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## Grove - Slide Potentiometer



The Grove - Slide Potentiometer module incorporates a linear variable resistor with a maximum resistance of  $10K\Omega$ . When you move the slider from one side to the other, its output voltage will range from 0 V to the Vcc you apply. It connects to the other Grove modules through a standard 4-Pin **Grove Cable**. Three of the pins are connected to OUT (Pin 1), Vcc (Pin 3) and GND (Pin 4), while the fourth pin (Pin 2) is connected to a on-board green indicator LED. The LED is used to visually represent the resistance change on the potentiometer.

### **Features**

- 30 mm long slide length
- Linear resistance taper
- Grove compatible

### Tip

More details about Grove modules please refer to Grove System

### **Application Ideas**

Here are some projects for your reference.



### Specifications

| Item                       | Min            | Typical | Max  |
|----------------------------|----------------|---------|------|
| Voltage (DC)               | 3.3V           | 5.0V    | 30V  |
| Current                    | -              | -       | 30mA |
| Dimension                  | 24mm x60mm     |         |      |
| Net Weight                 | 8.6g           |         |      |
| Rotational life            | >15,000 cycles |         |      |
| Total resistance           | 10ΚΩ           |         |      |
| Stroke length              | 30mm           |         |      |
| Total resistance tolerance | +/- 20%        |         |      |

### **Platforms Supported**

| Arduino             | Raspberry Pi | BeagleBone | Wio | LinkIt ONE |
|---------------------|--------------|------------|-----|------------|
| $\bigcirc \bigcirc$ | B            |            |     |            |

### Caution

The platforms mentioned above as supported is/are an indication of the module's software or theoritical compatibility. We only provide software library or code examples for Arduino platform in most cases. It is not possible to provide software library / demo code for all possible MCU platforms. Hence, users have to write their own software library.

### **Getting Started**

### As an Adjustable Resistor

As shown below, the Grove - Slide Potentiometer can be used as a simple slide potentiometer in any MCU controlled or stand-alone project.



### Standalone

Follow these steps to build a sample Grove circuit using this module but without using any microcontroller board:

1. Connect the slide potentiometer module to the input side of your circuit (to the left of the power module). On the output side of the circuit, you may use a range of User Interface modules (Grove - Red LED, Grove - LED String Light, Grove - Mini Fan, Grove - Buzzer, Grove - Recorder etc.)

- 2. Power up the circuit when complete.
- 3. The slide potentiometer module can now be used to trigger an output. For example:
  - When used in conjunction with a Grove Red LED output module, observe that the brightness of the LED increases as you move the slider from GND to Vcc. At Vcc, the resistance of the potentiometer is minimum and the LED burns the brightest. The same behavior can be seen when the slide potentiometer is used with the Grove - LED String Light module - the more voltage you apply by taking the slider towards the Vcc mark, the brighter the LED lights would become.
  - Similarly, you can use the slide potentiometer to vary the speed of your Grove Mini Fan or the frequency with which your Grove Buzzer module sounds
  - The slide potentiometer can also be used as an ON/OFF switch for any circuit. Take the slider to the Vcc position to switch it ON and move it down to GND to switch OFF a circuit.

In terms of choosing a power module, you can use either the Grove - USB Power module or the Grove - DC Jack Power module for building standalone Grove circuits.

### With Arduino

### As a Voltage Divider

Follow these simple steps to make the slide potentiometer module function as a voltage divider:

1. When using the module in conjunction with an Arduino or a Seeeduino, use the Grove - Base Shield and connect the Grove - Slide Potentiometer module to the shield using a designated Grove Interface (e.g. Analog Port 0 as shown below).



- 2.Connect the board to PC using USB cable.
- 3.Upload the following sample sketch.

```
lint adcPin = A0; // select the input pin for the potentiometer
2int ledPin = A1; // select the pin for the LED
3int adcIn = 0; // variable to store the value coming from the sensor
4void setup()
5 {
     Serial.begin(9600); // init serial to 9600b/s
6
     pinMode(ledPin, OUTPUT); // set ledPin to OUTPUT
7
     Serial.println("Sliding Potentiometer Test Code!!");
8
9}
10void loop()
11{
     // read the value from the sensor:
12
13 adcIn = analogRead(adcPin);
14 if(adcIn >= 500) digitalWrite(ledPin,HIGH); // if adc in > 500,
15led light
    else digitalWrite(ledPin, LOW);
16
17
     Serial.println(adcIn);
18
    delay(100);
}
```

4. Open the serial monitor. You should see some data from ADC.

| 99 CO <b>E</b> 17                 |           |
|-----------------------------------|-----------|
|                                   | Send      |
| Sliding Potentiometer Test Code!! | ~         |
| 244                               |           |
| 244                               |           |
| 244                               |           |
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| 🛛 Autoscroll Carriage return 💌 🧕  | 00 baud 💌 |

5. Move the lever back and forth. The serial data will change correspondingly. When the output resistance exceeds a certain preset value, the on-board indicator LED will also light up.

### As an HID Device

Slide Potentiometer can be an effective Human Interface Device (HID) and can be used, for example, in the radio controller of a Radio Controlled toy car. The picture below shows two Slide Potentiometers on the control panel - one to control the speed of the left wheel, and the other to control the speed of the right wheel of the toy car respectively. Now you can change the speeds of both motors and see the behavior. You will see that if you make the right wheel spin faster than the left wheel, the car will turn rightwards, and if you make the left wheel spin faster than the right wheel, the car will turn leftwards.



### Play With Raspberry Pi (With Grove Base Hat for Raspberry Pi)

### Hardware

• Step 1. Things used in this project:

| Raspberry pi | Grove Base Hat for RasPi | Grove - Slide Potentiometer  |
|--------------|--------------------------|--|
|              |                          | Contraction of the second seco |

- Step 2. Plug the Grove Base Hat into Raspberry.
- **Step 3**. Connect the Slide Potentiometer to A0 port of the Base Hat.
- **Step 4**. Connect the Raspberry Pi to PC through USB cable.



#### Note

For step 3 you are able to connect the slide potentiometer to **any Analog Port** but make sure you change the command with the corresponding port number.

#### Software

• Step 1. Follow Setting Software to configure the development environment.

```
• Step 2. Download the source file by cloning the grove.py library.
1cd ~
2git clone https://github.com/Seeed-Studio/grove.py
```

• Step 3. Excute below commands to run the code. 1cd grove.py/grove 2python grove\_slide\_potentiometer.py 0

Following is the grove\_slide\_potentiometer.py code.

```
limport math
limport sys
limport time
from grove.adc import ADC
f
limport ADC
limport
```

```
@property
12
13
      def value(self):
          return self.adc.read(self.channel)
14
15
16
17Grove = GroveSlidePotentiometer
18
19
20def main():
21
     if len(sys.argv) < 2:</pre>
22
          print('Usage: {} adc_channel'.format(sys.argv[0]))
23
          sys.exit(1)
24
25
      sensor = GroveSlidePotentiometer(int(sys.argv[1]))
26
27
     while True:
28
          print('Slide potentiometer value: {}'.format(sensor.value))
29
          time.sleep(.2)
30
31
32if _____ == '____main___':
33
    main()
```

### Success

```
If everything goes well, you will be able to see the following result
1pi@raspberrypi:~/grove.py/grove $ python grove_slide_potentiometer.py 0
 2Slide potentiometer value: 987
 3Slide potentiometer value: 988
 4Slide potentiometer value: 986
 5Slide potentiometer value: 8
 6Slide potentiometer value: 2
 7Slide potentiometer value: 0
 8Slide potentiometer value: 1
9Slide potentiometer value: 0
10Slide potentiometer value: 24
11Slide potentiometer value: 0
12Slide potentiometer value: 0
13Slide potentiometer value: 11
14Slide potentiometer value: 995
15Slide potentiometer value: 999
16Slide potentiometer value: 999
17<sup>CTraceback</sup> (most recent call last):
18 File "grove_slide_potentiometer.py", line 66, in <module>
19
     main()
20 File "grove_slide_potentiometer.py", line 62, in main
21
     time.sleep(.2)
22KeyboardInterrupt
```

You can quit this program by simply press Ctrl + C.

### Notice

You may have noticed that for the analog port, the silkscreen pin number is something like **A0**, **A1**, however in the command we use parameter **0** and **1**, just the same as digital port. So please make sure you plug the module into the correct port, otherwise there may be pin conflicts.

### Play With Raspberry Pi (with GrovePi\_Plus)

1. You should have got a raspberry pi and a grovepi or grovepi+.

2.You should have completed configuring the development enviroment, otherwise follow here.

#### 3.Connection

1

• Plug the sensor to grovepi socket A0 by using a grove cable.

cd yourpath/GrovePi/Software/Python/

4.Navigate to the demos' directory:

```
To see the code
1
   nano grove_slide_potentiometer.py # "Ctrl+x" to exit #
1import time
 2import grovepi
 3
 4# Connect the Grove Slide Potentiometer to analog port A0
 5# OUT, LED, VCC, GND
 6slide = 0 # pin 1 (yellow wire)
 7
 8# The device has an onboard LED accessible as pin 2 on port A0
 9# OUT, LED, VCC, GND
10led = 1  # pin 2 (white wire)
11
12grovepi.pinMode(slide, "INPUT")
13grovepi.pinMode(led, "OUTPUT")
14time.sleep(1)
15
16while True:
17 try:
18
        # Read sensor value from potentiometer
19
         sensor_value = grovepi.analogRead(slide)
20
21
         # Illuminate onboard LED
22
         if sensor_value > 500:
```

```
23 grovepi.digitalWrite(led,1)
24 else:
25 grovepi.digitalWrite(led,0)
26
27 print "sensor_value =", sensor_value
28
29 except IOError:
30 print "Error"
```

### 5.Run the demo.

1sudo python grove\_slide\_potentiometer.py

### **Resources**

- Sliding Potentiometer Eagle File https://raw.githubusercontent.com/SeeedDocument/Grove-Slide\_Potentiometer/master/res/Sliding\_Potentiometer.rar
- Sliding Potentiometer in PDF

https://raw.githubusercontent.com/SeeedDocument/Grove-Slide\_Potentiometer/master/res/Sliding\_protentiometer\_sch.pdf

Sliding Potentiometer datasheet

https://raw.githubusercontent.com/SeeedDocument/Grove-Slide\_Potentiometer/master/res/Sliding\_potentiometer\_datasheet.pdf

### **Projects**

Raspberry pi music server: A first step to Raspberry Pi project

### **Tech Support**

Please submit any technical issue into our forum.