

## 12 V/24 V smart analog high-side MOSFET gate driver

### Features

- PRO-SIL™ ISO 26262-ready for supporting the integrator in evaluation of hardware element according to ISO 26262:2018 Clause 8-13
- One channel device with two high-side gate driver outputs
- 3  $\Omega$  pull-down, 50  $\Omega$  pull-up for fast switch on/off
- Support back-to-back MOSFET topologies (common drain and common source)
- Two bidirectional high-side analog current sense interfaces with externally adjustable gain
- Adjustable overcurrent/short-circuit protection
- Versatile comparator to implement: adjustable I-t wire protection, overvoltage/undervoltage or overtemperature protection



### Potential applications

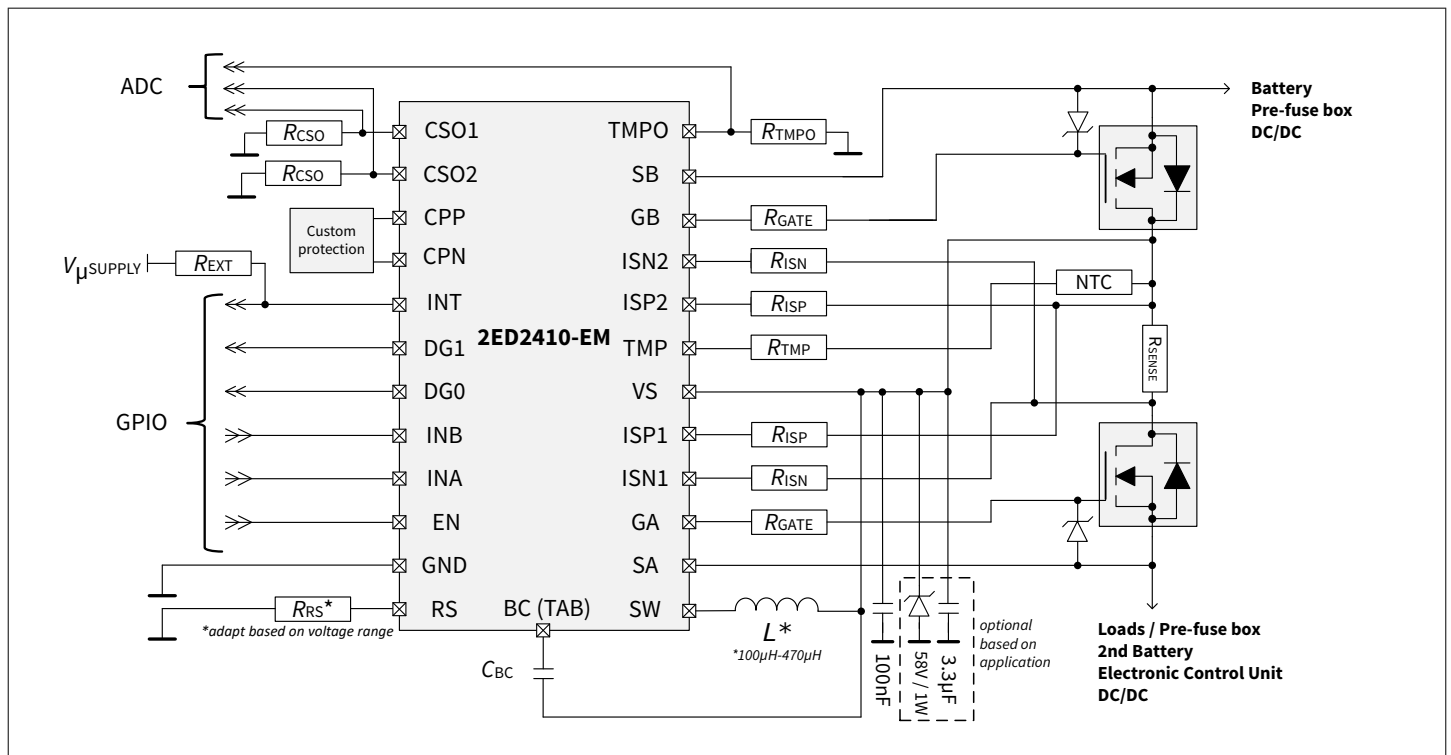
- Fail operational power supply targeting high current applications
- Connection/isolation switch between power supplies (e.g. for hybrids and electric vehicles)
- Developed to support dependable power supply and distribution

### Product validation

Qualified for automotive applications. Product validation according to AEC-Q100, Grade 1.

### Description

2ED2410-EM is a one channel gate driver with two independent gate outputs for 12 / 24 V automotive applications. It offers several protection features for connecting/disconnecting loads or different power supplies.



Typical application example

Product type	Package	Marking
2ED2410-EM	PG-TSDSO-24	2ED2410-EM

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1 Block diagrams

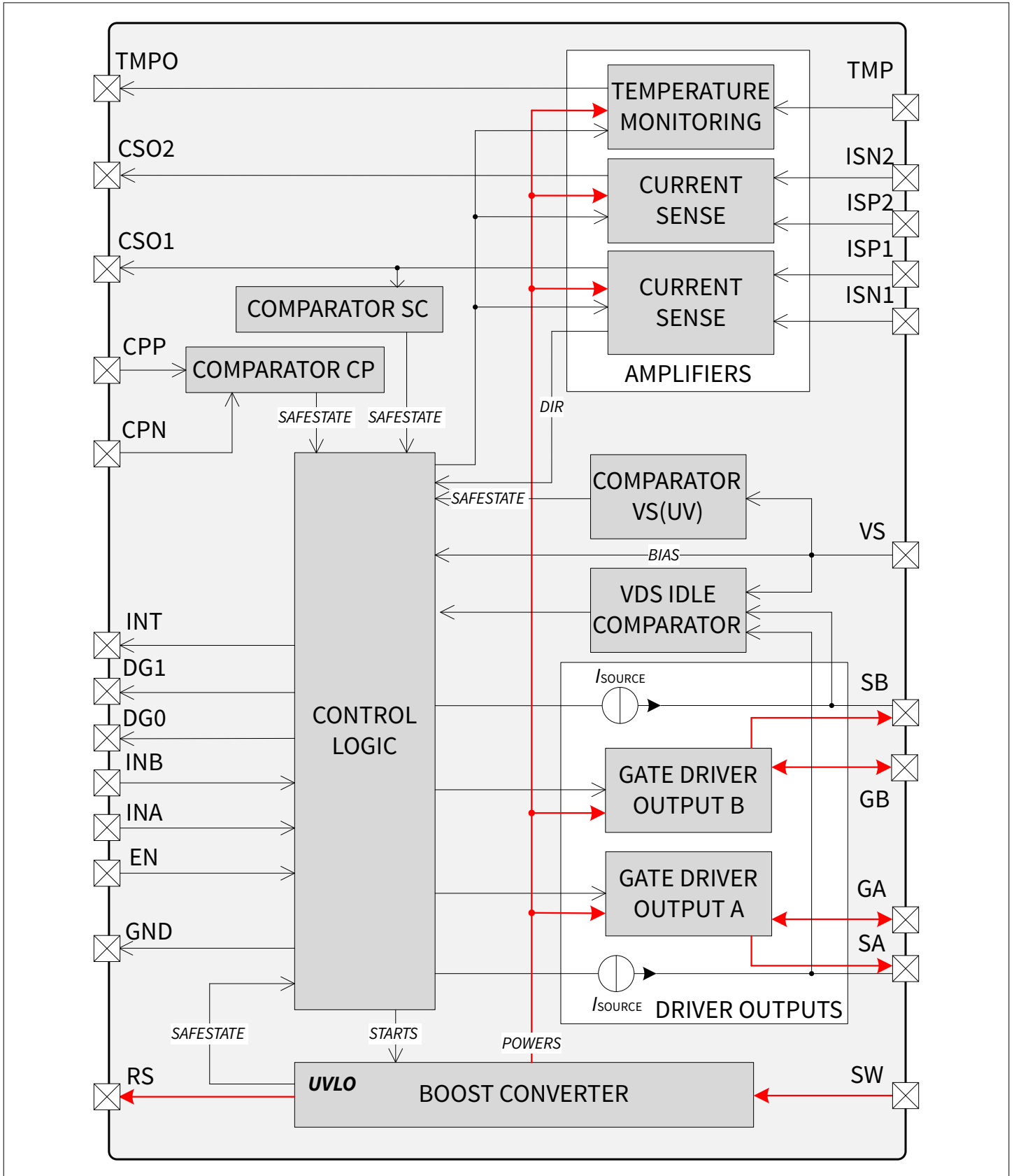


Figure 2 Functional block diagram

1 Block diagrams

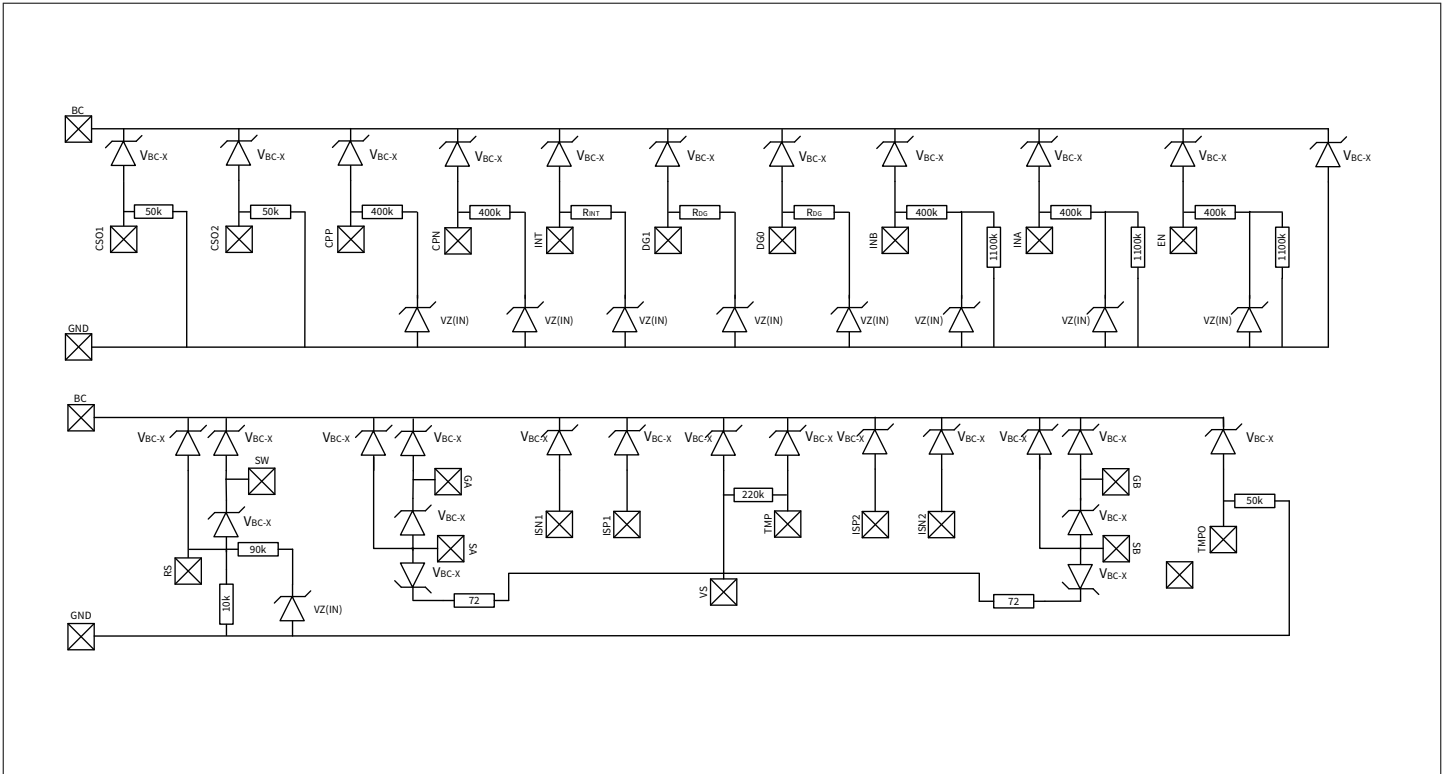


Figure 3 Diodes block diagram

## 2 Pin configuration

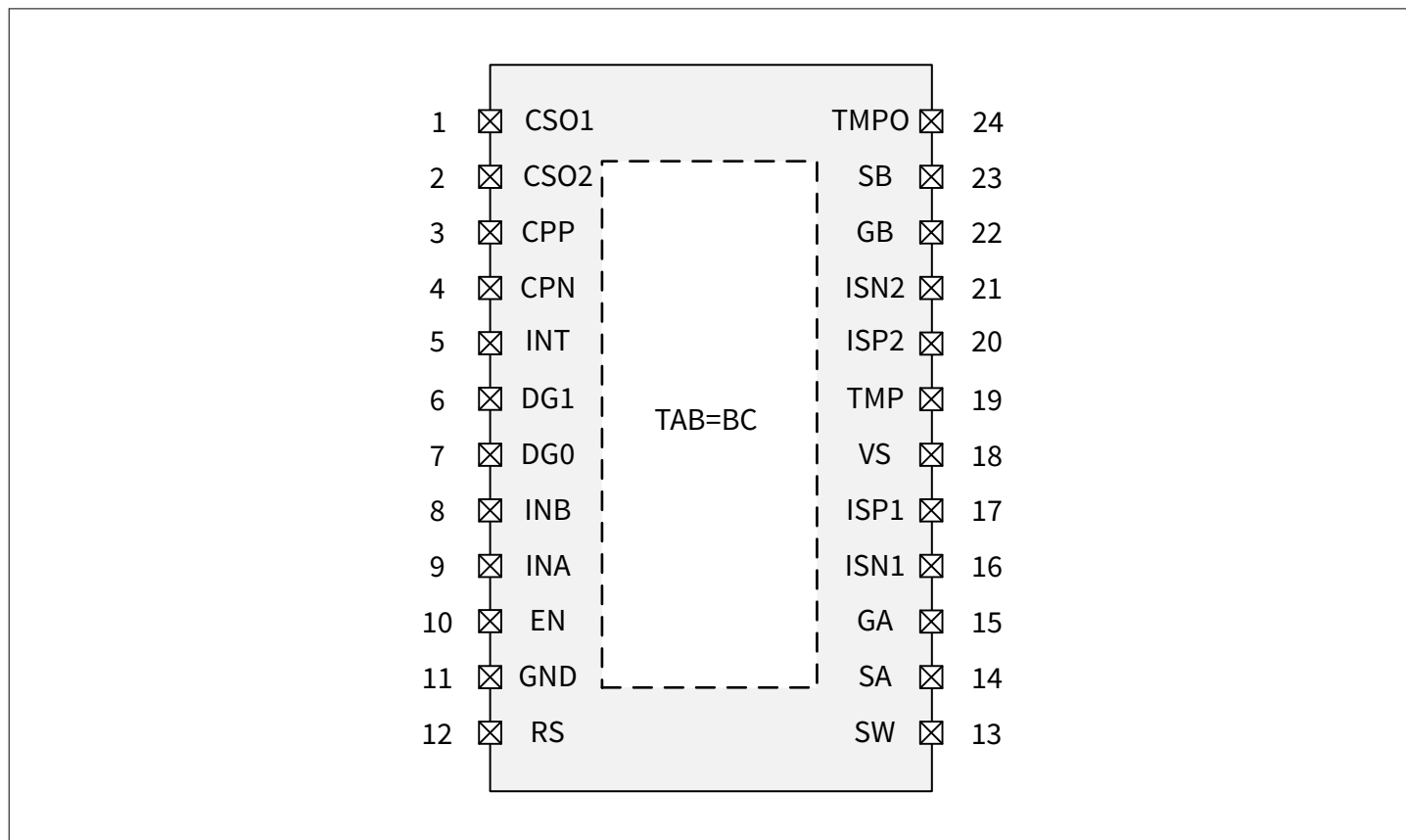


Figure 4

Table 1 Pin definitions and functions

Pin number	Symbol	I/O	Function
1	CSO1	I	Analog voltage to force SAFESTATE mode.
		O	<b>C</b> urrent <b>S</b> ense <b>O</b> utput <b>1</b> : analog voltage feedback, provides a voltage proportional to the shunt current or VDS across ISP1/ISN1.
2	CSO2	O	<b>C</b> urrent <b>S</b> ense <b>O</b> utput <b>2</b> : analog voltage feedback, provides a voltage proportional to the shunt current or VDS across ISP2/ISN2.
3	CPP	I	<b>C</b> omparator <b>P</b> ositive: analog positive input of comparator.
4	CPN	I	<b>C</b> omparator <b>N</b> egative: analog negative input of comparator.
5	INT	O	<b>I</b> nterrupt: open drain interrupt output.

(table continues...)

**Table 1** (continued) Pin definitions and functions

6	DG1	O	<p><b>Diagnostic 1:</b>          DG1 is logic low in SLEEP mode.          Digital voltage information of channel B VDS comparison to VS in IDLE mode.          Digital voltage information of current flow direction in ON mode:</p> <ul style="list-style-type: none"> <li>• DG1 is logic high if current flows from ISP1 to ISN1 connection</li> <li>• DG1 is logic low if current flows from ISN1 to ISP1 connection</li> </ul> <p>Digital voltage information in SAFESTATE mode:</p> <ul style="list-style-type: none"> <li>• DG1 is logic high if SAFESTATE because of CP or SC or VS(UV)</li> <li>• DG1 is logic low if SAFESTATE because of UVLO</li> </ul>
7	DG0	O	<p><b>Diagnostic 0:</b>          DG0 is logic low in SLEEP mode.          Digital voltage information of channel A VDS comparison to VS in IDLE mode.          Digital voltage information of boost converter frequency in ON mode.          Digital information in SAFESTATE mode:</p> <ul style="list-style-type: none"> <li>• DG0 is logic high if SAFESTATE because of CP or UVLO</li> <li>• DG0 is logic low if SAFESTATE because of SC or VS(UV)</li> </ul>
8	INB	I	<p><b>Input B:</b>          If INB digital logic is low, channel B switches OFF. If INB digital logic is high, channel B switches ON and gate driver is in ON mode only if pin ENABLE is logic high.</p>
9	INA	I	<p><b>Input A:</b>          If INA digital logic is low, channel A switches OFF. If INA digital logic is high, channel A switches ON and gate driver is in ON mode only if pin ENABLE is logic high.</p>
10	EN	I	<p>If <b>ENABLE</b> digital logic is low, gate driver is in SLEEP mode, channels A and B are switched OFF and gate driver is RESET.          If ENABLE digital logic is high, gate driver is in IDLE mode when INA and INB are both logic low.</p>
11	GND	I/O	<b>Ground</b> connection.
12	RS	O	<b>Resistor sense</b> output of boost converter: current measurement of the boost converter.
13	SW	I	<b>Switching supply</b> input of boost converter. Inductance connection.
14	SA	O	<b>Source A:</b> output A connection to external MOSFET sources.
15	GA	I/O	<b>Gate A:</b> output A connection to external MOSFET gates.
16	ISN1	I	<b>I Sense Negative 1:</b> external shunt or VDS negative connection.
17	ISP1	I	<b>I Sense Positive 1:</b> external shunt or VDS positive connection.
18	VS	I/O	<b>Voltage</b> reference, extended 3 V to 58 V.
19	TMP	I	<b>Temperature</b> Input: analog connection to external NTC or PTC thermistor.
20	ISP2	I	<b>I Sense Positive 2:</b> external shunt or VDS negative connection.

(table continues...)

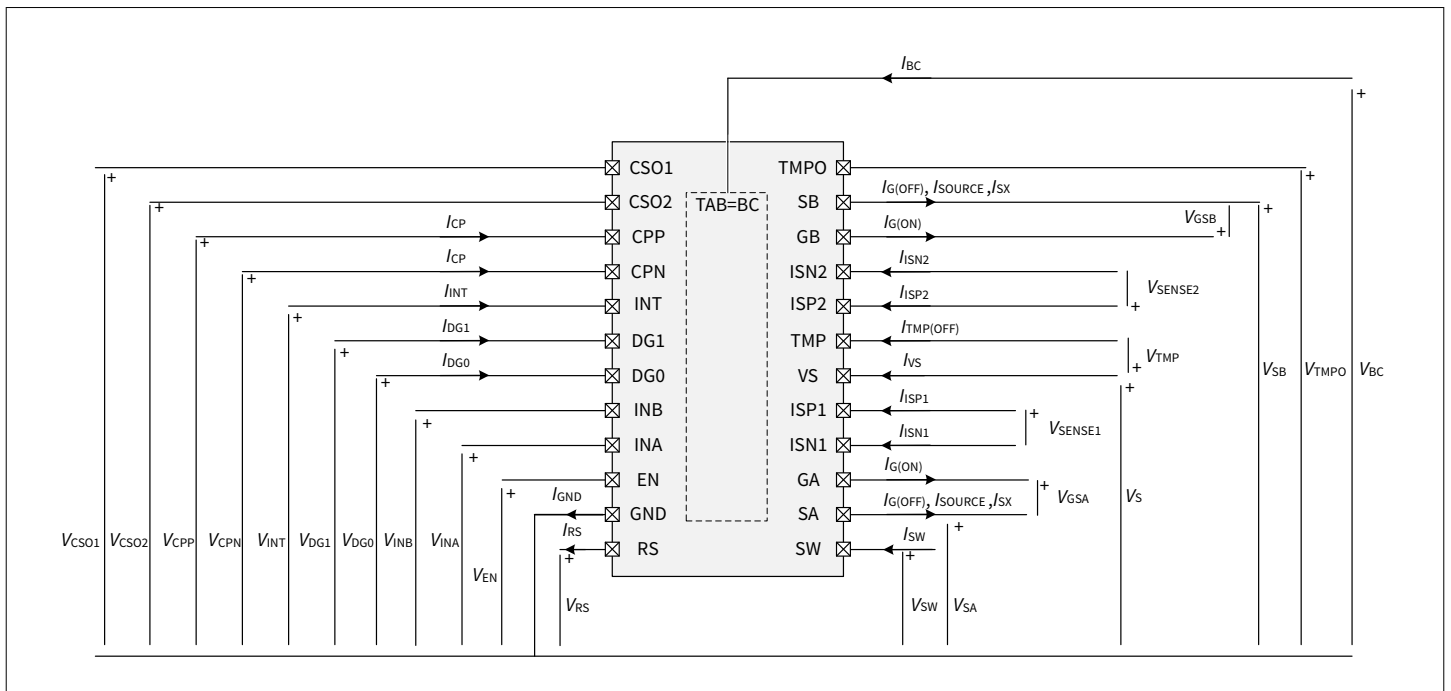
**2 Pin configuration**

**Table 1 (continued) Pin definitions and functions**

21	ISN2	I	<b>I Sense Negative 2:</b> external shunt or VDS positive connection.
22	GB	I/O	<b>Gate B:</b> output B connection to external MOSFET gates.
23	SB	I	<b>Source B:</b> output B connection to external MOSFET sources.
24	TMPO	O	<b>Temperature Output:</b> analog voltage feedback provides a voltage proportional to thermistor temperature.
TAB	BC	O	<b>Boost Converter output capacitor connection;</b> driver supply.

Voltages are defined positive with respect to ground.

Currents are defined flowing into or from the pin depending on pins.



**Figure 5 Voltage and current definitions – IEC 60375**



### 3 General product characteristics

#### 3.1 Absolute maximum ratings

$T_J = -40^\circ\text{C}$  to  $+150^\circ\text{C}$ ; all voltages with respect to ground, positive current flowing into pin (unless otherwise specified)

**Table 2 Absolute maximum ratings**

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
Maximum voltage VBC (boost converter output) - all pins	$V_{BC-X}$	-0.3	–	75	V	1)	PRQ-26
Maximum drain-source voltages on each output	$V_S - V_{SX}$	-36	–	75	V	1)	PRQ-14
Maximum voltage between gate and source pins on each output	$V_{GX} - V_{SX}$	-0.3	–	75	V	1)	PRQ-331
Maximum voltage between SW and RS pin	$V_{SW} - V_{RS}$	-0.3	–	75	V	1)	PRQ-332
Maximum pulsed current in SW pin	$I_{SW}$	–	–	200	mA	1)	PRQ-16
Maximum operating junction temperature	$T_{J(MAX)}$	-40	–	150	$^\circ\text{C}$	1)	PRQ-23
Storage temperature	$T_{STG(MAX)}$	-55	–	150	$^\circ\text{C}$	1)	PRQ-24
ESD HBM susceptibility all pins	$V_{ESD(HBM)}$	-2	–	2	kV	1) HBM according to ANSI/ESDA/JEDEC JS001 (1.5 k $\Omega$ , 100 pF)	PRQ-130
ESD CDM susceptibility all pins	$V_{ESD(CDM)}$	-500	–	500	V	1) Charged Device Model “CDM” according to ANSI/ESDA/JEDEC JS-002	PRQ-131
ESD CDM susceptibility corner pins	$V_{ESD(CDM)}$	-750	–	750	V	1) Charged Device Model “CDM” according to ANSI/ESDA/JEDEC JS-002	PRQ-132

1) Not subject to production test, specified by design

#### 3.2 Functional ranges

$T_J = -40$  to  $150^\circ\text{C}$ , all voltages with respect to ground, typical values are given for  $V_S = 14\text{ V}$  and  $T_J = 25^\circ\text{C}$

**Table 3** Functional ranges

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
Voltage reference range for normal operation	$V_{S(NOR)}$	8	–	36	V	<sup>1)</sup>	PRQ-39
Voltage reference extended range	$V_{S(EXT)}$	3	–	58	V	<sup>1)</sup> Parameter deviations possible	PRQ-266
Voltage reference range with lower short-circuit protection	$V_{S(SC)LOW}$	3	–	8	V	<sup>1)</sup>	PRQ-40
Input pins ENABLE, INA, INB	$V_{EN}, V_{INA}, V_{INB}$	0	–	5.5	V	<sup>1)</sup>	PRQ-307
Diagnostic pins DG0, DG1	$V_{DG0}, V_{DG1}$	0	–	$k_{DG} * V_{EN}$	V	<sup>1)</sup> See $k_{DG}$ parameter	PRQ-308
Interrupt pin INT	$V_{INT}$	0	–	5.5	V	<sup>1)</sup>	PRQ-309
Comparator reference voltage pins CPN, CPP	$V_{CP(REF)}$	1	–	5.5	V	<sup>1)</sup>	PRQ-183
Analog output pins saturation CSO 1&2, TMPO	$V_{AMP(SAT)}$	4	4.6	5.5	V	$V_S = V_{S(NOR)}$	PRQ-310
Current sense amplifiers gain range	$G$	10	–	200	–	<sup>1)</sup> For $G \leq 30$ , use only $R_{CSO} = 10 \text{ k}\Omega$	PRQ-317
Supply voltage range for amplifier operation	$V_{BC} - V_S$	6	–	15	V	<sup>1)</sup>	PRQ-339
Amplifier input voltage range	$V_{BC} - V_{ISxx}$	6	–	15	V	<sup>1)</sup>	PRQ-341
Amplifier input voltage threshold for disconnection	$V_{ISxx-GND(TH)}$	0.2	0.7	1.5	V	<sup>1)</sup>	PRQ-340

<sup>1)</sup> Not subject to production test, specified by design

### 3.3 Thermal characteristics

**Table 4** Thermal characteristic

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
Thermal resistance junction to ambient	$R_{thJA}$	–	27	–	K/W	<sup>1)</sup> <sup>2)</sup>	PRQ-38

<sup>1)</sup> Not subject to production test, specified by design

<sup>2)</sup> According to JEDEC51-2,-5,-7 at natural convection on FR4 2s2p board; the product (chip + package) was simulated on a 76.2 x 114.3 x 1.5 mm board with 2 inner copper layers (2 x 70  $\mu\text{m}$  Cu, 2 x 35  $\mu\text{m}$  Cu). Where applicable a thermal via array under the exposed pad contacted the first inner copper layer.  $T_A = 85^\circ\text{C}$ . Device is loaded with 1 W power.

## 4 Electrical characteristics

### 4.1 Static electrical characteristics

$T_J = -40$  to  $150^\circ\text{C}$ ,  $V_S = 8$  V to  $36$  V (unless otherwise specified), all voltages with respect to ground, positive current flowing into pin (unless otherwise specified), typical values are given for  $V_S = 14$  V and  $T_J = 25^\circ\text{C}$

**Table 5** Static electrical characteristics

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
<b>Inputs pins</b>							
Input A,B & Enable voltage high level	$V_{IN(H)}, V_{EN(H)}$	2.5	–	–	V	–	PRQ-74
Input A,B & Enable voltage low level	$V_{IN(L)}, V_{EN(L)}$	–	–	0.7	V	–	PRQ-75
Input A,B & Enable pull-down internal resistor	$R_{IN(GND)}$	0.5	1.5	2.5	M $\Omega$	–	PRQ-318
Input zener diode for local pins	$V_{Z(IN)}$	5.5	6	6.5	V	<sup>1)</sup> See <a href="#">Figure 3</a>	PRQ-319
<b>Digital diagnostic pins</b>							
Ratio diagnostic pin voltage high level over VEN	$k_{DG(H)}$	0.9	1	1.1	–	–	PRQ-84
Diagnostic pin voltage low level	$V_{DG(L)}$	–	–	0.1	V	$V_{BC} = 72$ V	PRQ-85
Diagnostic pin serial resistor	$R_{DG(GND)}$	5	10	20	k $\Omega$	–	PRQ-86
Threshold for diagnostic change in IDLE mode	$V_{DS\_DIAG(TH)}$	1	2	3	V	$V_S - V_{SA}$ (DG0) $V_S - V_{SB}$ (DG1)	PRQ-91
Diagnostic delay in IDLE mode	$t_{DG(IDLE)}$	0	40	100	$\mu\text{s}$	IDLE mode only	PRQ-275
Delay for current direction change on DG1	$t_{ISD}$	0	8	18	$\mu\text{s}$	Indicates current flow direction change on CSA1 only ON mode only	PRQ-164
Interrupt pin pull-down internal resistor, SAFESTATE active	$R_{INT}$	7	12	17	k $\Omega$	–	PRQ-88
Interrupt pin current leakage	$I_{INT(NOSAFESTATE)}$	–	–	0.3	$\mu\text{A}$	$V_{INT(H)} \leq 5.5$ V	PRQ-89
<b>Comparator (CP)</b>							
Comparator offset	$V_{CP(OFFSET)}$	-50	–	50	mV	$V_{CP(REF)MIN} \leq V_{CP(REF)} \leq V_{CP(REF)MAX}$	PRQ-284
Comparator leakage input current	$I_{CP}$	-100	–	100	nA	$V_{CP} = 5.5$ V	PRQ-242

(table continues...)

**Table 5 (continued) Static electrical characteristics**

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
<b>Temperature amplifier (TMPA)</b>							
TMPA input current	$I_{\text{TMP(OFF)}}$	-100	–	100	nA	–	PRQ-185
TMPA input offset	$V_{\text{TMP(OFFSET)}}$	-10	0	+10	mV	–	PRQ-186
TMPA ratio	$k_{\text{TMP}}$	9.5	10	10.5	–	–	PRQ-187
TMPA pull-down resistor	$R_{\text{TMPO}}$	20	–	100	k $\Omega$	1)	PRQ-188
<b>Current sense amplifiers (CSA1 &amp; CSA2)</b>							
CSA input offset	$V_{\text{ISX(OFFSET)}}$	-50	0	50	$\mu\text{V}$	1)	PRQ-323
CSA input blind range	$V_{\text{ISX(BLIND)}}$	-500	0	500	$\mu\text{V}$	–	PRQ-324
CSA delay maximum accuracy	$t_{\text{CSA(ACC)}}$	0	200	400	$\mu\text{s}$	–	PRQ-325
CSA settling time	$t_{\text{CSA(SET)}}$	1	10	20	$\mu\text{s}$	1) Step 25% $G=100$	PRQ-328
CSA output pull-down resistor	$R_{\text{CSOx}}$	10	20	50	k $\Omega$	1)	PRQ-326
CSA gain intrinsic error	$\varepsilon(G)$	-1	0	1	%	1) $G = 10..200$	PRQ-327
PSRR - CSA power supply rejection ratio	$PSRR_{1\text{kHz}}$	–	105	–	dB	2) $f = 1 \text{ kHz}$ , $G = 100$ , $R_{\text{CSO}} = 20 \text{ k}$ see <a href="#">Figure 34</a>	PRQ-336
CMRR - CSA common mode rejection ratio	$CMRR_{1\text{kHz}}$	–	116	–	dB	2) $f = 1 \text{ kHz}$ , $G = 100$ , $R_{\text{CSO}} = 20 \text{ k}$ see <a href="#">Figure 34</a>	PRQ-337
Noise - CSA Voltage noise, RTI	Noise	–	180	–	nV <sub>RMS</sub>	2) $G = 100$ , $R_{\text{CSO}} = 20 \text{ k}$ RTI	PRQ-338

1) Not subject to production test, specified by design

2) Not subject to production test, specified by characterization.

## 4.2 Protection characteristics

$T_J = -40$  to  $150^\circ\text{C}$ ,  $V_S = 8 \text{ V}$  to  $36 \text{ V}$  (unless otherwise specified), all voltages with respect to ground, positive current flowing into pin (unless otherwise specified), typical values are given for  $V_S = 14 \text{ V}$  and  $T_J = 25^\circ\text{C}$

**Table 6 Protection characteristics**

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
<b>Protection thresholds</b>							
Current shutdown internal threshold ratio from Enable pin voltage	$k_{CSO1(TH)}$	0.71	0.74	0.77	–	$V_S = 8\text{ V to }58\text{ V}$ ON mode, CSA1 only See <a href="#">Chapter 8.1</a>	PRQ-168
Under voltage threshold	$V_{S(UV)}$	0.5	1	1.5	V	$V_S - GND$ ON mode only	PRQ-66
<b>Protection delays</b>							
Delay between short circuit and CSO1 high	$t_{DSCCSO1(H)}$	0.2	1.5	6	$\mu\text{s}$	<sup>1)</sup> $G = 100$ $V_{EN} = 3.3\text{ V}$	PRQ-181
Delay between CSO1 high and INT = low	$t_{DCSO1(H)INT(L)}$	0.5	5	10	$\mu\text{s}$	<sup>1)</sup> $G = 100$	PRQ-182
Delay between CP high and INT	$t_{DCP(H)INT(L)}$	1	9	17	$\mu\text{s}$	$V_{CP(REF)MIN} \leq V_{CP(REF)} \leq V_{CP(REF)MAX}$	PRQ-184
Delay between UV on VS and INT = low	$t_{DUV(H)INT(L)}$	8	22	40	$\mu\text{s}$	–	PRQ-320
Delay between INT = low and gate 80%	$t_{DINT(L)G(L)}$	–	3	5	$\mu\text{s}$	<sup>1)</sup> $C_{G(EQ)} = 100\text{ nF}$	PRQ-136
Delay between short circuit and gate 80%	$t_{DSCG(L)}$	0.7	5.5	10	$\mu\text{s}$	<sup>1)</sup> $G = 100$ $V_{EN} = 3.3\text{ V}$ $C_{G(EQ)} = 100\text{ nF}$	PRQ-330
Time to reset	$t_{RESET}$	3	–	30	$\mu\text{s}$	Reset from SAFESTATE: $V_{EN} < V_{EN(L)}$ for $t_{RESET}$ duration	PRQ-94

<sup>1)</sup> Sum of PRQ-181, PRQ-182, PRQ-136 max. does match max. of the sum PRQ-330 due to silicon process and variation.

### 4.3 Driver outputs electrical characteristics

$T_J = -40$  to  $150^\circ\text{C}$ ,  $V_S = 8\text{ V to }36\text{ V}$  (unless otherwise specified), all voltages with respect to ground, current positive while flowing out of pin (unless otherwise specified), typical values are given for  $V_S = 14\text{ V}$  and  $T_J = 25^\circ\text{C}$

**Table 7 Driver outputs electrical characteristics**

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
Source pre-charge current	$I_{SOURCE}$	6	15	25	mA	$V_S - V_{SX} \geq V_{DS\_DIAG(TH)}$	PRQ-56

(table continues...)

**Table 7** (continued) Driver outputs electrical characteristics

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
Delay between Enable = high and Source pre-charge current active	$t_{DSOURCE}$	4	-	100	$\mu\text{s}$	IDLE mode only	PRQ-210
Power on input delay	$t_{POI}$	0	2	5	$\mu\text{s}$	Time to activate protections before turn-on after INx = high	PRQ-158
Turn-on delay	$t_{D(ON)}$	1	4	7	$\mu\text{s}$	$C_{G(EQ)} = 100 \text{ nF}$	PRQ-50
Rise time on gate 20% to 80% of VBC - VS	$t_R$	0	7	15	$\mu\text{s}$	$C_{G(EQ)} = 100 \text{ nF}$	PRQ-51
Gate turn on short circuit pulsed current per gate	$I_{G(ON)}$	50	175	-	mA	$V_{GX} - V_{SX} = 0 \text{ V}$	PRQ-52
Turn-off delay	$t_{D(OFF)}$	1	4	7	$\mu\text{s}$	$C_{G(EQ)} = 100 \text{ nF}$	PRQ-53
Fall time on gate 80% to 20% of VBC - VS	$t_F$	0	2	5	$\mu\text{s}$	$C_{G(EQ)} = 100 \text{ nF}$	PRQ-54
Gate turn-off short circuit pulsed current per gate	$I_{G(OFF)}$	350	1400	-	mA	$V_{GX} - V_{SX} = 14 \text{ V}$	PRQ-276

#### 4.4 Boost converter (BC) characteristics

$T_J = -40$  to  $150^\circ\text{C}$ ,  $V_S = 8 \text{ V}$  to  $36 \text{ V}$  (unless otherwise specified), all voltages with respect to ground, typical values are given for  $V_S = 14 \text{ V}$  and  $T_J = 25^\circ\text{C}$

**Table 8** Boost converter (BC) characteristics

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
BC Boost capacitor	$C_{BC}$	20 * $C_{G(EQ)}$	-	-	F	<sup>1)</sup> $C_{G(EQ)}$ = external MOSFET equivalent gate source capacitance	PRQ-137
BC switching current limitative resistor	$R_{RS}$	10	-	30	$\Omega$	<sup>1)</sup> Use 1/2 W resistor min.	PRQ-138
BC output VBC - VS regulation voltage	$V_{BC(TH)}$	11.5	12.5	14	V	-	PRQ-139
VBC(TH) to UVLO regulation gap	$V_{BC(RG)}$	1.9	2.5	-	V	-	PRQ-141
BC undervoltage lockout voltage	$UVLO$	9.5	10	11	V	-	PRQ-140

(table continues...)

**Table 8 (continued) Boost converter (BC) characteristics**

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
Delay between UVLO and INT = low	$t_{DUVLO(H)INT(L)}$	0	10	40	$\mu\text{s}$	–	PRQ-142
RS deactivation threshold	$V_{RS(TH)}$	0.7	1	1.4	V	–	PRQ-147
Forward voltage of BC diode	$V_{FBC}$	0	0.9	1.1	V	$I_F = 100 \text{ mA}$	PRQ-148
On-state resistance of BC switch	$R_{DS(ON)K1(25)}$	1	11	15	$\Omega$	$I = 100 \text{ mA}; T_J = 25^\circ\text{C}$	PRQ-150
Boost converter off-time	$t_{BC(OFF)}$	1	4	5	$\mu\text{s}$	–	PRQ-152
Time to reach RS deactivation threshold	$t_{RS(TH)}$	–	920	–	ns	<sup>2)</sup> $V_S = 12 \text{ V};$ $R_{RS} = 10 \Omega;$ $L = 100 \mu\text{H} / 1.7 \Omega;$ $T_J = 25^\circ\text{C}$	PRQ-154
Turn-off delay of K1	$t_{D(OFF)K1}$	0.05	0.2	0.3	$\mu\text{s}$	–	PRQ-155
Boost power-on delay	$t_{POD}$	–	960	–	$\mu\text{s}$	<sup>3)</sup> $V_S = 12 \text{ V}; R_{RS} = 10 \Omega;$ $L = 100 \mu\text{H} / 2 \Omega; C_{BC} = 1 \mu\text{F}; T_J = 25^\circ\text{C}$ See AppNote Getting Started with 2ED2410-EM	PRQ-157

- 1) Not subject to production test, specified by design  
2) Not subject to production test, specified by calculation.  
3) Not subject to production test, specified by characterization.

## 4.5 Current consumptions

$T_J = -40$  to  $150^\circ\text{C}$ ,  $V_S = 8 \text{ V}$  to  $36 \text{ V}$  (unless otherwise specified), all voltages with respect to ground, positive current flowing into pin (unless otherwise specified), typical values are given for  $V_S = 14 \text{ V}$  and  $T_J = 25^\circ\text{C}$

**Table 9 Current consumptions**

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
GND pin current in SLEEP mode	$I_{GND+RS(SLEEP)}$	1	6	15	$\mu\text{A}$	$V_S = 24 \text{ V}$ $V_{BC} = V_S$	PRQ-68
Sources leakage current in SLEEP mode	$I_{SX(SLEEP)}$	0.1	0.5	4	$\mu\text{A}$	$V_{BAT} = 24 \text{ V}$ $V_S - V_{SX} = V_{BAT}$	PRQ-285
VS pin current in IDLE mode	$I_{VS(IDLE)}$	-15	-6	-2	$\mu\text{A}$	$V_S = 24 \text{ V}$ $V_{SX} = V_S$	PRQ-69
VS pin current in IDLE mode, $25^\circ\text{C}$	$I_{VS(IDLE)25}$	-10	-6	-2	$\mu\text{A}$	$T_J = 25^\circ\text{C}$	PRQ-294

(table continues...)

**Table 9 (continued) Current consumptions**

Parameter	Symbol	Values			Unit	Note or condition	P-Number
		Min.	Typ.	Max.			
BC current in IDLE mode	$I_{BC(IDLE)}$	5	10	50	$\mu\text{A}$	$V_S = 24\text{ V}$ $V_{BC} - V_S = 14\text{ V}$	PRQ-144
BC current in IDLE mode, 25°C	$I_{BC(IDLE)25}$	5	10	20	$\mu\text{A}$	$T_J = 25^\circ\text{C}$	PRQ-297
VS pin current in ON mode	$I_{VS(ON)}$	-20	-4	0	$\mu\text{A}$	-	PRQ-72
VS pin current in ON mode, 25°C	$I_{VS(ON)25}$	-10	-4	-1	$\mu\text{A}$	$T_J = 25^\circ\text{C}$	PRQ-295
BC current in ON mode	$I_{BC(ON)}$	10	55	150	$\mu\text{A}$	$V_{BC} - V_S = 14\text{ V}$	PRQ-145
BC current in ON mode, 25°C	$I_{BC(ON)25}$	10	55	90	$\mu\text{A}$	$T_J = 25^\circ\text{C}$	PRQ-298
BC current in ON mode, 25°C, one CSA disconnected	$I_{BC(ON)25\_1CSA(OFF)}$	10	45	70	$\mu\text{A}$	<sup>1)</sup> $T_J = 25^\circ\text{C}$ CSA 1 <b>or</b> 2 not used see <a href="#">Chapter 7</a>	PRQ-300
BC current in ON mode, 25°C, all amplifiers disconnected	$I_{BC(ON)25\_2CSA(OFF)}$	6	20	35	$\mu\text{A}$	<sup>1)</sup> $T_J = 25^\circ\text{C}$ CSA 1 and 2 not used see <a href="#">Chapter 7</a>	PRQ-301
BC current in ON mode, $\leq 85^\circ\text{C}$ , one CSA disconnected	$I_{BC(ON) \leq 85\_1CSA(OFF)}$	10	45	85	$\mu\text{A}$	<sup>1)</sup> $T_J \leq 85^\circ\text{C}$ CSA 1 <b>or</b> 2 not used see <a href="#">Chapter 7</a>	PRQ-302
BC current in ON mode, $\leq 85^\circ\text{C}$ , all amplifiers disconnected	$I_{BC(ON) \leq 85\_2CSA(OFF)}$	6	20	45	$\mu\text{A}$	<sup>1)</sup> $T_J \leq 85^\circ\text{C}$ CSA 1 and 2 not used see <a href="#">Chapter 7</a>	PRQ-303
VS pin current in SAFESTATE mode	$I_{VS(SAFESTATE)}$	-20	-4	0	$\mu\text{A}$	-	PRQ-73
BC current in SAFESTATE mode	$I_{BC(SAFESTATE)}$	10	55	150	$\mu\text{A}$	$V_{BC} - V_S = 14\text{ V}$	PRQ-146

<sup>1)</sup> Not subject to production test, specified by design



## 5 General operation

### 5.1 Operating modes

2ED2410-EM works with 4 operating modes: SLEEP, IDLE, ON and SAFESTATE, selected by a combination of inputs INA, INB and ENABLE pins, and in the case of SAFESTATE, by protection features or force signal.

INPUTS			Operating mode	OUTPUTS										comments	
EN	INA	INB		Boost converter output $V_{BC} - V_S$	INT	DG0	DG1	$V_{CS01}$	$V_{CS02}$	$V_{TMPO}$	$V_{GA} - V_{SA}$	$V_{GB} - V_{SB}$	ISOURCE		
0	X	X	SLEEP	0	1*	0	0	0	0	0	0	0	0	0	*once reset is done, provided that pull-up voltage is available
1	0	0	IDLE	$V_{BC(TH)}$	1	$V_S - V_{SA}^*$	$V_S - V_{SB}^*$	0	0	0	0	0	active <sup>J</sup>	* $DG_x = 0$ if $V_S - V_{SX} > V_{DS\_DIAG(TH)}$ for each output, else $DG_x = 1$ if $V_S - V_{SX} \leq V_{DS\_DIAG(TH)}$	
1	1	0	ON	$V_{BC(TH)}$	1	pulse when K1 activated*	direction of current CSA1*	active	active	active	$V_{BC(TH)}$	0	active <sup>J</sup>	*high level: see $V_{DG0}$ , $V_{DG1}$ in Functional ranges Table	
	0	$V_{BC(TH)}$													
	$V_{BC(TH)}$	$V_{BC(TH)}$													
1	X	X	SAFESTATE	SC or UV	$V_{BC(TH)}$	0	0	1	active	active	active	0	0	active <sup>J</sup>	NB: if several faults occurs in series, only first fault is indicated by DG1 and DG0 *depends on UVLO root cause
				UVLO	$\leq V_{BC(TH)}^*$		1	0							
				CP	$V_{BC(TH)}$		1	1							

Figure 6 Inputs, modes and outputs states

(1) See Chapter 6.

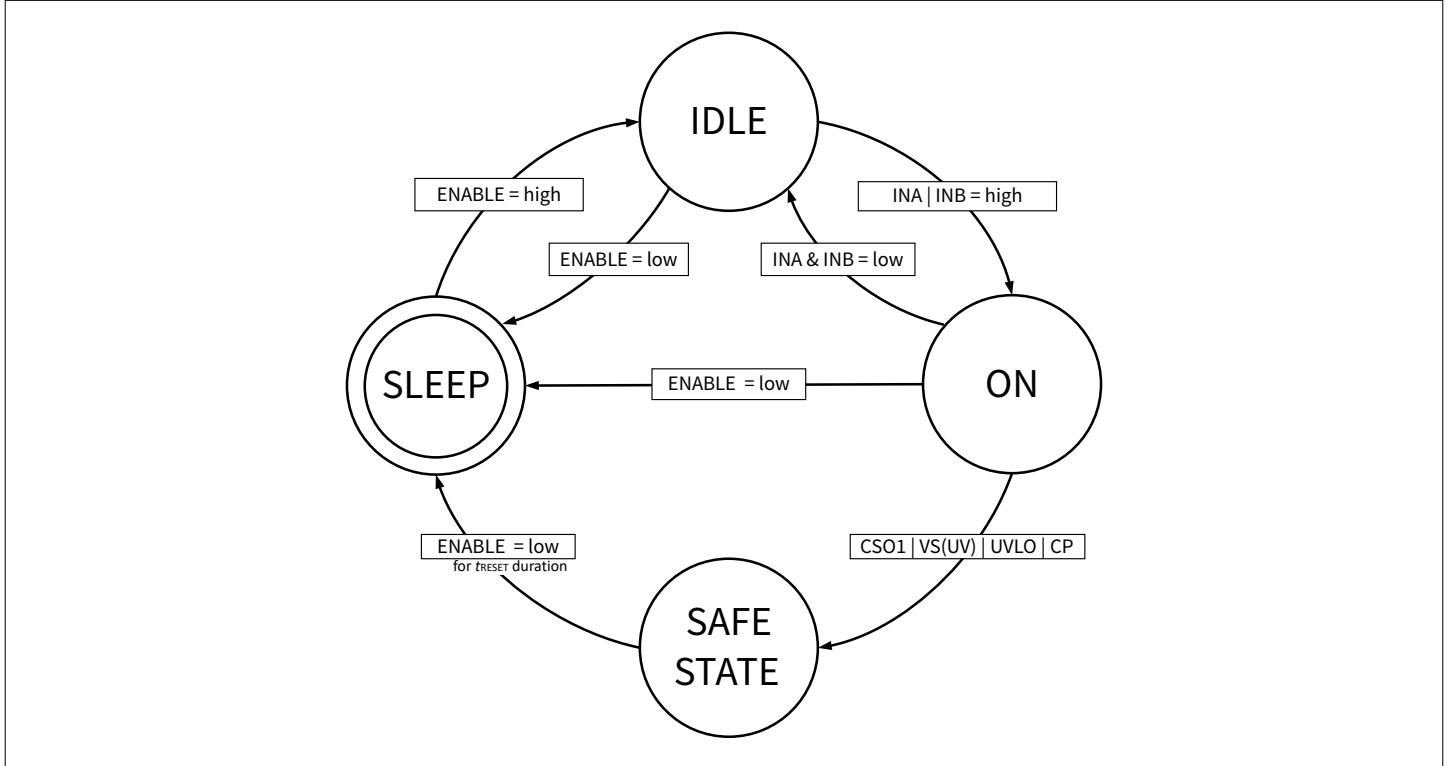


Figure 7 State machine of 2ED2410-EM

### 5.2 Current consumption

The current consumption of the driver from the system battery(or power supply), also named quiescent current ( $I_q$ ) of 2ED2410-EM, depends on:

5 General operation

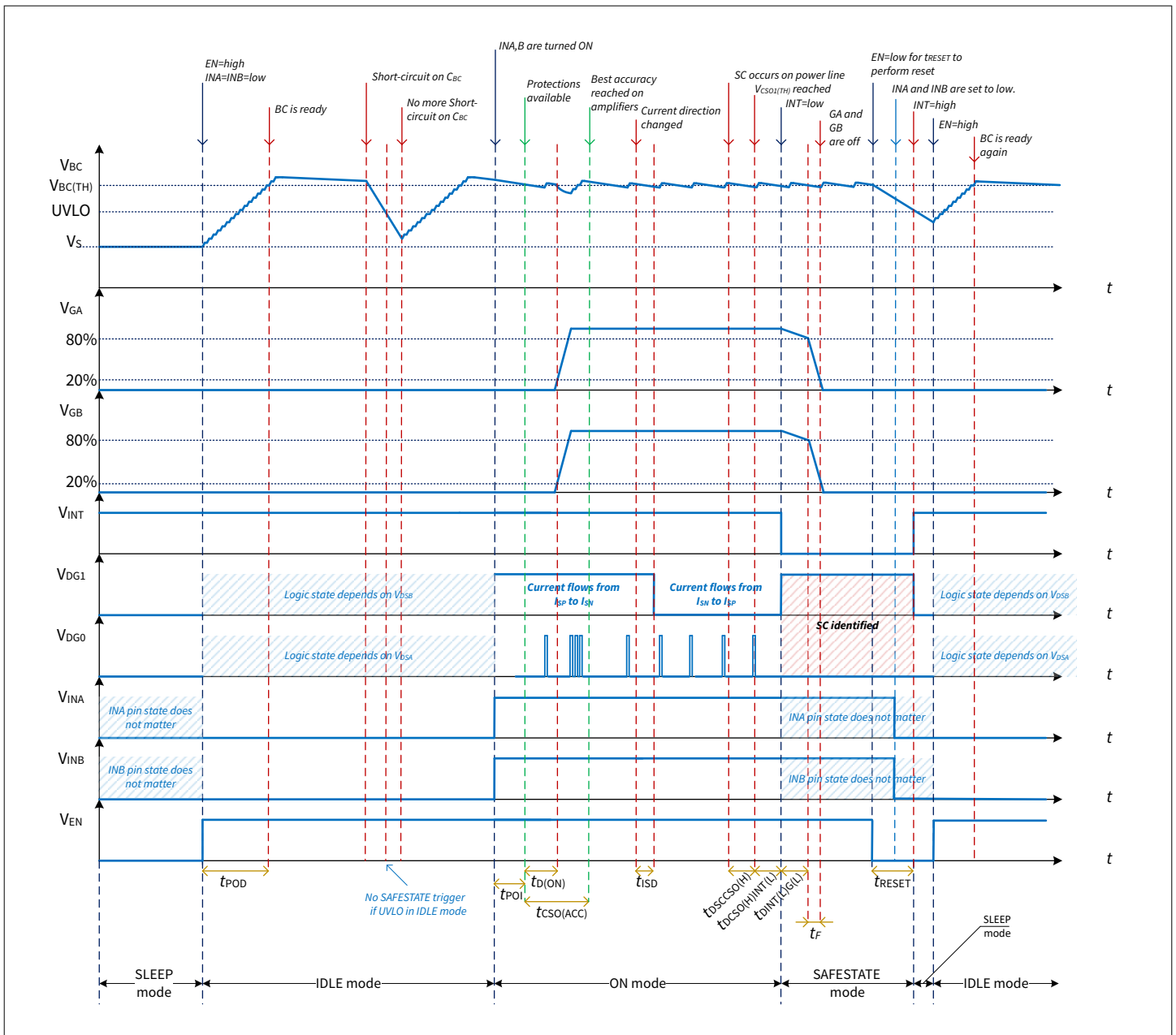
- the mode the driver is in.
- the external components used for the boost converter, which is both the driver supply and the external MOSFET gate supply.
- for SLEEP mode, it also depends on the MOSFET structure used.

In this datasheet are only given consumption at driver level, not at system battery/power supply level.

Details of quiescent current calculation from the battery are given in the application note "Getting started with 2ED2410-EM".

**5.3 Timing diagram**

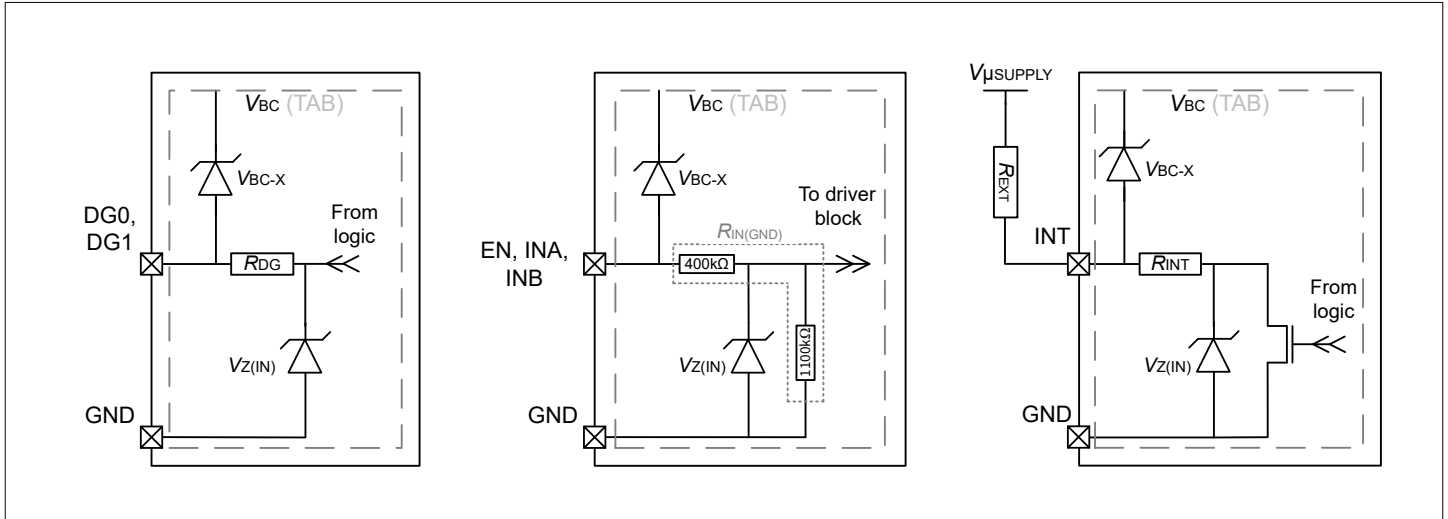
The following diagram shows digital inputs, digital outputs, the boost converter output and gate outputs from SLEEP to ON until short-circuit event occurs, and the reset procedure back to SLEEP mode.



**Figure 8** Timings diagram with IDLE mode, ON mode with short-circuit event and SAFESTATE with reset – Note: time and voltages are not to scale

## 5.4 Logic pins

Logic pins are compatible to 5 V and 3.3 V microcontrollers. They can be connected directly to a microcontroller output without the need of an additional component. There is an internal series and pull-down resistor [PRQ-318]. A RC network for stabilizing voltage on EN pin can be used, since EN voltage is used for internal reference in the logic.



**Figure 9** Digital I/O

The inputs control circuitry drives the output gate driver stage. They are pulled-down to GND with a  $R_{IN(GND)}$  resistor to avoid unintended switch-on.

The inputs circuitry are set to logic high when  $V_{INX} > V_{IN(H)}$  or  $V_{EN} > V_{IN(H)}$ .

The ENABLE pin controls the ON/OFF of the boost converter and biases all analog logic.

ENABLE = 1 sets  $V_{BC} - V_S \geq V_{BC(TH)}$  after a time  $t_{POD}$ .

The INx pins directly control the gate outputs therefore INA = 1 sets GA = 1 and INB = 1 sets GB = 1. The inputs/outputs A and B are independent

If ENABLE and at least one of the INx pins are set high together, protections and measurements are turned ON but gates will turn-on only when  $V_{BC} - V_S \geq V_{BC(TH)}$ .

When driver enters ON mode by INx = 1, protections are ready after a time  $t_{POI}$  and amplifiers get maximum accuracy after a time  $t_{CSA(ACC)}$  (see [Chapter 4.1](#)).

The INx and ENABLE pins are set to logic low when  $V_{INX} < V_{IN(L)}$  or  $V_{EN} < V_{IN(L)}$ .

The digital outputs give back either a low or high logic level signal. The output high voltage level is based on  $V_{EN}$  and is given in the electrical characteristics table as a ratio between  $V_{DGx}$  and  $V_{EN}$ . See parameter  $k_{DG}$  in [Chapter 4.1](#).

DG0 and DG1 in a low logic state have a value  $\leq V_{DG(L)}$ . The state of the diagnostic depends the operating mode the driver is in, refer to [Chapter 5.1](#).

In ON mode, DG0 reflects the activation of boost converter switch K1 (see [Chapter 9](#)): each time K1 is activated, DG0 = 1.

In ON mode, DG1 reflects the current direction on CSA1: DG1 = 0 if current is flowing from ISP1 to ISN1, DG1 = 1 if current is flowing from ISN1 to ISP1 (see [Chapter 7](#)).

INT pin is an open-drain output. The intent is to deliver an interrupt signal to relevant surrounding devices, such as microcontroller or power supply management chip (e.g. Infineon SBC).

INT needs to be externally pulled-up, e.g. to the microcontroller supply  $V_{\mu SUPPLY}$ . The value of  $V_{INT}$  when SAFESTATE is triggered, is the result of the voltage divider between the external resistor  $R_{EXT}$  and  $R_{INT}$ .

5 General operation

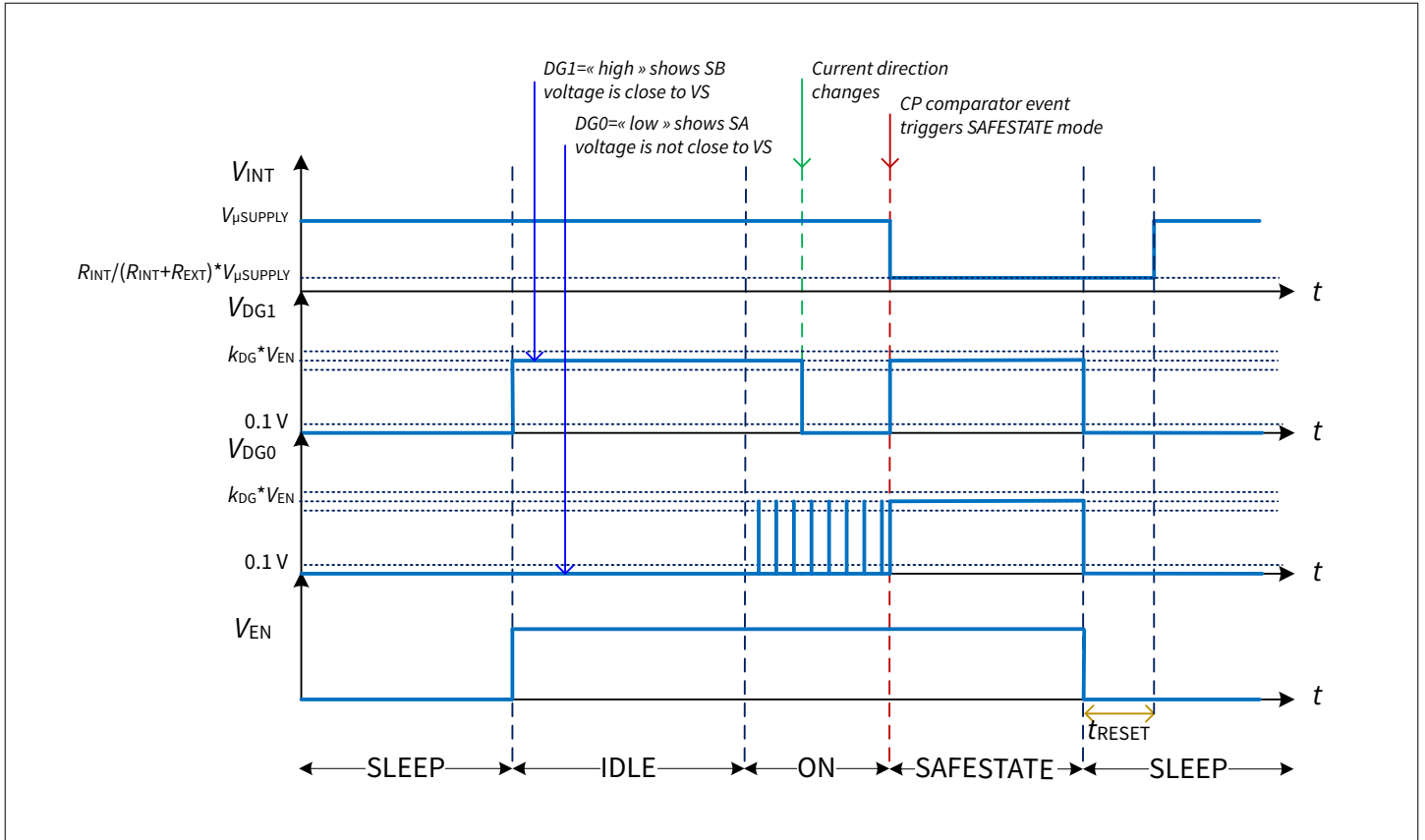
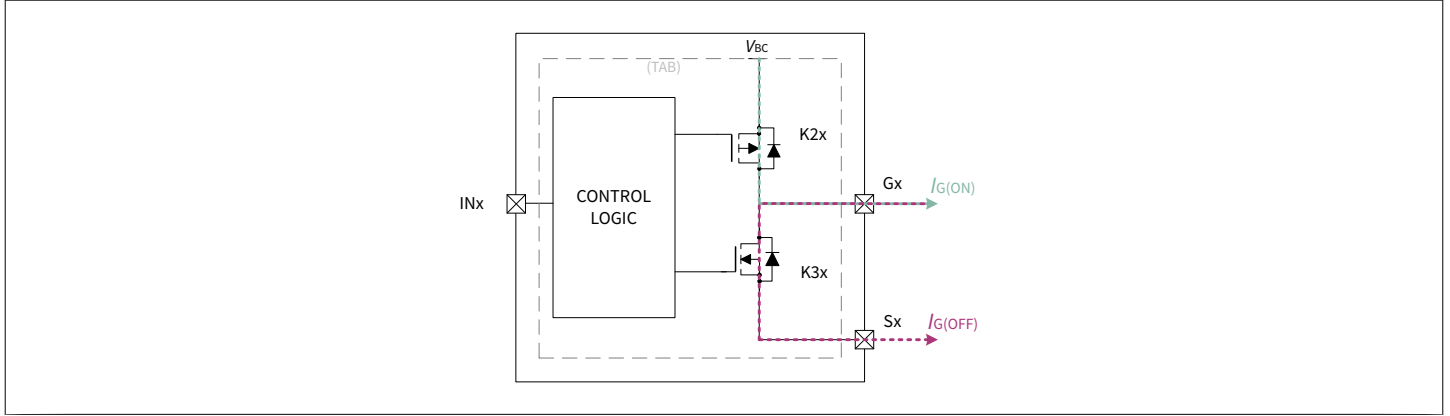


Figure 10 Diagnostics behavior

5.5 Gate outputs

2ED2410-EM features two identical gate outputs GA and GB working with source pins SA and SB respectively. These outputs are activated by setting the corresponding digital input INA or INB to a high logic level. The structure of these outputs is a push-pull and the logic ensures by design that both MOSFET K2x and K3x will not be ON at the same time (no shoot-through).

K2x are P-channel enhancement MOSFET and K3x are N-channel enhancement MOSFET. The current to switch ON the external MOSFET connected to the gate driver is delivered by boost converter capacitor  $C_{BC}$ , through K2x to the gate pins Gx. The current to switch OFF the external MOSFET is sunk from gate pins Gx through K3x to the source pins Sx.



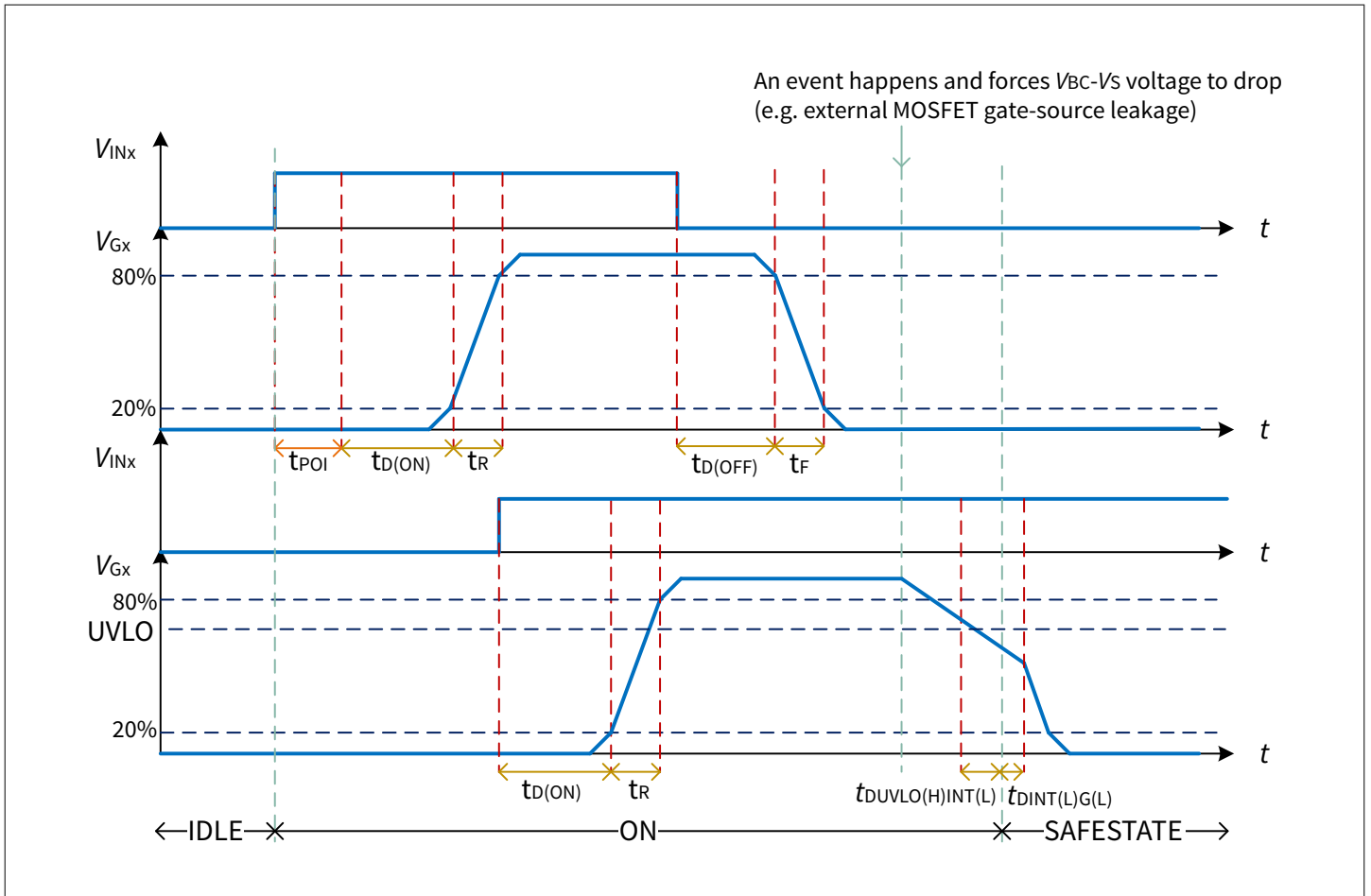
**Figure 11** Gate output structure

When the first input is switched on, a time delay  $t_{POI}$  needs to be considered. This time delay, power-on-input, is needed to make sure protections are activated before sending gate signal activation, so 2ED2410-EM never switches the MOSFET on without current sense and temperature amplifiers. If these functions are not used,  $t_{POI}$  still needs to be considered.

If  $V_{BC} - V_S \leq V_{BC(TH)}$  when the input signals  $IN_x$  are set high, the driver will be in ON mode but the gate outputs will remain OFF until  $V_{BC(TH)}$  is reached on boost converter output.

If  $V_{BC} - V_S \leq V_{BC(TH)}$  occurs when the gates are ON, this under-voltage on the boost converter will trigger the lock-out of the gates and the driver will enter SAFESTATE, consequently turning and keeping off the gates. See Chapter 8.4 and refer to Chapter 9 to see how gate outputs and the boost converter are connected.

The timings for the gate outputs are described in Figure 12.



**Figure 12** Gate timings (not to scale, for understanding purposes only)

## 5.6 Ground loss protection: module level

MOSFET K3 (see Figure 11, chapter 5.5) is turned on by default on each output as long as VS present.

If GND board/ECU connection is lost, K3 remains on or is turned on as long as the below conditions are true.

As a result gate-source is pulled-down in the following conditions:

- VS pin is connected to battery line
- GND board/ECU disconnected
- SLEEP, IDLE, ON or SAFESTATE modes

In ON mode, if GND board/ECU is connected back, driver outputs will be turned on again (and therefore K3 switch off) without necessary reset from pin ENABLE.

## 6 Low by-pass current feature

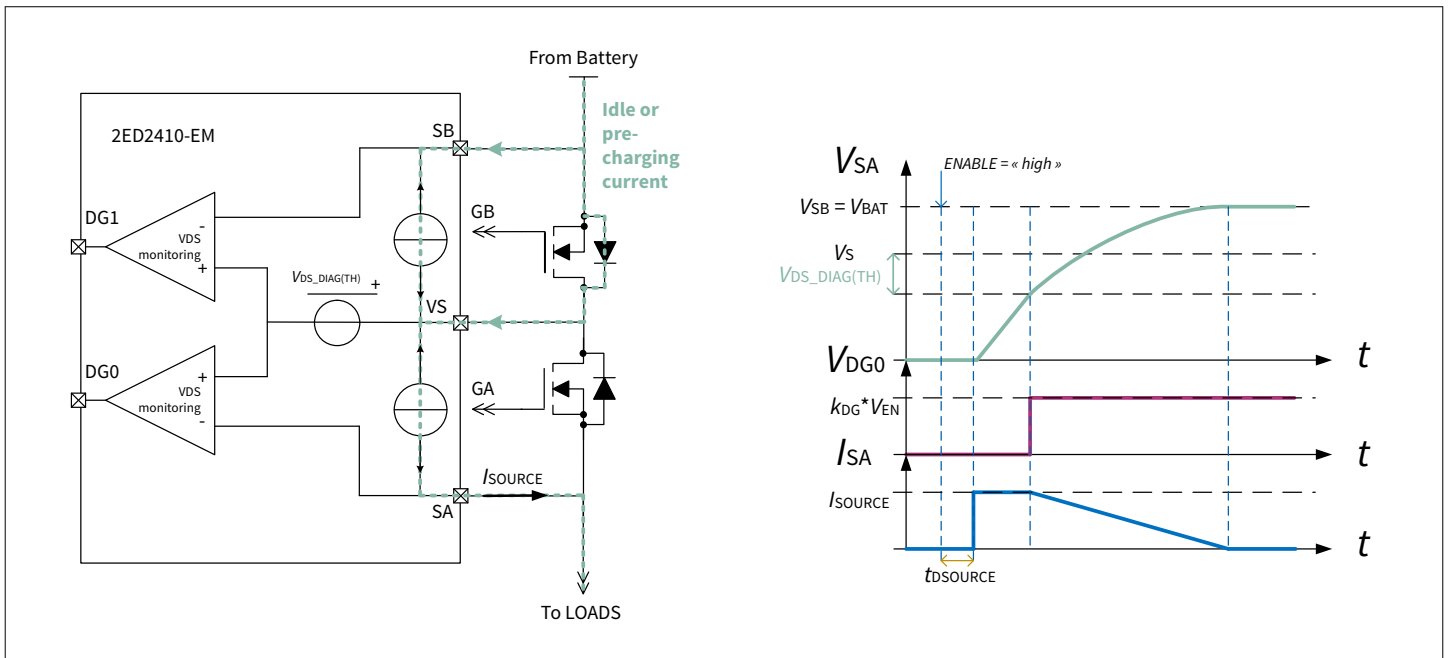
When in IDLE mode, 2ED2410-EM can sink a low current from VS pin to its source pins SA and/or SB and from SA to SB or SB to SA.

The activation is autonomous.

Up to  $V_{SX} = V_S - V_{DS\_DIAG(TH)}$ ,  $I_{SOURCE}$  is delivered with typical value [see PRQ-56]. When  $V_S - V_{DS\_DIAG(TH)}$  threshold [see PRQ-91] is reached on the corresponding source the  $I_{SOURCE}$  decreases gradually and is turned-off when  $V_{SA} = V_{SB} = V_S$ . As a consequence, 2ED2410-EM is able to supply a current  $I_{SOURCE}$  to supply ECU idle mode currents, while keeping its self-consumption very low.

It can also be used to pre-charge ECU input capacitors in the downstream power-net, and keep them charged in car park mode with minimal current consumption.

If a short-circuit occurs at ECU side during the driver's IDLE mode,  $I_{SOURCE}$  is still supplied, however  $V_{DSX}$  is constantly monitored and the corresponding DGx is set to low. This allows, for example, detection of a short-circuit before turn-on. See [Chapter 7.1](#) for diagnostics behaviour in IDLE mode.



**Figure 13** Low by-pass current principle of operation and timing diagram (not to scale)

## 7 Measurement features

### 7.1 VDS monitoring in IDLE mode

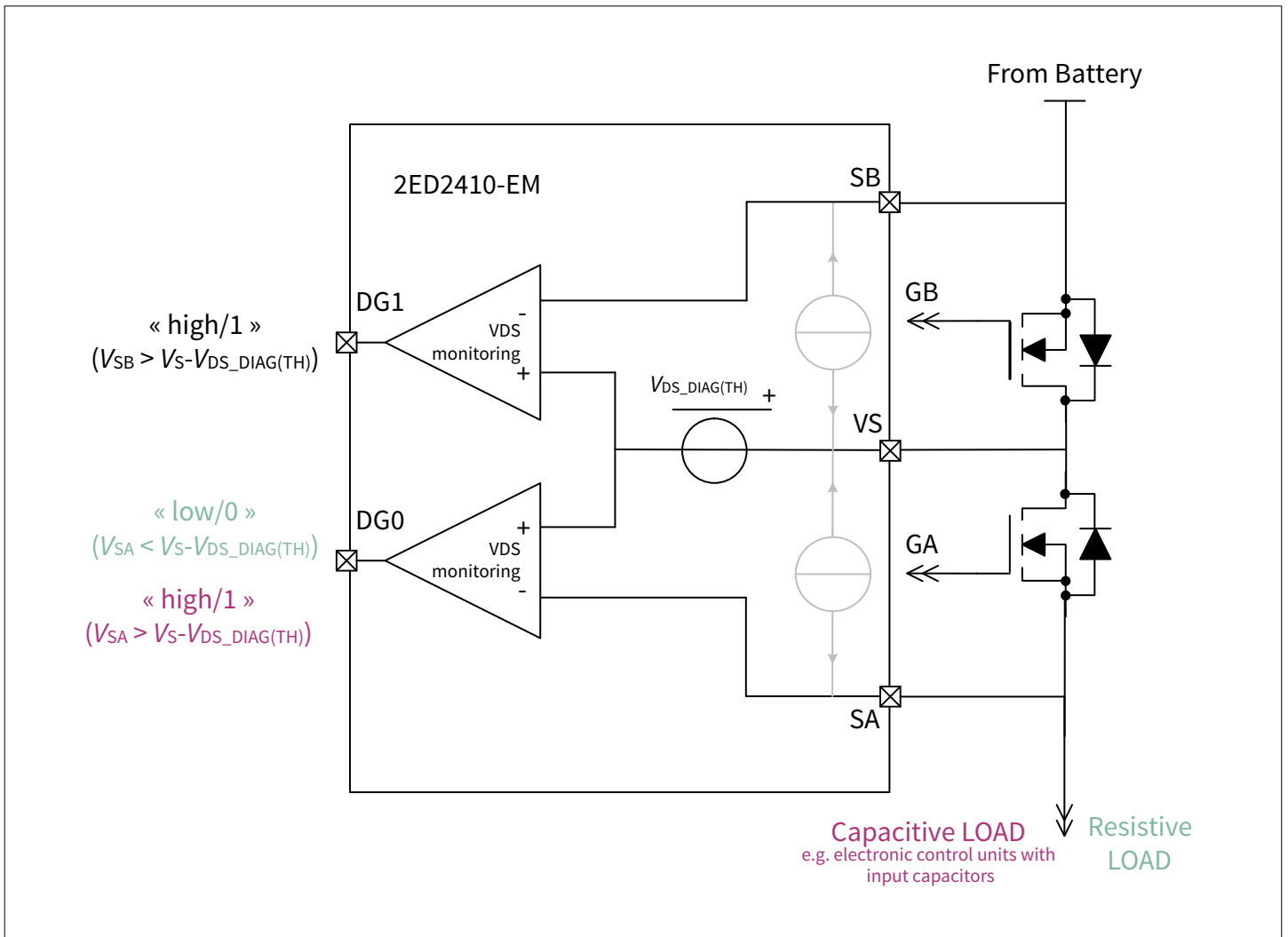
The VDS monitoring function can be read on DGx pins in IDLE mode.

DG0 and DG1 respectively monitor  $V_{DSA}$  ( $V_S - V_{SA}$ ) and  $V_{DSB}$  ( $V_S - V_{SB}$ ), provided that MOSFET drains are connected to VS pin.

If  $V_{DSA}$  (or  $V_{DSB}$ )  $> V_S - V_{DS\_DIAG(TH)} \Rightarrow$  DG0 (or DG1) = high level ( $I_{SOURCE B}$  active, see Chapter 6).

If  $V_{DSA}$  (or  $V_{DSB}$ )  $< V_S - V_{DS\_DIAG(TH)} \Rightarrow$  DG0 (or DG1) = low level ( $I_{SOURCE B}$  active, see Chapter 6).

MOSFET sources are compared to an internal reference voltage  $V_S - V_{DS\_DIAG(TH)}$  (see parameter  $V_{DS\_DIAG(TH)}$ ).



**Figure 14 VDS monitoring diagram with example**

VDS monitoring allows to detect various situations depending on the switch positions in the boardnet.

It depends on the application.

A non-exhaustive list of possible switch position in the boardnet and situation are described below:

#### Case 1: battery - resistive / inductive load configuration

The driver is used to drive the load.

DG1 = high show an open connector / or load is high impedance (HZ)  $> V_{BAT} / I_{SOURCE}$ .



**7 Measurement features**

DG1 = low shows that the load is still present. To avoid leakage  $I_{SOURCE}$  in IDLE mode, SLEEP mode can be used in car park mode.

Case 2: battery - Electronic Control Units (ECU)/capacitive load configuration

The driver is used to separate a power-net which is without power supply from the main power-net with power supply. DG1 = high shows that all ECUs input capacitors are charged and that there is no leakage.

DG1 = low shows that ECUs input capacitors are charging with  $I_{SOURCE}$  or that there is a leakage.

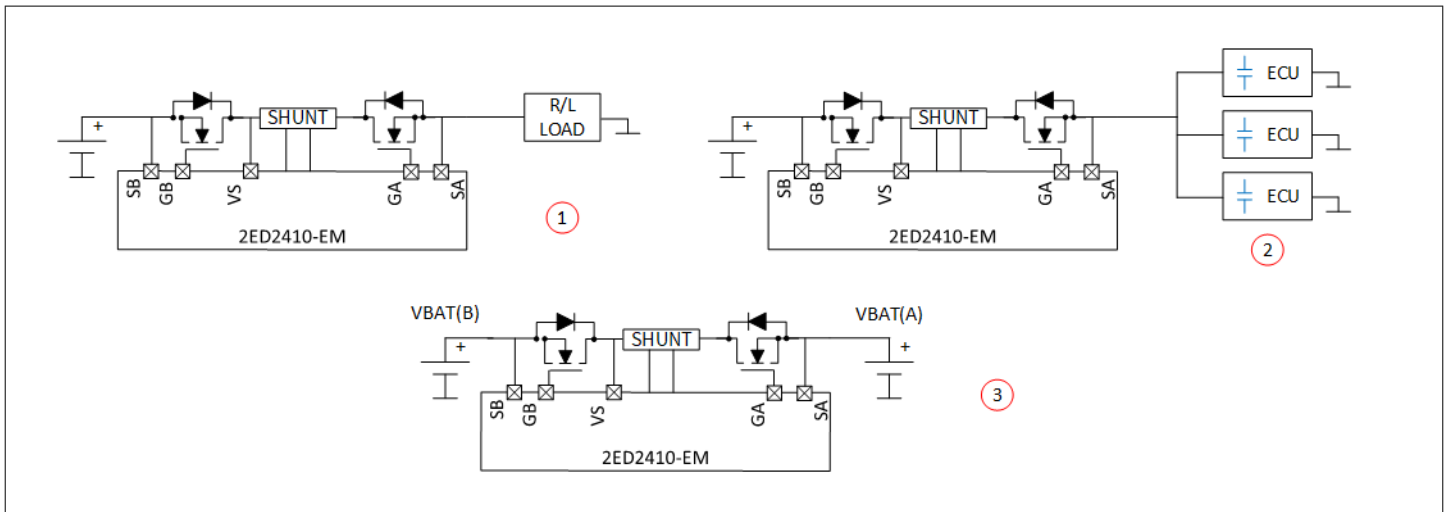
Case 3: battery - battery configuration

The driver is used to connect two power-nets where both power-nets have their power supply.

DG1 = high shows that  $V_{BAT(A)} - V_{BAT(B)} < V_{DS\_DIAG(TH)}$ .

DG1 = low shows that  $V_{BAT(A)} - V_{BAT(B)} > V_{DS\_DIAG(TH)}$ .

A very high current may flow when reconnecting and trigger SAFESTATE. Inductances between batteries must be carefully considered, including ground path.



**Figure 15** Cases 1, 2, 3

**7.2 Current senses in ON and SAFESTATE modes**

2ED2410-EM features two integrated current sense amplifiers (active in ON and SAFESTATE modes).

These **current sense amplifiers CSA1 and CSA2** are implemented with two identical differential amplifiers with a wide adjustable gain (G) (see PRQ-317).

The inputs are ISP1/2 and ISN1/2 pins and the outputs are CSO1/2 pin.

The current sensors must have a high-side position, or be positioned between the MOSFET drains in a back-to-back common drain configuration.

The current sense amplifier allows to monitor the currents flowing into the shunt (or MOSFET) in **both** directions, which is referred to as bidirectional current sensing.

The gain is set with external resistors  $R_{ISP1/2} = R_{ISN1/2}$  on input (on sensor side) and  $R_{CSO1/2}$  on output (on microcontroller/connector side).  $R_{ISP}$  and  $R_{ISN}$  can be different if a different gain is necessary depending of the current direction. On CSA1, this difference in gain will also impact the short-circuit protection which can be higher or lower depending on the gain magnitude.

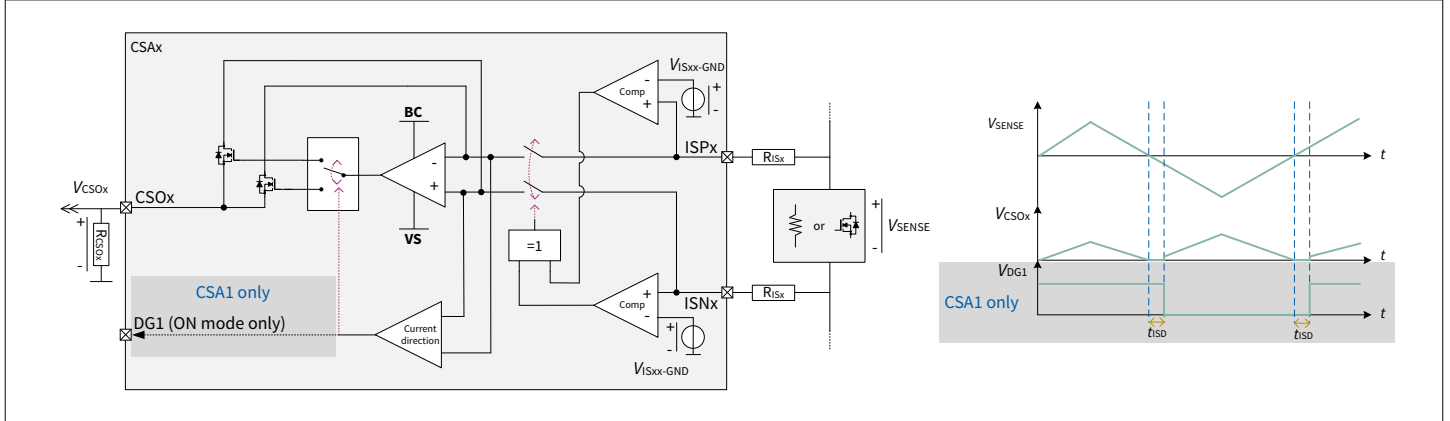
Resistor values can be adjusted based on the customer's current sensor solution.

The output is an analog voltage signal,  $V_{CSO1/2}$ , which represents the current flowing in the current sensor. It can be directly read on pin CSO1/2 (Current Sense Output) by a microcontroller.  $V_{CSO1/2}$  output voltage varies from 0 V to  $V_{EN}$ , in both directions, allowing better accuracy than current sensors using an offset as middle point for zero current.

7 Measurement features

The information of current direction is available only for **CSA1** and can be read in ON mode directly on pin DG1 (0 if current direction is from ISN1 to ISP1, 1 otherwise) by a microcontroller.

**CSA1** features an integrated comparator for fast short-circuit protection. See [Chapter 8.1](#).



**Figure 16** Current sense measurement principle and timing diagram [not to scale]

The amplifiers are supplied between BC and VS. If the  $V_{BC}-V_S$  voltage is below or above its functional range (see [PRQ-339](#)), the amplifiers input switches will open. As a result the current sense function is ensured and random reconnection can connect unwanted SAFESTATE.

The gain of the current sense amplifiers is configurable by three external resistors ( $R_{CS0}$ ,  $2 \times R_{IS}$ ).

The relationship between  $V_{SENSE}$  and  $V_{CS0}$  through the current sense amplifier is given by:

$$V_{CS0} = |V_{SENSE}| \times \frac{R_{CS0}}{R_{IS}} \quad (1)$$

Where the gain is set by:

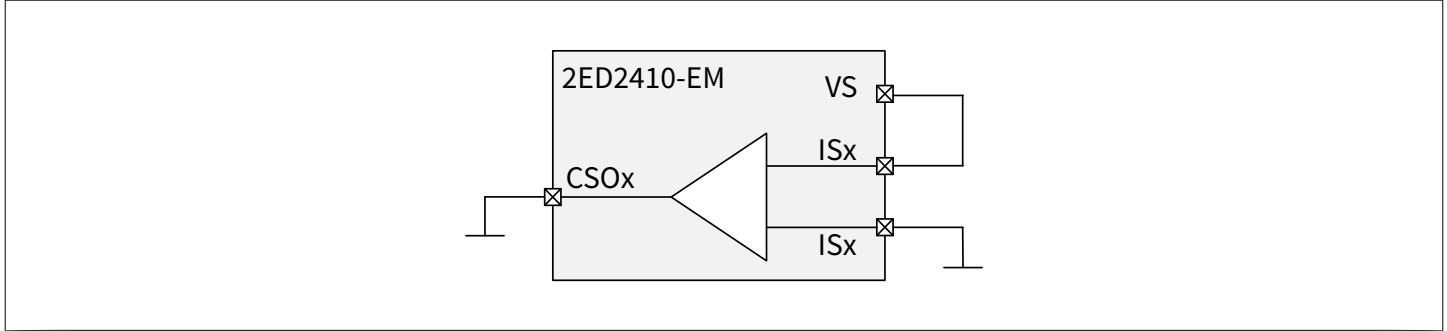
$$G_{CS0} = \frac{R_{CS0}}{R_{IS}} \quad (2)$$

Special care has to be taken when setting the gain and the parameters  $G_{CS0}$  and  $R_{CS0}$  must be observed. Resistors are recommended with at least 1% precision and should be placed as close as possible to the 2ED2410-EM pins. See application note "Getting started with 2ED2410-EM" for a complete description on how to use the current sense amplifiers.

If not used, CSA1 or CSA2, or both, can be simply disconnected with the following configuration. One of the two input pins, either ISP or ISN needs to be connected close to GND (see [PRQ-340](#)).

This will reduce the driver self-consumption in ON and SAFESTATE modes.

Warning: short-circuit protection with internal comparator on CSA1 will also be disabled if CSA1 is disabled.



**Figure 17** CSA1 & 2 disconnection configuration

### 7.3 Temperature measurement amplifier in ON and SAFESTATE modes

2ED2410-EM features an integrated temperature monitoring amplifier **TMPA** (active in ON and SAFESTATE modes). This **temperature monitoring** function is implemented with a differential amplifier.

The input pin is TMP and the output pin is TMPO.

The temperature amplifier allows to monitor the heat flowing into the  $R_{NTC}$  by monitoring  $V_{TMPO}$ .

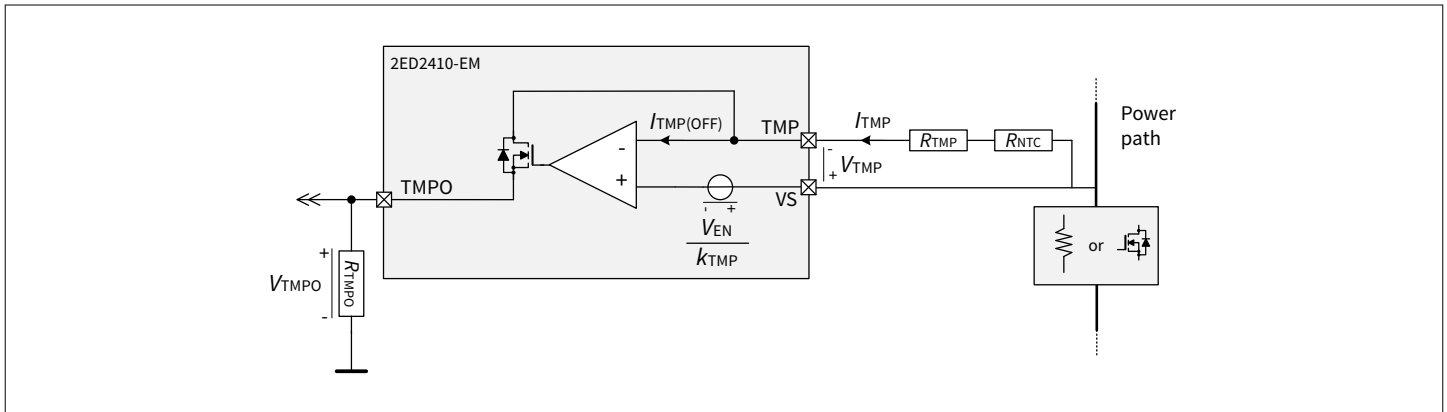
The gain is not directly adjustable and the ratio  $k_{TMP}$  is kept constant by the driver auto-adjusting the gain.

The ratio is kept with the  $R_{NTC}$  in input and  $R_{TMP}$  in output. Resistor values can be adjusted based on customer's thermistor solution.

In the present document, the temperature sensor is referred to as " $R_{NTC}$ " but other sensors, such as PTC or other thermistors can be implemented.

The output is an analog voltage signal:  $V_{TMPO}$  represents the temperature in the  $R_{NTC}$ . It can be directly read on pin TMPO (Temperature Output) by a microcontroller.  $R_{TMP}$  is not mandatory, but may be needed for linearisation of the output signal  $V_{TMPO}$ , depending on the thermistor solution choice.

Finally, TMPA can also be disabled if not used. TMP and TMPO pins can be left open.



**Figure 18** Temperature measurement diagram

The ratio  $k_{TMP}$  is defined as follows according to the [Figure 18](#).

$$k_{TMP} = \frac{V_{EN}}{V_{TMP}} \quad (3)$$

## 8 Protections features in ON mode

### 8.1 Short-circuit protection

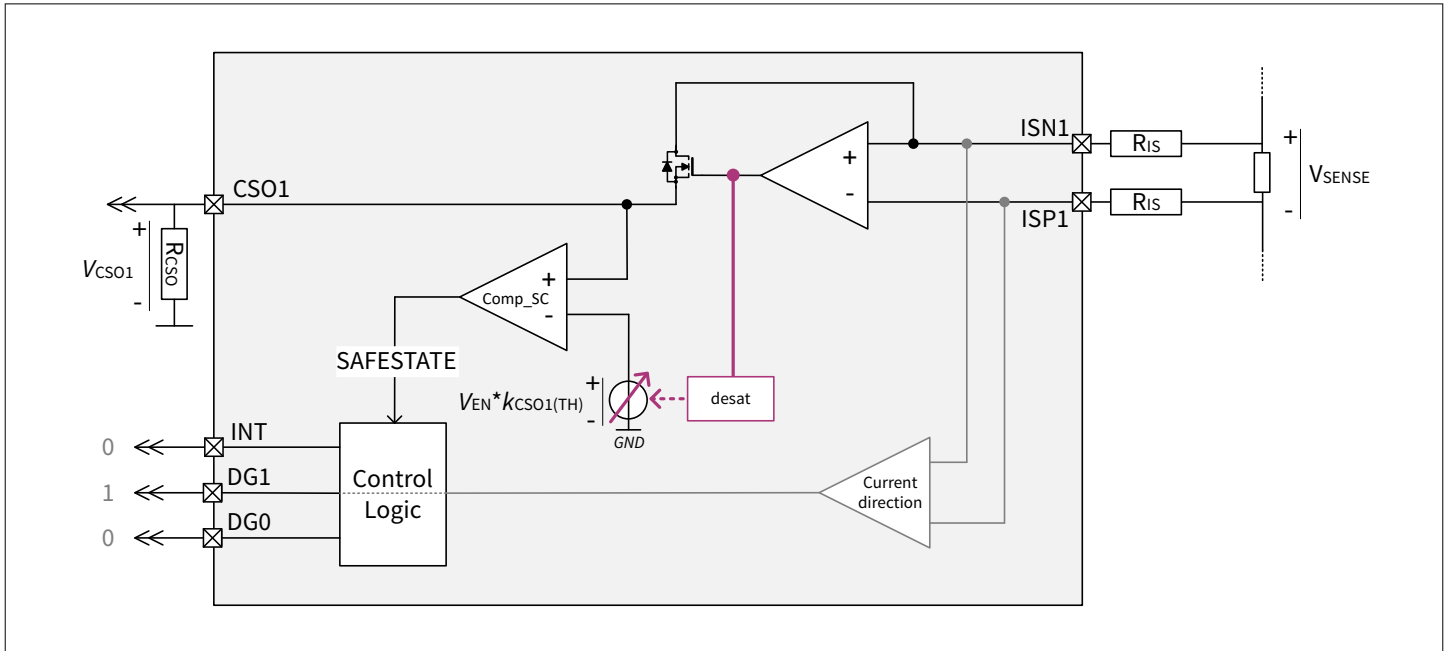
CSA1 has a fast comparator on its output CSO1, which allows 2ED2410-EM to enter SAFESTATE mode when  $V_{CSO1}$  reaches  $V_{CSO1(TH)} = k_{CSO} \times V_{EN}$ .

This allows fast turn-off delay time in case of overcurrent/short-circuit when CSA1 is used. 2ED2410-EM is able to switch off the MOSFET without the microcontroller.

The turn-off delay time is  $t_{DSCG(L)}$  and can be computed by the sum  $t_{DSCCSO1(H)} + t_{DCSO1(H)INT(L)} + t_{DINT(L)G(L)}$ . However, the maximum of  $t_{DSCG(L)}$  is not the sum of the maximum of the other delays, because by construction, the silicon process and variation make such a case impossible. This is why only the maximum of  $t_{DSCG(L)}$  (PRQ-330) should be considered when considering the worst case turn-off delay in case of short-circuit detection by CSA1 comparator.

See Chapter 5.1 for details on diagnostics in SAFESTATE mode.

Once in SAFESTATE mode, the driver needs to be reset.



**Figure 19** CSA1, internal comparator and diagnostics (one amplifier direction represented for simplicity)

The nominal voltage range for short-circuit protection is  $V_{S(NOR)}$ . As represented in the graph in Figure 20, in the  $V_{S(SC)LOW}$  range (PRQ-40), 2ED2410-EM keeps operating if already in ON or IDLE mode. In the  $V_{S(SC)LOW}$  range the short-circuit detection and shutdown are operational and 2ED2410-EM is protected but the  $V_{CSO1(TH)}$  parameter, hence the short-circuit detection depends on  $V_S$  and  $V_{EN}$ . A dedicated function named DESAT covers the protection threshold in the  $V_{S(SC)LOW}$  range.

The variation of  $V_{CSO1(TH)}$  is shown in the following graphs.

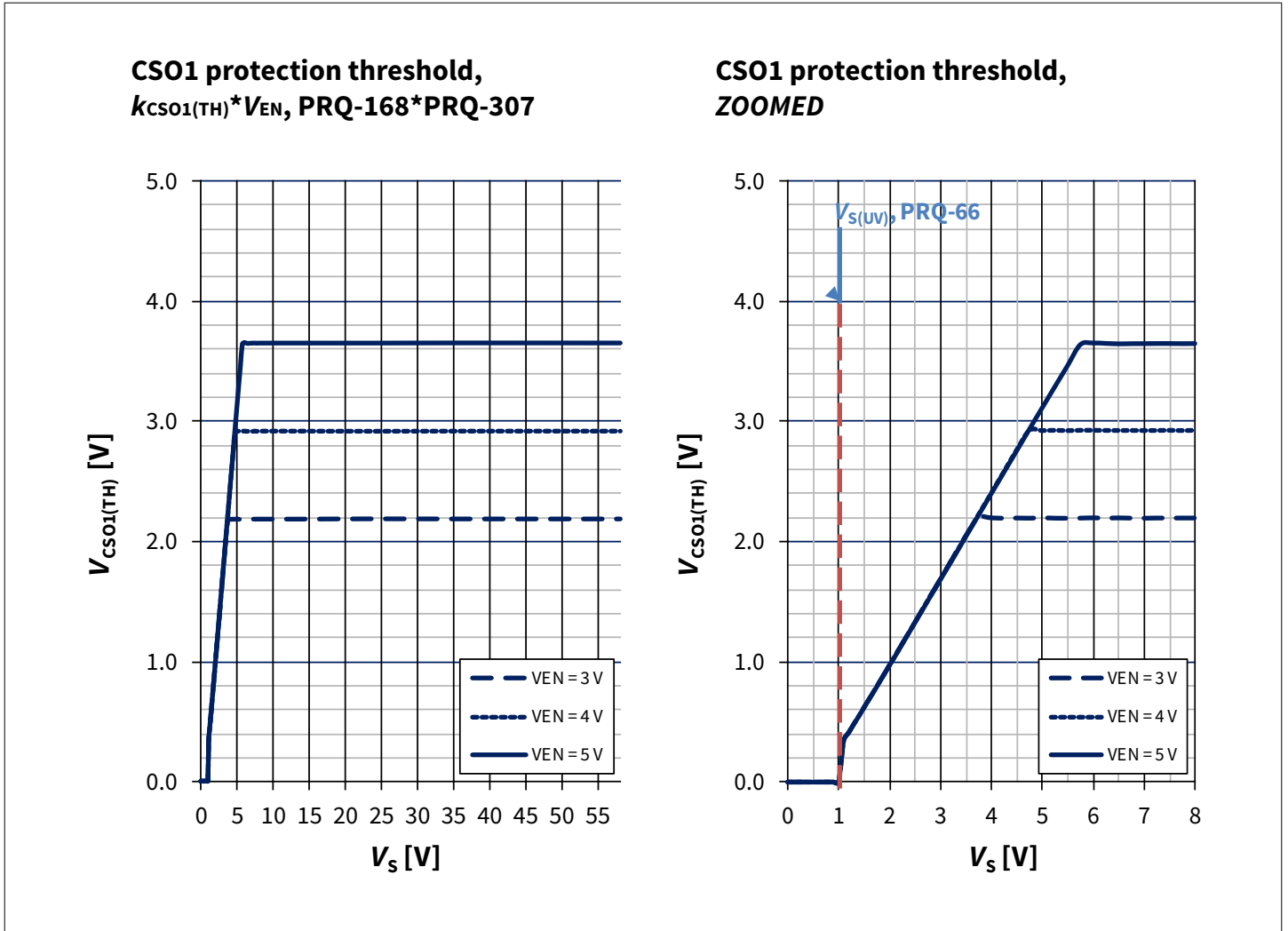


Figure 20 Typical  $V_{CS01(TH)}$  versus  $V_S$  and  $V_{EN}$  (independent of  $T_J$ )

## 8.2 Undervoltage protection on VS

VS pin has an integrated comparator comparing permanently  $V_S$  voltage to  $V_{S(UV)}$  reference (PRQ-66), which allows 2ED2410-EM to enter SAFESTATE mode when  $V_S$  reaches down  $V_{S(UV)}$  level.

The turn-off delay time is computed by the sum  $t_{DUV(H)INT(L)} + t_{DINT(L)G(L)}$  (PRQ-320, PRQ-136).

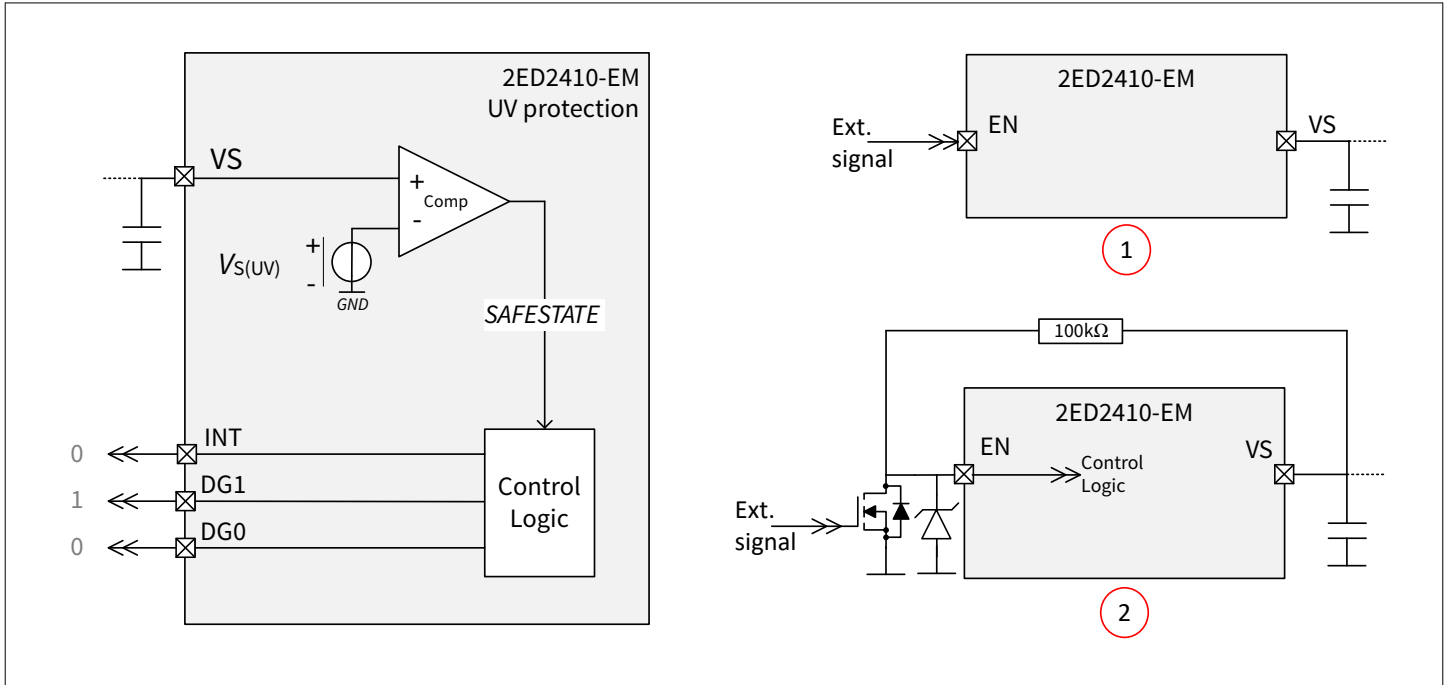
This has two consequences:

- The driver is protected down to 0 V on battery, meaning that a very strong short-circuit that would actually bring the voltage on VS node to 0 V is covered and switch is protected.
- The driver could be sensitive to micro-cuts on the supply if the micro-interruptions are longer than  $t_{DUV(H)INT(L)}$ . To overcome this effect, a capacitor can be used next to VS pin (e.g. a few micro-farad). Additionally, if large micro-cuts are expected in the application, ENABLE pin can be connected to VS pin directly through a 100kΩ (or more) resistor. An additional Zener diode is necessary on the ENABLE pin to limit the voltage to the desired value, e.g. 3.3 V or 5 V. When the micro-interruption is over, the driver will automatically turn-on again as soon as  $V_{EN(H)}$  (PRQ-74) threshold is reached again on the ENABLE pin.

See Chapter 5.1 for details on diagnostics in SAFESTATE mode.

Once in SAFESTATE mode, the driver needs to be reset.

The figure below shows the diagram, (1), the normal driver configuration, and (2), a possible adapted configuration with external circuitry for connection of the ENABLE pin to VS which will reset the driver automatically in case of a large micro-interruption.



**Figure 21**  $V_{S(UV)}$  protection diagram and possible driver configuration

### 8.3 Custom protections with comparator

2ED2410-EM features a voltage comparator with inputs CPP and CPN.

This comparator can be used to trigger SAFESTATE mode based on any analog voltage, even a voltage external to 2ED2410-EM.

CPP is the positive input of the comparator and CPN is the negative input.

$V_{CPREF}$  can be adjusted by microcontroller, or fixed by an on-board power supply chip, such as an Infineon SBC, or a simple voltage divider, within the limits  $V_{CP(REF)}$  for stability.

Using this comparator allows 2ED2410-EM to enter SAFESTATE and turn-off MOSFET independently from the microcontroller. The comparator reacts with a delay time  $t_{DCP(H)INT(L)}$ . Consequently the turn-off delay time in case of shutdown by comparator CP can be computed by the sum  $t_{DCP(H)INT(L)} + t_{DINT(L)G(L)}$ .

When SAFESTATE mode is triggered, digital outputs {DG0;DG1} will feedback {1;1}. See [Chapter 5.1](#). Once in SAFESTATE, driver needs to be reset.

Below are illustrated 4 possible use cases, and more are possible:

Case 1: overtemperature protection using TMPO output.

Case 2: I-t wire protection using RC. Both limits, short-reaction time and long-time direct current are adjustable dynamically (e.g. a microcontroller PWM output) with  $V_{EN}$  and  $V_{CPREF}$  respectively.

Case 3: protection using any external signal. The  $V_{CP(REF)}$  can be dynamically adjusted by microcontroller. For example, for battery switch application, the current feedback from BMS can be used to trigger the SAFESTATE mode.

Case 4: undervoltage protection by monitoring VS with simple voltage divider.

Note: this custom protection is available together with the short-circuit comparator on CSA1 output.

8 Protections features in ON mode

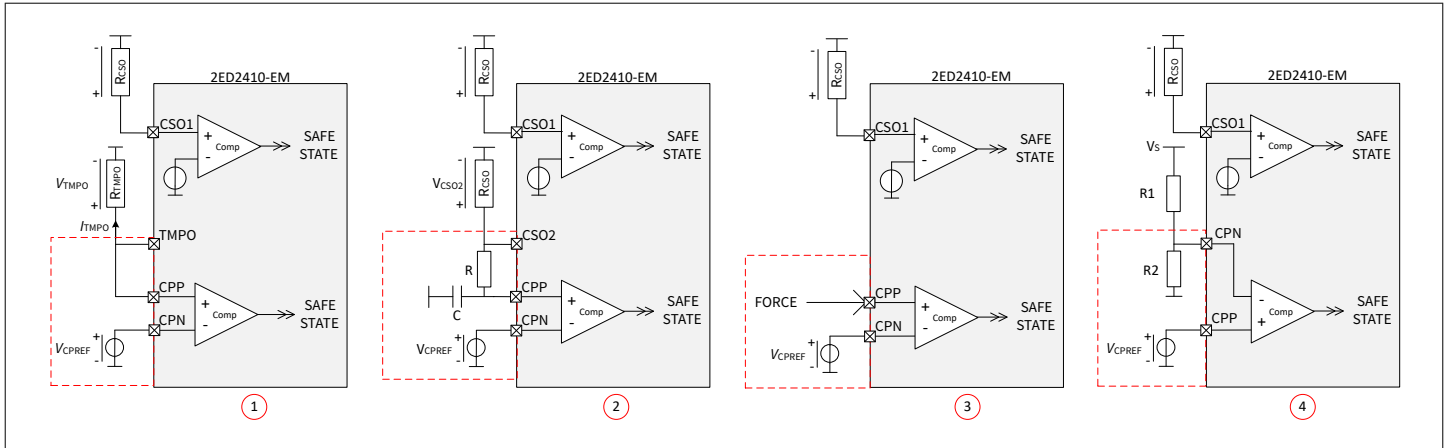


Figure 22 Comparator use cases examples

### 8.4 Gate undervoltage lock-out protection

The purpose of the gate undervoltage lock-out protection **UVLO** is to avoid to drive MOSFET in linear mode due to a leakage on boost converter output or MOSFET gates.

If  $V_{BC} - V_S < UVLO$  in ON mode, the driver enters SAFESTATE mode.

UVLO protection function is activated in ON mode, if at least  $V_{BC} - V_S$  has satisfied the condition  $V_{BC} - V_S > V_{BC(TH)}$  at least once in ON mode.

If  $V_{BC} - V_S < UVLO$  in ON mode and  $V_{BC(TH)}$  has not been reached once in ON mode, the device does not enter SAFESTATE mode because UVLO is not activated, but **gates do not turn on**.

As a result this situation can be detected by  $INT = 1$  and  $DG0$  displaying the maximum frequency of the boost converter, given the implemented boost converter external components. Once in SAFESTATE, driver needs to be reset.

### 8.5 Reset of SAFESTATE

2ED2410-EM has one way to actively reset the SAFESTATE: the voltage on EN pin needs to be pulled low for  $t_{RESET}$ .

Set  $V_{EN} < V_{EN(L)}$  for  $t_{RESET}$ , see [PRQ-75](#). See [Figure 8](#) for timing diagram.

Once EN pin is pulled down, INT signal will go up one the driver reaches SLEEP state again. SLEEP state can be verified by  $DG0 = DG1 = low$ .

2ED2410-EM can move back to IDLE mode by  $EN=high$  and  $INA=INB=low$ .

Note: If INA or INB remain "high" when EN is set "high", the driver will immediately enter ON mode if the condition  $V_{BC} - V_S \geq V_{BC(TH)}$  is satisfied.

## 9 Driver supply: boost converter

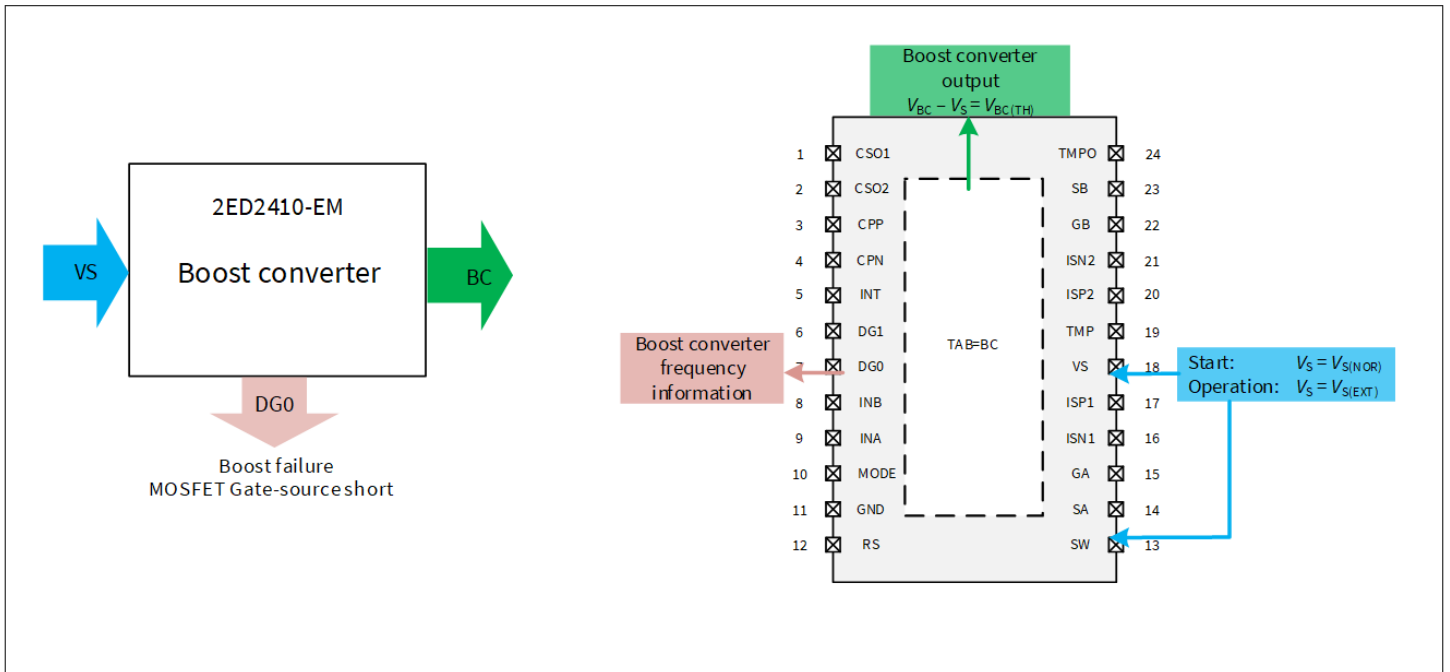
A **boost DC/DC converter structure** is the supply of 2ED2410-EM.

The diode and the activation switch K1 are implemented in the driver, but the capacitor  $C_{BC}$ , the resistor  $R_{RS}$  and the inductor L1 have to be added as external components.

The boost converter is active in IDLE mode, ON mode, SAFESTATE mode. It is off in SLEEP mode.

The boost converter starts when  $V_S \geq V_{S(NOR)}$  and  $V_{EN} \geq V_{EN(H)}$  (PRQ-74). Then, once  $V_{BC} - V_S \geq V_{BC(TH)}$  (PRQ-139), the boost converter operates normally over the  $V_{S(EXT)}$  range. If  $V_{EN} \leq V_{EN(L)}$ , the driver goes back to SLEEP mode from any of the other three operating modes and the boost converter is stopped.

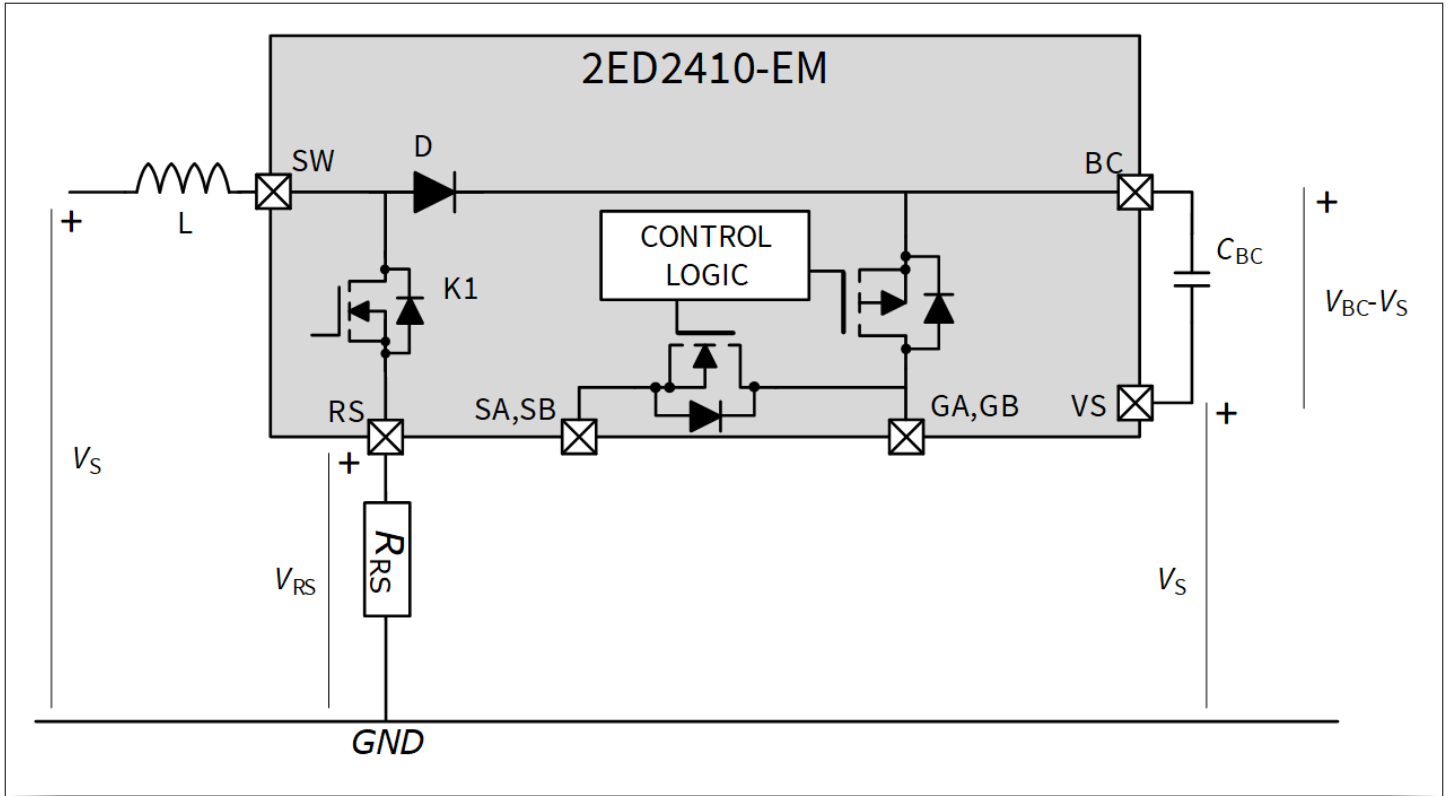
The switch K1 activation time is reflected on pin DG0 in ON mode.



**Figure 23 Principle of boost converter as driver supply**

The topology of the 2ED2410-EM supply is a boost DC/DC converter working in current mode control.





**Figure 24** BC topology used as gate supply

Activation:

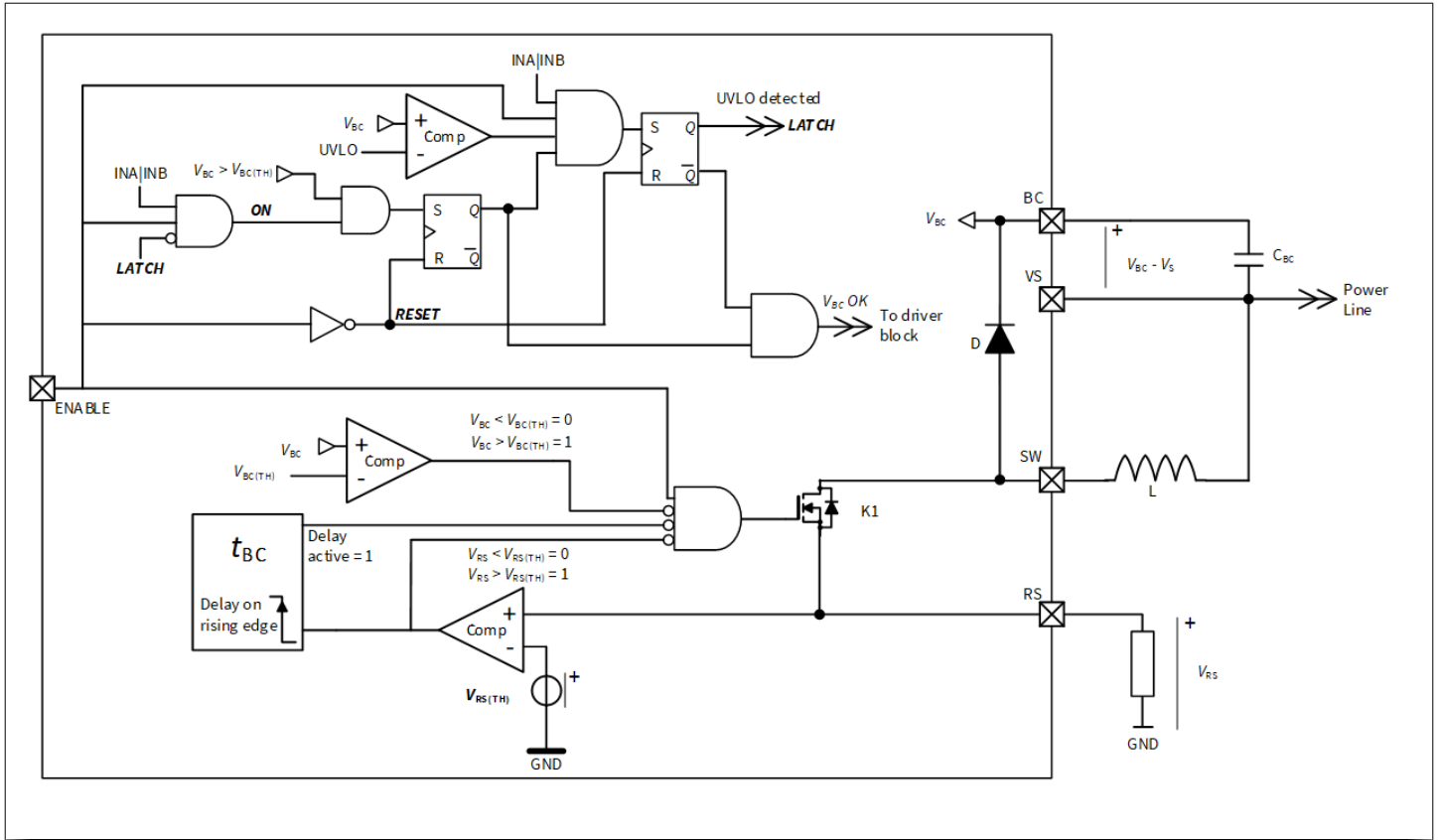
$K1$  is an integrated MOSFET, switched on when  $V_{BC} - V_S < V_{BC(TH)}$  and  $V_{RS} < V_{RS(TH)}$  (PRQ-147).

$K1$  is turned off when  $V_{RS} > V_{RS(TH)}$  or  $V_{BC} - V_S > V_{BC(TH)}$ .

The inductor charges the  $C_{BC}$  capacitor through diode  $D$ .

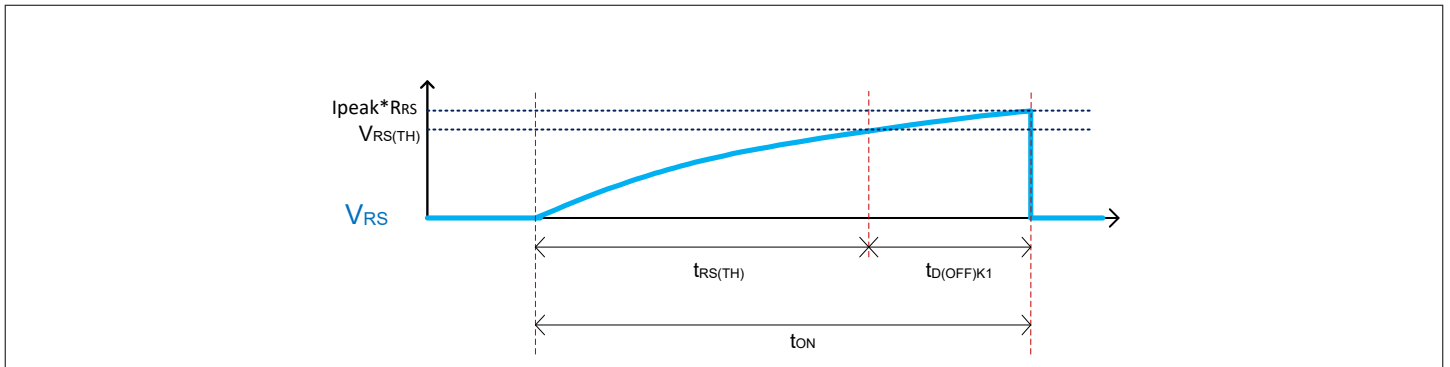
$D$  has a forward voltage drop of  $V_{FBC}$  (PRQ-148).

The  $K1$  MOSFET cannot restart during  $t_{BC(OFF)}$  (PRQ-152) after  $V_{RS(TH)}$  has been reached. This limits the boost converter maximum frequency.



**Figure 25 Boost converter control logic**

The current in the inductor is limited by the  $V_{RS(TH)}$  comparator which monitors the voltage across  $R_{RS}$ . Due to the delay in the loop,  $t_{D(OFF)K1}$  (PRQ-155), the inductor current exceeds the threshold set by:  $V_{RS(TH)}$ . The current waveform in the inductor is not linear, but exponential, because the sum of the resistance of  $K1$ , of the parasitic inductor of  $L1$  ( $R_L$ ), and  $R_{RS}$  are not negligible in the  $K1$  short activation timeframe. The calculations are described in the application note "Getting started with 2ED2410-EM".



**Figure 26 Current peak control**

The peak current must not exceed the maximum rating of  $I_{SW}$  (PRQ-16).

## **10 MOSFET connections in application**

The next figure shows a few typical connections in which the 2ED2410-EM driver can operate.

Amplifiers CSO1 and/or CSO2 can be disconnected to reduce 2ED2410-EM self-consumption. See [Chapter 7.3](#).

Any custom protection signal can be connected to the additional comparator regardless of the power MOSFET structure used, see [Chapter 8.3](#).

See application note "Getting started with 2ED2410-EM" on what to do with non-used pins.

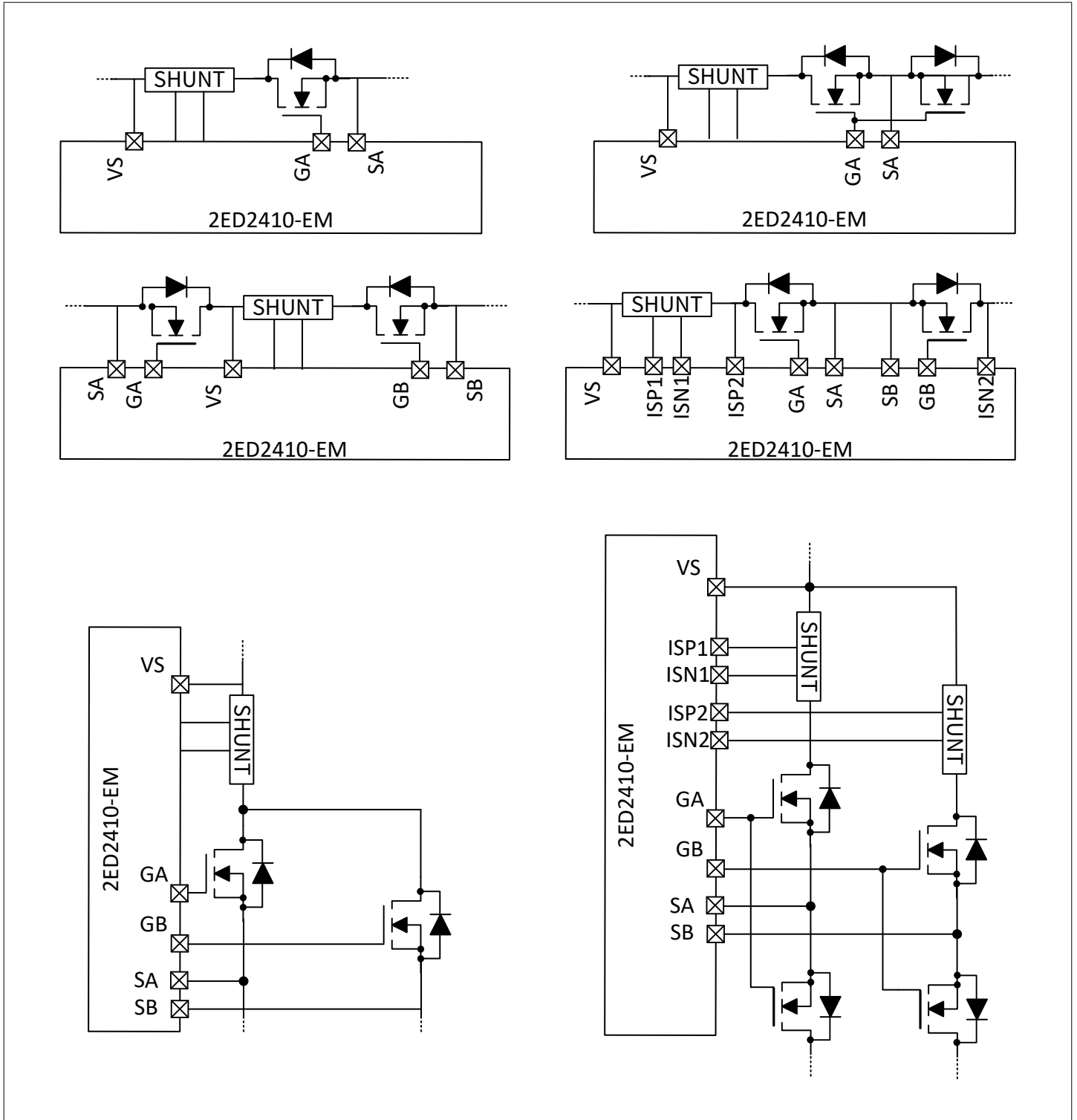


Figure 27 Typical MOSFET and shunt resistor connections

## 11 Characterization graphs

The graphs shown in this section are measured on typical parts, on a limited number of samples.

The goal is to show the variation of some parameters along the driver's operating voltage range and temperature, or a specific behaviour.

$T_J = -40$  to  $150^\circ\text{C}$ ,  $V_S = 8$  V to  $36$  V (unless otherwise specified), all voltages with respect to ground, typical values are given for  $V_S = 14$  V or/and  $T_J = 25^\circ\text{C}$ .

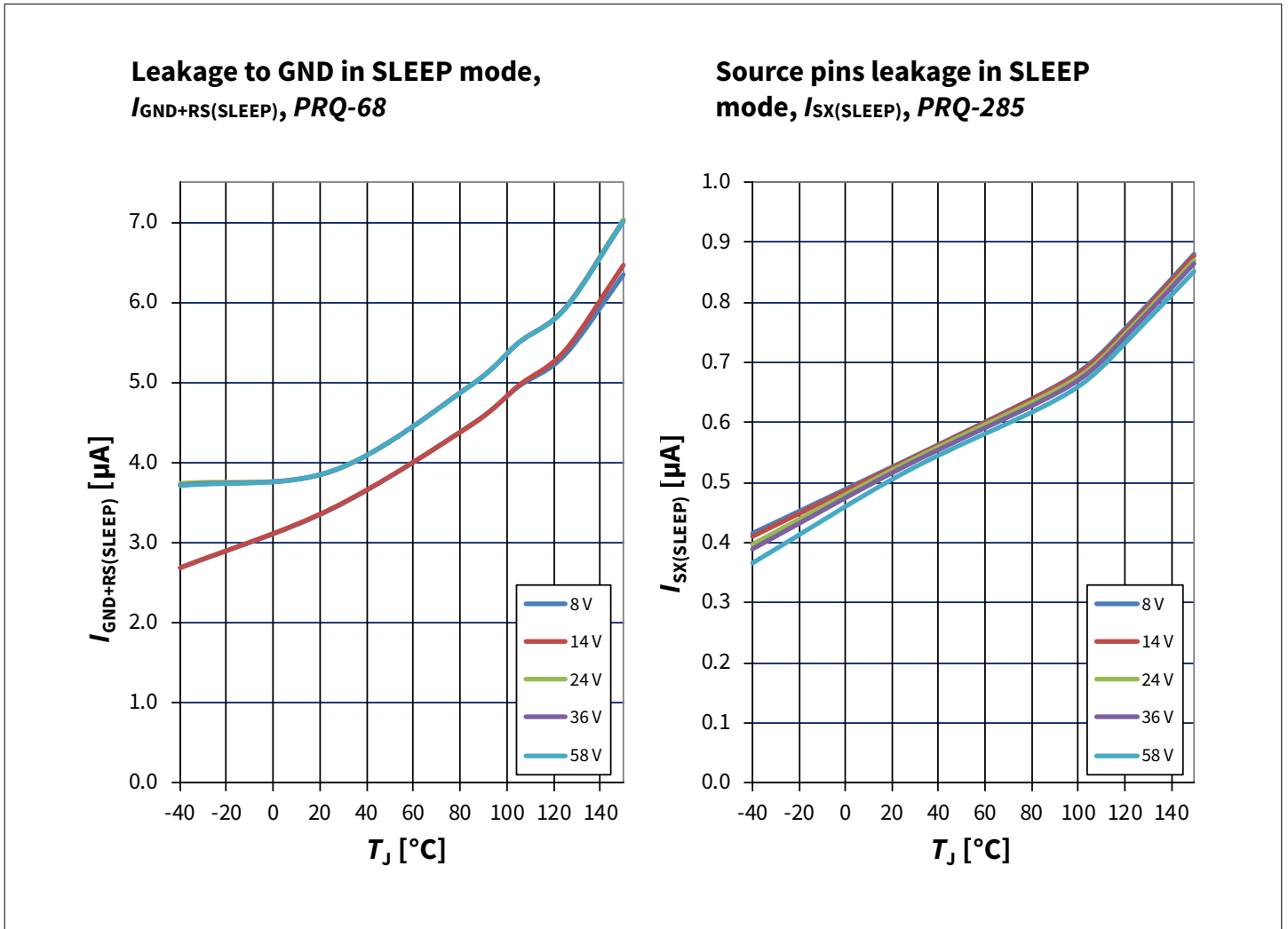


Figure 28 Driver leakage in SLEEP mode

11 Characterization graphs

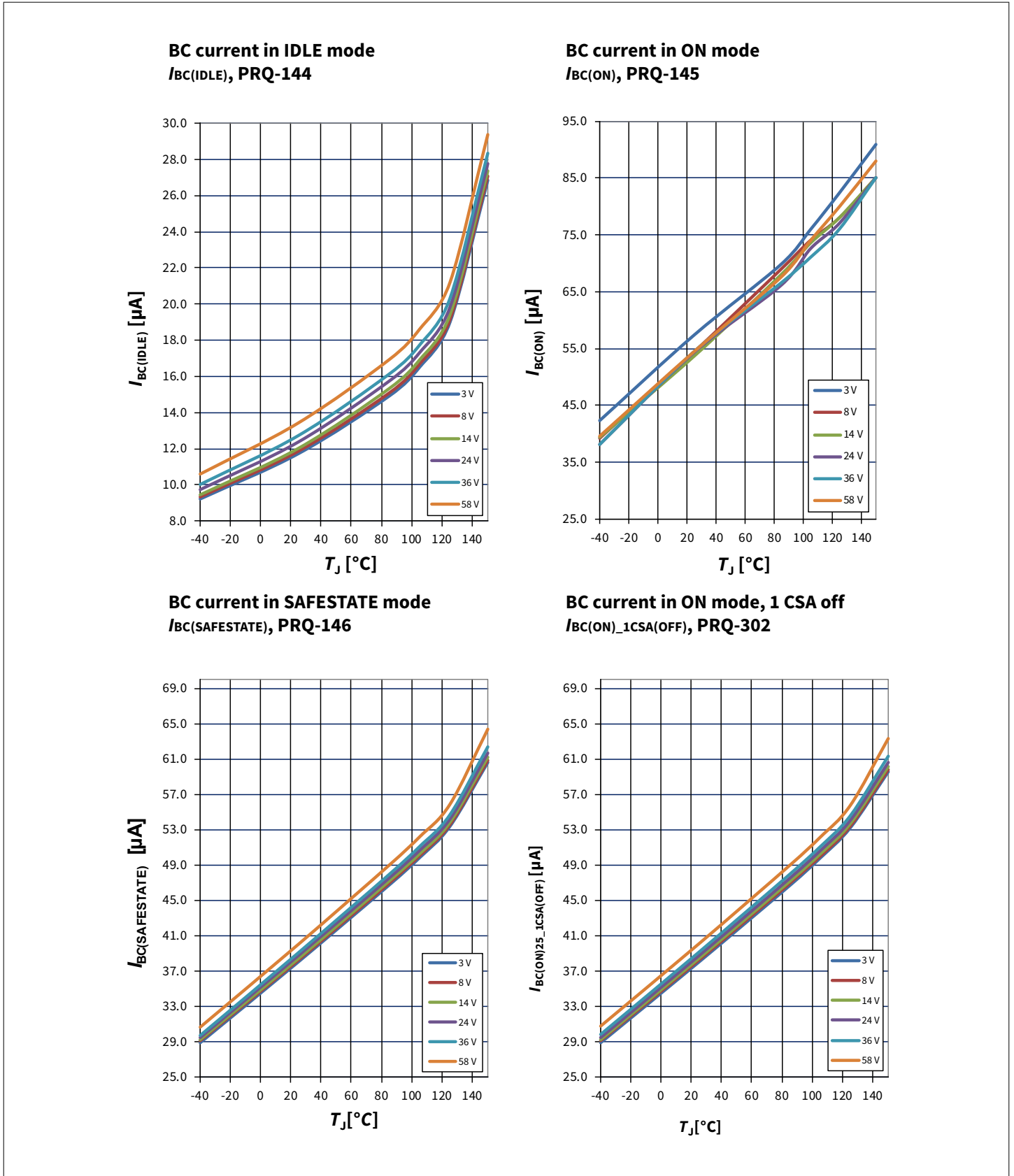


Figure 29 Current consumption

11 Characterization graphs

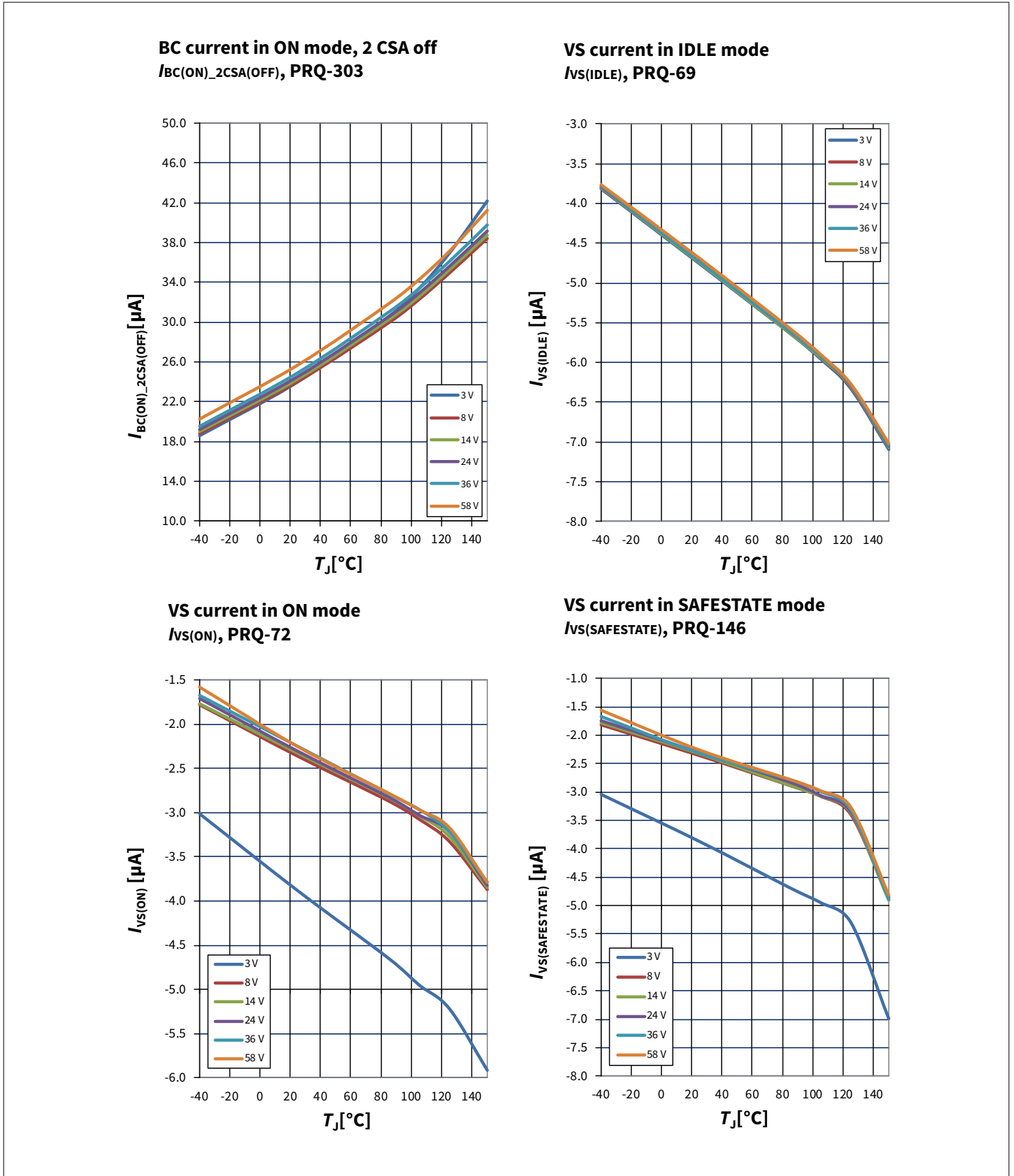


Figure 30 Current consumption continued

11 Characterization graphs

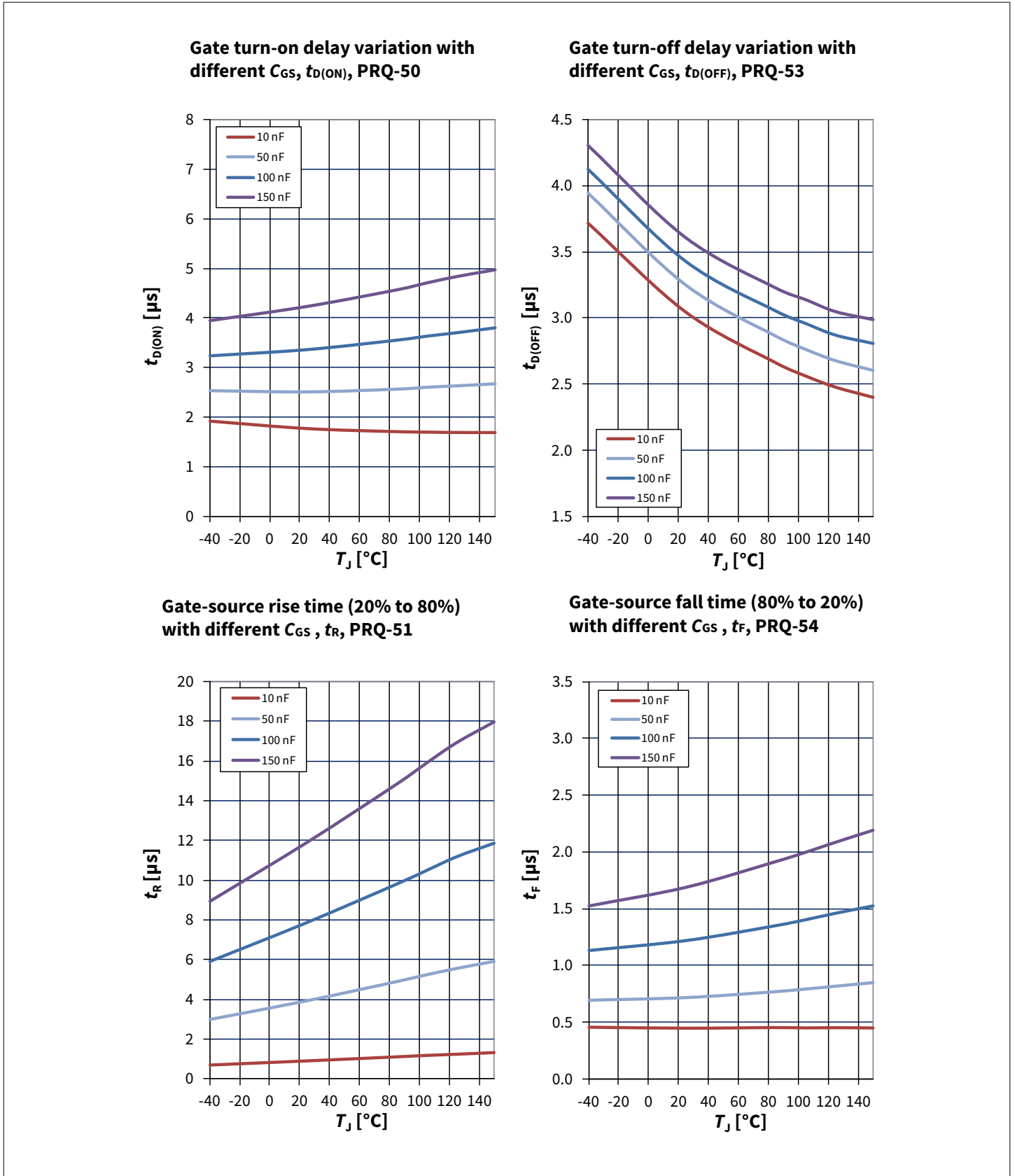


Figure 31 Switching timings (GA or GB)



11 Characterization graphs

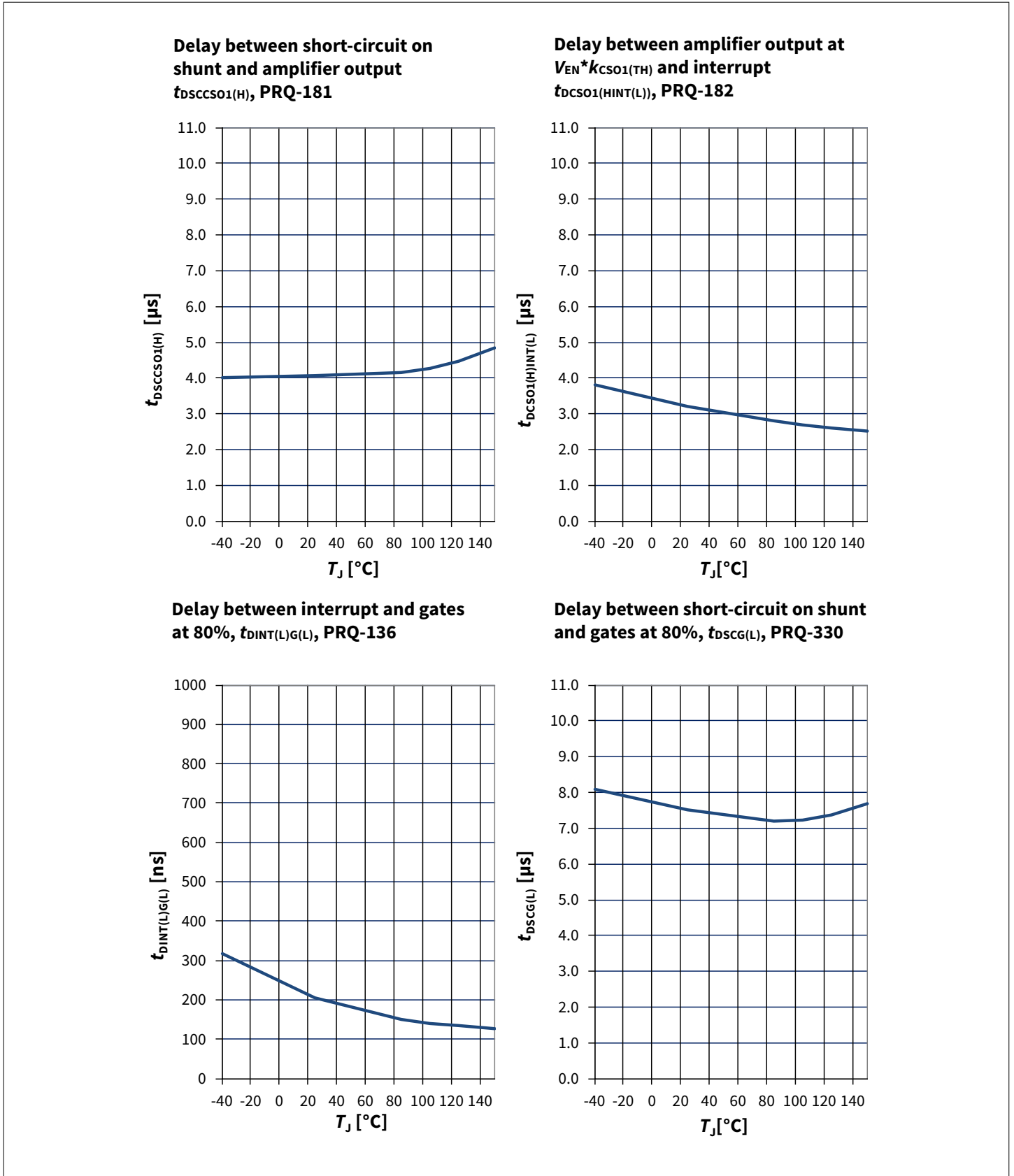


Figure 32 Short-circuit protection timings

11 Characterization graphs

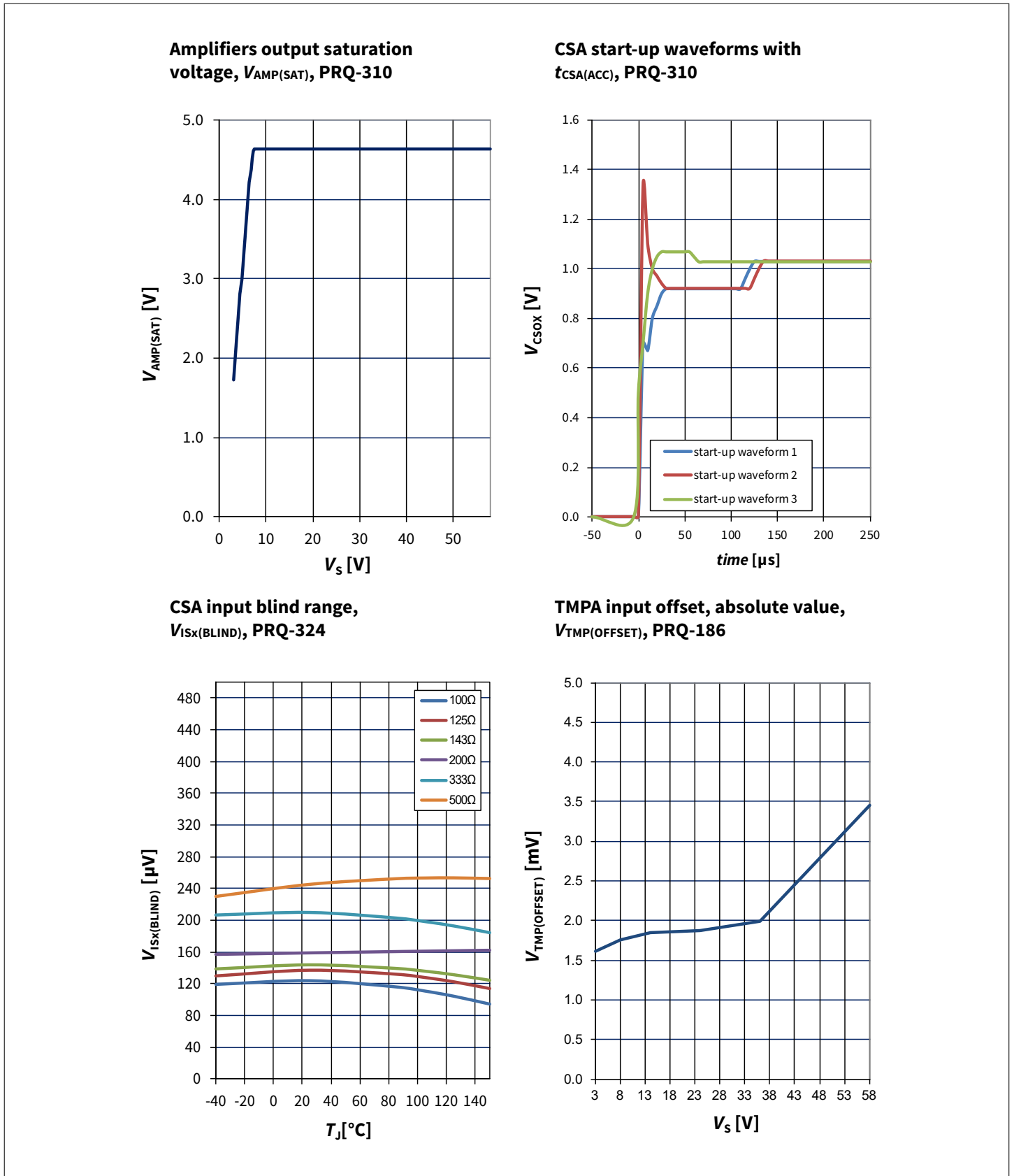


Figure 33 Amplifier characteristics

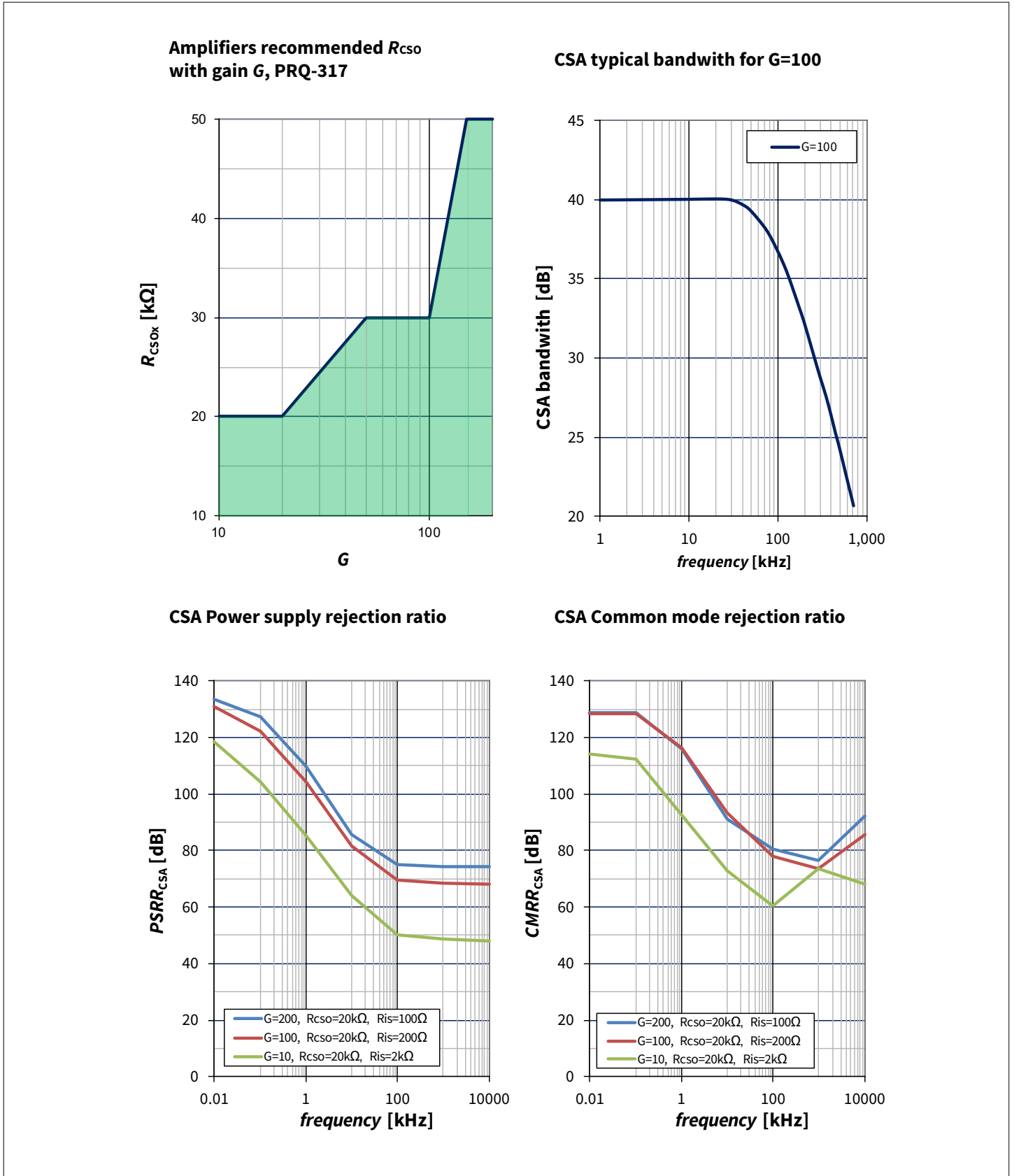


Figure 34 Amplifiers characteristics continued

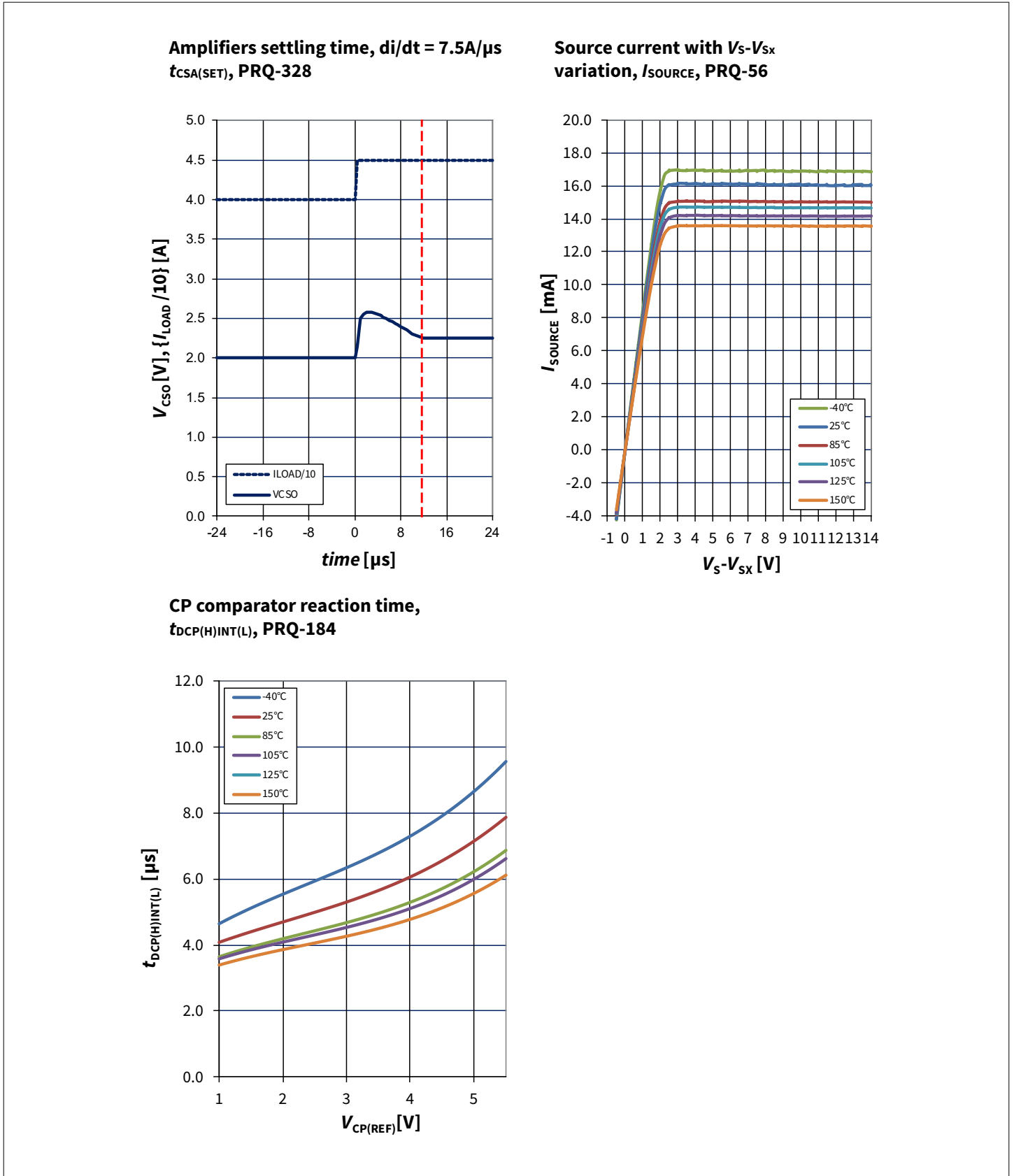


Figure 35 Miscellaneous characteristics

## 12 Package information

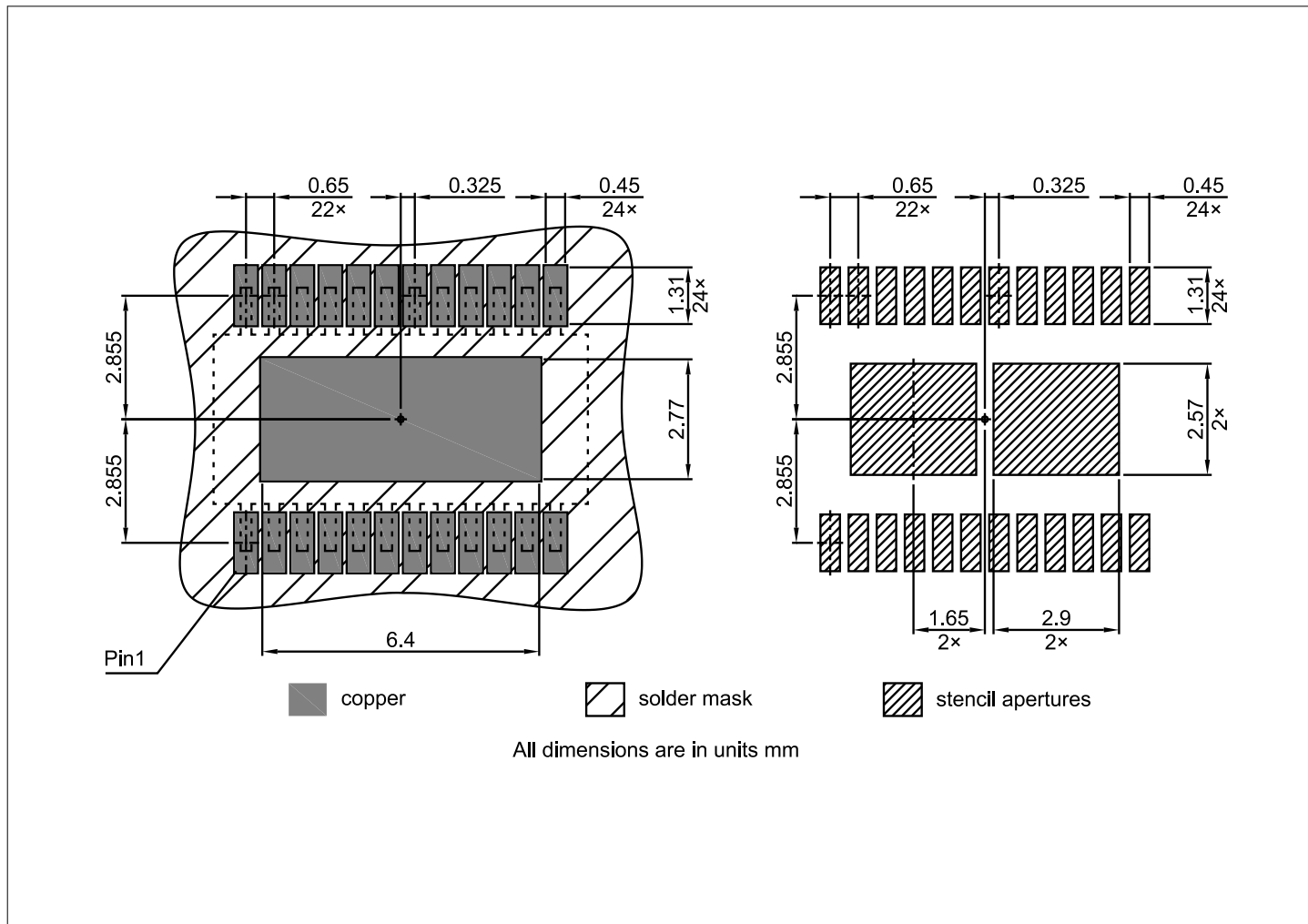


Figure 36 Footprint drawing

12 Package information

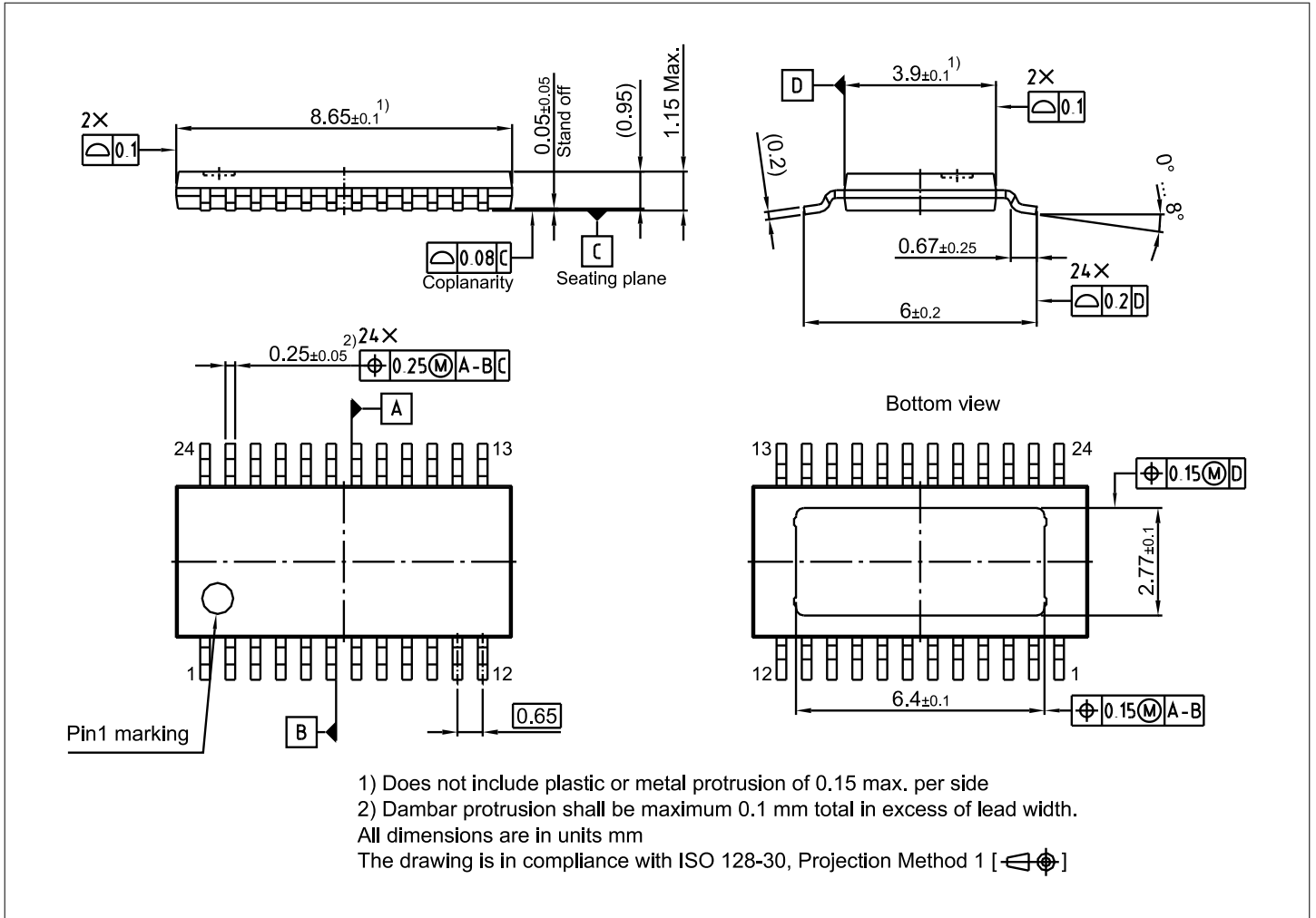
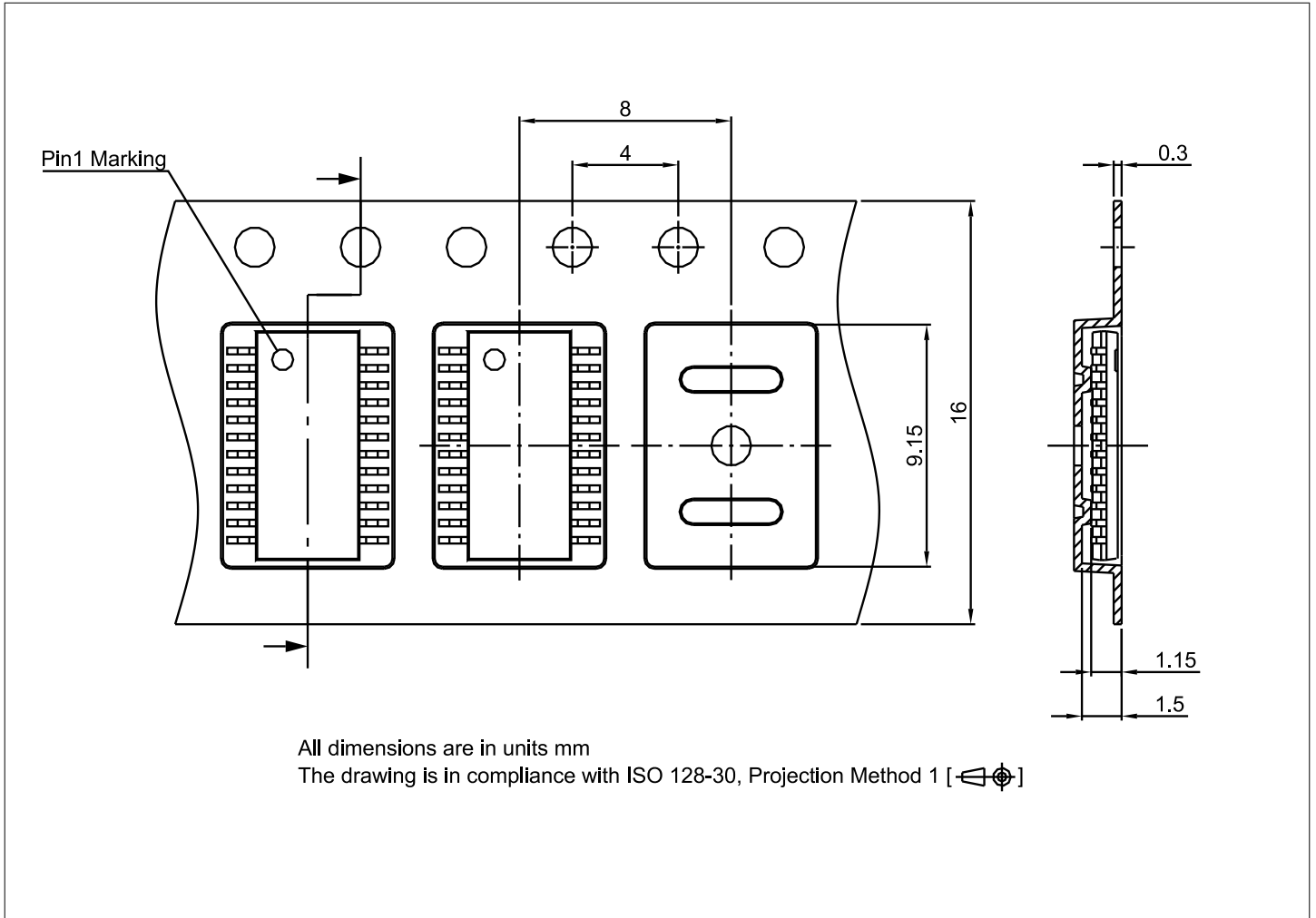


Figure 37 Package outline



**Figure 38** Tape & Reel

To meet the world-wide customer requirements for environmentally friendly products and to be compliant with government regulations the device is available as a green product. Green products are RoHS-Compliant (i.e Pb-free finish on leads and suitable for Pb-free soldering according to IPC/JEDEC J-STD-020).

## Revision history

Document version	Date of release	Description of changes
Rev. 2.10	2023-01-26	<ul style="list-style-type: none"><li>• PRQ-341 added</li><li>• PRQ-69 lower limit changed from -12μA to -15μA</li></ul>
Rev. 2.00	2022-07-11	<ul style="list-style-type: none"><li>• Device released</li><li>• Footnote added in column “Note or condition“ of PRQ-157, PRQ-336, PRQ-337, PRQ-338</li><li>• Footnote added in column “Note or condition” of PRQ-154</li></ul>
Rev. 1.00	2022-05-23	<ul style="list-style-type: none"><li>• Datasheet creation during development phase</li></ul>



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