ATmega16A

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8-bit Microcontroller with 16K Bytes In-System Programmable Flash

DATASHEET SUMMARY

Features

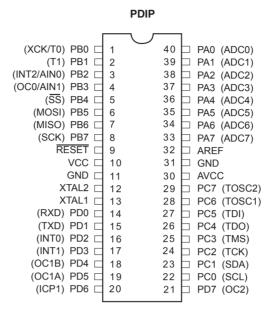
- High-performance, Low-power Atmel AVR 8-bit Microcontroller
- Advanced RISC Architecture
 - 131 Powerful Instructions Most Single-clock Cycle Execution
 - 32 x 8 General Purpose Working Registers
 - Fully Static Operation
 - Up to 16MIPS Throughput at 16MHz
 - On-chip 2-cycle Multiplier
- High Endurance Non-volatile Memory segments
 - 16KBytes of In-System Self-programmable Flash program memory
 - 512Bytes EEPROM
 - 1KByte Internal SRAM
 - Write/Erase Cycles: 10,000 Flash/100,000 EEPROM
 - Data retention: 20 years at 85°C/100 years at 25°C⁽¹⁾
 - Optional Boot Code Section with Independent Lock Bits
 - In-System Programming by On-chip Boot Program
 - True Read-While-Write Operation
 - Programming Lock for Software Security
- JTAG (IEEE std. 1149.1 Compliant) Interface
 - Boundary-scan Capabilities According to the JTAG Standard
 - Extensive On-chip Debug Support
 - Programming of Flash, EEPROM, Fuses, and Lock Bits through the JTAG Interface
- Peripheral Features
 - Two 8-bit Timer/Counters with Separate Prescalers and Compare Modes
 - One 16-bit Timer/Counter with Separate Prescaler, Compare Mode, and Capture Mode
 - Real Time Counter with Separate Oscillator
 - Four PWM Channels
 - 8-channel, 10-bit ADC
 - 8 Single-ended Channels
 - 7 Differential Channels in TQFP Package Only
 - 2 Differential Channels with Programmable Gain at 1x, 10x, or 200x
 - Byte-oriented Two-wire Serial Interface
 - Programmable Serial USART
 - Master/Slave SPI Serial Interface
 - Programmable Watchdog Timer with Separate On-chip Oscillator
 - On-chip Analog Comparator

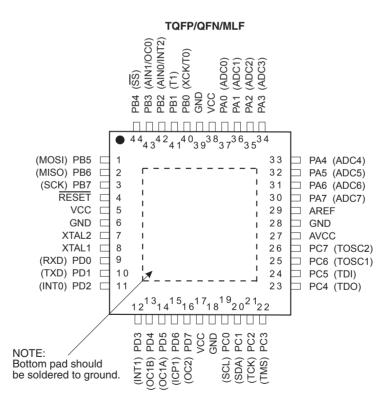
- Special Microcontroller Features
 - Power-on Reset and Programmable Brown-out Detection
 - Internal Calibrated RC Oscillator
 - External and Internal Interrupt Sources
 - Six Sleep Modes: Idle, ADC Noise Reduction, Power-save, Power-down, Standby and Extended Standby
- I/O and Packages
 - 32 Programmable I/O Lines
 - 40-pin PDIP, 44-lead TQFP, and 44-pad QFN/MLF
- Operating Voltages
 - 2.7 5.5V
- Speed Grades
 - 0 16MHz
- Power Consumption @ 1MHz, 3V, and 25°C
 - Active: 0.6mA
 - Idle Mode: 0.2mA
 - Power-down Mode: < 1µA



1. Pin Configurations

Figure 1-1. Pinout ATmega16A





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2. Overview

The ATmega16A is a low-power CMOS 8-bit microcontroller based on the Atmel AVR enhanced RISC architecture. By executing powerful instructions in a single clock cycle, the ATmega16A achieves throughputs approaching 1MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

2.1 Block Diagram

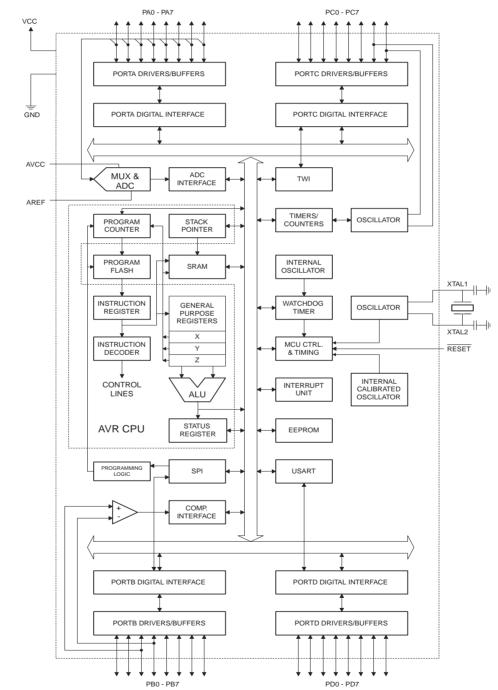


Figure 2-1. Block Diagram



The Atmel AVR core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The ATmega16A provides the following features: 16Kbytes of In-System Programmable Flash Program memory with Read-While-Write capabilities; 512bytes EEPROM; 1Kbyte SRAM; 32 general purpose I/O lines, 32 general purpose working registers; a JTAG interface for Boundary-scan; On-chip Debugging support and programming; three flexible Timer/Counters with compare modes; Internal and External Interrupts; a serial programmable USART; a byte oriented Two-wire Serial Interface, an 8-channel; 10-bit ADC with optional differential input stage with programmable gain (TQFP package only); a programmable Watchdog Timer with Internal Oscillator; an SPI serial port; and six software selectable power saving modes. The Idle mode stops the CPU while allowing the USART; Two-wire interface; A/D Converter; SRAM; Timer/Counters; SPI port; and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next External Interrupt or Hardware Reset. In Power-save mode, the Asynchronous Timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except Asynchronous Timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the crystal/resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with lowpower consumption. In Extended Standby mode, both the main Oscillator and the Asynchronous Timer continue to run.

The device is manufactured using Atmels high density nonvolatile memory technology. The On-chip ISP Flash allows the program memory to be reprogrammed in-system through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core. The boot program can use any interface to download the application program in the Application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel ATmega16A is a powerful microcontroller that provides a highly-flexible and cost-effective solution to many embedded control applications.

The ATmega16A is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, in-circuit emulators, and evaluation kits.

2.2 Pin Descriptions

2.2.1 VCC

Digital supply voltage.

2.2.2 GND

Ground.

2.2.3 Port A (PA7:PA0)

Port A serves as the analog inputs to the A/D Converter.

Port A also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. When pins PA0 to PA7 are used as inputs and are externally pulled low, they will source current if the internal pull-up resistors are activated. The Port A pins are tri-stated when a reset condition becomes active, even if the clock is not running.

2.2.4 Port B (PB7:PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B also serves the functions of various special features of the ATmega16A as listed on page 57.

2.2.5 Port C (PC7:PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tristated when a reset condition becomes active, even if the clock is not running. If the JTAG interface is enabled, the pull-up resistors on pins PC5(TDI), PC3(TMS) and PC2(TCK) will be activated even if a reset occurs.

Port C also serves the functions of the JTAG interface and other special features of the ATmega16A as listed on page 59.

2.2.6 Port D (PD7:PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega16A as listed on page 62.

2.2.7 **RESET**

Reset Input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running. The minimum pulse length is given in Table 27-2 on page 281. Shorter pulses are not guaranteed to generate a reset.

2.2.8 XTAL1

Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.



2.2.9 XTAL2

Output from the inverting Oscillator amplifier.

2.2.10 AVCC

AVCC is the supply voltage pin for Port A and the A/D Converter. It should be externally connected to V_{CC} , even if the ADC is not used. If the ADC is used, it should be connected to V_{CC} through a low-pass filter.

2.2.11 AREF

AREF is the analog reference pin for the A/D Converter.

3. Resources

A comprehensive set of development tools, application notes and datasheets are available for download on http://www.atmel.com/avr.

4. Data Retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C or 100 years at 25°C.

5. About Code Examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C Compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C Compiler documentation for more details.



6. Register Summary

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
\$3F (\$5F)	SREG	I	Т	Н	S	V	N	Z	С	9
\$3E (\$5E)	SPH	-	-	-	-	-	SP10	SP9	SP8	11
\$3D (\$5D)	SPL	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	11
\$3C (\$5C)	OCR0		0 Output Compar	-				I	I	81
\$3B (\$5B)	GICR	INT1	INT0	INT2	-	-	-	IVSEL	IVCE	47, 67
\$3A (\$5A)	GIFR	INTF1	INTF0	INTF2	-	-	-	-	-	68
\$39 (\$59)	TIMSK	OCIE2	TOIE2	TICIE1	OCIE1A	OCIE1B	TOIE1	OCIE0	TOIE0	82, 109, 128
\$38 (\$58)	TIFR SPMCR	OCF2 SPMIE	TOV2 RWWSB	ICF1	OCF1A RWWSRE	OCF1B BLBSET	TOV1 PGWRT	OCF0 PGERS	TOV0 SPMEN	82, 110, 128 242
\$37 (\$57) \$36 (\$56)	TWCR	TWINT	TWEA	– TWSTA	TWSTO	TWWC	TWEN	-	TWIE	189
\$35 (\$55)	MCUCR	SM2	SE	SM1	SM0	ISC11	ISC10	ISC01	ISC00	35, 66
\$34 (\$54)	MCUCSR	JTD	ISC2	-	JTRF	WDRF	BORF	EXTRF	PORF	41, 67, 236
\$33 (\$53)	TCCR0	FOC0	WGM00	COM01	COM00	WGM01	CS02	CS01	CS00	79
\$32 (\$52)	TCNT0	Timer/Counter	r0 (8 Bits)							81
	OSCCAL	Oscillator Calil	bration Register							30
\$31 ⁽¹⁾ (\$51) ⁽¹⁾	OCDR	On-Chip Debu	ıg Register							218
\$30 (\$50)	SFIOR	ADTS2	ADTS1	ADTS0	-	ACME	PUD	PSR2	PSR10	64,84,129,194,212
\$2F (\$4F)	TCCR1A	COM1A1	COM1A0	COM1B1	COM1B0	FOC1A	FOC1B	WGM11	WGM10	105
\$2E (\$4E)	TCCR1B	ICNC1	ICES1	-	WGM13	WGM12	CS12	CS11	CS10	107
\$2D (\$4D)	TCNT1H	Timer/Counter	r1 – Counter Regi	ster High Byte						108
\$2C (\$4C)	TCNT1L		r1 – Counter Regi	,						108
\$2B (\$4B)	OCR1AH		r1 – Output Comp	-						109
\$2A (\$4A)	OCR1AL		1 – Output Comp							109
\$29 (\$49)	OCR1BH		r1 – Output Comp	•	• •					109
\$28 (\$48)	OCR1BL	1	r1 – Output Comp	0	,					109
\$27 (\$47)	ICR1H		1 – Input Capture							109
\$26 (\$46)	ICR1L		1 – Input Capture			14/01/01	0000	0001	0000	109
\$25 (\$45)	TCCR2	FOC2	WGM20	COM21	COM20	WGM21	CS22	CS21	CS20	125
\$24 (\$44)	TCNT2 OCR2	Timer/Counter	2 (6 Bits) 2 Output Compar	o Pagistar						127 127
\$23 (\$43) \$22 (\$42)	ASSR	Timer/Counter				AS2	TCN2UB	OCR2UB	TCR2UB	127
\$21 (\$41)	WDTCR	_	_	_	WDTOE	WDE	WDP2	WDP1	WDP0	41
	UBRRH	URSEL	_	_	-	WDL		R[11:8]	WBI 0	162
\$20 ⁽²⁾ (\$40) ⁽²⁾	UCSRC	URSEL	UMSEL	UPM1	UPM0	USBS	UCSZ1	UCSZ0	UCPOL	161
\$1F (\$3F)	EEARH	-	-	-	-	-	-	-	EEAR8	20
\$1E (\$3E)	EEARL	EEPROM Add	Iress Register Lov	v Byte	•		•	•	•	20
\$1D (\$3D)	EEDR	EEPROM Data	a Register							20
\$1C (\$3C)	EECR	-	-	-	-	EERIE	EEMWE	EEWE	EERE	20
\$1B (\$3B)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	64
\$1A (\$3A)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	64
\$19 (\$39)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	64
\$18 (\$38)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	64
\$17 (\$37)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	64
\$16 (\$36)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	65
\$15 (\$35)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	65
\$14 (\$34) \$13 (\$33)	DDRC PINC	DDC7 PINC7	DDC6 PINC6	DDC5 PINC5	DDC4 PINC4	DDC3 PINC3	DDC2 PINC2	DDC1 PINC1	DDC0 PINC0	65 65
\$13 (\$33) \$12 (\$32)	PINC	PINC7 PORTD7	PINC6 PORTD6	PINC5 PORTD5	PINC4 PORTD4	PINC3 PORTD3	PINC2 PORTD2	PINCT PORTD1	PINCO	65
\$12 (\$32) \$11 (\$31)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	65
\$10 (\$30)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	65
\$0F (\$2F)	SPDR	SPI Data Reg								138
\$0E (\$2E)	SPSR	SPIF	WCOL	-	-	-	-	-	SPI2X	138
\$0D (\$2D)	SPCR	SPIE	SPE	DORD	MSTR	CPOL	CPHA	SPR1	SPR0	137
\$0C (\$2C)	UDR	USART I/O D								158
\$0B (\$2B)	UCSRA	RXC	TXC	UDRE	FE	DOR	PE	U2X	MPCM	159
\$0A (\$2A)	UCSRB	RXCIE	TXCIE	UDRIE	RXEN	TXEN	UCSZ2	RXB8	TXB8	160
\$09 (\$29)	UBRRL	USART Baud	Rate Register Lo	w Byte						162
	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	194
\$08 (\$28)			REFS0	ADLAR	MUX4	MUX3	MUX2	MUX1	MUX0	208
\$07 (\$27)	ADMUX	REFS1				ADIE	ADPS2	ADPS1	ADPS0	210
\$07 (\$27) \$06 (\$26)	ADCSRA	ADEN	ADSC	ADATE	ADIF	ADIL	ADI OL	7,0101	7121 00	
\$07 (\$27) \$06 (\$26) \$05 (\$25)	ADCSRA ADCH	ADEN ADC Data Reg	ADSC gister High Byte	ADATE	ADIF	ADIL	7101 02	ABIOT	7.01.00	211
\$07 (\$27) \$06 (\$26) \$05 (\$25) \$04 (\$24)	ADCSRA ADCH ADCL	ADEN ADC Data Reg ADC Data Reg	ADSC gister High Byte gister Low Byte		ADIF	ADIL	ABI OL		1.51.00	211 211
\$07 (\$27) \$06 (\$26) \$05 (\$25) \$04 (\$24) \$03 (\$23)	ADCSRA ADCH ADCL TWDR	ADEN ADC Data Reg ADC Data Reg Two-wire Seria	ADSC gister High Byte gister Low Byte al Interface Data F	Register	•	1				211 211 191
\$07 (\$27) \$06 (\$26) \$05 (\$25) \$04 (\$24)	ADCSRA ADCH ADCL	ADEN ADC Data Reg ADC Data Reg	ADSC gister High Byte gister Low Byte		ADIF TWA3 TWS4	TWA2 TWS3	TWA1	TWA0 TWPS1	TWGCE TWPS0	211 211

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- Notes: 1. When the OCDEN Fuse is unprogrammed, the OSCCAL Register is always accessed on this address. Refer to the debugger specific documentation for details on how to use the OCDR Register.
 - 2. Refer to the USART description for details on how to access UBRRH and UCSRC.
 - 3. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
 - 4. Some of the Status Flags are cleared by writing a logical one to them. Note that the CBI and SBI instructions will operate on all bits in the I/O Register, writing a one back into any flag read as set, thus clearing the flag. The CBI and SBI instructions work with registers \$00 to \$1F only.



7. Instruction Set Summary

Mnemon-				Flags	
ics	Operands	Description	Operation		#Clocks
	LOGIC INSTRUCTION				
ADD	Rd, Rr	Add two Registers	Rd ← Rd + Rr	Z,C,N,V,H	1
ADC	Rd, Rr	Add with Carry two Registers	$Rd \leftarrow Rd + Rr + C$	Z,C,N,V,H	1
ADIW	Rdl,K	Add Immediate to Word	Rdh:Rdl ← Rdh:Rdl + K	Z,C,N,V,S	2
SUB	Rd, Rr	Subtract two Registers	Rd ← Rd - Rr	Z,C,N,V,H	1
SUBI	Rd, K	Subtract Constant from Register	Rd ← Rd - K	Z,C,N,V,H	1
SBC	Rd, Rr	Subtract with Carry two Registers	$Rd \leftarrow Rd - Rr - C$	Z,C,N,V,H	1
SBCI	Rd, K	Subtract with Carry Constant from Reg.	$Rd \leftarrow Rd - K - C$	Z,C,N,V,H	1
SBIW	Rdl,K	Subtract Immediate from Word	Rdh:Rdl ← Rdh:Rdl - K	Z,C,N,V,S	2
AND	Rd, Rr	Logical AND Registers	$Rd \leftarrow Rd \bullet Rr$	Z,N,V	1
ANDI	Rd, K	Logical AND Register and Constant	$Rd \leftarrow Rd \bullet K$	Z,N,V	1
OR	Rd, Rr	Logical OR Registers	Rd ← Rd v Rr	Z,N,V	1
ORI	Rd, K	Logical OR Register and Constant	$Rd \leftarrow Rd \lor K$	Z,N,V	1
EOR	Rd, Rr	Exclusive OR Registers	$Rd \leftarrow Rd \oplus Rr$	Z,N,V	1
COM	Rd	One's Complement	Rd ← \$FF – Rd	Z,C,N,V	1
NEG	Rd	Two's Complement	Rd ← \$00 – Rd	Z,C,N,V,H	1
SBR	Rd,K	Set Bit(s) in Register	$Rd \leftarrow Rd \lor K$	Z,N,V	1
CBR	Rd,K	Clear Bit(s) in Register	$Rd \leftarrow Rd \bullet (\$FF - K)$	Z,N,V	1
INC	Rd	Increment	$Rd \leftarrow Rd + 1$	Z,N,V	1
DEC	Rd	Decrement	$Rd \leftarrow Rd - 1$	Z,N,V	1
TST	Rd	Test for Zero or Minus	$Rd \leftarrow Rd \bullet Rd$	Z,N,V	1
CLR	Rd	Clear Register	$Rd \leftarrow Rd \oplus Rd$	Z,N,V	1
SER	Rd	Set Register	$Rd \leftarrow FF$	None	1
MUL	Rd, Rr	Multiply Unsigned	$R1:R0 \leftarrow Rd \times Rr$	Z,C	2
MULS	Rd, Rr	Multiply Signed	$R1:R0 \leftarrow Rd \times Rr$	Z,C	2
MULSU	Rd, Rr	Multiply Signed with Unsigned	$R1:R0 \leftarrow Rd \times Rr$	Z,C	2
FMUL	Rd, Rr	Fractional Multiply Unsigned	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
FMULS	Rd, Rr	Fractional Multiply Signed	$R1:R0 \leftarrow (Rd \times Rr) << 1$	Z,C	2
FMULSU	Rd, Rr	Fractional Multiply Signed with Unsigned	$R1:R0 \leftarrow (Rd \times Rr) \le 1$	Z,C	2
BRANCH INSTRUC	k	Deletive lump		Mana	2
IJMP	ĸ	Relative Jump	$PC \leftarrow PC + k + 1$ $PC \leftarrow Z$	None	2
JMP	k	Indirect Jump to (Z) Direct Jump	$PC \leftarrow Z$ $PC \leftarrow k$	None None	3
RCALL	k	Relative Subroutine Call	$PC \leftarrow PC + k + 1$	None	3
ICALL	ĸ	Indirect Call to (Z)	$PC \leftarrow Z$	None	3
CALL	k	Direct Subroutine Call	$PC \leftarrow k$	None	4
RET	K	Subroutine Return	PC ← STACK	None	4
RETI		Interrupt Return	PC ← STACK		4
CPSE	Rd,Rr	Compare, Skip if Equal	if (Rd = Rr) PC \leftarrow PC + 2 or 3	None	1/2/3
CP	Rd,Rr	Compare	Rd – Rr	Z, N,V,C,H	1
CPC	Rd,Rr	Compare with Carry	Rd – Rr – C	Z, N,V,C,H	1
CPI	Rd,K	Compare Register with Immediate	Rd – K	Z, N,V,C,H	1
SBRC	Rr, b	Skip if Bit in Register Cleared	if (Rr(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBRS	Rr, b	Skip if Bit in Register is Set	if (Rr(b)=1) PC \leftarrow PC + 2 or 3	None	1/2/3
SBIC	P, b	Skip if Bit in I/O Register Cleared	if (P(b)=0) PC ← PC + 2 or 3	None	1/2/3
SBIS	P, b	Skip if Bit in I/O Register is Set	if (P(b)=1) PC ← PC + 2 or 3	None	1/2/3
BRBS	s, k	Branch if Status Flag Set	if (SREG(s) = 1) then $PC \leftarrow PC+k + 1$	None	1/2
BRBC	s, k	Branch if Status Flag Cleared	if (SREG(s) = 0) then $PC \leftarrow PC+k + 1$	None	1/2
BREQ	k	Branch if Equal	if (Z = 1) then PC \leftarrow PC + k + 1	None	1/2
BRNE	k	Branch if Not Equal	if (Z = 0) then PC \leftarrow PC + k + 1	None	1/2
BRCS	k	Branch if Carry Set	if (C = 1) then PC \leftarrow PC + k + 1	None	1/2
BRCC	k	Branch if Carry Cleared	if (C = 0) then PC \leftarrow PC + k + 1	None	1/2
BRSH	k	Branch if Same or Higher	if (C = 0) then PC \leftarrow PC + k + 1	None	1/2
BRLO	k	Branch if Lower	if (C = 1) then PC \leftarrow PC + k + 1	None	1/2
BRMI	k	Branch if Minus	if (N = 1) then PC \leftarrow PC + k + 1	None	1/2
BRPL	k	Branch if Plus	if (N = 0) then PC \leftarrow PC + k + 1	None	1/2
BRGE	k	Branch if Greater or Equal, Signed	if (N \oplus V= 0) then PC \leftarrow PC + k + 1	None	1/2
BRLT	k	Branch if Less Than Zero, Signed	if (N \oplus V= 1) then PC \leftarrow PC + k + 1	None	1/2
	1 1	Branch if Half Carry Flag Set	if (H = 1) then PC \leftarrow PC + k + 1	None	1/2
BRHS	k				
BRHS BRHC	k	Branch if Half Carry Flag Cleared	if (H = 0) then PC \leftarrow PC + k + 1	None	1/2
BRHS				None None None	1/2 1/2 1/2



Mnemon-				Flags	
ics	Operands	Description	Operation		#Clocks
BRVS	k	Branch if Overflow Flag is Set	if (V = 1) then PC \leftarrow PC + k + 1	None	1/2
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC \leftarrow PC + k + 1	None	1/2
BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC \leftarrow PC + k + 1	None	1/2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC \leftarrow PC + k + 1	None	1/2
DATA TRANSFER	INSTRUCTIONS		1		
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	$Rd+1:Rd \leftarrow Rr+1:Rr$	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X), X \leftarrow X + 1$	None	2
LD LD	Rd, - X Rd, Y	Load Indirect and Pre-Dec.	$X \leftarrow X - 1, Rd \leftarrow (X)$ $Rd \leftarrow (Y)$	None None	2
LD	Rd, 1 Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1, Rd \leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1, Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Rd, k	Load Direct from SRAM	$Rd \leftarrow (k)$	None	2
ST	X, Rr	Store Indirect	$(X) \leftarrow Rr$	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	$(X) \leftarrow Rr, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1$, (X) $\leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1$, (Y) $\leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	$(Y + q) \leftarrow Rr$	None	2
ST	Z, Rr	Store Indirect	$(Z) \leftarrow Rr$	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	$(Z) \leftarrow \operatorname{Rr}, Z \leftarrow Z + 1$	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	$Z \leftarrow Z - 1, (Z) \leftarrow Rr$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$(Z + q) \leftarrow Rr$	None	2
STS	k, Rr	Store Direct to SRAM	$(k) \leftarrow Rr$	None	2
LPM LPM	Rd, Z	Load Program Memory Load Program Memory	$R0 \leftarrow (Z)$ $Rd \leftarrow (Z)$	None None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	3
SPM	Να, Ζ'	Store Program Memory	$(Z) \leftarrow R1:R0$	None	-
IN	Rd, P	In Port	$Rd \leftarrow P$	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	$Rd \leftarrow STACK$	None	2
BIT AND BIT-TEST	INSTRUCTIONS				
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	$I/O(P,b) \leftarrow 0$	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
LSR	Rd	Logical Shift Right	$Rd(n) \leftarrow Rd(n+1), Rd(7) \leftarrow 0$	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	$Rd(0) \leftarrow C, Rd(n+1) \leftarrow Rd(n), C \leftarrow Rd(7)$	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	$Rd(7) \leftarrow C, Rd(n) \leftarrow Rd(n+1), C \leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=0.6$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(3:0)←Rd(7:4),Rd(7:4)←Rd(3:0)	None	1
BSET	s	Flag Set	SREG(s) $\leftarrow 1$	SREG(s)	1
BCLR	S Date	Flag Clear	$SREG(s) \leftarrow 0$	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	T	1
BLD	Rd, b	Bit load from T to Register	$Rd(b) \leftarrow T$	None C	1
SEC		Set Carry	$\begin{array}{c} C \leftarrow 1 \\ C \leftarrow 0 \end{array}$	C	1
CLC SEN		Clear Carry Set Negative Flag	C ← 0 N ← 1	N	1
CLN		Clear Negative Flag	$N \leftarrow 1$ $N \leftarrow 0$	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 1 Z ← 0	Z	1
SEI		Global Interrupt Enable	1 ← 1		1
CLI	1	Global Interrupt Enable	1 ← 0	1	1
SES	1	Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	s	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET	1	Set T in SREG	T ← 1	Т	1

Mnemon-				Flags	
ics	Operands	Description	Operation		#Clocks
CLT		Clear T in SREG	T ← 0	Т	1
SEH		Set Half Carry Flag in SREG	H ← 1	Н	1
CLH		Clear Half Carry Flag in SREG	H ← 0	Н	1
MCU CONTROL I	INSTRUCTIONS				
NOP		No Operation		None	1
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/timer)	None	1
BREAK		Break	For On-Chip Debug Only	None	N/A

8. Ordering Information

Speed (MHz)	Power Supply	Ordering Code ⁽¹⁾	Package	Operation Range
16	2.7 - 5.5V	ATmega16A-AU ATmega16A-AUR ⁽²⁾ ATmega16A-PU ATmega16A-MU ATmega16A-MUR ⁽²⁾	44A 44A 40P6 44M1 44M1	Industrial (-40°C to 85°C)

Notes: 1. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

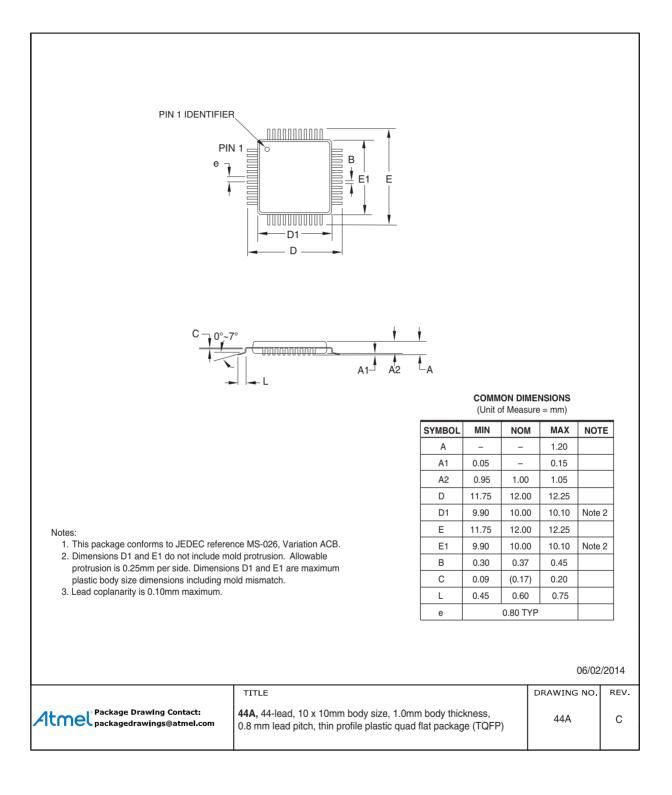
2. Tape & Reel.

Package Type				
44 A	44-lead, Thin (1.0 mm) Plastic Gull Wing Quad Flat Package (TQFP)			
40P6	40-pin, 0.600" Wide, Plastic Dual Inline Package (PDIP)			
44M1	44-pad, 7 x 7 x 1.0mm body, lead pitch 0.50mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)			

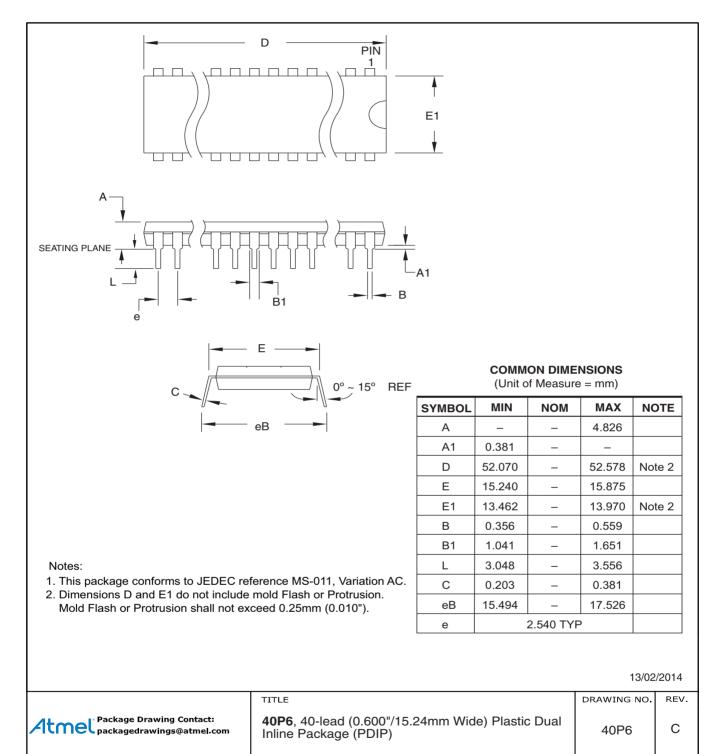
Atmel

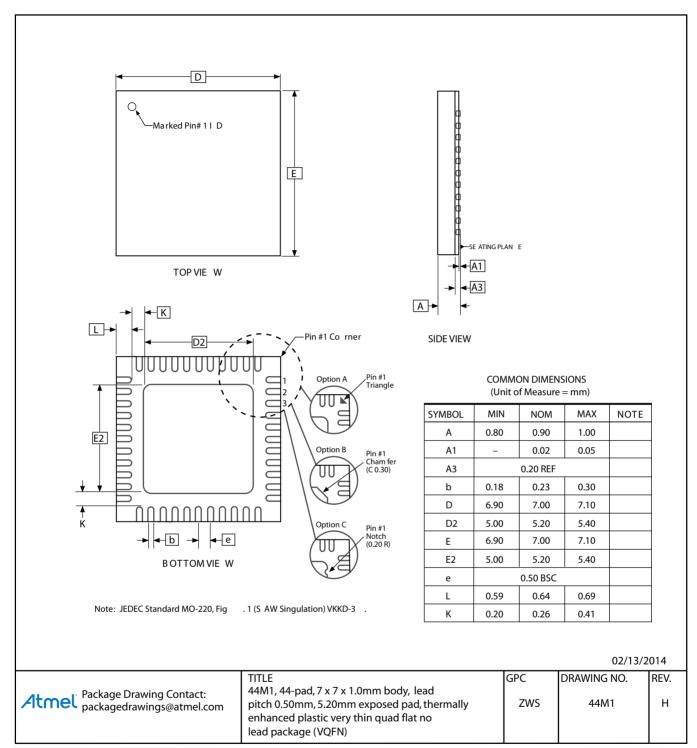
9. Packaging Information

9.1 44A



9.2 40P6





10. Errata

The revision letter in this section refers to the revision of the ATmega16A device.

10.1 ATmega16A rev. N to rev. Q

- · First Analog Comparator conversion may be delayed
- Interrupts may be lost when writing the timer registers in the asynchronous timer
- IDCODE masks data from TDI input
- · Reading EEPROM by using ST or STS to set EERE bit triggers unexpected interrupt request

1. First Analog Comparator conversion may be delayed

If the device is powered by a slow rising V_{CC} , the first Analog Comparator conversion will take longer than expected on some devices.

Problem Fix/Workaround

When the device has been powered or reset, disable then enable the Analog Comparator before the first conversion.

2. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

3. IDCODE masks data from TDI input

The JTAG instruction IDCODE is not working correctly. Data to succeeding devices are replaced by all-ones during Update-DR.

Problem Fix / Workaround

- If ATmega16A is the only device in the scan chain, the problem is not visible.
- Select the Device ID Register of the ATmega16A by issuing the IDCODE instruction or by entering the Test-Logic-Reset state of the TAP controller to read out the contents of its Device ID Register and possibly data from succeeding devices of the scan chain. Issue the BYPASS instruction to the ATmega16A while reading the Device ID Registers of preceding devices of the boundary scan chain.
- If the Device IDs of all devices in the boundary scan chain must be captured simultaneously, the ATmega16A must be the fist device in the chain.

4. Reading EEPROM by using ST or STS to set EERE bit triggers unexpected interrupt request.

Reading EEPROM by using the ST or STS command to set the EERE bit in the EECR register triggers an unexpected EEPROM interrupt request.

Problem Fix / Workaround

Always use OUT or SBI to set EERE in EECR.



11. Datasheet Revision History

Please note that the referring page numbers in this section are referred to this document. The referring revision in this section are referring to the document revision.

Rev. 8154C -- 07/2014

- 1. Atmel brand style guide and datasheet template of 2014-0502 updated in datasheet including the last page.
- 2. Updated the Ordering Code to include Tape & Reel part numbers.
- 3. Removed notes 6 and 7 concerning actual low period in Table 27-4 on page 282.
- 4. Changed notes 3, 4 and 5, removed note 6 concerning TQFP/MLF packages in Section 27.2 "DC Characteristics" on page 278

Rev. 8154B - 07/09

- 1. Updated "Errata" on page 17.
- 2. Updated the last page with Atmel's new addresses.

Rev. 8154A - 06/08

1. Initial revision (Based on the ATmega16/L datasheet revision 2466R-AVR-05/08)

Changes done compared ATmega16/L datasheet revision 2466R-AVR-05/08:

- Updated description in "Stack Pointer" on page 11.
- All Electrical characteristics is moved to "Electrical Characteristics" on page 278.
- Register descriptions are moved to sub sections at the end of each chapter.
- Added "Speed Grades" on page 280.
- New graphs in "Typical Characteristics" on page 289.
- New "Ordering Information" on page 13.

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