

# X-LRQ-E Series Datasheet



- 75, 150, 300, 450, 600 mm travel
- Up to 840 mm/s speed and up to 300 N thrust
- 100 kg load capacity
- Ball screw and lead screw configurations
- Inline and parallel drive configurations
- Integrated, 500 CPR, motor mounted encoder provides slip/stall detection and recovery
- Built-in controller; daisy-chains with other Zaber products
- Custom versions available

#### X-LRQ-E Series Overview

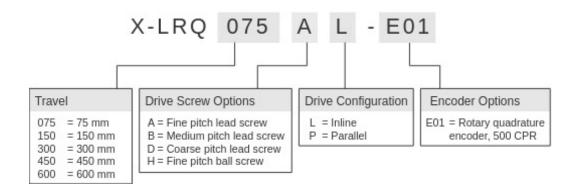
Zaber's X-LRQ-E Series devices are computer-controlled, motorized linear stages with high stiffness, load, and lifetime capabilities in a compact size. Each device is available in either an inline or parallel drive configuration. They are stand-alone units requiring only a standard 24 V or 48 V power supply. The built-in motor encoder allows closed-loop operation and slip/stall recovery features. An optional indexed knob provides convenient manual control for versatile operation even without a computer.

These stages connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other Zaber products. The daisy-chain also shares power, making it possible for multiple X-Series products to share a single power supply. Convenient locking, 4-pin, M8 connectors on the unit allow for secure connection between units.

At only 36 mm high, these stages are excellent for applications where a low profile is required. The X-LRQ-E's innovative design allows speeds up to 840 mm/s and loads up to 100 kg. Like all of Zaber's products, the X-LRQ-E Series is designed to be 'plug and play' and very easy to set up and operate. These stages can bolt together into XY and XYZ systems. Some multi axis configurations may require additional accessories, please contact Zaber Technical Support to ensure the correct ones are selected.

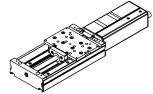
For more information visit: https://www.zaber.comproducts/linear-stages/X-LRQ-E

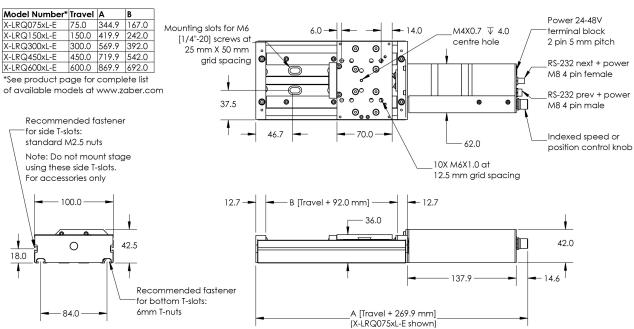
#### X-LRQ-E Series Part Numbering



### X-LRQ-E Series Drawings

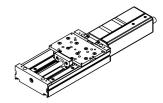


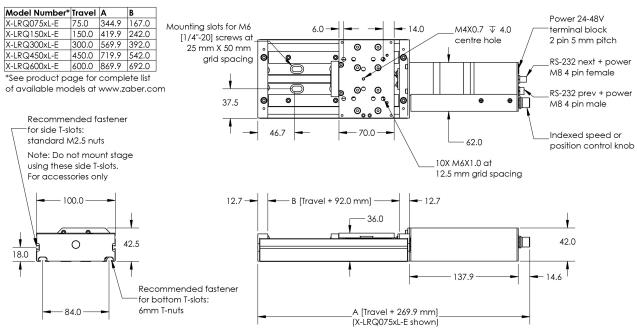




DWG 1086 R018







DWG 1086 R018



| Model Number* | Travel | Α     | В     |
|---------------|--------|-------|-------|
| X-LRQ075xP-E  | 75.0   | 209.8 | 167.0 |
| X-LRQ150xP-E  | 150.0  | 284.8 | 242.0 |
| X-LRQ300xP-E  | 300.0  | 434.8 | 392.0 |
| X-LRQ450xP-E  | 450.0  | 584.8 | 542.0 |
| X-I ROAOOxP-F | 400 D  | 7348  | 692 N |

<sup>|</sup> X-LRQ600xP-E | 600.0 | 734.8 | 692.0 | \*See product page for complete list of available models at www.zaber.com

Indexed speed or position control knob

RS-232 prev + power

Power 24-48V terminal block

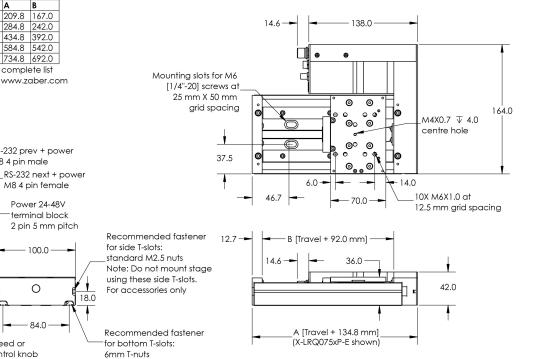
- 100.0 —

0

84.0

2 pin 5 mm pitch

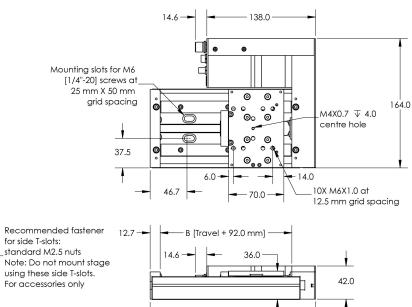
M8 4 pin male





| Model Number*       | Travel | Α     | В     |
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| Y_L P() A() () VP_E | 400 O  | 73/18 | 492 N |

<sup>|</sup> X-LRQ600xP-E | 600.0 | 734.8 | 692.0 | \*See product page for complete list of available models at www.zaber.com



\_A [Travel + 134.8 mm] (X-LRQ075xP-E shown)

RS-232 prev + power

M8 4 pin male

RS-232 next + power

M8 4 pin female

Power 24-48V
terminal block
2 pin 5 mm pitch

Recommer
for side T-sla
standard M
Note: Do na
using these
For accessor

Indexed speed or
position control knob

Recommen
for bottom T
6mm T-nuts

Recommended fastener for bottom T-slots:

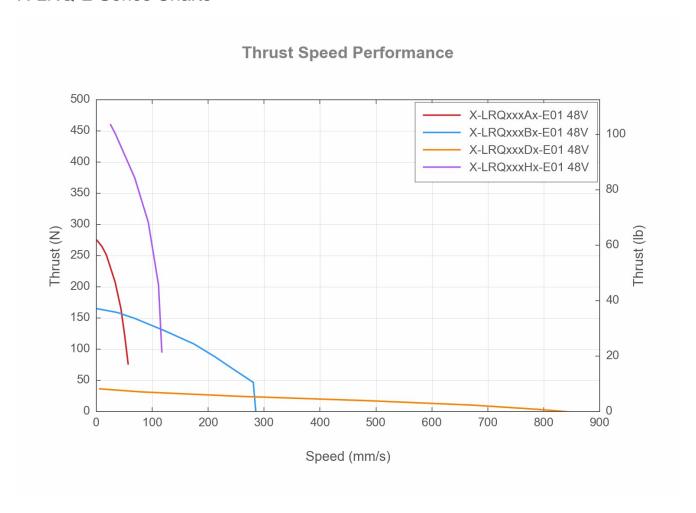
DWG 1258 R01

# X-LRQ-E Series Specifications

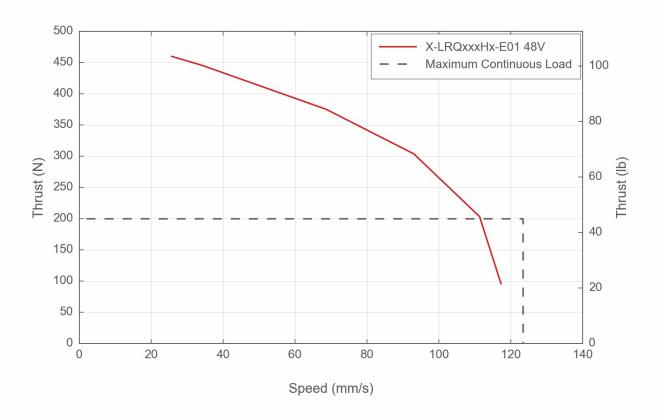
| Specification                       | Value                               | Alternate Unit  |
|-------------------------------------|-------------------------------------|-----------------|
| Microstep Size (Default Resolution) | 0.09921875 μm                       |                 |
| Built-in Controller                 | Yes                                 |                 |
| Travel Range                        | 75 mm                               | 2.953"          |
| Accuracy (unidirectional)           | 23 µm                               | 0.000906"       |
| Repeatability                       | < 2.5 µm                            | < 0.000098"     |
| Backlash                            | < 8 µm                              | < 0.000315"     |
| Maximum Speed                       | 54 mm/s                             | 2.126"/s        |
| Minimum Speed                       | 0.000061 mm/s                       | 0.000002"/s     |
| Speed Resolution                    | 0.000061 mm/s                       | 0.000002"/s     |
| Encoder Resolution                  | 500 CPR                             | 2000 states/rev |
| Encoder Type                        | Rotary quadrature encoder           |                 |
| Peak Thrust                         | 230 N                               | 51.6 lb         |
| Back-driving Force                  | Non-back-driving                    |                 |
| Maximum Continuous Thrust           | 100 N                               | 22.4 lb         |
| Communication Interface             | RS-232                              |                 |
| Communication Protocol              | Zaber ASCII (Default), Zaber Binary |                 |
| Maximum Centered Load               | 1000 N                              | 224.3 lb        |
| Maximum Cantilever Load             | 3000 N-cm                           | 4248.4 oz-in    |
| Guide Type                          | Recirculating Ball Linear Guide     |                 |
| Vertical Runout                     | < 20 µm                             | < 0.000787"     |
| Horizontal Runout                   | < 20 µm                             | < 0.000787"     |
| Pitch                               | 0.025°                              | 0.436 mrad      |
| Roll                                | 0.01°                               | 0.174 mrad      |
| Yaw                                 | 0.02°                               | 0.349 mrad      |
| Stiffness in Pitch                  | 640 N-m/°                           | 27 μrad/N-m     |
| Stiffness in Roll                   | 1850 N-m/°                          | 9 μrad/N-m      |
| Stiffness in Yaw                    | 665 N-m/°                           | 26 μrad/N-m     |
| Maximum Current Draw                | 1900 mA                             |                 |
| Power Supply                        | 24-48 VDC                           |                 |
| Power Plug                          | 2-pin screw terminal                |                 |

| Specification               | Value                         | Alternate Unit |
|-----------------------------|-------------------------------|----------------|
| Linear Motion Per Motor Rev | 1.27 mm                       | 0.050"         |
| Motor Steps Per Rev         | 200                           |                |
| Motor Type                  | Stepper (2 phase)             |                |
| Motor Rated Current         | 2300 mA/phase                 |                |
| Inductance                  | 2.8 mH/phase                  |                |
| Default Resolution          | 1/64 of a step                |                |
| Data Cable Connection       | Locking 4-pin M8              |                |
| Mechanical Drive System     | Precision lead screw          |                |
| Limit or Home Sensing       | Magnetic home sensor          |                |
| Manual Control              | Indexed knob with push switch |                |
| Axes of Motion              | 1                             |                |
| LED Indicators              | Yes                           |                |
| Mounting Interface          | M6 and M3 threaded holes      |                |
| Operating Temperature Range | 0 to 50 °C                    |                |
| Vacuum Compatible           | No                            |                |
| RoHS Compliant              | Yes                           |                |
| CE Compliant                | Yes                           |                |
| Weight                      | 2.19 kg                       | 4.828 lb       |

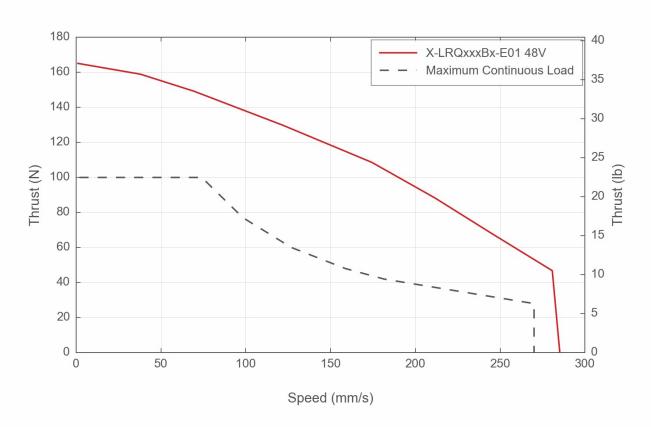
#### X-LRQ-E Series Charts

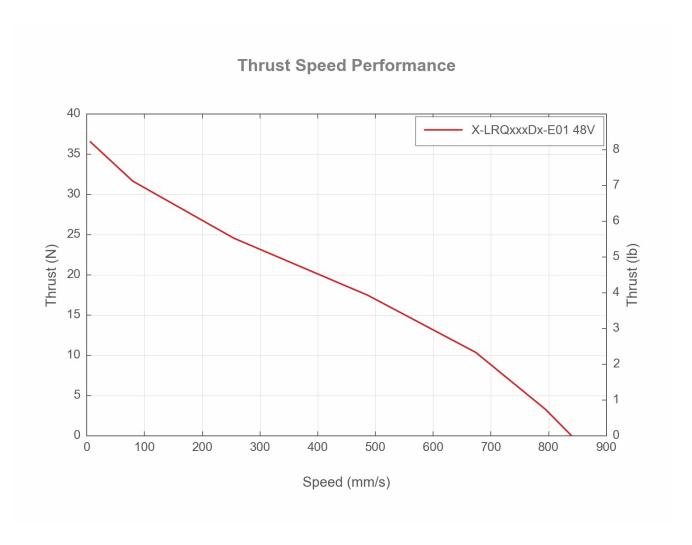


### **Thrust Speed Performance**



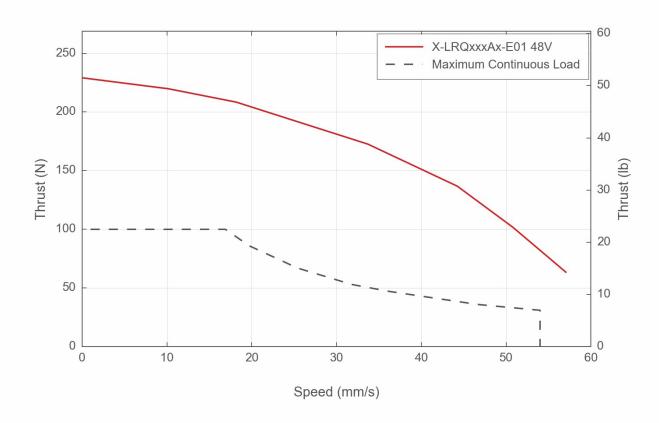
### **Thrust Speed Performance**



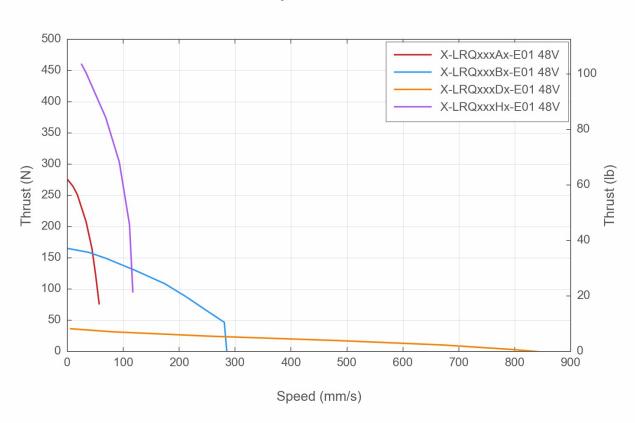




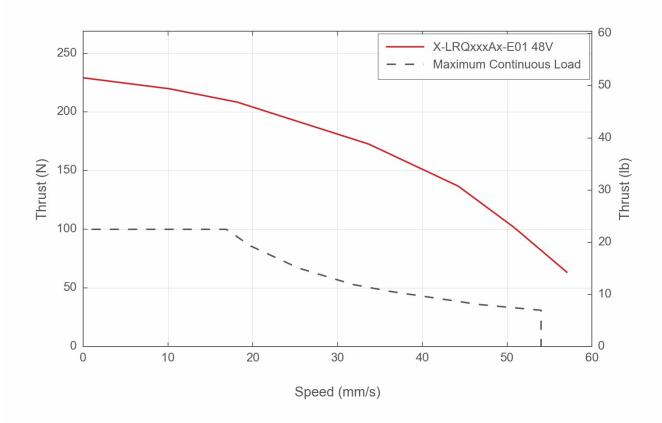




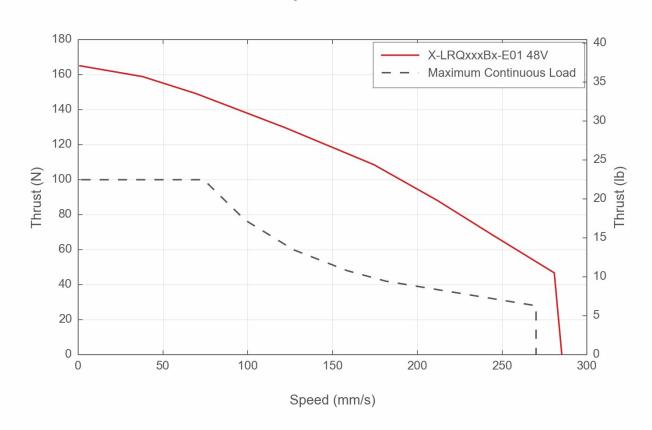




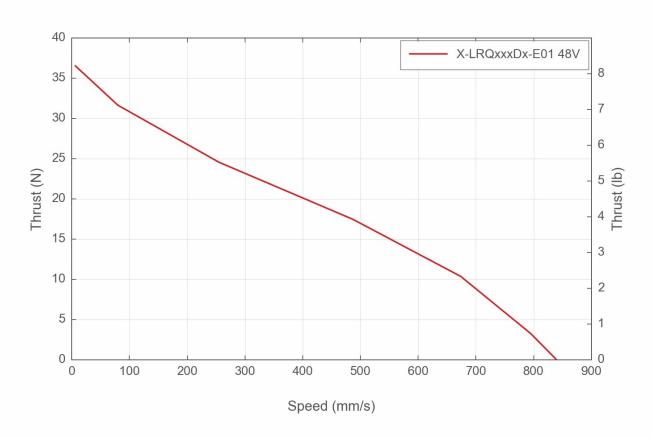


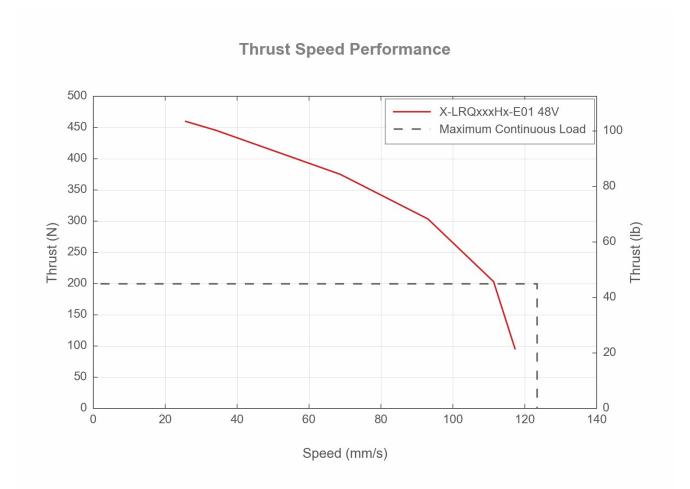


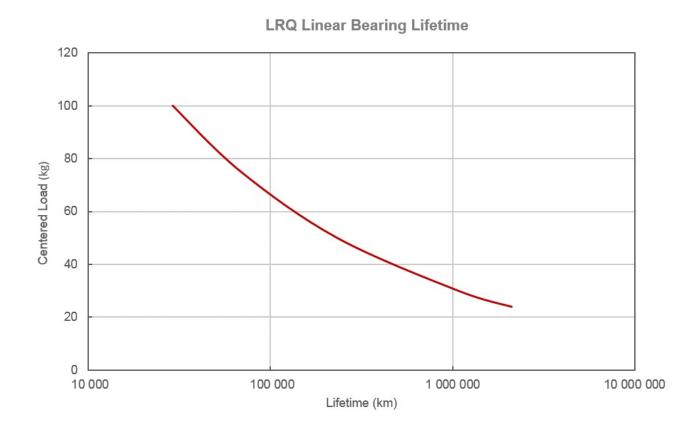




# **Thrust Speed Performance**







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