

P.C.B.MOUNTING DETAIL

				Р.(C.B.MOUI	NTING DETAI	_
VERSION	深圳市百斯特电子有限公司		MODEL: EC11I-152			DRAW	SCALE
A 0			DRAWING NO:				3: 1
. ISSU.	DATE	REVISION	Design	Design TOL. UNLESS OTHERWISE SPEC.		CHKD	UNIT
0.0	2014-09-01	ORIGINAL DRAWING		BASIC DIMENSIONS	TOL.		UNII
01				L ≤ 10	± 0.3		mm
02				10 < L	± 0.5	APPD	
03				100 ≤ L	± 0.8		
04				ANGLE	± 5°		第 1 页

EC11 FORWARD DIRECTION SERIES SPECIFICATION

1. 一般事项General

1-1. 适用规格 Scope

本规格书适用于微小电流回路的电子设备,属11型回转型编码器.

This specification applies to 11mm size low-profile rotary encoder (incremental type)

for microscopic current circuits, used in electronic equipment.

1-2. 标准状态Standard atmospheric conditions

除另有规定外,测量应在以下状态下进行:

Unless otherwise specified, the standard range of atmospheric conditions for making measurements and test is as following limits:

温 度 Ambient temperature: 15℃ to 35℃ 相对湿度 Relative humidity : 25% to 85% 气 压 Air pressure :86kpa to 106kpa

如果对在上述所提到的条件中所做的实测值有疑问的话,应使用以下条件进行测量:

If doubt arises on the decision based on the measured values under the above-mentioned conditions, the following conditions shall be employed:

温 度 Ambient temperature: 20±1℃ 相对湿度 Relative humidity : 63% to 67% 气 压 Air pressure :86kpa to 106kpa

1-3. 使用温度范围

Operating temperature range :-30℃ to+80℃

1-4. 保存温度范围

Storage temperature range : -40℃ to+85℃

2. 构造Construction

2-1.尺寸 Dimensions

见所附成品图 Refer to attached drawing

3. 额定值 Rating

3-1. 额定电压

Rated voltage: DC 5V

3-2. 最大额定电流 (阻抗负载)

Maximum operating current (resistive load) 各相导线 Each lead: 0.5mA(Max 5mA; Min 0.5mA) 公共导线Common lead: 1mA(Max 10mA; Min 0.5mA)

4. 使用上的事项Application Notes

4-1. 避免储藏于高温潮湿及腐蚀的场所. 产品购入后尽可能在6个月内使用完. 拆包装后未使用完的剩余产品需储藏于防潮防毒的环境下.

Avoid storing the products in a place at high temperature, high humidity and in Corrosive gases. Please use this product as soon as possible with 6 months limitation. If any remainder left after packing is opened, please store it with proper moisture proofing, gasproofing etc.

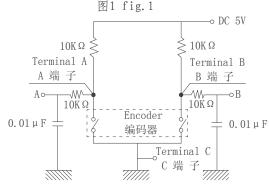
- 4-2. 编码器信号的计算方法应将操作的速度,信号的取样时间及电子回路中的微电脑软体等考虑进去.
 The encoder pulses count method should be designed with taking operating speed, sampling time and esign of the microcomputer software into cosideration.
- 4-3. 此产品在定位点的输出波形参照(5-1),因此在设计软体时请留意其状态,推荐以A相位为参考基准。 With this products the detent position output consult fig. 5-1. Therefore make the A phase the reference at the soft ware design stage. Recommended that use A output signal for the reference.
- 4-4. 在设计时要考虑到杂讯, 建议使用R/C滤波电路, (图1)

At design of the pulse count process. Using the C/R filter circuit is Recommended. (fig. 1)

4-5. 本产品请勿碰触到水,可能会导致输出波形的异常.

Care must be taken not to expose this product to water or dew to prevent possible problem in pluses output waveform.





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5. 电气性能 Electrical Characteristics						
项目						
ITEM		CONDITIONS	13	SPECIFICATIONS		
A、B两信号输出相位差,输出波形详细见(图2/3)(虚线表示带卡点装置的上擎子处位置)				•		
	2 Phase-different si	gnals (signal A	, signal B) Details	shown in <fig. 2="" 3=""></fig.>		
	(The broken line show					
	轴回转方向	信号		输出波形		
	Shaft rotati-	Signal		Output		
5-1. 输出信号	onal direction		图2 fig. 2 图3 fig. 3			
Output signal		A (A-C端子间)	OFF	OFF -		
format	顺时针方向	A(TerminalA-C)	ON	DN L L		
	C. W	B(B-C端子间)	OFF — i	OFF H		
		B(TerminalB-C)	ON			
		A (A-C端子间)	0FF — ! — !	OFF H		
	逆时针方向	A(TerminalA-C)	ON			
	C. C. W	B(B-C端子间)	OFF 7	OFF -		
		B(TerminalB-C)	ON -	ON		
				■15 个脉冲/360°(图2)		
5-2. 分解能力	回转360°的输出脉冲数	t.	236-	15pulses/360° (fig. 2)		
Resolution	Number of pulses in	360° rotation.	不 对	□20个脉冲/360° (图3)		
	20pulses/360° (fig. 3)					
	下(图4)所示回路, 轴	b以360°/S的速度	转动测定。			
	Measurement shall be	made under the	condition as follow	vs.		
	Shaft rotational spec	ed: 360°/S	Test circuit : (fi	ig. 4)		
		图4〈fig.4〉		图5〈fig.5〉		
	DC 5V OFF — A A A A A					
	$10K\Omega$ \geqslant $10K\Omega$ $3.5V - + - + + + + - +$					
5-3. 开关特性	Terminal A	<u></u>	erminal B	/\		
Switching	A 端 子		B 端 子 1.5V	<u>-</u>		
characteristics	' 编码器 ON V V V V					
	→ Terminal C					
	//////, C 端 子					
	(注)编码OFF指输出电压3.5V以上的状态(fig.5).					
	Code-OFF area: The area which the voltage is 3.5V or more (fig. 5).					
	编码ON指输出电压1.5V以下的状态(fig.5).					
			the voltage is 1.5	5V or less (fig. 5).		
	编码从0FF→0N或0N→0					
5-3-1. 振荡	间. 应符合规定Specific			t1, t3 ≤ 3mS		
Chattering	time from 1.5V to 3.		hing	ŕ		
position(code OFF ~ ON or ON ~ OFF)						
编码0N部份的1.5V以上的电压变动时间在振荡t1,t3之						
	间会产生1mS以上, 1.5V以下的0N部份. 另外, 如果各突跳					
5-3-2. 滑动杂讯 1. 5V以下的范围在1mS以上时,则判定为另一个突跳. (突跳) Sliding Specified by the time of voltage change exceed						
				2.42.7		
noise (Bounce)	1.5V in code-ON area . When the bounce has code $t 2 \leqslant 2 \text{mS}$					
	-ON time less than 1mS between chattering (tlor					
t3) the voltage change shall be regarded as a part of						
	chattering. When the code-ONtime between 2 bounces is					
	less than 1mS, they are regarded as 1 linked bounce.					

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5-3-3. 滑动噪音	编码0FF部份的电压变动。	3.5V以上				
Sliding noise	The voltage change in code-OFF area.	3.5Vmin				
	下(图6)所示回路,轴以360°/S的速度转动测定。					
	Measurement shall be made under the condition					
	which the shaft is rotated at 60r/min					
5-4. 相差位	T	T1、T2、T3、T4≥0.08T				
Phase	A信号(A~C间) OFF	见图6 (fig.6)				
difference	signal A 图6 fig.6					
	OFF					
	B信号(B~C间)0N					
	signal B $T_1T_2T_3T_4$					
	C.W Direction					
5-5. 绝缘阻抗	在端子和支架间施加电压 250V DC。					
Insulation	Measurement shall be made under the condition	100ΜΩ 以上				
resistance	which a voltage of 250V DC is applied between	100MΩ Min				
	individual terminals and frame.					
5-6. 耐电压	在端子和支架间施加AC300V电压1分钟	不得有绝缘破坏				
Dielectric	A voltage of 300V AC shall be applied for	Without arcing or breakdown.				
strength	1 minute between individual terminals and frame.	J 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1				
	出力信号处于ON时安定状态条件下测定。	10以下				
	Measurement shall be stable condition which a	1ΩMax				
	output signal is ON.	49				
6. 机械性能 Mecha	nical Characteristics	1				
6-1. 全回转角度		360° (无止档点)				
Total ratational angle		360° (Endless)				
6-2. 定位点力矩	只适用于附卡点装置	$2 \sim 15$ mN. m. $(20 \sim 150$ gf. cm)				
Detent torque	Only suitable for C.C, equipment.					
	只适用于附卡点装置	■30点定位间隔角度12° ± 2°				
Number	Only suitable for C.C, equipment.	30detents Step angle: 12° ± 2°				
and position		□20点定位间隔角度18°±2°				
of detent		20detents Step angle: 18° ± 2°				
6-4. 轴的推拉强度	在轴端,沿轴向施加 8Kg 的静负荷力推和拉各10秒钟	轴向虚位间隙0.4以内				
Push-pull	(产品焊锡固定在PCB上。)	Shaft play in axial				
strength of	Push and pull static load of 8Kg shall be	direction 0.4 Max				
shaf t	applied to the shaft in the axial direction for					
	10s. (After soldering of the PC board)					
6-5. 端子强度	在端子的先端施加5N (500g)的力1分钟。	端子无损坏,无过度的松动.允许变形.				
Terminal	A static load of 5N(500g) be applied to the tip of	Without damage or excessive				
strength	terminals for 1 minute in any direction.	looseness of terminals. terminal				
_		bend is permitted.				
6-6. 轴套螺纹紧固强度		7. 0kgf. cm以上				
Bushing Nut		7. Okgf. cm Min				
Tighten Strength						
6-7. 轴向间隙		0.4mm 以下				
Shaft play in axial		0.4mm Max				
direction						
	在距离轴顶端5MM处,沿径向瞬间施加50mN.m(500gf.cm)的	0.7*L/30mm p-p 以下 (L: 指				
6-8. 轴摆动	力测试	安装平面到轴的柄端的距离.)				
Shaft wobble	A momentary load of 500gf.cm should be applied at the	0.7*L/30mm p-p Max				
	point 5mm from the tip of the shaft in a direction	L: Distance between mounting surface				
	perpendicular to the axis of shaft.	and measuring point on the shaft				
6-9. 轴的回转方向摆动	用角度板测定.	5°以下				
Shaft play	Testing by angle board.	5° Max				
in rotational						
wobble						

EC11 FORWARD DIRECTION SERIES SPECIFICATION

EC11 FORWARD DIRECTION SERIES SPECIFICATION 7 耐久性能 Endurance Characteristics						
项目	条件	规格				
ITEM	CONDITIONS	SPECIFICATIONS				
	在无负荷条件下轴以600~1000周/小时速度回转,	■在力矩≤100gf.cm时30,000±200周				
	一日连续5000~8000次.	$30,000 \pm 200$ cycles per below 100gf.cm.				
	The shaft of encoder shall be rotated at a speed of	□在力矩 > 100gf. cm时15,000 ± 200周.				
7-1. 回转寿命	600 ~ 1000cycles/H without electrical load, after with	$15,000 \pm 200$ cycles per above 100gf.cm.				
Rotational	measurements shall be made.	振荡 t1, t3≤5mS. 突跳 t2≤3mS.				
life	(5000 to 8000 continuous cycles for 24 hours.)	尚余有轻微定位感.				
		端子间接触阻抗200Ω以下				
		Chattiring t1, t3 \leq 5mS. Bounce t2 \leq 3mS.				
		Detent feeling has to remains				
		Contact resistance 200ΩMax				
	温度40±2℃,湿度90~95%的恒温恒湿槽中放置96±4	所有项应满足初期规格				
	小时后,在常温、常湿中放置1.5小时后测试. The	Specifications in clause				
7-2. 耐湿性	encoder shall be stored at temperature of 40 $\pm 2^{\circ}$ C	all items is shall be				
Damp heat	with relative humidity of 90% to95% for96 ± 4H	satisfied.				
	in a thermostatic chamber. And the encoder shall	3 kg				
	be subjected to standard atmospheric conditions	W. 1				
	for 1.5H, After which measurements shall be made.	17 十元 1				
	温度85±3℃的恒温箱中放置96±4小时, 常温、常湿放置1.5小时后测试.	所有项应满足初期规格。 Specifications in clause				
7-3. 耐热性	The encoder shall be stored at a temperature of	all items is shall be				
Dry heat	85 ± 3°C for 96 ± 4H in a thermostatic chamber. And	satisfied.				
Diy neat	then the encoder. shall be subjected to standard	Satisfied.				
	atmospheric conditions for 1.5H, After which					
	measurements shall be made.					
	温度-40±3℃的恒温箱中放置96±4小时,	所有项应满足初期规格。				
	常温、常湿放置1.5小时后测试.	Specifications in clause				
	The encoder shall be stored at a temperature of	all items is shall be				
7-4. 低温特性	-40 ± 3 C for 96 ± 4 H in a thermostatic chamber. And	satisfied.				
Cold	then the encoder shall be subjected to standard					
	atmospheric conditions for 1.5H, After which					
	measurements shall be made.					
	槽焊 Dip soldering.	不得有绝缘体的破损、变形、				
7-5. 焊锡耐热性	使用基板: t=1.6mm的单面覆铜板.	接触无异常.				
Resistance	Printed wiring board: single-sided copper clad	Electrical characteristics				
to Soldering	laminate board with thickness of 1.6mm.	shall be satisfied No				
heat	预热: 基板表面温度100℃以下, 时间1分钟以内.	mechanical abnormality.				
	Preheating: 1. Surface temperature of board: 100°C. or less 2. Preheating time: within 1 minute.					
	/					
	Soldering: Solder temperature: 260 ± 5 °C or less					
	Immersion time: within 3S					
	手焊 Manual soldering.					
	温度300℃以下,时间3秒以内.					
	Bit temperature of soldering iron: 300℃less than					
	Application time of soldering iron: within 3S					
	端子在260℃±5℃温度的焊锡槽内浸锡3秒±0.5秒.	浸渍面须有75%以上焊锡附着				
7-6. 焊锡性	The terminals shall be immersed into solder bath	A new uniform coating of				
Solderability	at 260°C for 3S ± 0.5S.	solder shall cover75% minimum				
		of the surface being immersed.				

EC11 FORWARD DIRECTION SERIES SPECIFICATION

推动开关部分Push Switch Portion

备注: 以下规格适用于RE11编码器带开关系列.

Note: The following specification is only suitable for the one type with switch construction of RE11 encoder series.

1. 额定值 Rating

1-1. 额定电压 Rated voltage: DC 5V

1-2 是大麵宁由流 (阳站角點)

1-2. 最大额定电流(Maximum operat	(阻抗负载) zing current (resistive	e load):10mA Max					
2. 电气性能 Elect							
项目	条件			规格			
ITEM	CONDITIONS			SPECIF	ICATIONS		
2-1. 接触电阻	用DC 5V 1mA 电压测定.	用DC 5V 1mA 电压测定.			$\leq 100 \text{m}\Omega$		
Contact	Voltage test at DC	5V 1mA.		$100m\Omega$ or less			
resistance							
2-2. 绝缘阻抗	在端子和安装板间施加电压 250V DC.			3.5			
Insulation	Measurement shall be	made under the	condition	100ΜΩ 以上			
resistance which a voltage of 250V DC is applied between $100 \text{M}\Omega$ Min							
	individual terminals	and bushing and	l plank.				
2-3. 振荡	以1秒钟1往返(0FF-0N-	0FF) 按压动作.		≤ 10mS			
Bouncing	Shaft shall be push a	at 1 cycles/s(OF	FF-ON-OFF)	10mS or less			
2-4. 耐电压	在端子和安装板间施加	AC300V电压1分钟		不得有绝缘破坏			
Dielectric	A voltage of 300V AC shall be applied for 1 minute			Without arcing or	breakdown.		
strength	between individual to	erminals and bus	hing and plank.				
3 机械性能 Mech	anical Characterist	ics					
3-1. 开关电路				单极单投(按压ON)			
接点数				Single pole and single throw			
Switch circuit and				(push ON)			
number of pulse							
3-2. 开关动作力	在轴端,沿轴向施加的:	按压力.					
Operation	Push static load to	the shaft in the	axial	$500 \pm 200 gf$			
fore of switch	direction			3.35			
3-3. 开关移动量					■ 0. 5 ± 0. 3 mm		
Travel of switch					□ 1.5 ± 0.5 mm		
4 耐久性能 Endur	ance Characteristic	cs					
	在无负荷条件下沿轴向施以1Kgf以下的力,以600次/小时			■20,000±200次. (0.5行程)			
	的速度按压。				20,000 ± 200cycles. (0.5 Travel)		
	Push 1Kgf to the share				□15,000±200次. (1.5行程)		
4-1. 按压寿命	direction under non-				15,000 ± 200cycles. (1.5 Travel)		
Push-life	Push-life of 600 times/hour.			接触电阻: ≤200mΩ. 其它应满足初期规格			
				Contact resistance: $200\text{m}\Omega$ or less. Specification in clause shall be satisfied.			
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