

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

General Description

The MAX270/MAX271 are digitally-programmed, dual second-order continuous-time lowpass filters. Their typical dynamic range of 96dB surpasses most switched capacitor filters which require additional filtering to remove clock noise. The MAX270/MAX271 are ideal for anti-aliasing and DAC smoothing applications and can be cascaded for higher-order responses.

The two filter sections are independently programmable by either microprocessor (μ P) control or pin strapping. Cutoff frequencies in the 1kHz to 25kHz range can be selected.

The MAX270 has an on-board, uncommitted op amp, while the MAX271 has an internal track-and-hold (T/H).

Applications

Lowpass Filtering

Anti-Aliasing Filter

Output Smoothing

Low-Noise Applications

Anti-Aliasing and Track-and-Hold (MAX271)

_Features

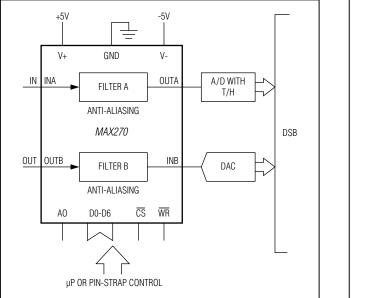
- Continuous-Time Filtering No Clock Required
- Dual 2nd-Order Lowpass Filters
- Sections Independently Programmable: 1kHz to 25kHz
- 96dB Dynamic Range
- No External Components
- Cascadable for Higher Order
- Low-Power Shutdown Mode
- Track-and-Hold (MAX271)

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX270CPP	0°C to +70°C	20 PDIP
MAX270CWP	0°C to +70°C	20 Wide SO
MAX270EPP	-40°C to +85°C	20 PDIP
MAX270EWP	-40°C to +85°C	20 Wide SO
MAX271CNG	0°C to +70°C	20 PDIP
MAX271CWG	0°C to +70°C	20 Wide SO
MAX271ENG	-40°C to +85°C	20 PDIP
MAX271EWG	-40°C to +85°C	20 Wide SO

Devices are available in a lead(Pb)-free/RoHS-compliant package. Specify lead-free by adding a plus (+) to the part number when ordering.

Pin Configurations



TOP VIEW OP OUT OP IN 20 1 2 V+ D6 19 3 OUTA D5 18 SHDN D4 17 4 MAX270 INA D3 16 5 6 V-D2 15 7 INB D1 14 OUTB 13 8 D0 GND 9 A0 12 Pin Configurations CS continued at end 10 WR 111 of data sheet PDIP/SO(W)

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maximintegrated.com.

19-3701; Rev 2; 1/12

Typical Operating Circuit

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

ABSOLUTE MAXIMUM RATINGS

V+ to V0.3V to +17V
V+ to GND0.3V to +8.5V
V- to GND0.3V to -8.5V
nput Voltage to GND, Any Input Pin (V 0.3V) to (V+ + 0.3V)
Duration of Output Short Circuit to GNDContinuous
Continuous Power Dissipation ($T_A = +70^{\circ}C$)
MAX270
PDIP (derate 11.1mW/°C above +70°C)889mW
SO (W) (derate 10mW/°C above +70°C800mW
MAX271

PDIP (derate 13.3mW/°C above +70°C) 1067mW

SO (W) (derate 11.7mW/°C above +70°C)	
Operating Temperature Ranges:	
MAX27_C	0°C to +70°C
MAX27_E	40°C to +85°C
Storage Temperature Range	65°C to +165°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	
Lead(Pb)-free	+260°C
Containing lead(Pb)	+240°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V + = +5V, V - = -5V; T_A = +25^{\circ}C, unless otherwise noted.)$

PARAMETER	SYMBOL	CONDITIONS		MIN	ТҮР	MAX	UNITS	
FILTER CHARACTERISTICS								
Operating Frequency Range		(Note 1)			2		MHz	
Programmed Cutoff Frequency (fc) Range					1 to 25		kHz	
Programmed Cutoff Frequency		fc code = 53 (2.536kHz typ))		±2.9		%	
Error		fc code = 127 (25kHz typ)			±9.5		/0	
		fc code = 0 (1kHz typ),	$f_{IN} = 1 kHz$	-3.6		-2.4		
Filter Gain		TA = TMIN to TMAX	f _{IN} = 8kHz			-33	dB	
		$f_{\rm C}$ code = 127 (25kHz typ),	$f_{IN} = 25 kHz$	-6		-0.5	UB	
		TA = TMIN to TMAX	$f_{IN} = 200 kHz$		-34			
Maximum Gain (Peaking)		fc code = 0 (1kHz typ)				0.15	dB	
		$f_{C} \operatorname{code} = 127 (25 \text{kHz typ})$			0.15		uв	
Wideband Noise		f _C code = 0 (1kHz typ)		12				
	fC		fC code = 127 (25kHz typ)		38		μVRMS	
DC CHARACTERISTICS								
DC Output Signal Swing OUTA, OUTB, OP OUT (MAX270) OUTA, OUTB, T/H OUT (MAX271)		$R_{LOAD} = 5k\Omega$, $T_A = T_{MIN}$ to	$R_{LOAD} = 5k\Omega$, $T_A = T_{MIN}$ to T_{MAX}			+3	V	
Offset Voltage at Outputs OUTA, OUTB, OP OUT (MAX270) OUTA, OUTB, T/H OUT (MAX271)				-2		+2	mV	
DC Input Leakage Current INA, INB (MAX270) INA, INB (MAX271)		Ta = Tmin to Tmax		-1		+1	μA	

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ELECTRICAL CHARACTERISTICS (continued)

(V+ = +5V, V- = -5V; TA = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DYNAMIC FILTER CHARACTERIS	TICS (MAX	270)				•
Total Harmonic Distortion	THD				-70	
Signal Noise Plus Distortion	SINAD	fc code = 44 (2.01kHz typ), VIN = 3.5VP-P at 390.625Hz (Notes 2 and 3)		73		dB
Spurious-Free Dynamic Range	SFDR		70			
UNCOMMITTED AMPLIFIER (MAX	270)					•
Slew Rate				1.2		V/µs
Bandwidth				2		MHz
TRACK AND HOLD (MAX271)						·
Hold Settling Time		To 0.1% (Note 4)		500		ns
Acquisition Time		To 0.1% (Note 5)		1.8		μs
Hold Step				1		mV
Droop Rate		$T_A = T_{MIN}$ to T_{MAX}		30		μV/μs
Offset Voltage at T/H OUT		Includes filter offset	-6		+6	mV
T/H OUT Disabled Output Leakage Current		$T_A = T_{MIN}$ to T_{MAX} , $V_{T/H} = 0V$ (Track Mode)	-10		+10	μA
Total Harmonic Distortion	THD	f _C code = 44 (2.01kHz typ), V _{IN} = 3.5VP-P at _ 390.625Hz, sampling rate = 50kHz (Notes 2, 6, 7)			-70	
Spurious-Free Dynamic Range	SFDR					dB
DIGITAL INPUTS	1	· · · · · · · · · · · · · · · · · · ·				
Digital Input High Voltage		T _A = T _{MIN} to T _{MAX} (Note 8)	2.4			
Digital Input Low Voltage					0.8	V
Digital Input Current		$T_A = T_{MIN}$ to T_{MAX} , digital input held at ±5V, includes MODE (MAX271)(Note 8)	-1		+1	μA
POWER REQUIREMENTS						
Supply Voltage Range				±2.375 to ±8		V
Supply Current		T _A = T _{MIN} to T _{MAX} (Note 9)			6.5	mA
Shutdown Supply Current		T _A = T _{MIN} to T _{MAX} (Note 10)			15	μA
Power-Supply Rejection Ratio at 1kHz	PSRR	f _C code = 0 (1kHz typ), V+ = 5V _{DC} + 10mV _{P-P} at 1kHz		30		dB

Note 1: All internal amplifiers limited to 2MHz bandwidth.

Note 2: Only filter A tested for these parameters.

Note 3: Spurious-Free Dynamic Range is the ratio of the fundamental to the largest of any harmonic or noise spur in dB.

Note 4: Includes T/H propagation delays. With $5k\Omega$, parallel 100pF load.

Note 5: $\pm 2V$ input step settling 0.1% with $5k\Omega$ parallel 100pF load.

Note 6: \overline{T}/H pin toggled at sampling rate, 50% duty cycle.

Note 7: THD and SFDR specifications for T/H include contributions from filter.

Note 8: Digital pins include SHDN, WR, CS, A0, D0–D6 (MAX270) and SHDN, T/H, A/B, WR, T/H EN, CS, A0, A1, D0–D6, T/H (MAX271).

Note 9: Input of uncommitted op amp disconnected with a $5k\Omega$ feedback resistor from input to output.

Note 10: WR, CS, A0, D0–D6 held at +5V; VSHDN = 0V (MAX270). WR, CS, A0, A1, D0–D6, T/H, T/H, A/B, T/H, MODE held at +5V; VSHDN = 0V (MAX271).

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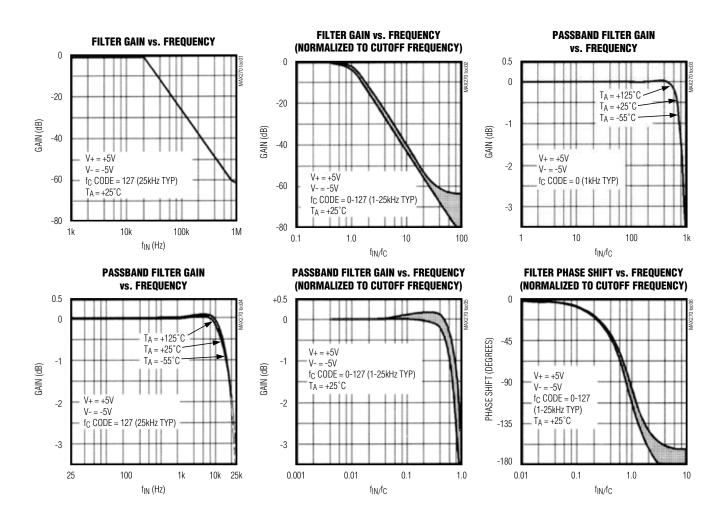
TIMING CHARACTERISTICS (Figure 2)

(V+ = +5V, V- = -5V; TA = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CS to WR Setup	t _{WS}				0	ns
CS to WR Hold	t _{WH}				0	ns
WR Pulse Width	t _{SV}		100			ns
Address-Setup Time	t _{AS}		30			ns
Address-Hold Time	t _{AH}		10			ns
Data-Setup Time	t _{DS}		30			ns
Data-Hold time	t _{DH}		10			ns

Note 11: All input control signals specified with $t_r = t_f = 5ns$ (10% to 90% of +5V) and timed from a +1.6V voltage level.

Typical Operating Characteristics



Maxim Integrated

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

_Typical Operating Characteristics (continued)

CASCADED FILTER GAIN vs. FREQUENCY (NORMALIZED TO CUTOFF FREQUENCY) +0.5

 f_C (FILTER A) = f_C (FILTER B) =

FILTERS A AND B CASCADED

0-127 (1-25kHz TYP)

-1.5

-2.5

-3.5

-4.5

-5.5

-6.5

-7.5

0.01

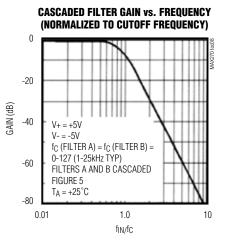
 $V_{+} = +5V$

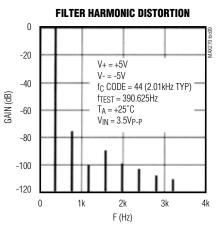
 $V_{-} = -5V$

FIGURE 5

 $T_A = +25^{\circ}C$

GAIN (dB)





FILTER TOTAL HARMONIC DISTORTION PLUS NOISE vs.INPUT FREQUENCY

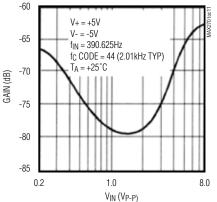
0.1

fIN/fC

1.0

fın (Hz)	fc CODE	fc (Hz) (TYP)	THD PLUS Noise (Typ)
190	0	1k	-78
390	44	2.01k	-73
1367	100	7.01k	-67
4875	4875 127		-66

FILTER TOTAL HARMONIC DISTORTION PLUS NOISE vs. INPUT AMPLITUDE



MAX271 FILTER PLUS TRACK-AND-HOLD Spurious-free Dynamic Range vs. Input Frequency

fın (Hz)	fc CODE	fc (Hz) (TYP)	SFDR (dB)
195	0	1k	73.5
781	72	4.01k	69.5
1562.5	105	8.08k	66
3906	124	19.4k	61.5

V+ = 5V, V- = -5V; V_{IN} = $3.5V_{P-P}$; T/H SWITCHED AT 50kHz, 50% DUTY CYCLE; T_A = +25°C

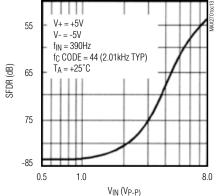
MAX271 FILTER PLUS TRACK-AND-HOLD Spurious-free Dynamic Range vs. Sampling Frequency

fsample (Hz)	fın (Hz)	fc CODE	fc (Hz)	SFDR (dB)	AAY970 to d A
100k	781	72	4.01k	72	
200k	1562	105	8.08k	72	
500k	3906	124	19.4k	64	

 $V_{+} = 5V, V_{-} = -5V; V_{IN} = 3.5V_{P-P}; \\ T/H \ S\overline{W}ITCHED \ AT \ 50kHz, \ 50\% \ DUTY \ CYCLE; \ T_{A} = +25^{\circ}C$

V+ = 5V, V- = -5V; V_{IN} = 3.5Vp₋p; T_A = +25°C





Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

PIN

1

2

З

4

5

6

7

8

9

10

11

12

13-

19

20

A0

D0-D6

OP IN

Detailed Description

Pin Description

Figures 1a, 1b, and 1c show the MAX270/MAX271 functional diagrams. Both the MAX270 and MAX271 contain two independent, second-order, Sallen-Key, lowpass filter sections, A and B to provide a frequency vs. gain rolloff of approximately 40dB/decade. These are not switched-capacitor filters, but have a continuous-time design similar to discrete active filters built around op amps. The MAX270/MAX271 eliminate clock noise and aliasing problems which limit low-noise performance of switched-capacitor filters; resulting dynamic range is over 96dB.

Each filter section contains two banks of programmable capacitors, controlled by an internal 7-bit memory, which set filter cutoff frequencies (fc) from 1kHz to 25kHz. The filters provide two program modes. In µP mode, cutoff frequencies are programmed by writing 7-bit data to one of two memory addresses (one for each filter section). Alternately, a pin-strap programming mode programs both filter sections simultaneously. In this mode, both memory latches are transparent (not addressable), and data pins D0-D6 may be pin-strapped (hard-wired) to set a common fc for both filter sections.

The filters are trimmed at the wafer level, setting 0 for a maximum of 0.15dB passband peaking for fc programmed to 1kHz. Maximum passband peaking at other codes is typically less than 0.15dB. Filter Q is not userprogrammable.

The MAX270 includes an uncommitted op amp (noninverting input grounded); the MAX271 has an on-chip T/H that tracks and holds the output of either filter section (selectable). The held output is provided at T/H OUT. T/H functions are controlled by writing control bits to internal registers (in µP mode) or by control pins directly (in pinstrap mode).

The MAX270 and MAX271 provide a low quiescent current shutdown mode controlled by the SHDN pin, which turns off internal amplifiers and disconnects all outputs, reducing guiescent operating current to less than 15µA. When the MAX271 is in µP mode, shutdown mode is selected by writing control bits to memory (the SHDN pin is disabled).

NAME	FUNCTION
OP OUT	Uncommitted Op Amp Output
V+	Positive Supply Voltage
OUTA	Filter A Output
SHDN	Shutdown Control. Low level disconnects OUTA, OUTB, and OP OUT and places device into shutdown mode.
INA	Filter A Input
V-	Negative Supply Voltage
INB	Filter B Input
OUTB	Filter B Output
GND	Ground
WR	Write Control Input. A low level writes data D0–D6 to program memory addressed by A0. High level latches data.
CS	Chip-Select Input. Must be low for \overline{WR} input to be recognized.

MAX270

Note: All digital input levels are TTL and CMOS compatible, unless otherwise noted.

25kHz range.

Three-Level Address Input

Logic High: Addresses filter A

Logic Low: Addresses filter B

Connect to V-: Pin-strap mode

Uncommitted Op Amp Input

7-Bit Data Inputs. Allows programming

of 128 cutoff frequencies in a 1kHz to

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

Pin Description (continued)

MAX271

PIN	NAME	FUNCTION, FP MODE (MODE = GND OR V-)	FUNCTION, FP MODE (MODE = GND OR V+)
1	T/H OUT	Track-and-Hold Output	<u>`</u>
2	V+	Positive Supply Voltage	
3	OUTA	Filler A Signal Output	
4	SHDN	_	SHUTDOWN Control. A low level disconnects outputs and places device into shutdown mode
5	INA	Filter A Signal Input	
6	V-	Negative Supply Voltage	
7	INB	Filter B Signal Input	
8	MODE	Selects μ P mode when connected to GND or V- a	nd pin-strap mode when connected to V+.
9	OUTB	Filter B Signal Output	
10	GND	Ground	
11	T/H A/B	_	Track-and-Hold Input Control. A high/low level internally connects OUTNOUTB to input of Track-and-Hold
12	WR	WRITE Control Input. A low level writes data D0-D6 program memory addressed by A1, A0 (or performs function as described for address inputs). High level latches data.	_
13	T/H EN	X	Track-and-Hold Output Control. Low level disconnects T/H OUT. Connect pin high for normal operation
14	CS	$\overline{\text{Chip Select Input. Must be low for WR}}$ input to be recognized.	_
15, 16	A1, A0	Address and μ P Control Inputs. 0, 0 Programs f _C , filter A 0, 1 Programs f _C , filter B 1,0 Controls T/H functions: D0 performs T/H En pin function D1 performs T/H A/B pin function. 1,1 Controls device shutdown: D0 performs SHDN pin function Note: The WR pin must be strobed low to initiate a program/function (Figure 2).	
17-23	D0-D6	7-bit Data Inputs. Allows programming of 128 cutoff frequencies (also performs control functions as described above).	7-bit Data Inputs. Program memory latches are trans- parent in this mode. Connect pins high or low to program filters A and B simultaneously to the same f _C .
24	T/H	Track-and-Hold Control. Low level causes T/H OL T/H OUT synchronous with \overline{T} /H rising transition.	JT to track selected filter output. Filter output level held at

X = Pin has no function in this mode.

Note: All digital input levels are TTL and CMOS compatible, unless otherwise noted.

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

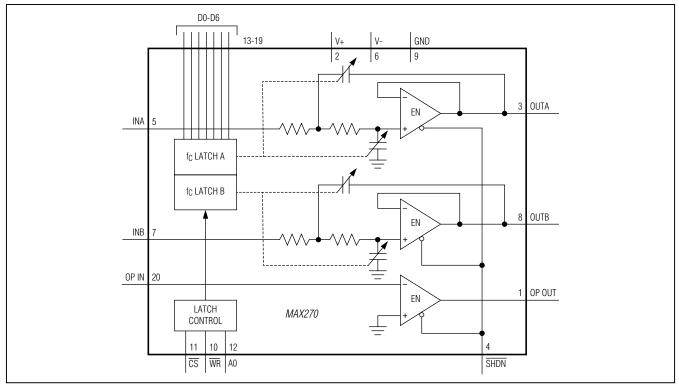


Figure 1a. MAX270 Block Diagram

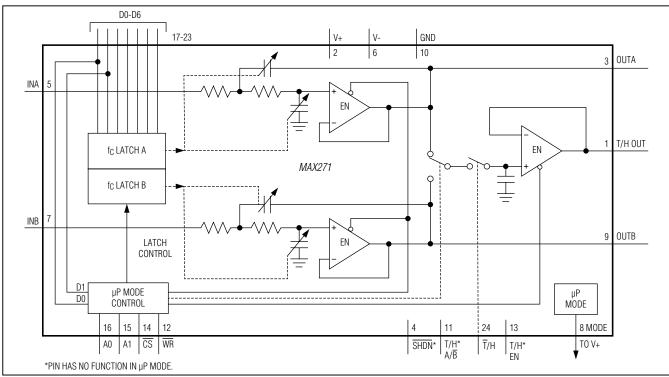


Figure 1b. MAX271 Block Diagram—µP Mode

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

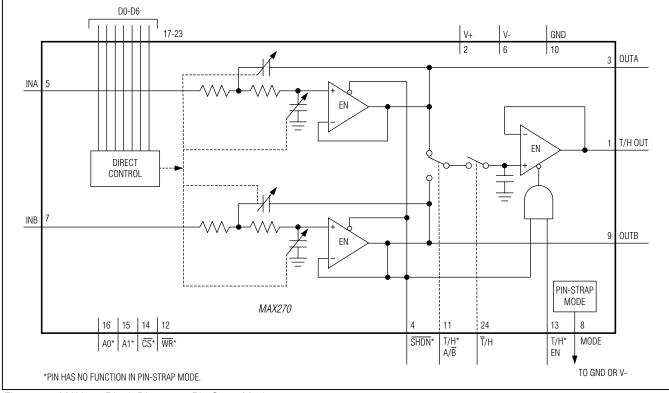


Figure 1c. MAX271 Block Diagram—Pin-Strap Mode

Filter Programming Cutoff Frequency

fc is the frequency of 3dB attenuation in the filter response.

Table 1 shows how data pins D0–D6 allow programming of 128 cutoff frequencies from 1kHz to 25kHz.

The equations for calculating f_{C} from the programmed code are as follows:

$$f_{C} = \frac{87.5}{87.5 - \text{CODE}} \times 1 \text{kHz} \quad \begin{array}{l} \text{for codes 0-63} \\ (f_{C} = 1 \text{kHz to 3.57 \text{kHz}}) \end{array}$$

$$f_{C} = \frac{262.5}{137.5 - \text{CODE}} \times 1 \text{kHz} \quad \begin{array}{l} \text{for codes 64 - 127} \\ (f_{C} = 3.57 \text{kHz to 25 \text{kHz}}) \end{array}$$

where CODE is the data on pins D0–D6 (0–127). D6 is the most significant bit (MSB).

Actual cutoff frequencies are subject to some error for each programmed code. Highest accuracy occurs at CODE = 0 where filters are trimmed for a 1kHz cutoff frequency. At higher codes, CODE vs. f_C errors increase; the frequency error at CODE = 127 {highest code) remains typically within $\pm 9.5\%$. This means that the actual filter cutoff frequency, when programmed to CODE = 127, falls between 22.63kHz and 27.38kHz.

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

PROGRAMMED CODE	f _C (kHz)	PROGRAMMED CODE	f _C (kHz)	PROGRAMMED CODE	fC (kHz)	PROGRAMMED CODE	f _C (kHz)
0	1.000	32	1.576	64	3.571	96	6.325
1	1.011	33	1.605	65	3.620	97	6.481
2	1.023	34	1.635	66	3.671	98	6.645
3	1.035	35	1.666	67	3.723	99	6.818
4	1.047	36	1.699	68	3.777	100	7.008
5	1.060	37	1.732	69	3.832	101	7.191
6	1.073	38	1.767	70	3.888	102	7.394
7	1.087	39	1.804	71	3.947	103	7.608
8	1.100	40	1.842	72	4.007	104	7.835
9	1.114	41	1.881	73	4.069	105	8.076
10	1.129	42	1.923	74	4.133	106	8.333
11	1.143	43	1.966	75	4.200	107	8.606
12	1.158	44	2.011	76	4.268	108	8.898
13	1.174	45	2.058	77	4.338	109	9.210
14	1.190	46	2.108	78	4.411	110	9.545
15	1.206	47	2.160	79	4.487	111	9.905
16	1.223	48	2.215	80	4.565	112	10.294
17	1.241	49	2.272	81	4.646	113	10.714
18	11.259	50	2.333	82	4.729	114	11.170
19	1.277	51	2.397	83	4.816	115	11.666
20	1.296	52	2.464	84	4.906	116	12.209
21	1.315	53	2.536	85	5.000	117	12.804
22	1.335	54	2.611	86	5.097	118	13.461
23	1.356	55	2.692	87	5.198	119	14.189
24	1.378	56	2.777	88	5.303	120	15.000
25	1.400	57	2.868	89	5.412	121	15.909
26	1.422	58	2.966	90	5.526	122	16.935
27	1.446	59	3.070	91	5.645	123	18.103
28	1.470	60	3.181	92	5.769	124	19.444
29	1.495	61	3.301	93	5.898	125	21.000
30	1.521	62	3.431	94	6.034	126	22.826
31	1.548	63	3.571	95	6.176	127	25.000

Table 1. Programmed Cutoff Frequency Codes (typ)

Programmed code is the data on pins D0–D6 (0–127). D6 is the MSB.

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

MAX270 Control Interlace

The A0 pin is a three-level input that selects the memory addresses for updating cutoff frequency data in μ P mode:

A0	SELECTS
Logic Low	Filter B
Logic High	Filter A

Figure 2 shows µP-mode interface timing.

Connecting A0 to the negative supply selects pin-strap mode. Pin-strap mode allows filter programming with no timing requirements. Internal memory latches are disabled, permitting filters A and B to be programmed directly to f_C data strapped on D0–D6. This mode disables \overline{CS} and \overline{WR} controls, and filters A and B are programmed to the same f_C.

A low level on the \overline{SHDN} pin shuts down all amplifiers and disconnects OUTA, OUTB, and OP OUT. Current consumption drops to less than 15µA in this mode.

MAX271 Control Interlace

Connecting the MODE pin to GND or V- selects the μ P mode. In this mode, addressable program memory controls filter cutoff frequency programming and all T/H functions, except T/H. See the Figure 2 for timing characteristics. Table 2 describes available functions:

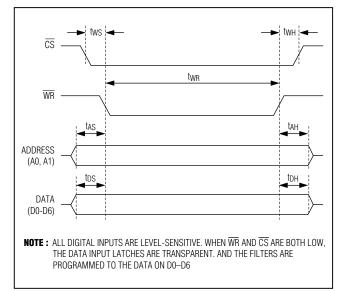


Figure 2. MAX270/MAX271 Digital Timing Diagram

In μ P mode, SHDN, T/H A/B, and T/H EN pins are disabled. T/H remains enabled and performs the T/H tracking/holding function.

Tying MODE to V+ selects pin-strap mode. In this mode, both memory latches are transparent, and data on D0–D6 controls the f_C of filters A and 8 directly (filters A and 8 are programmed to the same f_C). Pin strap D0–D6 for operation without μ P. A0, A1, \overline{CS} , and \overline{WR} are disabled.

A1	A0	06	05	04	03	02	01	D0	FUNCTION
0	0	7-bit fC data						Selects filter A	
0	1	7-bit fC data						Selects filter B	
1	0	Х	Х	Х	Х	Х	Х	0	T/H OUT disabled
1	0	X	X	Х	Х	X	Х	1	T/H OUT enabled
1	0	Х	Х	Х	Х	Х	0	Х	Selects OUTB as input to T/H
1	0	Х	X	Х	Х	X	1	X	Selects OUTA as input to T/H
1	1	Х	Х	x	х	x	x	0	Filter shutdown mode. All outputs floated, 15µA max supply current
1	1	Х	Х	Х	Х	Х	Х	1	Removes filter from shutdown mode

Table 2. MAX271 µP-Mode Interface

X = Don't care

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

Digital Threshold Levels

All digital inputs are TTL and CMOS compatible, unless otherwise stated. Inputs are CMOS gates with less than 1μ A leakage current and 8pF capacitance loading. Typical logic voltage thresholds are a function of the V+ supply voltage as shown below (voltages are referenced to GND).

V+ (V)	LOGIC THRESHOLD VOLTAGE (V)
8	+2.4
7	+2.3
6	+2.0
5	+1.75
4	+1.5
2.5	+1.0

Note: For +5V single-supply operation, where incoming logic signals are referenced to V-, typical logic thresholds are +3.5V. Therefore, a CMOS (rail-to-rail) logic interface is recommended.

Filter Performance

All MAX270/MAX271 internal amplifier and output stages for filter sections. uncommitted op amp, and T/H are identical. The outputs are designed to drive 5k Ω in parallel with a maximum capacitance of 100pF. At higher load levels, the output swing becomes asymmetric. All outputs can be short circuited to GND for an indefinite duration.

The MAX270/MAX271 operating frequency range is limited to approximately 2MHz by the bandwidth of the internal amplifiers.

Filter Noise

Wideband filter noise over a 50kHz bandwidth is 12μ VRMS and 38μ VRMS per section for fC programmed to 1kHz and 25kHz, respectively. A dynamic range of over 96dB results.

Filter Input Impedance

At DC, the input impedance at INA and INB is equal to the DC input impedance of the amplifier, which is about $5M\Omega$. At higher frequencies, internal capacitors contribute to an effective input impedance that may fall as low as $100k\Omega$ at 25kHz.

MAX271 Track-and-Hold

The MAX271 T/H is functionally equivalent to a switched 200pF capacitor buffered by a unity-gain amplifier (Figures 1b and 1c). When the \overline{T}/H pin is driven low, the output of filter A or filter B (whichever is selected via control interface) internally connects to the amplifier, and T/H OUT follows the filter output. The offset at T/H OUT (±6mV max) is the combined offset of the filter amplifier and the T/H buffer. When \overline{T}/H is pulled high, the switch disconnects the filter signal from the T/H. The T/H capacitor holds the stored charge, and that voltage is buffered at T/H OUT.

A low level at T/H EN disconnects T/H OUT, enabling multiplexed operation (Figure 3). T/H A/B selects between OUTA and OUTB as the T/H input. In FP mode, the T/H EN and T/H OUT functions are controlled by writing control bits to program memory, with T/H EN and T/H OUT pins disabled.

See the *Typical Operating Characteristics* graphs for T/H dynamic accuracy.

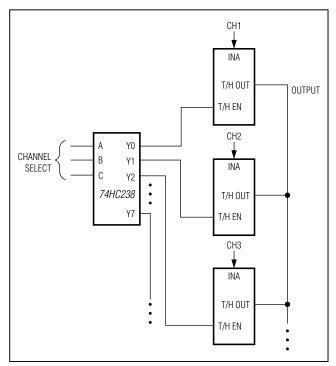


Figure 3. MAX271 Multiplexed Operation

Digitally-Programmed, Dual 2nd-Order Continuous Lowpass Filter

Applications Information

Power-Supply Configurations

The MAX270/MAX271 power supplies must be properly bypassed. Best performance is achieved if V+ and V- are bypassed to GND with 4.7μ F electrolytic (tantalum is preferred) and 0.1μ F ceramic capacitors in parallel. These should be as close as possible to the chip supply pins.

Single supplies in the range of 4.75V to 16V may be used to power the MAX270/MAX271 as shown in Figure 4. Digital logic may be referenced to V- (system ground), but will not maintain TTL compatibility. CMOS (rail-to-rail) logic recommended. For µP-mode operation with a

single supply, the MAX270 A0 pin must be configure with a voltage divider (Figure 4).

Lowest quiescent current in shutdown mode is achieved when A0 is either at V+ or V-.

Independent f_C Programming Without a µP Figure 6 shows how filter sections A and B may be programmed to different cutoff frequencies without the use of a µP. The MAX690 µP supervisory circuit provides the proper programming sequence when the circuit is powered up by controlling the 74HC373 data buffer and the MAX270 addressing pin to load independent fC data for filters A and B.

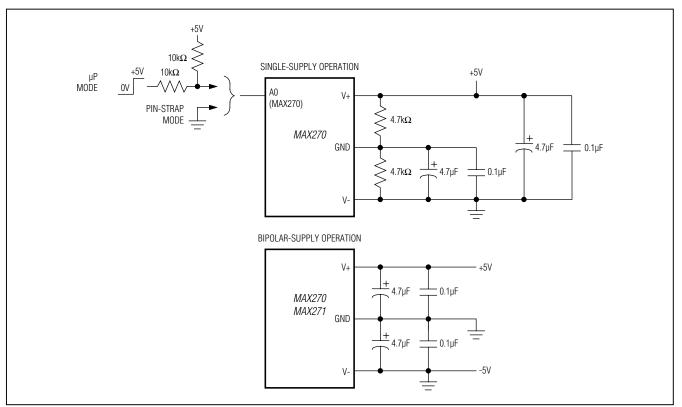


Figure 4. Power-Supply Configurations

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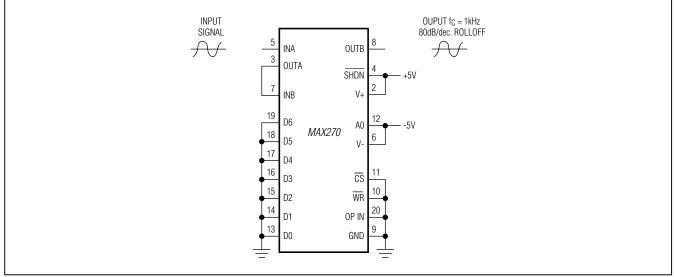


Figure 5. Cascading Filter Sections

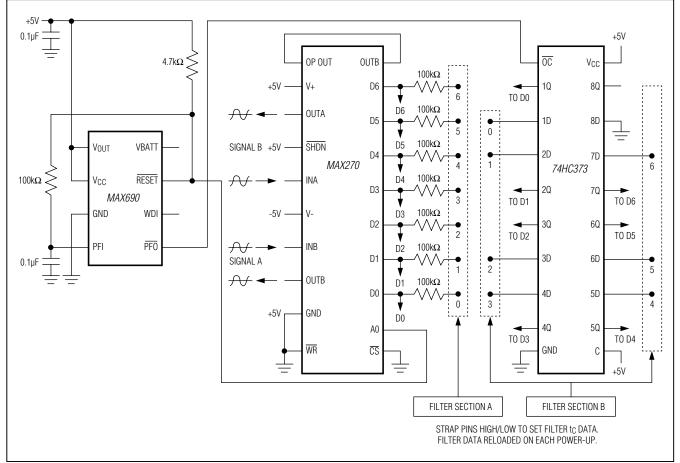


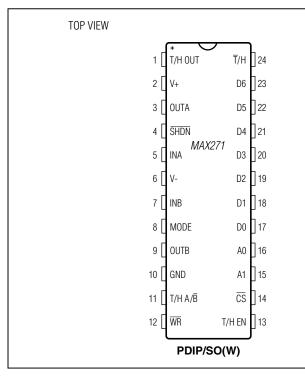
Figure 6. Independent f_C Programming without a μ P

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Pin Configurations (continued)



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Package Information

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PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
20 PDIP	P20-2	<u>21-0043</u>	—
20 SO (W)	W20-3	<u>21-0042</u>	<u>90-0108</u>
24 PDIP	N24-3	<u>21-0043</u>	—
24 SO (W)	W24-2	<u>21-0042</u>	<u>90-0182</u>

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Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	4/91	Initial release	—
1	8/91	Revised Electrical Characteristics	2
2	1/12	Revised Ordering Information and Absolute Maximum Ratings.	1, 2



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