High Efficiency White LED Driver

The NCP5604A and NCP5604B products are multiple output LED drivers dedicated to the display back light. The NCP5604A drives up to 4 LEDs, the NCP5604B version being dedicated to the three LED applications.

The two parts share a common built-in DC/DC converter, based on a charge pump structure, including the new 1.33X mode of operation, improving the efficiency over the full input battery supply voltage span over 90%.

Features

- 2.7 to 5.5 V Input Voltage Range
- Consistent 85% Efficiency
- 1.0 µA Quiescent Supply Current
- All Pins are Fully ESD Protected
- Built-in Short Circuit Protection
- Provides Four Independent LED Drives
- 200 kHz Digital Dimming Function
- Unloaded LED Protection
- Short Circuit Current Proof
- Tight 0.5% LED Current Matching
- These are Pb-Free Devices*

Typical Applications

- Portable Back Light
- •-Digital Cellular Phone Camera Photo Flash
- LCD and Key Board Simultaneously Drive

ON Semiconductor®

http://onsemi.com

(Note: Microdot may be in either location)

(Top View) * Pin 5 in not connected in the NCP5604B

ORDERING INFORMATION

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specification

Brochure, BRD8011/D.

*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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Figure 1. Typical Multiple White LED Driver

Figure 2. NCP5604A Simplified Block Diagram

Figure 3. NCP5604B Simplified Block Diagram (Pin 5 disconnected)

PIN FUNCTION DESCRIPTION

1. Using low ESR 1.0 µF ceramic capacitor is mandatory to optimize the Charge Pump efficiency. The DC Bias effect must be taken into account when selecting the ceramic capacitor. Smallest foot print packages (size 0602 and lower) are prone to strong DC bias effect, reducing the real capacitance significantly.

2. Total DC-DC output current is limited to 100 mA.

3. The exposed flag shall be connected to ground.

MAXIMUM RATINGS

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

4. This device series contains ESD protection and exceeds the following tests: Human Body Model (HBM): JESD22-A114.

Machine Model (MM): JESD22-A115.

5. The maximum package power dissipation limit must not be exceeded.

6. Latchup current maximum rating: \pm 100 mA per JEDEC standard: JESD78.

7. Moisture Sensitivity Level (MSL): per IPC/JEDEC standard: J-STD-020A.

POWER SUPPLY SECTION (Typical values are referenced to $T_A = +25^\circ C$, Min & Max values are referenced -40 $^\circ C$ to +85 $^\circ C$ ambient temperature, operating conditions 2.85 V < Vbat < 5.5 V, unless otherwise noted.)

8. The total output current is evenly distributed across the external LED.

9. LED4 is not connected in the NCP5604B version.

10.The NCP5604B controls 75 mA in total in the three current mirrors, the extra 25 mA available current from the DC-DC converter being available for external purpose.

ANALOG SECTION (Typical values are referenced to $T_A = +25^\circ \text{C}$, Min & Max values are referenced -40°C to $+85^\circ \text{C}$ ambient temperature, operating conditions 2.85 V < Vbat < 5.5 V, unless otherwise noted.)

11. The overall output current tolerance depends upon the accuracy of the external resistor. Using 1% or better resistor is recommended. 12. The external circuit must not force the IREF pin voltage either higher or lower than the 600 mV specified.

DIGITAL PARAMETERS SECTION (Typical values are referenced to $T_A = +25^\circ C$, Min & Max values are referenced -40°C to +85°C ambient temperature, operating conditions 2.85 V < Vbat < 5.5 V, unless otherwise noted.) Note: Digital inputs undershoot < - 0.30 V to ground, Digital inputs overshoot < 0.30 V to V_{BAT}.

| Pin | Symbol | Rating | Min | Typ | Max | Unit |
|------------|---------------|--|------|-----|------------------|------|
| | ™PWM | Input Enable PWM | 0.1 | - | 200 | kHz |
| | V_{IH} | Positive Going Input High Voltage Threshold, EN Signal | l .3 | - | Ѵ _{ват} | |
| | V_{IL} | Negative Going Input High Voltage Threshold, EN Signal | | - | 0.4 | |

APPLICATIONS INFORMATION

DC-DC OPERATION

The converter is based on a charge pump technique to generate a DC voltage capable to supply the White LED load The system regulates the current flowing into each LED by means of internal current mirrors associated with the white diodes. Consequently, the output voltage will be equal to the Vf of the LED, plus the 300 mV (typical) developed across the internal NMOS mirror. Typically, assuming a standard white LED forward biased at 10 mA, the output voltage will be 3.8 V.

The third external capacitor makes possible the 1.33X extra mode of operation, with a significant efficiency improvement of the converter over the normal battery voltage span. The threshold levels have been defined to optimize this range of operating voltage, assuming a high efficiency is not relevant when the system is connected to a battery charger (i.e. Vbat > 4.5 V).

The built-in OVP circuit continuously monitor each output and stops the converter when the voltage is above 5.0 V. The converter resumes to normal operation when the voltage drops below 5.0 V (no latch-up mechanism). Consequently, the chip can operate with no load during any test procedures, but in the case of special applications, it is recommended to connect the non used LED driver either to a LED, or to the Vbat supply to minimize the internal losses (see LOAD CONNECTION paragraph).

LOAD CURRENT CALCULATION

The load current is derived from the 600 mV reference voltage provided by the internal Band Gap associated to the external resistor connected across I_{RFF} pin and Ground (see Figure 4). In any case, no voltage shall be forced at IREF pin, either downward or upward.

The reference current is multiplied by the constant $k = 260$ to yield the output load current. Since the reference

voltage is based on a temperature compensated Band Gap structure, a tight tolerance resistor will provide a very accurate load current. The resistor is calculated from the Ohm's law $(R_{bias} = Vref/I_{REF})$ and a more practical equation can be arranged to define the resistor value for a given output current:

$$
R_{bias} = (Vref * k) / lout
$$
\n
$$
R_{bias} = (0.6 * 260) / lout
$$
\n
$$
(eq. 1)
$$

$$
R_{bias} = 156/Iout
$$
 (eq. 2)

Consequently, the resistor value will range between $R_{bias} = 156/25$ mA = 6240 Ω and $R_{bias} = 156/0.5$ mA = 312 k Ω . Obviously, the tolerance of such a resistor must be 1% or better, with a 100 ppm thermal coefficient, to get the expected overall tolerance.

Figure 4. Basic Reference Current Source

Figure 5. Typical IOUT Tolerance as a Function of the VBAT Supply

Figure 7. Typical LED to LED Current Matching at IREF Maximum

LOAD CONNECTION

The NCP5604A chip is capable of driving the four LED simultaneously, as depicted in Figure [1,](#page-1-0) but the load can be arranged to accommodate one or two LED if necessary in the application (see Figure 8). The four current mirror can be connected in parallel to drive a single powerful LED, thus yielding 100 mA current capability in a single LED.

Figure 8. Typical Single and Double LED Connections

The applications using three LED shall use the NCP5604B version to make profit of the highest efficiency (see Figure [9](#page-9-0)). In this case, LED4 is not connected and pin 5 is internally unconnected.

Figure 9. Using the NCP5604B to Drive a Three LED Layout

Finally, an external network can be connected across Vout and ground, but the current through such network will not be regulated by the NCP5604A chip (see Figure 10). On top of that, the total current out of the Vout pin shall be limited to 100 mA.

Figure 10. Extra Load Connected to Vout

DIMMING

The dimming can be achieved by two means:

- Use a digital PWM signal to control the EN pin
- Use an analog signal to control the reference current IREF pin.

The digital PWM is straightforward, yielding a zero to 100% duty cycle, but the output current is pulsed since the system is continuously switched ON/OFF. There is no need for extra passive component, the clock being provided by an I/O port from the MCU (see Figure 11).

Input PWM Signal Frequency: 100 Hz to 200 kHz

Figure 11. Basic Digital PWM Dimming Control

The PWM frequency can be up to 200 kHz once the circuit has been properly started. On the other hand, with a 1% to 99% span, the circuit supports a large Duty Cycle to accommodate any range of dimming. The waveforms given in Figure 12 illustrate the NCP5604A behavior during the 50 kHz PWM operation. The same mechanism applies for the NCP5604B version.

Figure 12. PWM Modulation Span: 1% to 99%

Besides the popular PWM mode, a simple analog technique can be built with two extra components (one resistor + one NMOS), the net advantage being a continuous output current once the operating point has been stabilized (see Figure [13](#page-10-0)). The absolute output current tolerance depends upon the precision of the two external resistors, the $R_{DS(on)}$ of the NMOS being negligible in front of the resistor value. The example given, Figure [13](#page-10-0) yields a 1.0 mA output current when Q1 is OFF,

and 23 mA when Q1 is ON. The concept can use either a DC drive or a pulsed mode to dynamically dim the light out of the LED.

A different analog approach, but more complex solution, can be derived from either a DC or a pulsed voltage associated with a current mirror built with low cost discrete devices (see Figure 14). The associated filter (R2/R3/C1) provides a continuous voltage to the current mirror, thus a digitally controlled continuous output current. Generally speaking, the PWM frequency could be either in the low end 20 Hz to 200 Hz band, or above the audio band (25 kHz and beyond) to make sure the dimming can be adjusted from zero to 100% without any audible noise. As a matter of fact, the NCP5604A has been designed to guarantee 200 kHz PWM at the ENABLE pin.

The current mirror can be largely improved by using an external operational amplifier to get a very stable and temperature independent current, but such a solution could turn out to be too expensive and, generally speaking, the basic structure given, Figure 13, gives good results since the current depends mostly upon the quality of resistor R2.

Figure 13. Basic Analog Dimming Control

Figure 14. Basic Analog PWM Dimming Control

Figure 17. Input Current Short Circuit Operation

SHORT CIRCUIT OPERATION

The circuit is designed to support a short circuit across Vout and Ground without damage. When a short occurs, the pulsed output current increases to the maximum peak value until the output voltage drops below 1 V. At this point, the pulsed current is limited to 40 mA average (typical), until the short is removed. The waveforms given in Figure 16 illustrate the functional operation. Similarly, the input current is limited 300 mA peak (typical) as depicted in Figure 17.

Figure 16. Output Short Circuit Operation

Figure 18. Typical Efficiency

Figure 20. Silk View Top Layer

Figure 21. Demo Board Printed Circuit Layout

PACKAGE DIMENSIONS

WQFN16 MT SUFFIX CASE 488AK-01 ISSUE O

- NOTES: 1. DIMENSIONING AND TOLERANCING PER
- ASME Y14.5M, 1994. 2. CONTROLLING DIMENSION: MILLIMETERS. **2. DOMINICERTO DIMENSION: MEERS**
3. DIMENSION **b** APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN
- 0.25 AND 0.30 MM FROM TERMINAL. 4. COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERMINALS.
- 5. Lmax CONDITION CAN NOT VIOLATE 0.2 MM SPACING BETWEEN LEAD TIP AND FLAG.

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