

SR1

### 4 pin Smart Reset™

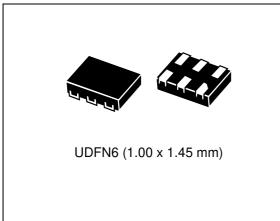
**Applications** 

Activity tracker Smartwatch Smartglasses

Wearable

•

Datasheet - production data



# Features

- Operating voltage range 2 V to 5.5 V
- Low supply current 1 μA
- Integrated test mode
- Single Smart Reset<sup>™</sup> push-button input with fixed extended reset setup delay (t<sub>SRC</sub>) from 0.5 s to 10 s in 0.5 s steps (typ.), option with internal input pull-up resistor
- Push-button controlled reset pulse duration
  - Option 1: fully push-button controlled, no fixed or minimum pulse width guaranteed
  - Option 2: defined output reset pulse duration (t<sub>REC</sub>), factory-programmed
- Single reset output
  - Active low or active high
  - Push-pull or open drain with optional pullup resistor
- Fixed Smart Reset input logic voltage levels
- Operating temperature: -40 °C to +85 °C
- UDFN6 package 1.00 mm x 1.45 mm
- ECOPACK<sup>®</sup>2 (RoHS compliant, Halogen-Free)

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#### 1 Description

The Smart Reset<sup>TM</sup> devices provide a useful feature which ensures that inadvertent short reset push-button closures do not cause system resets. This is done by implementing an extended Smart Reset input delay time ( $t_{SRC}$ ), which ensures a safe reset and eliminates the need for a specific dedicated reset button.

This reset configuration provides versatility and allows the application to distinguish between a software generated interrupt and a hard system reset. When the input push-button is connected to the microcontroller interrupt input, and is closed for a short time, the processor can only be interrupted. If the system still does not respond properly, continuing to keep the push-button closed for the extended setup time  $t_{SRC}$  causes a hard reset of the processor through the reset output.

The SR1 has one Smart Reset input ( $\overline{SR}$ ) with preset delayed Smart Reset setup time ( $t_{SRC}$ ). The reset output ( $\overline{RST}$ ) is asserted after the Smart Reset input is held active for the selected  $t_{SRC}$  delay time. The RST output remains asserted either until the  $\overline{SR}$  input goes to inactive logic level (i.e. neither fixed nor minimum reset pulse width is set) or the output reset pulse duration is fixed for  $t_{REC}$  (i.e. factory-programmed). The device fully operates over a broad  $V_{CC}$  range from 2.0 V to 5.5 V.

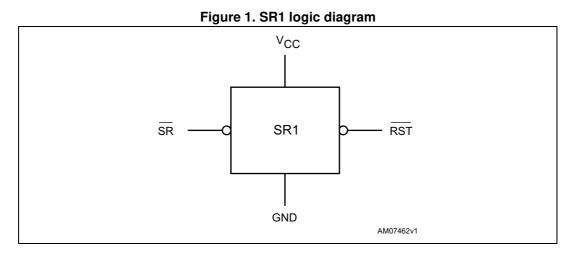
#### 1.1 Test mode

After pulling SR up to V<sub>TEST</sub> (V<sub>CC</sub> + 1.4 V) or above, the counter starts to count the initial shortened t<sub>SRC-INI</sub> (42 ms, typ.). After t<sub>SRC-INI</sub> expires, the RST output either goes down for t<sub>REC</sub> (if t<sub>REC</sub> option is used) or stays low as long as overvoltage on SR is detected (if t<sub>REC</sub> option is not used). This is feedback, and the user only knows that the device is locked in test mode. Each time the SR input is connected to ground in test mode, a shortened t<sub>SRC-SHORT</sub> (t<sub>SRC</sub>/128) is used instead of regular t<sub>SRC</sub> (0.5 s - 10 s). In this way the device can be quickly tested without repeating test mode triggering. Return to normal mode is possible by performing a new startup of the device (i.e. V<sub>CC</sub> goes to 0 V and back to its original state).

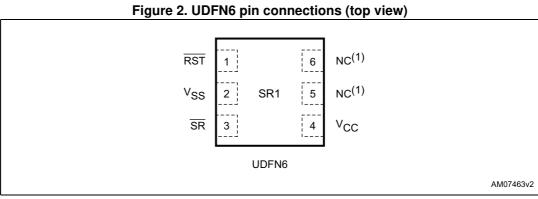
The advantages of this solution are its high glitch immunity, user feedback regarding entry into test mode, and testability within the full  $V_{CC}$  range.



### 1.2 Logic diagram



#### 1.3 Pin connections



1. Not connected (not bonded); should be connected to V<sub>SS</sub>.

SR1

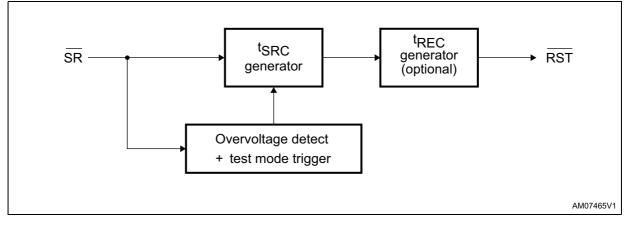


# 2 Device overview

Pin n°	Name	Туре	Description			
1	RST	Output	Reset output, active low, open drain.			
2	V <sub>SS</sub>	Supply ground	Ground			
3	SR	Input	Smart Reset input, active low.			
4	V <sub>CC</sub>	Supply voltage	Positive supply voltage for the device. A 0.1 $\mu F$ decoupling ceramic capacitor is recommended to be connected between $V_{CC}$ and $V_{SS}$ pins.			
5	NC	-	Not connected (not bonded); should be connected to $\ensuremath{V_{SS}}\xspace$			
6	NC	-	Not connected (not bonded); should be connected to $\ensuremath{V_{SS}}\xspace$			

Table	1	Signal	names
Iable		Jigilai	Hames

#### Figure 3. SR1 block diagram





### 3 Pin descriptions

#### 3.1 Power supply (V<sub>CC</sub>)

This pin is used to provide power to the Smart Reset device. A 0.1  $\mu F$  ceramic decoupling capacitor is recommended to be connected between the V<sub>CC</sub> and V<sub>SS</sub> pins, as close to the SR1 device as possible.

#### 3.2 Power-up sequence

In normal mode, if different input side ( $\overline{SR}$ ) and V<sub>CC</sub> voltage domains are used, power-on sequence must avoid meeting the test mode entry condition to avoid inadvertent test mode entry: there should not be logic high present on the  $\overline{SR}$  input before the V<sub>CC</sub> power-up. However V<sub>CC</sub> and V( $\overline{SR}$ ) rising at the same time is OK (e.g. if both are in the same voltage domain), the device will then safely start into normal operating mode, with  $\overline{RST}$  output inactive (in High-Z mode for open-drain option).

#### 3.3 Ground (V<sub>SS</sub>)

This is the ground pin for the device.

#### 3.4 Smart Reset input (SR)

Push-button Smart Reset input, active low with optional <u>pull-up</u> resistor.  $\overline{SR}$  input needs to be asserted for at least t<sub>SRC</sub> to assert the reset output (RST).

By connecting a voltage higher than  $V_{CC}$  + 1.4 V to the  $\overline{SR}$  input the device enters test mode (see *Section 1: Description on page 3* for more information).

#### 3.5 Reset output (RST)

RST is active low or active high, open drain or push-pull reset output with optional internal pull-up resistor.

Output reset pulse width is optional as follows:

- Neither fixed nor minimum output reset pulse duration (releasing the push-button while reset output is active, causes the output to de-assert)
- Fixed, factory-programmed output reset pulse duration for t<sub>REC</sub> independent on Smart Reset input state.

### 3.6 **RST** output undervoltage behavior (for open-drain option)

High-Z on  $\overline{RST}$  output below the specified operating voltage range is guaranteed at  $V_{CC}$  power-on or in case that valid  $V_{CC}$  dropped while the device was idle, i.e. while both output and input were inactive.



# 4 Typical application diagrams

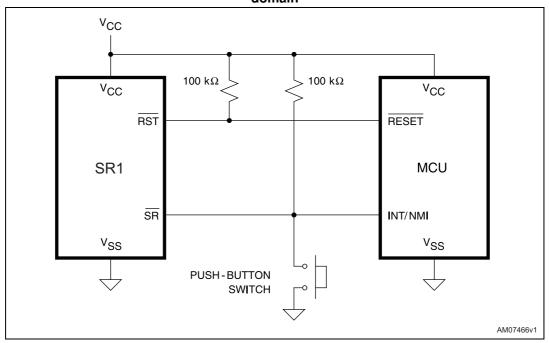
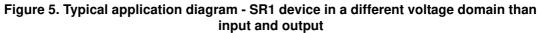
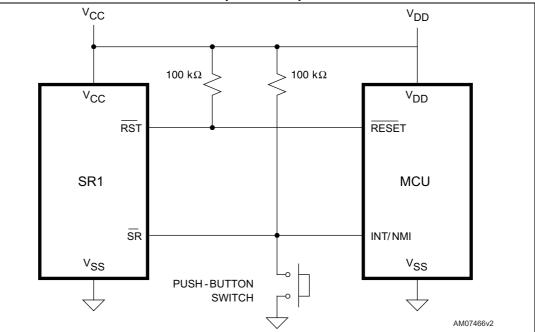


Figure 4. Typical application diagram - input, output and SR1 device in one voltage domain





 Open-drain RST output type and fixed SR input logic threshold allows to use the device in different voltage domains. To prevent entering test mode by creating a condition V(SR) > V<sub>CC</sub> + 1.1 V typ., V<sub>CC</sub> should be powered up before or together with voltage on the SR input.



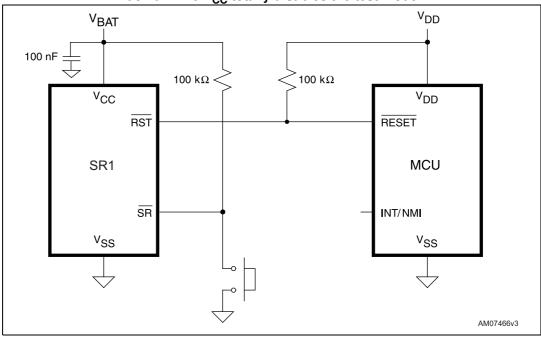


Figure 6. Typical application diagram in different voltage domains - SR input in V<sub>BAT</sub> domain like V<sub>CC</sub> totally disables the test mode



# 5 Timing diagrams

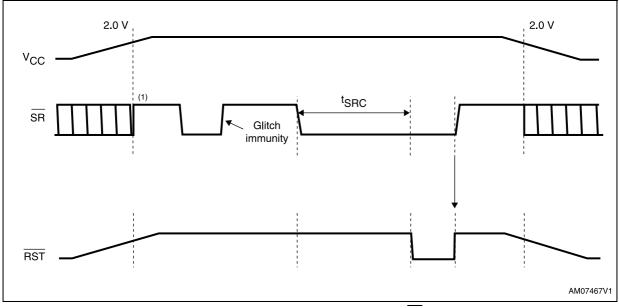
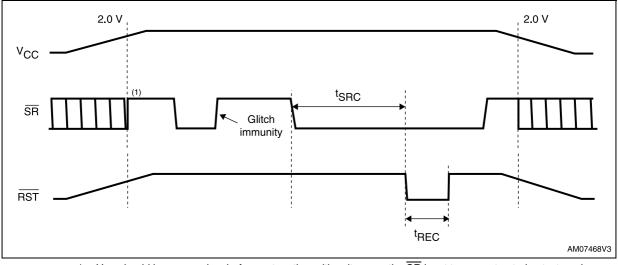


Figure 7. RST output without t<sub>REC</sub> option

1.  $V_{CC}$  should be powered up before or together with voltage on the  $\overline{SR}$  input to prevent entering test mode by creating a condition  $V(\overline{SR}) > V_{CC} + 1.1 V$  typ.

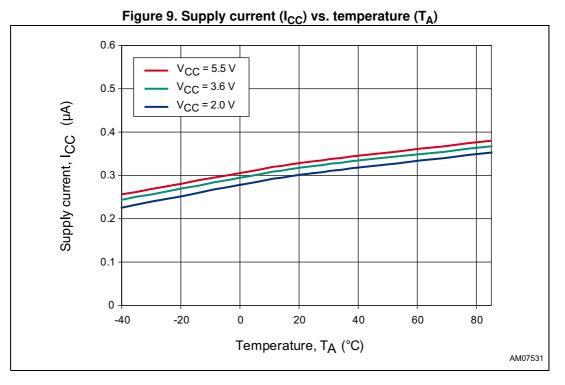




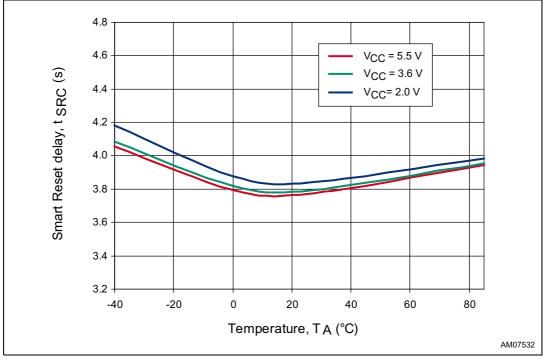
1.  $V_{CC}$  should be powered up before or together with voltage on the  $\overline{SR}$  input to prevent entering test mode by creating a condition  $V(\overline{SR}) > V_{CC} + 1.1$  V typ.



# 6 Typical operating characteristics







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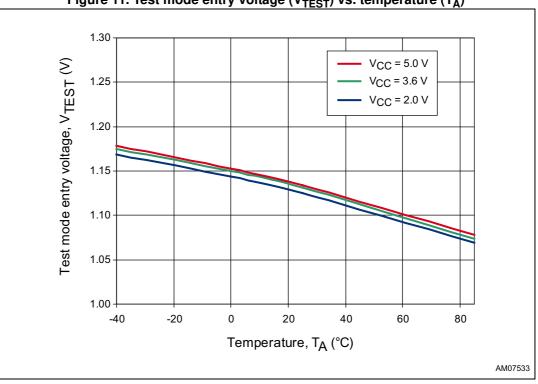


Figure 11. Test mode entry voltage ( $V_{TEST}$ ) vs. temperature ( $T_A$ )

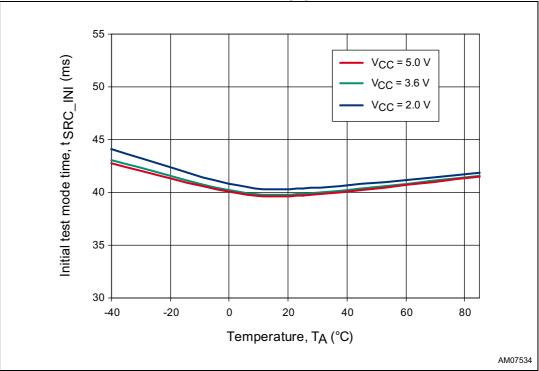


Figure 12. Initial test mode time  $(t_{SRC-INI})$  vs. temperature  $(T_A)$ 



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# 7 Maximum ratings

Stressing the device above the rating listed in *Table 2: Absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in *Table 3: Operating and measurement conditions* of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics<sup>™</sup> SURE program and other relevant quality documents.

Symbol	Parameter	Value	Unit		
T <sub>STG</sub>	Storage temperature (V <sub>CC</sub> off)	-55 to +150	°C		
T <sub>SLD</sub> <sup>(1)</sup>	Lead solder temperature for 10 seconds	260	°C		
V <sub>IO</sub>	Input or output voltage	-0.3 to 5.5	V		
V <sub>CC</sub>	Supply voltage	-0.3 to 7	V		
ESD	ESD				
V <sub>HBM</sub>	Electrostatic discharge protection, human body model (JESD22- A114-B level 2)	2	kV		
V <sub>RCDM</sub>	Electrostatic discharge protection, charged device model, all pins	1	kV		
V <sub>MM</sub>	Electrostatic discharge protection, machine model, all pins (JESD22-A115-A level A)	200	V		
	Latch-up ( $V_{CC}$ pin, $\overline{SR}$ reset input pin)	EIA/JESD78			

Table 2.	Absolute	maximum	ratings
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1. Reflow at peak temperature of 260 °C. The time above 255 °C must not exceed 30 seconds.



### 8 DC and AC parameters

This section summarizes the operating measurement conditions, and the DC and AC characteristics of the device. The parameters in *Table 4: DC and AC characteristics* are derived from tests performed under the measurement conditions summarized in *Table 3: Operating and measurement conditions*. Designers should check that the operating conditions in their circuit match the operating conditions when relying on the quoted parameters.

Symbol	Parameter	Value	Unit
V <sub>CC</sub>	Supply voltage	2.0 to 5.5	V
T <sub>A</sub>	Ambient operating temperature	-40 to +85	°C
t <sub>R</sub> , t <sub>F</sub>	Input rise and fall times	≤ <b>5</b>	ns
	Input pulse voltages	0.2 to 0.8 V <sub>CC</sub>	V
	Input and output timing reference voltages	0.3 to 0.7 V <sub>CC</sub>	V

Table 3. Operating and measurement conditions	5
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Symbol	Parameter	Test conditions <sup>(1)</sup>	Min.	Typ. <sup>(2)</sup>	Max.	Unit
V <sub>CC</sub>	Supply voltage		2.0		5.5	V
I <sub>CC</sub>	Supply current	$\overline{SR} = V_{CC}$ , $t_{REC}$ and $t_{SRC}$ counter is not running		0.4	1.0	μA
		$V_{CC} \ge 4.5 \text{ V}$ , sinking 3.2 mA			0.3	V
V <sub>OL</sub>	Reset output voltage low	$V_{CC} \ge 3.3 \text{ V}$ , sinking 2.5 mA			0.3	V
		$\begin{array}{c c c c c c c c c } \hline 2.0 & 5.5 & V \\ \hline \hline R = V_{CC}, t_{REC} and t_{SRC} \\ ounter is not running & 0.4 & 1.0 & \mu A \\ \hline c_C \ge 4.5 V, sinking 3.2 mA & 0.3 & V \\ \hline c_C \ge 3.3 V, sinking 2.5 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline c_C \ge 2.0 V, sinking 1 mA & 0.3 & V \\ \hline device option) & 65 & k\Omega \\ \hline t_{STT} = 5.5 V, open drain \\ evice option without output \\ ull-up resistor & -0.1 & 0.1 & \mu A \\ \hline mathbf{k} = -40 to +85 ^{\circ}C & 0.8 \times t_{SRC} & t_{SRC} ^{(3)} & \frac{1.2 \times t_{SRC}}{1.1 \times t_{SRC}} & s \\ \hline v_{SS} - 0.3 & 0.3 & V \\ \hline device option) & 65 & 5.5 & V \\ \hline device option) & 65 & k\Omega \\ \hline evice option) & 65 & k\Omega \\ \hline ull-up resistor & -0.1 & 0.1 & \mu A \\ \hline ull-up resistor & -0.1 & 0.1 & \mu A \\ \hline v_{CC} + 0.9 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.1 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & V \\ \hline v_{CC} + 0.4 & V_{CC} + 1.4 & $	V			
t	Reset timeout delay,	(device option)	140	210	280	ms
t <sub>REC</sub>	factory-programmed		240	360	480	ms
R <sub>PUO</sub>	Internal out <u>put p</u> ull-up resistor on RST	(device option)		65		kΩ
I <sub>LO</sub>	Output leakage current	$V_{\overline{RST}} = 5.5 V$ , open drain device option without output pull-up resistor	-0.1		0.1	μA
Smart Rese	t					
	Creart Depart delay	T <sub>A</sub> = -40 to +85 °C	0.8 x t <sub>SRC</sub>	+ (3)	1.2 x t <sub>SRC</sub>	- s
t <sub>SRC</sub>	Smart Reset delay	T <sub>A</sub> = 25 °C	0.9 x t <sub>SRC</sub>	<sup>I</sup> SRC <sup>(*)</sup>	1.1 x t <sub>SRC</sub>	
V <sub>IL</sub>	SR input voltage low		V <sub>SS</sub> -0.3		0.3	V
V <sub>IH</sub>	SR input voltage high		0.85		5.5	V
R <sub>PUI</sub>	Internal inp <u>ut p</u> ull-up resistor on SR	(device option)		65		kΩ
I <sub>LEAK</sub>	SR input leakage current	device option without input pull-up resistor	-0.1		0.1	μA
	Input glitch immunity			t <sub>SRC</sub>		s
est mode			·	·		
V <sub>TEST</sub>	Test mode entry voltage		V <sub>CC</sub> +0.9	V <sub>CC</sub> +1.1	V <sub>CC</sub> +1.4	V
t <sub>SRC-INI</sub>	Initial test mode time		28	42	56	ms
SRC-SHORT	Shortened Smart Reset delay			t <sub>SRC</sub> / 128		ms

1. Valid for ambient operating temperature  $T_A$  = -40 to +85 °C,  $V_{CC}$  = 2.0 to 5.5 V.

2. Typical values are at 25 °C and  $V_{CC}$  = 3.3 V unless otherwise noted.

3. Factory-programmable in the range of 0.5 s to 10 s typ. in 0.5 s steps.



# 9 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK<sup>®</sup> packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: *www.st.com*. ECOPACK is an ST trademark.

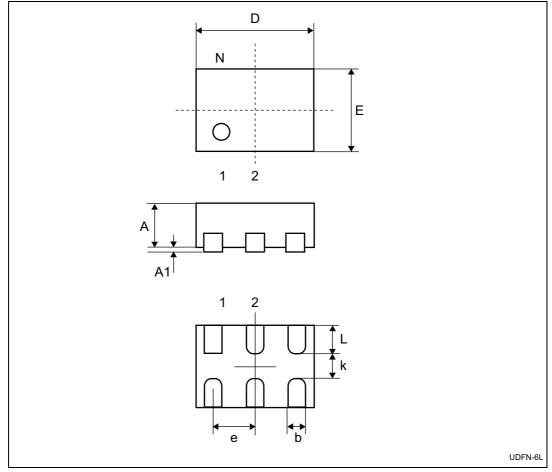


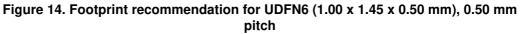
Figure 13. UDFN6, (1.00 x 1.45 x 0.50 mm), 0.50 mm pitch package outline

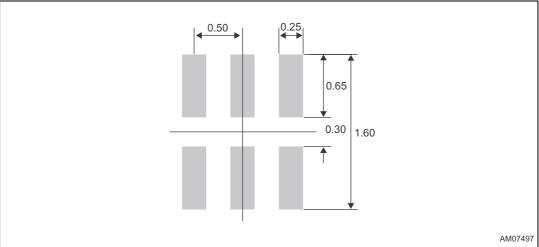


			Dir	nensions			
Symbol	(mm)			(inches)			Note <sup>(1)</sup>
	Min.	Тур.	Max.	Min.	Тур.	Max.	
А	0.50	0.55	0.60	0.0197	0.0217	0.0236	
A1	0.00	0.02	0.05	0.000	0.0008	0.0020	
b	0.18	0.25	0.30	0.0071	0.0098	0.0118	
D	1.40	1.45	1.50	0.0551	0.0571	0.0591	
Е	0.95	1.00	1.05	0.0374	0.0394	0.0413	
е	0.45	0.50	0.55	0.0177	0.0197	0.0217	
k	0.20			0.0079			
L	0.30	0.35	0.40	0.0118	0.0138	0.0157	

Table 5. UDFN6, (1.00 x 1.45 x 0.50 mm), 0.50 mm pitch package mechanical data

1. Package outline exclusive of any mold flashes dimensions and metal burrs.







# 10 Tape and reel information

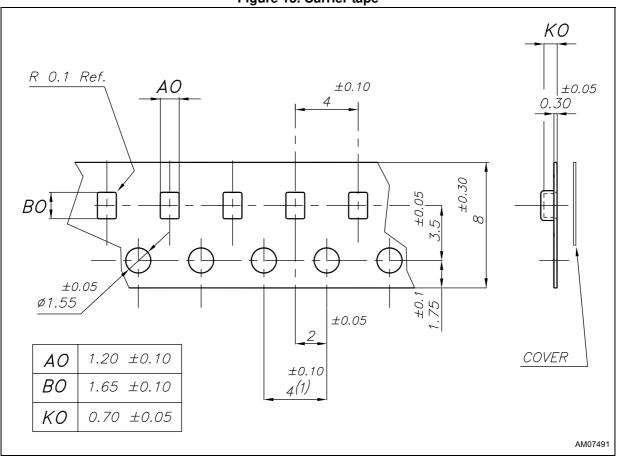
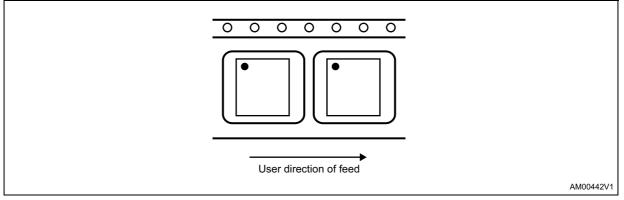


Figure 15. Carrier tape

1. 10-sprocket hole pitch cumulative tolerance  $\pm 0.20$ .

Figure 16. Pin 1 orientation





#### Part numbering 11

Example:	SR1	н	Α	R	ι
Device type					
SR1					
Smart Reset setu	o delay (t <sub>SRC</sub> ) <sup>(1)</sup>				
C = factory program	nmable t <sub>SRC</sub> = 1.5 s (typ.)				
H = factory program	nmable t <sub>SRC</sub> = 4.0 s (typ.)				
L = factory program	nmable t <sub>SRC</sub> = 6.0 s (typ.)				
P = factory program	nmable t <sub>SRC</sub> = 7.5 s (typ.)				
U = factory program	nmable t <sub>SRC</sub> = 10.0 s (typ.)				
_					
Inputs, outputs ty	pe <sup>(2)</sup>				
	nput with no pull-up,				
active low open dra B = active low $\overline{SR}$ i	ain RST output with no pull-up				
	ain $\overline{RST}$ output with no pull-up				
active low open dra					
active low open dra Reset timeout per A = factory program	iod (t <sub>REC</sub> )				
active low open dra <b>Reset timeout per</b> A = factory program B = factory program	<b>iod (t<sub>REC</sub>)</b> nmable t <sub>REC</sub> = 210 ms (typ.)				

- Smart Reset delay (t<sub>SRC</sub>) is available from 0.5 s to 10 s in 0.5 s steps (typ.). Minimum order quantities may apply. Contact local sales office for availability.
- 2. Push-pull reset output type also available (active low or active high). SR input and open drain reset output available with optional pull-up resistor. Minimum order quantities may apply. Contact local sales office for availability.



# 12 Package marking information

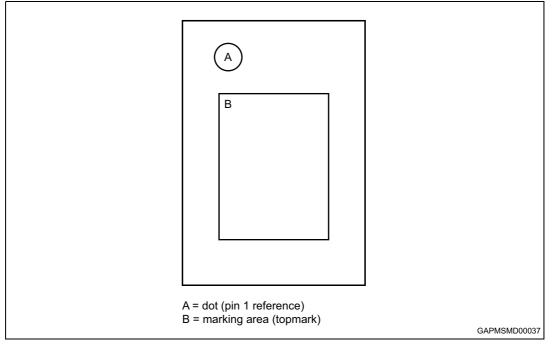
Part number	t <sub>SRC</sub> (s)	Smart Reset inputs <sup>(1)</sup>	Output type <sup>(2)</sup>	t <sub>REC</sub> option <sup>(3)</sup>	Package	Topmark		
SR1CARU	1.5	AL	OD, AL	No t <sub>REC</sub>	UDFN6	CA		
SR1HARU	4.0	AL	OD, AL	No t <sub>REC</sub>	UDFN6	HA		
SR1LARU	6.0	AL	OD, AL	No t <sub>REC</sub>	UDFN6	LA		
SR1PAAU	7.5	AL	OD, AL	210 ms	UDFN6	PB		
SR1PARU	7.5	AL	OD, AL	No t <sub>REC</sub>	UDFN6	PA		
SR1PBBU	7.5	AL + pull-up	OD, AL	360 ms	UDFN6	PC		
SR1UARU	10.0	AL	OD, AL	No t <sub>REC</sub>	UDFN6	UA		

#### Table 7. Package marking

1. AL = active low.

2. OD = open drain, AL = active low.

3. No  $t_{REC}$  = push-button controlled reset pulse width, any other value represents typical value of  $t_{REC}$ .



#### Figure 17. Package marking (top view)



# 13 Revision history

Date	Revision	Changes
10-Mar-2014	1	Initial release
13-May-2014	2	Modified t <sub>REC</sub> values Table 4 on page 14

Table 8. Document revision history



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