

### **General Description**

The MAX1316-MAX1318/MAX1320-MAX1322/MAX1324-MAX1326 14-bit, analog-to-digital converters (ADCs) offer two, four, or eight independent input channels. Independent track/hold (T/H) circuitry provides simultaneous sampling for each channel. The MAX1316/ MAX1317/MAX1318 have a 0 to +5V input range with ±6.0V fault-tolerant inputs. The MAX1320/MAX1321/ MAX1322 have a ±5V input range with ±16.5V fault-tolerant inputs. The MAX1324/MAX1325/MAX1326 have a ±10V input range with ±16.5V fault-tolerant inputs. These ADCs convert two channels in 2µs, and up to eight channels in 3.8µs, and have an 8-channel throughput of 250ksps per channel. Other features include a 10MHz T/H input bandwidth, internal clock, internal (+2.5V) or external (+2.0V to +3.0V) reference, and powersaving modes.

A 16.6MHz, 14-bit, bidirectional, parallel interface provides the conversion results and accepts digital configuration inputs.

These devices operate from a +4.75V to +5.25V analog supply and a separate +2.7V to +5.25V digital supply, and consume less than 50mA total supply current.

These devices come in a 48-pin LQFP package and operate over the extended -40°C to +85°C temperature range.

### **Applications**

Multiphase Motor Control Power-Grid Synchronization Power-Factor Monitoring and Correction Vibration and Waveform Analysis

### **Selector Guide**

PART	INPUT RANGE (V)	CHANNEL COUNT
MAX1316ECM	0 to +5	8
MAX1317ECM	0 to +5	4
MAX1318ECM	0 to +5	2
MAX1320ECM	±5	8
MAX1321ECM	±5	4
MAX1322ECM	±5	2
MAX1324ECM	±10	8
MAX1325ECM	±10	4
MAX1326ECM	±10	2

Pin Configurations and Typical Operating Circuits appear at end of data sheet.

### **Features**

- ♦ 8-/4-/2-Channel, 14-Bit ADCs ±1.5 LSB INL, ±1 LSB DNL, No Missing Codes 90dBc SFDR, -86dBc THD, 76.5dB SINAD, 77dB SNR at 100kHz Input
- ♦ On-Chip T/H Circuit for Each Channel 10ns Aperture Delay 50ps Channel-to-Channel T/H Matching
- **♦ Fast Conversion Time** One Channel in 1.6µs Two Channels in 1.9µs Four Channels in 2.5us Eight Channels in 3.7µs
- **♦** High Throughput 526ksps/ch for One Channel 455ksps/ch for Two Channels 357ksps/ch for Four Channels 250ksps/ch for Eight Channels
- **♦ Flexible Input Ranges** 0 to +5V (MAX1316/MAX1317/MAX1318) ±5V (MAX1320/MAX1321/MAX1322) ±10V (MAX1324/MAX1325/MAX1326)
- ♦ No Calibration Needed
- ♦ 14-Bit, High-Speed, Parallel Interface
- ♦ Internal or External Clock
- ♦ +2.5V Internal Reference or +2.0V to +3.0V **External Reference**
- ◆ +5V Analog Supply, +3V to +5V Digital Supply 46mA Analog Supply Current (typ) 1.6mA Digital Supply Current (max) **Shutdown and Power-Saving Modes**
- ♦ 48-Pin LQFP Package (7mm x 7mm Footprint)

### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX1316ECM	-40°C to +85°C	48 LQFP
MAX1317ECM	-40°C to +85°C	48 LQFP
MAX1318ECM	-40°C to +85°C	48 LQFP
MAX1320ECM	-40°C to +85°C	48 LQFP
MAX1321ECM	-40°C to +85°C	48 LQFP
MAX1322ECM	-40°C to +85°C	48 LQFP
MAX1324ECM	-40°C to +85°C	48 LQFP
MAX1325ECM	-40°C to +85°C	48 LQFP
MAX1326ECM	-40°C to +85°C	48 LQFP

MIXIM

### **ABSOLUTE MAXIMUM RATINGS**

AVDD to AGND	
$\overline{\text{EOC}}$ , $\overline{\text{EOLC}}$ , $\overline{\text{WR}}$ , $\overline{\text{RD}}$ , $\overline{\text{CS}}$ to DGND0.3V to $(\overline{\text{DV}}_{\text{DD}} + 0.3V)$	
CONVST, CLK, SHDN,	
ALLON to DGND0.3V to (DV <sub>DD</sub> + 0.3V)	
MSV, REF <sub>MS</sub> , REF to AGND0.3V to (AV <sub>DD</sub> + 0.3V)	

REF+, COM, REF- to AGND0.3V to (AV <sub>DD</sub> + 0.3V) D0-D13 to DGND0.3V to (DV <sub>DD</sub> + 0.3V)
Maximum Current into Any Pin Except AV <sub>DD</sub> , DV <sub>DD</sub> , AGND, DGND±50mA
Continuous Power Dissipation
LQFP (derate 22.7mW/°C above +70°C)1818mW
Operating Temperature Range40°C to +85°C
Junction Temperature+150°C Storage Temperature Range65°C to +150°C
Lead Temperature (soldering, 10s)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **ELECTRICAL CHARACTERISTICS**

 $(V_{AVDD} = +5V, V_{DVDD} = +3V, V_{AGND} = V_{DGND} = 0, V_{REF} = V_{REFMS} = +2.5V \ (external\ reference), C_{REF} = C_{REFMS} = 0.1 \mu F, C_{REF+} = C_{REFM-10-REF-} = 2.2 \mu F \ || \ 0.1 \mu F, C_{COM} = 2.2 \mu F \ || \ 0.1 \mu F, C_{MSV} = 2.2 \mu F \ || \ 0.1 \mu F \ (unipolar\ devices, MAX1316/MAX1318), MSV = AGND \ (bipolar\ devices, MAX1320/MAX1321/MAX1322/MAX1324/MAX1325/MAX1326), f_{CLK} = 10MHz, 50%\ duty\ cycle,\ INTCLK/EXTCLK = AGND\ (external\ clock), SHDN = DGND, T_A = T_{MIN}\ to\ T_{MAX}, unless\ otherwise\ noted. Typical\ values\ are\ at\ T_A = +25°C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
STATIC PERFORMANCE (Note	1)						
Resolution	N		14			Bits	
Integral Nonlinearity	INL	(Note 2)		±0.8	±2.0	LSB	
Differential Nonlinearity	DNL	No missing codes (Note 2)		±0.5	±1	LSB	
Offset Error		Unipolar devices			±40	LSB	
Oliset Error		Bipolar devices			±40	LOD	
Offset Drift		Unipolar devices		-4		nnm/°C	
Oliset Driit		Bipolar devices		-4		ppm/°C	
Channel Offset Metabing		Unipolar devices between all channels		35	80	LSB	
Channel Offset Matching		Bipolar devices between all channels		25	60	LOD	
Gain Error		(Note 3)		±8	±40	LSB	
Channel Gain-Error Matching		Between all channels			25	LSB	
Gain Temperature Coefficient				3		ppm/°C	
DYNAMIC PERFORMANCE (at f	<sub>N</sub> = 100kHz, -	0.4dB FS)					
•	SNR	Unipolar	74.5	76		٩D	
Signal-to-Noise Ratio	SINH	Bipolar	75	76.5		dB	
Signal-to-Noise and Distortion	SINAD	Unipolar	74.5	76		dB	
Ratio	SIIVAD	Bipolar	75	76.5		ab ab	
Spurious-Free Dynamic Range	SFDR		83	93		dBc	
Total Harmonic Distortion	THD			-90	-83	dBc	
Channel-to-Channel Isolation			83			dB	
ANALOG INPUTS (CH0-CH7)							
		MAX1316/MAX1317/MAX1318	0		+5		
Input Voltage Range		MAX1320/MAX1321/MAX1322	-5		+5	V	
		MAX1324/MAX1325/MAX1326	-10		+10		

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{AVDD} = +5V, V_{DVDD} = +3V, V_{AGND} = V_{DGND} = 0, V_{REF} = V_{REFMS} = +2.5V \ (external reference), C_{REF} = C_{REFMS} = 0.1 \mu F, C_{REF+} = C_{REF-} = 0.1 \mu F, C_{REF+} = 2.2 \mu F \ II \ 0.1 \mu F, C_{COM} = 2.2 \mu F \ II \ 0.1 \mu F, C_{MSV} = 2.2 \mu F \ II \ 0.1 \mu F \ (unipolar devices, MAX1316/MAX1317/MAX1318), MSV = AGND \ (bipolar devices, MAX1320/MAX1321/MAX1322/MAX1324/MAX1325/MAX1326), f_{CLK} = 10MHz, 50% \ duty \ cycle, INTCLK/EXTCLK = AGND \ (external clock), SHDN = DGND, T_A = T_{MIN} \ to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)$ 

PARAMETER	SYMBOL	CONDITIONS	CONDITIONS			MAX	UNITS
		MAX1316/MAX1317/MAX1318	$V_{IN} = +5V$		0.54	0.72	
		IVIAX 13 TO/IVIAX 13 TY/IVIAX 13 TO	$V_{IN} = 0V$	-0.157	-0.12		
Input Current (Note 4)		MAX1320/MAX1321/MAX1322	$V_{IN} = +5V$		0.29	0.39	mA
Imput Guirent (Note 4)		IVIAX 1320/IVIAX 132 I/IVIAX 1322	$V_{IN} = -5V$	-1.16	-0.87		IIIA
		MAX1324/MAX1325/MAX1326	$V_{IN} = +10V$		0.56	0.74	
			$V_{IN} = -10V$	-1.13	-0.85		
		MAX1316/MAX1317/MAX1318			7.58		
Input Resistance (Note 4)		MAX1320/MAX1321/MAX1322			8.66		kΩ
		MAX1324/MAX1325/MAX1326			14.26		
Input Capacitance					15		рF
TRACK/HOLD							
		One channel			526		
External-Clock Throughput Rate		Two channels			455		liana
(Note 5)		Four channels			357		ksps
		Eight channels		250			
		One channel (INTCLK/EXTCLK = AVDD)			526		
Internal-Clock Throughput Rate		Two channels (INTCLK/EXTCL		455			
(Note 5)		Four channels (INTCLK/EXTCL		357		ksps	
		Eight channels (INTCLK/EXTCL					
Small-Signal Bandwidth					10		MHz
Full-Power Bandwidth					10		MHz
Aperture Delay					16		ns
Aperture Jitter					50		ps <sub>RMS</sub>
Aperture-Delay Matching					100		ps
INTERNAL REFERENCE							
REFMS Voltage	VREFMS			2.475	2.500	2.525	V
REF Voltage	V <sub>REF</sub>			2.475	2.500	2.525	V
REF Temperature Coefficient					30		ppm/°C
EXTERNAL REFERENCE (REF <sub>M</sub>	S AND REF E	EXTERNALLY DRIVEN)					
Input Current				-250		+250	μΑ
REFMS Input Voltage Range	V <sub>REFMS</sub>	Unipolar devices		2.0	2.5	3.0	V
REF Voltage Input Range	V <sub>REF</sub>			2.0	2.5	3.0	V
REF Input Capacitance					15		рF
REFMS Input Capacitance					15		рF
DIGITAL INPUTS (D0–D7, $\overline{RD}$ , $\overline{W}$	R, CS, CLK,	SHDN, ALLON, CONVST)					
Input-Voltage High	VIH			0.7 x DV <sub>DD</sub>			V

### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{AVDD} = +5V, V_{DVDD} = +3V, V_{AGND} = V_{DGND} = 0, V_{REF} = V_{REFMS} = +2.5V \ (external \ reference), C_{REF} = C_{REFMS} = 0.1 \mu F, C_{REF+} = C_{REF-} = 0.1 \mu F, C_{REF+} = 2.2 \mu F \ II \ 0.1 \mu F, C_{COM} = 2.2 \mu F \ II \ 0.1 \mu F, C_{MSV} = 2.2 \mu F \ II \ 0.1 \mu F \ (unipolar \ devices, MAX1316/MAX1317/MAX1318), MSV = AGND \ (bipolar \ devices, MAX1320/MAX1321/MAX1322/MAX1324/MAX1325/MAX1326), f_{CLK} = 10MHz, 50% \ duty \ cycle, INTCLK/EXTCLK = AGND \ (external \ clock), SHDN = DGND, T_A = T_{MIN} \ to T_{MAX}, unless \ otherwise \ noted. Typical \ values are at T_A = +25°C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
Input-Voltage Low	VIL				0.3 x DV <sub>DD</sub>	V	
Input Hysteresis				15		mV	
Input Capacitance	CIN			15		рF	
Input Current	I <sub>IN</sub>	$V_{IN} = 0V \text{ or } DV_{DD}$			±1	μΑ	
CLOCK-SELECT INPUT (INTCL	K/EXTCLK)						
Input-Voltage High			0.7 x AV <sub>DD</sub>			V	
Input-Voltage Low					0.3 x AV <sub>DD</sub>	V	
DIGITAL OUTPUTS (D0-D13, E	OC, EOLC)						
Output-Voltage High	Voн	ISOURCE = 0.8mA	DV <sub>DD</sub> - 0.6			V	
Output-Voltage Low	V <sub>OL</sub>	ISINK = 1.6mA			0.4	V	
Tri-State Leakage Current		$\overline{RD} \ge V_{IH} \text{ or } \overline{CS} \ge V_{IH}$		0.06	1	μΑ	
Tri-State Output Capacitance		$\overline{RD} \ge V_{IH} \text{ or } \overline{CS} \ge V_{IH}$		15		рF	
POWER SUPPLIES							
Analog-Supply Voltage	AV <sub>DD</sub>		4.75		5.25	V	
Digital-Supply Voltage	DV <sub>DD</sub>		2.70		5.25	V	
Analog-Supply Current	lavdd	All channels selected		46	56	mA	
Digital-Supply Current	I <sub>DVDD</sub>	C <sub>LOAD</sub> = 100pF, all channels selected (Note 6)		1.6	mA		
Charteleure Carrent (Note 7)	lavdd	V <sub>SHDN</sub> = DV <sub>DD</sub> , V <sub>CH</sub> = float			10	_	
Shutdown Current (Note 7)	I <sub>DVDD</sub>	$V_{\overline{RD}} = V_{\overline{WR}} = DV_{DD}, V_{SHDN} = DV_{DD}$		0.1	2	μA	
Power-Supply Rejection Ratio	PSRR	$AV_{DD} = +4.75V \text{ to } +5.75V \text{ (Note 8)}$		50		dB	

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### TIMING CHARACTERISTICS (Figures 3, 4, 5, 6 and 7) (Tables 1, 3)

PARAMETER SYMBOL CONDI		CONDITIONS	MIN	TYP	MAX	UNITS
		Internal clock		1.6	1.8	μs
Time-to-First-Conversion Result	tCONV	External clock, Figure 6		16		Clock cycles
		Internal clock		0.3	0.36	μs
Time-to-Next-Conversion Result	tNEXT	External clock, Figure 6		3		Clock cycles
CONVST Pulse-Width Low (Acquisition Time)	tACQ	(Note 9)	0.16		100	μs
CS Pulse Width	t <sub>2</sub>		30			ns
RD Pulse-Width Low	t <sub>3</sub>		30			ns
RD Pulse-Width High	t4		30			ns
WR Pulse-Width Low	t <sub>5</sub>		30			ns
CS to WR	t <sub>6</sub>			(Note 10)		ns
WR to CS	t <sub>7</sub>			(Note 10)		ns
CS to RD	t <sub>8</sub>			(Note 10)		ns
RD to CS	t9			(Note 10)		ns
Data-Access Time (RD Low to Valid Data)	t <sub>10</sub>				30	ns
Bus-Relinquish Time (RD High)	t <sub>11</sub>				30	ns
		Internal clock	80			ns
EOC Pulse Width	t <sub>12</sub>	External clock, Figure 6		1		Clock cycles
Input-Data Setup Time	t <sub>14</sub>		10			ns
Input-Data Hold Time	t <sub>15</sub>		10			ns
External-Clock Period	t <sub>16</sub>		0.08		10.00	μs
External-Clock High Period	t <sub>17</sub>	Logic sensitive to rising edges	20			ns
External-Clock Low Period	t <sub>18</sub>	Logic sensitive to rising edges	20			ns
External-Clock Frequency		(Note 11)	0.1		12.5	MHz
Internal-Clock Frequency				10		MHz
CONVST High to CLK Edge	t <sub>19</sub>		20	(Note 12)		ns

**Note 1:** For the MAX1316/MAX1317/MAX1318,  $V_{IN} = 0$  to +5V. For the MAX1320/MAX1321/MAX1322,  $V_{IN} = -5V$  to +5V. For the MAX1324/MAX1325/MAX1326,  $V_{IN} = -10V$  to +10V.

Note 2: All channel performance is guaranteed by correlation to a single channel test.

Note 3: Offset nulled.

Note 4: The analog input resistance is terminated to an internal bias point. Calculate the analog input current using:

$$I_{CH_{-}} = \frac{V_{CH_{-}} - V_{BIAS}}{R_{CH_{-}}}$$

for V<sub>CH</sub> within the input voltage range.

**Note 5:** Throughput rate is given per channel. Throughput rate is a function of clock frequency (fclk = 10MHz). See the *Data Throughput* section for more information.

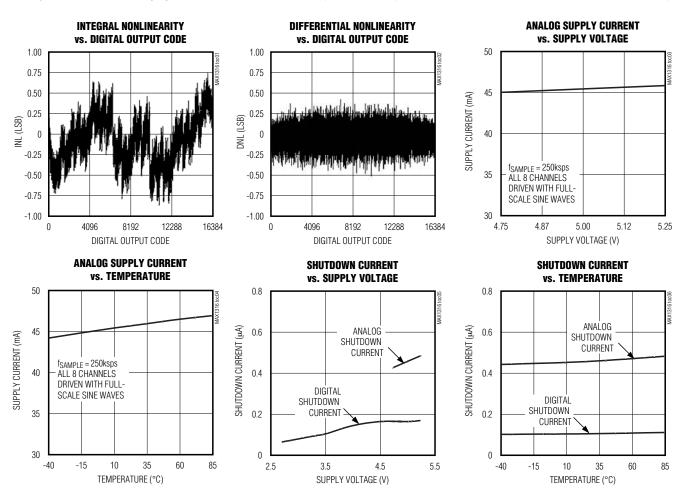
Note 6: All analog inputs are driven with an FS 100kHz sine wave.

### TIMING CHARACTERISTICS (Figures 3, 4, 5, 6 and 7) (Tables 1, 3) (continued)

- **Note 7:** Shutdown current is measured with analog input floating. The large amplitude of the maximum shutdown current specification is due to automatic test equipment limitations.
- **Note 8:** Defined as the change in positive full scale caused by ±5% variation in the nominal supply voltage.
- **Note 9:** CONVST must remain low for at least the acquisition period. The maximum acquisition time is limited by internal capacitor droop.
- Note 10:  $\overline{\text{CS}}$ -to- $\overline{\text{WR}}$  and  $\overline{\text{CS}}$ -to- $\overline{\text{RD}}$  pins are internally AND together. Setup and hold times do not apply.
- Note 11: Minimum clock frequency is limited only by the internal T/H droop rate. Limit the time between the falling edge of CONVST to the falling edge of EOLC to a maximum of 0.25ms.
- Note 12: To avoid T/H droop degrading the sampled analog input signals, the first clock pulse should occur within 10μs of the rising edge of CONVST, and have a minimum clock frequency of 100kHz.

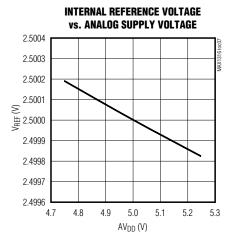
### \_Typical Operating Characteristics

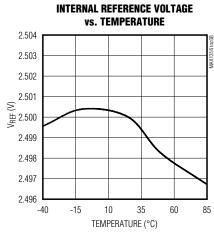
 $(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0V, V_{REF} = V_{REFMS} = +2.5V$  (external reference), see the *Typical Operating Circuits* section,  $f_{CLK} = 10MHz$ , 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), SHDN = DGND,  $T_A = +25$ °C, unless otherwise noted.)

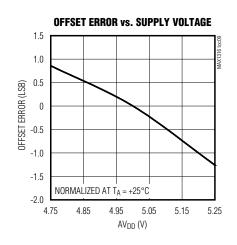


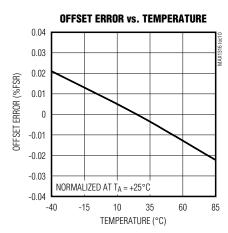
### Typical Operating Characteristics (continued)

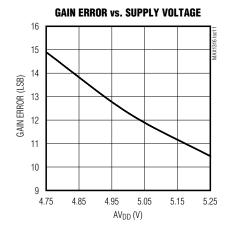
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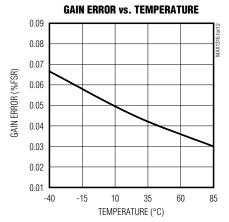






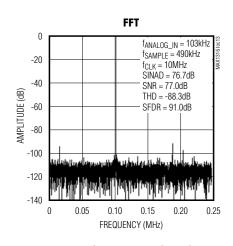


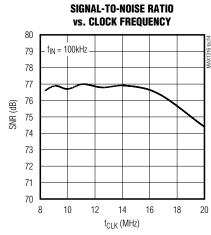


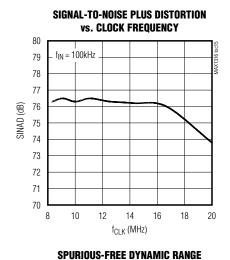


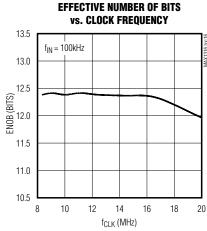
### Typical Operating Characteristics (continued)

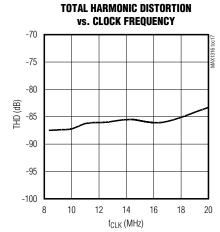
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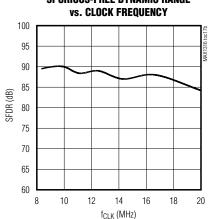






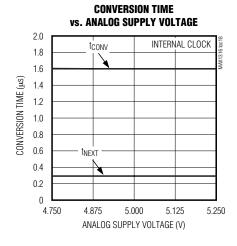


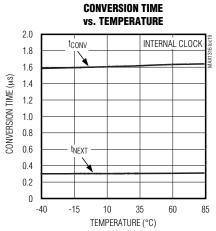


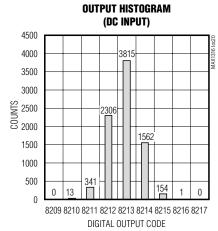


### Typical Operating Characteristics (continued)

 $(AV_{DD} = +5V, DV_{DD} = +3V, AGND = DGND = 0V, V_{REF} = V_{REFMS} = +2.5V$  (external reference), see the *Typical Operating Circuits* section,  $f_{CLK} = 10MHz$ , 50% duty cycle, INTCLK/EXTCLK = AGND (external clock), SHDN = DGND,  $T_A = +25^{\circ}C$ , unless otherwise noted.)







### **Pin Description**

	PIN			
MAX1316 MAX1320 MAX1324	MAX1317 MAX1321 MAX1325	MAX1318 MAX1322 MAX1326	NAME	FUNCTION
1, 15, 17	1, 15, 17	1, 15, 17	$AV_DD$	Analog Supply Input. AVDD is the power input for the analog section of the converter. Apply 4.75V to 5.25V to AVDD. Bypass AVDD to AGND (pin 14 to pin 15, pin 16 to pin 17, pin 1 to pin 2) with a 0.1 $\mu$ F capacitor at each AVDD input.
2, 3, 14, 16, 23	2, 3, 14, 16, 23	2, 3, 14, 16, 23	AGND	Analog Ground. AGND is the power return for AVDD. Connect all AGNDs together.
4	4	4	CH0	Channel 0 Analog Input
5	5	5	CH1	Channel 1 Analog Input
6	6	6	MSV	Midscale Voltage Bypass. For the MAX1316/MAX1317/MAX1318, connect a 2.2µF and a 0.1µF capacitor from MSV to AGND. For the MAX1320/MAX1321/MAX1322/MAX1324/MAX1325/MAX1326, connect MSV directly to AGND.
7	7	_	CH2	Channel 2 Analog Input
8	8	_	CH3	Channel 3 Analog Input
9	_	_	CH4	Channel 4 Analog Input

### **Pin Description (continued)**

PIN				
MAX1316 MAX1320 MAX1324	MAX1317 MAX1321 MAX1325	MAX1318 MAX1322 MAX1326	NAME	FUNCTION
10	_	_	CH5	Channel 5 Analog Input
11	_	_	CH6	Channel 6 Analog Input
12	_	_	CH7	Channel 7 Analog Input
13	13	13	INTCLK/ EXTCLK	Clock-Mode Select Input. Use INTCLK/EXTCLK to select the internal or external conversion clock. Connect INTCLK/EXTCLK to AV <sub>DD</sub> to select the internal clock. Connect INTCLK/EXTCLK to AGND to use an external clock connected to CLK.
18	18	18	REFMS	Midscale Reference Bypass or Input. REF <sub>MS</sub> is the bypass point for an internally generated reference voltage. For the MAX1316/MAX1317/MAX1318, connect a 0.1µF capacitor from REF <sub>MS</sub> to AGND. For the MAX1320/MAX1321/MAX1322/MAX1324/MAX1325/MAX1326, connect REF <sub>MS</sub> directly to REF and bypass with a 0.1µF capacitor from REF <sub>MS</sub> to AGND.
19	19	19	REF	ADC Reference Bypass or Input. REF is the bypass point for an internally generated reference voltage. Bypass REF with a 0.01µF capacitor to AGND. REF can be driven externally by a precision external voltage reference.
20	20	20	REF+	Positive Reference Bypass. REF+ is the bypass point for an internally generated reference voltage. Bypass REF+ with a 0.1µF capacitor to AGND. Also bypass REF+ to REF- with a 2.2µF and a 0.1µF capacitor.
21	21	21	СОМ	Reference Common Bypass. COM is the bypass point for an internally generated reference voltage. Bypass COM to AGND with a 2.2µF and a 0.1µF capacitor.
22	22	22	REF-	Negative Reference Bypass. REF- is the bypass point for an internally generated reference voltage. Bypass REF- with a 0.1µF capacitor to AGND. Also bypass REF- to REF+ with a 2.2µF and a 0.1µF capacitor.
24	24	24	D0	Digital I/O Bit 0 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .
25	25	25	D1	Digital I/O Bit 1 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .
26	26	26	D2	Digital I/O Bit 2 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .

### **Pin Description (continued)**

	PIN		PIN			
MAX1316 MAX1320 MAX1324	MAX1317 MAX1321 MAX1325	MAX1318 MAX1322 MAX1326	NAME	FUNCTION		
27	27	27	D3	Digital I/O Bit 3 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
28	28	28	D4	Digital I/O Bit 4 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
29	29	29	D5	Digital I/O Bit 5 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
30	30	30	D6	Digital I/O Bit 6 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
31	31	31	D7	Digital I/O Bit 7 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
32	32	32	D8	Digital Out Bit 8 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
33	33	33	D9	Digital Out Bit 9 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
34	34	34	D10	Digital Out Bit 10 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
35	35	35	D11	Digital Out Bit 11 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
36	36	36	D12	Digital Out Bit 12 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
37	37	37	D13	Digital Out Bit 13 of 14-Bit Parallel Data Bus. High impedance when $\overline{RD} = 1$ or $\overline{CS} = 1$ .		
38	38	38	DV <sub>DD</sub>	Digital-Supply Input. Apply +2.7V to +5.25V to DV <sub>DD</sub> . Bypass DV <sub>DD</sub> to DGND with a 0.1µF capacitor.		
39	39	39	DGND	Digital-Supply GND. DGND is the power return for DV <sub>DD</sub> . Connect DGND to AGND at only one point (see the <i>Layout, Grounding, and Bypassing</i> section).		
40	40	40	EOC	End-of-Conversion Output. EOC goes low to indicate the end of a conversion. EOC returns high after one clock period.		

### **Pin Description (continued)**

	PIN			
MAX1316 MAX1320 MAX1324	MAX1317 MAX1321 MAX1325	MAX1318 MAX1322 MAX1326	NAME	FUNCTION
41	41	41	EOLC	End-of-Last-Conversion Output. EOLC goes low to indicate the end of the last conversion. EOLC returns high when CONVST goes low for the next conversion sequence.
42	42	42	RD	Read Input. When $\overline{RD}$ and $\overline{CS}$ go low, the device initiates a read command of the parallel data buses, D0–D13. D0–D13 are high impedance while either $\overline{RD}$ or $\overline{CS}$ is high.
43	43	43	WR	Write Input. The write command initiates when $\overline{\text{WR}}$ and $\overline{\text{CS}}$ go low. A write command loads the configuration byte on D0–D7.
44	44	44	CS	Chip-Select Input. Pulling $\overline{\text{CS}}$ low activates the digital interface. D0–D13 are high impedance while either $\overline{\text{CS}}$ or $\overline{\text{RD}}$ is high.
45	45	45	CONVST	Convert-Start Input. Driving CONVST high places the device in hold mode and initiates the conversion process. The analog inputs are sampled on the rising edge of CONVST. When CONVST is low, the analog inputs are tracked.
46	46	46	CLK	External-Clock Input. CLK accepts an external-clock signal up to 15MHz. Connect CLK to DGND for internally clocked conversions. To select external-clock mode, set INTCLK/EXTCLK = 0.
47	47	47	SHDN	Shutdown Input. Set SHDN = 0 for normal operation. Set SHDN = 1 for shutdown mode.
48	48	48	ALLON	Enable-All-Channels Input. Drive ALLON high to enable all input channels. When ALLON is low, only input channels selected as active are powered. Select channels as active using the configuration register.
_	9–12	7–12	I.C.	Internally Connected. Connect I.C. to AGND. For factory use only.

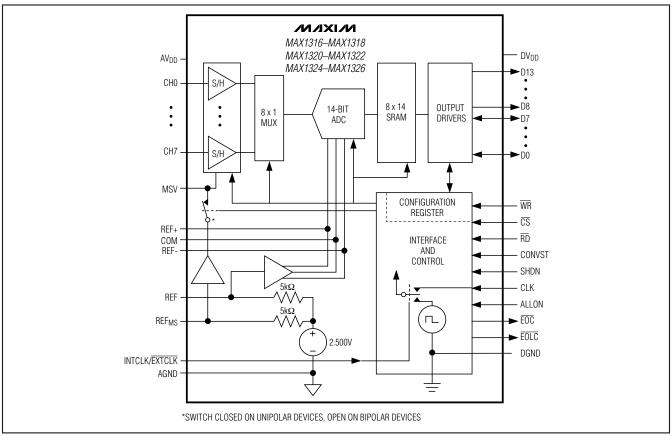


Figure 1. Functional Diagram

### **Detailed Description**

The MAX1316-MAX1318/MAX1320-MAX1322/MAX1324-MAX1326 are 14-bit ADCs. They offer two, four, or eight (independently selectable) input channels, each with its own T/H circuitry. Simultaneous sampling of all active channels preserves relative phase information, making these devices ideal for motor control and power monitoring. These devices are available with 0 to +5V, ±5V, and ±10V input ranges. The 0 to +5V devices feature ±6V fault-tolerant inputs. The ±5V and ±10V devices feature ±16.5V fault-tolerant inputs. Two channels convert in 2µs; all eight channels convert in 3.8µs, with a maximum 8channel throughput of 263ksps per channel. Internal or external reference and internal- or external-clock capability offer great flexibility and ease of use. A write-only configuration register can mask out unused channels, and a shutdown feature reduces power. A 16.6MHz, 14-bit, parallel data bus outputs the conversion result. Figure 1 shows the functional diagram of these devices.

### **Analog Inputs**

T/H

To preserve phase information across these multichannel devices, each input channel has a dedicated T/H amplifier.

Use a low-input source impedance to minimize gainerror harmonic distortion. The time required for the T/H to acquire an input signal depends on the input source impedance. If the input signal's source impedance is high, the acquisition time lengthens and more time must be allowed between conversions. The acquisition time (t<sub>1</sub>) is the maximum time the device takes to acquire the signal. Use the following formula to calculate acquisition time:

$$t_1 = 10 (R_S + R_{IN}) \times 6pF$$

where  $R_{IN}=2.2k\Omega$ ,  $R_S=$  the input signal's source impedance, and  $t_1$  is never less than 180ns. A source impedance of less than  $100\Omega$  does not significantly affect the ADC's performance.

To improve the input-signal bandwidth under AC conditions, drive the input with a wideband buffer (>50MHz) that can drive the ADC's input capacitance and settle quickly. For example, the MAX4265 can be used for  $\pm 5$ V unipolar devices, or the MAX4350 can be used for  $\pm 5$ V bipolar inputs.

The T/H aperture delay is typically 13ns. The aperturedelay mismatch between T/Hs of 50ps allows the relative phase information of up to eight different inputs to be preserved. Figure 2 shows a simplified equivalent input circuit, illustrating the ADC's sampling architecture.

### Input Bandwidth

The input tracking circuitry has a 12MHz small-signal bandwidth, making it is possible to digitize high-speed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. To avoid high-frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.

### Input Range and Protection

These devices provide ±10V, ±5V, or 0 to +5V analog input voltage ranges. Figure 2 shows the equivalent input circuit. Overvoltage protection circuitry at the analog input provides ±16.5V fault protection for the bipolar input devices and ±6.0V fault protection for the unipolar input devices. This fault-protection circuit limits the current going into or out of the device to less than 50mA, providing an added layer of protection from momentary overvoltage or undervoltage conditions at the analog input.

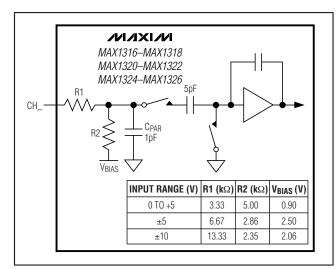


Figure 2. Typical Input Circuit

#### **Power-Saving Modes**

#### Shutdown Mode

During shutdown, the analog and digital circuits in the device power down and the device draws less than 100 $\mu$ A from AVDD, and less than 100 $\mu$ A from DVDD. Select shutdown mode using the SHDN input. Set SHDN high to enter shutdown mode. After coming out of shutdown, allow a 1ms wake-up time before making the first conversion. When using an external clock, apply at least 20 clock cycles with CONVST high before making the first conversion. When using internal-clock mode, wait at least 2 $\mu$ s before making the first conversion.

#### **ALLON**

ALLON is useful when some of the analog input channels are selected (see the Configuration Register section). Drive ALLON high to power up all input channel circuits, regardless of whether they are selected as active by the configuration register. Drive ALLON low or connect to ground to power only the input channels selected as active by the configuration register, saving 2mA per channel (typ). The wake-up time for any channel turned on with the configuration register is 2µs (typ) when ALLON is low. The wake-up time with ALLON high is only 0.01µs. New configuration-register information does not become active until the next CONVST falling edge. Therefore, when using software to control power states (ALLON = 0), pulse CONVST low once before applying the actual CONVST signal (Figure 3). With an external clock, apply at least 15 clock cycles before the second CONVST. If using internal-clock mode, wait at least 1.5µs or until the first EOC before generating the second CONVST.

Table 1. Conversion Times Using the Internal Clock

NUMBER OF CHANNELS	INTERNAL-CLOCK CONVERSION TIME
1	1.6
2	1.9
3	2.2
4	2.5
5	2.8
6	3.1
7	3.4
8	3.7

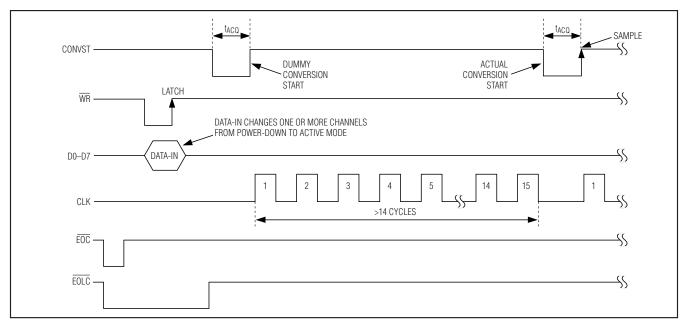


Figure 3. Software Channel Wake-Up Timing (ALLON = 0)

#### **Clock Modes**

These devices provide an internal clock of 10MHz (typ). Alternatively, an external clock can be used.

#### Internal Clock

Internal-clock mode frees the microprocessor from the burden of running the ADC conversion clock. For internal-clock operation, connect INTCLK/EXTCLK to AVDD and connect CLK to DGND. Table 1 illustrates the total conversion time using internal-clock mode.

#### External Clock

For external-clock operation, connect INTCLK/EXTCLK to AGND and connect an external-clock source to CLK. Note that INTCLK/EXTCLK is referenced to the analog power supply, AVDD. The external-clock frequency can be up to 15MHz, with a duty cycle between 30% and 70%. Clock frequencies of 100kHz and lower can be used, but the droop in the T/H circuits reduce linearity.

#### Selecting an Input Buffer

Most applications require an input buffer to achieve 14-bit accuracy. Although slew-rate and bandwidth are important, the most critical specification is settling time. The sampling requires a relatively brief sampling interval of 150ns. At the beginning of the acquisition, the internal sampling capacitor array connects to CH\_ (the amplifier output), causing some output disturbance. Ensure the amplifier is capable of settling to at least 14-bit accuracy during this interval. Use a low-noise, low-distortion, wideband amplifier (such as the MAX4350 or

MAX4265), which settles quickly and is stable with the ADC's capacitive load (in parallel with any bypass capacitors on the analog inputs).

### Applications Section

### **Digital Interface**

The bidirectional, parallel, digital interface sets the 8-bit configuration register (see the *Configuration Register* section) and outputs the 14-bit conversion result. The interface includes the following control signals: chip select  $(\overline{CS})$ , read  $(\overline{RD})$ , write  $(\overline{WR})$ , end of conversion  $(\overline{EOC})$ , end of last conversion  $(\overline{EOLC})$ , convert start  $(\overline{CONVST})$ , shutdown  $(\overline{SHDN})$ , all on  $(\overline{ALLON})$ , internal-clock select  $(\overline{INTCLK}, \overline{EXTCLK})$ , and external-clock input  $(\overline{CLK})$ . Figures 4, 5, 6, 7, Table 4, and the *Timing Characteristics* section show the operation of the interface. D0–D7 are bidirectional, and D8–D13 are output only. All bits are high impedance when  $\overline{RD} = 1$  or  $\overline{CS} = 1$ .

### **Configuration Register**

Enable channels as active by writing to the configuration register through I/O lines D0–D7 (Table 2). The bits in the configuration register map directly to the channels, with D0 controlling channel zero, and D7 controlling channel seven. Setting any bit high activates the corresponding input channel, while resetting any bit low deactivates the corresponding channel. Devices with fewer than eight channels contain some bits that have no function.

**Table 2. Configuration Register** 

PART NO.	STATE	BIT/CHANNEL							
PARTINO. STATE	D0/CH0	D1/CH1	D2/CH2	D3/CH3	D4/CH4	D5/CH5	D6/CH6	D7/CH7	
MAX1316	ON	1	1	1	1	1	1	1	1
MAX1320 MAX1324	OFF	0	0	0	0	0	0	0	0
MAX1317 MAX1321 MAX1325	ON	1	1	1	1	NA	NA	NA	NA
	OFF	0	0	0	0	NA	NA	NA	NA
MAX1318	ON	1	1	NA	NA	NA	NA	NA	NA
MAX1322 - MAX1326	OFF	0	0	NA	NA	NA	NA	NA	NA

NA = Not applicable.

To write to the configuration register, pull  $\overline{\text{CS}}$  and  $\overline{\text{WR}}$  low, load bits D0–D7 onto the parallel bus, and force  $\overline{\text{WR}}$  high. The data are latched on the rising edge of  $\overline{\text{WR}}$  (Figure 4). It is possible to write to the configuration register at any point during the conversion sequence; however, it is not active until the next convert-start signal. At power-up, write to the configuration register to select the active channels before beginning a conversion. Shutdown does not change the configuration register. See the *Shutdown Mode* and the *ALLON* sections for information about using the configuration register for power saving.

#### Starting a Conversion

To start a conversion using internal-clock mode, pull CONVST low for at least the acquisition time (t<sub>1</sub>). The T/H acquires the signal while CONVST is low, and conversion begins on the <u>rising</u> edge of CONVST. An end-of-conversion signal ( $\overline{EOC}$ ) pulses low when the first result becomes available, and for each subsequent result until the end of the conversion cycle. The end-of-last-conversion signal ( $\overline{EOLC}$ ) goes low when the last conversion result is available (Figures 5, 6, and 7).

To start a conversion using external-clock mode, pull CONVST low for at least the acquisition time (t<sub>1</sub>). The T/H acquires the signal while CONVST is low, and conversion begins on the rising edge of CONVST. Apply an external clock to CLK. To avoid T/H droop degrading the sampled analog input signals, the first clock pulse should occur within 10µs from the rising edge of CONVST, and have a minimum clock frequency of 100kHz. The first conversion result is available for read on the rising edge of the 17th clock cycle, and subsequent conversions after every third clock cycle thereafter (Figures 5, 6, and 7).

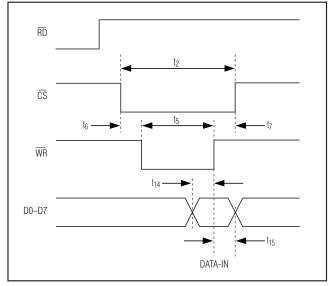


Figure 4. Write Timing

In both internal- and external-clock modes, CONVST must be held high until the last conversion result is read. For best operation, the rising edge of CONVST must be a clean, high-speed, low-jitter digital signal.

Table 3 shows the total throughput as a function of the clock frequency and the number of channels selected for conversion. The calculations use the nominal speed of the internal clock (10MHz) and a 200ns CONVST pulse width.

### **Data Throughput**

The data throughput (f<sub>TH</sub>) of the MAX1316–MAX1318/MAX1320–MAX1322/MAX1324–MAX1326 is a function of the clock speed (f<sub>CLK</sub>). In internal-clock mode, f<sub>CLK</sub> = 10MHz. In external-clock mode, 100kHz  $\leq$  f<sub>CLK</sub>  $\leq$  12.5MHz. When reading during conversion (Figures 5 and 6), calculate f<sub>TH</sub> as follows:

$$f_{TH} = \frac{1}{t_{QUIET} + \frac{16 + 3 \times (N-1) + 1}{f_{CLK}}}$$

where N is the number of active channels and tquiet includes acquistion time tacq. tquiet is the period of bus inactivity before the rising edge of CONVST. Typically use tquiet = tacq + 50ns, and prevent disturbance on the output bus from corrupting signal acquistion. See the Starting a Conversion section for more information.

### **Reading a Conversion Result**

#### Reading During a Conversion

Figures 5 and 6 show the interface signals for initiating a read operation during a conversion cycle. These figures show two channels selected for conversion. If more channels are selected, the results are available successively every third clock cycle.  $\overline{CS}$  can be low at all times; it can be low during the  $\overline{RD}$  cycles, or it can be the same as  $\overline{RD}$ .

After initiating a conversion by bringing CONVST high, wait for EOC to go low (about 1.6µs in internal-clock mode or 17 clock cycles in external-clock mode) before reading the first conversion result. Read the conversion result by bringing RD low, thus latching the data to the parallel digital-output bus. Bring RD high to release the digital bus. Wait for the next falling edge of EOC (about 300ns in internal-clock mode or three clock cycles in external-clock mode) before reading the next result. When the last result is available, EOLC goes low.

Table 3. Throughput vs. Channels Sampled (tQUIET = tACQ = 200ns, fCLK = 10MHz)

CHANNELS SAMPLED (N)	CLOCK CYCLES UNTIL LAST RESULT	CLOCK CYCLE FOR READING LAST CONVERSION	TOTAL CONVERSION TIME (ns)	SAMPLES PER SECOND (ksps)	THROUGHPUT PER CHANNEL (ksps)
1	16	1	1900	526	526
2	19	1	2200	909	455
3	22	1	2500	1200	400
4	25	1	2800	1429	357
5	28	1	3100	1613	323
6	31	1	3400	1765	294
7	34	1	3700	1892	270
8	37	1	4000	2000	250

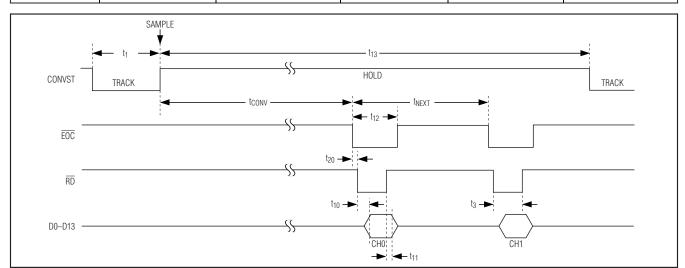


Figure 5. Read During Conversion—Two Channels Selected, Internal Clock

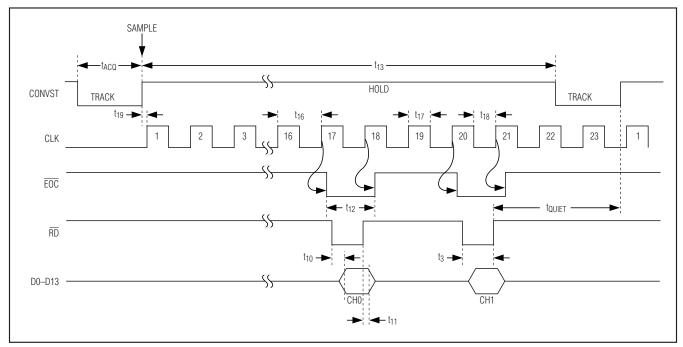


Figure 6. Read During Conversion—Two Channels Selected, External Clock

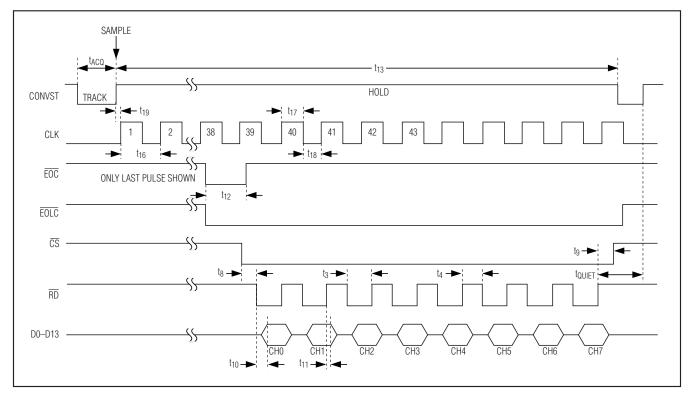


Figure 7. Reading After Conversion—Eight Channels Selected, External Clock

#### Reading After Conversion

Figure 7 shows the interface signals for a read operation after a conversion with all eight channels enabled. At the falling edge of  $\overline{EOLC}$ , on the 38th clock pulse after the initiation of a conversion, driving  $\overline{CS}$  and  $\overline{RD}$  low places the first conversion result onto the parallel bus, which can be latched on the rising edge of  $\overline{RD}$ . Successive low pulses of  $\overline{RD}$  place the successive conversion results onto the bus. Pulse CONVST low to initiate a new conversion.

#### **Power-Up Reset**

At power-up, all channels are selected for conversion (see the *Configuration Register* section). After applying power, allow a 1.0ms wake-up time to elapse before initiating the first conversion. Then, hold CONVST high for at least 2.0µs after the wake-up time is complete. If using an external clock, apply 20 clock pulses to CLK with CONVST high before initiating the first conversion.

#### Reference

#### Internal Reference

The internal-reference circuits provide for analog input voltages of 0 to +5V unipolar (MAX1316/MAX1317/MAX1318), ±5V bipolar (MAX1320/MAX1321/MAX1322), or ±10V bipolar (MAX1324/MAX1325/MAX1326). Install external capacitors for reference stability, as indicated in Table 4, and as shown in the *Typical Operating Circuits*.

#### External Reference

Connect a +2.0V to +3.0V external reference at REFMs and/or REF. When connecting an external reference, the input impedance is typically  $5k\Omega$ . The external reference must be able to drive  $200\mu A$  of current and have a low output impedance. For more information about using external references see the *Transfer Functions* section.

#### Layout, Grounding, and Bypassing

For best performance use PC boards with ground planes. Board layout should ensure that digital and analog signal lines are separated from each other. Do not run analog and digital lines parallel to one another (especially clock lines), or do not run digital lines underneath the ADC package. Figure 8 shows the recommended system ground connections when not using a ground plane. A single-point analog ground (star ground point) should be established at AGND, separate from the logic ground. All other analog grounds and DGND should be connected to this ground.

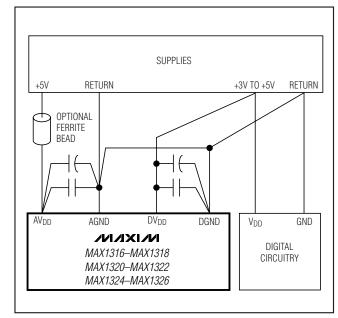


Figure 8. Power-Supply Grounding and Bypassing

### **Table 4. Reference Bypass Capacitors**

LOCATION	INPUT VOLTAGE RANGE			
LOCATION	UNIPOLAR (μF)	BIPOLAR (μF)		
MSV bypass capacitor to AGND	2.2    0.1	NA		
REF <sub>MS</sub> bypass capacitor to AGND	0.01	0.01 (connect REF <sub>MS</sub> to REF)		
REF bypass capacitor to AGND	0.01	0.01 (connect REF <sub>MS</sub> to REF)		
REF+ bypass capacitor to AGND	0.1	0.1		
REF+ to REF- capacitor	2.2    0.1	2.2    0.1		
REF- bypass capacitor to AGND	0.1	0.1		
COM bypass capacitor to AGND	2.2    0.1	2.2    0.1		

NA = Not applicable (connect MSV directly to AGND).

No other digital system ground should be connected to this single-point analog ground. The ground return to the power supply for this ground should be low impedance and as short as possible for noise-free operation. High-frequency noise in the  $V_{DD}$  power supply may affect the high-speed comparator in the ADC. Bypass these supplies to the single-point analog ground with 0.1 $\mu$ F and 2.2 $\mu$ F bypass capacitors close to the device. If the +5V power supply is very noisy, a ferrite bead can be connected as a lowpass filter, as shown in Figure 8.

### **Transfer Functions**Bipolar ±10V Devices

Table 5 and Figure 9 show the two's complement transfer function for the MAX1324/MAX1325/MAX1326 with a ±10V input range. The full-scale input range (FSR) is eight times the voltage at REF. The internal +2.500V reference gives a +20V FSR, while an external +2V to +3V reference allows an FSR of +16V to +24V, respectively. Calculate the LSB size using the following equation:

$$LSB = \frac{8 \times V_{REF}}{2^{14}}$$

This equals 1.2207mV with a +2.5V internal reference.

Table 5. ±10V Bipolar Code Table

TWO'S COMPLEMENT BINARY OUTPUT CODE	DECIMAL EQUIVALENT OUTPUT (CODE <sub>10</sub> )	INPUT VOLTAGE (V) (V <sub>REF</sub> = 2.5V, V <sub>MSV</sub> = 0V)
01 1111 1111 1111 0x1FFF	8191	9.9994 ±0.5 LSB
01 1111 1111 1110 0x1FFE	8190	9.9982 ±0.5 LSB
00 0000 0000 0001 0x0001	1	0.0018 ±0.5 LSB
00 0000 0000 0000 0x0000	0	0.0006 ±0.5 LSB
11 1111 1111 1111 0x3FFF	-1	-0.0006 ±0.5 LSB
10 0000 0000 0001 0x2001	-8191	-9.9982 ±0.5 LSB
10 0000 0000 0000 0x2000	-8192	-9.9994 ±0.5 LSB

The input range is centered about V<sub>MSV</sub>. Normally, MSV = AGND, and the input is symmetrical about zero. For a custom midscale voltage, drive MSV with an external voltage source. Noise present on MSV directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, be careful not to violate the absolute maximum voltage ratings of the analog inputs when choosing V<sub>MSV</sub>.

Determine the input voltage as a function of VREF, VMSV, and the output code in decimal using the following equation:

$$V_{CH} = LSB \times CODE_{10} + V_{MSV}$$

#### Bipolar ±5V Devices

Table 6 and Figure 10 show the two's complement transfer function for the MAX1320/MAX1321/MAX1322 with a ±5V input range. The FSR is four times the voltage at REF. The internal +2.500V reference gives a +10V FSR, while an external +2V to +3V reference allows an FSR of +8V to +12V, respectively. Calculate the LSB size using the following equation:

$$LSB = \frac{4 \times V_{REF}}{2^{14}}$$

This equals 0.6104mV when using the internal reference.

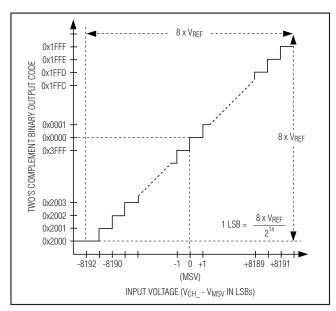


Figure 9. ±10V Bipolar Transfer Function

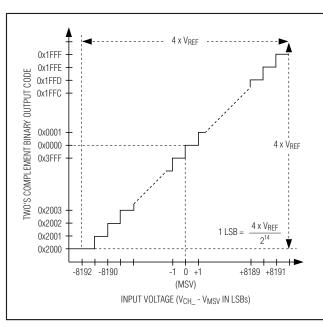


Figure 10. ±5V Bipolar Transfer Function

The input range is centered about  $V_{MSV}$ . Normally, MSV = AGND, and the input is symmetrical about zero. For a custom midscale voltage, drive MSV with an external voltage source. Noise present on MSV directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, be careful not to violate the absolute maximum voltage ratings of the analog inputs when choosing VMSV. Determine the input voltage as a function of VREF, VMSV, and the output code in decimal using the following equation:

$$V_{CH_{-}} = LSB \times CODE_{10} + V_{MSV}$$

#### Unipolar 0 to +5V Devices

Table 7 and Figure 11 show the offset binary transfer function for the MAX1316/MAX1317/MAX1318 with a 0 to +5V input range. The FSR is two times the voltage at REF. The internal +2.500V reference gives a +5V FSR, while an external +2V to +3V reference allows an FSR of +4V to +6V, respectively. Calculate the LSB size using the following equation:

$$LSB = \frac{2 \times V_{REF}}{2^{14}}$$

This equals 0.3052mV when using the internal reference.

Table 6. ±5V Bipolar Code Table

TWO'S COMPLEMENT BINARY OUTPUT CODE	DECIMAL EQUIVALENT OUTPUT (CODE <sub>10</sub> )	INPUT VOLTAGE (V) (V <sub>REF</sub> = 2.5V, V <sub>MSV</sub> = 0V)
01 1111 1111 1111 0x1FFF	8191	4.9997 ±0.5 LSB
01 1111 1111 1110 0x1FFE	8190	4.9991 ±0.5 LSB
00 0000 0000 0001 0x0001	1	0.0009 ±0.5 LSB
00 0000 0000 0000 0x0000	0	0.0003 ±0.5 LSB
11 1111 1111 1111 0x3FFF	-1	-0.0003 ±0.5 LSB
10 0000 0000 0001 0x2001	-8191	-4.9991 ±0.5 LSB
10 0000 0000 0000 0x2000	-8192	-4.9997 ±0.5 LSB

Table 7. 0 to +5V Unipolar Code Table

BINARY OUTPUT CODE	DECIMAL EQUIVALENT OUTPUT (CODE <sub>10</sub> )	INPUT VOLTAGE (V) (VREF = VREFMS = 2.5V)
11 1111 1111 1111 0x3FFF	16383	4.9998 ±0.5 LSB
11 1111 1111 1110 0x3FFE	16382	4.9995 ±0.5 LSB
10 0000 0000 0001 0x2001	8193	2.5005 ±0.5 LSB
10 0000 0000 0000 0x2000	8192	2.5002 ±0.5 LSB
01 1111 1111 1111 0x1FFF	8191	2.4998 ±0.5 LSB
00 0000 0000 0001 0x0001	1	0.0005 ±0.5 LSB
00 0000 0000 0000 0x0000	0	0.0002 ±0.5 LSB

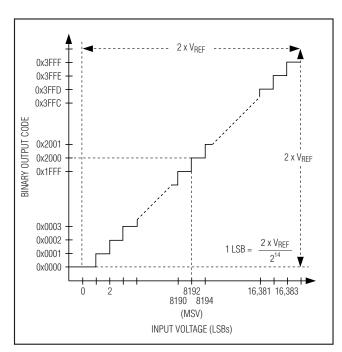


Figure 11. 0 to +5V Unipolar Transfer Function

The input range is centered about V<sub>MSV</sub>, which is internally set to +2.500V. For a custom midscale voltage, drive REF<sub>MS</sub> with an external voltage source and MSV will follow REF<sub>MS</sub>. Noise present on MSV or REF<sub>MS</sub> directly couples into the ADC result. Use a precision, low-drift voltage reference with adequate bypassing to prevent MSV from degrading ADC performance. For maximum FSR, be careful not to violate the absolute maximum voltage ratings of the analog inputs when choosing V<sub>MSV</sub>. Determine the input voltage as a function of V<sub>REF</sub>, V<sub>MSV</sub>, and the output code in decimal using the following equation:

$$V_{CH_{-}} = LSB \times CODE_{10} + (V_{MSV} - 2.500V)$$

#### **Definitions**

### **Integral Nonlinearity**

Integral nonlinearity (INL) is the deviation of the values on an actual transfer function from a straight line. For these devices, this straight line is a line drawn between the end points of the transfer function, once offset and gain errors have been nullified.

### **Differential Nonlinearity**

Differential nonlinearity (DNL) is the difference between an actual step width and the ideal value of 1 LSB. For these devices, the DNL of each digital output code is measured and the worst-case value is reported in the *Electrical Characteristics* table. A DNL error specification of less than ±1 LSB guarantees no missing codes and a monotonic transfer function.

### **Unipolar Offset Error**

For the unipolar MAX1316/MAX1317/MAX1318, the ideal zero-scale transition from 0x0000 to 0x0001 occurs at 1 LSB (see Figure 11). The unipolar offset error is the amount of deviation between the measured zero-scale transition point and the ideal zero-scale transition point.

### **Bipolar Offset Error**

For the bipolar MAX1320/MAX1321/MAX1322/MAX1324/MAX1325/MAX1326, the ideal zero-point transition from 0x3FFF to 0x0000 occurs at MSV, which is usually connected to ground (see Figures 9 and 10). The bipolar offset error is the amount of deviation between the measured zero-point transition and the ideal zero-point transition.

#### **Gain Error**

The ideal full-scale transition from 0x1FFE to 0x1FFF occurs at 1 LSB below full scale (see the *Transfer Functions* section). The gain error is the amount of deviation between the measured full-scale transition point and the ideal full-scale transition point, once offset error has been nullified.

### Signal-to-Noise Ratio

For a waveform perfectly reconstructed from digital samples, signal-to-noise ratio (SNR) is the ratio of the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization noise error only and results directly from the ADC's resolution (N bits):

$$SNR = (6.02 \times N + 1.76)dB$$

where N = 14 bits.

In reality, there are other noise sources besides quantization noise: thermal noise, reference noise, clock jitter, etc. SNR is computed by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first five harmonics, and the DC offset.

### Signal-to-Noise Plus Distortion

Signal-to-noise plus distortion (SINAD) is the ratio of the fundamental input frequency's RMS amplitude to the RMS equivalent of all the other ADC output signals:

$$SINAD(dB) = 20 \times log \left[ \frac{Signal_{RMS}}{(Noise + Distortion)_{RMS}} \right]$$

#### **Effective Number of Bits**

The effective number of bits (ENOB) indicates the global accuracy of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. With an input range equal to the full-scale range of the ADC, calculate the ENOB as follows:

ENOB = 
$$\frac{\text{SINAD - 1.76}}{6.02}$$

#### **Total Harmonic Distortion**

Total harmonic distortion (THD) is the ratio of the RMS sum of the first five harmonics of the input signal to the fundamental itself. This is expressed as:

THD = 20 × log 
$$\left[ \frac{\sqrt{V_2^2 + V_3^2 + V_4^2 + V_5^2}}{V_1} \right]$$

where  $V_1$  is the fundamental amplitude and  $V_2$  through  $V_5$  are the 2nd- through 5th-order harmonics.

### **Spurious-Free Dynamic Range**

Spurious-free dynamic range (SFDR) is the ratio of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest frequency component.

### **Aperture Delay**

Aperture delay (t<sub>AD</sub>) is the time delay from the sampling clock edge to the instant when an actual sample is taken.

### **Aperture Jitter**

Aperture Jitter (t<sub>AJ</sub>) is the sample-to-sample variation in aperture delay.

### **Channel-to-Channel Isolation**

Channel-to-channel isolation indicates how well each analog input is isolated from the other channels. Channel-to-channel isolation is measured by applying DC to channels 1 to 7, while a -0.5dBFS sine wave is applied to channel 0. A 100kHz FFT is taken for channel 0 and channel 1. Channel-to-channel isolation is expressed in dB as the power ratio of the two 100kHz magnitudes.

#### **Small-Signal Bandwidth**

A small -20dBFS analog input signal is applied to an ADC in a manner that ensures that the signal's slew rate does not limit the ADC's performance. The input frequency is then swept up to the point where the amplitude of the digitized conversion result has decreased 3dB.

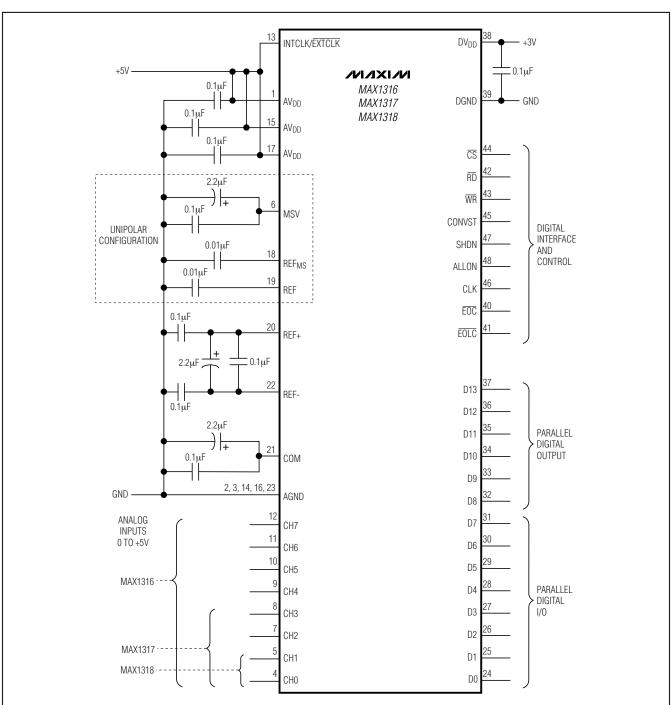
#### **Full-Power Bandwidth**

A large -0.5dBFS analog input signal is applied to an ADC, and the input frequency is swept up to the point where the amplitude of the digitized conversion result has decreased by 3dB. This point is defined as full-power input bandwidth frequency.

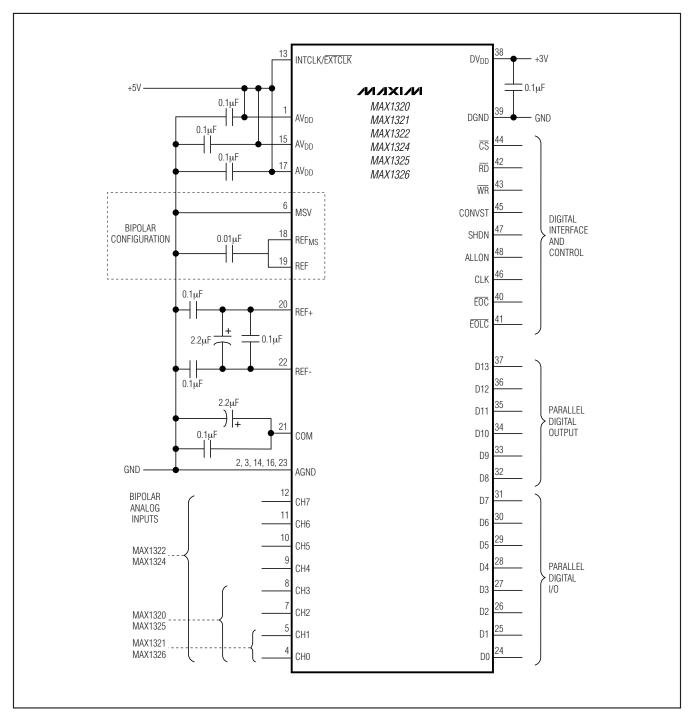
### **Chip Information**

TRANSISTOR COUNT: 80,000 PROCESS: BICMOS 0.6µm

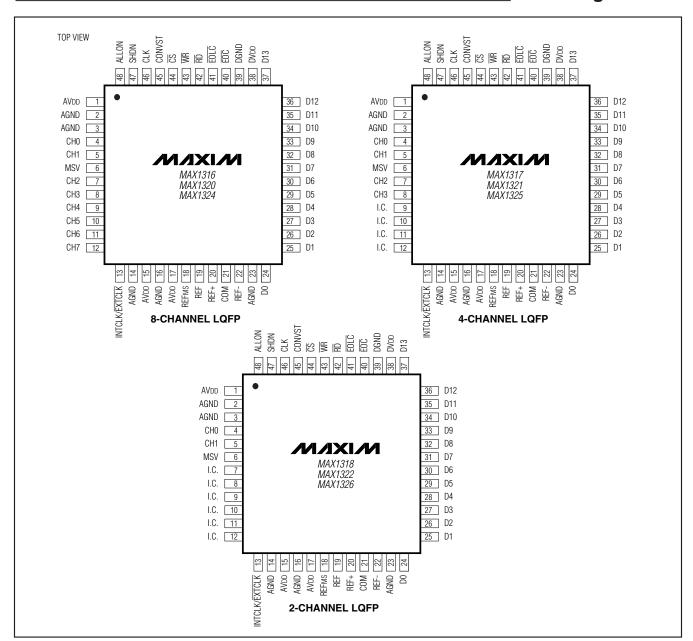
Typical Operating Circuits



Typical Operating Circuits (continued)



**Pin Configurations** 



### Package Information

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.
48 LQFP	C48-6	<u>21-0054</u>

### **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
3	2/07	Corrected units for input resistance in EC table	3
4	10/08	Changed specs for analog and digital supply current in EC table	4

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