

TDC1000-GASEVM User's Guide

User's Guide



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TDC1000-GASEVM and TDC1000-BSTEVM Kit User's Guide

1 General Overview

This user's guide details the use of the TDC1000-GASEVM, which is comprised of two boards. The first board is the main TDC1000-GASEVM, which includes an on-board TDC1000 (ultrasonic analog-front-end), TDC7200 (time-to-digital converter), and MSP430 microcontroller. The purpose of this board is to excite the transducers, receive the returned echo, generate the STOP pulses, and digitize the time-of-flight to the MSP430 for further processing. This main board connects with a separate TDC1000-BSTEVM board (referred to as HV board for the remainder of this document). The purpose of the HV board is to boost the transmit pulses from 3.7V-to-30V to get a better received echo for applications where a higher range is necessary or when the ultrasonic medium is a gas or is exposed to vibration.

2 TDC1000-GASEVM vs. TDC1000-TDC7200EVM

The TDC1000-GASEVM is compatible with the Firmware and GUI of the TDC1000-TDC7200EVM since all the components are the same. However, the TDC1000-GASEVM has the following component changes to facilitate rapid evaluation for water/gas flow applications.

1. The TDC1000-GASEVM has been designed for Gas Flow applications. The passive components that determine the first order filter of the Rx signal path have been tuned for frequencies between 58 kHz to 300 KHz.
2. The resistors connecting the TX2/RX1 and TX1/RX2 channel have been removed to enable the TDC1000-GASEVM to be used with the TDC1000-BSTEVM. When resistors have been removed, the transmitting pulses increase from 3.7 V to 30 V.

3 EVM Package Contents

The TDC1000-GASEVM evaluation kit contains the following:

- On board TDC1000 (ultrasonic analog-front-end) and TDC7200 (time-to-digital converter)
- On board MSP430 microcontroller
- USB Mini-B to USB-A plug cable

The TDC1000-BSTEVM kit contains the following:

- On board LM2733XMF boost converter
- On board UCC27531 Gate drivers
- Connectors to plug into the TDC1000-GASEVM or TDC1000-TDC7200EVM

4 Software

The firmware and GUI is the same as the TDC1000-TDC7200 EVM. For detail information about the GUI and troubleshooting the software, see the TDC1000-TDC7200EVM User's Guide [SNIU021](#).

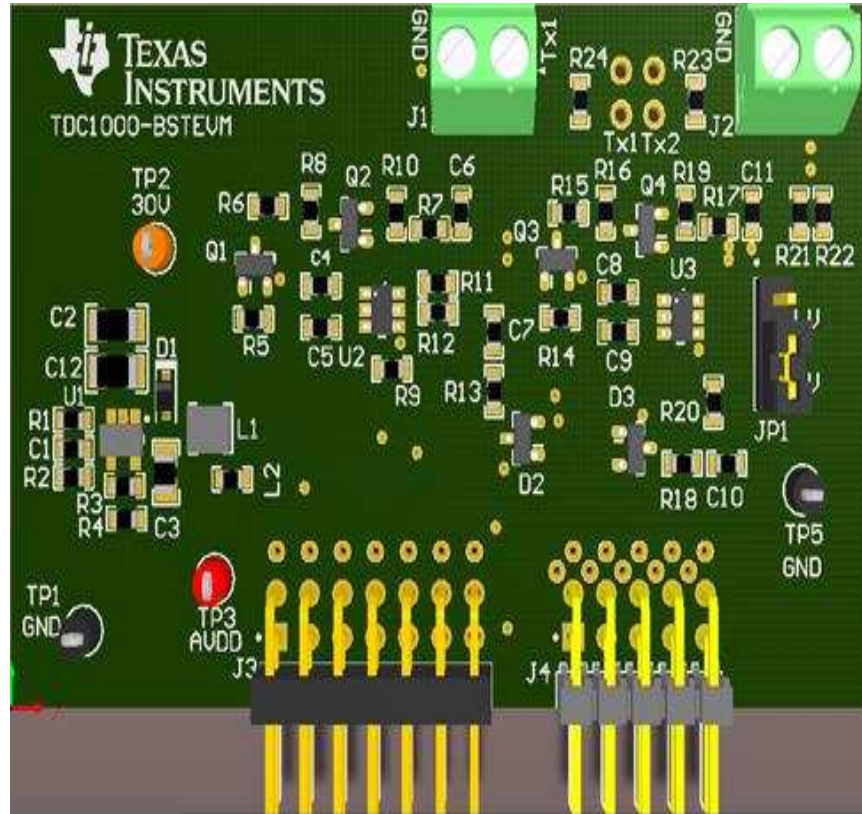


Figure 2. TDC1000-BSTEVM Board

6 Software Installation

6.1 Graphical User Interface (GUI)

Installing the TDC1000-GASEVM GUI software:

1. Download the GUI <http://www.ti.com/product/TDC1000/toolssoftware>
2. Unzip the downloaded file into a known directory and run it
3. Follow the pop-up screen instructions. Click “Next” to install the software.

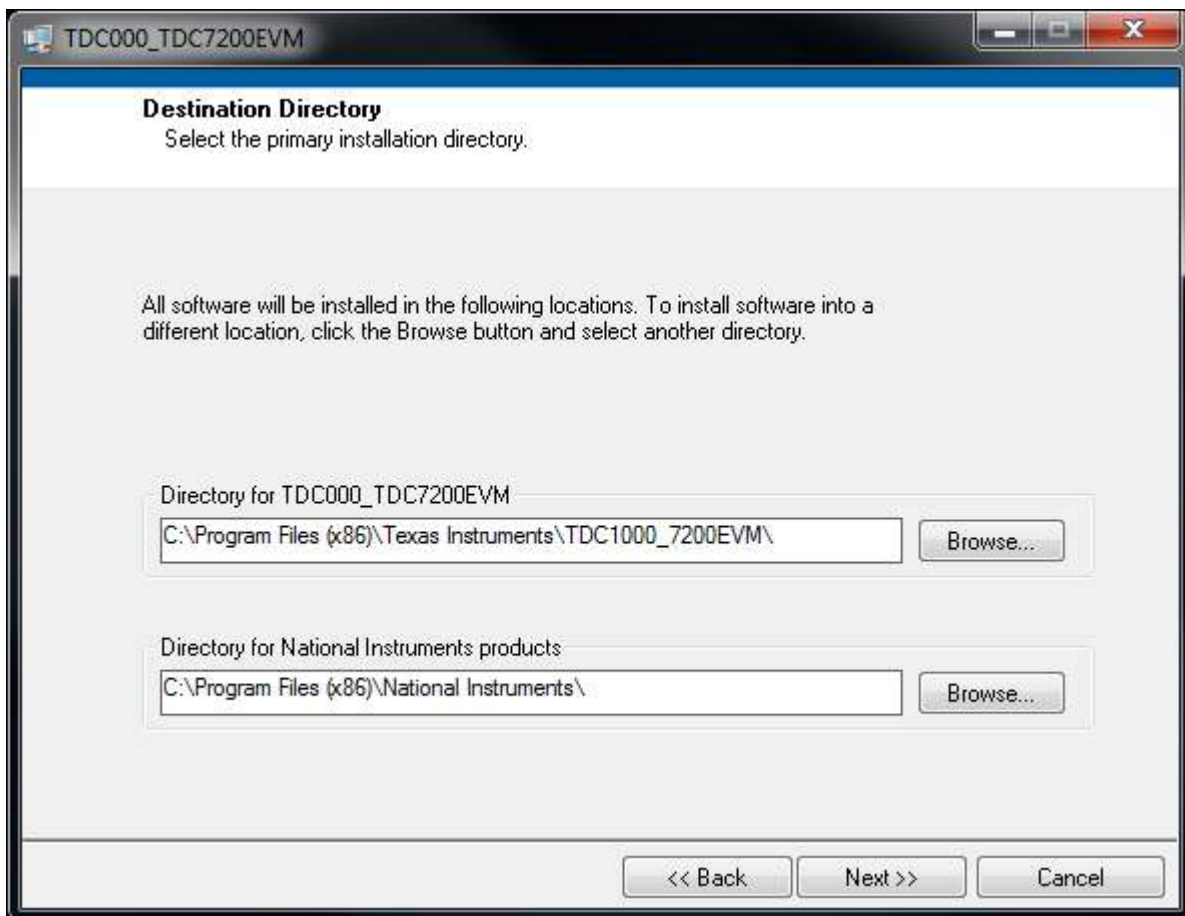


Figure 3. TDC1000-7200EVM Installation Directory

4. When the installation is done, click “Finish”.

7 TDC1000-BSTEVM Setup and Operation

7.1 Connections

1. Connect the USB cable (J2) from the TDC1000-GASEVM to the PC.
2. Plug the TDC1000-BSTEVM (HV board) into the TDC1000-GASEVM (see [Figure 4](#)).
3. Attach the transducer wires to the connectors J1 and J2 on the HV board.

On the TDC1000-GASEVM, make sure the following jumpers are in place.

1. JP1: TDC7200 - connect pin 1 to pin 2 (via a jumper)
2. JP2: CPU - connect pin 1 to pin 2 (via a jumper)
3. JP3: TDC1000 - connect pin 1 to pin 2
4. JP4: VIO - connect pin 1 to pin 2
5. JP5: Trigger - connect pin 2 to pin 3
6. JP6: CLOCK - connect pin 5 to pin 6

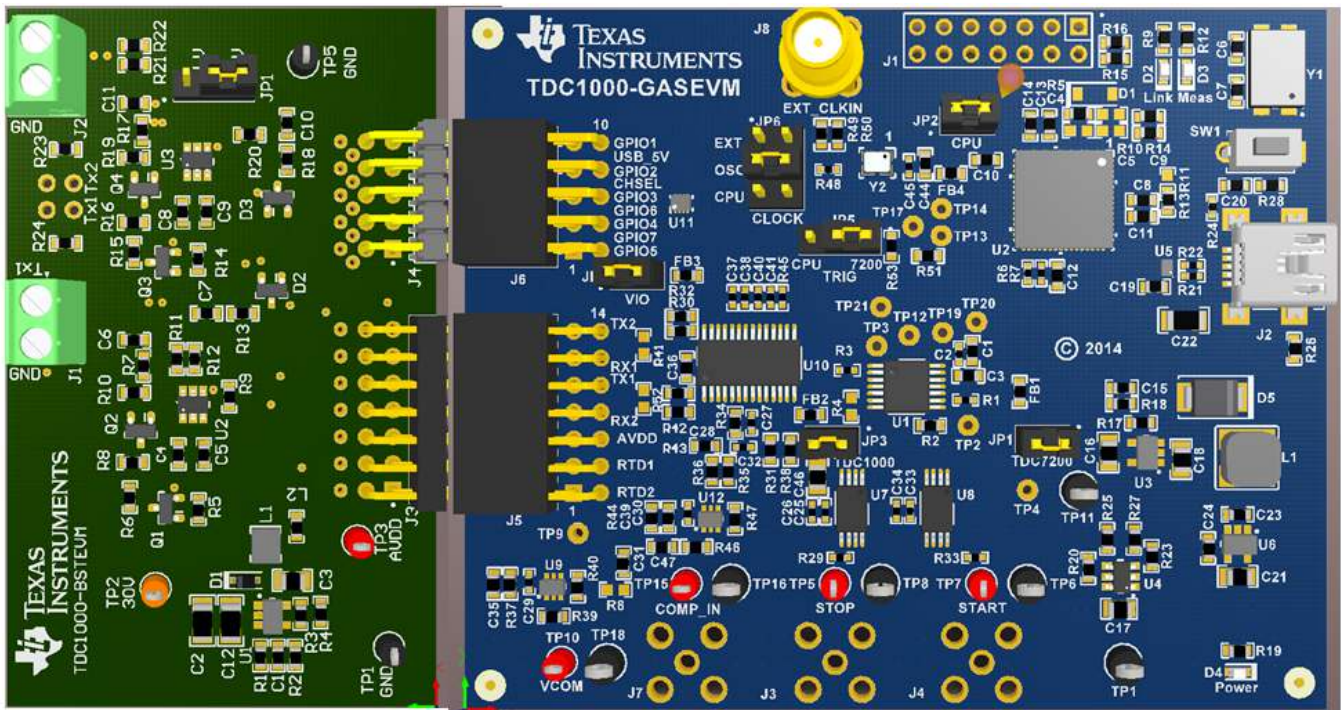


Figure 4. TDC1000-BSTEVM Plugged into TDC1000-TDC7200EVM

8 Launching the Software

1. The TDC1000_TDC7200EVM GUI software can be run by clicking on **Start >> All Programs >> Texas Instruments >> TDC1000_7200**.
2. See TDC100-TDC7200EVM_Users_Manual ([SNIA020](#)) on how to use the GUI
3. **When using the HV board:** Go to the "SETUP" tab on the TDC1000-7200EVM GUI and select "TDC1000-HV Boost Power Enable" to enable the 30V boost supply. The supply will remain on constantly (Always ON) unless a different time period is selected via the pulldown box. The capacity to reduce the Boost power supply active time is to enable very low power applications testing so the BOOST supply is only active during the measurement cycle time. Next make sure to select either "TDC1000-HV Driver EN1" or "TDC1000-HV Driver EN2" -- or both of them by checking the respective box.
 - (a) Select an "EN period (us)" in μs . This is the time the EN will stay HIGH after the START pulse of the EVM. EN will go high about 30 μs before START to ensure that the driver ICs on the HV interface board are powered up in time for the first Tx pulses. Example: If you choose an EN period of 40 μs (default = 30 μs), you will see a EN pulse with the length of 70 μs , because it consists of the constant 30 μs before the START signal plus whatever you choose for EN period.
 - (b) A longer EN period can be used to dampen the oscillation of the ultrasonic transducers. After the last Tx pulse, the output of the driver IC will be pulled to ground via the 110- Ω resistor that is on the board until the voltage on the VDD pin drops below about 3 V.
4. You can set the "EN period" for EN1 and EN2 separately, but whichever is higher will be applied to BOTH enables if EN1 and EN2 are checked.
5. If you choose to use one channel with 5V pulses and the other with 30V, you can bypass the HV driver of Channel 2. Make sure to uncheck the box "TDC1000-HV Driver EN2" in the GUI and to also place the jumper JP1 on the HV board to "LV" for low voltage.

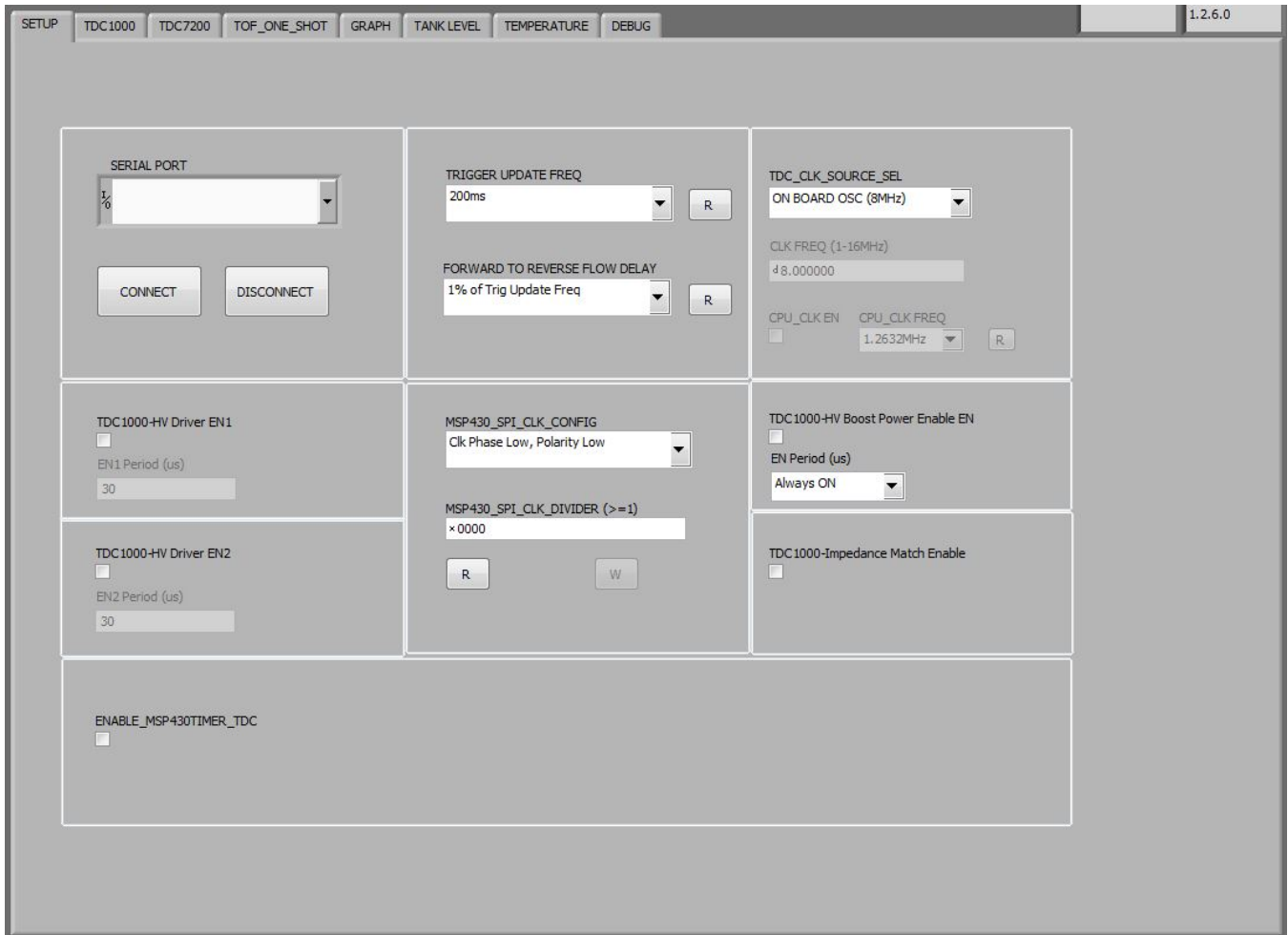
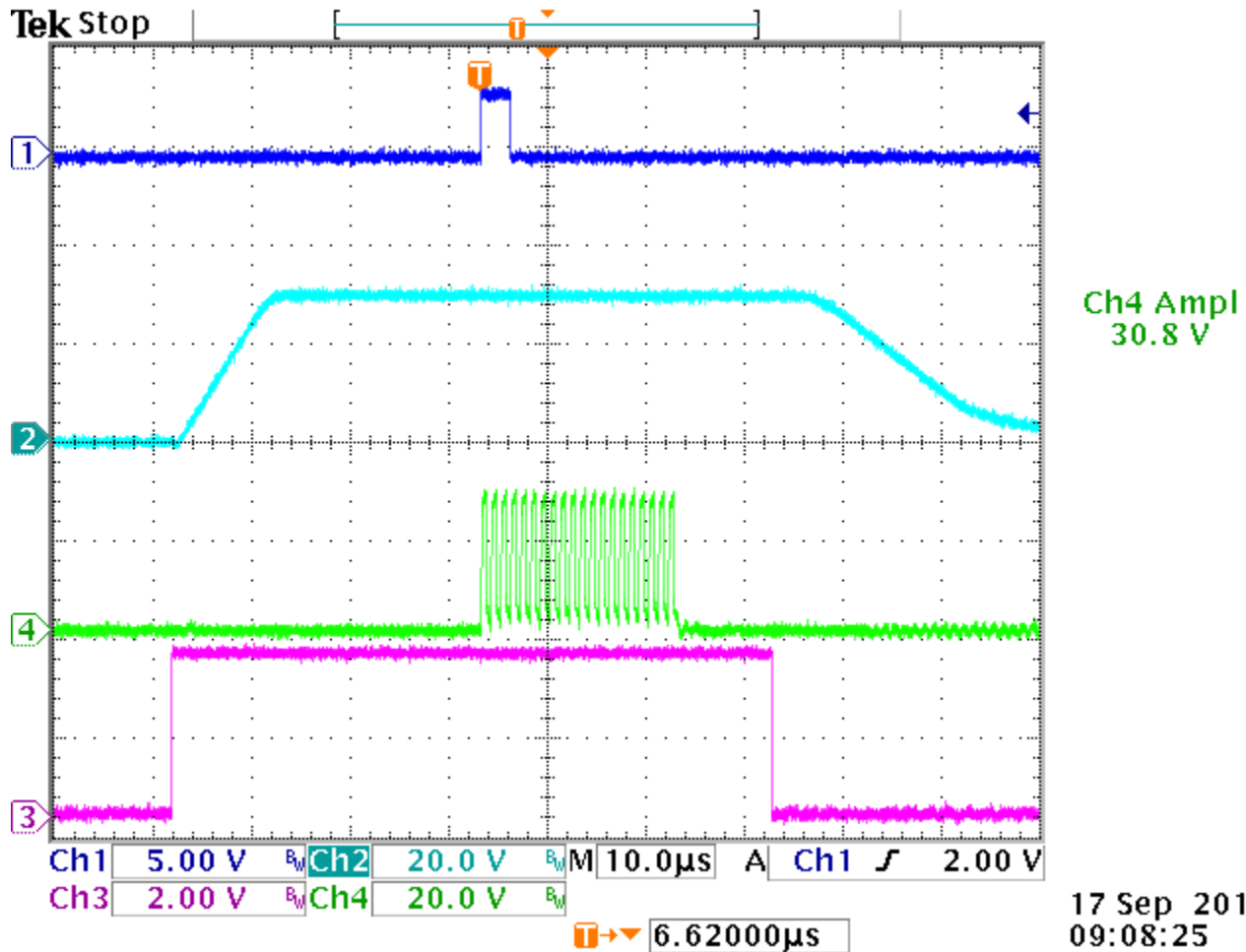


Figure 5. SETUP Tab in TDC1000-TDC7200EVM



**Figure 6. Top to Bottom:
START Pulse,
Voltage on VDD Pin of UCC Driver,
Voltage Across Connector J1,
EN1 Signal on Oscilloscope**

6. Observe the following signals: TDC1000's START (dark blue) on the TDC1000-GASEVM, VDD of driver IC U2(light blue) on the HV board, transmit pulses on transducer connector J1 (green) and EN1 (pink) signals on the oscilloscope as shown in [Figure 6](#). This shows that the VDD of the driver is turned on in time and long enough for this number of pulses. If the last pulses are reduced in amplitude, increase EN period in the "SETUP" tab of the GUI.
7. EN signal should go high about 30µs before START goes high.
8. Observe Tx pulses and voltage at the output of the high voltage drivers as shown in [Figure 7](#). Tx and transducer voltage at connectors J1/2 should be in phase. Tx should have an amplitude of 3.7Vpk-pk and transducer voltage 30Vpk-pk.

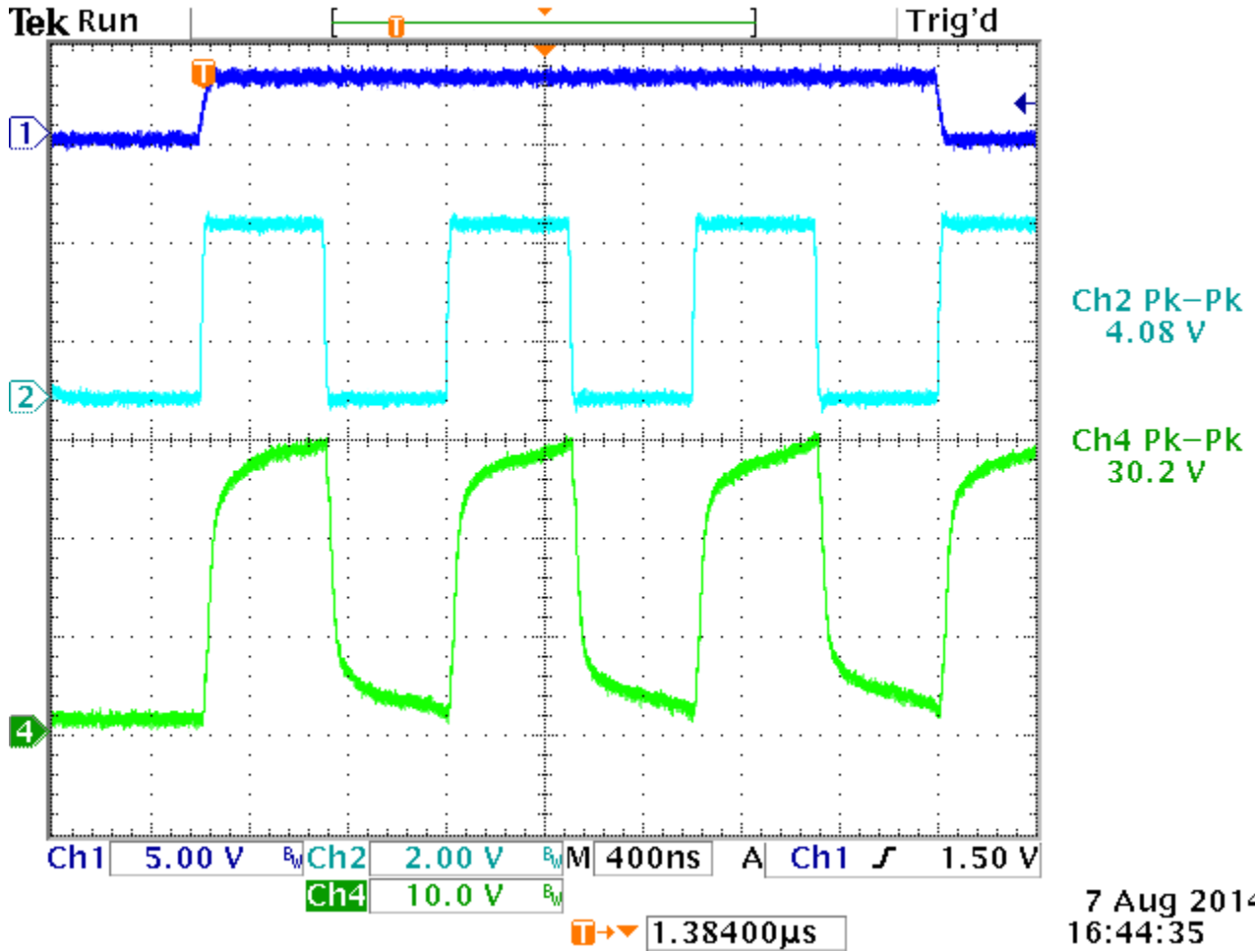


Figure 7. Top to Bottom:
TDC1000's START Pulse (Dark Blue),
TDC1000's Tx Signal (Light Blue),
and the Boosted 30 V of TD1000's Tx Signal (Green)

9 Clock Selection

In order to excite the transducer with its resonant frequency and to achieve the maximum energy transfer and therefore generate a big echo, the EVM allows you to apply the external clock, use the onboard oscillator, or to use the CPU clock.

For gas flow applications, we recommend using the CPU clock. The steps to select the CPU clock can be seen in the following subsections.

9.1 Steps to Select the CPU Clock

1. On the TDC1000-GASEVM, place the JP6 Jumper on the CPU position

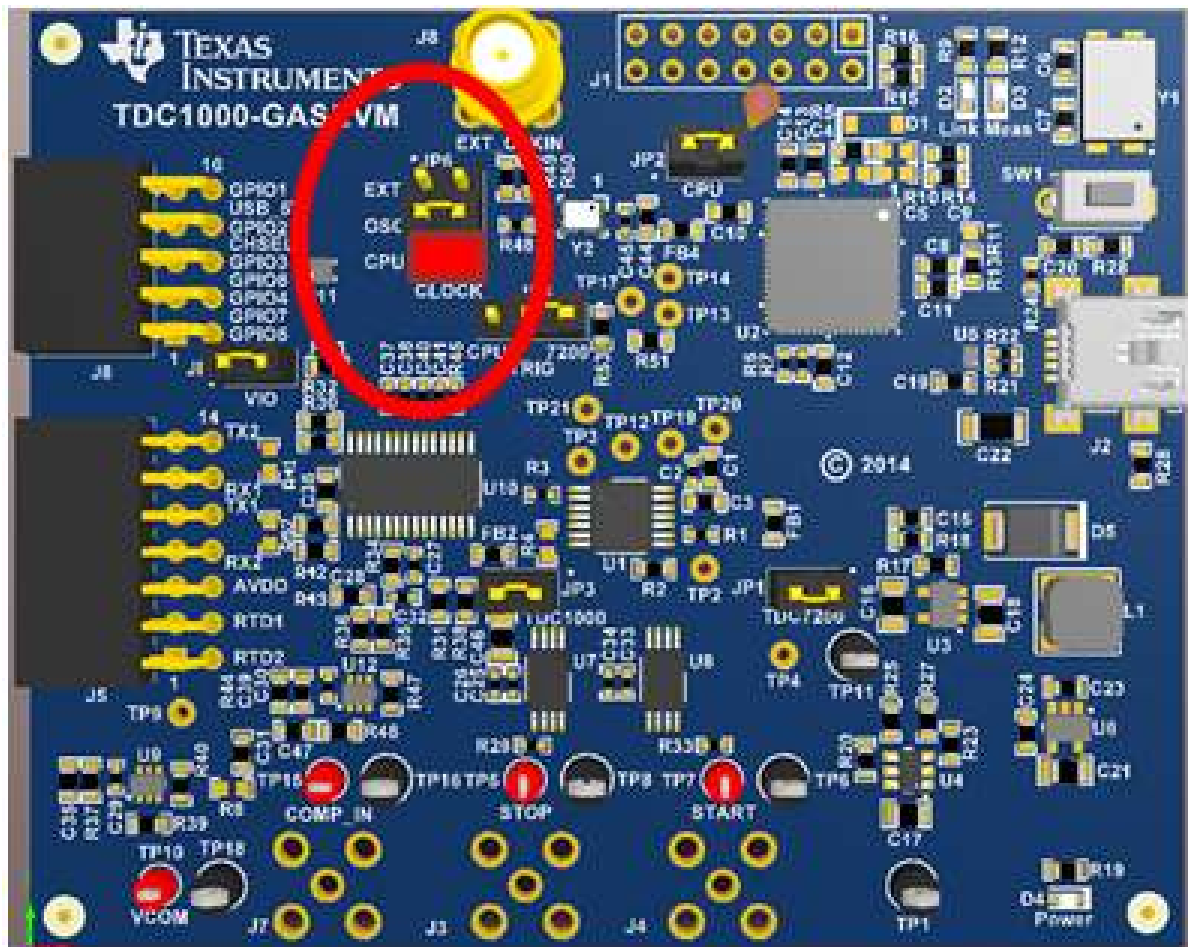


Figure 8. Place Jumper on JP6 to Use the CPU Clock

2. Select CPU_CLK on the SETUP tap of the GUI. A message will pop up. Click "OK".

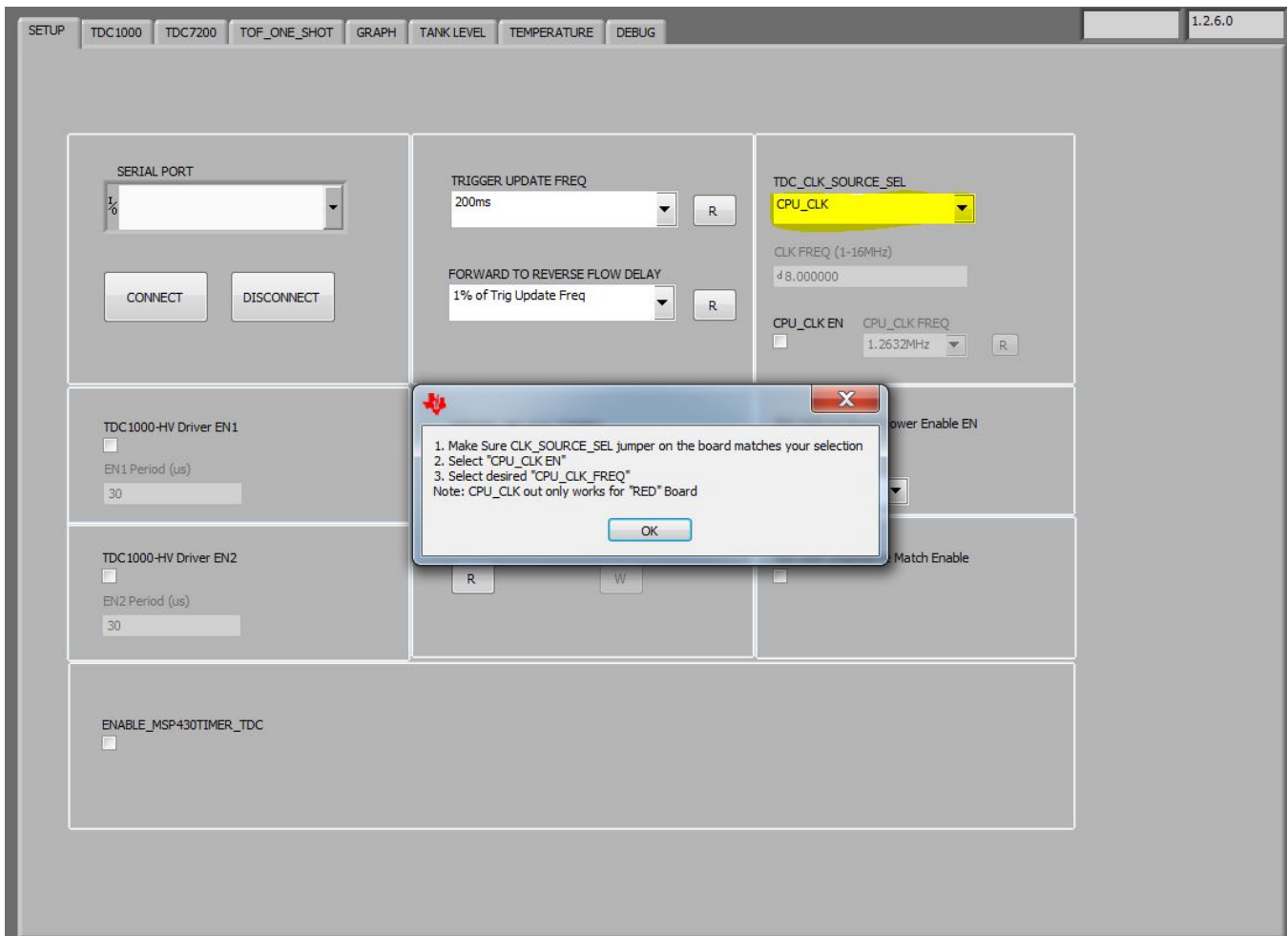


Figure 9. Select CPU-CLK

3. Check the CPU-CLK EN box and Select desired frequency from the drop down menu.

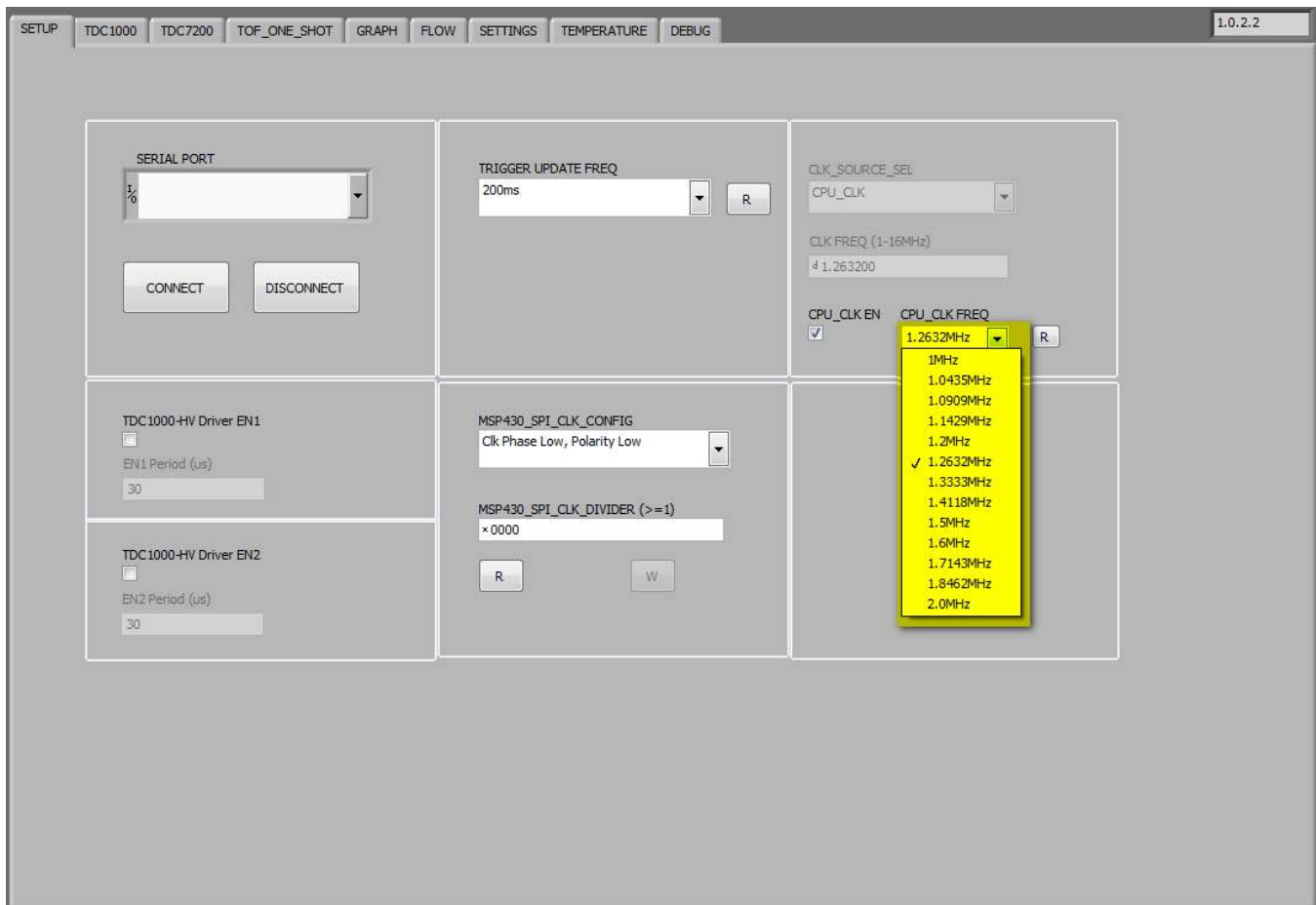


Figure 10. Clock Options

4. In the GUI and on the TDC1000 tab, select a clock divider from the TX_FREQ_DIV register. Note the transducer's resonant frequency = (external clock) / (TX_FREQ_DIV). For example, if the transducer's resonant frequency is 500kHz, and a CPU clock of 2MHz is chosen, then the TX_FREQ_DIV needs to be 4. [Figure 11](#) shows possible excitation pulses using the CPU clock or on-board oscillator of 8MHz.

10 Possible Excitation Pulses

	TX-Frequency Division	2	4	8	16	32	64	128	256
On Board Oscillator	8,000,000	4,000,000	2,000,000	1,000,000	500,000	250,000	125,000	62,500	31,250
CPU Clock (Hz)	1,000,000	500,000	250,000	125,000	62,500	31,250	15,625	7,813	3,906
	1,043,500	521,750	260,875	130,438	65,219	32,609	16,305	8,152	4,076
	1,090,900	545,450	272,725	136,363	68,181	34,091	17,045	8,523	4,261
	1,142,900	571,450	285,725	142,863	71,431	35,716	17,858	8,929	4,464
	1,200,000	600,000	300,000	150,000	75,000	37,500	18,750	9,375	4,688
	1,263,200	631,600	315,800	157,900	78,950	39,475	19,738	9,869	4,934
	1,333,300	666,650	333,325	166,663	83,331	41,666	20,833	10,416	5,208
	1,411,800	705,900	352,950	176,475	88,238	44,119	22,059	11,030	5,515
	1,500,000	750,000	375,000	187,500	93,750	46,875	23,438	11,719	5,859
	1,600,000	800,000	400,000	200,000	100,000	50,000	25,000	12,500	6,250
	1,714,300	857,150	428,575	214,288	107,144	53,572	26,786	13,393	6,696
	1,846,200	923,100	461,550	230,775	115,388	57,694	28,847	14,423	7,212
	2,000,000	1,000,000	500,000	250,000	125,000	62,500	31,250	15,625	7,813

Figure 11. Excitation Pulses Chart

11 Troubleshooting

11.1 Boost converter

The DC/DC converter on the HV board is a LM2733X 1.6 MHz boost converter with integrated switch. Test point TP2 should show a voltage of 30 V. If this is not the case, check if TP3 shows the required input voltage of 5 V.

11.2 Jumper

Table 1. Jumper

JUMPERS	DESCRIPTION
JP1	Tx2 voltage selector: bypass HV driver when placed in "LV" position

For default operation (use high voltage for both channels), place jumper on the following:

1. JP1.P2 and JP1.P3 – HV

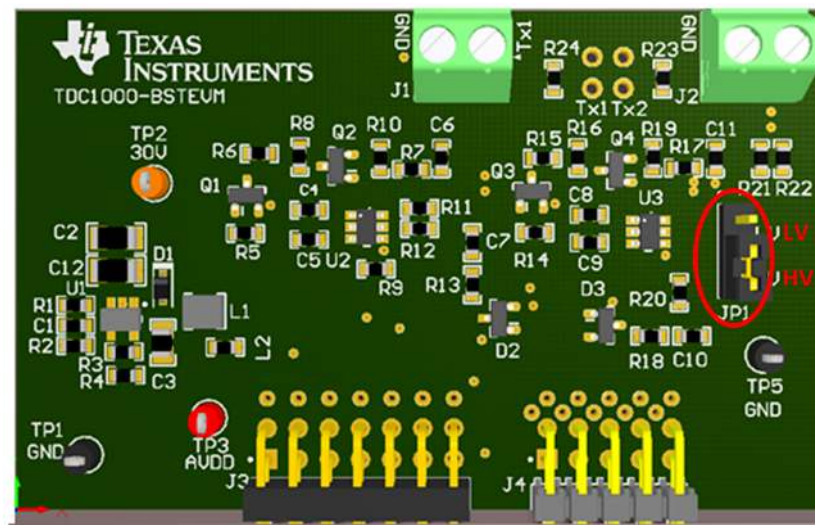


Figure 12. Jumper

When placing the jumper in LV position (on pins 1 and 2), "TDC1000-HV Driver EN2" should be unchecked in the GUI. Otherwise the UCC27531 will pull its output to ground.

11.3 Firmware Upgrade

Note: This section is only necessary if the firmware needs to be changed. The TDC1000-TDC7200EVM comes pre-loaded with firmware already. The HV board needs firmware TDC1000_7200_FW-v1.16-1MHz or newer.

To change the firmware, complete the following steps:

1. Connect the TDC1000-TDC7200EVM to a PC.
2. Open the TDC1000-7200EVM GUI then go to the “DEBUG” tab. Press “OK” if a connection error window pops up. Click on the Update Firmware button.

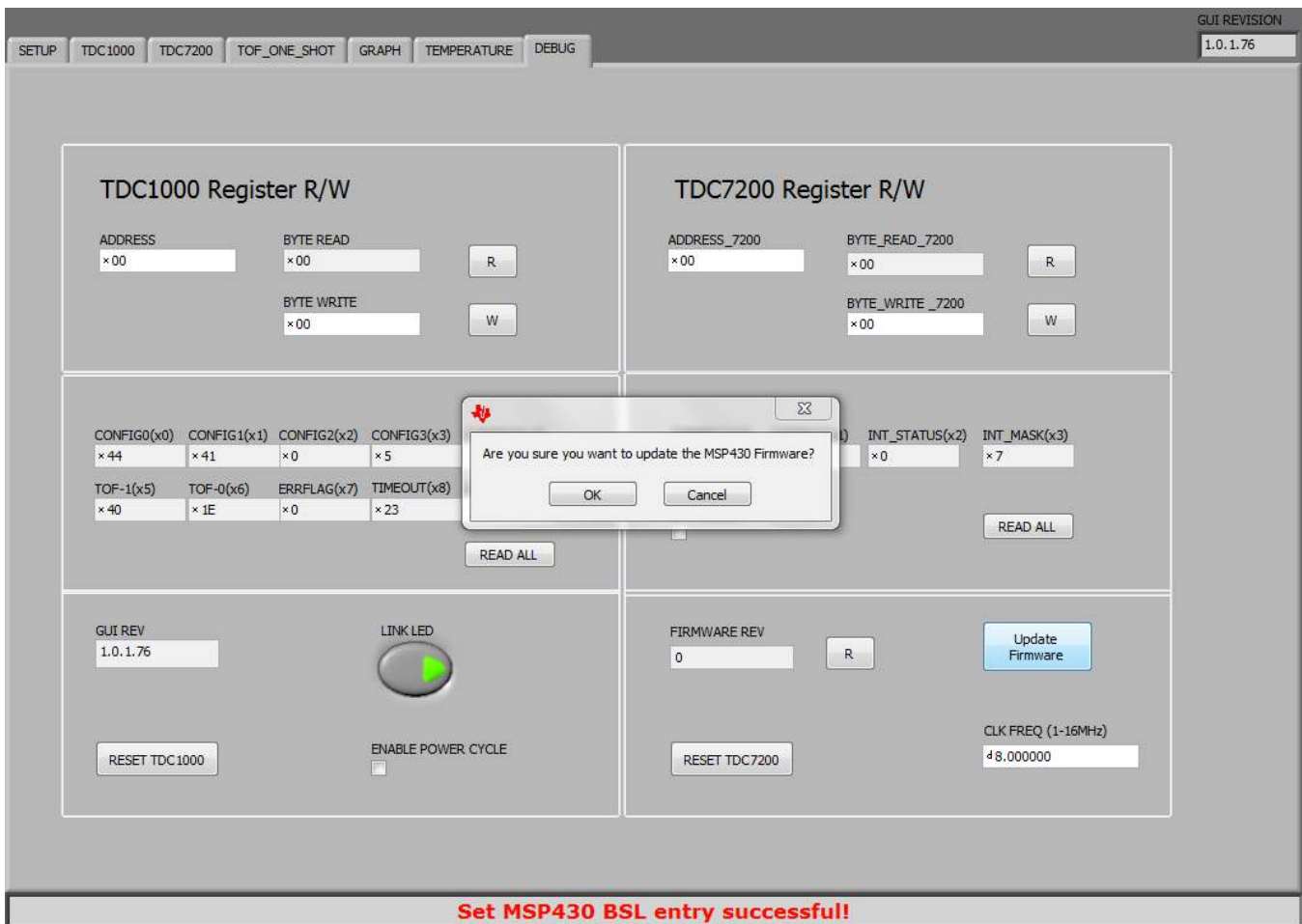


Figure 13. Connection Error Pop-up Window

3. The MSP430 USB Firmware Upgrade windows will pop up. Click “Next” to proceed on the first prompt. Read and accept the license agreement and click “Next” to continue.

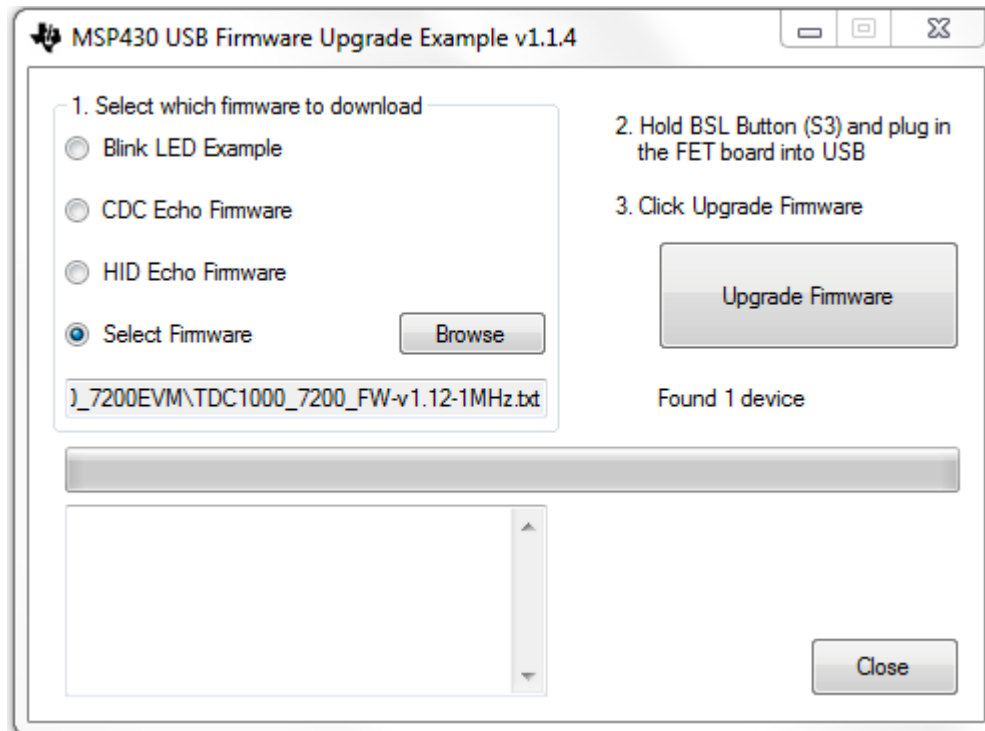


Figure 14. USB Firmware Upgrade Window

1. Disconnect and reconnect the LaunchPad to PC while holding the BSL button down.
2. Select the Select Firmware button and browse to the firmware file.
3. Click on the Upgrade Firmware button to program the EVM. Close the application when done and restart the TDC1000_7200EVM GUI.

12 TDC1000-GASEVM Board Layout

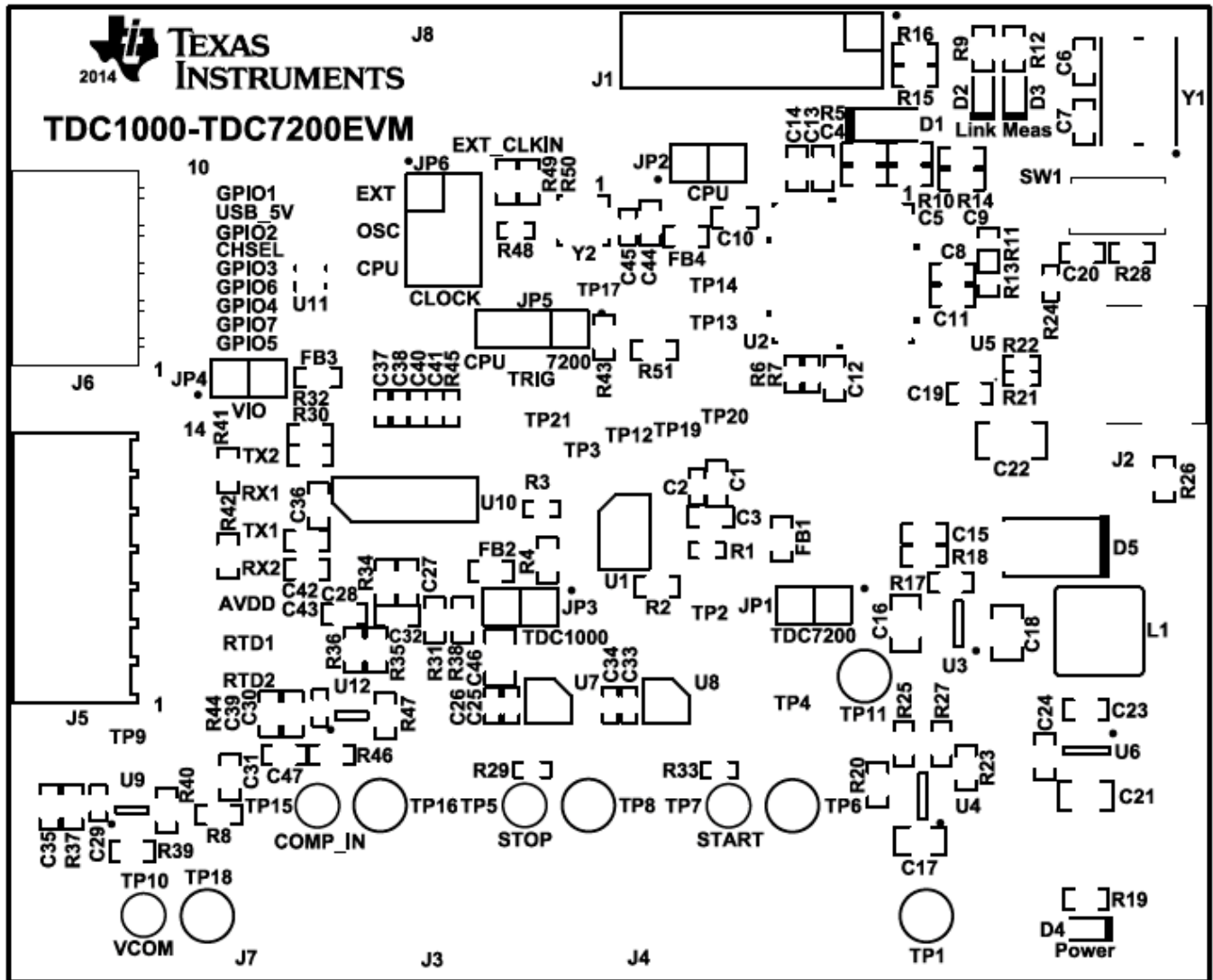


Figure 15. Top Overlay

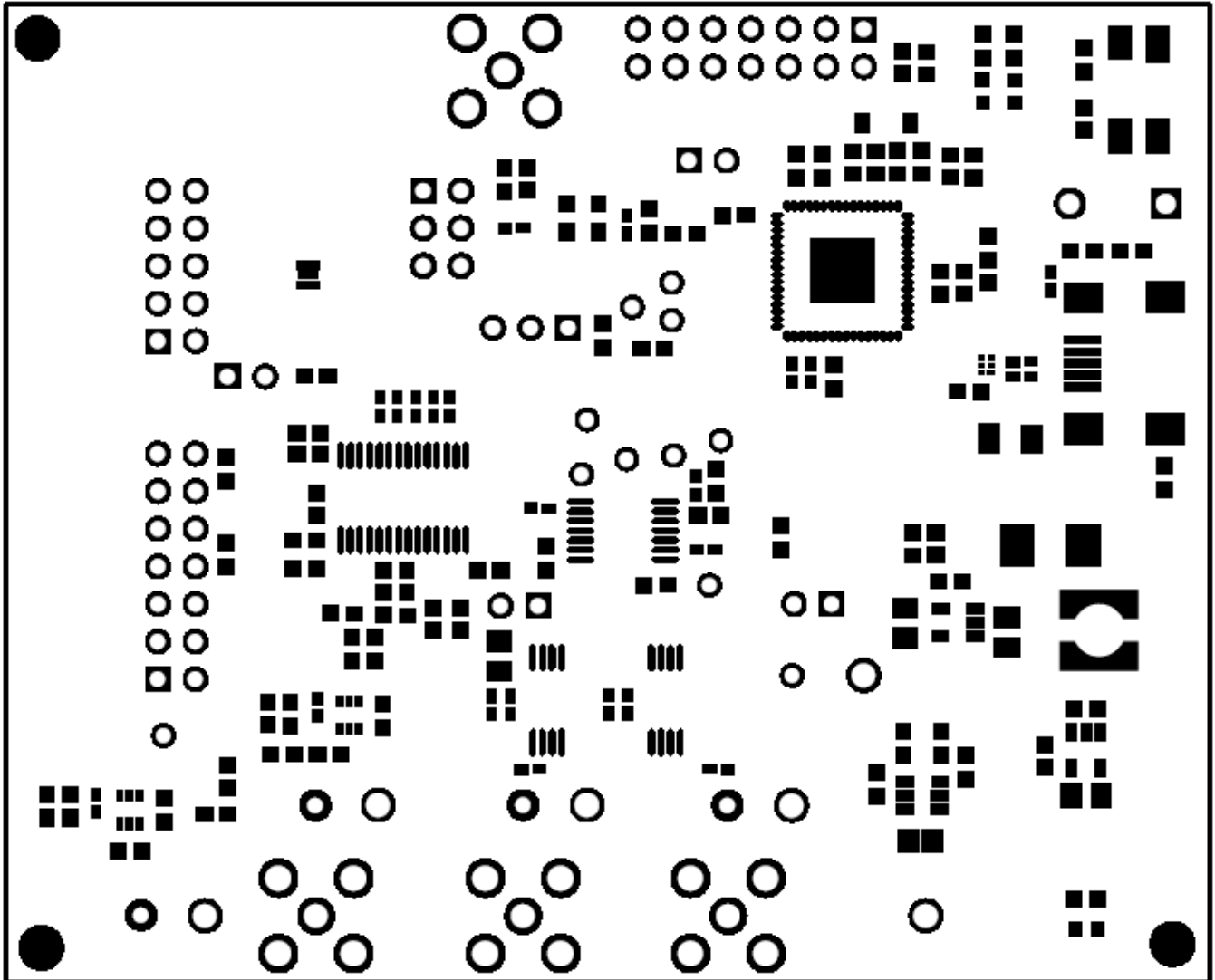


Figure 16. Top Solder Mask

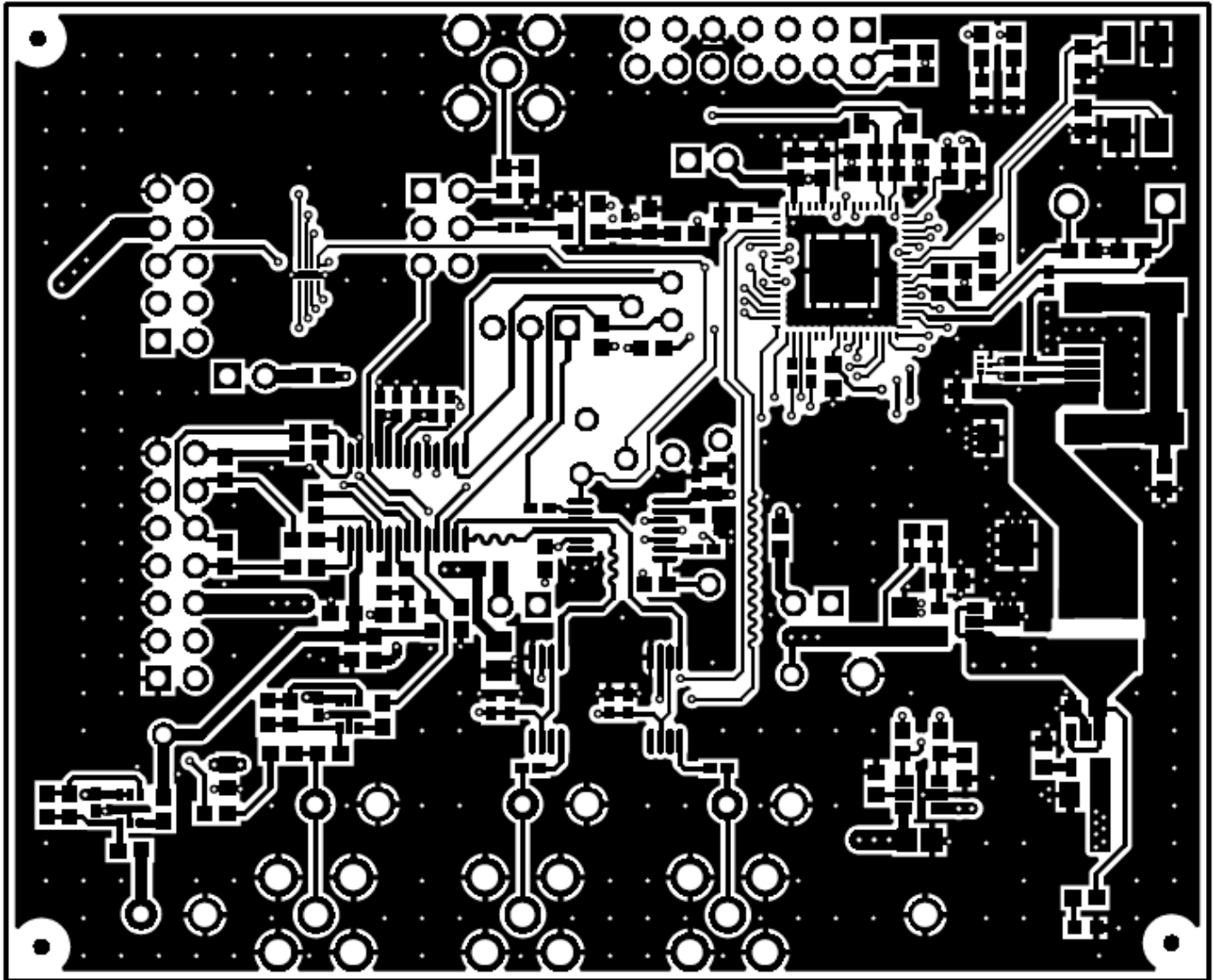


Figure 17. Top Layer

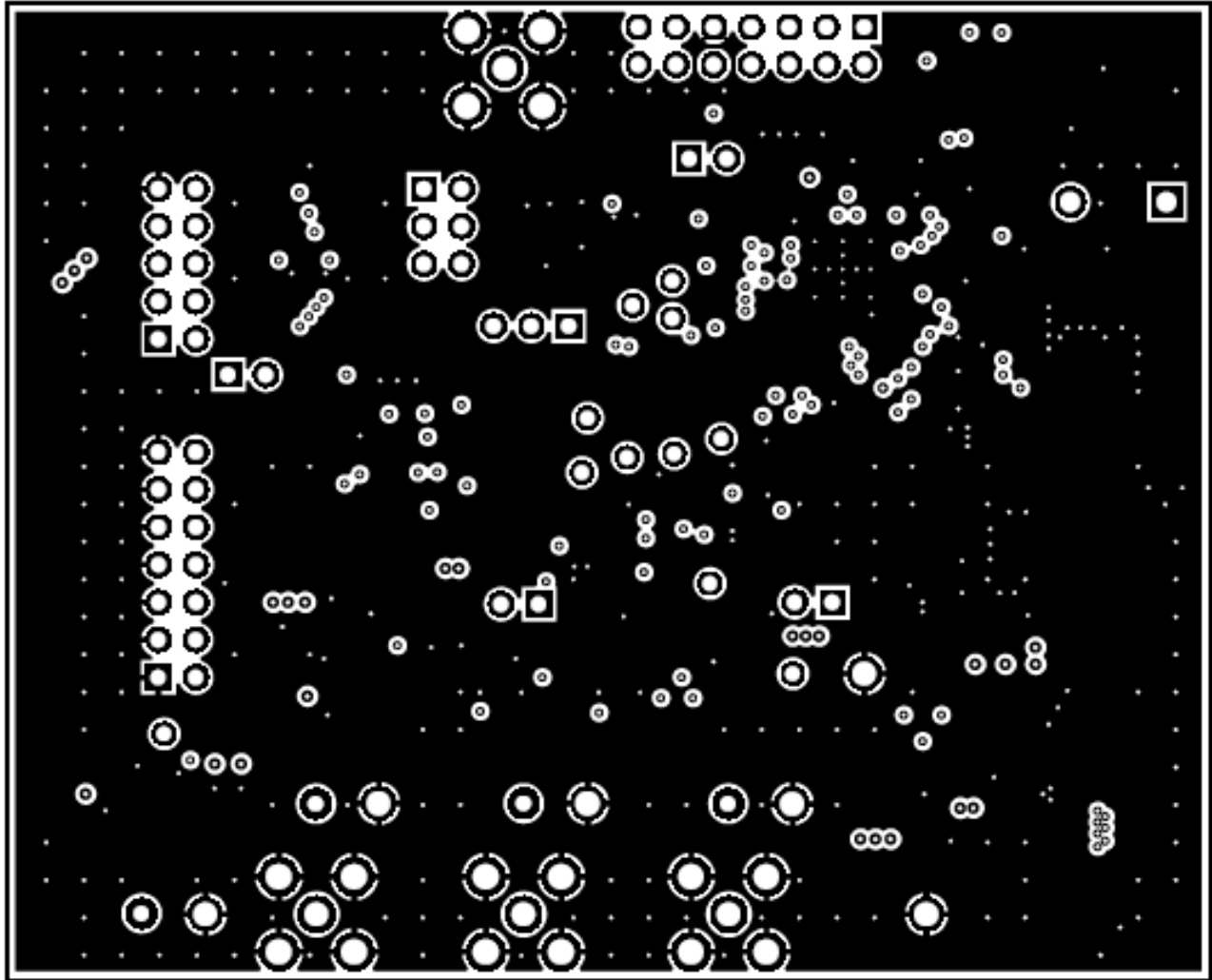


Figure 18. Mid Layer 1

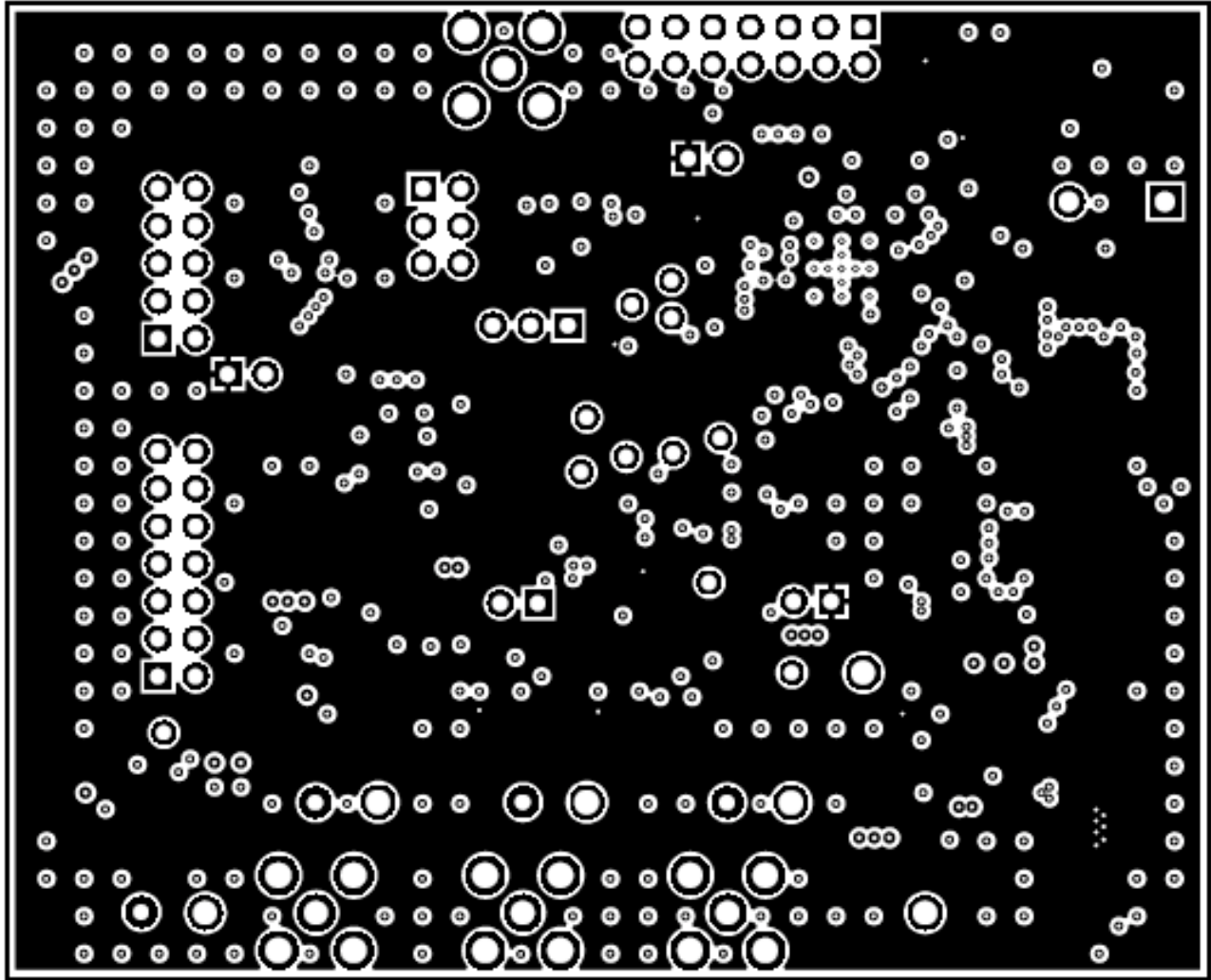


Figure 19. Mid Layer 2

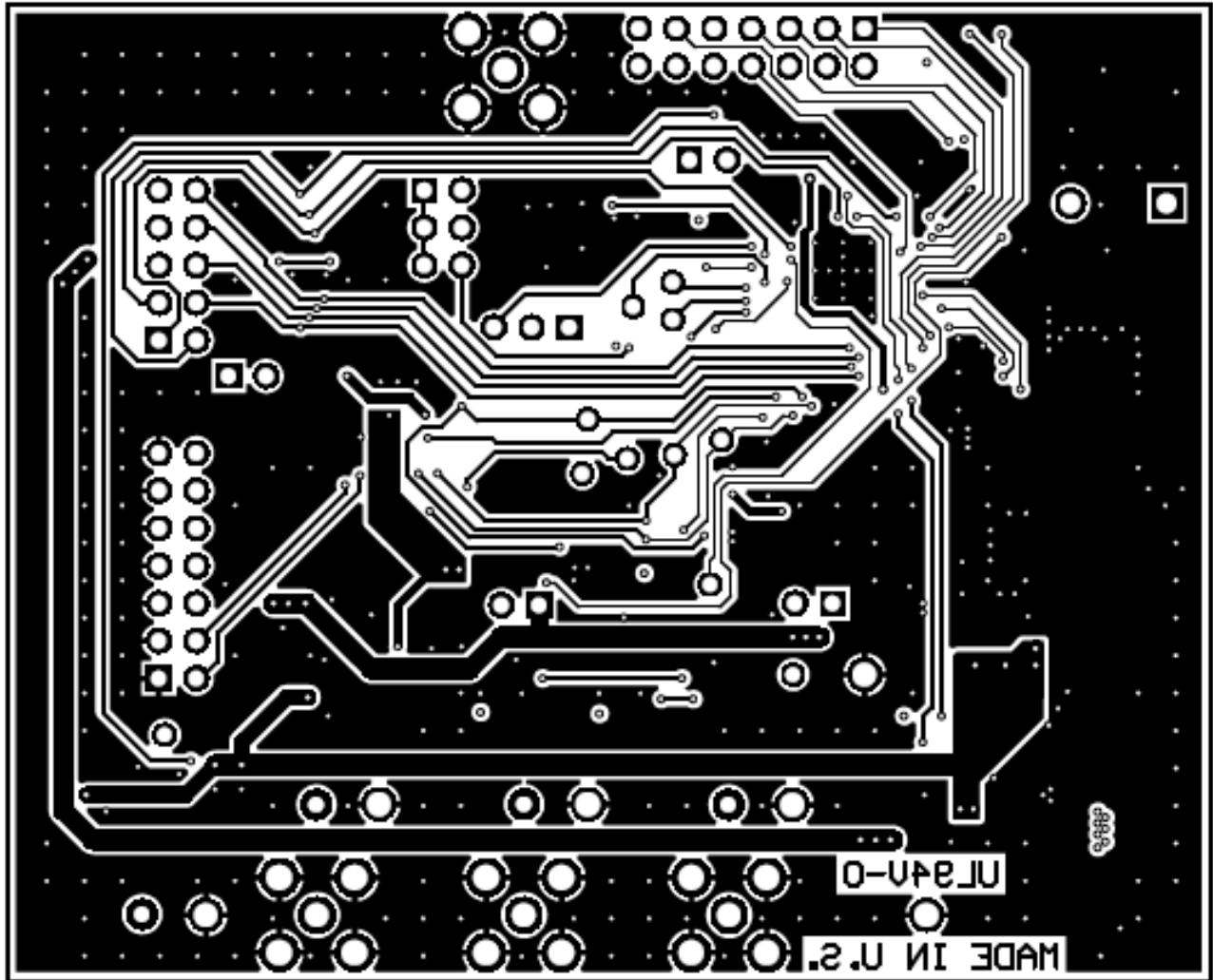


Figure 20. Bottom Layer

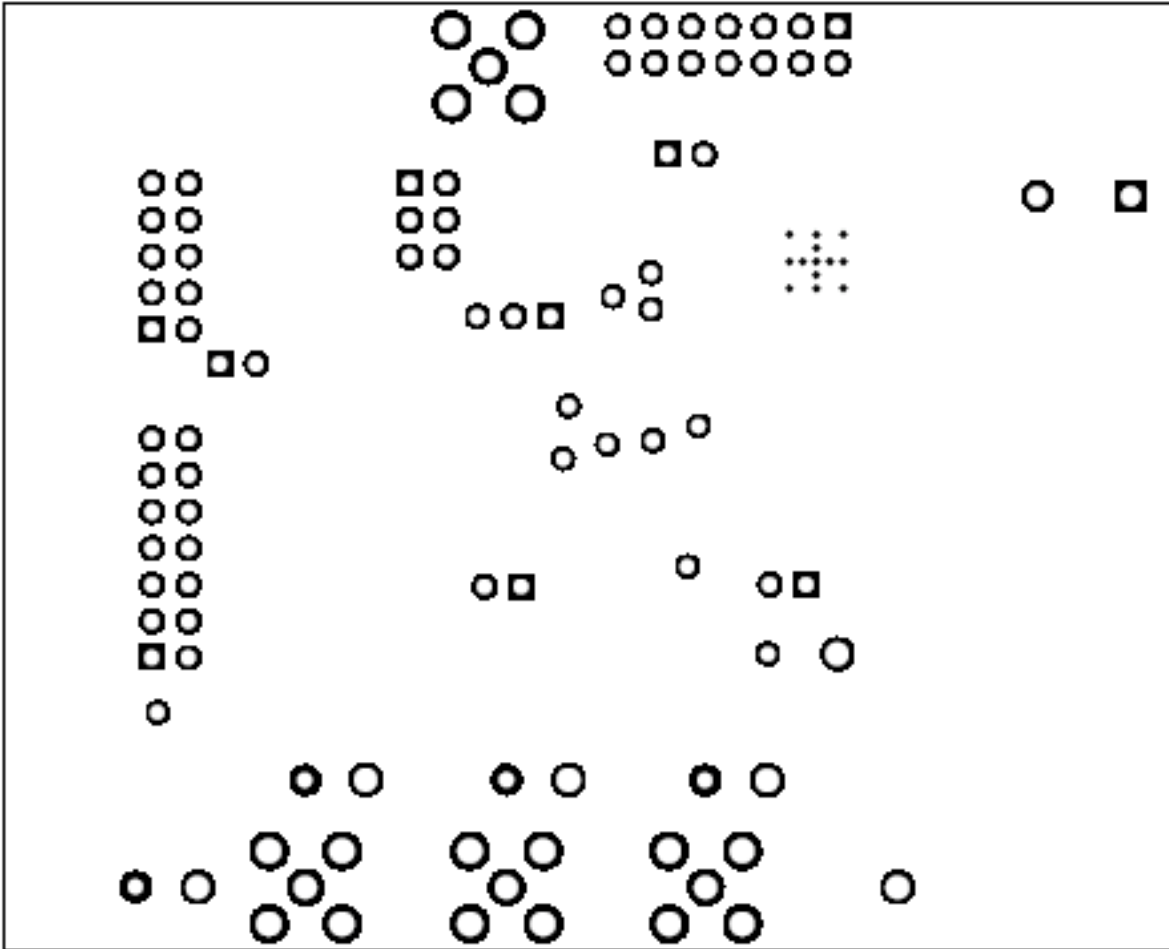


Figure 21. Bottom Solder Mask

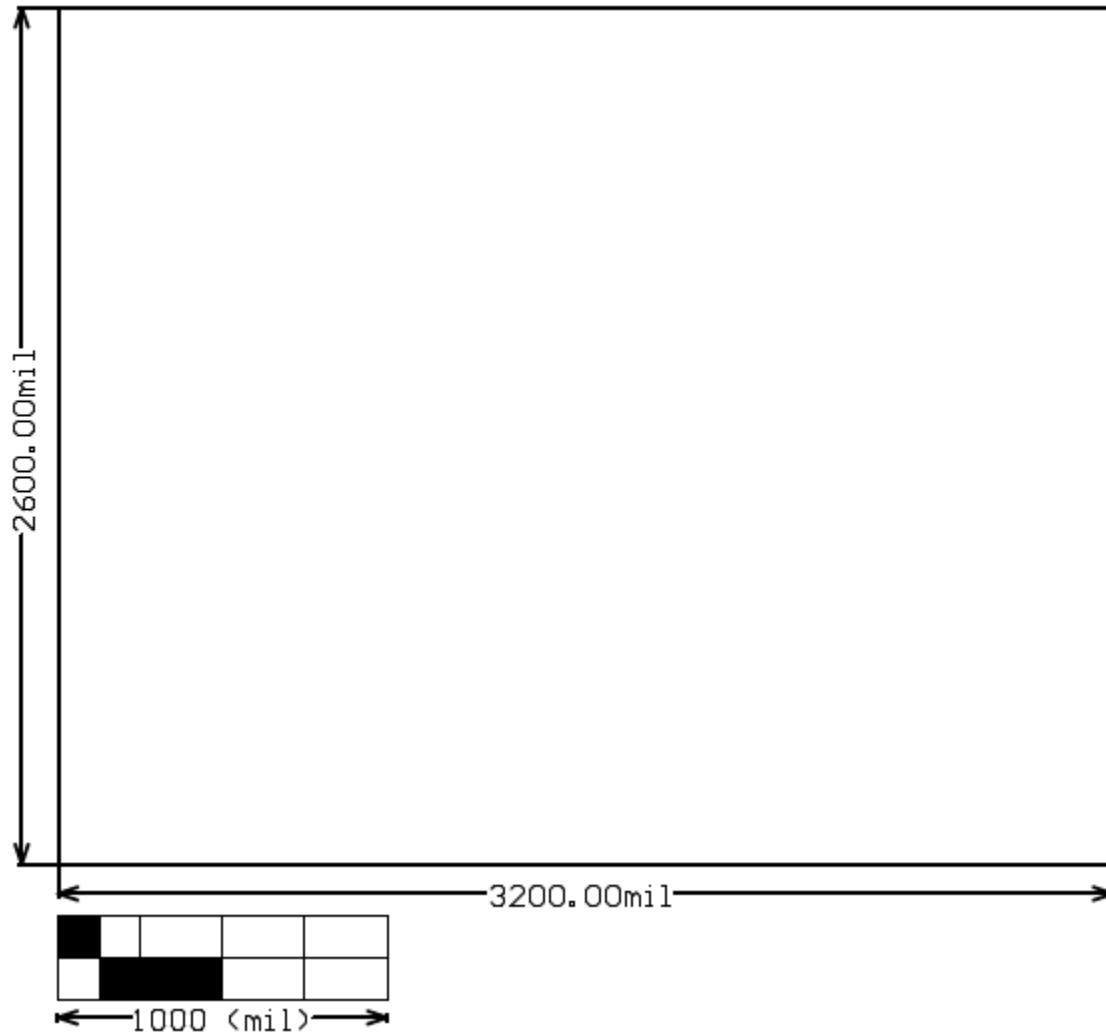


Figure 22. Board Dimensions

13 TDC1000-GASEVM Schematic

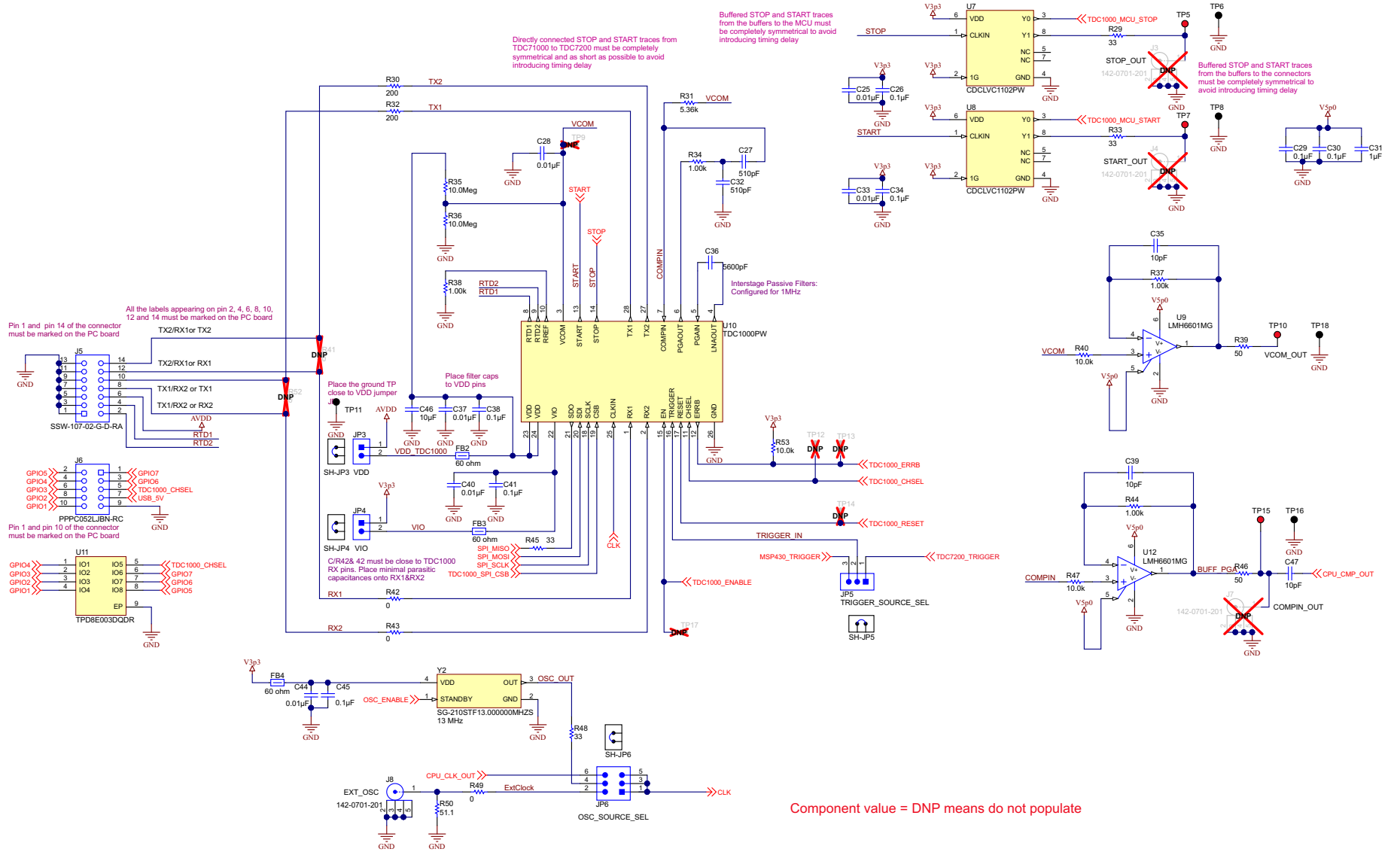
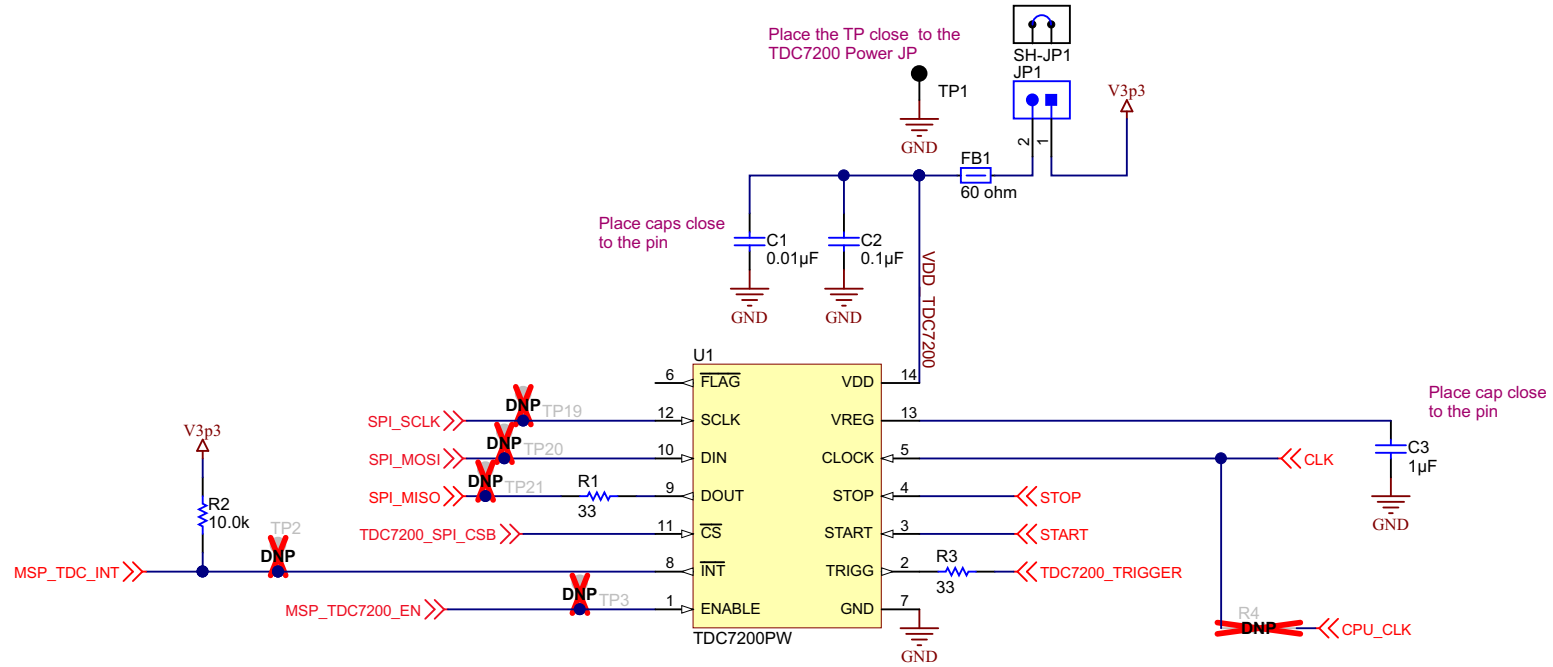


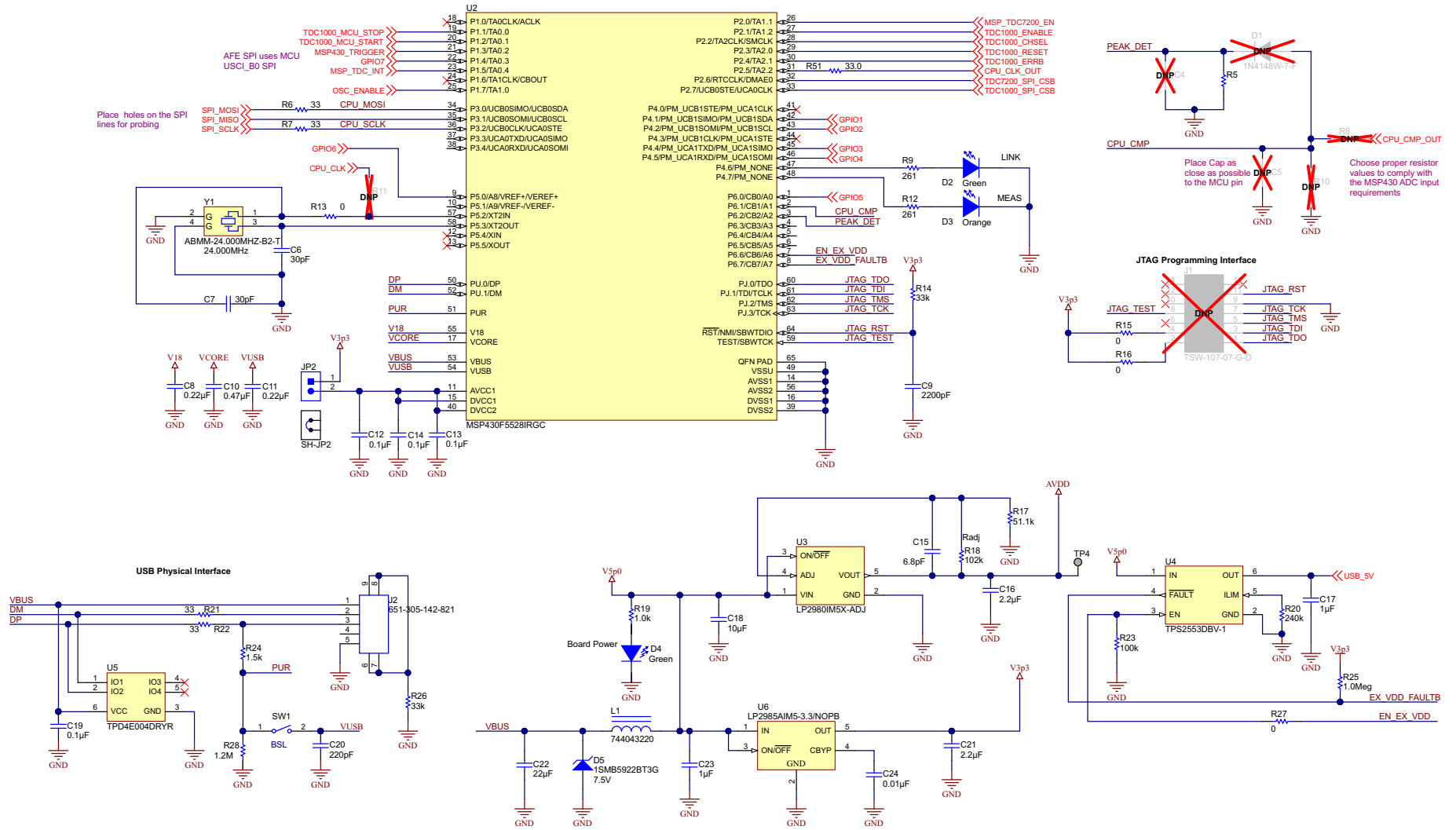
Figure 23. TDC1000-GASEVM Schematic 1



Component value = DNP means do not populate

Figure 24. TDC1000-GASEVM Schematic 2

STOP is connected to TA0.0, as this has quickest responding ISR. In this way STOP pulses can be closer together.
 START is connected to TA0.1, which is slower. This produces a delay to timestamp, but this can be compensated.
 TRIGGER is on TA0.2, used to reset counter so there are no rollover issues.



Component value = DNP means do not populate

Figure 25. TDC1000-GASEVM Schematic 3

14 TDC1000-BSTEVM Board Layout

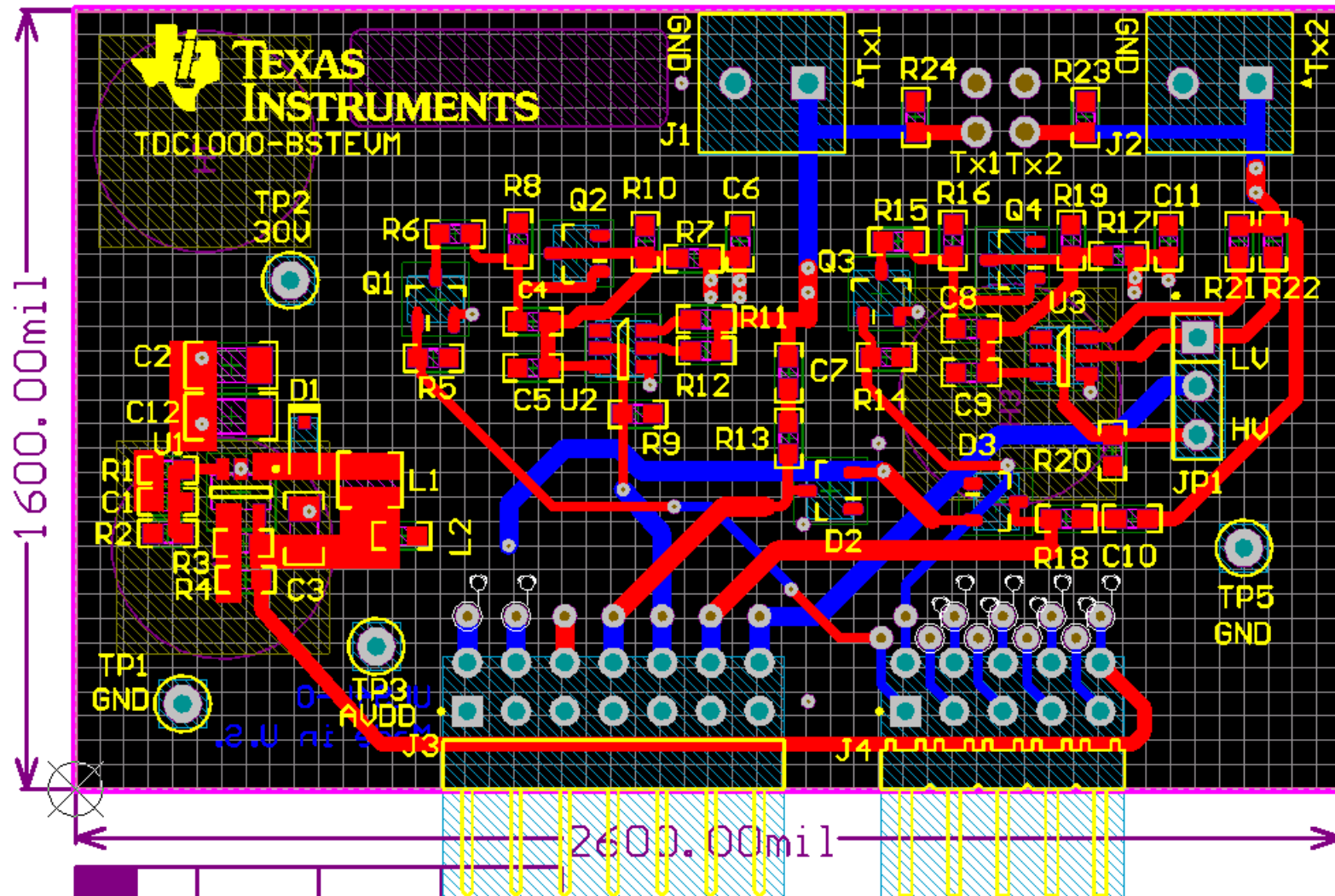


Figure 26. BSTEVM Layout

15 BSTEVM Schematic

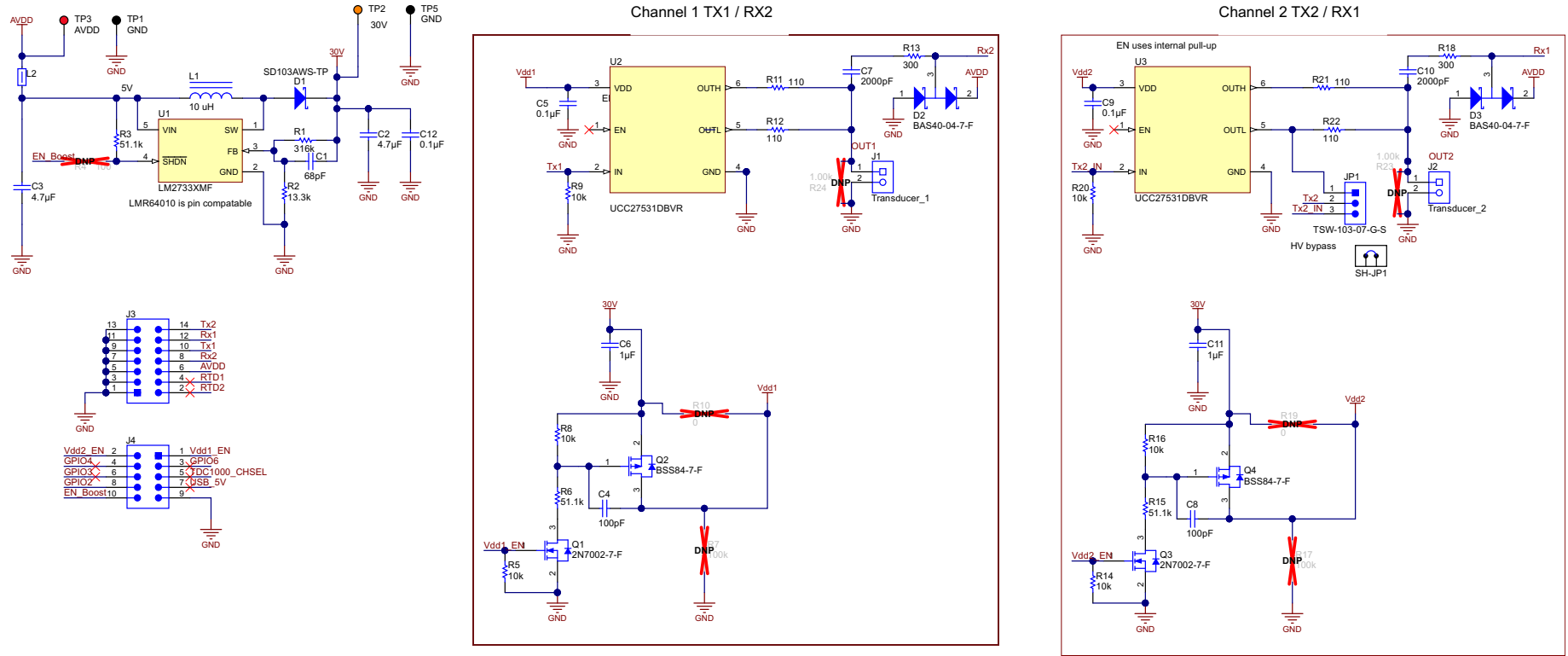


Figure 27. TDC1000-BSTEVM

Revision History

Changes from Original (March 2015) to A Revision	Page
• Changed SETUP Tab.....	3
• Changed SETUP Tab	11
• Changed Schematic.....	29

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

STANDARD TERMS AND CONDITIONS FOR EVALUATION MODULES

1. *Delivery:* TI delivers TI evaluation boards, kits, or modules, including any accompanying demonstration software, components, or documentation (collectively, an "EVM" or "EVMs") to the User ("User") in accordance with the terms and conditions set forth herein. Acceptance of the EVM is expressly subject to the following terms and conditions.
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 - 2.3 If any EVM fails to conform to the warranty set forth above, TI's sole liability shall be at its option to repair or replace such EVM, or credit User's account for such EVM. TI's liability under this warranty shall be limited to EVMs that are returned during the warranty period to the address designated by TI and that are determined by TI not to conform to such warranty. If TI elects to repair or replace such EVM, TI shall have a reasonable time to repair such EVM or provide replacements. Repaired EVMs shall be warranted for the remainder of the original warranty period. Replaced EVMs shall be warranted for a new full ninety (90) day warranty period.
3. *Regulatory Notices:*
 - 3.1 *United States*
 - 3.1.1 *Notice applicable to EVMs not FCC-Approved:*

This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.
 - 3.1.2 *For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:*

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

3.3 Japan

3.3.1 *Notice for EVMs delivered in Japan:* Please see http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_01.page 日本国内に輸入される評価用キット、ボードについては、次のところをご覧ください。
http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_01.page

3.3.2 *Notice for Users of EVMs Considered "Radio Frequency Products" in Japan:* EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required by Radio Law of Japan to follow the instructions below with respect to EVMs:

1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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4 *EVM Use Restrictions and Warnings:*

4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.

4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.

4.3 *Safety-Related Warnings and Restrictions:*

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4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and liability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.

4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.

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