## **ACPL-P456 and ACPL-W456**

High CMR Intelligent Power Module and Gate Drive Interface Optocoupler



### **Data Sheet**

### **Description**

The ACPL-P456 and ACPL-W456 contain a GaAsP LED optically coupled to an integrated high-gain photo detector. Minimized propagation delay difference between devices make these optocouplers excellent solutions for improving inverter efficiency through reduced switching dead time. Specifications and performance plots are given for typical IPM applications.

### **Functional Diagram**



Note: A 0.1 μF bypass capacitor must be connected between pins 4 and 6.

### **Truth Table (Positive Logic)**



### **Applications**

- IPM Isolation
- Isolated IGBT/MOSFET Gate Drive
- AC and Brushless DC Motor Drives
- Industrial Inverters

### **Features**

- **Performance Specified for Common IPM Applications Over** Industrial Temperature Range
- Short Maximum Propagation Delays
- Minimized Pulse Width Distortion (PWD)
- Very High Common Mode Rejection (CMR)
- High CTR
- Available in Stretched SO-6 Package with 8 mm creepage and clearance
- Safety Approval:
	- **—** UL Recognized with 3750V<sub>RMS</sub> for 1 minute (5000V<sub>RMS</sub> for 1 minute for all ACPL-W456 devices and Option 020 device for ACPL-P456) per UL1577
	- **—** CSA Approved
	- $-$  IEC/EN/DIN EN 60747-5-5 approved with V<sub>IORM</sub> = 1140 $V<sub>peak</sub>$  (ACPL-W456) and  $V<sub>IORM</sub> = 891V<sub>peak</sub>$ (ACPL-P456) for Option 060

### **Specifications**

- Wide Operating Temperature Range: –40°C to 100°C
- Maximum Propagation Delay  $t_{PHL}$  = 400 ns,  $t_{PLH}$  = 490 ns
- Maximum Pulse Width Distortion (PWD) = 450 ns
- 15 kV/ $\mu$ s Minimum Common Mode Rejection (CMR) at V<sub>CM</sub>  $= 1500V$
- $\blacksquare$  CTR > 44% at  $I_F = 10 \text{ mA}$
- **CAUTION** It is advised that normal static precautions be taken in handling and assembly of this component to prevent damage and/or degradation which may be induced by ESD.

### **Ordering Information**

ACPL-P456 and ACPL-W456 are UL Recognized with 3750V<sub>RMS</sub> (5000V<sub>RMS</sub> for ACPL-W456) for 1 minute per UL1577 and are approved under CSA Component Acceptance Notice #5, File CA 88324.



To order, choose a part number from the part number column and combine with the desired option from the option column to form an ordering part number.

Example 1:

ACPL-P456-560E to order product of Stretched SO-6 package in Tape and Reel packaging with IEC/EN/DIN EN 60747-5-5 Safety Approval in RoHS compliant.

Example 2:

ACPL-P456-000E to order product of Stretched SO-6 package in tube packaging and RoHS compliant.

Option data sheets are available. Contact your Broadcom sales representative or authorized distributor for information.

### **Solder Reflow Profile**

The recommended reflow profile is per JEDEC Standard, J-STD-020 (latest revision). Non-halide flux should be used.

### **Regulatory Information**

The ACPL-P456 and ACPL-W456 are approved by the following organizations:

- **IFC/EN/DIN EN 60747-5-5 (Option 060 only): Approved with Maximum Working Insulation Voltage V<sub>IORM</sub> = 1140V<sub>peak</sub>** (ACPL-W456) and  $V_{\text{IORM}} = 891V_{\text{peak}}$  (ACPL-P456).
- UL: Approval under UL 1577, component recognition program up to  $V_{ISO} = 3750V_{RMS}$  (or 5000V<sub>RMS</sub> for ACPLW456). File E55361.
- CSA: Approval under CSA Component Acceptance Notice #5, File CA 88324.

### **Package Outline Drawings**

#### **ACPL-P456 Stretched SO-6 Package (7 mm Clearance)**







Floating Lead Protusions max. 0.25 [0.01]

Dimensions in Millimeters [ Inches ] Lead Coplanarity= 0.1mm [0.004 Inches ]

#### **ACPL-W456 Stretched SO-6 Package (8 mm Clearance)**



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### **IEC/EN/DIN EN 60747-5-5 Insulation Characteristics (Option 060)**



a. Refer to the optocoupler section of the Isolation and Control Components Designer's Catalog, under the Product Safety Regulations section, (IEC/EN/DIN EN 60747-5-5), for a detailed description of Method a and Method b partial discharge test profiles.

### **Insulation and Safety Related Specifications**



### **Absolute Maximum Ratings**



### **Recommended Operating Conditions**



### **Electrical Specifications**

Over recommended operating conditions unless otherwise specifi ed: T<sub>A</sub> = –40°C to +100°C, V<sub>CC</sub> = 4.5V to 30V, I<sub>F(ON)</sub> = 10 mA to 20 mA,  $V_{F(OFF)} = -5V$  to  $+0.8V$ .





### **Switching Specifications (R<sup>L</sup> = 20 kΩ)**

Over recommended operating conditions unless otherwise specified. T<sub>A</sub> = –40°C to +100°C, V<sub>CC</sub> = +4.5V to 30V, I<sub>F(ON)</sub> = 10 mA to 20 mA,  $V_{F(OFF)} = -5V$  to 0.8V.



### **Package Characteristics**



a. The Input-Output Momentary Withstand Voltage is a dielectric voltage rating that should not be interpreted as an input-output continuous voltage rating. For the continuous voltage rating refer to the IEC/EN/DIN EN 60747-5-5 Insulation Characteristics Table (if applicable).

b. For all ACPL-W456 devices.

c. For ACPL-W456 and Option 020 of ACPL-P456)

#### Notes:

- 1. Derate linearly above 90°C free-air temperature at a rate of 0.8 mA/°C.
- 2. Derate linearly above 90°C free-air temperature at a rate of 1.6 mA/°C.
- 3. Derate linearly above 90°C free-air temperature at a rate of 3.0 mA/°C.
- 4. Derate linearly above 90°C free-air temperature at a rate of 4.2 mA/°C.
- 5. CURRENT TRANSFER RATIO in percent is defined as the ratio of output collector current ( $I_O$ ) to the forward LED input current (IF) times 100.
- 6. Device considered a two-terminal device: Pins 1 and 3 shorted together and Pins 4, 5, and 6 shorted together.
- 7. In accordance with UL1577, each optocoupler is proof tested by applying an insulation test voltage. 4500V<sub>RMS</sub> for 1 second (leakage detection current limit, I<sub>I-O</sub>  $\leq$  5 µA); each optocoupler under ACPL-W456 is proof tested by applying an insulation test voltage. 6000V<sub>RMS</sub> for 1 second (leakage detection current limit,  $I_{I-O} \le 5 \mu A$ ).
- 8. Pulse:  $f = 20$  kHz, Duty Cycle = 10%.
- 9. Use of a 0.1 μF bypass capacitor connected between pins 4 and 6 can improve performance by filtering power supply line noise.
- 10. The difference between t<sub>PLH</sub> and t<sub>PHL</sub> between any two parts under the same test condition. (See IPM Dead Time and Propagation Delay Specifications section.)
- 11. Common mode transient immunity in a Logic High level is the maximum tolerable  $dV_{CM}/dt$  of the common mode pulse,  $V_{CM}$ , to assure that the output will remain in a Logic High state (i.e.,  $V_{\Omega} > 3.0V$ ).
- 12. Common mode transient immunity in a Logic Low level is the maximum tolerable  $dV_{CM}/dt$  of the common mode pulse,  $V_{CM}$ , to assure that the output will remain in a Logic Low state (i.e.,  $V_{\rm O}$  < 1.0V).
- 13. Pulse Width Distortion (PWD) is defi ned as  $|t_{PHL} t_{PLH}|$  for any given device.



<span id="page-7-3"></span>



<span id="page-7-4"></span>



<span id="page-7-1"></span>Figure 1 Typical Transfer Characteristics **Figure 2 Normalized Output Current vs. Temperature** 

<span id="page-7-2"></span>

<span id="page-7-0"></span>





#### <span id="page-8-4"></span>**Figure 6 CMR Test Circuit and Waveforms**





<span id="page-8-0"></span>**Figure 7 Propagation Delay with External 20 kΩ RL vs. Temp. Figure 8 Propagation Delay vs. Load Resistance**



<span id="page-8-2"></span>



<span id="page-8-1"></span>



<span id="page-8-3"></span>



<span id="page-9-0"></span>



### **Applications Information**

#### **LED Drive Circuit Considerations For Ultra High CMR Performance**

Without a detector shield, the dominant cause of optocoupler CMR failure is capacitive coupling from the input side of the optocoupler, through the package, to the detector IC as shown in [Figure 13.](#page-9-1) The ACPL-P456/W456 improve CMR performance by using a detector IC with an optically transparent Faraday shield, which diverts the capacitively coupled current away from the sensitive IC circuitry. However, this shield does not eliminate the capacitive coupling between the LED and the optocoupler output pin and output ground as shown in [Figure 14.](#page-9-2) This capacitive coupling causes perturbations in the LED current during common mode transients and becomes the major source of CMR failures for a shielded optocoupler. The main design objective of a high CMR LED drive circuit becomes keeping the LED in the proper state (on or off) during common mode transients. For example, the recommended application circuit ([Figure 12](#page-9-3)), can achieve 15 kV/μs CMR while minimizing component complexity. Note that a CMOS gate is recommended in [Figure 12](#page-9-3) to keep the LED off when the gate is in the high state.

#### <span id="page-9-3"></span>**Figure 12 Recommended LED Drive Circuit**



<span id="page-9-1"></span>**Figure 13 Optocoupler Input to Output Capacitance Model for Unshielded Optocouplers**



Another cause of CMR failure for a shielded optocoupler is direct coupling to the optocoupler output pins through CLEDO1 in [Figure 14.](#page-9-2) Many factors influence the effect and magnitude of the direct coupling including: the position of the LED current setting resistor and the value of the capacitor at the optocoupler output (CL).

#### <span id="page-9-2"></span>**Figure 14 Optocoupler Input to Output Capacitance Model for Shielded Optocouplers**



#### **CMR With The LED On (CMRL)**

A high CMR LED drive circuit must keep the LED on during common mode transients. This is achieved by overdriving the LED current beyond the input threshold so that it is not pulled below the threshold during a transient. The recommended minimum LED current of 10 mA provides adequate margin over the maximum  $I_{TH}$  of 4.0 mA (see [Figure 1\)](#page-7-1) to achieve 15 kV/μs CMR.

The placement of the LED current setting resistor effects the ability of the drive circuit to keep the LED on during transients and interacts with the direct coupling to the optocoupler output. For example, the LED resistor in [Figure 15](#page-10-0) is connected to the anode. [Figure 16](#page-10-1) shows the AC equivalent circuit for [Figure 15](#page-10-0) during common mode transients. During a  $+dV_{CM}/dt$ in [Figure 16,](#page-10-1) the current available at the LED anode  $(I_{total})$  is limited by the series resistor. The LED current (I<sub>F</sub>) is reduced from its DC value by an amount equal to the current that flows through  $C_{LEDP}$  and  $C_{LEDO1}$ . The situation is made worse because the current through  $C_{LEDO1}$  has the effect of trying to pull the output high (toward a CMR failure) at the same time the LED current is being reduced. For this reason, the recommended LED drive circuit ([Figure 12](#page-9-3)) places the current setting resistor in series with the LED cathode. [Figure 17](#page-10-2) is the AC equivalent circuit for [Figure 12](#page-9-3) during common mode

transients. In this case, the LED current is not reduced during a  $+dV<sub>CM</sub>/dt$  transient because the current fl owing through the package capacitance is supplied by the power supply. During a  $-dV<sub>CM</sub>/dt$  transient, however, the LED current is reduced by the amount of current flowing through  $C_{\text{LFDM}}$ . But, better CMR performance is achieved since the current fl owing in  $C_{\text{FDO1}}$ during a negative transient acts to keep the output low.

#### <span id="page-10-0"></span>**Figure 15 LED Drive Circuit with Resistor Connected to LED Anode (Not Recommended)**



#### <span id="page-10-1"></span>**Figure 16 AC Equivalent Circuit for Figure 15 During Common Mode Transients**



#### <span id="page-10-2"></span>**Figure 17 AC Equivalent Circuit for Figure 12 During Common Mode Transients**



#### **CMR With The LED Off (CMRH)**

A high CMR LED drive circuit must keep the LED off (V<sub>F</sub>  $\leq$  $V_{F(OFF)}$ ) during common mode transients. For example, during a +dV $_{CM}$ /dt transient in [Figure 17](#page-10-2), the current flowing through CLEDN is supplied by the parallel combination of the LED and series resistor. As long as the voltage developed across the resistor is less than  $V_{F(OFF)}$  the LED will remain off and no common mode failure will occur. Even if the LED momentarily turns on, the 100 pF capacitor from pins 5-4 will keep the output from dipping below the threshold. The recommended LED drive circuit [\(Figure 12\)](#page-9-3) provides about 10V of margin between the lowest optocoupler output voltage and a 3V IPM threshold during a 15 kV/ $\mu$ s transient with V<sub>CM</sub> = 1500V. Additional margin can be obtained by adding a diode in parallel with the resistor, as shown by the dashed line connection in [Figure 17](#page-10-2), to clamp the voltage across the LED below  $V_{F(OFF)}$ .

Since the open collector drive circuit, shown in [Figure 18](#page-10-3), cannot keep the LED off during a  $+dV_{CM}/dt$  transient, it is not desirable for applications requiring ultra high CMR $_H$ performance. [Figure 19](#page-10-4) is the AC equivalent circuit for [Figure 18](#page-10-3) during common mode transients. Essentially all the current flowing through  $C_{LEDN}$  during a +dV<sub>CM</sub>/dt transient must be supplied by the LED. CMRH failures can occur at dv/dt rates where the current through the LED and C<sub>LEDN</sub> exceeds the input threshold. [Figure 20](#page-11-0) is an alternative drive circuit which does achieve ultra high CMR performance by shunting the LED in the off state.

#### <span id="page-10-3"></span>**Figure 18 Not Recommended Open Collector LED Drive Circuit**



<span id="page-10-4"></span>



#### <span id="page-11-0"></span>**Figure 20 Recommended LED Drive Circuit for Ultra High CMR**



#### **IPM Dead Time and Propagation Delay Specifications**

The ACPL-P456/W456 includes a Propagation Delay Difference specification intended to help designers minimize "dead time" in their power inverter designs. Dead time is the time period during which both the high and low side power transistors (Q1 and Q2 in [Figure 21\)](#page-11-1) are off. Any overlap in Q1 and Q2 conduction will result in large currents flowing through the power devices between the high and low voltage motor rails.

To minimize dead time the designer must consider the propagation delay characteristics of the optocoupler as well as the characteristics of the IPM IGBT gate drive circuit. Considering only the delay characteristics of the optocoupler (the characteristics of the IPM IGBT gate drive circuit can be analyzed in the same way) it is important to know the minimum and maximum turn on  $(t_{PHI})$  and turn-off  $(t_{PIH})$ propagation delay specifications, preferably over the desired operating temperature range.

#### The limiting case of zero dead time occurs when the input to Q1 turns off at the same time that the input to Q2 turns on. This case determines the minimum delay between LED1 turn-off and LED2 turn-on, which is related to the worst case optocoupler propagation delay waveforms, as shown in [Figure 22.](#page-12-0) A minimum dead time of zero is achieved in [Figure 22](#page-12-0) when the signal to turn on LED2 is delayed by  $(t_{PIH})$ max –  $t_{PHI}$  min) from the LED1 turn off. Note that the propagation delays used to calculate PDD are taken at equal temperatures since the optocouplers under consideration are typically mounted in close proximity to each other. (Specifically, previous equation are not the same as the  $t_{PIH}$ max and  $t_{PHI}$  min, over the full operating temperature range, specified in the data sheet.) This delay is the maximum value for the propagation delay difference specification which is specified at 450 ns for the ACPL-P456/W456 over an operating temperature range of –40°C to +100°C.

Delaying the LED signal by the maximum propagation delay difference ensures that the minimum dead time is zero, but it does not tell a designer what the maximum dead time will be. The maximum dead time occurs in the highly unlikely case where one optocoupler with the fastest  $t_{PLH}$  and another with the slowest t<sub>PHL</sub> are in the same inverter leg. The maximum dead time in this case becomes the sum of the spread in the  $t_{PIH}$  and  $t_{PHI}$  propagation delays as shown in [Figure 23](#page-12-1). The maximum dead time is also equivalent to the difference between the maximum and minimum propagation delay difference specifications. The maximum dead time (due to the optocouplers) for the ACPL-P456/W456 are 600 ns (= 450 ns – (–150 ns)) over an operating temperature range of –40°C to  $+100^{\circ}$ C.



#### <span id="page-11-1"></span>**Figure 21 Typical Application Circuit**



<span id="page-12-0"></span>**Figure 22 Minimum LED Skew for Zero Dead Time Figure 23 Waveforms for Deadtime Calculation**

**PDD ARE TAKEN AT EQUAL TEMPERATURES.**

<span id="page-12-1"></span>



**= (tPLH MAX. - tPLH MIN.) + (tPHL MAX. - tPHL MIN.) = (tPLH MAX. - tPHL MIN.) - (tPLH MIN. - tPHL MAX.) = PDD\* MAX. - PDD\* MIN.**

**\*PDD = PROPAGATION DELAY DIFFERENCE**

**NOTE: THE PROPAGATION DELAYS USED TO CALCULATE THE MAXIMUM DEAD TIME ARE TAKEN AT EQUAL TEMPERATURES.**

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