

Data Sheet

June 2008

Features

- Supports the requirements of Telcordia GR-253 and GR-1244 for Stratum 3, 4E, 4 and SMC clocks, and the requirements of ITU-T G.781 SETS, G.813 SEC, G.823, G.824 and G.825 clocks
- Internal APLL provides standard output clock frequencies up to 622.08 MHz with jitter $<$ 3 ps RMS suitable for GR-253-CORE OC-12 and G.813 STM-16 interfaces
- Programmable output synthesizers generate clock frequencies from any multiple of 8 kHz up to 77.76 MHz in addition to 2 kHz
- Provides two DPLLs which are independently configurable through a serial software interface
- DPLL1 provides all the features necessary for generating SONET/SDH compliant clocks including automatic hitless reference switching, automatic mode selection (locked, free-run, holdover), selectable loop bandwidth and pull-in range
- DPLL2 provides a comprehensive set of features necessary for generating derived output clocks and other general purpose clocks
- Provides 8 reference inputs which support clock frequencies with any multiples of 8 kHz up to 77.76 MHz in addition to 2 kHz

Ordering Information

ZL30121GGGV2 100 Pin CABGA Trays ZL30121GGG2V2 100 Pin CABGA** Trays **Pb Free Tin/Silver/Copper **-40oC to +85oC**

- Supports master/slave configuration for AdvancedTCATM
- Configurable input to output delay and output to output phase alignment
- Optional external feedback path provides dynamic input to output delay compensation
- Provides 3 sync inputs for output frame pulse alignment
- Generates several styles of output frame pulses with selectable pulse width, polarity and frequency
- Flexible input reference monitoring automatically disqualifies references based on frequency and phase irregularities
- Supports IEEE 1149.1 JTAG Boundary Scan

Figure 1 - Block Diagram

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Applications

- AdvancedTCATM Systems
- Multi-Service Edge Switches or Routers
- Multi-Service Provisioning Platforms (MSPPs)
- Add-Drop Multiplexers (ADMs)
- Wireless/Wireline Gateways
- Wireless Base Stations
- DSLAM / Next Gen DLC
- Core Routers

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Change Summary

The following table captures the changes from the May 2006 issue.

Pin Description

Pin#	Name	I/O Type	Description
D4	V_{SS}	G	Ground. 0 Volts.
D ₅		${\mathsf G}$	
D ₆		${\mathsf G}$	
D7 E ₅		G $\mathsf G$	
E ₆		$\mathsf G$	
E7		G	
F ₅			
F ₆		G G	
F7		G	
G4		${\mathsf G}$	
G ₅		$\mathsf G$	
G ₆		$\mathsf G$	
G7		G	
E ₉ F ₈		$\mathsf G$ $\mathsf G$	
F ₉		$\mathsf G$	
H ₉		${\bf G}$	
A7	AV_{SS}		Analog Ground. 0 Volts.
C7		G G	
${\rm C}8$		G	
C ₉		${\mathsf G}$	
D ₈		$\mathsf G$	
H ₃		${\bf G}$	

I - Input

- I_d -- Input, Internally pulled down
- I_{u} -
O -Input, Internally pulled up
- Output
- A Analog
- P Power
- G Ground

1.0 Functional Description

The ZL30121 SONET/SDH System Synchronizer is a highly integrated device that provides the functionality required for synchronizing network equipment. It incorporates two independent DPLLs, each capable of locking to one of eight input references and provides a wide variety of synchronized output clocks and frame pulses.

1.1 DPLL Features

The ZL30121 provides two independently controlled Digital Phase-Locked Loops (DPLL1, DPLL2) for clock and/or frame pulse synchronization. [Table 1](#page-11-2) shows a feature summary for both DPLLs.

1. Limited to 14 Hz for 2 kHz references)

2. In the wideband mode, the loop bandwidth depends on the frequency of the reference input. For reference frequencies greater than

8 kHz, the loop bandwidth = 890 Hz. For reference frequencies equal to 8 kHz, the loop bandwidth = 56 Hz. The loop bandwidth is equal to 14 Hz for reference frequencies of 2 kHz.

1.2 DPLL Mode Control

Both DPLL1 and DPLL2 independently support three modes of operation - free-run, normal, and holdover. The mode of operation can be manually set or controlled by an automatic state machine as shown in [Figure 2.](#page-12-1)

Figure 2 - Automatic Mode State Machine

Free-run

The free-run mode occurs immediately after a reset cycle or when the DPLL has never been synchronized to a reference input. In this mode, the frequency accuracy of the output clocks is equal to the frequency accuracy of the external master oscillator.

Lock Acquisition

The input references are continuously monitored for frequency accuracy and phase regularity. If at least one of the input references is qualified by the reference monitors, then the DPLL will begin lock acquisition on that input. Given a stable reference input, the ZL30121 will enter in the Normal (locked) mode.

Normal (locked)

The usual mode of operation for the DPLL is the normal mode where the DPLL phase locks to a selected qualified reference input and generates output clocks and frame pulses with a frequency accuracy equal to the frequency accuracy of the reference input. While in the normal mode, the DPLL's clock and frame pulse outputs comply with the MTIE and TDEV wander generation specifications as described in Telcordia and ITU-T telecommunication standards.

Holdover

When the DPLL operating in the normal mode loses its reference input, and no other qualified references are available, it will enter the holdover mode and continue to generate output clocks based on historical frequency data collected while the DPLL was synchronized. The transition between normal and holdover modes is controlled by the DPLL so that its initial frequency offset is better than 1 ppb which meets the requirement of Stratum 3E. The frequency drift after this transition period is dependant on the frequency drift of the external master oscillator.

1.3 Ref and Sync Inputs

There are eight reference clock inputs (**ref0** to **ref7**) available to both DPLL1 and DPLL2. The selected reference input is used to synchronize the output clocks. Each of the DPLLs have independent reference selectors which can be controlled using a built-in state machine or set in a manual mode.

Figure 3 - Reference and Sync Inputs

Each of the **ref** inputs accept a single-ended LVCMOS clock with a frequency ranging from 2 kHz to 77.76 MHz. Built-in frequency detection circuitry automatically determines the frequency of the reference if its frequency is within the set of pre-defined frequencies as shown in [Table 2](#page-13-2). Custom frequencies definable in multiples of 8 kHz are also available.

2 kHz	16.384 MHz
8 kHz	19.44 MHz
64 kHz	38.88 MHz
1.544 MHz	77.76 MHz
2.048 MHz	
6.48 MHz	
8.192 MHz	

Table 2 - Set of Pre-Defined Auto-Detect Clock Frequencies

In addition to the reference inputs, DPLL1 has three optional frame pulse synchronization inputs (**sync0** to **sync2**) used to align the output frame pulses. The sync_n input is selected with its corresponding ref_n input, where n = 0, 1, or 2. Note that the sync input cannot be used to synchronize the DPLL, it only determines the alignment of the frame pulse outputs. An example of output frame pulse alignment is shown in [Figure 4.](#page-14-0)

Figure 4 - Output Frame Pulse Alignment

Each of the **sync** inputs accept a single-ended LVCMOS frame pulse. Since alignment is determined from the rising edge of the frame pulse, there is no duty cycle restriction on this input, but there is a minimum pulse width requirement of 5 ns. Frequency detection for the sync inputs is automatic for the supported frame pulse frequencies shown in [Table 3.](#page-14-1)

Table 3 - Set of Pre-Defined Auto-Detect Sync Frequencies

1.4 Ref and Sync Monitoring

All input references (**ref0** to **ref7**) are monitored for frequency accuracy and phase regularity. New references are qualified before they can be selected as a synchronization source and qualified references are continuously monitored to ensure that they are suitable for synchronization. The process of qualifying a reference depends on four levels of monitoring.

Single Cycle Monitor (SCM)

The SCM block measures the period of each reference clock cycle to detect phase irregularities or a missing clock edge. In general, if the measured period deviates by more than 50% from the nominal period, then an SCM failure (scm_fail) is declared.

Coarse Frequency Monitor (CFM)

The CFM block monitors the reference frequency over a measurement period of 30 μs so that it can quickly detect large changes in frequency. A CFM failure (cfm fail) is triggered when the frequency has changed by more than 3% or approximately 30000 ppm.

Precise Frequency Monitor (PFM)

The PFM block measures the frequency accuracy of the reference over a 10 second interval. To ensure an accurate frequency measurement, the PFM measurement interval is re-initiated if phase or frequency irregularities are detected by the SCM or CFM. The PFM provides a level of hysteresis between the acceptance range and the rejection range to prevent a failure indication from toggling between valid and invalid for references that are on the edge of the acceptance range.

When determining the frequency accuracy of the reference input, the PFM uses the external oscillator's output frequency (f_{ocsi}) as its point of reference.

Guard Soak Timer (GST)

The GST block mimics the operation of an analog integrator by accumulating failure events from the CFM and the SCM blocks and applying a selectable rate of decay when no failures are detected.

As shown in [Figure 5](#page-15-1), a GST failure (gst fail) is triggered when the accumulated failures have reached the upper threshold during the disqualification observation window. When there are no CFM or SCM failures, the accumulator decrements until it reaches its lower threshold during the qualification window.

Figure 5 - Behaviour of the Guard Soak Timer during CFM or SCM Failures

All sync inputs (**sync0 to sync2**) are continuously monitored to ensure that there is a correct number of reference clock cycles within the frame pulse period.

1.5 Output Clocks and Frame Pulses

The ZL30121 offers a wide variety of outputs including two low-jitter differential LVPECL clocks (diff0 p/n, diff1 p/n), two SONET/SDH LVCMOS (sdh clk0, sdh clk1) output clocks, and four programmable LVCMOS (**p0_clk0, p0_clk1, p1_clk0, p1_clk1**) output clocks. In addition to the clock outputs, two LVCMOS SONET/SDH frame pulse outputs (**sdh_fp0, sdh_fp1**) and two LVCMOS programmable frame pulses (**p0_fp0, p0_fp1**) are also available.

The feedback clock (**fb_clk**) of DPLL1 is available as an output clock. Its output frequency is always equal to DPLL1's selected input frequency.

The output clocks and frame pulses derived from the SONET/SDH APLL are always synchronous with DPLL1, and the clocks and frame pulses generated from the programmable synthesizers can be synchronized to either DPLL1 or DPLL2. This allows the ZL30121 to have two independent timing paths.

Figure 6 - Output Clock Configuration

The supported frequencies for the output clocks and frame pulses are shown in [Table 4](#page-17-0).

Table 4 - Output Clock and Frame Pulse Frequencies

1. M= -128 to 127 defined as an 8-bit two's complement value. +ve values divide, -ve values multiply

2. N = 0 to 9270, N = 0 selects 2 kH

1.6 Configurable Input-to-Output and Output-to-Output Delays

The ZL30121 allows programmable static delay compensation for controlling input-to-output and output-to-output delays of its clocks and frame pulses.

All of the output synthesizers (SONET/SDH, P0, P1, Feedback) locked to DPLL1 can be configured to lead or lag the selected input reference clock using the **DPLL1 Fine Delay**. The delay is programmed in steps of 119.2 ps with a range of -128 to +127 steps giving a total delay adjustment in the range of -15.26 ns to +15.14 ns. Negative values delay the output clock, positive values advance the output clock. Synthesizers that are locked to DPLL2 are unaffected by this delay adjustment.

In addition to the fine delay introduced in the DPLL1 path, the SONET/SDH, P0, and P1 synthesizers have the ability to add their own fine delay adjustments using the **P0 Fine Delay**, **P1 Fine Delay**, and **SDH Fine Delay**. These delays are also programmable in steps of 119.2 ps with a range of -128 to +127 steps.

In addition to these delays, the single-ended output clocks of the SONET/SDH, P0, and P1 synthesizers can be independently offset by 90, 180 and 270 degrees using the **Coarse Delay**, and the SONET/SDH differential outputs can be independently delayed by -1.6 ns, 0 ns, +1.6 ns or +3.2 ns using the **Diff Delay**. The output frame pulses (SONET/SDH, P0) can be independently offset with respect to each other using the **FP Delay**.

Figure 7 - Phase Delay Adjustments

1.7 Master/Slave Configuration

In systems that provide redundant timing sources, it is desirable to minimize the output skew between the master and the slave's output clocks. This can be achieved by synchronizing the slave to one of the master's output clocks instead of synchronizing the slave to an external reference. If frame pulse alignment between the timing sources is required, then the crossover link should consist of a clk/fp pair.

One method of connecting two ZL30121 devices in a master/slave configuration is shown in [Figure 8](#page-19-1) where there is a dedicated crossover link between timing cards. Any of the master's unused outputs and the slave's unused inputs can be used as a crossover link.

Figure 8 - Typical Master/Slave Configuration

1.8 External Feedback Inputs

In addition to the static delay compensation described in the ["External Feedback Inputs" section on page 21](#page-20-0), the ZL30121 also provides the option of dynamic delay compensation to minimize path delay variation associated with external clock drivers and long PCB traces. This is accomplished by re-directing the internal DPLL1 feedback path to external pins and closing the loop externally as shown in [Figure 9](#page-20-1).

Figure 9 - External Feedback Configuration

2.0 Software Configuration

The ZL30121 is mainly controlled by accessing software registers through the serial peripheral interface (SPI). The device can be configured to operate in a highly automated manner which minimizes its interaction with the system's processor, or it can operate in a manual mode where the system processor controls most of the operation of the device.

The following table provides a summary of the registers available for status updates and configuration of the device.

Table 5 - Register Map

3.0 References

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