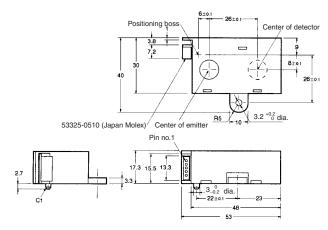
OMRON

Multiple Beam Sensor (3 Beams: 50 mm) EY3A-3051

Dimensions

Note: All units are in millimeters unless otherwise indicated.



Pin no.	Remarks	Name			
1	01	Output 1 (OUT 1)		T 1)	
2	O2	Output 2 (OUT 2)			
3	O3	Output 3 (OUT 3)		T 3)	
4	V		Power supply (Vcc)		
5	G	G	around (GND))	
Unless o	therwise sp	e	cified, the tol	eran	ces are as shown below.
Dimensions			Tolerance		
3 mm max.			±0.3		
3 < mm ≤ 6		±0.375			
6 < mm ≤ 10		±0.45			
10 < mm ≤ 18		±0.55			

±0.65

±0.8

±0.95

18 < mm ≤ 30

30 < mm ≤ 50

50 < mm ≤ 80

Recommended Mating Connectors: Japan Molex 51090-0500 (crimp connector)

52484-0510 (press-fit connector)

Features

- Simultaneously senses three objects positioned differently, thus saving space.
- Ensures higher sensitivity and external light interference resistivity than any other photomicrosensor.
- Narrow sensing range ensures stable sensing of a variety of sensing objects.

Application Examples

Sensing of paper sizes.

■ Absolute Maximum Ratings (Ta = 25° C)

Item		Symbol	Rated value
Power supply voltage		V _{cc}	7 V
Load voltage		V _{OUT}	7 V
Load current		I _{OUT}	10 mA
Ambient	Operating	Topr	0°C to 65°C
temperature	Storage	Tstg	-15° C to 70° C

Note: Make sure there is no icing or condensation when operating the Sensor.

Ordering Information

Description	Model
Multiple beam sensor	EY3A-3051

■ Electrical and Optical Characteristics (Ta = 0° C to 65° C)

Item	Value	Condition
Power supply voltage	5 V ±5%	
Current consumption	50 mA max.	$V_{CC} = 5 V, R_L = \infty$
Peak current consumption	300 mA max.	$V_{CC} = 5 V, R_L = \infty$
Low-level output voltage	0.6 V max.	$V_{CC} = 5 \text{ V}, I_{OL} = 4 \text{ mA} \text{ (see note 1)}$
High-level output voltage	3.5 V min.	$V_{CC} = 5 \text{ V}, \text{ R}_{L} = 4.7 \text{ k}\Omega \text{ (see note 2)}$
Response delay time (high to low)	35 ms max.	The time required for the output to become "Lo" after placing sensing object.
Response delay time (low to high)	20 ms max.	The time required for the output to become "Hi" after removing sensing object.

Note: 1. These conditions are for the sensing of lusterless paper with an OD of 0.8 maximum located at the correct sensing position of the Sensor as shown in the optical path arrangement on the next page.

2. These conditions are for the sensing of the paper supporting plate with an OD of 0.05 located using the glass plate without paper as shown in the optical path arrangement on the next page.

Characteristics (Paper Table Glass: t = 6 mm max., Transparency Rate: 90% min.) (Ta =0° C to 65° C)

Item	Characteristic value
Sensing density	Lusterless paper with an OD of 0.8 max. (sensing distance: 50 mm) (see note)
Non-sensing distance	80 mm (from the top of the sensor), OD: 0.05
Paper sensing distance	50 mm (from the top of the sensor)
Ambient illumination	Sunlight: 3,000 //x max., fluorescent light: 2,000 //x max.

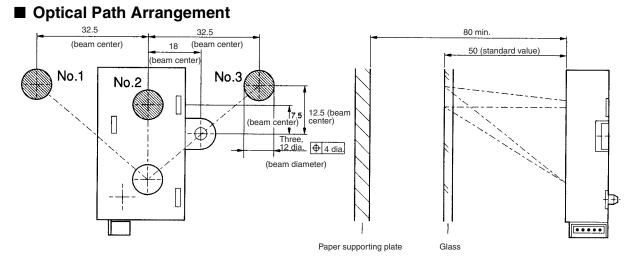
Note: 1. The data shown are initial data.

2. Optical darkness (OD) is defined by the following formula:

$$OD = -\log_{10}\left(\frac{P_{OUT}}{P_{IN}}\right)$$

 \mathbf{P}_{IN} (mW): Light power incident upon the document

 $\mathsf{P}_{\mathsf{OUT}}$ (mW): Reflected light power from the document



Engineering Data

Distance Characteristics (Estimated Lower-limit Value)

