

TLD5542-1HIPOW_EVAL board

Evaluation board manual

About this document

Scope and purpose

The scope of this user manual is to provide instructions on the use of the TLD5542-1HIPOW-EVAL evaluation board.

TLD5542-1HIPOW_EVAL board is a 4-switch synchronous buck-boost regulator that demonstrates the high-power capability of the TLD5542-1. The output is adjustable from 5 V to 24 V and the maximum output current is 25 A for up to 300 W power delivery without heatsink.

The switching frequency is 250 kHz and efficiency can go up to 98%.

The board can be configured as current regulator or voltage regulator.

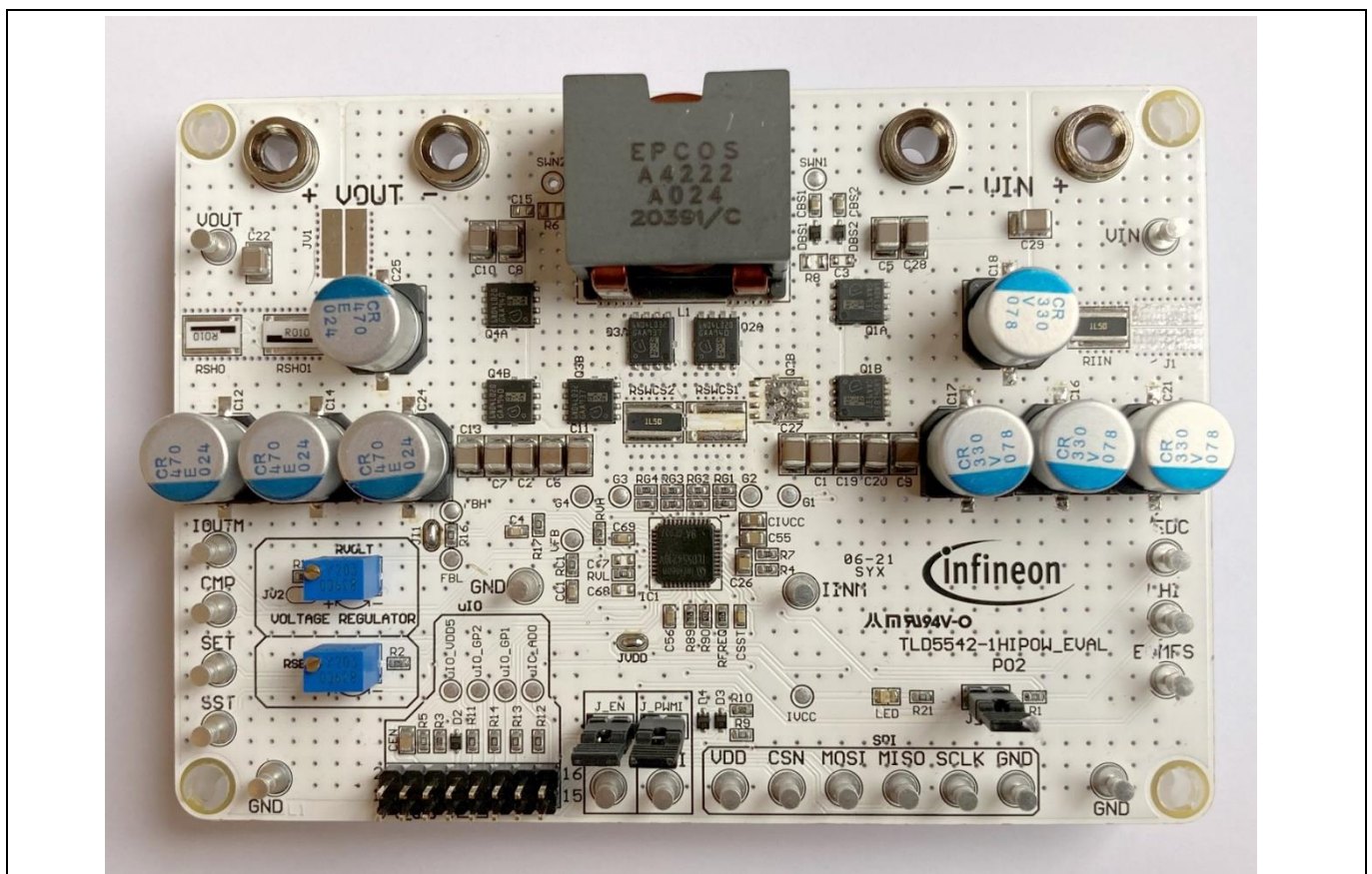


Figure 1 TLD5542-1HIPOW_EVAL device board

Intended audience

Hardware engineers, software engineers, system architects

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Description

1 Description

The H-bridge architecture is amongst the most efficient buck-boost topologies for high current applications. The TLD5542-1 provides complete control and diagnostics through the SPI interface. The TLD5542-1 can also be used in applications without microcontroller because of the limp home mode.

The TLD5542-1HIPOW_EVAL demonstrates the high-power capability of the TLD5542-1 as current or voltage regulator.

The default configuration is adjustable voltage regulator with 25 A maximum output current. By reconfiguring few solder jumps, the board becomes a current regulator for battery or supercapacitors charger applications.

The board can be controlled by the PC GUI via the Infineon μ IO stick (see Chapter 4).

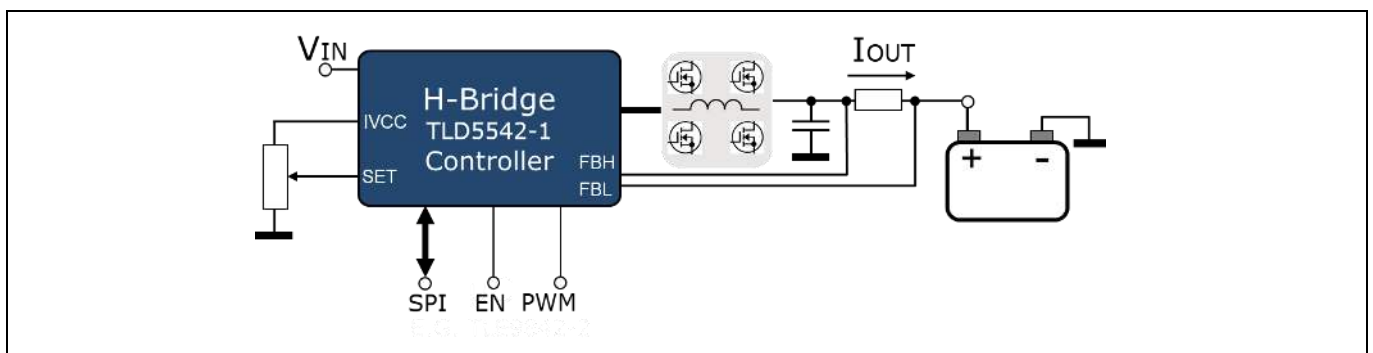


Figure 2 TLD5542-1 as battery charger

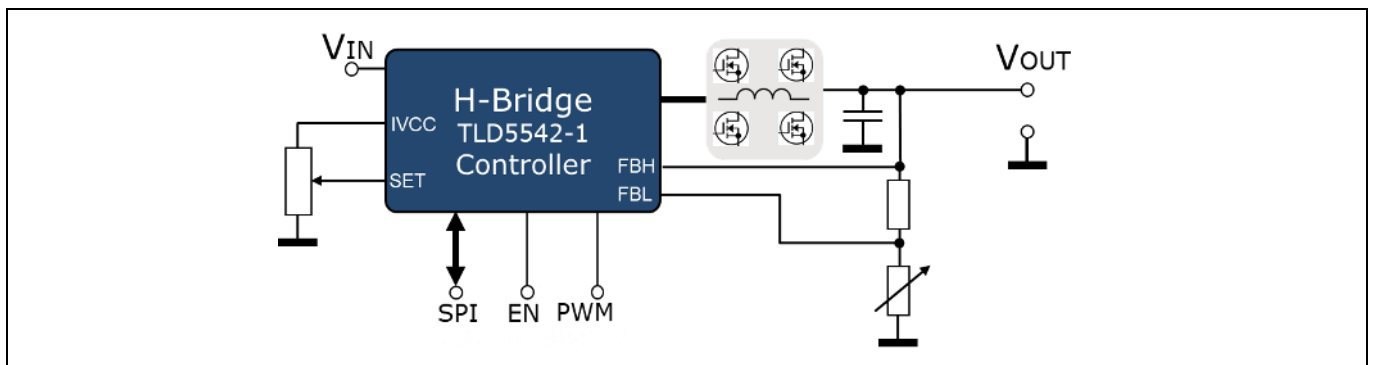


Figure 3 TLD5542-1 as voltage regulator

There are 2 trimmers, RVOLT and RSET, to easily adjust output voltage and output current in the entire range (see table 6).

2 Quick start procedure

Below, step by step procedures are laid out for setup and running the TLD5542-1HIPOW_EVAL in all available configurations.

Installation procedure for PC GUI (graphical user interface) and μ IO stick interface is described in Chapter 4.

2.1 Setup as current regulator with no microcontroller

Setup of the board as simple current regulator, without a microcontroller connection and without μ IO stick nor PC GUI.

The device is configured in limp home. All the registers are set to their default value and the analog dimming is provided by the voltage on the SET pin which is adjustable with RSET trimmer.

Table 1 Jumper reference and setup for current regulator

Jumper reference	Status	Description
JV1	OPEN	Bypass output current shunt resistor
JV2	OPEN	Disconnect voltage regulator feedback voltage divider
J11	CLOSE	Connect current shunt
JVDD	CLOSE	Connect Internal 5V IVCC to VDD
J1	CLOSE	Bypass input current shunt resistor

In order to run the board in this configuration

1. Configure solder jumper for LED driver configuration as in Figure 4
2. Connect LHI (limp home) and J_PWM1 jumpers

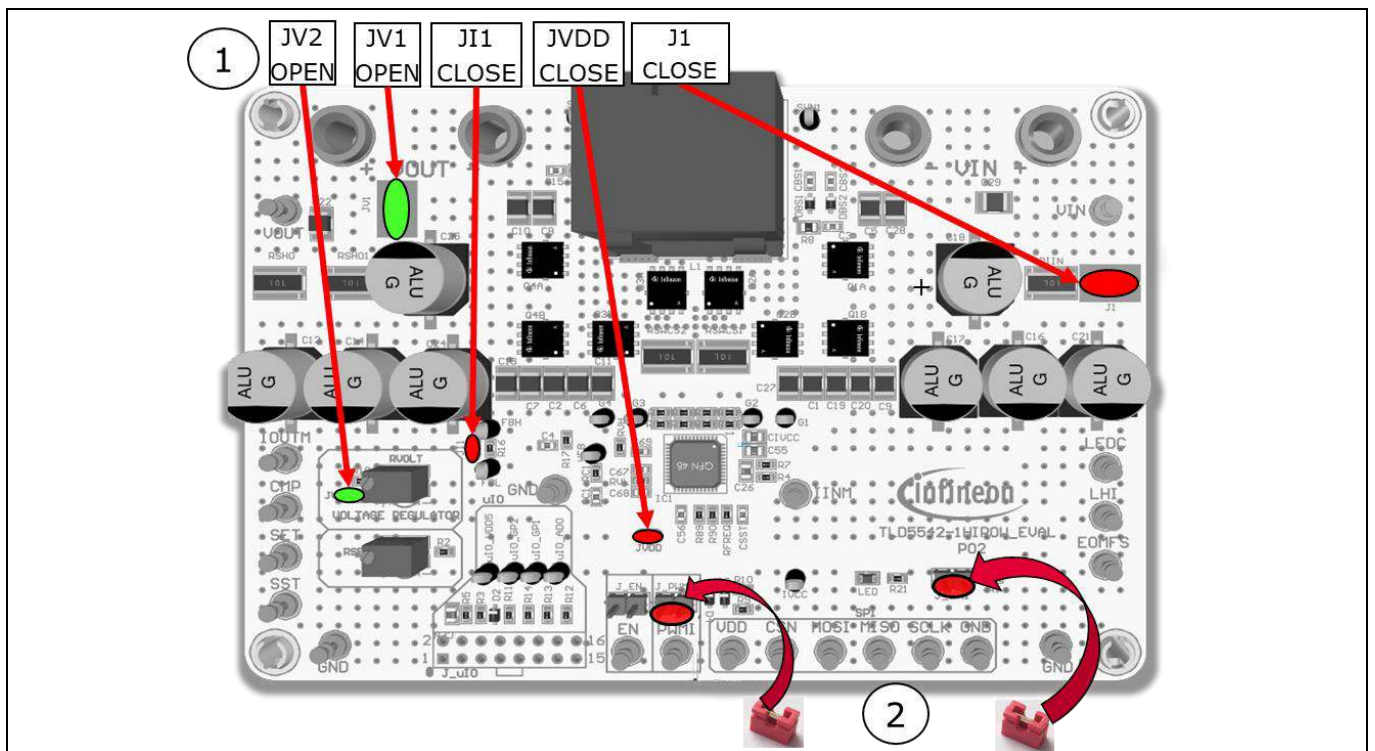


Figure 4 Jumpers to be set for current regulator mode no μ C

Quick start procedure

3. Connect the load (Note that the output current can be as high as 30 A if SET is adjusted to maximum)
4. Connect a 12 V power supply to the V_{IN} connector
5. Rotate RSET trimmer completely anti-clockwise to lower the output current to the minimum
6. Connect the EN jumper to start providing output current to the load
7. Adjust I_{OUT} with RSET (output current should be higher than 2 A for better transient response)

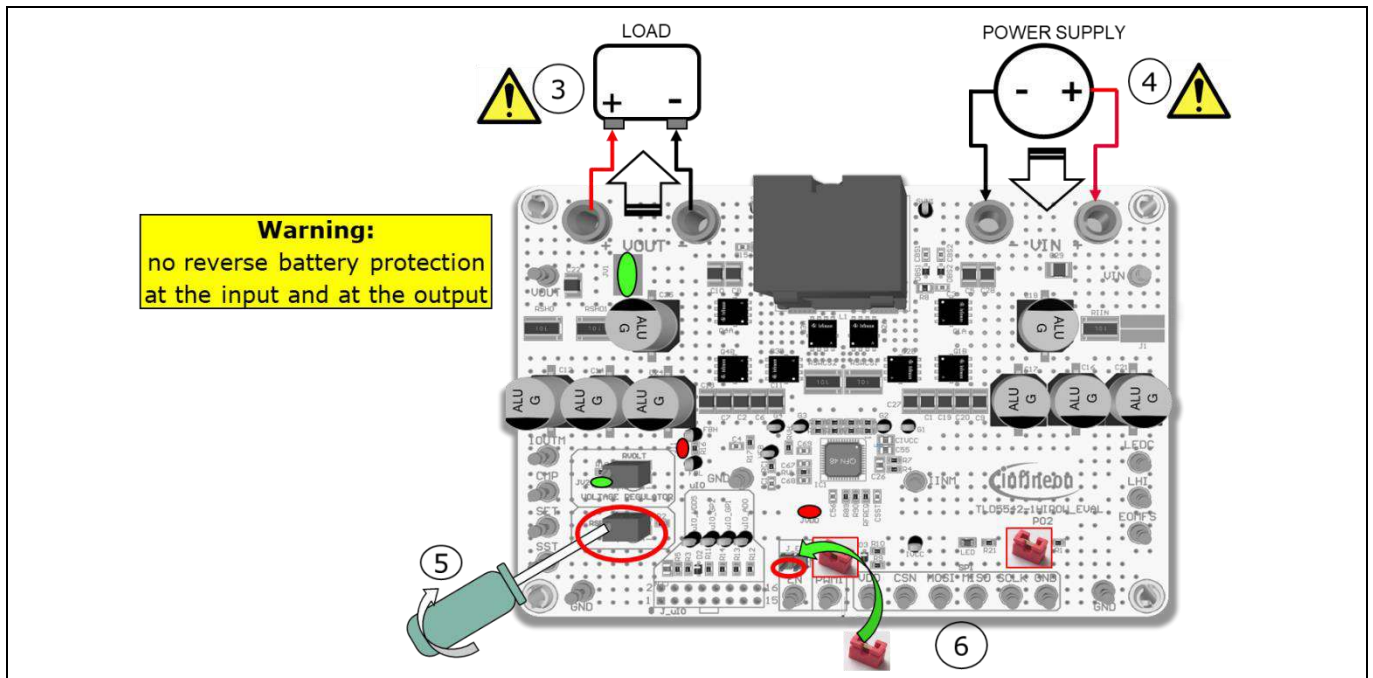


Figure 5 Connect power supply and load, adjust output current

Warning:

1. If the load is a battery or a supercapacitor, do not use PWMI to stop output current, use EN instead. Otherwise, the device will affect a startup without soft-start assistance sinking high current from the charging battery at the V_{OUT} connector.
2. The board is not reverse protected at the input nor at the output, if a battery is connected with reverse polarity the board or the battery may catch fire.

Correct start-up sequence, to provide current at the load is:

- Set EN to ON with PWMI kept to OFF (blue LED on the PCB turns ON)
- Set desired analog dimming level by using SET pin if limp home mode, otherwise operate via SPI
- Set PWMI to ON

2.2 Board set up as voltage regulator with no microcontroller nor PC GUI

The following describes how to setup the board as a simple voltage regulator without PC GUI. No microcontroller connection and no μ IO stick is present.

Table 2 Jumper reference and setup for voltage regulator

Jumper reference	Status	Description
JV1	CLOSE	Bypass output current shunt resistor
JV2	CLOSE	Connect voltage regulator feedback voltage divider
J11	OPEN	Disconnect current shunt from FBL
JVDD	CLOSE	Connect Internal 5V IVCC to VDD
J1	CLOSE	Bypass input current shunt resistor

1. Configure all solder jumpers as shown in Figure 6
2. Connect J_EN, LHI and PWMI jumpers

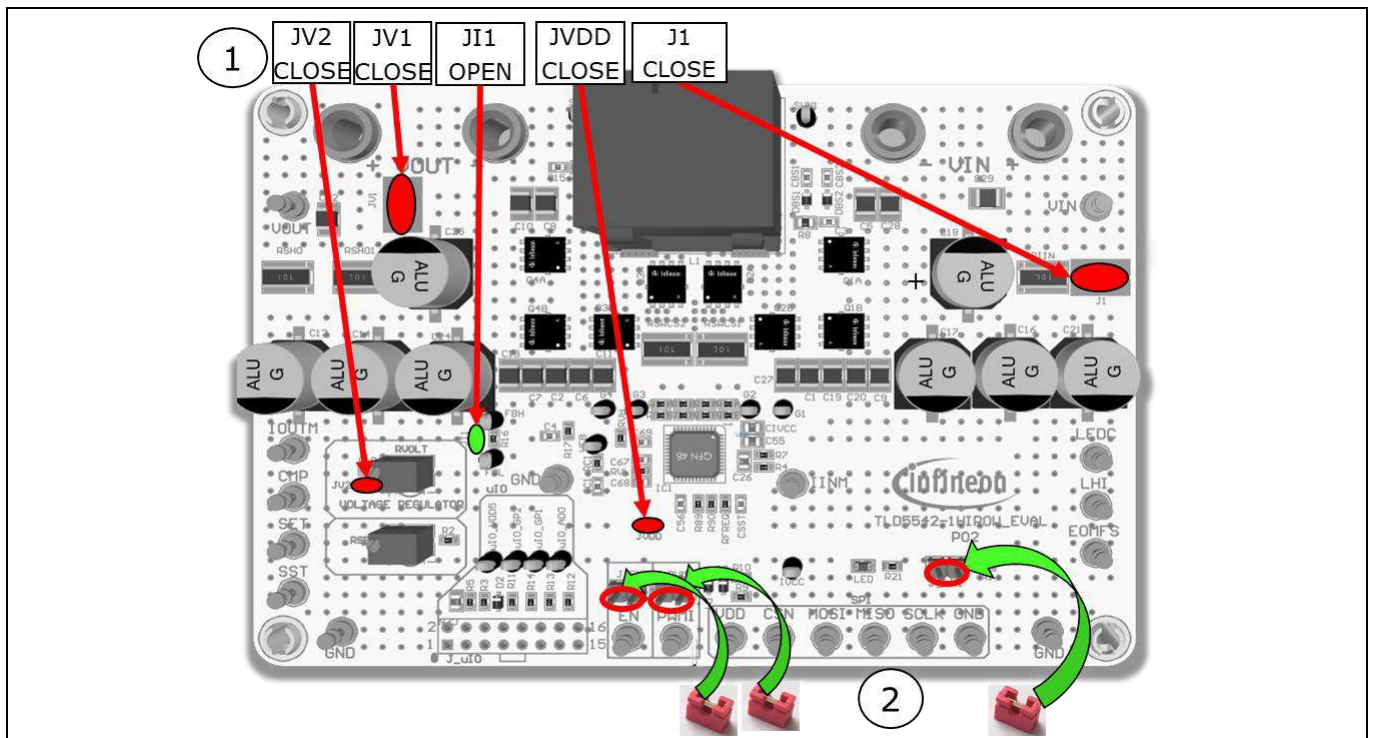


Figure 6 Jumpers to be set for voltage regulator mode no μ C

3. Connect a 12 V power supply to the V_{IN} connector
4. Rotate RSET trimmer completely clockwise (100% analog dim, improves transient response and accuracy)

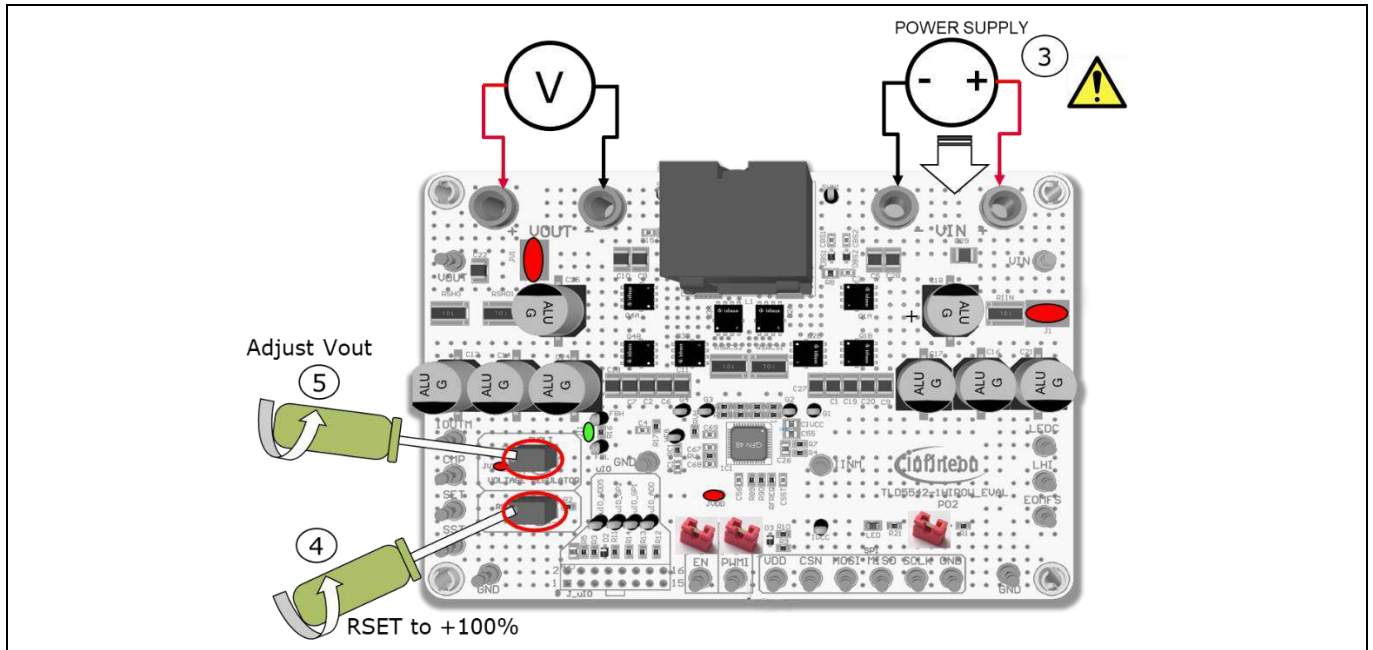


Figure 7 Connect power supply, turn RSET to maximum and adjust V_{OUT} with RVOLT

5. Rotate RVOLT trimmer to obtain the desired V_{OUT}
6. Connect the load to V_{OUT}

2.3 Board set up as voltage/current regulator with PC GUI

The TLD5542-1 HIPOW_EVAL can be controlled by the PC GUI via a μ IO stick. All the plug jumpers have to be removed, or the μ IO will not be able to control the TLD5542-1 properly.

1. Set solder jumpers for voltage (Chapter 2.1) or current (Chapter 2.2) regulator
2. Remove jumper plugs J_LHI, J_PWM, J_EN

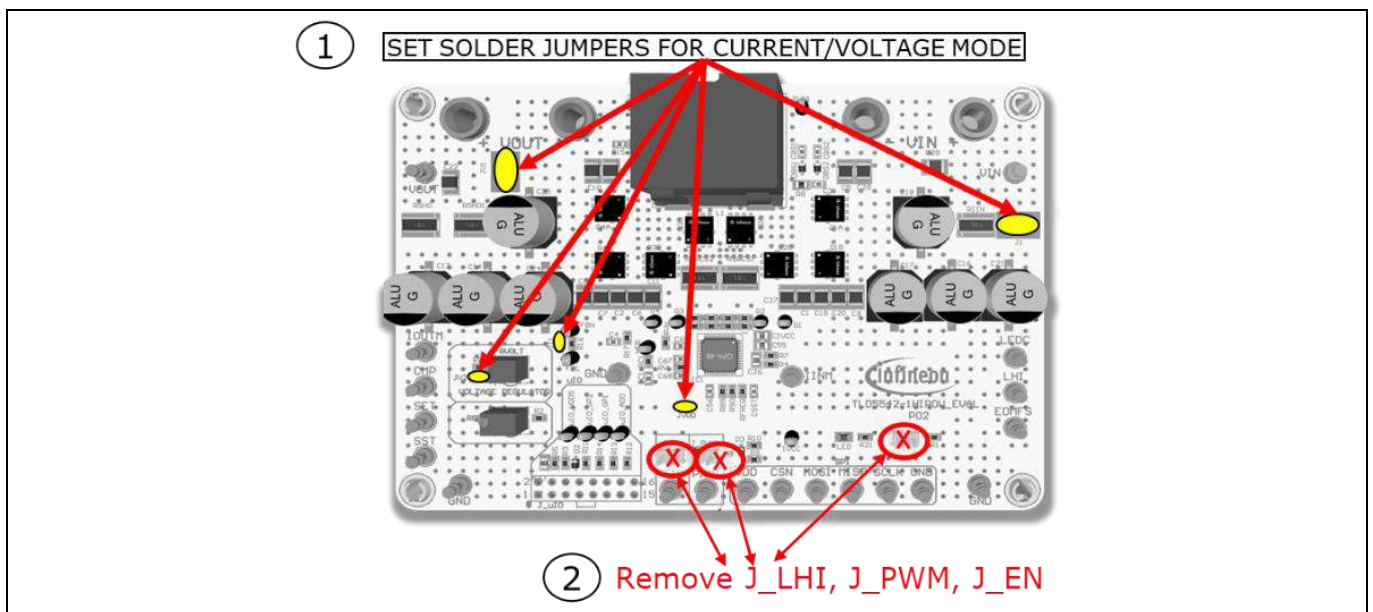


Figure 8 Control with μ IO stick board preparation

3. Connect the μ IO to J_uIO connector (pin 1 mark on PCB on RED cable strip) and uIO stick to the PC

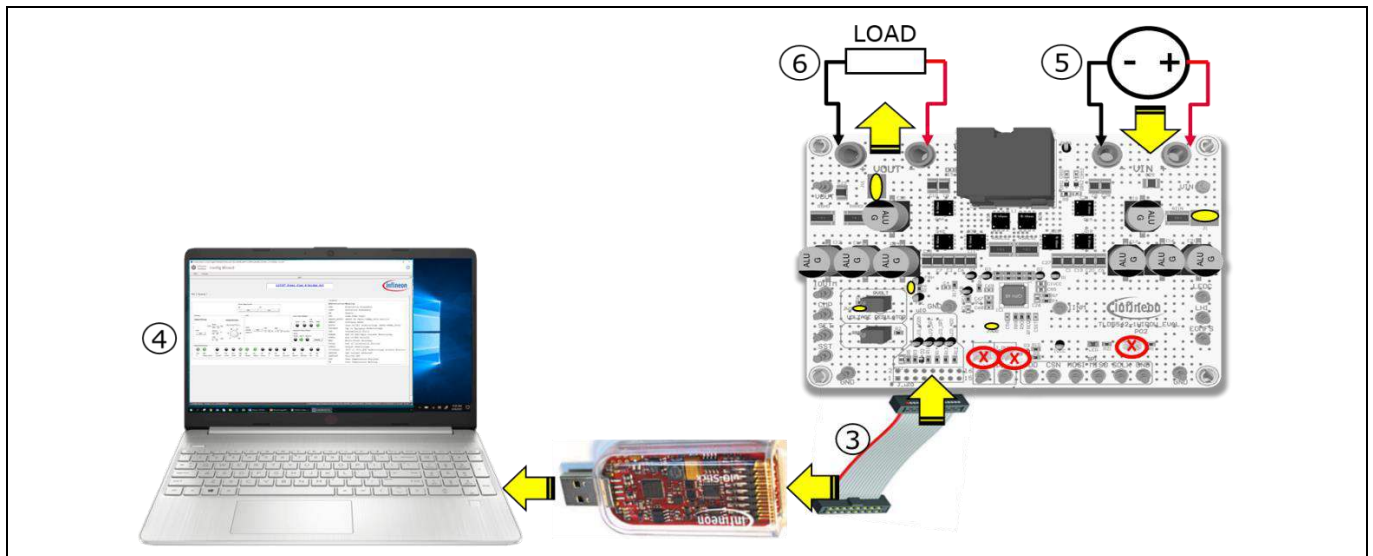


Figure 9 Connect μ IO stick, power supply, load

4. Launch Infineon Toolbox and the Config Wizard for LED, see chapter 3.1
5. Connect power supply to the V_{IN} connector
6. Adjust for the desired output current/voltage with the GUI (see Chapter 4) and connect the load

3 Infineon μ O stick and Infineon Toolbox

The Infineon μ O stick is an interface device for controlling Infineon boards/kits during run time through PC.

- Enables the connection between the evaluation board and USB for SPI programming and monitoring by using the [Config Wizard](#) software, which can be downloaded via the [Infineon Toolbox \[1\]](#)
- Plugs into the evaluation board via a standard 16-pin connector and allows easy interface to the microcontroller via USB for SPI, CAN and LIN communication



Figure 10 Infineon μ O stick

The Infineon Toolbox it is a single platform interface which allows for:

- Quick installation of tools by name or QR code
- Help with documentation
- Viewing and starting installed tools from built-in launcher
- Receiving update notifications



Figure 11 Infineon Toolbox

For details about Infineon toolbox and μ O stick check the Infineon website: [Infineon Toolbox](#).

3.1 Install and launch Config Wizard

1. Open the “Manage tools” tab
2. Search for “Config Wizard for LED” and click on “Install” button

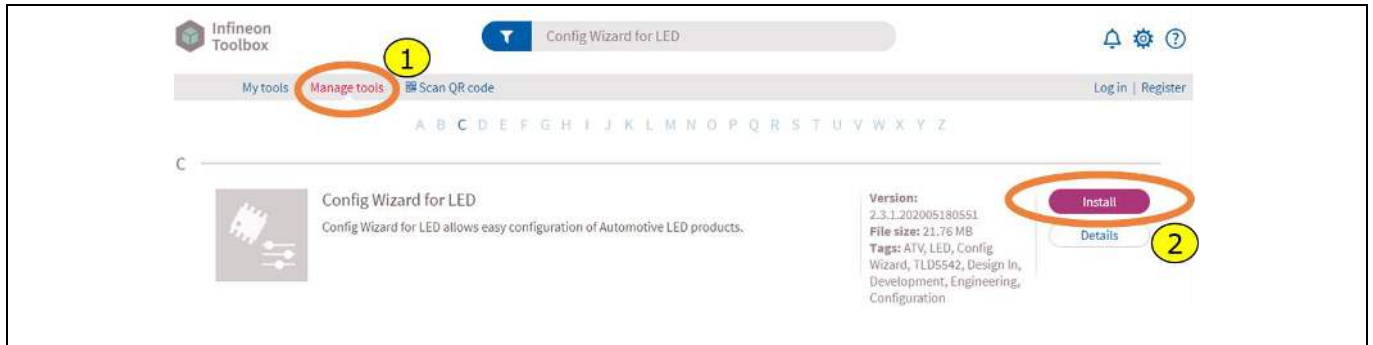


Figure 12 Install Config Wizard for LED

3. Select “My Tools” tab on Infineon Toolbox
4. Press “Start” on the config wizard for LED to start

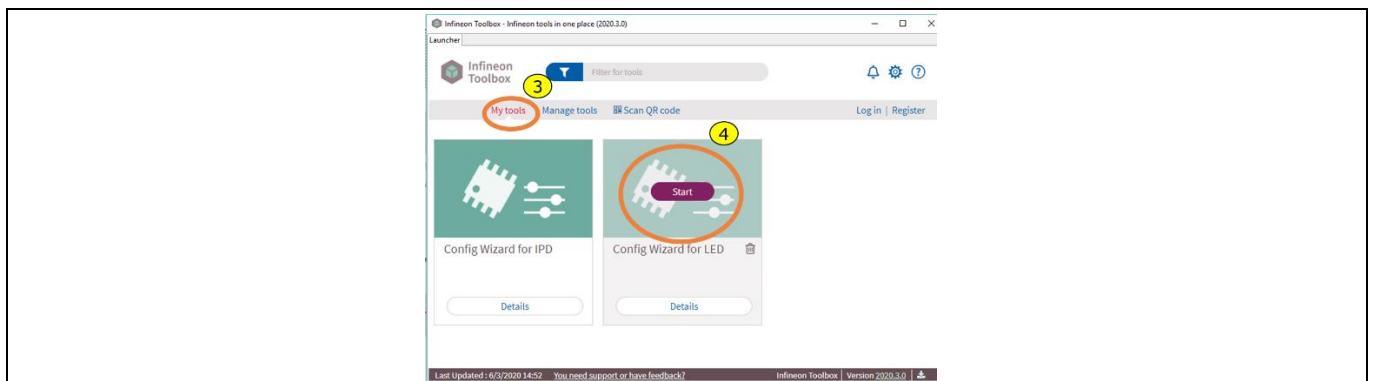


Figure 13 Start Config Wizard tool

5. Click on TLD5542-1 icon to start the LED GUI interface

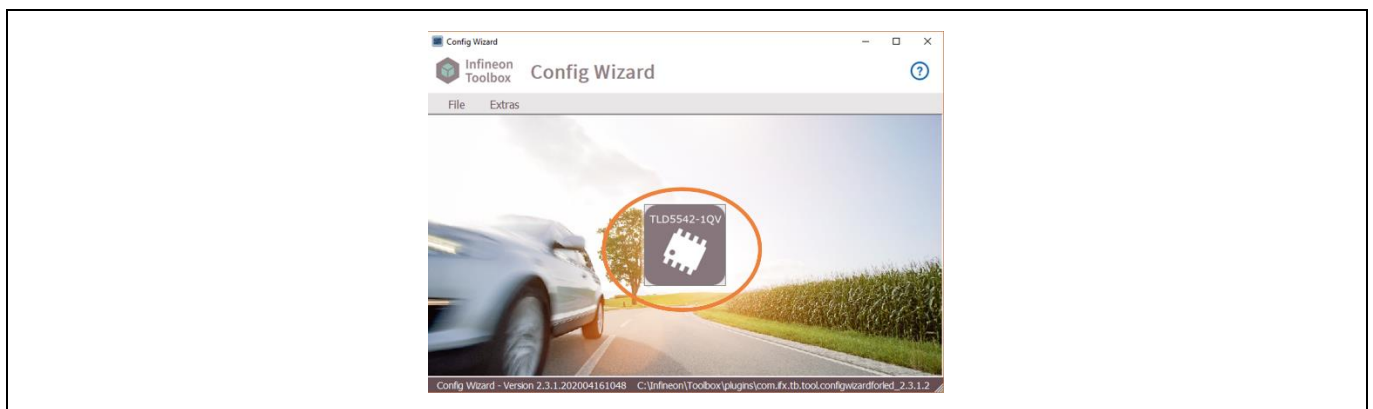


Figure 14 Launch TLD5542-1 GUI

4 Board control with PC GUI

The TLD5542-1 PC GUI consists of 2 interfaces:

- Basic user interface
- Engineering user interface

The GUI works only if the TLD5542-1 evaluation board is correctly connected to the μ IO stick and power supply is applied to the V_{IN} connector.

4.1 Basic user interface

Basic user interface allows simplified access to the main registers on TLD5542-1 (e.g. analog dimming with a knob) and provides direct feedback on TLD5542-1 status, showing indicators for each standard diagnosis register bit.

It is possible to provide EN signal and PWMI without the need for a function generator.

In order to turn on the device press the EN button, the “Active” indicator shall turn on.

Only once the device is on, the desired analog dimming value can be set by the “Analog Dimming” knob on the “Dimming” tab.

Correct startup sequence is:

- Have a power supply connected at V_{IN}
- Set EN to ON with PWMI kept to OFF (blue LED on the PCB turns ON)
- Set desired analog dimming level (RSET trimmer if limp home mode otherwise via GUI)
- Set PWMI to ON

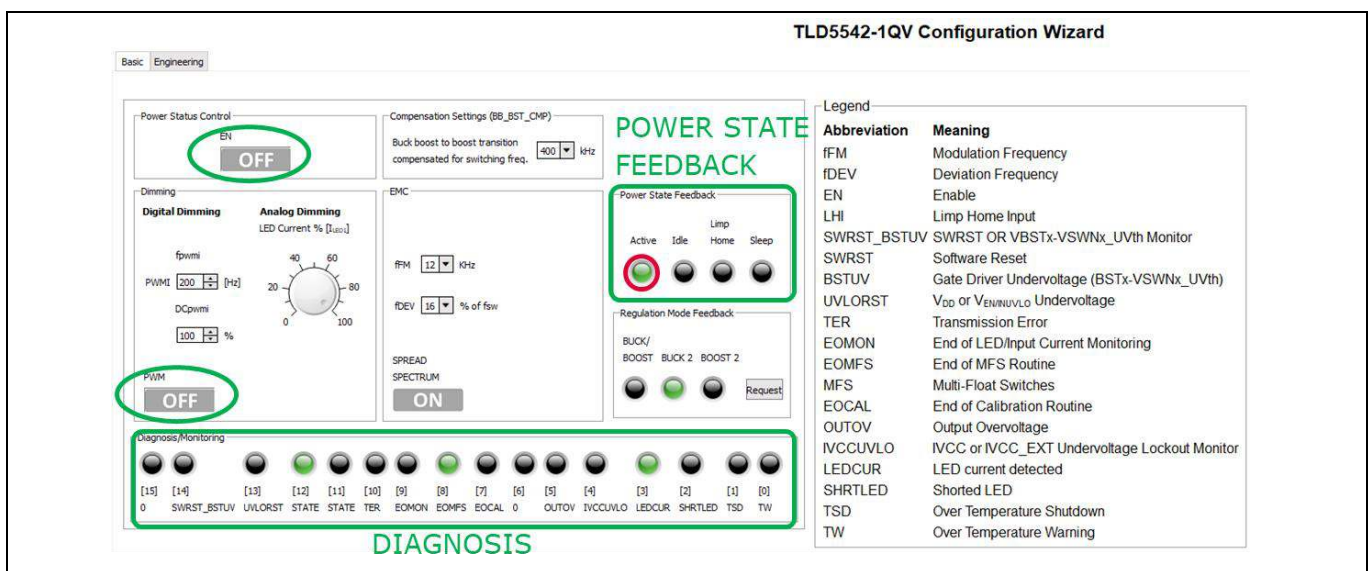


Figure 15 TLD5542-1 GUI – Basic user interface

On the “Diagnosis/Monitoring” tab, (see Figure 15) the standard diagnosis register is provided, showing information on the working status of the device.

TLD5542-1HIPOW_EVAL board

Evaluation board manual

Board control with PC GUI

On the “Compensation Setting” tab (see Figure 16), it is possible to tune the compensation transfer function in order to have the smoothest transition from buck-boost to boost mode, which depends on the switching frequency (385 kHz for the TLD5542-1 HIPOW_EVAL board)

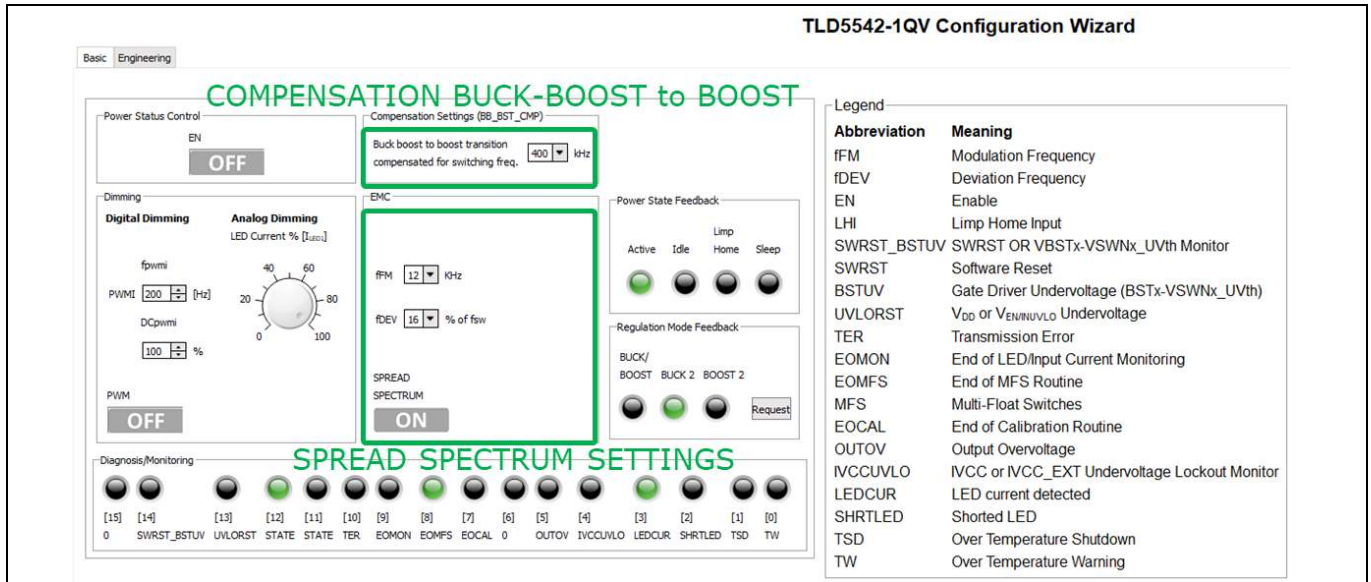


Figure 16 TLD5542-1 GUI basic user interface – compensation and EMC tabs

4.2 Engineering user interface

The engineering user interface allows the user to send a sequence of SPI commands to the TLD5542-1. PWMI and EN pin control is also possible on this interface.

The suggested sequence of operations in order to send the SPI commands is as follows:

1. Write the list of SPI commands that has to be sent
2. Turn on the device by pressing the EN button
3. Press the SEND button to send commands on the list, starting from the black row in the list Figure 17
4. Enable the switching activity by pressing PWMI button

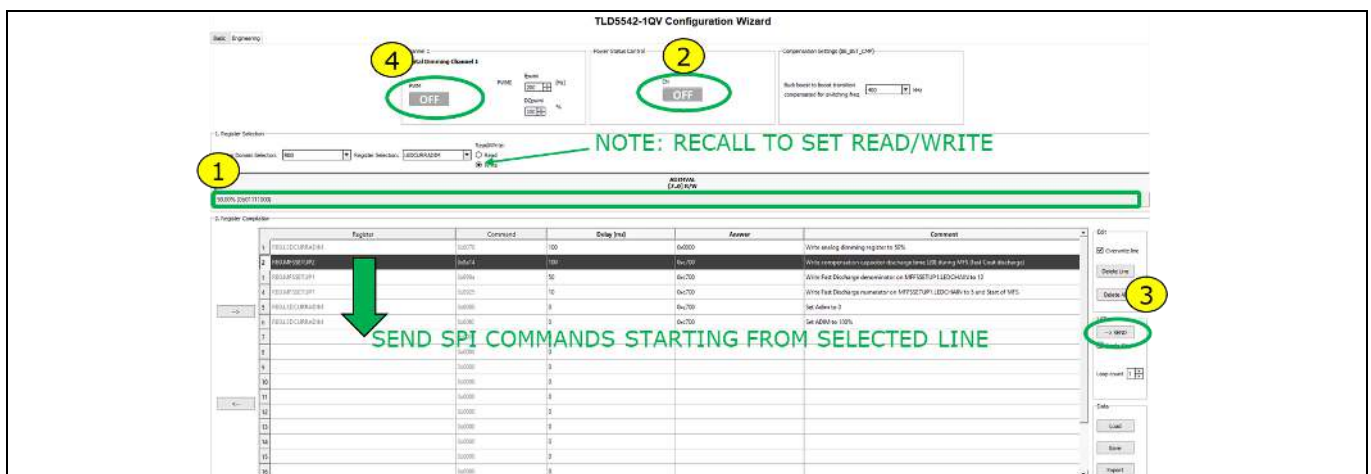


Figure 17 TLD5542-1 GUI – Engineering user interface

It is possible to describe each command with a comment and to save the list of commands by clicking on the “Save” button.

It is possible to set the delay applied before executing the next command in the “Delay” column, the accuracy of the timer is approximately 10 ms.

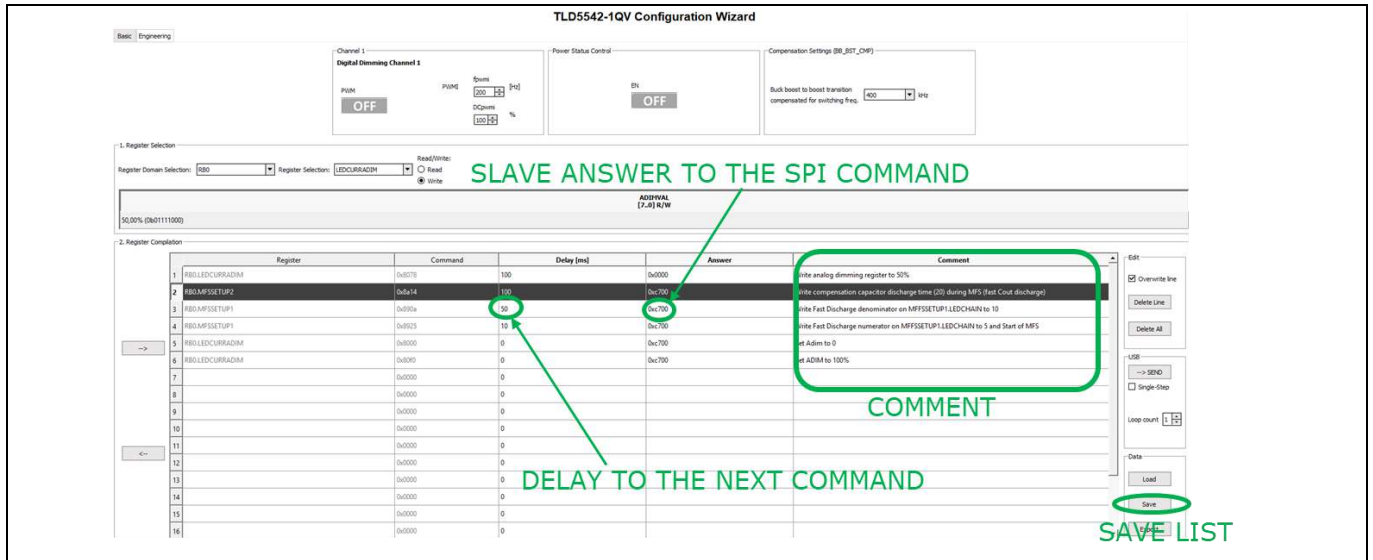


Figure 18 TLD5542-1 GUI – writing comment - saving command list - delay between commands

5 Operating range and power derating

The TLD5542-1HIPOW-EVAL has very high efficiency, so it can deliver up to 300 W at the output without a heatsink at $T_A = 25^\circ\text{C}$, for V_{IN} down to 9 V.

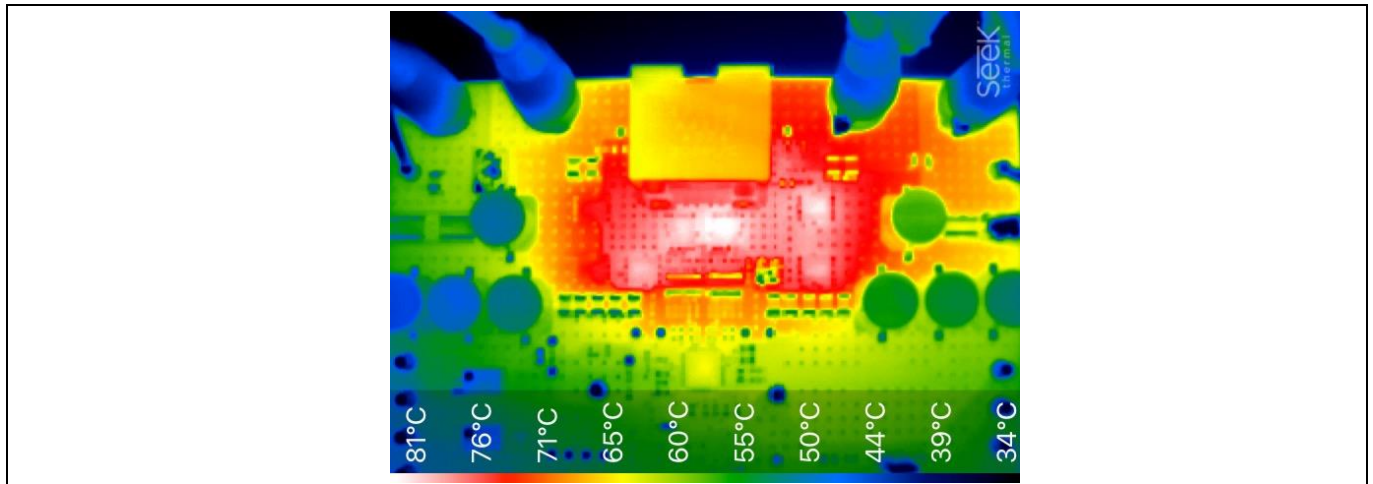


Figure 19 Thermal acquisition, voltage REG, $V_{IN} = 12\text{ V}$, $V_{OUT} = 12\text{ V}$, $I_{OUT} = 25\text{ A}$, $T_A = 25^\circ\text{C}$ no heatsink

Please note that the module does not implement thermal protection, so ensure proper cooling when output power exceeds the power-derating curve. The heatsink must be positioned below the switching MOSFETs as shown in Figure 20.

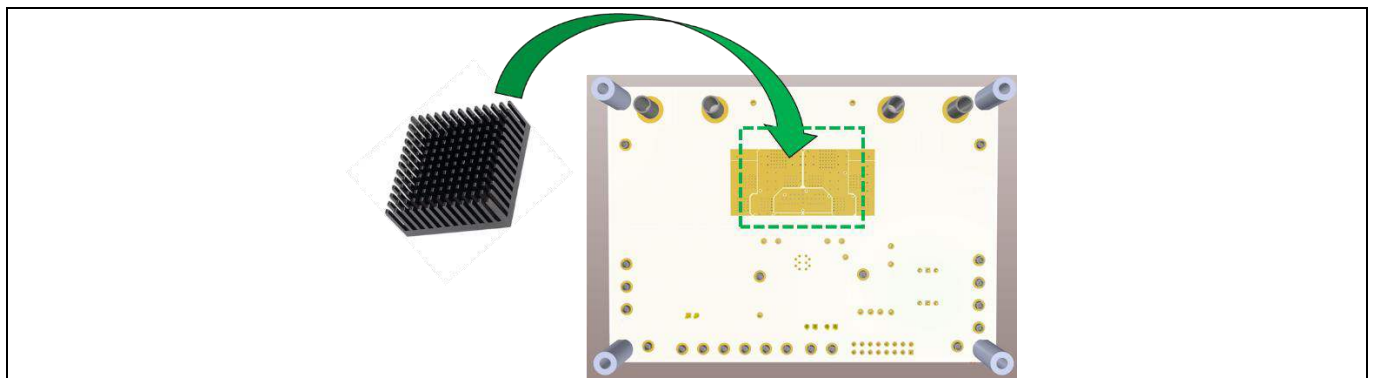


Figure 20 Optional heatsink placement

The heatsink shall be electrically insulated from the PCB, by means of a thermal pad.

6 Electrical characteristics

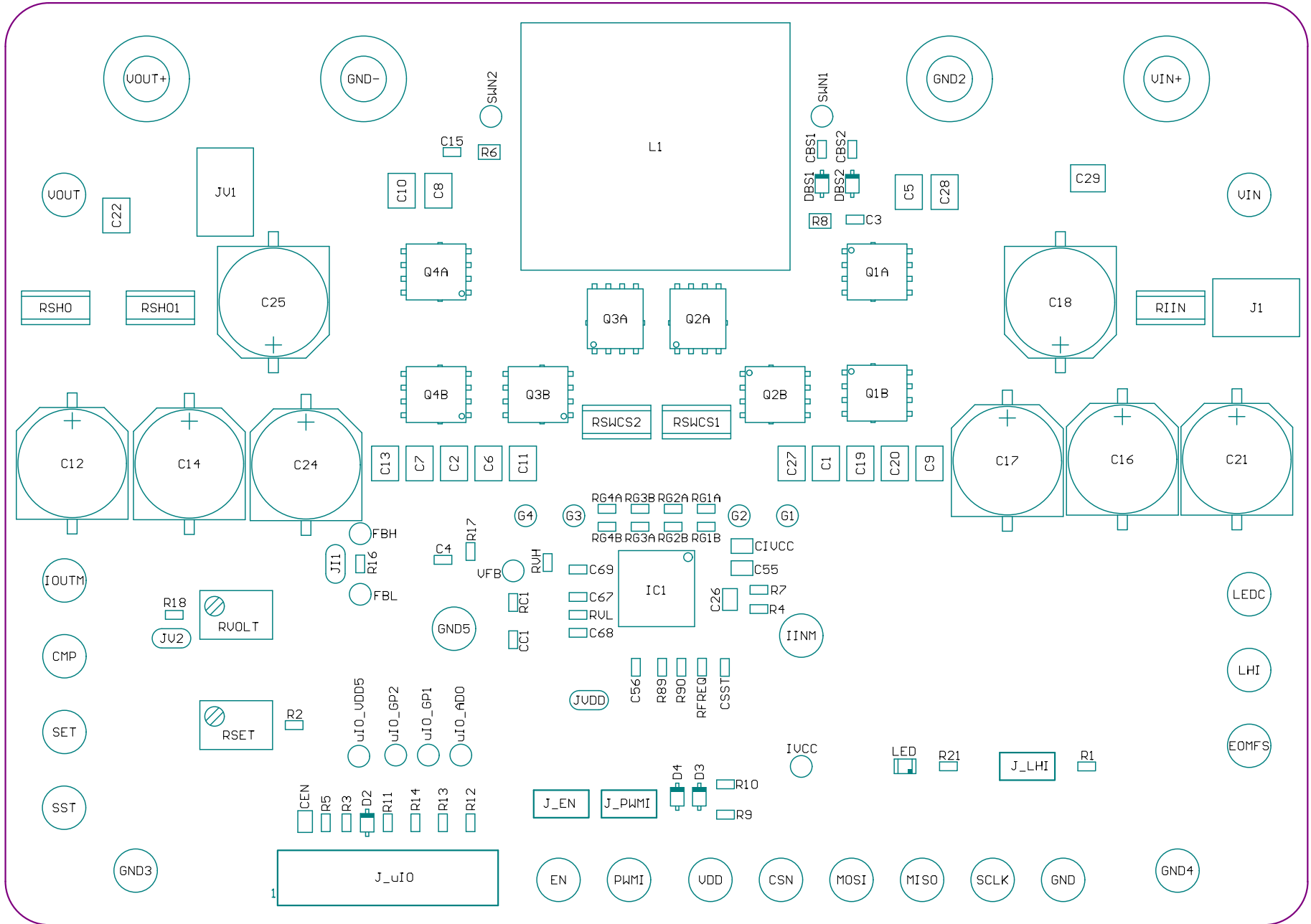
Table 3 TLD5542-1 HIPOW -EVAL version S03 P01 – electrical characteristics

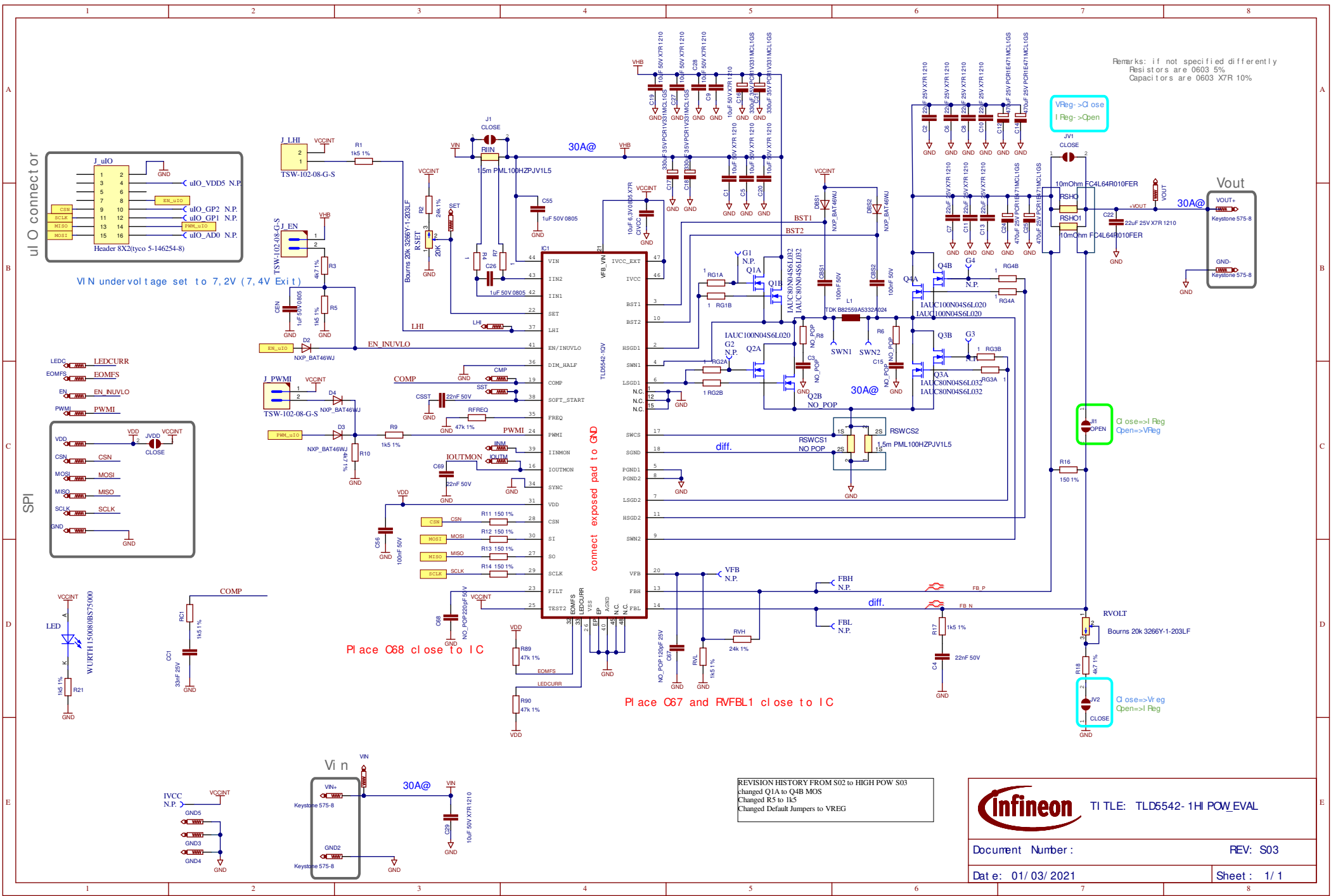
Parameter	Symbol	Value			Unit	Note/Test Condition
		Min.	Typ.	Max.		
Input voltage	V_{IN}	7.5	–	35	V	Power derating may occur for $V_{IN} < 9\text{ V}$
Output voltage	V_{OUT}	2	–	24	V	Current regulator mode Voltage regulator mode
		5	–	24		
Output current	I_{OUT}	0	–	25	A	
Output power	P_{OUT}	-	300	–	W	No heatsink V_{IN} 9 V to 35 V, $T_A = 25^\circ\text{C}$
			400		W	With heatsink V_{IN} 9 V to 35 V, $T_A = 25^\circ\text{C}$
Switching frequency	Switching frequency	–	250	–	kHz	Spread spectrum deviation is present
PWM frequency	PWM_{freq}	100	–	500	Hz	–
System efficiency	η	–	97	–	%	Voltage mode: $V_{IN} = 12\text{ V}$ $V_{OUT} = 12\text{ V}$ $I_{OUT} = 25\text{ A}$
			96			Current mode: $V_{IN} = 12\text{ V}$ $V_{OUT} = 12\text{ V}$ $I_{OUT} = 20\text{ A}$

7 Bill of material, PCB layout and schematic

Table 4 Bill of material

Designator	Value	Footprint	Quantity
C1, C5, C9, C19, C20, C27, C28, C29	10 μ F 50V X7R 1210	C1210	8
C2, C6, C7, C8, C10, C11, C13, C22	22 μ F 25V X7R 1210	C1210	8
C4, C69, CSST	22nF 50V	C0603	3
C12, C14, C24, C25	470 μ F 25V PCR1E471MCL1GS	CE D10 CASE G	4
C16, C17, C18, C21	330 μ F 35V PCR1V331MCL1GS	CE D10 CASE G	4
C26, C55, CEN	1 μ F 50V 0805	C0805	3
C56, CBS1, CBS2	100nF 50V	C0603	3
CC1	33nF 25V	C0603	1
CIVCC	10 μ F 6,3V 0805 X7R	C0805	1
CMP, CSN, EN, EOMFS, GND, GND3, GND4, GND5, IINM, IOUTM, LEDC, LHI, MISO, MOSI, PWMI, SCLK, SET, SST, VDD, VIN, VOUT	Mill-Max 2501-2-00-80-00-00-07-0	–	21
D2, D3, D4, DBS1, DBS2	NXP_BAT46WJ	SOD323F	5
GND2, GND-, VIN+, VOUT+	Keystone 575-8		4
IC1	TLD5542-1QV	VQFN48 7X7 P05	1
J_EN, J_LHI, J_PWM1	TSW-102-08-G-S	CON-M-THT-TSW-102-08-G-S	3
J_uIO	Header 8X2(tyco 5-146254-8)	HDR2X8	1
L1	TDK B82559A5332A024	IND SMD B82559A	1
LED	WURTH 150080BS75000	LED 0805 BLU	1
Q1A, Q1B, Q3A, Q3B	IAUC80N04S6L032	PG-TDSON-8-33	4
Q2A, Q4A, Q4B	IAUC100N04S6L020	PG-TDSON-8-33	3
R1, R9, R17, RC1, RVL, R5, R21	1.5k Ω 1%	R0603	7
RFREQ,R89, R90	47k Ω 1%	R0603	3
R3,R10,R18	4.7k Ω 1%	R0603	3
R4, R7, RG1A, RG1B, RG2A, RG2B, RG3A, RG3B, RG4A, RG4B	1 Ω	R0603	10
R11, R12, R13, R14, R16	150 Ω 1%	R0603	5
R2,RVH	24k Ω 1%	R0603	2
RSET, RVOLT	Bourns 3266Y-1-203LF	–	2
RSHO1,RSHO	10m Ω FC4L64R010FER	–	2
RSWCS2,RIIN	1.5m Ω PML100HZPJV1L5	–	2
C3, C15, C67, C68, FBH, FBL, G1, G2, G3, G4, IVCC, SWN1, SWN2, uIO_AD0, uIO_GP1, uIO_GP2, uIO_VDD5, VFB, Q2B, R6, R8, RSWCS1	NOT POPULATED	–	–
Spacer 12mm	Würth 702935000	–	4



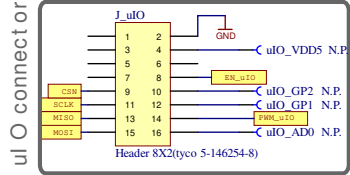


Remarks: if not specified differently
Resistors are 0603 5%
Capacitors are 0603 X7R 10%

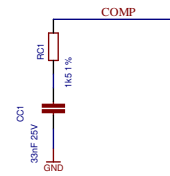
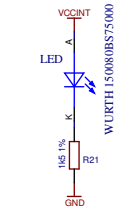
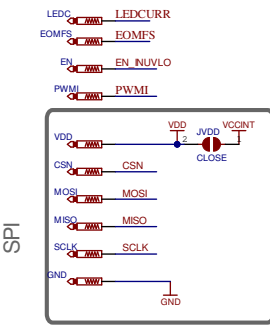
VReg->C use
I Reg->Open

Ci ose=>I Reg
Open=>VReg

Ci ose=>Vr eg
Open=>I Reg



VI n undervoltage set to 7,2V (7,4V Exit)



Place C68 close to IC

Place C67 and RVFBL1 close to IC

REVISION HISTORY FROM S02 to HIGH POW S03
Changed Q1A to Q4B MOS
Changed R5 to R5
Changed Default Jumpers to VREG

Infineon TI TLE: TLD5542-1HI POW_EVAL

Document Number: REV: S03

Date: 01/03/2021 Sheet: 1/1

8 List of references

[1] Infineon Toolbox and Config Wizard www.infineon.com

Revision history

Document version	Date of release	Description of changes
Rev.1.0	2021-03-04	Initial User Manual

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Document reference

UM TLD5542-1HIPOW_EVAL

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