

# **Automotive IPD Series**

# 8ch Low Side Switch

# BD8LD650EFV-C

### **General Description**

BD8LD650EFV-C is an 8-channel SPI-input low side switch for automotive and industrial application. It has built-in open load detection function, short ground detection function, over current protection function, thermal shutdown function, and active clamp function.

### **Features**

- AEC-Q100 Qualified<sup>(Note 1)</sup>
- Monolithic Power Management IC with Control Block (CMOS) and a Power MOSFET Mounted on a Single Chip
- Channel Control/error can be Detected by 16 bit SPI Commands.
- Built-in Open Load Detection Function (OLD)
- Built-in Short Ground Detection Function (SGD)
- Built-in Over Current Protection Function (OCP)
- Built-in Thermal Shutdown Function(TSD)
- Built-in Active Clamp Function
- Built-in Synchro Mode
- Built-in Limp Home Mode
- Surface-mount HTSSOP-B20 Packaging (Note 1) Grade1

### Application

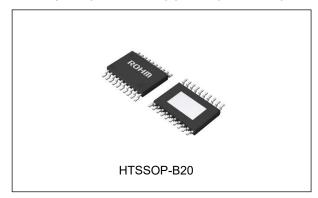
Driving Resistive and Inductive Load

# **Key Specifications**

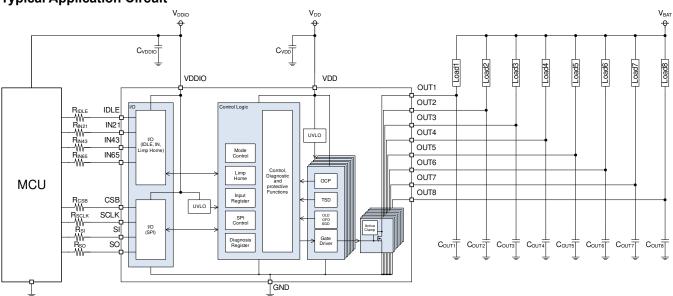
Input Voltage Range VDD:
 Input Voltage Range VDDIO:
 On State Resistance:
 Over Current Threshold Value:
 Active Clamp Energy:
 Operating Temperature Range Tj:-40 °C to +150 °C

### Package HTSSOP-B20

**W** (Typ) x D (Typ) x H (Max) 6.5 mm x 6.4 mm x 1.0 mm



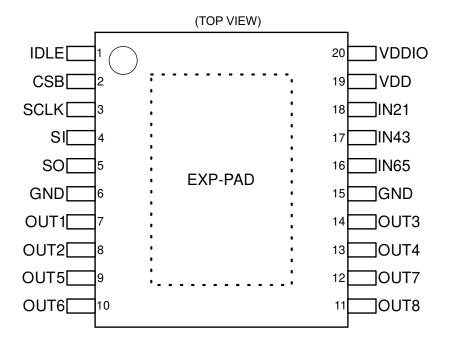
# **Typical Application Circuit**



# **Contents**

General Description	1
Features	1
Application	1
Key Specifications	1
Package	1
Typical Application Circuit	1
Contents	2
Pin Configuration	3
Pin Descriptions	3
Definition	4
Block Diagram	4
Absolute Maximum Ratings	5
Thermal Resistance	6
Recommended Operating Conditions	10
Electrical Characteristics	10
Typical Performance Curves	12
Measurement Circuit	23
Timing Chart	25
Synchro Mode	27
Limp Home Mode	28
SPI Specification	29
Register Map	33
Over Current Protection Function	35
Thermal Shutdown Function	36
Open Load Detection (OLD)	37
Output Overhead Fault Detection Function (OFD)	38
Short Ground Detection (SGD)	39
Application Example	41
Selection of Components Externally Connected	41
I/O Equivalence Circuits	42
Operational Notes	43
Ordering Information	46
Marking Diagram	46
Physical Dimension and Packing Information	47
Povicion History	40

# **Pin Configuration**

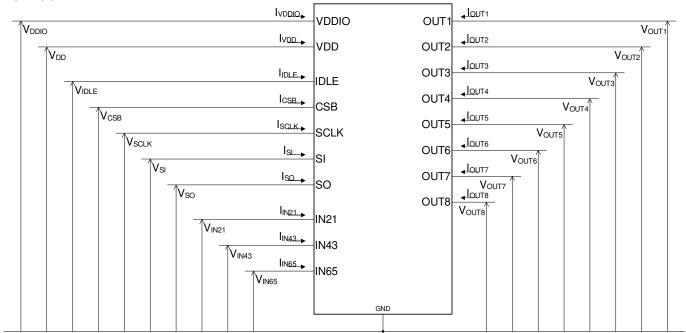


**Pin Descriptions** 

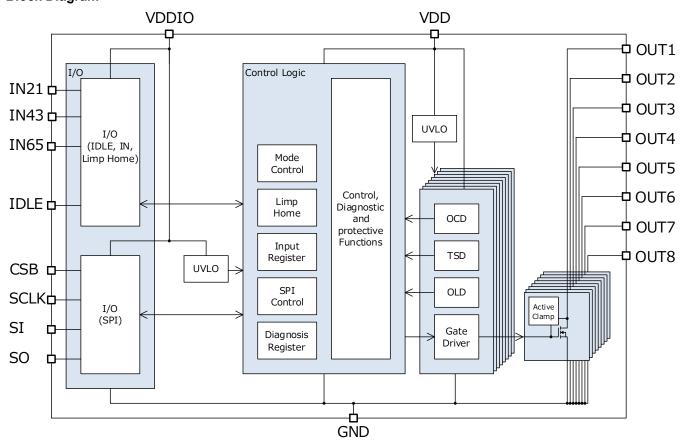
Descriptions		
Pin No.	Pin Name	Function
1	IDLE	Limp home mode control This pin is connected to GND via an internal pull-down resistor.
2	CSB	SPI enable This pin is connected to VDDIO via an internal pull-up resistor.
3	SCLK	Serial clock input This pin is connected to GND via an internal pull-down resistor.
4	SI	Serial data input This pin is connected to GND via an internal pull-down resistor.
5	SO	Serial data output
6	GND	GND
7	OUT1	ch1 output
8	OUT2	ch2 output
9	OUT5	ch5 output
10	OUT6	ch6 output
11	OUT8	ch8 output
12	OUT7	ch7 output
13	OUT4	ch4 output
14	OUT3	ch3 output
15	GND	GND
16	IN65	ch5, ch6 control <sup>(Note 1)</sup> This pin is connected to GND via an internal pull-down resistor.
17	IN43	ch3, ch4 control <sup>(Note 1)</sup> This pin is connected to GND via an internal pull-down resistor.
18	IN21	ch1, ch2 control <sup>(Note 1)</sup> This pin is connected to GND via an internal pull-down resistor.
19	VDD	Analog power supply
20	VDDIO	Digital power supply
-	EXP-PAD	Be sure to connect EXP-PAD to GND.

(Note 1) Controlled channels can be changed by accessing DIRCTRL register from the SPI.

# **Definition**



# **Block Diagram**



Absolute Maximum Ratings (Tj = 25 °C)

Parameter	Symbol	Rating	Unit
VDDIO, VDD Power Supply Voltage	$V_{DDIO}, V_{DD}$	-0.3 to +7	V
Output Voltage (Power MOS Output)	V <sub>OUT1-8</sub>	-0.3 to (Internal Limit)(Note 1)	V
Output Current (Power MOS Output)	I <sub>OUT1-8</sub>	(Internal Limit)(Note 2)	Α
Output Voltage (SPI)	Vso	-0.3 to +7	V
Input Voltage (IDLE)	VIDLE	-0.3 to +7	V
Input Voltage (SPI)	Vcsb, Vsclk, Vsi	-0.3 to +7	V
Input Voltage (IN65, IN43, IN21)	VIN65, VIN43, VIN21	-0.3 to +7	V
Storage Temperature Range	Tstg	-55 to +150	°C
Maximum Junction Temperature	Tjmax	150	°C
Active Clamp Energy (Single Pulse) Tj(START) = 25 °C, IOUT1-8(START) = 0.4 A	Eas1-8(25 °C)	125	mJ
Active Clamp Energy (Single Pulse) <sup>(Note 3)</sup> Tj(START) = 150 °C, IOUT1-8(START) = 0.4 A	Eas1-8(150 °C)	25	mJ
Active Clamp Energy (Single Pulse) Tj <sub>(START)</sub> = 25 °C, I <sub>OUT1-8(START)</sub> = 0.8 A, Synchro Mode	Es, AS1-8(25 °C)	57	mJ
Active Clamp Energy (Single Pulse) <sup>(Note 3)</sup> Tj <sub>(START)</sub> = 150 °C, I <sub>OUT1-8(START)</sub> = 0.8 A, Synchro Mode	Es, AS1-8(150 °C)	19	mJ
Active Clamp Energy (Repetitive) <sup>(Note 3)(Note 4)</sup> Tj <sub>(START)</sub> = 125 °C, I <sub>OUT(START)</sub> = 0.2 A	E <sub>AR(125 °C)</sub>	12	mJ
Active Clamp Energy (Repetitive)(Note 3)(Note 4)  Tj(START) = 125 °C, IOUT(START) = 0.4 A, Synchro Mode	Es, AR(125 °C)	9	mJ

(Note 1) Limited by the active clamp function.

(Note 2) Limited by the over current protection function. The over current detection value can be adjusted in two levels.

(Note 3) Not 100 % are tested.

(Note 4) 2M cycles, All channel input.

Caution 1: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Caution 2: Should by any chance the maximum junction temperature rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, design a PCB with thermal resistance taken into consideration by increasing board size and copper area so as not to exceed the maximum junction temperature rating.

Caution 3: When IC is turned off with an inductive load, reverse energy has to be dissipated in the IC. This energy can be calculated by the following equation:

$$E_L = \frac{1}{2}LI_{OUT(START)}^2 \times \left(1 - \frac{V_{BAT}}{V_{BAT} - V_{OUT(CL)}}\right)$$

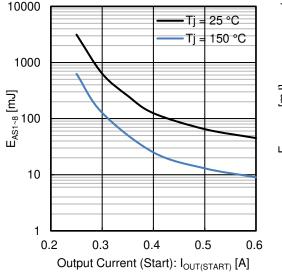
Where:

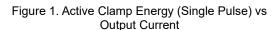
L is the inductance of the inductive load.

lout(START) is the output current at the time of turning off.

 $V_{OUT(CL)}$  is the output clamp voltage.

The IC integrates the active clamp function to internally absorb the reverse energy  $E_L$  which is generated when the inductive load is turned off. When the active clamp operates, the thermal shutdown function does not work. Decide a load so that the reverse energy  $E_L$  is active clamp energy  $E_A$ s (Figure 1.),  $E_{S,AS}$  (Figure 2.) or under when inductive load is used.





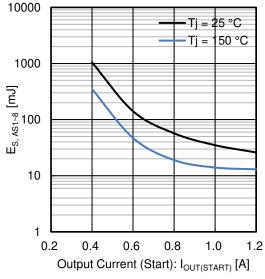


Figure 2. Active Clamp Energy (Single Pulse) Synchro Mode vs Output Current

# Thermal Resistance (Note 1)

Parameter	Symbol	Тур	Unit	Condition
HTSSOP-B20				
		96.6	°C/W	1s <sup>(Note 2)</sup>
Between Junction and Surroundings Temperature Thermal Resistance	$\theta_{JA}$	35.1	°C/W	2s <sup>(Note 3)</sup>
Thomas Nooletanee		24.5	°C/W	2s2p <sup>(Note 4)</sup>

(Note 1) The thermal impedance is based on JESD51-2A(Still-Air) standard.
(Note 2) JESD51-3 standard FR4 114.3 mm x 76.2 mm x 1.57 mm 1-layer (1s)

(Top copper foil: ROHM recommended Footprint + wiring to measure, 2 oz. copper.)
(Note 3) JESD51-5 standard FR4 114.3 mm x 76.2 mm x 1.60 mm 2-layers (2s).

(Top copper foil: ROHM recommended Footprint + wiring to measure/
Copper foil area on the reverse side of PCB: 74.2 mm × 74.2 mm, copper (top & reverse side) 2 oz )

(Note 4) JESD51-5/-7 standard FR4 114.3 mm x 76.2 mm x 1.60 mm 4-layers (2s2p)

(Top copper foil: ROHM recommended Footprint + wiring to measure/

2 inner layers and copper foil area on the reverse side of PCB: 74.2 mm × 74.2 mm, copper (top & reverse side/inner layers) 2 oz./1 oz.)

# ■ PCB Layout 1 layer (1s)

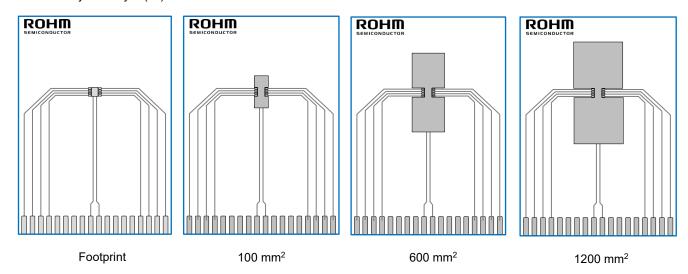


Figure 3. PCB Layout 1 Layer (1s)

Dimension	Value
Board Finish Thickness	1.57 mm ± 10 %
Board Dimension	76.2 mm x 114.3 mm
Board Material	FR4
Copper Thickness (Top Layer)	0.070 mm (Cu: 2 oz)
Copper Foil Area Dimension	Footprint/100 mm <sup>2</sup> /600 mm <sup>2</sup> /1200 mm <sup>2</sup>

# Thermal Resistance - continued

■ PCB Layout 2 layers (2s)

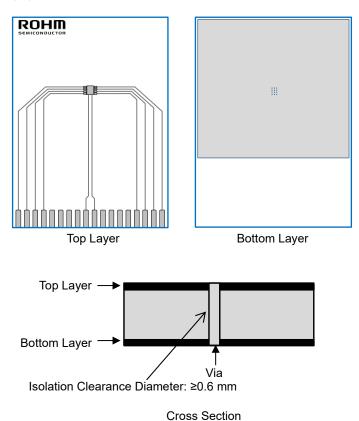


Figure 4. PCB-layout 2-layer (2s)

Dimension	Value
Board Finish Thickness	1.60 mm ± 10 %
Board Dimension	76.2 mm x 114.3 mm
Board Material	FR4
Copper Thickness (Top/Bottom Layers)	0.070 mm (Cu +Plating)
Thermal Vias Separation/Diameter	1.2 mm/0.3 mm

# Thermal Resistance - continued

■ PCB Layout 4 layers (2s2p)

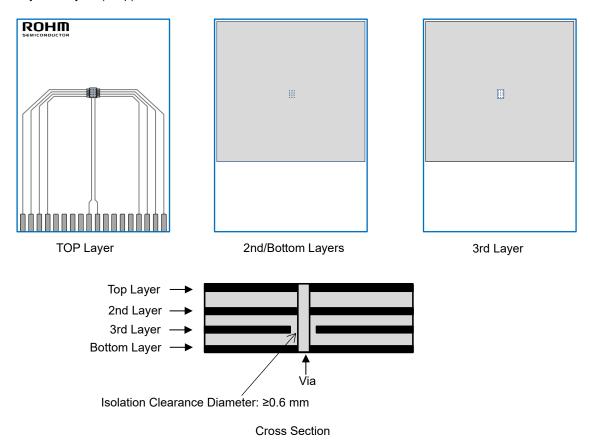


Figure 5. PCB-layout 4-layer (2s2p)

Dimension	Value
Board Finish Thickness	1.60 mm ± 10 %
Board Dimension	76.2 mm x 114.3 mm
Board Material	FR4
Copper Thickness (Top/Bottom Layers)	0.070 mm (Cu +Plating)
Copper Thickness (Inner Layers)	0.035 mm
Thermal Vias Separation/Diameter	1.2 mm/0.3 mm

# Thermal Resistance - continued

■ Transient Thermal Resistance (Single Pulse)

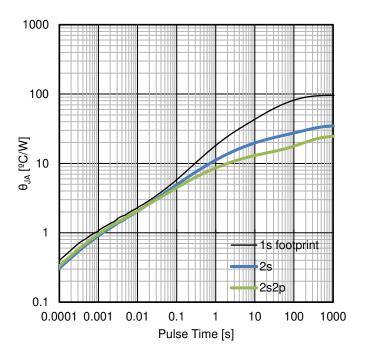


Figure 6. Transient Thermal Resistance

■ Thermal Resistance (θ<sub>JA</sub> vs Copper Foil area 1s)

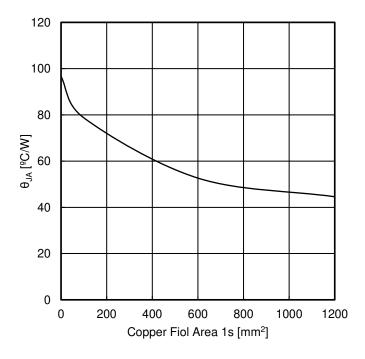


Figure 7. Thermal Resistance

**Recommended Operating Conditions** 

Parameter	Symbol	Min	Тур	Max	Unit
VDD Power Supply Voltage	$V_{DD}$	4.0	5.0	5.5	V
VDDIO Power Supply Voltage	V <sub>DDIO</sub>	3.0	5.0	5.5	V
Operating Temperature	Topr	-40	+25	+150	°C

# **Electrical Characteristics**

(Unless otherwise specified  $V_{DD}$  = 4.0 V to 5.5 V,  $V_{DDIO}$  = 3.0 V to 5.5 V, Tj = -40 °C to +150 °C)

Parameter	Symbol	Min	Тур	Max	Unit	Conditions
[Power Supply]						
VDD Standby Current	Ivdds	-	0	20	μA	V <sub>IDLE</sub> = 0 V V <sub>IN21</sub> , V <sub>IN43</sub> , V <sub>IN65</sub> = 0 V
VDDIO Standby Current	Ivddios	-	0	20	μA	V <sub>IDLE</sub> = 0 V V <sub>IN21</sub> , V <sub>IN43</sub> , V <sub>IN65</sub> = 0 V
VDD Operating Current	I <sub>VDD</sub>	-	1.2	2.4	mA	V <sub>IDLE</sub> = 5 V V <sub>IN21</sub> , V <sub>IN43</sub> , V <sub>IN65</sub> = 5 V OUTCTRLn[7:0] = FF <sup>(Note 1)</sup>
VDDIO Operating Current	I <sub>VDDIO</sub>	-	30	150	μA	V <sub>IDLE</sub> = 5 V V <sub>IN21</sub> , V <sub>IN43</sub> , V <sub>IN65</sub> = 5 V OUTCTRLn[7:0] = FF <sup>(Note 1)</sup>
VDD Power On Reset Voltage	$V_{PORA}$	-	-	4.0	V	
VDDIO Power On Reset Voltage	VPORD	-	-	2.7	V	
[Input (IDLE, CSB, SCLK, SI, IN21, IN	143, IN65)]					
Low Level Input Voltage	V <sub>IL</sub>	0	-	V <sub>DDIO</sub> × 0.2	V	
High Level Input Voltage	V <sub>IH</sub>	V <sub>DDIO</sub> × 0.7	-	$V_{DDIO}$	V	
Input Hysteresis Voltage	V <sub>HYS</sub>	0.25	0.45	0.65	V	
Low Level Input Current 1 (except CSB)	I <sub>IL1</sub>	-10	0	+10	μA	VIDLE, VSCLK, VSI, VIN21, VIN43, VIN65 = 0 V
Low Level Input Current 2 (CSB)	I <sub>IL2</sub>	-100	-50	-25	μA	V <sub>CSB</sub> = 0 V
High Level Input Current 1 (except CSB)	I <sub>IH1</sub>	25	50	100	μΑ	VIDLE, VSCLK, VSI, VIN21, VIN43, VIN65 = 5 V
High Level Input Current 2 (CSB)	I <sub>IH2</sub>	-10	0	+10	μA	V <sub>CSB</sub> = 5 V
[Output (SO)]						
Low Level Output Voltage	Vol	0	0.15	0.45	V	Iso = 1 mA
High Level Output Voltage	V <sub>OH</sub>	V <sub>DDIO</sub> – 0.45	V <sub>DDIO</sub> – 0.15	-	V	I <sub>SO</sub> = -1 mA
Serial Out Output Leakage Current	Iso	-5	0	+5	μΑ	$V_{SO} = 0 \text{ V} / 5.5 \text{ V}$
[Power MOS Output]						
Output On Resistance	R <sub>DS(ON)</sub>	-	650	800	mΩ	V <sub>DD</sub> = 5 V I <sub>OUT</sub> = 0.2 A, Tj = 25 °C
	· 150(ON)	-	1200	1500	mΩ	V <sub>DD</sub> = 5 V I <sub>OUT</sub> = 0.2 A, Tj = 150 °C
Output Leakage Current	I <sub>OUT(L)</sub>	-	0	1	μA	V <sub>OUT</sub> = 30 V, Tj = 25 °C
	1001(E)	-	0.15	2.00	μΑ	V <sub>OUT</sub> = 30 V, Tj = 150 °C
Output Clamp Voltage	VcL	37	41	45	V	I <sub>OUT</sub> = 1 mA, Output Off

(Note 1) Set by SPI control. Details are given in "Register Map". n represents the channel number.

# Electrical Characteristics – continued

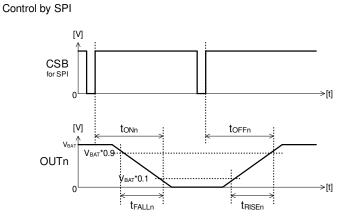
(Unless otherwise specified,  $V_{DD}$  = 4.0 V to 5.5 V,  $V_{DDIO}$  = 3.0 V to 5.5 V, Tj = -40 °C to +150 °C)

ess otherwise specified, VDD - 4.	U V 10 3.3	<b>v, v</b> DDIO -	- 3.0 V LC	7 3.3 V, I	<u> </u>	C 10 + 130 C)
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
[Power MOS Output]		<u>I</u>				
Turn-On Time 1	t <sub>ON1</sub>	-	-	50	μs	R <sub>L</sub> = 60 Ω, V <sub>IDLE</sub> = 5 V, V <sub>BAT</sub> =
Turn-Off Time 1	t <sub>OFF1</sub>	-	-	50	μs	12 V, SRCTRLn[1:0] = 00 <sup>(Note 1)</sup>
Turn-On Time 2	t <sub>ON2</sub>	-	-	200	μs	R <sub>L</sub> = 60 Ω, V <sub>IDLE</sub> = 5 V, V <sub>BAT</sub> =
Turn-Off Time 2	t <sub>OFF2</sub>	-	-	200	μs	12 V, SRCTRLn[1:0] = 10 <sup>(Note 1)</sup>
Turn-On Time 3	t <sub>ON3</sub>	-	-	25	μs	$R_L = 60 \Omega$ , $V_{IDLE} = 5 V$ , $V_{BAT} =$
Turn-Off Time 3	t <sub>OFF3</sub>	-	-	25	μs	12 V, SRCTRLn[1:0] = 01 <sup>(Note 1)</sup>
Slew Rate (On) 1	SR <sub>ON1</sub>	0.50	1.00	1.50	V/µs	$R_L = 60 \Omega$ , $V_{IDLE} = 5 V$ , $V_{BAT} =$
Slew Rate (Off) 1	SR <sub>OFF1</sub>	0.50	1.00	1.50	V/µs	12 V, SRCTRLn[1:0] = 00 <sup>(Note 1)</sup>
Slew Rate (On) 2	SR <sub>ON2</sub>	0.10	0.30	0.50	V/µs	R <sub>L</sub> = 60 Ω, V <sub>IDLE</sub> = 5 V, V <sub>BAT</sub> =
Slew Rate (Off) 2	SR <sub>OFF2</sub>	0.10	0.30	0.50	V/µs	12 V, SRCTRLn[1:0] = 10 <sup>(Note )</sup>
Slew Rate (On) 3	SR <sub>ON3</sub>	1.35	2.25	3.15	V/µs	$R_L = 60 \Omega$ , $V_{IDLE} = 5 V$ , $V_{BAT} =$
Slew Rate (Off) 3	SR <sub>OFF3</sub>	1.35	2.25	3.15	V/µs	12 V, SRCTRLn[1:0] = 01 <sup>(Note</sup>
PWM Output Range	f <sub>PWM</sub>	-	-	5	kHz	$R_L$ = 60 Ω, $V_{IDLE}$ = 5 V, $V_{BAT}$ = 12 V, $SRCTRLn[1:0] = 00^{(Note)}$
[Over Current Protection Function]						
Over Current Threshold Value 1	I <sub>OCP1</sub>	0.50	0.85	1.30	Α	OCPCTRLn = '0'(Note 1)
Over Current Threshold Value 2	I <sub>OCP2</sub>	1.00	1.70	2.40	Α	OCPCTRLn = '1'(Note 1)
Output Stop Time at OCP Detection	tocp_off	0.4	1.0	1.9	ms	OCPCTRLn = '0' / '1'(Note 1)
[Open Load Detection Function]						
Open Load Detect Voltage	$V_{OLD\_DET}$	1.2	2.2	3.2	V	DIAG_OLD/OFDn = '1'(Note 1)
Open Load Release Voltage	Vold_rel	1.6	2.6	3.6	V	Output Off
Output Sink Current	lold	15	40	90	μΑ	V <sub>OUT</sub> = 12 V
[Output Overhead Fault Detection Fur	nction]					
Output Overhead Detect Voltage	Vofd_det	1.6	2.6	3.6	V	DIAG_OLD/OFDn = '1'(Note 1)
Output Overhead Release Voltage	$V_{OFD\_REL}$	1.2	2.2	3.2	V	Output On
[Short Ground Detection Function]						
Short Ground Detect Voltage	Vsgd_det	0.3	1.0	1.5	V	DIAG_SGDn = '1'(Note 1)
Short Ground Release Voltage	Vsgd_rel	0.5	1.4	1.9	V	Output Off
Output Source Current	IsgD	-40	-25	-10	μA	V <sub>OUT</sub> = 0 V
[Thermal Shutdown Function]						
Detect Temperature <sup>(Note 2)</sup>	T <sub>TSD_DET</sub>	150	175	200	°C	
Hysteresis Temperature <sup>(Note 2)</sup>	T <sub>TSD_HYS</sub>	-	15	-	°C	
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(Note 1) Set by SPI control. Details are given in "Register Map". n represents the channel number. (Note 2) Not 100 % are tested.

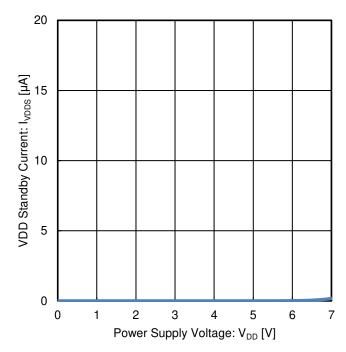
# Switching Time Measurement Waveform

Control by IN21 / IN43/ IN65  $SR_{ON} = (V_{BAT} * 0.8) / T_{FALL}$   $SR_{OFF} = (V_{BAT} * 0.8) / T_{RISE}$ IN21 / IN43 IN65  $V_{BAT} * 0.9$ OUTn  $V_{BAT} * 0.9$   $V_{BAT} * 0.9$ 



# **Typical Performance Curves**

(Reference data) (Unless otherwise specified, V<sub>DD</sub> = 5 V, V<sub>DDIO</sub> = 5 V, Tj = 25 °C)

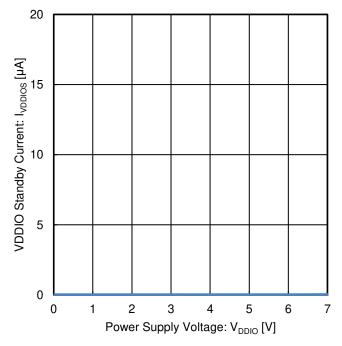


Top Standby Current: I<sub>2008</sub> [LA] 150 Standby Current: I<sub>2008</sub> [LA] 150 Junction Temperature: Tj [°C]

20

Figure 8. VDD Standby Current vs Power Supply Voltage

Figure 9. VDD Standby Current vs Junction Temperature





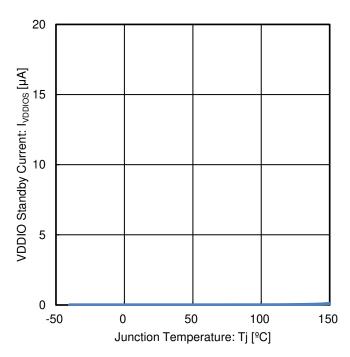


Figure 11. VDDIO Standby Current vs Junction Temperature

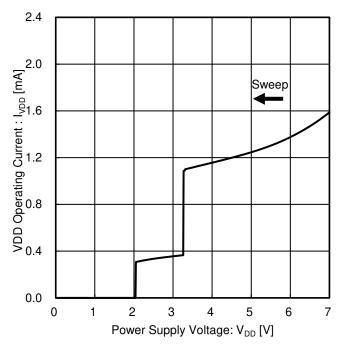


Figure 12. VDD Operating Current vs Power Supply Voltage

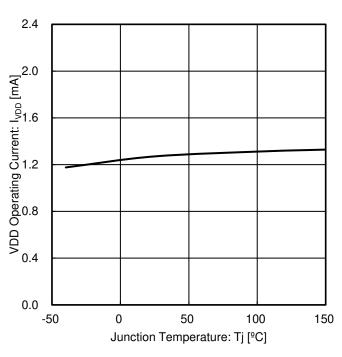


Figure 13. VDD Operating Current vs Junction Temperature

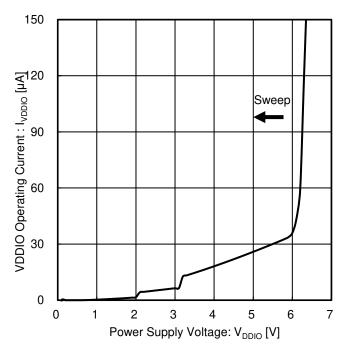


Figure 14. VDDIO Operating Current vs Power Supply Voltage

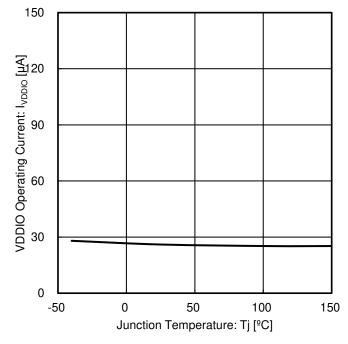


Figure 15. VDDIO Operating Current vs Junction Temperature

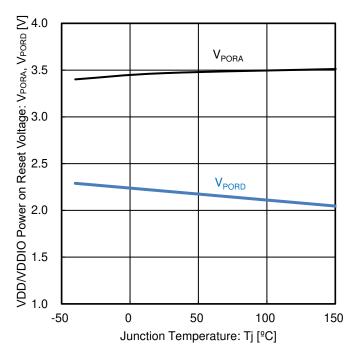


Figure 16. VDD/VDDIO Power On Reset Voltage vs Junction Temperature

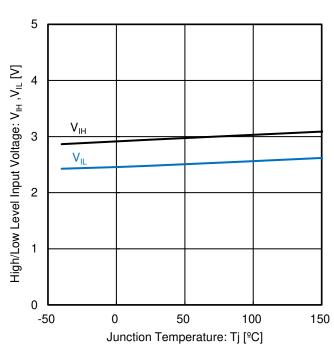


Figure 17. High/Low Level Input Voltage vs Junction Temperature

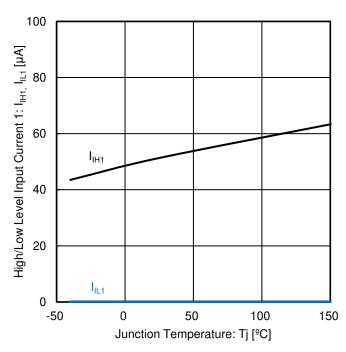


Figure 18. High/Low Level Input Current 1 vs Junction Temperature

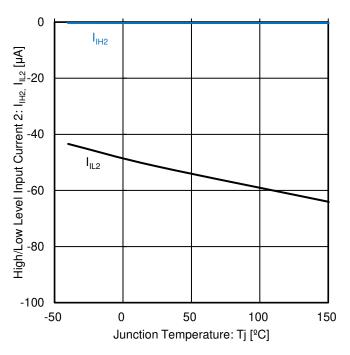


Figure 19. High/Low Level Input Current 2 vs Junction Temperature

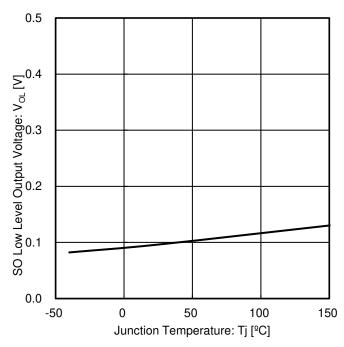


Figure 20. SO Low Level Output Voltage vs Junction Temperature

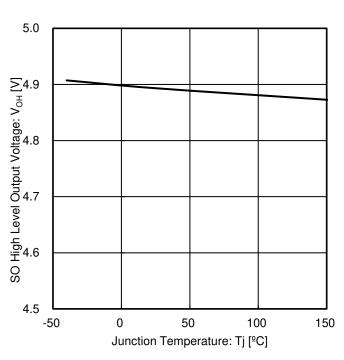


Figure 21. SO High Level Output Voltage vs Junction Temperature

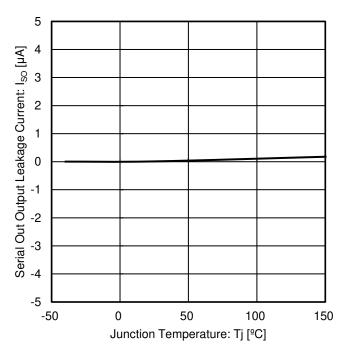


Figure 22. Serial Out Output Leakage Current vs Junction Temperature

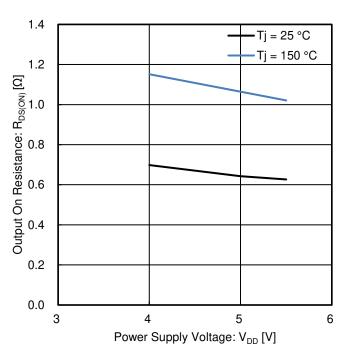


Figure 23. Output On Resistance vs Power Supply Voltage

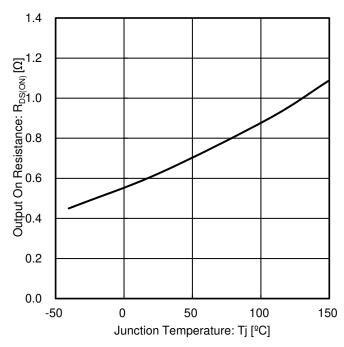


Figure 24. Output On Resistance vs Junction Temperature

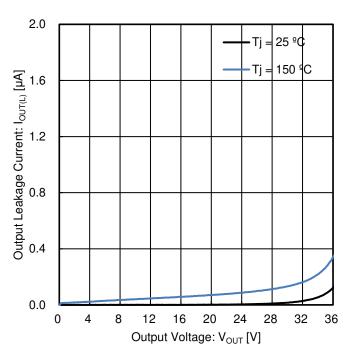


Figure 25. Output Leakage Current vs Output Voltage

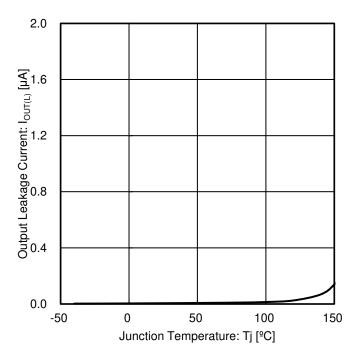


Figure 26. Output Leakage Current vs Junction Temperature

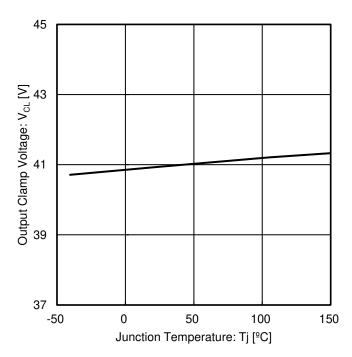


Figure 27. Output Clamp Voltage vs Junction Temperature

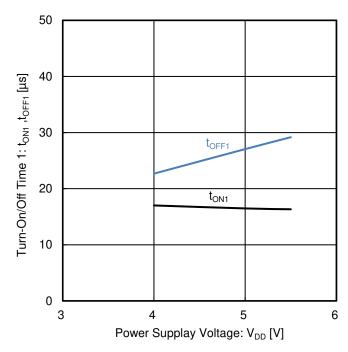


Figure 28. Turn-On/Off Time 1 vs Power Supply Voltage

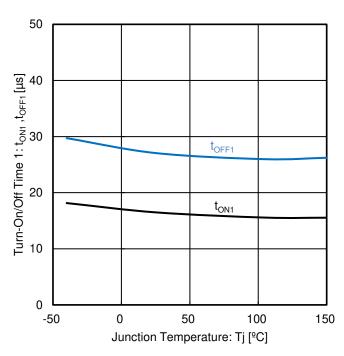


Figure 29. Turn-On/Off Time 1 vs Junction Temperature

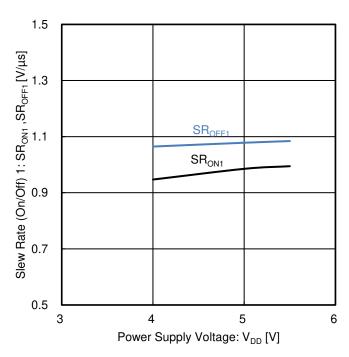


Figure 30. Slew Rate (On/Off) 1 vs Power Supply Voltage

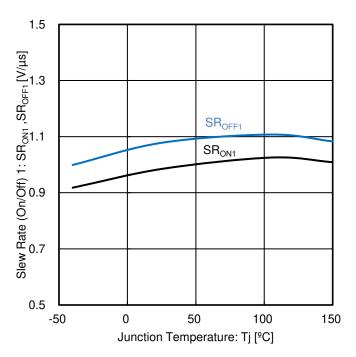


Figure 31. Slew Rate (On/Off) 1 vs Junction Temperature

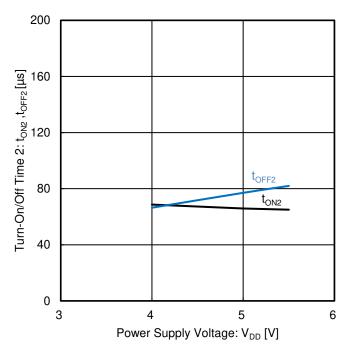


Figure 32. Turn-On/Off Time 2 vs Power Supply Voltage

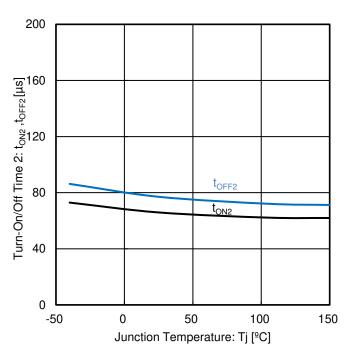


Figure 33. Turn-On/Off Time 2 vs Junction Temperature

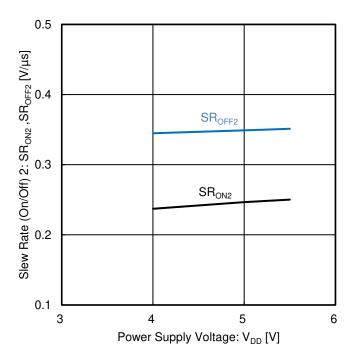


Figure 34. Slew Rate (On/Off) 2 vs Power Supply Voltage

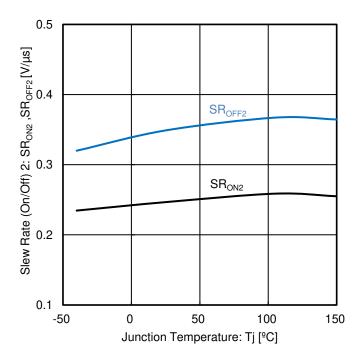


Figure 35. Slew Rate (On/Off) 2 vs Junction Temperature

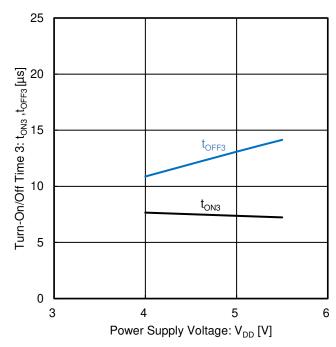


Figure 36. Turn-On/Off Time 3 vs Power Supply Voltage

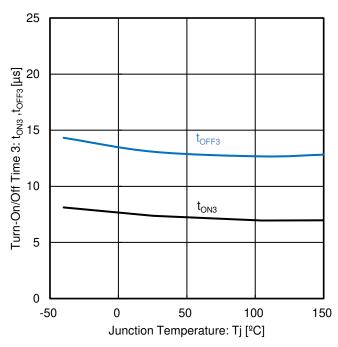


Figure 37. Turn-On/Off Time 3 vs Junction Temperature

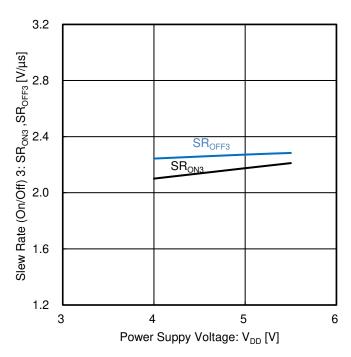


Figure 38. Slew Rate (On/Off) 3 vs Power Supply Voltage

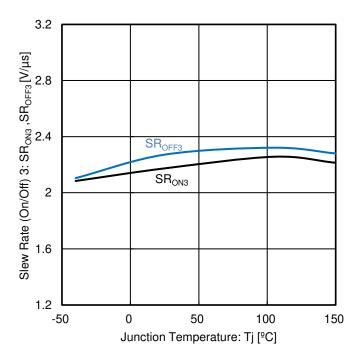


Figure 39. Slew Rate (On/Off) 3 vs Junction Temperature

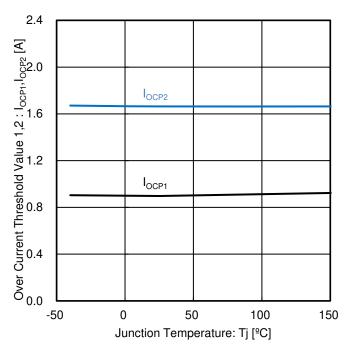


Figure 40. Over Current Threshold Value 1,2 vs Junction Temperature

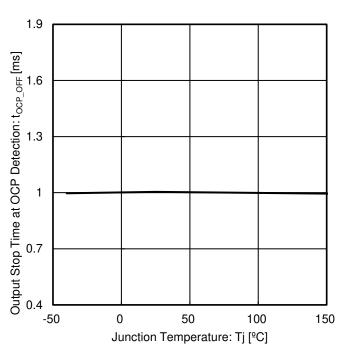


Figure 41. Output Stop Time at OCP Detection vs Junction Temperature

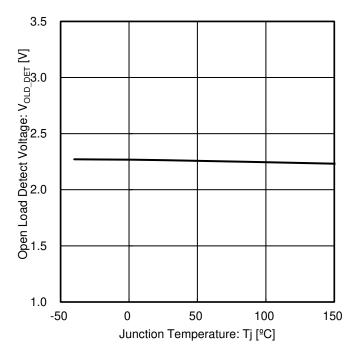


Figure 42. Open Load Detect Voltage vs Junction Temperature

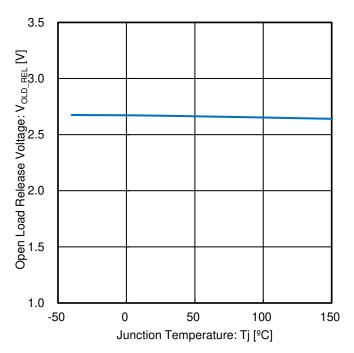


Figure 43. Open Load Release Voltage vs Junction Temperature

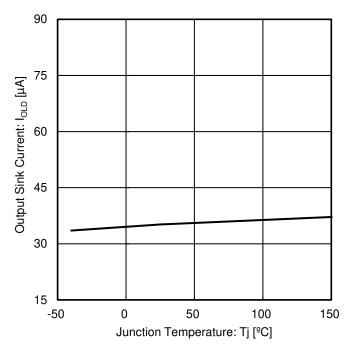


Figure 44. Output Sink Current vs Junction Temperature

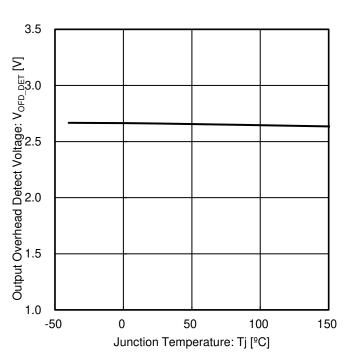


Figure 45. Output Overhead Detect Voltage vs Junction Temperature

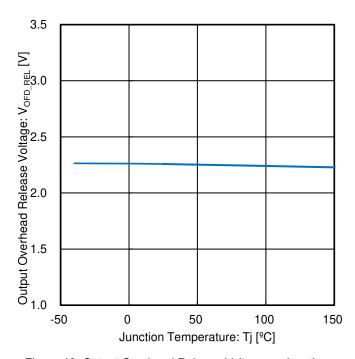


Figure 46. Output Overhead Release Voltage vs Junction Temperature

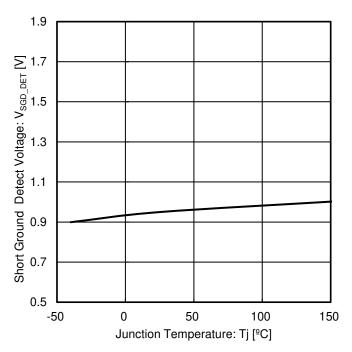


Figure 47. Short Ground Detect Voltage vs Junction Temperature

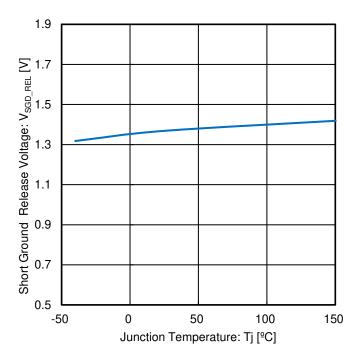


Figure 48. Short Ground Release Voltage vs Junction Temperature

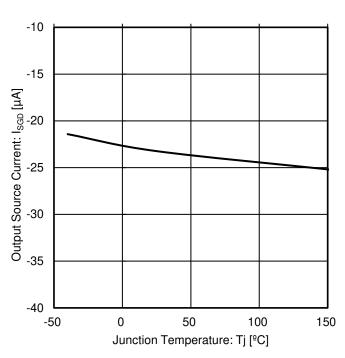


Figure 49. Output Source Current vs Junction Temperature

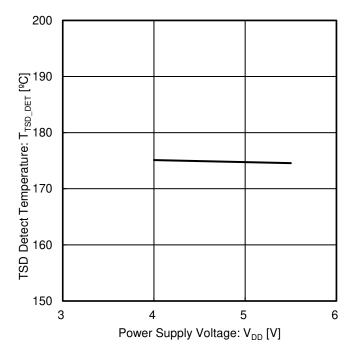


Figure 50. Thermal Shutdown Detect Temperature vs Power Supply Voltage

### **Measurement Circuit**

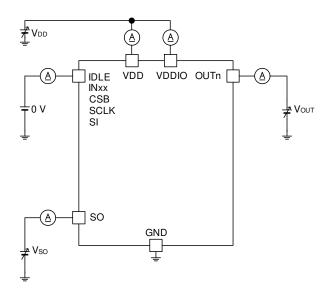


Figure 51. VDD Standby Current
VDDIO Standby Current
Low Level Input Current 1, 2
Output Leakage Current
Serial Out Output Leakage Current

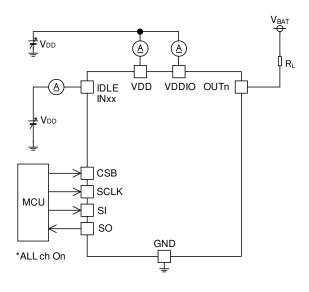


Figure 52. VDD Operating Current
VDDIO Operating Current
VDD Power On Reset Voltage
VDDIO Power On Reset Voltage
Thermal Shutdown Detect Temperature
Thermal Shutdown Hysteresis Temperature

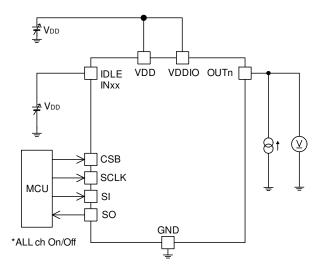


Figure 53. Output On Resistance Output Clamp Voltage

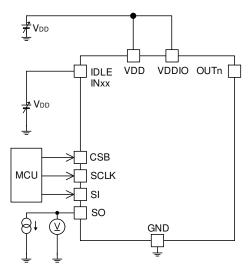


Figure 54. SO High/Low Level Output Voltage

### Measurement Circuit - continued

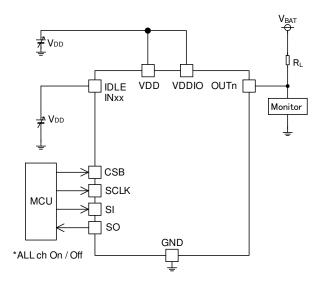


Figure 55. Slew Rate (On/Off) 1, 2, 3 Turn-On/Off Time 1, 2, 3

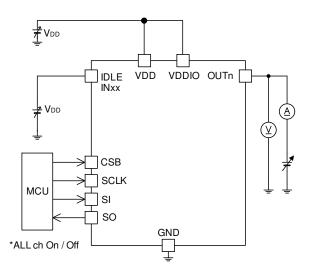


Figure 56. Open Load Detect/Release Voltage
Output Sink Current
Output Overhead Detect/Release Voltage
Short Ground Detect/Release Voltage
Output Source Current
Over Current Threshold Value 1, 2
Output Stop Time at OCP Detection

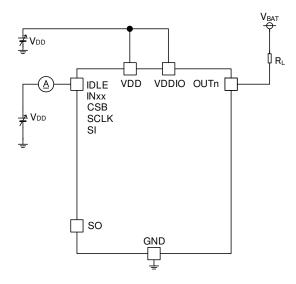
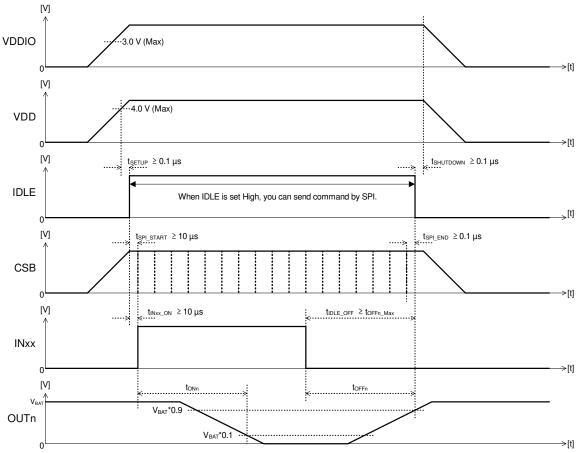


Figure 57. Low Level Input Voltage
High Level Input Voltage
Input Hysteresis Voltage
High Level Input Current 1, 2

# **Timing Chart**

The following shows the sequence when H is input to the IDLE pin after the power is supplied. "xx" denotes each input (21, 43, 65), and n denotes the channel number.



(Supplement) About Each Symbol

tsetup: Time from VDDIO and VDD reaches operating voltage until H can be input to IDLE.

 $t_{\text{SPI\_START}}. \label{eq:tspi_start} \text{ Time from H is input to IDLE until SPI communication is available}.$ 

 $t_{\text{INxx\_ON}}$ : Time from H is input to IDLE until control by INxx is available.

 $t_{SPI\_END}$ : Time from completion of SPI communication until L is input L to IDLE (Note 1).

t<sub>IDLE\_OFF</sub>: Time from end of control by INxx until input L to IDLE.

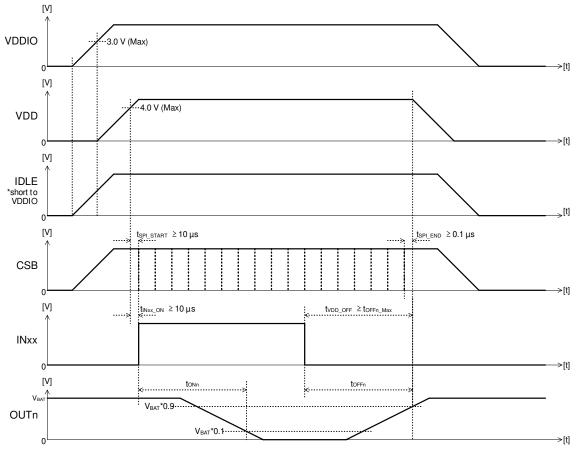
t<sub>ONn</sub>: Turn-On time t<sub>OFFn</sub>: Turn-Off time

toffn\_Max: Turn-Off Time (Max)

 $t_{\text{SHUTDOWN}} : \text{Time from input L to IDLE until VDDIO and VDD are turned off.} \\ \textit{(Note 1)} \text{ If using SPI control to turn off low side SW, wait } t_{\text{IDLE\_OFF}} \text{ before inputting L to IDLE.} \\$ 

# Timing Chart - continued

The following shows the sequence when the VDDIO and IDLE pins are simultaneously turned on/off. "xx" denotes each input (21, 43, 65), and n denotes the channel number.



(Supplement) About Each Symbol

 $t_{\text{SPI\_START}}$ : Time from H is input to IDLE until SPI communication is available.

 $t_{\text{INxx\_ON}} \hspace{-0.5em}\text{.} \hspace{-0.5em} \text{Time from VDD reaches operating voltage until control by INxx is available}.$ 

t<sub>SPI\_END</sub>: Time from completion of SPI communication until lowering VDD<sup>(Note 1)</sup>.

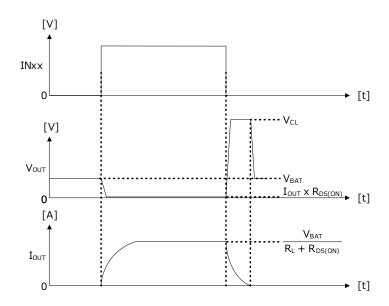
t<sub>VDD OFF</sub>: Time from end of control by INxx until lowering VDD.

 $t_{\text{ONn}}$ : Turn-On time  $t_{\text{OFFn}}$ : Turn-Off time

 $t_{\mathsf{OFFn\_Max}}$ : Turn-Off time (Max)

(Note 1) If using SPI control to turn off low side SW, wait t<sub>VDD\_OFF</sub> before lowering VDD.

# Inductive Load Operation



# **Synchro Mode**

Two adjacent output pins can be connected in parallel. Parallel connection is available by combining OUT1/OUT2, OUT3/OUT4, OUT5/OUT6, OUT7/OUT8. The synchro mode can be set by SPI. For details, refer to "Register Map".

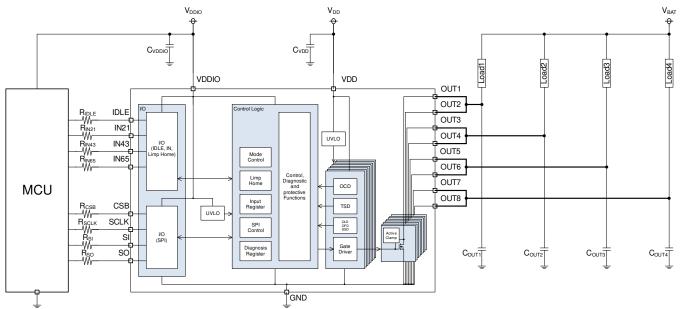
When controlling by IN21/IN43/IN65, channels connected in parallel are driven simultaneously.

All control by SPI is set from the odd number channel, and the even number channel setting is ignored. For example, to turn on OUT1/OUT2, write "1" to OUTCTRL1 bit of OUTCTRL register. Writing to OUTCTRL2 bit is ignored.

Over current protection and thermal shutdown is active on each channel connected in parallel, and both channels are turned off when protection is detected in either channel.

The detection of protection can be read from SPI by accessing DIAG\_OUT4321 or DIAG\_OUT8765 registers.

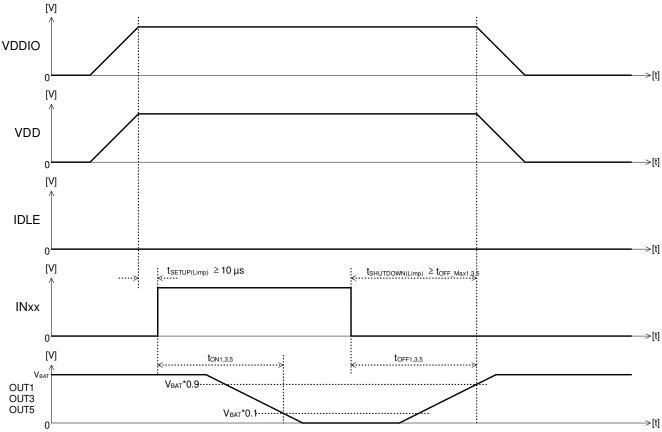
The error flag is output from the odd number channel and the error flag of the even number channel is fixed to "0". For example, if over current protection is detected in OUT1/OUT2, "1" is output from DIAG\_OCP1 bit of DIAG\_OUT4321 register, and DIAG\_OCP2 bit outputs "0".



Caution: Differences in wire impedance between two neighboring outputs may affect characteristics such as turn-On/Off, slew rate, over current threshold value, and active clamp energy. To avoid this, it is recommended to short output pin with near the IC as possible.

# **Limp Home Mode**

When IDLE is set to L, the IC enters Limp Home mode. This mode enables operation with low current consumption. Control by SPI is not possible in this mode, but on/off control by IN21/IN43/IN65 is available. Controllable channels are limited to odd number channels (1ch, 3ch, 5ch). When IDLE becomes L, the register is cleared and returns to the default setting. The timing chart in Limp Home mode is shown below.



(Supplement) About Each Symbol

t<sub>SETUP(Limp)</sub>: Time from VDDIO and VDD reaches operating voltage until control by INxx is available.

 $t_{\text{ON1,3,5}}$ : Turn-On time  $t_{\text{OFF1,3,5}}$ : Turn-Off time

toff\_Max1,3,5: Turn-Off time (Max)

 $t_{SHUTDOWN(Limp)}\!\!: Time \ from \ all \ INxx \ is \ set \ to \ L \ until \ VDDIO \ and \ VDD \ are \ turned \ off.$ 

# **SPI Specification**

SPI overview

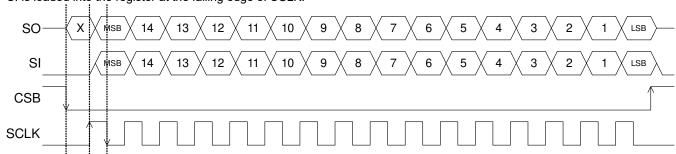
When CSB = H

SO is High-Z.

When CSB = L

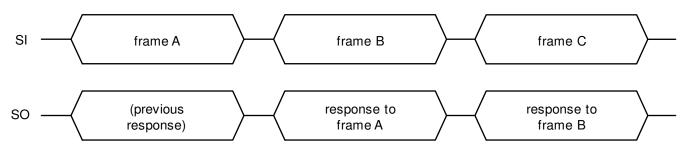
Outputs to SO at the rising edge of SCLK.

SI is loaded into the register at the falling edge of SCLK.



SPI protocol

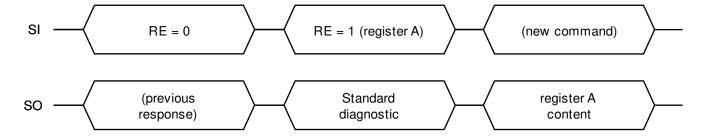
The SO response to SPI access is returned at the next SPI access as shown in the following figure.



·Response when accessing with RE = 0 and with RE = 1

When accessing with RE = 0, respond "Standard diagnostic".

When accessing with RE = 1, respond the value of the specified register.

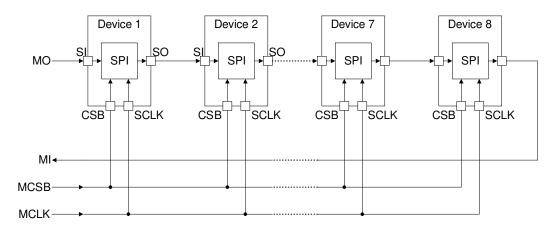


# SPI Specification - continued

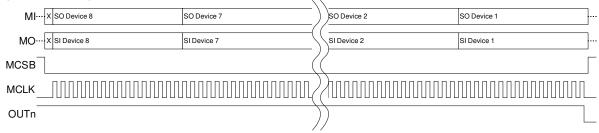
Serial Daisy Chain

Multiple devices can be connected in series as shown below.

For CSB signal and SCLK signal, connect a common signal. About SI / SO line, SO of Device 1 can be connected to SI of Device 2 as shown below.



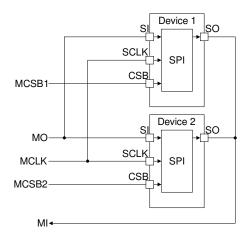
The timing chart when eight devices are connected is shown below.



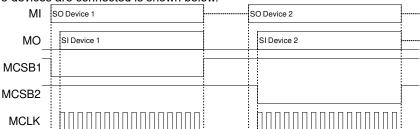
## **Parallel Connection**

Multiple devices can be connected in parallel as shown below.

For SI signal, SCLK signal, and SO signal, connect a common signal. Separate signals are required for the CSB signal for each device.

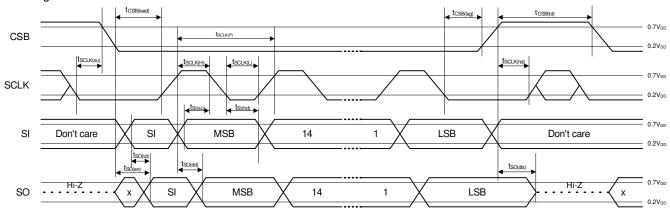


The timing chart when two devices are connected is shown below.



# SPI Specification - continued

SPI Timing chart



Parameter	Symbol	Min	Тур	Max	Unit
SCLK Frequency	f <sub>SCLK</sub>	0	-	5	MHz
SCLK Period	tsclk(P)	200	-	-	ns
SCLK High Time	tsclk(H)	50	-	-	ns
SCLK Low Time	t <sub>SCLK(L)</sub>	50	-	-	ns
SCLK Setup Time	tsclK(su)	50	-	-	ns
SCLK Hold Time	tsclK(hd)	50	-	-	ns
CSB Lead Time	$t_{\text{CSB(lead)}}$	250	-	-	ns
CSB Lag Time	t <sub>CSB(lag)</sub>	250	-	-	ns
Transfer Delay Time	t <sub>CSB(td)</sub>	250	-	-	ns
Data Setup Time	$t_{SI(su)}$	20	-	-	ns
Data Hold Time	t <sub>SI(hd)</sub>	20	-	-	ns
SPI Output Enable Time <sup>(Note 1)</sup>	t <sub>SO(en)</sub>	-	-	200	ns
SPI Output Disable Time <sup>(Note 1)</sup>	t <sub>SO(dis)</sub>	-	-	250	ns
SPI Output Data Delay Time(Note 1)(Note 2)	tso(dd)	-	-	100	ns
ERR Output Through Delay Time(Note 1)	t <sub>SO(td)</sub>	-	-	200	ns

(Note 1) Not 100 % tested. (Note 2) SO capacitance = 20 pF

## SPI Specification - continued

SI data structure

Bit[15]	Bit[14]	Bit[13]	Bit[12]	Bit[11]	Bit[10]	Bit[9]	Bit[8]	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
RE	WE				TEST	Data									

#### RE

0: SO outputs "Standard diagnostic" at the next SPI access.

1: SO outputs the register specified by Address at the next SPI access.

#### WF

0: Not Write.

1: Write.

#### **TEST**

Be sure to set 0.

#### Data

When WE = 1, various settings are enabled by writing '0' or '1' to Data.

For details, refer to "Register Map".

"Standard diagnostic" (when RE = 0 in the previous SPI access)

### Initial Value 0x4000

Bit[15]	Bit[14]	Bit[13]	Bit[12]	Bit[11]	Bit[10]	Bit[9]	Bit[8]	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
0	INIT	0	0	0	TER	0	0	ERR8	ERR7	ERR6	ERR5	ERR4	ERR3	ERR2	ERR1

#### INIT

- 0: Normal (after power on or IDLE = 'L'->'H', from the second time SPI access).
- 1: After power on or IDLE = 'L'->'H', first time SPI access.

### **TER**

- 0: Normal
- 1: SPI communication error

When High pulse input of SCLK is other than (16 times + 8 x m, m is an integer 0 or above) in the low level section of CSB, a communication error is judged.

# ERRn (n is the channel number)

- 0: Normal
- 1: The value is latched and output when over current protection or thermal shutdown of the corresponding channel is detected. This bit is cleared by reading DIAG register (DIAG\_OUT4321 or DIAG\_OUT8765) of the channel on which protection is detected.

SO output data structure (when RE = 1 in the previous SPI access)

Bit[15]	Bit[14]	Bit[13]	Bit[12]	Bit[11]	Bit[10]	Bit[9]	Bit[8]	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
1 1	WE					ERRALL	Data								

## WE, Address

Outputs WE and Address values that were set during the previous SPI access.

### FRR

Outputs 1 when either over current protection or thermal shutdown of OUT is detected on at least one channel.

### Data

Outputs the register value of Address that were set during the previous SPI access.

**Register Map** 

D	Register	Address	TEST	Data									
Register Name	Access	Bit[13:9]	Bit[8]	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]	Initial	
OUTCTRL	R/W	0x00	0	OUTCTRL8	OUTCTRL7	OUTCTRL6	OUTCTRL5	OUTCTRL4	OUTCTRL3	OUTCTRL2	OUTCTRL1	0x00	
SRCTRL0	R/W	0x01	0	SRCTRL4[1:0]		SRCTRL3[1:0]		SRCTRL2[1:0]		SRCTRL1[1:0]		0x00	
SRCTRL1	R/W	0x02	0	SRCTRL8[1:0]		SRCTRL7[1:0]		SRCTF	RL6[1:0]	SRCTF	0x00		
OCPCTRL	R/W	0x03	0	OCPCTRL8	OCPCTRL7	OCPCTRL6	OCPCTRL5	OCPCTRL4	OCPCTRL3	OCPCTRL2	OCPCTRL1	0x00	
DIRCTRL	R/W	0x04	0	0	1	DIRCTRL6	DIRCTRL5	DIRCTRL4	DIRCTRL3	DIRCTRL2	DIRCTRL1	0x55	
SYNC	R/W	0x05	0	0	0	0	0	SYNC87	SYNC65	SYNC43	SYNC21	0x00	
STATUS_IN	RO	0x06	0	0	0	0	0	0	STATUS_IN65	STATUS_IN43	STATUS_IN21	0x00	
DIAG_OLD/OFD	R/W	0x08	0	DIAG_OLD/OFD8	DIAG_OLD/OFD7	DIAG_OLD/OFD6	DIAG_OLD/OFD5	DIAG_OLD/OFD4	DIAG_OLD/OFD3	DIAG_OLD/OFD2	DIAG_OLD/OFD1	0x00	
DIAG_SGD	R/W	0x09	0	DIAG_SGD8	DIAG_SGD7	DIAG_SGD6	DIAG_SGD5	DIAG_SGD4	DIAG_SGD3	DIAG_SGD2	DIAG_SGD1	0x00	
DIAG_OUT4321	RO	0x0A	0	DIAG_OCP4	DIAG_TSD4	DIAG_OCP3	DIAG_TSD3	DIAG_OCP2	DIAG_TSD2	DIAG_OCP1	DIAG_TSD1	0x00	
DIAG_OUT8765	RO	0x0B	0	DIAG_OCP8	DIAG_TSD8	DIAG_OCP7	DIAG_TSD7	DIAG_OCP6	DIAG_TSD6	DIAG_OCP5	DIAG_TSD5	0x00	
HWCR	wo	0x0C	0	0	RST	0	0	0	0	0	0	0x00	
T_TESTMODE	wo	0x1E	1	0	0	0	0	0	0	0	TESTMODE	0x00	

Register Name	Register Access	Address	Explanation of Data
OUTCTRL	Read / Write	0x00h	OUTCTRLn bit (n represents the channel number) '0': OUTn off setting '1': OUTn on setting
SRCTRL0 SRCTRL1	Read / Write	0x01h 0x02h	SRCTRLn[1:0] bit '00': Slew Rate Setting 1.0 V/µs (Typ) '01': Slew Rate Setting 2.25 V/µs (Typ) '10': Slew Rate Setting 0.30 V/µs (Typ) '11': Same setting as '00'
OCPCTRL	Read / Write	0x03h	OCPCTRLn bit '0': Over Current Threshold Value 1 0.85 A (Typ) '1': Over Current Threshold Value 2 1.7 A (Typ)
DIRCTRL	Read / Write	0x04h	DIRCTRLn bit '0': IN control disabled '1': IN control enabled
SYNC	Read / Write	0x05h	SYNC21/SYNC43/SYNC65/SYNC87 bit '0': Synchro mode disabled '1': Synchro mode enabled
STATUS_IN	Read Only	0x06h	STATUS_IN65/STATUS_IN43/STATUS_IN21 bit '0': IN87/IN65/IN43/IN21 L input '1': IN87/IN65/IN43/IN21 H input
DIAG_OLD/OFD	Read / Write	0x08h	DIAG_OLD/OFDn bit  '0': OLD/OFD disabled '1': OLD/OFD enabled  OLD is enabled when OUTn is off. OFD is enabled when OUTn is on. When SPI access is performed again, it automatically returns to '0' (disabled).  Read OLD/OFD result by read access (RE = 1).  When OLD is active, the judgement is made as below. '0': OLD detection '1': Normal  When OFD is active, the judgement is made as below. '0': Normal '1': OFD detection  For details, refer to "Open Load Detection" and "Output Overhead Fault Detection Function".

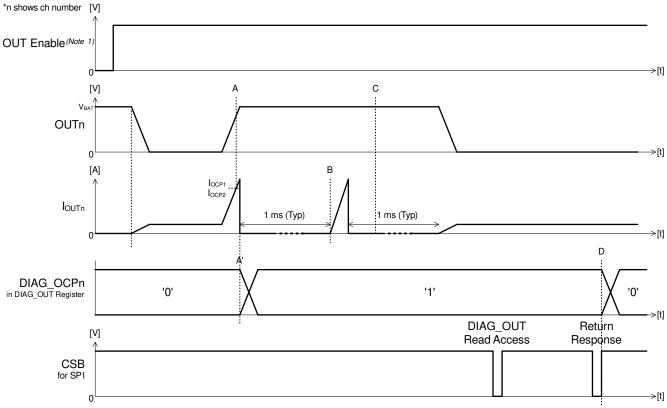
Register Map – continued

ister Map – conti			
Register Name	Register Access	Address	Explanation of Data
DIAG_SGD	Read / Write	0x09h	DIAG_SGDn bit
DIAG_OUT4321	Read Only	0x0Ah	Read the error flag of ch1/ch2/ch3/ch4.  DIAG_TSDn bit  '0': Normal  '1': TSD detection  DIAG_OCPn bit  '0': Normal  '1': OCP detection  It automatically returns to '0' when DIAG_OUT4321 is accessed.
DIAG_OUT8765	Read Only	0x0Bh	Read the error flag of ch5/ch6/ch7/ch8.  DIAG_TSDn bit  '0': Normal  '1': TSD detection  DIAG_OCPn bit  '0': Normal  '1': OCP detection  It automatically returns to '0' when DIAG_OUT8765 is accessed.
HWCR	Write Only	0x0Ch	RST '0': Normal '1': Hardware reset (auto clear)
T_TESTMODE	Write Only	0x1Eh	TESTMODE  '0': Normal  '1': Test Mode  If IDLE is 5.6 V (Min) or more and "1" is written to this register, IC enters test mode. For this reason, do not access to this register.

### **Over Current Protection Function**

Turns off the output when an over current error occurs in the output (A in the figure). The output returns to on when the output stop time of 1 ms (Typ) has passed. However, if an over current error still continue at this time, the output will be turned off again (B in the figure). When an over current error is improved, the output recovers after the output stop time from over current error is lastly detected has passed (C in the figure).

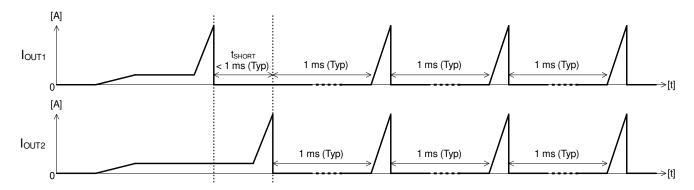
If an over current error is detected, the internal over current detection flag outputs '1' (A' in the figure). This flag can be read from SPI read access or from Standard diagnostic. When the flag is read by SPI read access, it is cleared by the next SPI access after read access (D in the figure).



(Note 1) Output on/off control signal. This signal is controlled by IN65, IN43, IN21 or OUT CTRL register.

When an over current error is detected in multiple channels, the output off time is measured starting from the channel that over current error was detected lastly.

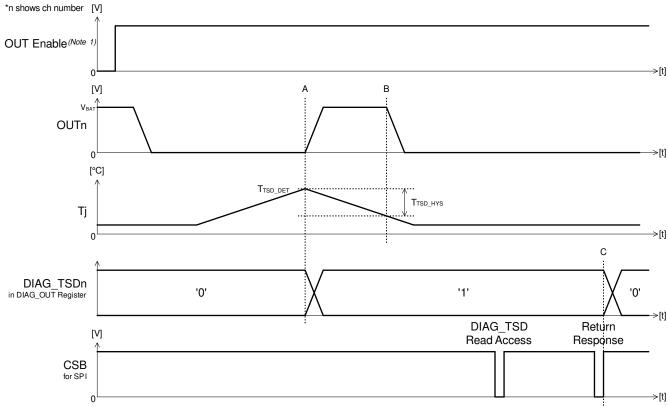
For example, if an over current error is detected in ch2 after an over current error is detected in ch1 before the output off time of ch1 passes, the time t<sub>SHORT</sub> from ch1 detects an error until an error is detected in ch2 will be added to the output off time of ch1.



# **Thermal Shutdown Function**

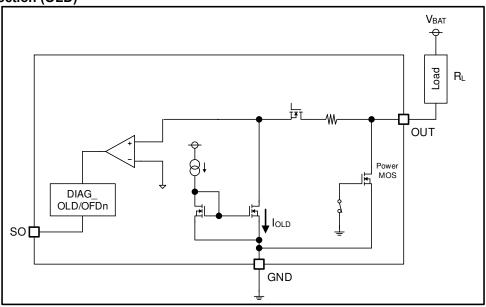
Turns off the output when the junction temperature rises 175 °C (Typ) or above (A in the figure). After that, the output automatically returns to on when the junction temperature falls 160 °C (Typ) or below (B in the figure).

When thermal shutdown is detected, the internal thermal shutdown flag outputs '1' (A in the figure). This flag can be read from SPI read access or Standard diagnostic. When the flag is read by SPI read access, it is cleared by the next SPI access after read access (C in the figure).



(Note 1) Output on/off control signal. This signal is controlled by IN65, IN43, IN21 or OUT\_CTRL register.

**Open Load Detection (OLD)** 



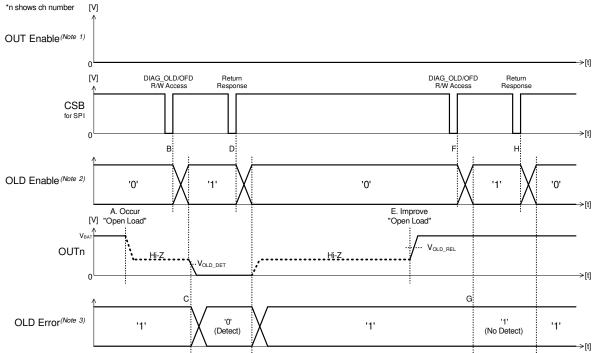
When OLD is enabled, output sink current IOLD flows from OUT. The output voltage VOUT drops when the load RL increases, and it is detected as OLD when it becomes  $V_{\text{OLD DET}}$  or less. R<sub>L</sub> for detecting OLDs is given by the following equation:

$$R_L \ge \frac{V_{BAT} - V_{OLD\_DET}}{I_{OLD}}$$

V<sub>BAT</sub>: Battery voltage

Vol.D\_DET: Open load detection voltage 3.2 V (Max) lo\_D: Output sink current when OLD function is active 90 μA (Max)

When the output is off, OLD can be enabled and diagnosed by one SPI access of write and read access (RE = 1, WE = 1) to DIAG OLD/OFD register (B, F in the figure). Diagnostic is output to SO at the next SPI access (D, H in the figure). At this time, OLD returns to inactive (D, H in the figure). When OUTn voltage is VolD\_DET or less, OLD is diagnosed as detected and the error flag inside the IC outputs "0" (C in the figure). If OUTn voltage is Vold ReL or more, OLD is diagnosed as undetected and the error flag output '1' (G in the figure).

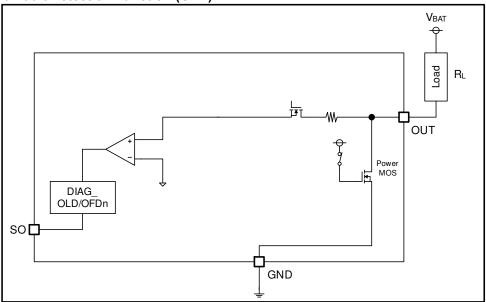


(Note 1) Output on/off control signal. This signal is controlled by IN65, IN43, IN21 or OUT\_CTRL register.

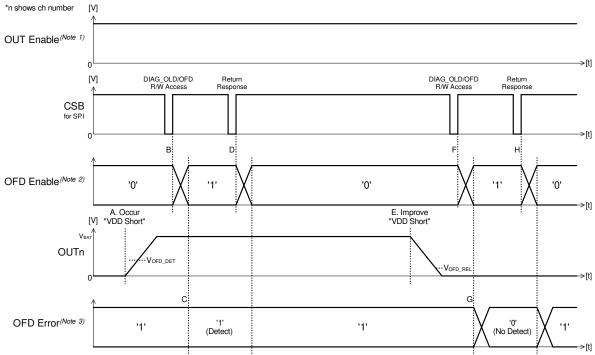
(Note 3) Internal enable signal. High and Low indicates enabled and disabled, respectively. This signal is controlled by write access to DIAG\_OLD/OFD register.

(Note 3) Internal enable signal. High and Low indicates enabled and disabled, respectively. Also the flag outputs High during disable. This signal can be retrieved to SO by read access to DIAG\_OLD/OFD register.

**Output Overhead Fault Detection Function (OFD)** 

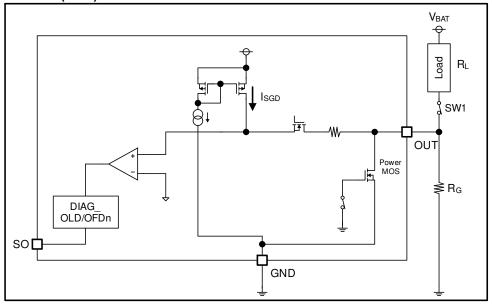


When the output is on, OFD can be enabled and diagnosed by one SPI access by write and read access (RE = 1, WE = 1) to DIAG\_OLD/OFD register (B, F in the figure). Diagnostic is output to SO at the next SPI access (D, H in the figure). At this time, OFD returns to be inactive (D, H in the figure). When OUTn voltage is  $V_{OFD\_DET}$  or more, OFD is diagnosed as detected and the error flag inside the IC outputs "1" (C in the figure). If OUTn voltage is  $V_{OFD\_REL}$  or less, OFD is diagnosed as undetected and the error flag output '0' (G in the figure).



(Note 1) Output on/off control signal. High and Low indicates on and off, respectively. This signal is controlled by IN65, IN43, IN21 or OUT\_CTRL register. (Note 2) Internal enable signal. High and Low indicates enabled and disabled, respectively. This signal is controlled by write access to DIAG\_OLD/OFD register. (Note 3) Internal error flag. High and Low indicates error detected and undetected, respectively. Also the flag outputs High during disable. This signal can be retrieved to SO by read access to DIAG\_OLD/OFD register.

**Short Ground Detection (SGD)** 



·When normal load is connected (SW1 is on)

The output voltage  $V_{OUT}$  is determined by the divided voltage between  $R_L$  (normal load) and  $R_G$  (OUT-GND impedance) and it is detected as SGD when  $V_{OUT}$  is  $V_{SGD\_DET}$  or less.

R<sub>G</sub> for detecting SGD is given roughly by the following equation.

$$R_G \le \frac{V_{SGD\_DET}}{V_{BAT} - V_{SGD\_DET}} * R_L$$

V<sub>BAT</sub>: Battery voltage

V<sub>SGD\_DET</sub>: Short ground detection voltage 0.3 V (Min)

·When the load is open (SW1 is off)

The output voltage  $\dot{V}_{\text{OUT}}$  is obtained from output source current I<sub>SGD</sub> that flows into R<sub>G</sub> and it is detected as SGD when V<sub>OUT</sub> is V<sub>SGD\_DET</sub> or less.

R<sub>G</sub> for detecting SGD is given by the following equation.

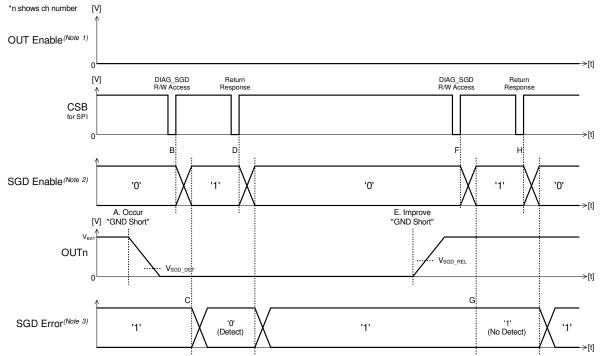
 $R_G \leq \frac{V_{SGD\_DET}}{I_{SGD}}$ 

 $V_{\text{SGD\_DET}}\!\!:$  Short ground detection voltage 0.3 V (Min)

I<sub>SGD</sub>: Output source current when SGD function is active 40 µA (Max)

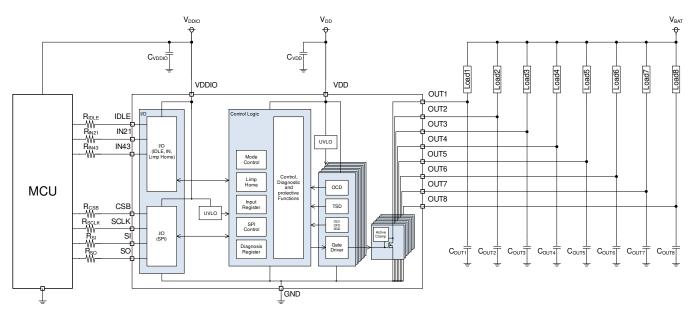
# Short Ground Detection (SGD) - continued

When the output is off, SGD can be enabled and diagnosed by one SPI access of write and read access (RE = 1, WE = 1) to DIAG\_SGD register (B, F in the figure). Diagnostic is output to SO at the next SPI access. At this time, SGD returns to be inactive (D, H in the figure). When OUTn voltage is V<sub>SGD\_DET</sub> or less, SGD is diagnosed as detected and the error flag inside the IC outputs "0" (C in the figure). If OUTn voltage is V<sub>SGD\_REL</sub> or more, SGD is diagnosed as undetected and the error flag output '1' (G in the figure).



(Note 1) Output on/off control signal. This signal is controlled by IN65, IN43, IN21 or OUT\_CTRL register.
(Note 2) Internal enable signal. High and Low indicates enabled and disabled, respectively. This signal is controlled by write access to DIAG\_SGD register.
(Note 3) Internal error flag. High and Low indicates error undetected and detected, respectively. Also the flag outputs High during disable. This signal can be retrieved to SO by read access to DIAG\_SGD register.

# **Application Example**



# **Selection of Components Externally Connected**

Symbol	Value	Purpose
R <sub>IDLE</sub>	1 kΩ	Register for microcontroller protection against negative voltage surge
R <sub>IN21</sub> , R <sub>IN43</sub> , R <sub>IN65</sub>	1 kΩ	Register for microcontroller protection against negative voltage surge
R <sub>CSB</sub> , R <sub>SCLK</sub> , R <sub>SI</sub> , R <sub>SO</sub>	1 kΩ	Register for microcontroller protection against negative voltage surge
CVDDIO, CVDD	0.1 µF	Capacitor for noise removal on the power supply line
C <sub>OUT1</sub> to C <sub>OUT8</sub>	0.1 µF	Capacitor for ESD surge and BCI protection

As a precaution in selecting a  $C_{OUT}$ , current flows from the capacitor when the switch is turned on. Depending on the capacitance, over current protection may be detected. This current depends on the slew rate setting, over current protection setting, and  $V_{BAT}$  voltage. As a reference, capacitance that can be used with  $V_{BAT}$  = 18 V without over current protection when the switch is turned on is shown in the below table.

V <sub>BAT</sub> = 18 V		
Slew Rate setting	Over Current Protection	Capacitance value that over current protection
Siew Rate setting	setting	is not detected (Max)
SDCTDI = [4:0] = 00	OCPCTRLn = 0	0.22 μF
SRCTRLn[1:0] = 00	OCPCTRLn = 1	0.22 μF
SRCTRLn[1:0] = 01	OCPCTRLn = 0	0.47 μF
SKCTKLII[1.0] = 01	OCPCTRLn = 1	0.83 μF
SDCTDI n[1:0] = 10	OCPCTRLn = 0	0.68 μF
SRCTRLn[1:0] = 10	OCPCTRLn = 1	1.5 μF

I/O

Equivalence C		
Pin No.	Pin Name	I/O Equivalence Circuit
1	IDLE	VDDIO Σ  100 kΩ  100 kΩ  GND
2	CSB	VDDIO ⊠ \$100 kΩ 1 kΩ GND
3, 4 16 to 18	SCLK SI IN65 IN43 IN21	SCLK SI IN65 IN43 IN21
5	SO	VDDIO S
6, 15	GND	-
7 to 14	OUT1 to OUT8	OUT1 to OUT8
19	VDD	-
20	VDDIO	

## **Operational Notes**

## 1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

# 2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

#### 3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

## 4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

#### 5. Recommended Operating Conditions

The function and operation of the IC are guaranteed within the range specified by the recommended operating conditions. The characteristic values are guaranteed only under the conditions of each item specified by the electrical characteristics.

#### 6. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

#### 7. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

## 8. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

## 9. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

# Operational Notes - continued

# 10. Regarding the Input and Output Pins of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode. When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

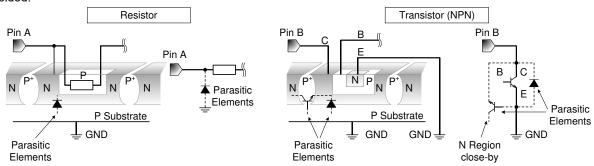


Figure 58. Example of Monolithic IC Structure

# 11. Ceramic Capacitor

When using a ceramic capacitor, determine a capacitance value considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

## 12. Thermal Shutdown Function (TSD)

This IC has a built-in thermal shutdown function that prevents heat damage to the IC. Normal operation should always be within the IC's maximum junction temperature rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD function that will turn OFF power output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD function operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD function be used in a set design or for any purpose other than protecting the IC from heat damage.

#### 13. Over Current Protection Function (OCP)

This IC incorporates an integrated overcurrent protection function that is activated when the load is shorted. This protection function is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection function.

# 14. Active Clamp Operation

The IC integrates the active clamp function to internally absorb the reverse energy  $E_L$  which is generated when the inductive load is turned off. When the active clamp operates, the thermal shutdown function does not work. Decide a load so that the reverse energy  $E_L$  is active clamp tolerance  $E_{AS}$  (refer to Figure 1.),  $E_{S,AS}$  (refer to Figure 2.) or under when inductive load is used.

# Operational Notes - continued

# 15. Power Supply Steep Fluctuation

If the voltage of the power supply pin (VDD) falls sharply, the output pin (OUT) may temporarily turn off as shown in Figure 55. If the power supply pin is expected to fall sharply, take measures such as inserting a capacitor between the power supply pin and the ground pin so that it falls within the recommended usage range shown in Figure 56.

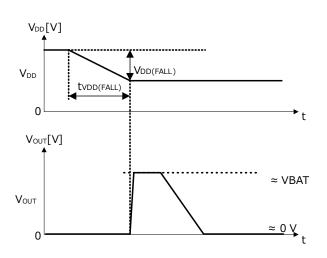


Figure 59. Output OFF operation when power supply fluctuates sharply

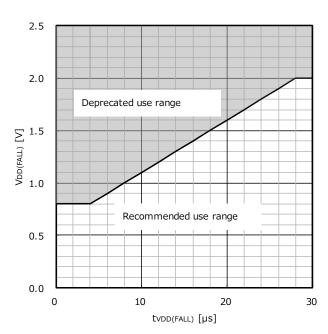
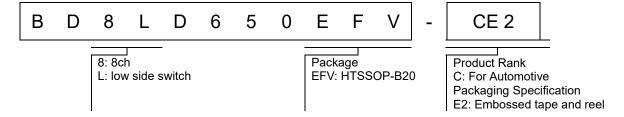


Figure 60. Recommended use range

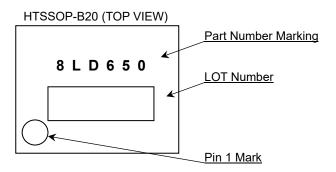
#### 16. GND Pin Connection

Connect all ground pins to ground.

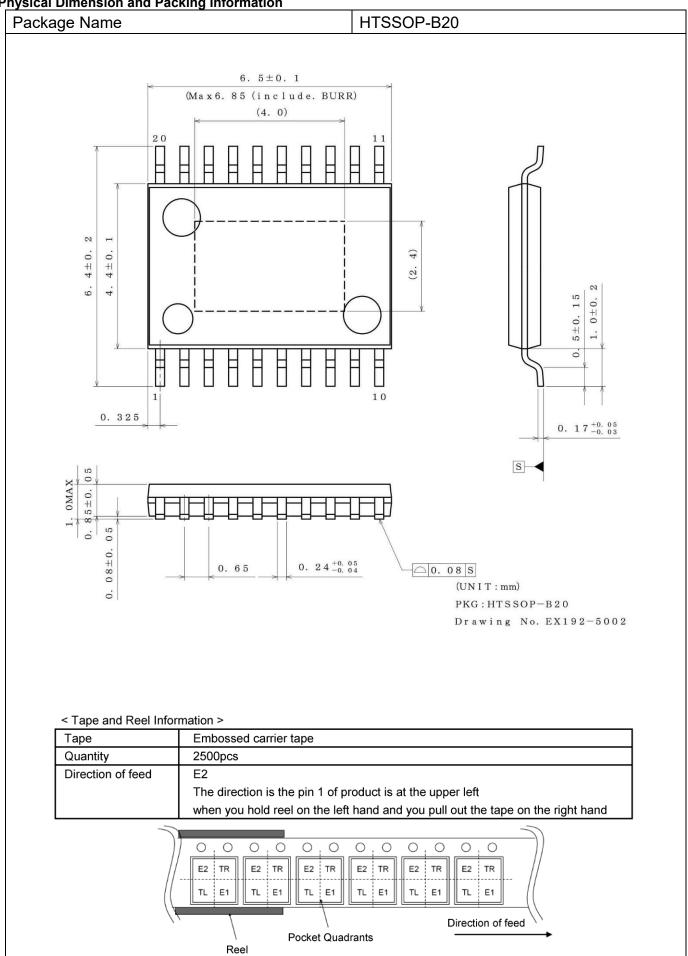
# **Ordering Information**



# **Marking Diagram**



**Physical Dimension and Packing Information** 



**Revision History** 

Date	Revision	Changes
26.Aug.2022	001	New Release

# **Notice**

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1. If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment (Note 1), aircraft/spacecraft, nuclear power controllers, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

( roto : ) modica: =qa.pon: olasomodis: ol ino opesino i ippiisanone				
JAPAN	USA	EU	CHINA	
CLASSⅢ	CLASSⅢ	CLASSIIb	CLASSⅢ	
CLASSIV	CLASSIII	CLASSⅢ	CLASSIII	

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  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (Exclude cases where no-clean type fluxes is used. However, recommend sufficiently about the residue.); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse, is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

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For details, please refer to ROHM Mounting specification

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- 1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
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This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

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  - [b] the temperature or humidity exceeds those recommended by ROHM
  - [c] the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
- Even under ROHM recommended storage condition, solderability of products out of recommended storage time period
  may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is
  exceeding the recommended storage time period.
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- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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