

CS43L42

Low Voltage, Stereo DAC with Headphone Amp

Features

 \Box 1.8 to 3.3 Volt supply 24-Bit conversion / 96 kHz sample rate \Box 96 dB dynamic range at 3 V supply \Box -85 dB THD+N Low power consumption Digital volume control

- **ï** 96 dB attenuation, 1 dB step size Digital bass and treble boost
	- **•** Selectable corner frequencies

ï Up to 12 dB boost in 1 dB increments □Peak signal limiting to prevent clipping De-emphasis for 32 kHz, 44.1 kHz, and 48 kHz Headphone amplifier

- **■** up to 25 mW_{rms} power output into 16 Ω load*
- **ï** 25 dB analog attenuation and mute
- **ï** Zero crossing click free level transitions

ATAPI mixing functions 24-Pin TSSOP package

* 1 kHz sine wave at 3.3V supply

Description

The CS43L42 is a complete stereo digital-to-analog output system including interpolation, 1-bit D/A conversion, analog filtering, volume control, line level outputs, and a headphone amplifier, in a 24-pin TSSOP package.

The CS43L42 is based on delta-sigma modulation, where the modulator output controls the reference voltage input to an ultra-linear analog low-pass filter. This architecture allows infinite adjustment of the sample rate between 2 kHz and 100 kHz simply by changing the master clock frequency.

The CS43L42 contains on-chip digital bass and treble boost, peak signal limiting, and de-emphasis. The CS43L42 operates from a +1.8 V to +3.3 V supply and consumes only 16 mW of power with a 1.8 V supply with the line amplifier powered-down. These features are ideal for portable CD, MP3 and MD players and other portable playback systems that require extremely low power consumption.

ORDERING INFORMATION
CS43L42-KZ
-10 to 70 °C CS43L42-KZZ, Lead Free -10 to 70 °C CDB43L42 Evaluation Board

24-pin TSSOP
24-pin TSSOP

Preliminary Product Information | This document contains information for a new product. Cirrus Logic reserves the right to modify this product without notice.

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1. CHARACTERISTICS/SPECIFICATIONS

ANALOG CHARACTERISTICS (T_A = 25° C; Logic "1" = VL = 1.8 V; Logic "0" = GND = 0 V;

Full-Scale Output Sine Wave, 997 Hz; MCLK = 12.288 MHz; Measurement Bandwidth 10 Hz to 20 kHz, unless otherwise specified; Fs for Base-rate Mode = 48 kHz, SCLK = 3.072 MHz. Fs for High-Rate Mode = 96 kHz,

SCLK = 6.144 MHz. Test load R_L = 10 kΩ, C_L = 10 pF (see Figure [17](#page-32-2)) for line out, R_L = 16 Ω, C_L = 10 pF (see Figure [18](#page-32-3)) for headphone out).

Notes: 1. One-half LSB of triangular PDF dither is added to data.

ANALOG CHARACTERISTICS (Continued)

ANALOG CHARACTERISTICS (Continued)

Notes: 2. See *[Line Amplifier Gain Compensation \(line\)](#page-23-2)* for details.

- 3. Filter response is not tested but is guaranteed by design.
- 4. Response is clock dependent and will scale with Fs. Note that the response plots (Figures [9](#page-31-0)[-16](#page-32-1)) have been normalized to Fs and can be de-normalized by multiplying the X-axis scale by Fs.
- 5. Referenced to a 1 kHz, full-scale sine wave.
- 6. For Base-Rate Mode, the measurement bandwidth is 0.5465 Fs to 3 Fs. For High-Rate Mode, the measurement bandwidth is 0.577 Fs to 1.4 Fs.
- 7. De-emphasis is not available in High-Rate Mode.

POWER AND THERMAL CHARACTERISTICS (GND = 0 V; All voltages with respect to

ground. All measurements taken with all zeros input and open outputs, unless otherwise specified.)

Notes: 8. Power Down Mode is defined as \overline{RST} = LO with all clocks and data lines held static.

9. Valid with the recommended capacitor values on FILT+, VQ_LINE and VQ_HP as shown in Figure [6](#page-13-1). Increasing the capacitance will also increase the PSRR. Note that care should be taken when selecting capacitor type, as any leakage current in excess of 1.0 µA will cause degradation in analog performance.

DIGITAL CHARACTERISTICS $(T_A = 25^\circ \text{ C}; \text{VL} = 1.7 \text{ V} - 3.6 \text{ V}; \text{GND} = 0 \text{ V})$

ABSOLUTE MAXIMUM RATINGS (GND = 0V; all voltages with respect to ground.)

WARNING: Operation at or beyond these limits may result in permanent damage to the device. Normal operation is not guaranteed at these extremes.

RECOMMENDED OPERATING CONDITIONS (GND = 0V; all voltages with respect to ground.)

Notes: 10. To prevent clipping the outputs, VA_HP_{MIN} is limited by the Full-Scale Output Voltage V_{FS_HP}, where VA_HP must be 200 mV greater than V_{FS_HP}. However, if distortion is not a concern, VA_HP may be as low as 0.9 V at any time.

SWITCHING CHARACTERISTICS (T_A = -10 to 70° C; VL = 1.7 V - 3.6 V; Inputs: Logic 0 = GND,

Logic 1 = VL, C_{L} = 20 pF)

Notes: 11. Internal SCLK Mode timing is not tested, but is guaranteed by design.

12. In Internal SCLK Mode, the LRCK duty cycle must be 50% +/− 1/2 MCLK Period.

Figure 1. External Serial Mode Input Timing Figure 2. Internal Serial Mode Input Timing *The SCLK pulses shown are internal to the CS43L42.

Figure 3. Internal Serial Clock Generation * The SCLK pulses shown are internal to the CS43L42. N equals MCLK divided by SCLK

SWITCHING CHARACTERISTICS - CONTROL PORT - TWO-WIRE MODE

 $(T_A = 25^\circ \text{ C}; \text{ VL} = 1.7 \text{ V} - 3.6 \text{ V}; \text{inputs: Logic 0 = GND}, \text{Logic 1 = VL}, C_L = 30 \text{ pF})$

Notes: 13. The Two-Wire Mode is compatible with the I²C protocol.

14. Data must be held for sufficient time to bridge the transition time, t_{fc} , of SCL.

Figure 4. Control Port Timing - Two-Wire Mode

SWITCHING CHARACTERISTICS - CONTROL PORT - SPI MODE

 $(T_A = 25^{\circ} \text{ C}; \text{ VL} = 1.7 \text{ V} - 3.6 \text{ V}; \text{ Inputs: Logic 0 = GND}, \text{ Logic 1 = VL}, C_L = 30 \text{ pF})$

Notes: 15. t_{spi} only needed before first falling edge of \overline{CS} after \overline{RST} rising edge. $t_{spi} = 0$ at all other times.

- 16. Data must be held for sufficient time to bridge the transition time of CCLK.
- 17. For F_{SCK} < 1 MHz

Figure 5. Control Port Timing - SPI Mode

2. TYPICAL CONNECTION DIAGRAM

Figure 6. Typical Connection Diagram

3. REGISTER QUICK REFERENCE

4. REGISTER DESCRIPTION

Note: All registers are read/write in Two-Wire mode and write only in SPI, unless otherwise noted.

4.1 Power and Muting Control (address 01h)

4.1.1 AUTO-MUTE (AMUTE)

Default = 1

- 0 Disabled
- 1 Enabled

Function:

The Digital-to-Analog converter output will mute following the reception of 8192 consecutive audio samples of static 0 or -1. A single sample of non-static data will release the mute. Detection and muting is done independently for each channel. The quiescent voltage on the output will be retained and the Mute Control pin will go active during the mute period. The muting function is affected, similar to volume control changes, by the Soft and Zero Cross bits in the Power and Muting Control register.

4.1.2 SOFT RAMP AND ZERO CROSS CONTROL (SZC)

Default = 10

- 00 Immediate Change
- 01 Zero Cross Digital and Analog
- 10 Ramped Digital and Analog
- 11 Reserved

Function:

Immediate Change

When Immediate Change is selected all level changes will take effect immediately in one step.

Zero Cross Digital and Analog

Zero Cross Enable dictates that signal level changes, either by attenuation changes or muting, will occur on a signal zero crossing to minimize audible artifacts. The requested level change will occur after a timeout period of 512 sample periods (10.7 ms at 48 kHz sample rate) if the signal does not encounter a zero crossing. The zero cross function is independently monitored and implemented for each channel.

Ramped Digital and Analog

Soft Ramp allows digital level changes, both muting and attenuation, to be implemented by incrementally ramping, in 1/8 dB steps, from the current level to the new level at a rate of 1 dB per 8 left/right clock periods. Analog level changes will occur in 1 dB steps on a signal zero crossing. The analog level change will occur after a timeout period of 512 sample periods (10.7 ms at 48 kHz sample rate) if the signal does not encounter a zero crossing. The zero cross function is independently monitored and implemented for each channel.

Note: Ramped Digital and Analog is not available in High-Rate Mode.

4.1.3 POPGUARD® TRANSIENT CONTROL (POR)

- *Default 1*
- 0 Disabled
- 1 Enabled

Function:

The PopGuard[®] Transient Control allows the quiescent voltage to slowly ramp to and from 0 volts to the quiescent voltage during power-on or power-off when this function is enabled. Please see section [6.5](#page-28-5) for implementation details.

4.1.4 POWER DOWN HEADPHONE AMPLIFIER (PDNHP)

- *Default = 0*
- 0 Disabled
- 1 Enabled

Function:

The headphone amplifier will independently enter a low-power state when this function is enabled.

4.1.5 POWER DOWN LINE AMPLIFIER (PDNLN)

Default = 0 0 - Disabled 1 - Enabled

Function:

The line output amplifier will independently enter a low-power state when this function is enabled.

4.1.6 POWER DOWN (PDN)

- *Default = 1*
- 0 Disabled
- 1 Enabled

Function:

The entire device will enter a low-power state when this function is enabled, and the contents of the control registers are retained in this mode. The power-down bit defaults to 'enabled' on power-up and must be disabled before normal operation will begin.

4.2 Channel A Analog Headphone Attenuation Control (address 02h) (HVOLA)

4.3 Channel B Analog Headphone Attenuation Control (address 03h) (hVOLB)

Default = 0 dB (No attenuation)

Function:

The Analog Headphone Attenuation Control operates independently from the Digital Volume Control. The Analog Headphone Attenuation Control registers allow attenuation of the headphone output signal for each channel in 1 dB increments from 0 to -25 dB. Attenuation settings are decoded using a 2's complement code, as shown in Table [1.](#page-17-4) The volume changes are implemented as dictated by the Soft and Zero Cross bits in the Power and Muting Control register. All volume settings greater than zero are interpreted as zero.

Note: The Analog Headphone Attenuation only affects the headphone outputs.

Table 1. Example Analog Volume Settings

4.4 Channel A Digital Volume Control (address 04h) (DVOLA)

4.5 Channel B Digital Volume Control (address 05h) (DVOLB)

Default = 0 dB (No attenuation)

Function:

The Digital Volume Control registers allow independent control of the signal levels in 1 dB increments from +18 to -96 dB. Volume settings are decoded using a 2ís complement code, as shown in Table [2](#page-18-3). The volume changes are implemented as dictated by the Soft and Zero Cross bits in the Power and Muting Control register. All volume settings less than -96 dB are equivalent to muting the channel via the ATAPI bits (see Section [4.10.4](#page-22-1)).

Note: The digital volume control affects both the line outputs and the headphone outputs. Setting this register to values greater than +18 dB will cause distortion in the audio outputs.

Table 2. Example Digital Volume Settings

4.6 Tone Control (address 06h)

4.6.1 BASS BOOST LEVEL (BB)

Default = 0 dB (No Bass Boost)

Function:

The level of the shelving bass boost filter is set by Bass Boost Level. The level can be adjusted in 1 dB increments from 0 to +12 dB of boost. Boost levels are decoded as shown in Table [3](#page-18-4). Levels above +12 dB are interpreted as +12 dB.

Table 3. Example Bass Boost Settings

4.6.2 TREBLE BOOST LEVEL (TB)

Default = 0 dB (No Treble Boost)

Function:

The level of the shelving treble boost filter is set by Treble Boost Level. The level can be adjusted in 1 dB increments from 0 to +12 dB of boost. Boost levels are decoded as shown in Table [4](#page-18-5). Levels above +12 dB are interpreted as +12 dB.

Note: Treble Boost is not available in High-Rate Mode.

Binary Code	Decimal Value	Boost Setting
0000		0 _d B
0010		$+2$ dB
1010		$+6$ dB
1001		$+9dB$
1100		$+12$ dB

Table 4. Example Treble Boost Settings

4.7 Mode Control (address 07h)

4.7.1 BASS BOOST CORNER FREQUENCY (BBCF)

Default = 00 00 - 50 Hz 01 - 100 Hz

10 - 200 Hz

11 - Reserved

Function:

The bass boost corner frequency is user selectable as shown above.

4.7.2 TREBLE BOOST CORNER FREQUENCY (TBCF)

Default = 00 00 - 2 kHz 01 - 4 kHz 10 - 7 kHz 11 - Reserved

Function:

The treble boost corner frequency is user selectable as shown above.

Note: Treble Boost is not available in High-Rate Mode.

4.7.3 CHANNEL A VOLUME = CHANNEL B VOLUME (A=B)

- *Default = 0* 0 - Disabled
- 1 Enabled

Function:

The AOUTA/HP_A and AOUTB/HP_B volume levels are independently controlled by the A and the B Channel Volume Control Bytes when this function is disabled. The volume on both AOUTA/HP_A and AOUTB/HP_B are determined by the A Channel Attenuation and Volume Control Bytes, and the B Channel Bytes are ignored when this function is enabled.

4.7.4 DE-EMPHASIS CONTROL (DEM)

Default = 00 00 - Disabled 01 - 44.1 kHz 10 - 48 kHz 11 - 32 kHz

Function:

Selects the appropriate digital filter to maintain the standard 15 $\mu s/50 \mu s$ digital de-emphasis filter response at 32, 44.1 or 48 kHz sample rates. (see Figure [30](#page-37-0))

Note: De-emphasis is not available in High-Rate Mode.

4.7.5 DIGITAL VOLUME CONTROL BYPASS (VCBYP)

Default = 0 0 - Disabled

1 - Enabled

Function:

The digital volume control section is bypassed when this function is enabled. This disables the digital volume control, muting, bass boost, treble boost, limiting and ATAPI functions. The analog headphone attenuation control will remain functional.

4.8 Limiter Attack Rate (address 08h) (ARATE)

Default = 10h - 2 LRCKís per 1/8 dB

Function:

The limiter attack rate is user selectable. The rate is a function of sampling frequency, Fs, and the value in the Limiter Attack Rate register. Rates are calculated using the function RATE = 32/{value}, where {value} is the decimal value in the Limiter Attack Rate register and RATE is in LRCKís per 1/8 dB of change.

Note: A value of zero in this register is not recommended, as it will induce erratic behavior of the limiter. Use the LIM_EN bit to disable the limiter function (see *[Peak Signal Limiter Enable \(LIM_EN\)](#page-22-0)*).

Table 5. Example Limiter Attack Rate Settings

4.9 Limiter Release Rate (address 09h) (RRATE)

Default = 20h - 16 LRCKís per 1/8 dB

Function:

The limiter release rate is user selectable. The rate is a function of sampling frequency, Fs, and the value in the Limiter Release Rate register. Rates are calculated using the function RATE = 512/{value}, where {value} is the decimal value in the Limiter Release Rate register and RATE is in LRCKís per 1/8 dB of change.

Note: A value of zero in this register is not recommended, as it will induce erratic behavior of the limiter. Use the LIM_EN bit to disable the limiter function (see *[Peak Signal Limiter Enable \(LIM_EN\)](#page-22-0)*).

Table 6. Example Limiter Release Rate Settings

4.10 Volume and Mixing Control (address 0Ah)

4.10.1 TONE CONTROL MODE (TC)

Default = 00

00 - All settings are taken from user registers

01 - 12 dB of Bass Boost at 100 Hz and 6 dB of Treble Boost at 7 kHz

10 - 8 dB of Bass Boost at 100 Hz and 4 dB of Treble Boost at 7 kHz

11 - 4 dB of Bass Boost at 100 Hz and 2 dB of Treble Boost at 7 kHz

Function:

The Tone Control Mode bits determine how the Bass Boost and Treble Boost features are configured. The user defined settings from the Bass and Treble Boost Level and Corner Frequency registers are used when these bits are set to '00'. Alternately, one of three pre-defined settings may be used.

4.10.2 TONE CONTROL ENABLE (TC_EN)

Default = 0

- 0 Disabled
- 1 Enabled

Function:

The Bass Boost and Treble Boost features are active when this function is enabled.

4.10.3 PEAK SIGNAL LIMITER ENABLE (LIM_EN)

- *Default = 0*
- 0 Disabled
- 1 Enabled

Function:

The CS43L42 will limit the maximum signal amplitude to prevent clipping when this function is enabled. Peak Signal Limiting is performed by first decreasing the Bass and Treble Boost Levels. If the signal is still clipping, the digital attenuation is increased. The attack rate is determined by the Limiter Attack Rate register.

Once the signal has dropped below the clipping level, the attenuation is decreased back to the user selected level followed by the Bass Boost being increased back to the user selected level. The release rate is determined by the Limiter Release Rate register.

Note: The A=B bit should be set to '1' for optimal limiter performance.

4.10.4 ATAPI CHANNEL MIXING AND MUTING (ATAPI)

Default = 1001 - AOUTA/HP_A = L, AOUTB/HP_B = R (Stereo)

Function:

The CS43L42 implements the channel mixing functions of the ATAPI CD-ROM specification. Refer to Table [7](#page-22-2) and Figure [31](#page-37-1) for additional information.

Note: All mixing functions occur prior to the digital volume control.

Table 7. ATAPI Decode

4.11 Mode Control 2 (address 0Bh)

4.11.1 MASTER CLOCK DIVIDE ENABLE (MCLKDIV)

Default = 0

0 - Disabled

1 - Enabled

Function:

The MCLKDIV bit enables a circuit which divides the externally applied MCLK signal by 2 prior to all other internal circuitry.

Note: Internal SCLK is not available when this function is enabled.

4.11.2 LINE AMPLIFIER GAIN COMPENSATION (LINE)

Default = 00 00 - 0.785 x VA 01 - 0.943 x VA 10 - 1.571 x VA 11 - Line Mute

Function:

The Line Amplifier Gain Compensation bits allow the user to scale the full-scale line output level according to the power supply voltage used. The full-scale line output level will be equal to {gain factor}xVA, where {gain factor} is selected from options above. For example, if the user wants the full-scale line output voltage to be 1 V_{RMS} (2.8 V_{PP}) with VA = 1.8 VDC and VA_LINE = 3.0 VDC, then the gain factor would be 1.571.

Note: It is possible to exceed the maximum output level, limited by VA_LINE, by incorrectly setting the gain compensation factor.

The Line Mute option is available to allow muting of the line output when the headphone output is still in use and the line amp is still powered up. To use this feature, first mute the outputs via the ATAPI bits. Next, set the LINE GAIN to Line Mute. Finally, un-mute the outputs with the ATAPI bits. Following these steps will ensure a click free mute.

4.11.3 DIGITAL INTERFACE FORMAT (DIF)

Default = 000 - Format 0 (I2S, up to 24-bit data, 64 x Fs Internal SLCK)

Function:

The required relationship between the Left/Right clock, serial clock and serial data is defined by the Digital Interface Format and the options are detailed in Figures [19-](#page-33-0)[25](#page-35-0).

Note: Internal SCLK is not available when MCLKDIV is enabled.

Table 8. Digital Interface Format

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5. PIN DESCRIPTION

MCLK 7 **Master Clock** (*Input*) - Frequency must be either 256x, 384x, 512x, 768x or 1024x the input sample rate in Base Rate Mode (BRM) and 128x, 192x, 256x or 384x the input sample rate in High Rate Mode (HRM). Note that some multiplication factors require setting the MCLKDIV bit (see *[Master Clock DIVIDE ENABLE \(mclkdiv\)](#page-23-1)*). Tables [10](#page-26-1) and [11](#page-26-2) illustrate several standard audio sample rates and the required master clock frequencies.

* Requires MCLKDIV bit = 1 in Mode Control 2 register (address 0Bh).

Table 10. HRM Common Clock Frequencies

* Requires MCLKDIV bit = 1 in Mode Control 2 register (address 0Bh).

Table 11. BRM Common Clock Frequencies

6. APPLICATIONS

6.1 Grounding and Power Supply Decoupling

As with any high resolution converter, the CS43L42 requires careful attention to power supply and grounding arrangements to optimize performance. Figure [6](#page-13-1) shows the recommended power arrangement with VA, VA_HP, VA_LINE and VL connected to clean supplies. Decoupling capacitors should be located as close to the device package as possible. If desired, all supply pins may be connected to the same supply, but a decoupling capacitor should still be used on each supply pin.

6.2 Clock Modes

The CS43L42 operates in one of two clocking modes. Base Rate Mode supports input sample rates up to 50 kHz, and High Rate Mode supports input sample rates up to 100 kHz, see Table [10](#page-26-1) and [11.](#page-26-2) All clock modes use 64x oversampling.

6.3 De-Emphasis

The CS43L42 includes on-chip digital de-emphasis. Figure [30](#page-37-0) shows the de-emphasis curve for Fs equal to 44.1 kHz. The frequency response of the de-emphasis curve will scale proportionally with changes in sample rate, Fs.

The de-emphasis feature is included to accommodate older audio recordings that utilize pre-emphasis equalization as a means of noise reduction.

6.4 Recommended Power-up Sequence

- 1) Hold \overline{RST} low until the power supply, master clock and left/right clock are stable. In this state, the control port is reset to its default settings and VQ_HP and VQ_LINE will remain low. Set the CP/SA pin at this time.
- 2) Bring RST high. The device will remain in a low power state and latch CP/SA , and VQ HP and VQ LINE remain low. If CP/SA is high, the control port will be accessible at this time

and the desired register settings can be loaded while keeping the PDN bit set to 1. If CP/SA is low, the device will begin the stand-alone power-up sequence

3) (For Control Port Mode) Once the registers are configured as desired, set the PDN bit to 0, initiating the power-up sequence. This requires approximately 50 µS when the PopGuard*^Æ* Transient Control (POR) bit is set to 0. If the POR bit is set to 1, see *PopGuard® Transient [Control](#page-28-5)* for total power-up timing.

6.5 PopGuard*^Æ* **Transient Control**

The CS43L42 uses PopGuard[®] technology to minimize the effects of output transients during power-up and power-down. This technique minimizes the audio transients commonly produced by single-ended, single-supply converters when it is implemented with external DC-blocking capacitors connected in series with the audio outputs.

When the device is initially powered-up, the audio outputs, AOUTA, AOUTB, HP_A and HP_B are clamped to GND. Following a delay of approximately 1000 sample periods, each output begins to ramp toward the quiescent voltage. Approximately 10,000 left/right clock cycles later, the outputs reach V_{Q} LINE and V_{Q} HP respectively, and audio output begins. This gradual voltage ramping allows time for the external DC-blocking capacitor to charge to the quiescent voltage, minimizing the power-up transient.

To prevent transients at power-down, the device must first enter its power-down state. When this occurs, audio output ceases and the internal output buffers are disconnected from AOUTA, AOUTB, HP_A and HP_B. In their place, a soft-start current sink is substituted which allows the DC-blocking capacitors to slowly discharge. Once this charge is dissipated, the power to the device may be turned off, and the system is ready for the next power-on.

To prevent an audio transient at the next power-on, the DC-blocking capacitors must fully discharge before turning off the power or exiting the power-down state. If full discharge does not occur, a transient will occur when the audio outputs are initially clamped to GND. The time that the device must remain in the power-down state is related to the value of the DC-blocking capacitance and the output load. For example, with a 220 µF capacitor and a 16 ohm load on the headphone outputs, the minimum power-down time will be approximately 0.4 seconds.

Use of the Mute Control function on the line outputs is recommended for designs requiring the absolute minimum in extraneous clicks and pops. Also, use of the Mute Control function can enable the system designer to achieve idle channel noise/signal-to-noise ratios only limited by the external mute circuit. See the CDB43L42 Datasheet for a suggested mute circuit.

7. CONTROL PORT INTERFACE

The control port is used to load all the internal settings. The operation of the control port may be completely asynchronous with the audio sample rate. However, to avoid potential interference problems, the control port pins should remain static if no operation is required.

The control port has 2 modes: SPI and Two-Wire, with the CS43L42 operating as a slave device. If Two-Wire operation is desired, $AD0/\overline{CS}$ should be tied to VL or GND. If the CS43L42 ever detects a high to low transition on $AD0/\overline{CS}$ after power-up, SPI mode will be selected.

7.1 SPI Mode

In SPI mode, \overline{CS} is the CS43L42 chip select signal, CCLK is the control port bit clock, CDIN is the input data line from the microcontroller and the chip address is 0010000. All signals are inputs and data is clocked in on the rising edge of CCLK. Figure [7](#page-30-0) shows the operation of the control port in SPI

mode. To write to a register, bring \overline{CS} low. The first 7 bits on CDIN form the chip address and must be 0010000. The eighth bit is a read/write indicator (R/\overline{W}) , which must be low to write. The next 8 bits form the Memory Address Pointer (MAP), which is set to the address of the register that is to be updated. The next 8 bits are the data which will be placed into register designated by the MAP.

The CS43L42 has a MAP auto increment capability, enabled by the INCR bit in the MAP register. If INCR is a zero, then the MAP will stay constant for successive writes. If INCR is set to a 1, then MAP will auto increment after each byte is written, allowing block writes of successive registers.

7.2 Two-Wire Mode

In Two-Wire mode, SDA is a bidirectional data line. Data is clocked into and out of the part by the clock, SCL, with the clock to data relationship as shown in Figure [8](#page-30-1). There is no \overline{CS} pin. Pin AD0 forms the partial chip address and should be tied to VL or GND as required. The upper 6 bits of the 7 bit address field must be 001000. To communicate with the CS43L42, the LSB of the chip address field, which is the first byte sent to the CS43L42, should match the setting of the AD0 pin. The eighth bit of the address byte is the R/\overline{W} bit (high for a read, low for a write). If the operation is a write, the next byte is the Memory Address Pointer, MAP, which selects the register to be read or written. The MAP is then followed by the data to be written. If the operation is a read, the contents of the register pointed to by the MAP will be output after the chip address.

The CS43L42 has MAP auto increment capability, enabled by the INCR bit in the MAP register. If INCR is 0, then the MAP will stay constant for successive writes. If INCR is set to 1, then MAP will auto increment after each byte is written, allowing block reads or writes of successive registers.

The Two-Wire mode is compatible with the $I²C$ protocol.

7.3 Memory Address Pointer (MAP)

7.3.1 INCR (AUTO MAP INCREMENT ENABLE)

Default = $0'$

0 - Disabled

1 - Enabled

7.3.2 MAP0-3 (MEMORY ADDRESS POINTER)

Default = ' 0000 '

MAP = Memory Address Pointer

Note: If operation is a write, this byte contains the Memory Address Pointer, MAP.

Figure 8. Control Port Timing, Two-Wire Mode

Figure 9. Base-Rate Stopband Rejection Figure 10. Base-Rate Transition Band

Figure 11. Base-Rate Transition Band (Detail) Figure 12. Base-Rate Passband Ripple

Figure 13. High-Rate Stopband Rejection Figure 14. High-Rate Transition Band

Figure 17. Line Output Test Load

Figure 18. Headphone Output Test Load

Figure 19. CS43L42 Control Port Mode - Serial Audio Format 0

Figure 20. CS43L42 Control Port Mode - Serial Audio Format 1

Figure 21. CS43L42 Control Port Mode - Serial Audio Format 2

Figure 22. CS43L42 Control Port Mode - Serial Audio Format 3

Figure 24. CS43L42 Control Port Mode - Serial Audio Format 5

Figure 25. CS43L42 Control Port Mode - Serial Audio Format 6

Figure 26. CS43L42 Stand Alone Mode - Serial Audio Format 0

Figure 27. CS43L42 Stand Alone Mode - Serial Audio Format 1

Figure 28. CS43L42 Stand Alone Mode - Serial Audio Format 2

Figure 29. CS43L42 Stand Alone Mode - Serial Audio Format 3

Figure 31. ATAPI Block Diagram

8. PARAMETER DEFINITIONS

Total Harmonic Distortion + Noise (THD+N)

The ratio of the rms value of the signal to the rms sum of all other spectral components over the specified bandwidth (typically 10 Hz to 20 kHz), including distortion components. Expressed in decibels.

Dynamic Range

The ratio of the full scale rms value of the signal to the rms sum of all other spectral components over the specified bandwidth. Dynamic range is a signal-to-noise measurement over the specified bandwidth made with a -60 dBFS signal. 60 dB is then added to the resulting measurement to refer the measurement to full scale. This technique ensures that the distortion components are below the noise level and do not effect the measurement. This measurement technique has been accepted by the Audio Engineering Society, AES17-1991, and the Electronic Industries Association of Japan, EIAJ CP-307.

Interchannel Isolation

A measure of crosstalk between the left and right channels. Measured for each channel at the converter's output with all zeros to the input under test and a full-scale signal applied to the other channel. Units in decibels.

Interchannel Gain Mismatch

The gain difference between left and right channels. Units in decibels.

Gain Error

The deviation from the nominal full scale analog output for a full scale digital input.

Gain Drift

The change in gain value with temperature. Units in ppm/°C.

9. REFERENCES

- 1) "How to Achieve Optimum Performance from Delta-Sigma A/D & D/A Converters" by Steven Harris. Paper presented at the 93rd Convention of the Audio Engineering Society, October 1992.
- 2) CDB43L42 Evaluation Board Datasheet
- 3) "The I²C-Bus Specification: Version 2.0" Philips Semiconductors, December 1998. http://www.semiconductors.philips.com

10. PACKAGE DIMENSIONS

JEDEC #: MO-153

Controlling Dimension is Millimeters.

- Notes: 1. "D" and "E1" are reference datums and do not included mold flash or protrusions, but do include mold mismatch and are measured at the parting line, mold flash or protrusions shall not exceed 0.20 mm per side.
	- 2. Dimension "b" does not include dambar protrusion/intrusion. Allowable dambar protrusion shall be 0.13 mm total in excess of "b" dimension at maximum material condition. Dambar intrusion shall not reduce dimension "b" by more than 0.07 mm at least material condition.
	- 3. These dimensions apply to the flat section of the lead between 0.10 and 0.25 mm from lead tips.