

March 1997

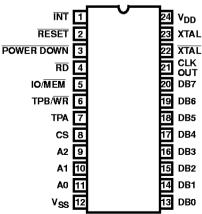
## CMOS Real-Time Clock

### Features

- CPU Interface for Use with General-Purpose Microprocessors
- · Time Of Day/Calendar
- · Reads Seconds, Minutes, Hours
- · Reads Day of Month and Month
- Alarm Circuit With Seconds, Minutes or Hours Operation
- · Power Down Mode
- Separate Clock Output Selects 1 of 15 Square Wave Signals
- Interrupt Output Activated By Clock Output and/or Alarm Circuit
- Date Integrity Sampling for Clock Rollover Eliminated
- · On-Board Oscillator:
  - Crystal Operation CDP1879 at 10V . . . . . 4.19MHz, 2.09MHz or 1.048MHz
  - Crystal Operation CDP1879C-1 at 5V . . . . 4.19MHz, 2.09MHz or 1.048MHz or 32kHz
  - External Clock Operation at 10V or 5V.... 4.19MHz, 2.09MHz, 1.048MHz or 32kHz
- Addressable in Memory Space or CDP1800 Series I/O Mode
- · Low Standby (Timekeeping) Voltage with External Clock
- · Related Literature
  - AN7275, Guide to the Use of CD1879 and CDP1879C1 Real Time Clock

#### Pinout

CDP1879, CDP1879C-1 (PDIP, SBDIP) TOP VIEW



## Description

The CDP1879 real-time clock supplies time and calendar information from seconds to months in BCD format. It consists of 5 separately addressable and programmable counters that divide down an oscillator input. The clock input can have any one of 4 possible frequencies, allowing flexibility in the choice of crystal or external clock sources. Using an external 32kHz clock source, timekeeping can be performed down to 2.5V (see Standby (Timekeeping) Voltage Operation).

The device can be memory-mapped for use with any general-purpose microprocessor and has the additional capability of operating in the CDP1800 series input/output mode.

The real-time clock functions as a time-of-day/calendar with an alarm capability that can be set for combinations of seconds, minutes or hours. Alarm time is configured by loading alarm latches that activate an interrupt output through a comparator when the counter and alarm latch values are equal.

Fifteen selectable square-wave signals are available as a separate clock output signal and can also activate the interrupt output. A status register is available to indicate the interrupt source. The value in an 8 bit control register determines the operational characteristics of the device, by selecting the prescaler divisor and the clock output, and controls the load and alarm functions.

A transparent "freeze" circuit preclude clock rollover during counter and latch access times to assure stable and accurate values in the counters and alarm latches.

The CDP1879 is functionally identical to the CDP1879C-1. The CDP1879 has a recommended operating voltage range of 4V to 10.5V, and the CDP1879C-1 has a recommended operating voltage range of 4V to 6.5V. The CDP1879 and the CDP1879C-1 are supplied in 24 lead hermetic dual-in-line side-brazed ceramic packages (D suffix) and 24 lead dual-in-line plastic packages (E suffix).

## Ordering Information

PACKAGE	TEMP RANGE	5V	10V	PKG. NO.
PDIP	-40°C to +85°C	CDP1879CE1	CDP1879E	E24.6
SBDIP		CDP1879CD1	-	D24.6
Burn-In	+85°C	CDP1879CD1X	-	D24.6

# CDP1879 Modes of Operation

OPERATION	FUNCTION
Read	Seconds, minutes, hours, date and month counters     Status register to identify interrupt source
Write	Control register to set device operation     Seconds, minutes, hours, date and month counters     Alarm latches for alarm time
Power Down	Three-state interrupt output with active alarm or clock out circuitry for wake-up control     Data bus and address inputs are "DON'T CARE"
Interrupt	Clock out as source     Alarm time as source     Either interrupt can occur during normal or power down mode

## **Absolute Maximum Ratings**

#### 

#### Thermal Information

Thermal Resistance (Typical)	$\theta_{JA}$ (°C/W)	θ <sub>JC</sub> (°C/W)
PDIP Package	60	N/A
SBDIP Package	50	12
Operating Temperature Range (TA)		
Package Type D, H	55 <sup>c</sup>	°C to +125°C
Package Type E	40	0°C to +85°C
Storage Temperature Range (TSTG)	65°	C to +150°C
Lead Temperature (During Soldering)		
At Distance 1/16 $\pm$ 1/32 in. (1.59 $\pm$ 0.79m	m) From Cas	e for 10s Max

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

**Operating Conditions** at T<sub>A</sub> = Full Package-Temperature Range, Unless Otherwise specified. For maximum reliability, operating conditions should be selected so that operation is always within the following ranges:

	CDF	1879	CDPI		
PARAMETER	MIN	MAX	MIN	MAX	UNITS
DC Operating Voltage Range	4	10.5	4	6.5	٧
Input Voltage Range	V <sub>SS</sub>	V <sub>DD</sub>	V <sub>SS</sub>	$V_{DD}$	٧
DC Standby (Timekeeping) Voltage (Note 1), V <sub>STBY</sub> $T_{A} = -40^{\circ}\text{C to } +85^{\circ}\text{C (Note 2)}$	3		3	-	٧
$T_A = 0^{\circ} \text{ to } +70^{\circ}\text{C}$	2.5	-	2.5		٧
Clock Input Rise or Fall Time, t <sub>R</sub> , t <sub>F</sub> $V_{DD} = 5V$	-	10	-	10	με
V <sub>DD</sub> = 10V	-	1	-	-	μs

#### NOTES:

- 1. Timekeeping function only, no READ/WRITE accesses, 32kHz external frequency source only, no crystal operation.
- 2. See Standby (Timekeeping) Voltage Operation.

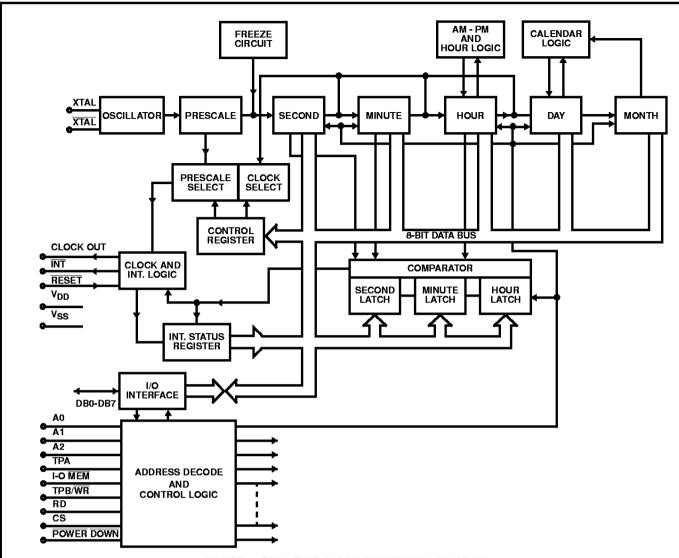


FIGURE 1. REAL-TIME CLOCK FUNCTIONAL DIAGRAM

TABLE 1. TABLE 2.

CONTROL REGIST	CONTROL REGISTER BIT ASSIGNMENT						
Bit 1, 0							
Frequency 00	32768Hz						
Select 01	1.048576MHz						
10	2.097152MHz						
11	4.194304MHz						
Bit 2							
Start/Stop	1 = Start						
	0 = Stop						
1	·						
Bit 3							
Counter/Latch Control							
"0" = Write to Counter and disa							
"1" = Write to and enable alarm	Clock Select						
Bit 7, 6, 5, 4							
0000 - disableμs	1000 - 62.5ms						
0001 - 488.2μs	1001 - 125ms						
0010 - 976.5μs	1010 - 250ms						
0011 - 1953.1μs	1011 - 500ms						
0100 - 3906.2μs	1100 - sec.						
0101 - 7812.5μs 0110 - 15.625ms	1101 - min. 1110 - hour						
0110 - 13.625ms 0111 - 31.25ms	1110 - 11001 1111 - dav						

ADDRESSES	<b>A</b> 2	<b>A</b> 1	A0			
Latch, Counter Seconds	0	1	0			
Latch, Counter Minutes	0	1	1			
Latch, Counter Hours	1	0	0			
Counter, Day	1	0	1			
Counter, Month	1	1	0			
Control, Register	1	1	1			
Status Register	1 1		1			
MSB of Hours Counters (E	3it 7) is an AM	1-PM Bit. 0 = <i>I</i>	AM; 1 = PM			
Bit 6 of Hours Counter Co	ntrols 12/24 h	r. 1 = 12 Hr: 0	) = 24 Hr.			
Status Register: Bit 7 MSB = Alarm Interrupt Source: Bit 6 = Clock.						
MSB of Month Counter (Bit 7) is a Leap Year Bit 0 = No, 1 = Yes.						

# Static Electrical Specifications at TA -40°C to +85°C $V_{DD} \pm 5\%$ , Unless Otherwise Specified

			ONDITION	1S	<u> </u>		LIM	ITS			I
					CDP1879		(	CDPI879C-	1	1	
PARAMETER		ν <sub>ο</sub> (۷)	V <sub>IN</sub> (V)	V <sub>DD</sub> (V)	MIN	(NOTE 1)	MAX	MIN	(NOTE 1) TYP	мах	UNITS
Ouiescent Device Current	I <sub>DD</sub>		0, 5	5	-	0.01	50	-	0.02	200	μΑ
			0, 10	10	-	1	200	-	-	-	
Output Low Drive (Sink)		0.4	0, 5	5	1.8	4	-	-	-	-	
Current, Data Bus and INT	$I_{OL}$	0.5	0,10	10	3.6	7	-	-	-	-	1
Output High Drive (Source)		4.6	0, 5	5	-1.1	-2.3	-	-1.1	-2.3	-	1
Current, Data Bus and INT	I <sub>OH</sub>	9.5	0,10	10	-2.6	-4.4	-	-	-	-	
Output Low Drive (Sink)		0.4	0, 5	5	0.6	1.4	-	0.6	1.4	-	1
Current, Clock Out	$I_{OL}$	0.5	0,10	10	1.2	3	-	-	-	-	١.
Output High Drive (Source)		4.6	0, 5	5	-1.1	-2.3	-	-1.1	-2.3	-	mΑ
Current, Clock Out	I <sub>OH</sub>	9.5	0,10	10	-2.6	-4.4	-	-	-	-	
Output Low Drive (Sink)		0.4	0, 5	5	0.2	0.9	-	0.2	0.9	-	1
Current, XTAL Out	loL	0.5	0,10	10	0.4	2	-	-	-	-	1
Output High Drive (Source)		4.6	0, 5	5	-0.15	-0.4	-	-0.15	-0.4	-	1
Current, XTAL Out	I <sub>OH</sub>	9.5	0,10	10	-0.3	-0.7	-	-	-	-	ı
Output Voltage		-	0, 5	5	-	0	0.1	-	0	0.1	
Low-Level (Note 2)	$V_{OL}$	-	0,10	10	-	0	0.1	-	-	-	
Output Voltage		-	0, 5	5	4.9	5	-	4.9	5	_	
High Level Note 2)	V <sub>OH</sub>	-	0, 10	10	9.9	10	-	-	-	-	٧
Input Low Voltage	V <sub>IL</sub>	0.5, 4.5 0.5, 9.5	-	5 10	-	-	1.5 3	-	-	1.5	
Input High Voltage	V <sub>IH</sub>	0.5, 4.5 0.5, 9.5	-	5 10	3.5 7	-	-	3.5 -	-	-	1
Input Leakage Current	IIN	Any Input	0, 5 0, 10	5 10	-	-	±1 ±2	-	-	±1 -	
Three-State Output		0, 5	0,5	5			±1	_	_	±1	μΑ
Leakage Current	I <sub>OUT</sub>	0,10	0,10	10		<u> </u>	±1	_			ł
Operating Current (Note 3)		0,10	0,10								
External Clock	32kHz	T -	_	5		0.01	0.15	_	0.01	0.15	
External Clock	1 MHz	_	_	5	-	0.2	1	-	0.2	1	l
External Clock	2MHz	_	-	5		0.35	1.5	_	0.35	1.5	l
External Clock	4MHz	-	_	5	-	0.7	2	_	0.7	2	ł
External Clock	32kHz	-	-	10	-	0.03	0.25		-	-	I
External Clock	1MHz	_		10	<u> </u>	0.4	2		-		ł
External Clock	2MHz	-		10	<del>-</del>	0.4	3				I
External Clock	4MHz	-	-	10	<u> </u>	1.6	4.5		-		mA
XTAL Oscillator (Note 4)	32kHz	-	-	5	-	0.1	0.25		0.1	0.25	111/7
XTAL Oscillator (Note 4)	1MHz		-	5	<del>-</del>	0.1			0.1		I
XTAL Oscillator (Note 4)	2MHz	-	•	5	<u> </u>	0.3	0.5		0.3	0.5	
, ,		-	-		-		0.6	-		0.6	I
XTAL Oscillator (Note 4)	4MHz	-	-	5	-	0.6	0.8	-	0.6	0.8	I
XTAL Oscillator (Note 4)	1MHz	-	-	10		1.6	3		-		I
XTAL Oscillator (Note 4)	2MHz	-	-	10	-	1.8	3.5	-	-	-	
XTAL Oscillator (Note 4)	4MHz	-	-	10	-	2	5	-	-	-	

## Static Electrical Specifications at $T_A$ -40°C to +85°C $V_{DD} \pm 5\%$ , Unless Otherwise Specified (Continued)

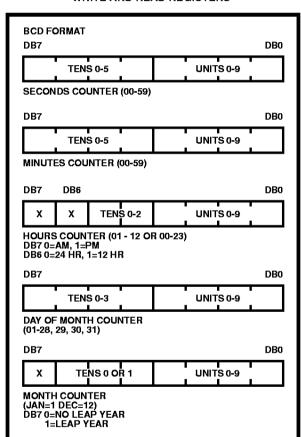
		CONDITIONS			LIMITS						
						CDP1879		1	CDPI879C-1	1	
PARAMETER	₹	v <sub>o</sub> (V)	ν <sub>IN</sub> (V)	V <sub>DD</sub> (V)	MIN	(NOTE 1) TYP	MAX	MIN	(NOTE 1) TYP	MAX	UNITS
Input Capacitance	CIN	-	-	-	-	5	7.5	-	5	7.5	рF
Output Capacitance	C <sub>OUT</sub>	-	-	-	-	10	15	-	10	15	
Maximum Clock Rise	t <sub>R</sub> , t <sub>F</sub>	-	-	5	-	-	10	-	-	10	μs
and Fall Times		-	-	10	-	-	1	-	-	-	

#### NOTES:

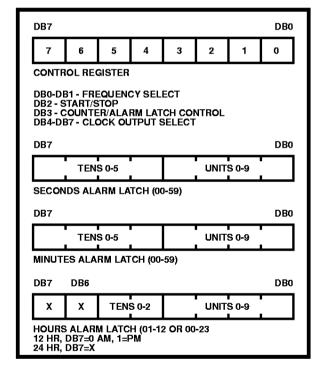
- 1. Typical values are for  $T_A = 25^{\circ}C$  and nominal  $V_{DD}$ .
- 2.  $I_{OL} = I_{OH} = 1\mu A$ .
- 3. Operating current measured with clockout = 488.2 µs and no load.
- 4. See Table 3 and Figure 6 for oscillator circuit information.

# **Programming Model**

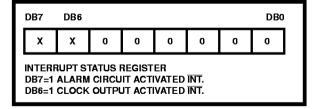
#### WRITE AND READ REGISTERS



#### WRITE ONLY REGISTERS



#### **READ ONLY REGISTER**



#### **REGISTER TRUTH TABLE**

	ADDRESS		ACTIVE SIGNAL		BIT 3 CONTROL	
<b>A</b> 2	<b>A</b> 1	AO	TPB/WR	RD	REGISTER	REGISTER OPERATION
0	1	0	X	-	0	Write Seconds Counter
0	1	0	-	Х	0	Read Seconds Counter
0	1	1	Х	-	0	Write Minutes Counter
0	1	1	-	Х	0	Read Minutes Counter
1	0	0	Х	-	0	Write Hours Counter
1	0	0	-	Х	0	Read Hours Counter
1	0	1	Х	-	0	Write Date Counter
1	0	1	-	X	0	Read Date Counter
1	1	0	Х	-	0	Write Month Counter
1	1	0	-	Х	0	Read Month Counter
0	1	0	Х	-	1	Write Seconds Alarm Latch
0	1	1	Х	-	1	Write Minutes Alarm Latch
1	0	0	Х		1	Write Hours Alarm Latch
1	1	1	Х	-	-	Write Control Register
1	1	1	-	Х	-	Read Int. Status Register

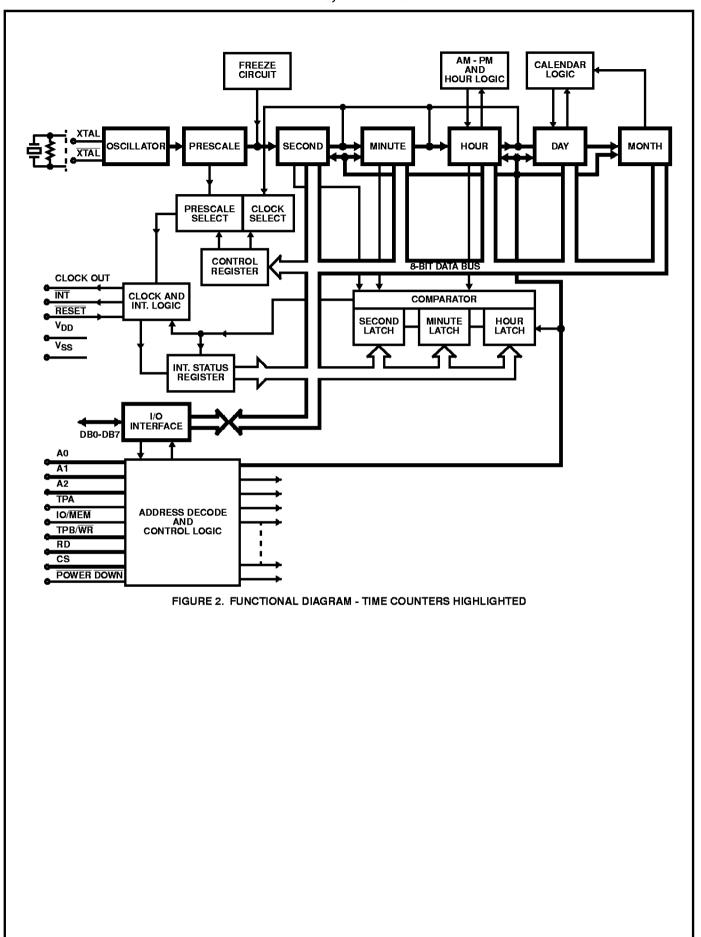
## General Operation

The real-time clock contains seconds, minutes, and hours, date and month counters that hold time of day/calendar information (see Figure 2). The frequency of an intrinsic oscillator is divided down to supply a once-a-second signal to the counter series string. The counters are separately addressable and can be written to or read from.

The real-time clock contains seconds, minutes and hour write-only alarm latches that store the alarm time (see Figure 3). When the value of the alarm latches and counters are equal, the interrupt output is activated. The interrupt output can also be activated by a clock output transition. The clock output is derived from the prescaler and counters and can be one of 15 square-wave signals. The value in the read-only interrupt status register identifies the interrupt source.

Operational control of the real-time clock is determined by the byte in a write-only control register. The 8-bit value in this register determines the correct divisor for the prescaler, a data direction and alarm enable bit, clock output select, and start/stop control (see Figure 4).

Data transfer and addressing are accomplished in two modes of operation, memory mapping and I/O mapping using the CDP1800-series microprocessors. The mode is selected by the level on an input pin. (IO/MEM). Memory mapping implies use of the address lines as chip selects and address inputs during linear selection or partial or full decoding methods. I/O mapping with the CDP1800-series microprocessors involves use of the N line outputs in conjunction with input and output instructions to transfer data to and from memory.



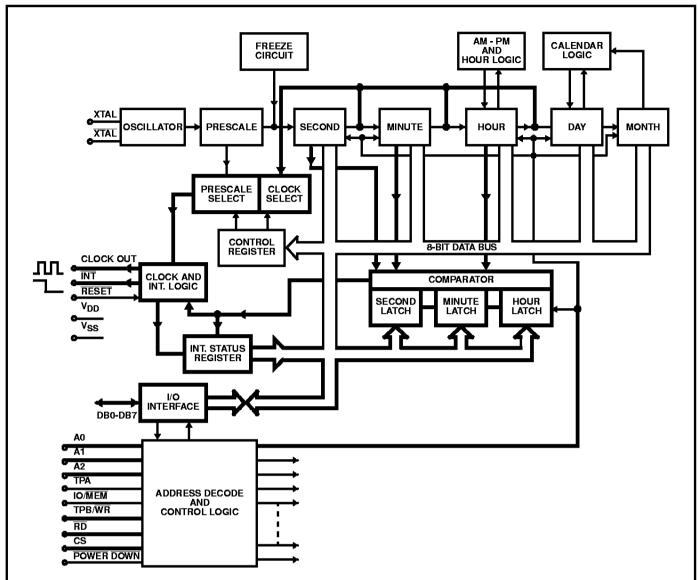


FIGURE 3. FUNCTIONAL DIAGRAM - ALARM CIRCUIT, CLOCK OUTPUT, INTERRUPT, AND STATUS REGISTERS HIGHLIGHTED

## Operational Sequence

Power is applied and the real-time clock is reset. This sets the interrupt output pin high. After the CS pin is set high and with address 7 on the address input lines, the control register is loaded via the data bus to configure the clock.

With selective addressing, the seconds through month counters are then written to and loaded to set the current time. The real-time clock will now hold the current "wall clock" time, with an accuracy determined by the crystal or external clock used. If the alarm function is desired, the control register is accessed and loaded again. This new byte will allow subsequent time data to be entered into the seconds, minutes and hours alarm latches. This sequence is also used when selecting one of the 15 available clock-out signals.

If the alarm function was selected, the interrupt output pin will be set low when the values in the seconds, minutes and hour alarm latches match those in the seconds, minutes and hour counters.

If one of the 15 sub second-to-day clock outputs is selected by the byte in the control register, the clock output pin toggles at that frequency (50% duty cycle) The interrupt output will also be set low on the first clock out negative transition. The interrupt source (alarm or clock out) can be determined by reading the interrupt status register. The clock output can be deselected by placing zero in the upper nibble of the control register if the alarm function is selected as the only interrupt source.

#### Counters

The counter section consists of an on-board oscillator, a prescaler and 5 counters that hold the time of day/calendar information (see Figure 2).

1 of 4 possible external crystals determine the frequency of the on-board oscillator (32,768Hz, 1.048576MHz, 2.097152MHz, 4.194304MHz). The oscillator output is divided down by a pres-

caler that supplies a once-a-second pulse to the counters. The seconds counter divide the pulse by 60 and its output clocks the minute counter every 60 seconds Further division by the minutes, hours, day of month and month counters result in 5 counters holding data that reflect the time/calendar from seconds to months. The counters are addressed separately and BCD data is transferred to and from via the data bus. The most significant bit of the hours counter (Bit 7) is user programmed to

indicate AM or PM and will be inverted every 12th hour. (0=AM, 1=PM). Bit 6 of the hours counter is user programmed to enable the hours counter for 12 or 24 hour operation. (0=24,1=12). If 24-hour operation is selected, the AM-PM bit is "don't care", but still toggles every 12th hour. Writing to the seconds counter resets the last 7 stages of the prescaler, allowing time accuracy to approximately 1/100 of a second.

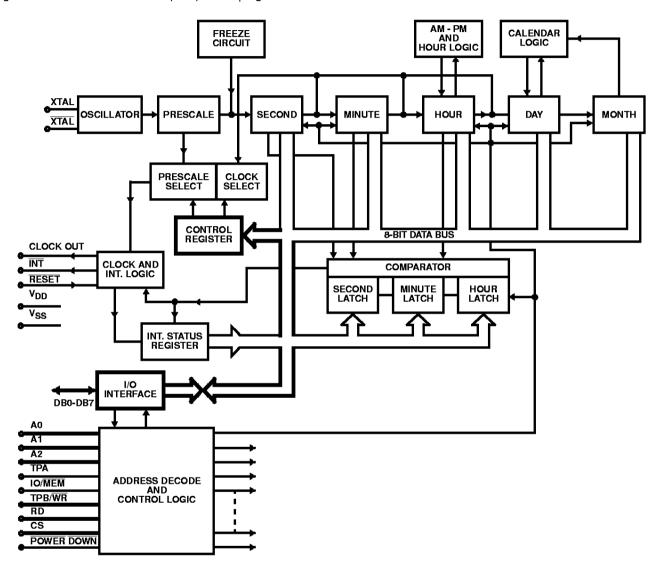


FIGURE 4. FUNCTIONAL DIAGRAM - CONTROL REGISTER HIGHLIGHTED

The most significant bit of the month counter is a Leap Year bit. If it is set to "1", the counter will count to February 29, then roll to March 1. If set to "0" it will go to March 1st after February 28th.

# Alarm And Interrupt Status Register

The alarm circuit consists of 1) seconds, minutes and hour alarm latches that hold the alarm time, 2) the outputs of the seconds, minutes and hour counters, and 3) a comparator that drives an interrupt output. The comparator senses the counter and alarm latch values and activates the interrupt output (active low) when they are equal (see Figure 3).

The write-only alarm latches have the same addresses as their comparable counters. Bit 3 in the control register determines data direction to the latches or counters and alarm enabling. For example, during a write cycle, if bit-3 in the control register is a "1", addressing the seconds counter or alarm latch will load the seconds alarm latch from the data bus and will enable the alarm function. Conversely, if bit-3 in the control register is a "0", addressing the seconds counter or alarm latch during a write cycle will place the value on the data bus into the seconds counter and will disable the alarm function. The interrupt output can be activated by the alarm circuit or the clock output. When an interrupt occurs, the

upper two bits of the interrupt status register identify the interrupt source. The interrupt status register has the same address as the control register. Addressing the interrupt status register with the  $\overline{\text{RD}}$  line active will place these register bits on the data bus. Bits 0-5 are held low. A "1" in bit-6 represents a clock output transition as the interrupt source. A "1" in bit-7 will identify the alarm circuit as the interrupt source.

Activating the reset pin (active low) resets the hour latch to "30" which prevents a match between alarm and time registers during an initialization procedure. Activating the reset pin or writing to the control register resets the interrupt output (high) and clears the interrupt status register

## **Clock Output**

One of 15 counter and prescaler overflows can be selected as a 50% duty cycle output signal that is available at the "clock out" pin. The frequency is selected by the upper nibble in the control register. For example, selecting a one-second clock output will result in a repetitive signal that will be high for 500ms and low for the same period. The high-to-low transition of the output signal will set the clock bit in the status register and activate the interrupt output. The level of the "clock out" signal is derived from the value in the counter. Example - if hours clock is selected and the minutes counter holds 4 minutes, the clock out will be low for 26 minutes and high for 30 minutes Thereafter, the clock out will toggle at a 50% duty cycle rate (see Table 1 and Figure 3).

#### CONTROL REGISTER (SEE TABLE 1 AND FIGURE 4)

BIT							BIT
7	6	5	4	3	2	1	0

#### CONTROL REGISTER BYTE

The 8-bit value in the control register determines the following:

Bit 0 and 1 - Frequency Select - Since there are one of 4
possible crystals the oscillator in the real-time clock can
operate with, these bit levels determine the prescaler divisor so that an accurate one second pulse is supplied to
the counter series string.

BIT 1	BIT 0	FREQUENCY
0	0	32,768Hz
0	1	1.048576MHz
1	0	2.097152MHz
1	1	4.194304MHz

- 2. Bit 2 Start-Stop Control Counter enabling is controlled by the value at this location. A "1" will allow the counters to function and a "0" in this location will disable the counters
- 3 Bit 3 Counter/Latch Control The level at this location controls two functions. It is required since the counters and alarm latches have the same addresses.

- A "0" in bit-3 will direct subsequent data to or from the counter selected and the alarm function will be disabled.
- 2) A "1" in bit-3 will direct subsequent data to or from the alarm latch and will enable the alarm.
- 4. Bits 4 to 7 Clock Select These bits select one of 15 square-wave signals that will be present at the "clock-out" pin. If bit-4 to bit-7 are zero's, the clock output pin will be high. If a clock is selected, the first high-to-low clock out transition will activate the interrupt pin (active low) and place a "1" in bit-6 of the status register. Writing to the control register or activating the reset pin will set the interrupt pin high and reset the interrupt status register.

Normal operation requires the control register to be written to and loaded first with a control word. However, subsequent writing to a counter if a "clock out" is selected may cause an interrupt out signal. Therefore, "clock-out" should be deselected by writing zero's into bit-4 through bit-7 if the interrupt is used. When the counters are loaded, the control register is again written to with the value in the upper nibble selecting the "clock out" signal. See Table 1.

## Read And Write Signals

When the IO/MEM pin is low, the real-time clock is enabled for memory mapped operation. Data on the bus is placed in, or read from a counter, alarm latch or register by 1) placing the CS pin high, 2) selective addressing, 3) placing the TPB/WR pin low during a write cycle with the RD pin high or 4) setting the RD pin low during a read cycle with this TPB/WR pin high.

The I/O mapping mode used with the CDP1800 series microprocessor is selected by setting the IO/ $\overline{\text{MEM}}$  pin high. The TPB/ $\overline{\text{WR}}$  pin on the real-time clock is connected to the TPB output pin of the microprocessor. Data on that bus is written to or read from the counters, latches and registers by 1) placing the CS pin high, 2) selective addressing utilizing the microprocessor N lines and I/O instructions, 3) placing the TPB/ $\overline{\text{WR}}$  pin high with the  $\overline{\text{RD}}$  pin low during an output or write operation (data is latched on TPB's trailing edge), 4) setting the  $\overline{\text{RD}}$  line high during an input or read operation. Data is placed on the bus by the real-time clock between the trailing edges of TPA and TPB.

## Freeze Circuit

Since writing to or reading from the counters or alarm latches is performed asynchronously, the once-a-second signal from the prescaler may pulse the counter series string during these operations. This can result in erroneous data. To avoid this occurring, a transparent "freeze" circuit is incorporated into the real-time clock. This circuit is designed to trap and hold the one-second input clock transition if it occurs during access times. When the operations are completed, it is inserted into the counter series string. To utilize the "freeze" circuit, address "1" (A0 = 1, A1 = 0, A2 = 0) is selected first while performing a write operation. Read or write accesses may now be performed with assurance the data is stable. All operations must be concluded within

250ms of the address "1" access. In memory mapping any dummy write operation after selecting address "1" will set the "freeze" circuit. If using the I/O mode, a 61 output instruction will perform the same function. There is no time restriction on subsequent accesses as long as the read or write operations are preceded by selecting address "1".

#### Power Down

Power down operation is initiated with a low signal on the "POWER DOWN" input pin. In conjunction with the interrupt output, it is used to supply external control circuits with a 3 level control signal. The operating current is not appreciably reduced during "POWER DOWN" operation. When power down is initiated, any inputs on the address or data bus are ignored. The clock output is set low. The interrupt output is three-stated. If enabled previously, the alarm circuitry is active and will set the interrupt output pin low when alarm time occurs. The interrupt output will also go low if a clock was selected and an internal high-to-low transition occurs during power down. The clock output pin will remain low. If power down is initiated in the middle of a read or write sequence, it will not become activated until the read or write cycle is completed.

#### Pin Functions

VDD, VSS - Power and ground for device.

**DB0 - DB7 - DATA BUS -** 8-bit bidirectional bus that transfers BCD data to and from the counters, latches and registers

A0, A1, A2 - Address inputs that select a counter, latch or register to read from or write to.

**TPA** - Strobe input used to latch the value on the chip select pin. CS is latched on the trailing edge of TPA. During memory mapping, it is used to latch the high order address bit used for the chip select. When the real-time clock is used with other microprocessors, or when the high order address of the CDP1800 series microprocessor is externally latched, it is connected to V<sub>DD</sub>. In the input/output mode, it is used to gate the N lines.

**IO/MEM** - Tied low during memory mapping and high when the input/output mode of the CDP1800 series microprocessor is used.

**RD**, **TPB/WR** - **Direction Signals** - Active signals that determine data direction flow. In the memory mapped mode, data is placed on the bus from the counters or status register when  $\overline{\text{RD}}$  pin is active.

Data is transferred to a counter, latch or the control register when  $\overline{RD}$  is high and TPB/WR is active and latched on the trailing edge (low to high) of the TPB/WR signal.

In the input/output mode, data is placed on the bus from a counter or status register when RD is not active between the trailing edges of TPA and TPB. Data on the bus is written to a counter, latch, or the control register during TPB when  $\overline{\text{RD}}$  is active and latched on TPB's trailing edge. The following connections are required between the microprocessor and real-time clock in the CDP1800 series I/O mode.

#### Microprocessor Real-Time Clock

MRD	RD
TPB	TPB/WR
TPA	TPA
N LINES	ADDRESS LINES
IO/MEM	V <sub>DD</sub>

**CS - CHIP SELECT -** Used to enable or disable the inputs and outputs. TPA is used to strobe and latch a positive level on this pin to enable the device.

**XTAL AND XTAL** - The frequency of the internal oscillator is determined by the value of the crystal connected to these pins. "XTAL" may be driven directly by an external frequency source.

Clock Out - 1 of 15 square wave frequencies will appear at this pin when selected. During power down, this pin will be placed low, and will be high during normal operation when the clock is deselected.

**Power Down - Power Down Control -** A low on this pin will place the device in the power down mode.

**INT** - Interrupt Output - A low on this pin indicates an active alarm time or high-to-low transition of the "clock out" signal.

**RESET -** A low on this pin clears the status register and places the interrupt output pin high.

## Frequency Input Requirements

The Real-Time Clock operates with the following frequency input sources:

- An external crystal that is used with the on-board oscillator. The oscillator is biased by a large feedback resistor and oscillates at the crystal frequency (see Figure 6, Table 3).
- An external frequency input that is supplied at the XTAL input. XTAL is left open (see Figure 5). A typical external oscillator circuit is shown in Figure 7 in section, "Standby (Timekeeping) Voltage Operation".

TABLE 3. TYPICAL OSCILLATOR CIRCUIT PARAMETERS FOR SUGGESTED OSCILLATOR CIRCUIT, SEE FIGURE 6

PARAMETER	4.197MHz	2.097MHz 1.049MHz		32768Hz (NOTE)	UNITS
R <sub>F</sub>	22	22	22	22	МΩ
C <sub>0</sub>	39	39	39	39	pF
C <sub>1</sub>	5	5	5	5	pF
R <sub>S</sub>	-	-	-	200	kΩ
C <sub>L</sub>	-	-	-	91	pF
Crystal Impedance	73	200	200	50K (max.)	Ω

NOTE: CDP1879C-1 only.

#### **Design Considerations for Stable Crystal Oscillation**

- Stray capacitances should be minimized for best oscillator performance. Circuit board traces should be kept to a maximum of 1 inch, and there should be no parallel traces.
- A signal line or power source line must not cross or go near the oscillator circuit line.
- 3. It is advisable to put a 0.1  $\mu F$  capacitor between  $V_{DD}$  and  $V_{SS}$  of the CDP1879.

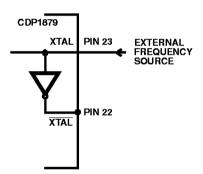


FIGURE 5. CONNECTIONS FOR AN EXTERNAL FREQUENCY SOURCE APPLIED TO REAL-TIME CLOCK

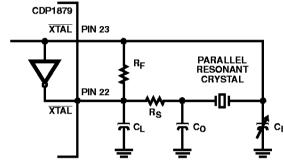


FIGURE 6. SUGGESTED OSCILLATOR CIRCUIT APPLIED TO REAL-TIME CLOCK (SEE TABLE 3)

## Standby (Timekeeping) Voltage Operation

When any one of the four specified crystals is used with the on-board oscillator, the Real-Time Clock can operate at a minimum of 4V  $V_{DD}$ . However, at 32kHz the clock will run (timekeeping only, no device READ/WRITE accesses) down to 3V at -40°C to +85°C and 2.5V at 0° to +70°C.

To achieve this low voltage operation, an external 32kHz clock source must be supplied at the XTAL input (see Figure 7). The standby requirements for CHIP SELECT/DESELECT are listed in Table 4, and Figure 8 indicates the timing waveforms. Figure 9 illustrates the typical timekeeping curve over the full temperature range.

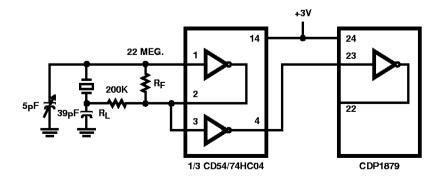
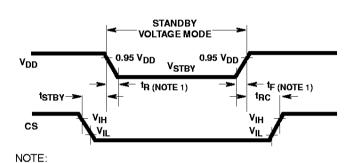


FIGURE 7. TYPICAL EXTERNAL CLOCK-SOURCE CIRCUIT

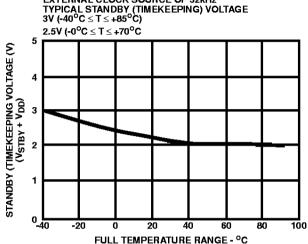
#### STANDBY (TIMEKEEPING) CHARACTERISTICS AT FULL TEMPERATURE RANGE

	\ <sub>\\-</sub>	\ \ <sub>V</sub>	CDP1879		CDP1879C-1		]
PARAMETER	V <sub>DD</sub> (V)	V <sub>STBY</sub> (V)	MIN	MAX	MIN	MAX	UNITS
Chip Deselect to Standby t <sub>CSTBY</sub> (Timekeeping) Voltage Time	5 10	2.5, 3 2.5, 3	2 1	-	2	-	
Recovery to Normal t <sub>RC</sub> Operation Time	5 10	2.5, 3 2.5, 3	2 1	-	2 -	-	μs



1. t<sub>R</sub>, t<sub>F</sub>≥1μs

FIGURE 8. STANDBY (TIMEKEEPING) VOLTAGE AND TIMING WAVEFORMS



**EXTERNAL CLOCK SOURCE OF 32kHz** 

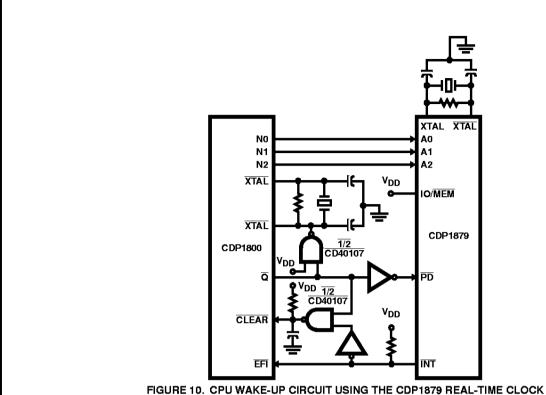
FIGURE 9. TYPICAL STANDBY (TIMEKEEPING) VOLTAGE vs FULL TEMPERATURE RANGE

## **Applications**

A typical application for this real-time clock is as a wake-up control to a CPU to reduce total system power in intermittent-use systems. A hookup diagram illustrating this feature is shown in Figure 10. In this configuration, the alarm and power-down features of the CDP1879 are utilized in the control of the sleep and wake-up states of the CPU. A typical shut-down/start-up sequence for this system could proceed as follows:

- The CPU has finished a current task and will be inactive for the next six hours.
- The CPU loads the CDP1879 alarm registers with the desired wake-up time.
- The CDP1800 Q output is set high, which stops the CPU oscillator (as an alternative, in an NMOS system, power to all components except the clock chip could be shut off).

- This Q output signal is received by the CDP1879 as a power-down signal.
- 5. The CDP1879 three-states the interrupt output pin.
- 6. The CDP1879 eventually times out, and sets an alarm by driving the  $\overline{\text{INT}}$  output low.
- The alarm signal resets the CPU (to avoid oscillator startup problems) and flags the processor for a warm-start routine.
- The CPU, once into its normal software sequence, writes to the CDP1879 control register to reset the interrupt request.



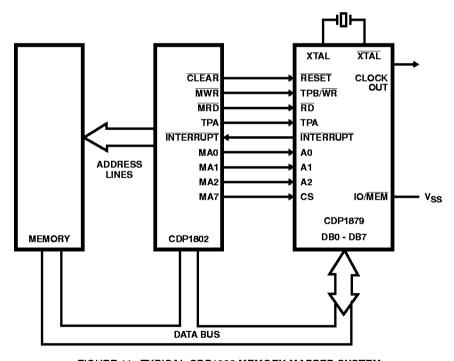


FIGURE 11. TYPICAL CDP1802 MEMORY MAPPED SYSTEM

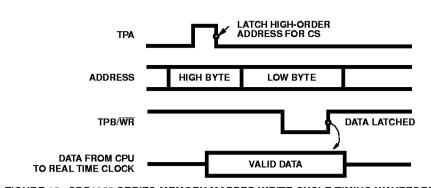


FIGURE 12. CDP1800 SERIES MEMORY MAPPED WRITE CYCLE TIMING WAVEFORMS

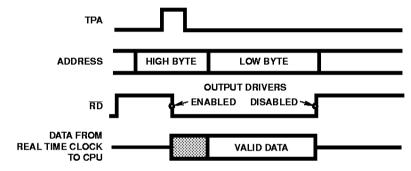


FIGURE 13. CDP1800 SERIES MEMORY MAPPED READ CYCLE TIMING WAVEFORMS

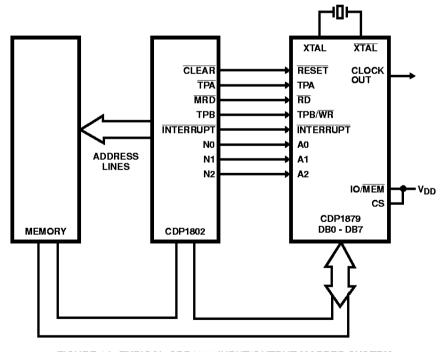


FIGURE 14. TYPICAL CDP1802 INPUT/OUTPUT MAPPED SYSTEM

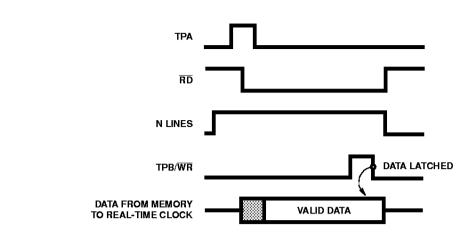


FIGURE 15. CDP1800 SERIES INPUT/OUTPUT MAPPING TIMING WAVEFORMS WITH OUTPUT INSTRUCTION

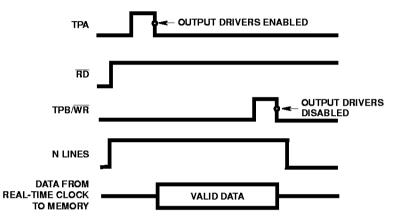


FIGURE 16. CDP1800 SERIES INPUT/OUTPUT MAPPING TIMING WAVEFORMS WITH INPUT INSTRUCTION

**Dynamic Electrical Specifications** at  $T_A$  -40°C to +85°C, Input  $t_{R_i}$   $t_F$  = 10ns,  $C_L$  = 50pF

				LII	LIMITS			
PARAMETER		V <sub>DD</sub> (V)	CDP1879		CDP1879C-1		1	
			(NOTE 1) MIN	MAX	(NOTE 1) MIN	MAX	UNITS	
Read Cycle Times (See Figure 17	')							
Data Access from Address	t <sub>DA</sub>	5	-	400	-	400		
	Ī	10	-	190	-	-	1	
Read Pulse Width	t <sub>RD</sub>	5	270	-	270	-	1	
	Ī	10	160	-	-	-	1	
Data Access from Read	t <sub>DR</sub>	5	-	375	-	375	1	
		10	-	170	-	-	1	
Address Hold after Read	t <sub>RH</sub>	5	0	-	0	-	ns	
	Ī	10	0	-	-	-	1	
Output Hold after Read	t <sub>DH</sub>	5	50	230	50	230	1	
	1	10	40	130	-	-	1	
Chip Select Setup to TPA	t <sub>CS</sub>	5	50	-	50	-		
	Ī	10	30	-	-	-	1	

## NOTE:

<sup>1.</sup> Time required by a limit device to allow for the indicated function.

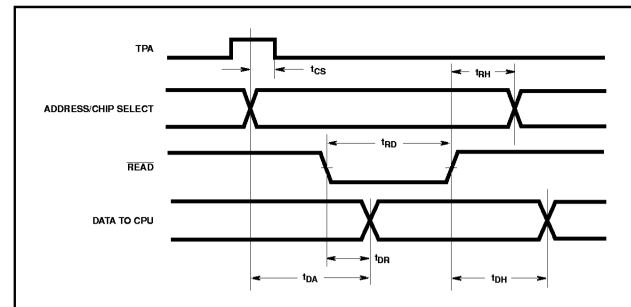


FIGURE 17. READ CYCLE TIMING WAVEFORMS

**Dynamic Electrical Specifications** at  $T_A$  -40°C to +85°C, Input  $t_R$ ,  $t_F$  = 10ns,  $C_L$  = 50 pF

			LIMITS				
PARAMETER		V <sub>DD</sub> (V)	CDP1879		CDP1879C-1		
			(NOTE 1) MIN	MAX	(NOTE 1) MIN	MAX	UNITS
Write Cycle Times (See Figure 18)							
Address Setup to Write	t <sub>AS</sub>	5 10	225 110	-	225 -	- -	
Write Pulse Width	t <sub>WR</sub>	5 10	150 70	-	150 -	<del>-</del> -	
Data Setup to Write	t <sub>DS</sub>	5 10	65 30	-	65 -	- -	
Address Hold after Write	t <sub>AH</sub>	5 10	0 0	- -	0 -	<del>-</del> -	ns
Data Hold after Write	t <sub>WH</sub>	5 10	150 80	- -	150 -	- -	
Chip Select Setup to TPA	tcs	5 10	50 30	- -	50 -	- -	

## NOTE:

<sup>1.</sup> Time required by a limit device to allow for the indicated function.

