zeros.

#### COMMAND REGISTER 1 BIT DESCRIPTION Calibration Control (CR10)

This bit automatically calibrates the onboard LOADIN/ LOADOUT synchronization circuit. MR15 of Mode Register MR1 must be set to "0."

### **SYNCOUT** Control (CR12)

This bit specified whether the video SYNCOUT signal is to be enabled. On power up a "0" is written to the bit and "SYNCOUT" is set three-state.



Command Register 1 (CR1) (CR19-CR10)

# **COMMAND REGISTER 2 (CR2)**

#### (Address Reg (A7–A0) = 06H)

This register contains a number of control bits as shown in the diagram. CR2 is a 10-bit wide register. However for programming purposes, it may be considered as an 8-bit wide register (CR28 and CR29 are both reserved).

The diagram shows the various operations under the control of CR2. This register can be read from as well written to. In read mode, CR28 and CR29 are both returned as zeros.

#### COMMAND REGISTER 2 BIT DESCRIPTION R7 Trigger Polarity Control (CR20)

This bit determines whether the pixel data is latched into the test registers on the rising or falling edge of R7, see "Test Diagnostics" section in Appendix 3.

# I<sub>PLL</sub> Trigger Control (CR21)

This bit specifies whether the  $I_{PLL}$  output is triggered from BLANK or SYNC.

#### **SYNC** Recognition Control (CR22)

This bit specifies whether the video  $\overline{SYNC}$  input is to be encoded onto the IOG analog output or ignored.

#### Pedestal Enable Control (CR23)

This bit specifies whether a 0 IRE or a 7.5 IRE blanking pedestal is to be generated on the video outputs.

#### True-Color/Pseudo-Color Mode Control (CR27-CR24)

These 4 bits specify the various color modes. These include a 24-bit true-color mode, two 15-bit true-color modes and three 8-bit pseudo color modes.



Command Register 2 (CR2) (CR29–CR20)

#### COMMAND REGISTER 3 (CR3) (Address Reg (A7–A0) = 07H)

This register contains a number of control bits as shown in the diagram. CR3 is a 10-bit wide register. However for programming purposes, it may be considered as an 8-bit wide register (CR38 and CR39 are both reserved).

The diagram shows the various operations under the control of CR3. This register can be read from as well written to. In read mode, CR38 and CR39 are both returned as zeros.

#### COMMAND REGISTER 3-BIT DESCRIPTION PRGCKOUT Frequency Control (CR31–CR30)

These bits specify the output frequency of the PRGCKOUT output. PRGCKOUT is a divided down version of the pixel

# BLANK Pipeline Delay Control (CR35-CR32)

These bits specify the additional pipeline delay that can be added to the  $\overline{BLANK}$  function, relative to the overall device pipeline delay (t<sub>PD</sub>). As the  $\overline{BLANK}$  control normally enters the video DAC from a shorter pipeline than the video pixel data, this control is useful in deskewing the pipeline differential.

### Pixel Multiplex Control (CR36)

These bits specify the device's multiplex mode. It, therefore, also determines the frequency of the LOADOUT signal. LOADOUT is a divided down version of the pixel CLOCK.

## **Revision Register**

#### (Address Reg (A7-A0) = 0BH)

This register is a read only register containing the revision of silicon.



Command Register 3 (CR3) (CR39–CR30)

# DIGITAL-TO-ANALOG CONVERTERS (DACS) AND VIDEO OUTPUTS

The AD V7152 contains three high speed video DACs. The DAC outputs are represented as the three primary analog color signals IOR (red video), IOG (green video) and IOB (blue video). Other analog signals on the part include  $I_{PLL}$  and  $V_{REF}$  as well as complementary video outputs IOR, IOG, IOB. These complementary outputs can be used to drive differentially terminated video loads, they will have equal but opposite output levels to IOR, IOG and IOB when loaded with a resistive load similar to IOR, IOG and IOB.

# **DACs and Analog Outputs**

The part contains three matched 10-bit digital-to-analog converters. The DACs are designed using an advanced, high speed, segmented architecture. The bit currents corresponding to each digital input are routed to either IOR, IOG, IOB (bit = "1") or IOR, IOG, IOB (bit = "0"). (Normally IOR, IOG, IOB = GND.) The analog video outputs are high impedance current sources.

Each of the these three ROB current outputs are specified to directly drive a 37.5  $\Omega$  load (doubly terminated  $\sqrt{5} \Omega$ ).



Figure 27. DAC Output Termination (Doubly Terminated 75  $\Omega$  Load)

#### Reference Input and $\mathbf{R}_{\text{SET}}$

An external 1.23 V voltage reference is required to drive the analog outputs of the AD V7152. The reference voltage is connected to the  $V_{REF}$  input.

A resistor  $R_{SET}$  is connected between the  $R_{SET}$  input of the part and ground. For specified performance,  $R_{SET}$  has a value of 280  $\Omega$ . This corresponds to the generation of RS-343A video levels (with SYNC on IOG and Pedestal = 7.5 IRE) into a doubly terminated 75  $\Omega$  load. Figure 28 illustrates the resulting video waveform, and the Video Output Truth Table shows the corresponding control input stimuli.



Figure 28. Composite Video Waveform (SYNC Decoded on IOG; Pedestal = 7.5 IRE;  $R_{SET}$  = 280  $\Omega$ )

### Table V. Video Output Truth Table

Description	IOG (mA)	IOR, IOB (mA)	SYNC	BLANK	DAC Input Data
WHITE LEVEL	26.67	19.05	1	1	3FFH
VIDEO	Video + 9.05	Video + 1.44	1	1	Data
VIDEO to BLANK	Video + 1.44	Video + 1.44	0	1	Data
BLACK LEVEL	9.05	1.44	1	1	000H
BLACK to BLANK	1.44	1.44	0	1	000H
BLANK LEVEL	7.62	0	1	0	xxxH
SYNC LEVEL	0	0	0	0	xxxH

#### Variations on RS-343A

Various other video output configurations can be implemented by the AD V7152, including RS-170. Values of  $R_{SET}$  for particular output video formats/levels are calculated by using the equations for  $R_{SET}$  given in the "Pin Configuration" section. The table shows calculated values of  $R_{SET}$  for some of the most common variants on the RS-343A standard. The associated waveforms are shown in the diagrams.

$\mathbf{R}_{SET}\left( \Omega ight)$	Video Signal
265 280 259	SYNC decoded on IOG; Pedestal = 0 IRENoSYNC decoded; Pedestal = 7.5 IRENoSYNC decoded; Pedestal = 0 IRE



Figure 29. Composite Video Waveform (SYNC Decoded on IOG; Pedestal = 0 IRE;  $R_{SET}$  = 265  $\Omega$ )



Figure 30. Composite Video Waveform (Pedestal = 7.5 IRE;  $R_{SET}$  = 280  $\Omega$ )



Figure 31. Composite Video Waveform (Pedestal = 0 IRE;  $R_{SET}$  = 259  $\Omega$ )

### I<sub>PLL</sub> Synchronization Output Control

This output synchronization signal is used in applications where it is necessary to synchronize multiple palette devices (ADV7150 + ADV7151) to subpixel resolution. Each devices  $I_{PLL}$  output signal is in phase with its analog RGB output signal. If multiple devices have differing output delays, the time difference can be defived from the  $I_{PLL}$  signals. This time difference is then used to phase shift the <u>CLOCK</u> inputs on one or other of the devices inputs.



#### **BOARD DESIGN AND LAYOUT CONSIDERATIONS**

The ADV7152 is a highly integrated circuit containing both precision analog and high speed digital circuitry. It has been designed to minimize interference effects on the integrity of the analog circuitry by the high speed digital circuitry. It is imperative that these same design and layout techniques be applied to the system level design such that high speed, accurate performance is achieved. The "Recommended Analog Circuit Layout" shows the analog interface between the device and monitor.

The layout should be optimized for lowest noise on the ADV7152 power and ground lines by shielding the digital inputs and providing good decoupling. The lead length between groups of  $V_{AA}$  and GND pint should by minimized so as to minimize inductive tinging.

# Ground Planes

The ground plane should encompass all AD V7152 ground pins, voltage reference circultry, pover supply bypass circuitry for the AD V7152, the analog output traces, and all the digital signal traces leading up to the AD V7152. The ground plane is the graphics board's common ground plane.

#### **Power Planes**

The ADV7152 and any associated analog circuitry should have its own power plane, referred to as the analog power plane ( $V_{AA}$ ). This power plane should be connected to the regular PCB power plane ( $V_{CC}$ ) at a single point through a ferrite bead. This bead should be located within three inches of the ADV7152.

The PCB power plane should provide power to all digital logic on the PC board, and the analog power plane should provide power to all ADV7152 power pins and voltage reference circuitry.

Plane-to-plane noise coupling can be reduced by ensuring that portions of the regular PCB power and ground planes do not overlay portions of the analog power plane, unless they can be arranged such that the plane-to-plane noise is common mode.

#### **Supply Decoupling**

For optimum performance, bypass capacitors should be installed using the shortest leads possible, consistent with reliable operation, to reduce the lead inductance. Best performance is obtained with 0.1  $\mu$ F ceramic capacitor decoupling. Each group of V<sub>AA</sub> pins on the ADV7152 must have at least one 0.1  $\mu$ F decoupling capacitor to GND. These capacitors should be placed as close as possible to the device. It is important to note that while the AD V7152 contains circuitry to reject power supply noise, this rejection decreases with frequency. If a high frequency switching power supply is used, the designer should pay close attention to reducing power supply noise and consider using a three terminal voltage regulator for supplying power to the analog power plane.

#### **Digital Signal Interconnect**

The digital inputs to the ADV7152 should be isolated as much as possible from the analog outputs and other analog circuitry. Also, these input signals should not overlay the analog power plane.

Due to the high clock rates involved, long clock lines to the ADV7152 should be avoided to reduce noise pickup.

Any active termination resistors for the digital inputs should be connected to the regular PCB power plane ( $V_{CC}$ ), and not the analog power plane.

Analog Signal Interconnect

The AD 17152 should be located as glose as possible to the outout connectors to minimize noise pick-up and reflections due to edance mismatch.

impedance mismatch. The video output signals should overlay the ground plane, and not the analog power plane, to maximize the high frequency power supply rejection.

Digital Inputs, especially Pixel Data Inputs and clocking signals (CLOCK, LOADOUT, LOADIN, etc.) should never overlay any of the analog signal circuitry and should be kept as far away as possible.

For best performance, the analog outputs (IOR, IOG, IOB) should each have a 75  $\Omega$  load resistor connected to GND. These resistors should be placed as close as possible to the ADV7152 so as to minimize reflections. Normally, the differential analog outputs ( $\overline{IOR}$ ,  $\overline{IOG}$ ,  $\overline{IOB}$ ) are connected directly to GND. In some applications, improvements in performance are achieved by terminating these differential outputs with a resistive load similar in value to the video load. For a doubly terminated 75  $\Omega$  load, this means that  $\overline{IOR}$ ,  $\overline{IOG}$ ,  $\overline{IOB}$  are each terminated with 37.5  $\Omega$  resistors.



# **APPENDIX 2**



TYPICAL FRAME BUFFER INTERFACE

#### **10-BIT DACS AND GAMMA CORRECTION**

#### **10-Bit DACs**

Gamma Correction 8 Bits vs. 10 Bits

10-bit RAM-DAC resolution allows for nonlinear video correction, in particular Gamma Correction. The ADV7152 allows for an increase in color resolution from 24-bit to 30-bit effective color without the necessity of a 30-bit deep frame buffer. In true-color mode, for example, the part effectively operates as a 24-bit to 30-bit color look-up table.

Up to now we have assumed that there exists a linear relationship between the actual RGB values input to a monitor and the intensity produced on the screen. This, however, is not the case. Haff scale digital input (1000 0000) might correspond to only 20% output intensity on the CRT (Cathode Ray Tube). The intensity  $(I_{CRT})$  produced on a CRT by an input value  $I_{IN}$  is given

 $(I_{IN})^{\chi}$ 

where  $\chi$  ranges from 240 to 2.8

If the individual values of x for red, green and plue are known, then so called "Gamma Correction" an be applied to each of the three video input signals (I<sub>IN</sub>);

therefore:

by:

# $I_{IN(corrected)} = k(I_{IN})^{1/\chi}$

(k = 1, normally)

Traditionally, there has been a tradeoff between implementing a nonlinear graphics function, such as gamma correction, and color dynamic range. The ADV7152 overcomes this by increasing the individual color resolution of each of the red, green and blue primary colors from 8 bits per color channel to 10 bits per channel (24 bits to 30 bits).

The table highlights the loss of resolution when 8-bit data is gamma-corrected to a value of 2.7 and quantized in a traditional 8-bit system. Note that there is no change in the 8-bit quantized data for linear changes in the input data over much of the transfer function. On the other hand, when quantized to 10 bits via the 10-bit RAMs and 10-bit DACs of the ADV7152, all changes on the input 8-bit data are reflected in corresponding changes in the 10-bit data.

The graph shows a typical gamma curve corresponding to a gamma value of 2.7. This is programmed to the red, green and blue RAMs of the color lookup table instead of the more traditional linear function. Different curves corresponding to any particular gamma value can be independently programmed to each of the red, green and blue RAMs.

Other applications of the 10-bit RAM-DAC include closed-loop monitor color calibration.

8-Bit Data	Gamma Corrected (2.7)	Quantized to 8 Bits	Quantized to 10 Bits
240	0.977797	250	1001
241	0.979304	250	1002
242	0.980807	251	1004
243	0.982306	251	1005
244	0.983801	25 1	1007
245	0.985292	252	1008
246	0.986780	252	1010
247	0.988264	252	1011
248	0.989744	253	1013
249	0.991220	253	1015
250	0.992693	254	1016
231	0.994161	254	1018
252 / /	0.995626	254	1019
253//	0.997088	2551	1021
254	0.998546	254	1022
255	1.000000	255	10/23
$+ \leq$			
1.00	71-4		
0.90			
		URVE	XM
2 0.80		TIONCOL	
ତ୍ରୁ 0.70 –	CORRE	HEEVE	4
	GAMMA	LO BY	
N		RECEIVE	
1 0.50		INSE F.	
립 0.40	RREST		
	LINE		
¥ 0.20	-	RIRES	
0.10			
0.10			
0.00	32 64 9	6 128 160 102	224 256

Gamma Correction Curve (Gamma Value = 2.7)

#### MULTIPLE PALETTE APPLICATIONS

(DEVICE: 2)

#### **Palette Priority Select Inputs**

The palette priority selection inputs allow up to four separate palette devices to be used in a single system to drive a single monitor. The IOR, IOG and IOB analog video output signals of each device are connected together, as shown. Signal inputs (PS0, PS1) determine on a pixel by pixel basis which palette device drives the monitor. This allows for implementation of multiple windows applications with each device acting as an independent palette. During initialization, each device is assigned two match bits, MR16 (PS0) and MR17 (PS1) in Mode Register MR1. PS0 and PS1 inputs will select one of the preprogrammed devices at any instant when PS0, PS1 matches MR16, MR17, respectively. When PSO and PS1 do not match these bits, the DAOs of the particular device are shut down, driving RGB outputs to/0 mA. PS0 and PS1 are multiplexed similar to the pixel data, thus attowing for subpixel resolution. The diashow an example of one ADVX152 operating in seudo-Color, RAM-DACs). Each tion with three AD V7151's ( displayed window on the monitor is driven by one of the four devices. Each device's analog output signals are c onnected together as shown.

Note: Only one palette device is selected at any particular instant. The analog output levels of the unselected devices will be 0 mA.

Other applications for the palette priority function using a minimum of two devices (two ADV7152s or one ADV7152 and one ADV7151) include:

Cursor Overlay on 24-Bit Graphics Active Live Video Overlay (from Frame Grabber) Text/Character Generation and Overlay

IOR, IOG, IOB



Multiple Devices Driving a Multiwindow Application

#### INITIALIZATION AND PROGRAMMING

#### **ADV7152** Initialization

After power has been supplied, the ADV7152 must be initialized. The Mode Register and Control Registers must be set. The values written to the various registers will be determined by the desired operating mode of the part, i.e., True Color/Pseudo Color, 2:1 Muxing/2:1 Muxing, etc. Example 1 Color Mode 24-Bit True Color Multiplexing 2:1Databus  $8 - R_i$ -DAC Resolution AIBit 6YNC Enabled on 7.5 TRE Redestal Register Initialization R/W Comment  $C_1$ 09H to Mode Register (MR) Write Resets to Normal Operation, 8-Bit Bus/RAM-DAC 0 Write 08H to Mode Register (MR) 0 \*(Initialize Pipelining 09H to Mode Register (MR) 0 Write \*( " Write 29H to Mode Register (MR1) \*(Calibrates LOADOUT LOADIN Timing 0 Write 09H to Mode Register (MR1) \*(" Write 04H to Address Register (A7-A0) Reg Points to Pixel Mask Register 0 Address Write FFH to Pixel Mask Register 0 σ Sets the Pikel Mask to All " 1 Write 05H to Address Register (A7-A0) 0 0 0 Address Reg Points to Command Register 1 (CR) 00H to Command Reg 1 (CR1) Write 1 0 0 Write 06H to Address Register (A7-A0) 0 0 0 Address Reg Points to Command Register 2 (CR2) ECH to Command Reg 2 (CR2) 0 Sets 24-Bit Color, 7.5 IRE, SYNC on Green (TOG) Write 0 1 0 0 0 Write 07H to Address Register (A7-A0) Address Reg Points to Command Register 3 (CR3) Write 40H to Command Reg 3 (CR3) 1 0 0 Sets 2:1 Multiplexing, PRGCKOUT = CLOCK/4 **Color Palette RAM Initialization** C1 C0 R/W Comment Write 00H to Address Register (A7-A0) 0 Points to Color Palette RAM 0 0 Write 00H (Red Data) to RAM Location (00H) 0 1 0 (Initializes Palette RAM Write 00H (Green Data) to RAM Location (00H) 0 0 to a Linear Ramp\*\* 1 00H (Blue Data) to RAM Location (00H) Write 0 0 1 Write 01H (Red Data) to RAM Location (01H) 0 0 1 Write 01H (Green Data) to RAM Location (01H) 0 0 1 01H (Blue Data) to RAM Location (01H) 0 0 Write 1 • • Write FFH (Red Data) to RAM Location (FFH) 0 1 0 Write FFH (Green Data) to RAM Location (FFH) 0 0 1 Δ 0 Write FFH (Blue Data) to RAM Location (FFH) 1 (RAM Initialization Complete

\*These four command lines reset the ADV7152. The pipelines for each of the Red, Creen and Blue pixel inputs are synchronously reset to the Multiplexer's "A" input. Mode Register bit MR10 is written by a "1" followed by "0" followed by "1." LOADIN/LOADOUT timing is internally synchronized by writing a "0" followed by a "1" followed by a "0" to Mode Register MR15.

\*\*This sequence of instructions would, of course, normally be coded using some form of loop instruction.

The following section gives examples of initialization of the ADV7152 operating in various modes.

Examp	le 2						
Color M	l ode	24-Bit Gamma Correct	ted True Col	lor ( 30 1	Bits)		
Multipl	exing	2:1		(	,		
Databu	s	10-Bit					
RAM-L	DAC Resolution	10-Bit					
SYNC		Ignored					
Pedesta	l	0 IRE					
Calibra	tion	Everv Vertical Sync					
Dogisto	n Initialization			C1	CO	D/W	Commont
Write	OFU to Mode	Pagistar (MP1)				<b>K/W</b>	Desets to Normal Operation 10 Pit Pus/PAM DAC
Write	OFII to Mode	Pagister (MP1)		1	1	0	*(Initializes Dipolining
Write	OEH to Mode	Register (MR1)		1	1	0	*( "
Write	2EH to Mode	Register (MR1)		1	1	0	( *(Colibrates LOADOUT/LOADIN Timing
Write	2FH to Mode	Register (MR1)		1	1	0	*( "
write		$\operatorname{Register}(\mathbf{M}\mathbf{K}\mathbf{I})$		1	1	0	( Address Des Deints to Divel Mask Desister
Write	EFU to Divel	SS Register (A7–A0)		0	0	0	Address Reg Points to Pixel Mask Register
write	FFR to Prel	Mask Register		1	0	0	Sets the Pixel Mask to All Is
write	OF TO Addres	ss Register (A7–A0)		0	0	0	Address Reg Points to Command Register 1 (CR1)
write	UIH to Comm	and Reg I (CRT)		0	0	0	Calibrates Every Vertical Sync
write	DOH to Addres	s Register (A/-AU)		0	0	0	Address Reg Points to Command Register 2 (CR2)
Write	EUA to Comm	and reg 2 (CRX)	$\neg$		$\sum_{n=1}^{n}$	0	Sets 24-Bit Color, U IRE, NO SYNC
Write	H to Addres	ss Register (AV-A0)		<b>*</b>	X		Address Reg Points to Command Register 3 (CR3)
Write	41H to Comm	and Reg 5 (GR3)	) / /	1)	0	/º /	Sets 2:1 Multiplexing, PRGCKOUT = $CLOCK/8$
Color 1	Palette RAMT	nitialization		C1 /	C0	/ R/₩	Comment
Write	00H to Addres	ss Register (A7–A0)		0 /	9/	0/	Points to Color Pale to RAM
Write	000H (Red Da	ata) to RAM Location	(00H) 🗡	<u> </u>	/1 /	0/	(Initializes Palette RAM
Write	000H (Green	Data) to RAM Locatio	n (00H)	0	1	¢	( to a "Gamma" Ramp*#
Write	000H (Blue D	ata) to RAM Location	(00H)	0	1	_0	
Write	xxxH (Red Da	ta) to RAM Location (	(01H)	0	1	0	
Write	xxxH (Green I	Data) to RAM Location	n (01H)	0	1	0	
Write	xxxH (Blue Da	ata) to RAM Location	(01H)	0	1	0	
•	•	• • •	•	•	•	•	
•	•	• • •	•	•	•	•	
Write	3FFH (Red D	ata) to RAM Location	(FFH)	0	1	0	
Write	3FFH (Green	Data) to RAM Locatio	on (FFH)	0	1	0	(
Write	3FFH (Blue D	ata) to RAM Location	(FFH)	0	1	0	(RAM Initialization Complete

\*These four command lines reset the ADV7152 The pipelines for each of the Red, Green and Blue pixel inputs are synchronously reset to the Multiplexer's "A" input. Mode Register bit MR10 is written by a "1" followed by "0" followed by "1." LOADIN/LOADOUT timing is internally synchronized by writing a "0" followed by a "1" followed by a "0" to Mode Register MR15.

\*\*Data for a gamma curve characteristic is obtainable in Appendix 3.

#### **REGISTER DIAGNOSTIC TESTING**

The previous examples show the register initialization sequence for the AD V7152. These show control data going to the registers and palette RAM. As well as this writing function, it may also be necessary, due to system diagnostic requirements, to confirm that correct data has been transferred to each register and palette RAM location. There are two ways to incorporate register value/RAM value checking:

1. *READ after each WRITE:* After data is written to a particular register, it can be read back immediately. The following table shows an example with Command Registers CR2 and CR3.

C1	C0	R/W	D 0-D 7	Comment
0	0	0	06H	Select Command Register 2 (CR2)
1	0	0	E0H	Sets 24-Bit True-Color
1	0	1	E0H	Command Reg 2 Value Read-Back
0	0	0	07H	Select Command Register 3 (CR3)
1	0	0	40H	Set 2:1 Mux Mode
1	0	1	40H	Command Reg 3 Value Read-Back

2. *READ after all WRITEs completed:* All registers and the color palette RAM are written to and set. Once this is complete, all registers are again accessed but this time in Read-Only mode. The table below shows this method for Command Registers CR2 and CR3.

C1	C0	R/W	D0-D7	Comment
0	0	0	06H	Select Command Register 2 (CR2)
1	0	0	E0H	Sets 24-Bit True-Color
0	0	0	07H	Select Command Register 3 (CR3)
1	0	0	40H	Set 2:1 Mux Mode
0	0	0	06H	Select CR2
1	0	1	E0H	CR2 Value Read-Back
0	0	0	07H	Select CR3
1	0	1	40H	CR3 Value Read-Back
1	0	1	40H	CR3 Value Read-Back

It is clear that this latter case requires more command lines than the previous READ after each WRITE case.

# APPENDIX 6





The ADV7152 contains onboard circuitry which enables both device and system level test diagnostics. The test circuitry can be used to test the frame buffer memory as well as the functionality of the ADV7152. A number of test registers are integrated into the part which effectively allow for monitoring of the graphics pipeline. Pixel data is read from the graphics pipeline independent of the pixel CLOCK. The pixel data itself contains the triggering information that latches data into the test registers. This allows for system diagnostics in a continuously clocked graphics system. The test register data is then read by the microprocessor over the MPU.

Access to the test registers is as described in the "Microprocessor (MPU) Port" section. This section also gives the address decode locations for the various test registers.

#### Test Trigger (R7)

The test trigger is decoded from the pixel data stream. Bit R7 of the RED channel is assigned the task of latching pixel data into the test registers. A "0" to "1" or a "1" to "0" (as determined by bit CR20 of Command Register 2) transition on R7, fills the test register with the corresponding pixel data. This effectively means that a sequence of data travels along the graphics pipeline, with the test registers taking a sample only when there is a transition on Bit R7. The following example shows a sequence with the ADV7152 preset to sample the graphics pipeline on a low to high transition of R7.

	RED	GREEN	BLUE
Pixel 0:	00000000	00000000	00000000
Pixel 1:	0		
Pixel 2:	1		
Pixel 3:	0		
Pixel n-1:	0		
Pixel n:	1		
Pixel n:	0		

In the above sequence of pixels, there is a rising edge on R7 on Pixel 2. The Red, Green and Blue data for Pixel 2, therefore, gets latched into the Pixel Test Register. Pixel 2 continues down the graphics pipeline and after a number of clocks get latched into the DAC Test Register. This data can then be read from the Pixel/Test Register and the DAC Test Registers over the MPU Port. This data will remain in the Pixel Test Registers and the DAC Test Registers until the next rising edge of 17 causes new data to be latched in.

In the above example, the next rising edge of R7 occurs on the Pixel n input. Therefore the data in the Pixel T est Registers and DAC T est Registers must be read over the MPU before the Pixel n data is applied, otherwise they will be overwritten by the Pixel n data and the Pixel 2 data will be lost.

### **Pixel Test Register**

The read-only Pixel Test Register is 24 bits wide, 8 bits each for red, green and blue. It is situated directly after the Pixel Mask Register. After data is latched into this register by a transition on R7, it is read in three cycles over the MPU Port as described in the "Microprocessor (MPU) Port" section.

### **DAC Test Register**

The DAC Test Register is latched with data some CLOCKs after the Pixel Test Register. The DAC Test Register is a 30-bit wide read-only register, corresponding to 10 bits each for red, green and blue data. It is located the Color Palette RAM. If the RAM-DAC is in 8-bit after resolution mode, the upper two bits of the red, green and blue data will be zero. After data is latched into the DAC Test Register by a transition on R7, it is read in three or six cycles over the MPU Port as described in the "Microprocessor (MPU) Port" section.

#### SYNC, BLANK and I<sub>PLL</sub> Test Register

This is an 8-bit wide register but with only three effective bits. The three lower bits correspond to SYNC, BLANK and  $I_{PLL}$  respectively. The upper bits should be masked in software. This register is at the same position in the graphics pipeline as the DAC Test Register. When pixel data is latched into the DAC Test Register, the corresponding status of SYNC, BLANK and  $I_{PLL}$  is latched into this register. It is read over the MPU Port as described in the "Microprocessor (MPU) Port" section.

(Note: If  $\overline{BLANK}$  is low, the corresponding pixel data to the DAC Test Register will be all "0s.")

(2)

# **APPENDIX 7**

#### THERMAL AND ENVIRONMENTAL CONSIDERATIONS

The ADV7152 is a very highly integrated monolithic silicon device. This high level of integration, in such a small package, inevitably leads to consideration of thermal and environmental conditions in which the ADV7152 must operate. Reliability of the device is significantly enhanced by keeping it as cool as possible. In order to avoid destructive damage to the device, the absolute maximum junction temperature of 150°C must never be exceeded. Certain applications, depending on pixel data rates, may require forced air cooling, or external heatsinks. The following data is intended as a guide in evaluating the operating conditions of a particular application so that optimum device and system performance is achieved.

It should be noted that information on package characteristics published herein may not be the most up to date at the time of reading this. A drances in package compounds and manufacture will inevitably lead to improvements in the thermal data. Please contact your local sales office for the most up-to-date information.

Power Dissipation

The diagram shows graphs of power dissipation in watts vs. pixel clock frequency for the AD V7152.



\* THE "TYPICAL ON-SCREEN PATTERN" CORRESPONDS TO LINEAR CHANGES IN THE PIXEL INPUT (LE, A BLACK TO WHITE RAMP). IN GENERAL, COLOR IMAGES TEND TO APPROXIMATE THIS CHARACTERISTIC.

#### Typical Power Dissipation vs. Pixel Rate

#### Package Characteristics

The table of thermal characteristics shows typical information for the ADV7152 (100-Lead Plastic Power QFP) using various values of Airflow.

Junction to Case  $(\theta_{JC})$  Thermal Resistance for this particular part is:

 $\theta_{IC}$  (100-Lead Plastic Power QFP) = 1.0 °C/W

(Note:  $0^{\circ}C$  is independent of airflow.)

#### Table A. Thermal Characteristics vs. Airflow

Air Velocity (Linear feet/min)	0 (Still Air)	50	100	200
$\theta_{JA}$ (°C/W)				
No Heatsink	35	31	28	25
EG&G D10100-28 Heatsink	32	28	25	22
Thermalloy 2290 Heatsink	25	21	18	15

#### **Thermal Model**

The junction temperature of the device in a specific application is given by:

 $T_J = T_A + P_D \left( \theta_{JA} \right)$ 

$$T_J = T_A + P_D \left(\theta_{JC} + \theta_{CA}\right) \tag{1}$$

or



pared to standard QFP. In this case, the die is attached to heatslug so that the power that is dissipated can be conducted to the external surface of the package. This provides a highly efficient path for the transfer of heat to the package surface. The package configuration also provides an efficient thermal path from the ADV7152 to the Printed Circuit Board via the leads.

#### Heatsinks

The maximum silicon junction temperature should be limited to  $100^{\circ}$ C. Temperatures greater than this will reduce long term device reliability. To ensure that the silicon junction temperature stays within prescribed limits, the addition of an external heatsink may be necessary. Heatsinks, will reduce  $\theta_{JA}$  as shown in the "Thermal Characteristics vs. Airflow" table.

#### **OUTLINE DIMENSIONS**

Dimensions shown in inches and (mm).

#### 100-Lead Plastic Power Quad Flatpack (S-100)

