AXL E PB DI8 DO8 M12 6M

Axioline E PROFIBUS device, metal housing, 8 inputs, 8 outputs, 24 V DC, M12 fast connection technology

Data sheet

8430_en_03

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1 Description

The Axioline E device is designed for use within a PROFIBUS network.

It is used to acquire and output digital signals.

The device is designed for use in systems manufacturing.

It is suitable for use without a control cabinet under harsh industrial conditions.

The Axioline E device can be used on tool platforms, directly on welding robots or in conveying technology, for example.

PROFIBUS features

- Connection to PROFIBUS DP using M12 connectors (B-coded)
- DP/V1 for Class 1 and Class 2 masters
- Data transmission speed of 9.6 kbps up to 12 Mbps (automatic detection)
- Rotary encoding switches for setting the PROFIBUS address
- Supported PROFIBUS addresses 0 to 126
- PROFIBUS features: Sync mode, Freeze mode, I & M functions
- Device description using GSD file

Axioline E features

- Connection of digital sensors and actuators to M12 connectors (A-coded)
- Diagnostic and status indicators
- Short-circuit and overload protection of the sensor supply
- IP65/67 degree of protection



This data sheet is only valid in association with the associated user manual.



Make sure you always use the latest documentation. It can be downloaded from the product at <u>phoenixcontact.net/products</u>.





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3 Ordering data

Description	Туре	Order No.	Pcs./Pkt.
Axioline E PROFIBUS device in a metal housing with 8 digital inputs and 8 digital outputs, 24 V DC, M12 fast connection technology	AXL E PB DI8 DO8 M12 6M	2701504	1
Accessories	Туре	Order No.	Pcs./Pkt.
An M12 screw plug for the unoccupied M12 sockets of the sensor/actuator cable, boxes and flush-type connectors (Protection and sealing elements)	PROT-M12	1680539	5
Bus system T-plug, PROFIBUS, M12 B-coded male plug to M12 B-coded male plug and M12 B-coded female plug, shielded (Connector/Adapter)	SAC-M12T/2XM12 PB DP	1507780	1
Terminating resistor PROFIBUS M12 (Connector/Adapter)	SAC-5P-M12MS PB TR	1507803	5
Mounting plate for Axioline E metal devices (Assembly)	AXL E MP 60	2701761	1
Snap-in markers, Sheet, white, unlabeled, can be labeled with: THERMOMARK CARD, BLUEMARK CLED, BLUEMARK LED, TOPMARK LASER, Mounting type: snapped into marker carrier, Lettering field: 7 x 10 mm (Marking)	UCT-EM (7X10)	0830765	10

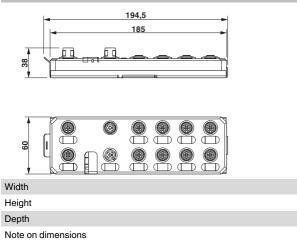
Documentation	Туре	Order No.	Pcs./Pkt.
User manual, English, Axioline E: system and installation	UM EN AXL E SYS INST	-	-
Application note, English, Startup of Axioline E PROFIBUS devices on a SIMATIC $^{\textcircled{B}}$ S7 controller (for experienced S7 users)	AH EN S7 - AXL E PB PRO	-	-

Additional ordering data

For additional accessories, visit phoenixcontact.net/products.

4 Technical data

Dimensions (nominal sizes in mm)



60 mm
185 mm
38 mm
The height is 194.5 mm including the mounting plate. With fixing clips pulled out, the height is 212 mm. The depth is 38 mm including the mounting plate (30.5 mm without the mounting plate).

General of	data	
Housing mat	erial	Zinc die-cast
Weight		750 g
Ambient tem	perature (operation)	-25 °C 60 °C
\triangle	CAUTION: Risk of burns If the device is used at an ambient temper	rature above 50°C, the contact temperature of metal surfaces may exceed 70°C.
Ambient tem	perature (storage/transport)	-25 °C 85 °C
Permissible	humidity (operation)	5 % 95 %
Permissible	humidity (storage/transport)	5 % 95 %
Air pressure	(operation)	70 kPa 106 kPa (up to 3000 m above sea level)
Air pressure	(storage/transport)	70 kPa 106 kPa (up to 3000 m above sea level)
Degree of pr	otection	IP65/IP67
Protection cl	ass	III, IEC 61140, EN 61140, VDE 0140-1
Connecti	on data	
Connection I	nethod	M12 connector
Interface	PROFIBUS DP	
Number		2
Connection i	nethod	2x M12 connectors, B-coded
Designation	connection point	Copper cable
Number of p	ositions	5
Transmissio	n speed	9,6 kBit/s 12 MBit/s (Automatic baud rate detection)
Transmissio	n physics	PROFIBUS-DP-compliant copper cable
PROFIBU	IS DP	
Equipment ty	/pe	PROFIBUS slave
PROFIBUS	protocols	DP V1
Supply:	Iodule electronics and sensors	(U _S)
Connection		M12 connector (T-coded)
	nethod	M12 connector (T-coded) 4
Connection	nethod ositions	
Connection i Number of p Supply volta	nethod ositions	4
Connection I Number of p Supply volta Nominal sup	nethod ositions ge	4 24 V DC
Connection I Number of p Supply volta Nominal sup	nethod ositions ge ply voltage range ent consumption	4 24 V DC 18 V DC 31.2 V DC (including all tolerances, including ripple)
Connection in Number of p Supply volta Nominal sup Typical currer Current cons	nethod ositions ge ply voltage range ent consumption	4 24 V DC 18 V DC 31.2 V DC (including all tolerances, including ripple) 165 mA ±15 % (at 24 V DC)
Connection in Number of p Supply volta Nominal sup Typical currer Current cons	nethod ositions ge ply voltage range ent consumption sumption	4 24 V DC 18 V DC 31.2 V DC (including all tolerances, including ripple) 165 mA ±15 % (at 24 V DC)
Connection I Number of p Supply volta Nominal sup Typical currer Current cons Supply: A	method ositions ge ply voltage range ent consumption sumption Actuators (U _A) method	4 24 V DC 18 V DC 31.2 V DC (including all tolerances, including ripple) 165 mA ±15 % (at 24 V DC) max. 12 A
Connection i Number of p Supply volta Nominal sup Typical curre Current cons Supply: A Connection i	method ositions ge ply voltage range ent consumption sumption Actuators (U _A) method ositions	4 24 V DC 18 V DC 31.2 V DC (including all tolerances, including ripple) 165 mA ±15 % (at 24 V DC) max. 12 A M12 connector (T-coded)
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Connection in Number of p Supply volta Nominal sup Typical currer Current cons Supply: <i>I</i> Connection in Number of p Supply volta Nominal sup	method ositions ge ply voltage range ent consumption sumption Actuators (U _A) method ositions ge	4 24 V DC 18 V DC 31.2 V DC (including all tolerances, including ripple) 165 mA ±15 % (at 24 V DC) max. 12 A M12 connector (T-coded) 4 24 V DC

Digital inputs	
Number of inputs	8 (EN 61131-2 types 1 and 3)
Connection method	M12 connector, double occupancy
Connection method	2, 3, 4-wire
Nominal input voltage	24 V DC
Nominal input current	typ. 3 mA
Sensor current per channel	typ. 0.75 mA (from U _S)
Total sensor current	max. 0.6 A (per device)
Input voltage range "0" signal	-30 V DC 5 V DC
Input voltage range "1" signal	11 V DC 30 V DC
Input filter time	< 1000 µs
Permissible conductor length to the sensor	30 m
Overload protection, short-circuit protection of sensor supply	Yes

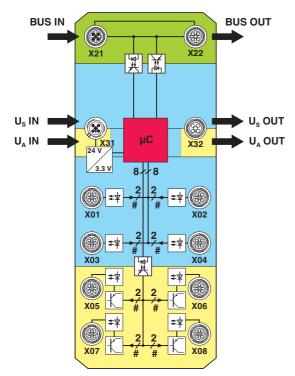
Digital outputs	
Number of outputs	8
Connection method	M12 connector, double occupancy
Connection method	2, 3-wire
Nominal output voltage	24 V DC (from voltage U _A)
Maximum output current per channel	500 mA
Nominal load, ohmic	12 W (48 Ω ; with nominal voltage)
Nominal load, inductive	12 VA (1.2 H; 48 Ω ; with nominal voltage)
Signal delay	max. 150 μ s (when switched on) max. 200 μ s (when switched off)
Switching frequency	max. 5500 per second (with at least 50 mA load current)
Switching frequency	max. 1 per second (with inductive load)
Limitation of the voltage induced on circuit interruption	-28 V17 V
Output voltage when switched off	max. 1 V
Output current when switched off	max. 20 μA
Behavior with overload	Auto restart
Reverse voltage resistance to short pulses	Reverse voltage proof
Overcurrent shut-down	min. 0.7 A
Overload protection, short-circuit protection of outputs	Electronic

Configuration data		
ID number	0E5E	
Input address area	8 Bit	
Output address area	8 Bit	

Test section	Test voltage
24 V supply (communications power and sensor supply, digital inputs)/ bus connection	500 V AC, 50 Hz, 1 min
24 V supply (communications power and sensor supply, digital inputs)/FE	500 V AC, 50 Hz, 1 min
Bus connection / FE	500 V AC, 50 Hz, 1 min
24 V supply (actuator supply, digital outputs)/ 24 V supply (communications power and sensor supply, digital inputs)	500 V AC, 50 Hz, 1 min
24 V supply (actuator supply, digital outputs)/bus connection	500 V AC, 50 Hz, 1 min
24 V supply (actuator supply, digital outputs)/FE	500 V AC, 50 Hz, 1 min
Mechanical tests	
Vibration resistance in acc. with EN 60068-2-6/IEC 60068-2-6	5g
Shock in acc. with EN 60068-2-27/IEC 60068-2-27	30g, 11 ms period, half-sine shock pulse
Continuous shock according to EN 60068-2-27/IEC 60068-2-27	10g
Conformance with EMC Directive 2004/108/EC	
Noise immunity test in accordance with EN 61000-6-2	
Electrostatic discharge (ESD) EN 61000-4-2/IEC 61000-4-2	Criterion B; 6 kV contact discharge, 8 kV air discharge
Electromagnetic fields EN 61000-4-3/IEC 61000-4-3	Criterion A; Field intensity: 10 V/m
Fast transients (burst) EN 61000-4-4/IEC 61000-4-4	Criterion B, 2 kV
Transient surge voltage (surge) EN 61000-4-5/IEC 61000-4-5	Criterion B; DC supply lines: $\pm 0.5 \text{ kV} \pm 0.5 \text{ kV}$ (symmetrical/asymmetrical)
Conducted interference EN 61000-4-6/IEC 61000-4-6	Criterion A; Test voltage 10 V
Noise emission test as per EN 61000-6-4	
Radio interference properties EN 55022	Class A

Approvals

For the latest approvals, please visit phoenixcontact.net/products.

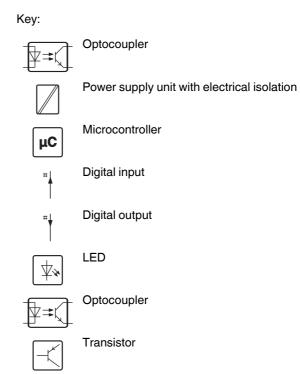


5 Internal circuit diagram

Figure 1 Internal wiring of connections

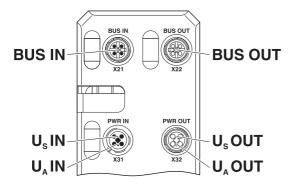
Key:

Green area:	Network
Blue area:	U _S
Yellow area:	U _A



6 Pin assignment

6.1 PROFIBUS and power supply connection



Designation	Meaning
BUS IN (X21)	PROFIBUS IN
BUS OUT (X22)	PROFIBUS OUT
U _S IN (X31)	Power supply IN (logic and sensors)
U _A IN (X31)	Power supply IN (actuators)
U _S OUT (X32)	Power supply OUT
	for additional devices
U _A OUT (X32)	Power supply OUT
	for additional devices

6.2 PROFIBUS pin assignment

The bus is connected via two B-coded M12 plug-in plugs. The incoming bus (IN) is a plug and the outgoing bus (OUT) is a socket.

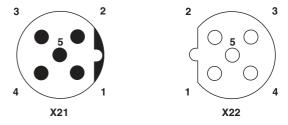


Figure 3 PROFIBUS pin assignment, B-coded

Pin	Signal	Specification	Description
1	VP	V	5 V termination resistor
2	RxD / TxD-N (A)	A, RS-485, PD	Inverted bus cable
3	DGND	V	0 V
4	RxD / TxD-P (B)	B, RS-485, PU	Non-inverted bus cable
5	Not used	-	-

Α	=	A line
В	=	B cable
RS-485	=	RS-485 level, bidirectional
V	=	Power supply
PU	=	Pullup
PD	=	Pulldown

i

The shield is connected to FE in the device.

i

The thread is used for additional shielding.

Ground the device by means of the mounting screws of the fixing clips or the mounting plate or the DIN rail.

6.3 Pin assignment of the power supply U_S/U_A

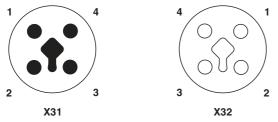
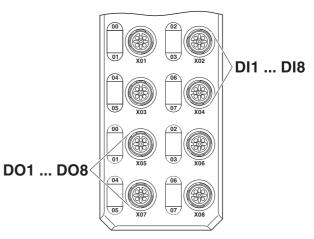
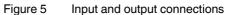


Figure 4 Pin assignment of the power supply, T-coded

Pin	IN	OUT	Conductor colors
1	+24 V DC (U _S)	+24 V DC (U _S)	Brown
2	GND (U _A)	GND (U _A)	White
3	GND (U _S)	GND (U _S)	Blue
4	+24 V DC (U _A)	+24 V DC (U _A)	Black

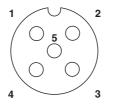
6.4 Connecting inputs and outputs

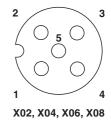




Designation	Meaning
DI1 DI8 (X01 X04)	Inputs 1 8
DO1 DO8 (X05 X08)	Outputs 1 8

6.5 Pin assignment of the inputs and outputs





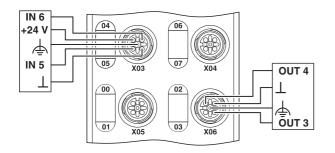
X01, X03, X05, X07

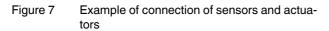
Figure 6

Pin assignment of the inputs and outputs, A-coded

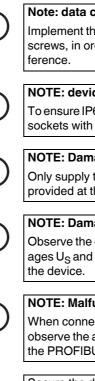
Pin	Input socket	Output socket
1	+24 V DC (U _S)	Not used
2	Input 2, 4, 6, 8	Output 2, 4, 6, 8
3	GND	GND
4	Input 1, 3, 5, 7	Output 1, 3, 5, 7
5	FE	FE

7 **Connection example**





8 **Connection notes**



Note: data corruption or loss

Implement the FE connection using mounting screws, in order to ensure immunity to inter-

NOTE: device damage

To ensure IP65/IP67 protection, cover unused sockets with protective caps.



NOTE: Damage to the electronics

Only supply the sensors with the voltage US provided at the terminal points.



NOTE: Damage to the electronics

Observe the correct polarity of the supply voltages US and UA in order to prevent damage to



NOTE: Malfunction

When connecting the sensors and actuators, observe the assignment of the connections to the PROFIBUS input and output data.



Secure the device to a level surface or to a profile. Do not use this device to bridge gaps, in order to prevent forces being transmitted via the device.



Use standard M5 screws with toothed lock washer and self-locking nuts. Observe the maximum torque of the screws.

9 Configuration via rotary encoding switch

Addresses are set using two rotary coding switches. Switch x10 is used to set the position in tens (x10) and switch x1 is used to set the position in units (x1). The address can be set between 1 and 126.

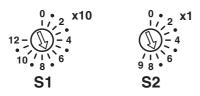


Figure 8 PROFIBUS rotary encoding switch

S1	S2	Code	Function
0	0	00	Reserved
0 12	1 5	01 125	Manual address assignment
12	6	126	Setting the slave address (set slave address com- mand)
12	7	127	Reserved
12	8	128	Reserved
12	9	129	Reserved

A new address value is only applied on device power up.

10 Local status and diagnostic indicators

10.1 Indicators for bus and power supply

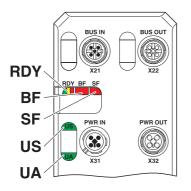


Figure 9 LEDs for bus and power supply

Designation	Color	Meaning	State	Description	
RDY	Green/ yellow/	Ready	Green ON	Device ready to operate	
	red		Yellow flashing	Firmware update is being performed.	
			Flashing	Over- or undervoltage at U _S	
			green/	Temperature of the device is in the critical area.	
			yellow	Failure of the actuator supply U _A	
				Surge voltage/undervoltage of the actuator supply U _A	
				And red US LED: sensor supply overload	
			Red ON	Rotary encoding switches are set to an invalid/reserved position.	
			OFF	Device is not ready for operation.	
BF	Red	Bus Fault	Red ON	No communication on PROFIBUS	
				Device is starting up.	
				No baud rate detected by device.	
			Red flashing	Device has not been configured by the master.	
				Device configuration does not match.	
				Invalid parameter data received from the master.	
				Invalid bus address	
				The device is in the clear or stop state. The outputs are in the safe state.	
			OFF	No error	
SF	Red	Group Red ON error	Red ON	Device-specific diagnostics present, e.g., short circuit at the I/O devices.	
				Hardware is faulty.	
				Device data or parameter data do not match.	
			OFF	No error	
US	Green/ red	/ U _{Sensorik}	U _{Sensorik} Green ON		Communications power/sensor voltage present
			OFF	Communications power/sensor voltage not present or too low.	
			Red ON	Sensor voltage overload	
UA	Green	U _{Aktorik}	ON	Actuator voltage present.	
			OFF	Actuator voltage not present.	

10.2 Input and output indicators

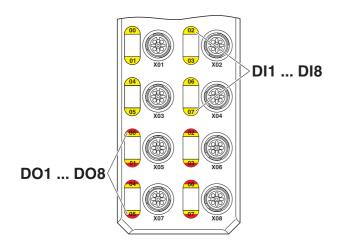


Figure 10 Input and output indicators

Designation	Color	Meaning	State	Description
00 07	Yellow	Status of the inputs	Status of the inputs ON Input is set.	
			OFF	Input is not set.
00 07	Yellow/red	Status of the outputs	Yellow ON	Output is set.
			Red ON	Output is short circuited or overloaded.
			OFF	Output is not set.



The numbering of the LEDs is as follows: the first number specifies the byte, the second number specifies the bit.

11 Process data

11.1 Assignment of the terminal points to the IN process data

The I/O data are mapped as follows:

Input process data									
Byte		Byte 0							
Bit	7	6	5	4	3	2	1	0	
IN	07	06	05	04	03	02	01	00	
Connection	Х	X04		X03 X			Х	01	
Pin	2	4	2	4	2	4	2	4	
DI	8	7	6	5	4	3	2	1	

Key:

Bit: Process data assignment

IN: LED marking

DI: Input of the device

11.2 Assignment of the terminal points to the OUT process data

The I/O data are mapped as follows:

		Output process data							
Byte		Byte 0							
Bit	7	6	5	4	3	2	1	0	
OUT	07	06	05	04	03	02	01	00	
Connection	Х	X08		X07		X06		X05	
Pin	2	4	2	4	2	4	2	4	
DO	8	7	6	5	4	3	2	1	

Key:

Bit: Process data assignment

OUT: LED marking

DO: Output of the device

11.3 Status module

The device has a status module in slot 1.

The status is mapped as follows.

Bit 31 bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Supply of the module electronics and sensors		Supply of the actuators (U_A)		Outputs	
	(U _S)					
Reserved	Undervoltage	Overload	Undervoltage	Short-circuit	Overload	Short-circuit

12 Parameterization

This section provides a detailed description of the format of the parameters for the input and output devices. This may be useful when setting parameters using acyclic services or if there is no user interface for the simple selection of parameters.

Byte	Meaning	
1 7	DP standard	
8 10	DP/V1 standard	
11 12	Module parameter	

Module parameter			
Byte	Meaning	Contents	
11	Behavior of the device	Bit 0 and Bit 1	Substitute value behavior
			00 _{bin} : "0" is output to all output bits
			01 _{bin} : "1" is output to all output bits
			10 _{bin} : hold last value
			11 _{bin} : substitute value
		Other	Reserved
12	Substitute values of individual channels	Bit 0	Substitute value for channel 1 (X05.00)
	18	Bit 1	Substitute value for channel 2 (X05.01)
		Bit 2	Substitute value for channel 3 (X06.02)
		Bit 3	Substitute value for channel 4 (X06.03)
		Bit 4	Substitute value for channel 5 (X07.04)
		Bit 5	Substitute value for channel 6 (X07.05)
		Bit 6	Substitute value for channel 7 (X08.06)
		Bit 7	Substitute value for channel 8 (X08.07)

13 I&M functions

The following Information & Maintenance functions are supported:

I&M 0

I&M data	Access / data type	Presets
MANUFACTURER_ID	Read / 2 bytes	B0 _{hex} (Phoenix Contact GmbH & Co. KG)
ORDER_ID	Read / 20 bytes	-
SERIAL_Number	Read / 16 bytes	-
HARDWARE_Revision	Read / 2 bytes	-
SOFTWARE_Revision	Read / 4 bytes	-
REVISION_Counter	Read / 2 bytes	0000 _{hex} (reserved)
PROFILE_ID	Read / 2 bytes	F600 _{hex} (generic device)
PROFILE_SPECIFIC_TYPE	Read / 2 bytes	0003 _{hex} (IO module)
IM_VERSION	Read / 2 bytes	0102 _{hex} (Version 1.2)
IM_SUPPORTED	Read / 2 bytes	000E _{hex} (I&M 1 3)

I&M 1

I&M data	Access / data type	Presets
TAG_FUNCTION	Read/write / 32 bytes	"20 _{hex} " (empty)
TAG_LOCATION	Read/write / 22 bytes	"20 _{hex} " (empty)

I&M 2

I&M data	Access / data type	Presets
INSTALLATION_DATE	Read/write / 16 bytes	"20 _{hex} " (empty)
RESERVED	Read/write / 38 bytes	0 _{hex}

I&M 3

I&M data	Access / data type	Presets
DESCRIPTOR	Read/write / 54 bytes	"20 _{hex} " (empty)

14 Sync/freeze mode

The device supports sync and freeze mode.

The functions must be activated by the PROFIBUS master in the parameter data.

Input and output data is written or read at defined times with the sync and freeze commands.

If the device receives a sync command from the PROFIBUS master at any given time, the current OUT process data is transferred and frozen until the next sync command.

Similarly, the states of the inputs are transferred on the respective freeze command and are frozen until the next freeze command.

15 Diagnostic alarms

PROFIBUS enables the PROFIBUS device to store diagnostic information together with the error location and error type.

In the default upon delivery the alarms are enabled, however, they can be disabled with parameters on startup.

An incoming alarm informs the PROFIBUS device that diagnostic information has been entered.

When the diagnostic information has been removed, an outgoing alarm is sent to the device.

If at least one piece of diagnostic information is stored, the SF LED is on. If no diagnostic information is present, the SF LED is off.

The following PROFIBUS diagnostic messages are indicated by the PROFIBUS device:

- Overtemperature of the device
- Surge voltage of U_S
- Overload of U_S
- Surge voltage of U_A
- Undervoltage of U_A
- Short circuit of U_A
- Short circuit of an output
- Output overload

16 Monitoring

A process data watchdog is integrated into the device to avoid uncontrolled setting/resetting of outputs in the event of an error.

If device outputs are set, the controlling process must be able to access the device.

In the event of an error, e.g., bus cable interrupted or function error in the controlling process, the device can respond appropriately via the process data watchdog.

When activating the process data watchdog, it is started by the first write process and the next write process is expected within the timeout period. During error-free operation, the write process is performed during the timeout period and the watchdog is restarted (triggered).



Reading calls do not trigger the process data watchdog.

If there is no triggering during the timeout period, an error occurred. Two responses follow:

- All outputs are set to the configured substitute value.
- The BF LED indicates the corresponding state.

17 Substitute value behavior

If PROFIBUS communication fails or if no valid process data is received from the PROFIBUS master, all device outputs are set to the parameterized substitute values.