

Dual PLL frequency synthesizer

BU2630F / BU2630FV

The BU2630F/BU2630FV are a CMOS LSI with an internal dual PLL synthesizer.

VCOs for transmission and reception can be controlled independently, and the reference frequency and main counter settings can also be programmed separately. This product is designed for applications involving cordless telephones and communications equipment worldwide.

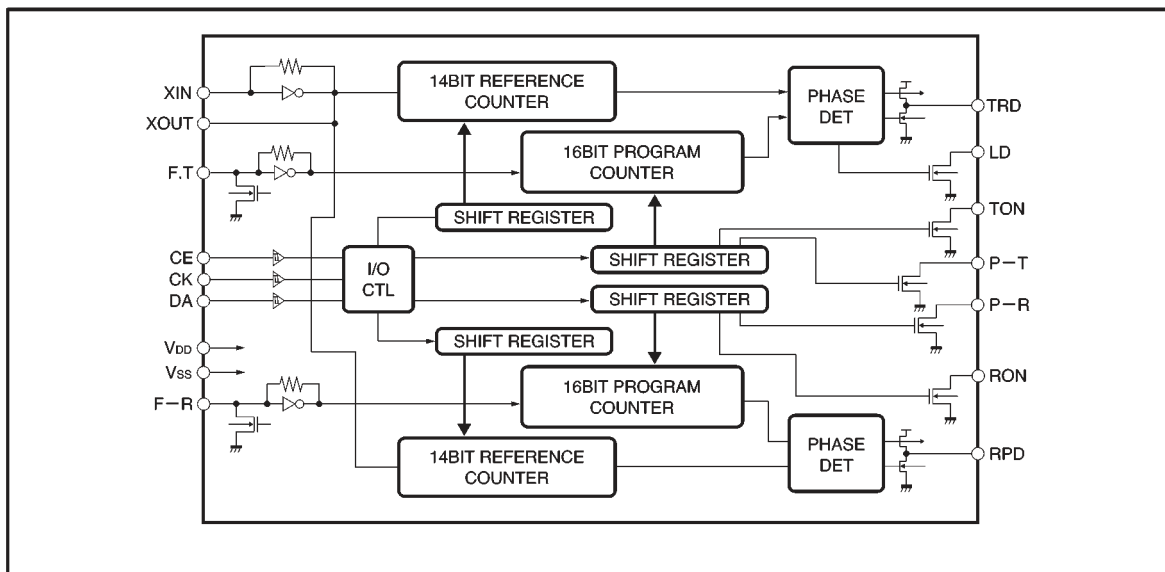
●Applications

Cordless telephones, amateur short wave radios, industrial transceivers, VHF/UHF frequency generators, and others

●Features

- | | |
|--|---|
| 1) Operation possible at up to 80MHz ($V_{DD} = 2.5$). | 3) 16-bit main counter. |
| 2) Low current dissipation | 4) Internal 14-bit reference frequency counter. |
| Dual-system operation : 2.2mA (typ), $V_{DD} = 3V$ | 5) Unlock detection possible. |
| Single-system operation : 1.2mA (typ), $V_{DD} = 3V$ | 6) Four output ports. (open drain) |
| Non-operating state : 0.2mA (typ), $V_{DD} = 3V$ | 7) Control possible using 3-wire serial input. |

●Block diagram



● Absolute maximum ratings (Ta = 25°C)

| Parameter | Symbol | Limits | Unit |
|-----------------------|------------------|-----------|-------|
| Power supply voltage | V _{DD} | -0.3~+7.0 | V |
| Power dissipation | BU2630F | Pd | mW |
| | BU2630FV | | |
| | | | 350*2 |
| Operating temperature | T _{opr} | -40~+85 | °C |
| Storage temperature | T _{stg} | -55~+125 | °C |

*1 Reduced by 5.0mW for each increase in Ta of 1°C over 25°C.

*2 Reduced by 3.5mW for each increase in Ta of 1°C over 25°C.

● Recommended operating conditions (Ta = 25°C)

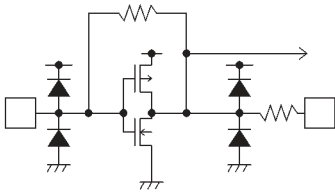
| Parameter | Symbol | Min. | Typ. | Max. | Unit |
|----------------------|-----------------|------|------|------|------|
| Power supply voltage | V _{DD} | 2.5 | 3.0 | 5.5 | V |

● Pin descriptions

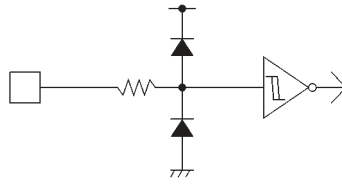
| Pin No. | Pin name | Name | Function | I/O circuit |
|---------|-----------------|--------------------------------------|---|-------------|
| 16 | XOUT | Crystal resonator | For reference frequency | TYPE A |
| 1 | XIN | | | |
| 2 | V _{SS} | | | |
| 3 | RPD | Phase comparator output | This is LO if the locally divided value is higher than the reference frequency, HI if it is lower, and Z if it matches. | TYPE E |
| 4 | P-R | Output port | This is controlled by the input data. | TYPE D |
| 5 | RON | | | |
| 6 | F-R | VCO input | Local input for reception | TYPE F |
| 7 | CE | Chip enable clock signal serial data | When CE is HIGH, the DA synchronized to the rise of CK is read into the internal shift register, and is latched at the timing of the CE fall. | TYPE B |
| 8 | CK | | | |
| 9 | DA | | | |
| 10 | LD | Unlock output | This goes ON when the PLL is unlocked on the transmission side | TYPE D |
| 11 | F-T | VCO input | Local input for transmission | TYPE F |
| 12 | TON | Output port | This is controlled by the input data | TYPE D |
| 13 | P-T | | | |
| 14 | TPD | Phase comparator output | This is LO if the locally divided value is higher than the reference frequency, HI if it is lower, and Z if it matches. | TYPE E |
| 15 | V _{DD} | Power supply | 2.5~5.5V | |

● Input/output circuits

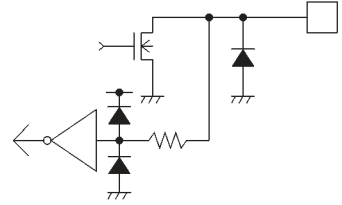
TYPE A



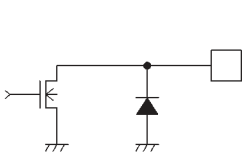
TYPE B



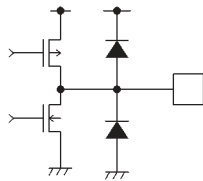
TYPE C



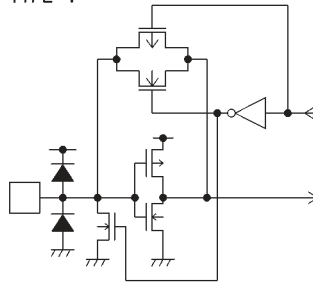
TYPE D



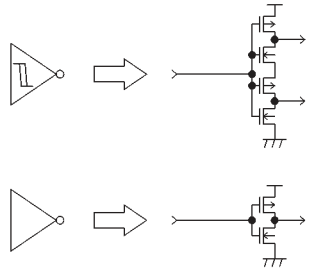
TYPE E



TYPE F



TYPE I



● Electrical characteristics (unless otherwise noted, Ta = 25°C, VDD = 3.0V, VSS = 0V)

| Parameter | Symbol | Min. | Typ. | Max. | Unit | Conditions |
|--------------------------------|----------|---------|---------|---------|------|---|
| Power supply current 1 | IDD1 | — | 2.2 | 3.0 | mA | Dual-system operation |
| Power supply current 2 | IDD2 | — | 1.2 | 2.0 | mA | Single-system operation |
| Power supply current 3 | IDD3 | — | 0.2 | 0.3 | mA | With operation stopped: XTAL = 10.24 MHz |
| Input high level voltage 1 | VIH1 | 0.8VDD | — | — | V | CE CK DA |
| Input low level voltage 1 | VIL1 | — | — | 0.2VDD | V | CE CK DA |
| Input high level current 1 | I IH1 | — | — | 1.0 | μA | CE CK DA VIN=VDD |
| Input high level current 2 | I IH2 | — | 0.3 | — | μA | XIN VIN=VDD |
| Input high level current 3 | I IH3 | — | 5.0 | — | μA | F-T F-R VIN=VDD |
| Input low level current 1 | I IL1 | -1.0 | — | — | μA | CE CK DA VIN=VSS |
| Input low level current 2 | I IL2 | — | -0.3 | — | μA | XIN VIN=VSS |
| Input low level current 3 | I IL3 | — | -5.0 | — | μA | F-T F-R VIN=VSS |
| Output low level voltage 1 | VOL1 | — | 0.3 | 0.5 | V | LD TON P-T RON P-R IO=1.0mA |
| Off level leakage current 1 | IOFF1 | — | — | 1.0 | μA | LD TON P-T RON P-R VO=10V |
| Output low level voltage 2 | VOL2 | — | — | 0.3 | V | F-T F-R IOUT=0.1mA |
| Output high level voltage | VOH3 | VDD-50 | VDD-1.0 | — | mV | TPD RPD IOUT=-0 μA |
| Output low level voltage | VOL3 | — | 1.3 | 50 | mV | TPD RPD IOUT=0 μA |
| Output high level voltage | VOH4 | VDD-100 | VDD-40 | — | mV | TPD RPD IOUT=-100 μA |
| Output low level voltage | VOL4 | — | 30 | 100 | mV | TPD RPD IOUT=100 μA |
| Off level leakage current 2 | IOFF2 | — | — | 100 | nA | TPD RPD VOUT=VDD |
| Off level leakage current 3 | IOFF3 | -100 | — | — | nA | TPD RPD VOUT=VSS |
| Internal feedback resistance 1 | RF1 | — | 10 | — | MΩ | XIN |
| Internal feedback resistance 2 | RF2 | — | 500 | — | kΩ | F-T F-R |
| Input frequency 1 | F IN1 | 1.0 | 10.24 | 16.0 | MHz | XIN, sine wave, C coupling |
| Input frequency 2 | F IN2 | 1.0 | — | 20 | MHz | F-T F-R, sine wave, C coupling*2, VIN = 100 mVrms |
| Input frequency 3 | F IN3 | 50 | — | 80 | MHz | F-T F-R, sine wave, C coupling*2, VIN = 100 mVrms |
| Input frequency 4 | F IN4 | 20 | — | 50 | MHz | F-T F-R, sine wave, C coupling*2, VIN = 50 mVrms |
| Input frequency 5*1 | F IN5 | 0.4 | — | 20 | MHz | F-T F-R, sine wave, C coupling*2, VIN =100mVrms |
| Maximum input amplitude | F INMax. | — | — | VDD+0.3 | VP-P | XIN, F-T F-R |
| Input capacitance | C IN | — | 4 | 7 | PF | F-T F-R |
| Minimum pulse width | TW | 1.0 | — | — | μs | CK, DA |
| Input data rise time | TR | — | — | 300 | ns | CK, DA |
| Input data fall time | TF | — | — | 300 | ns | CE, CK, DA |

© Not designed for radiation resistance.

*1 PS = 1

*2 Minimum input level at which operation is possible

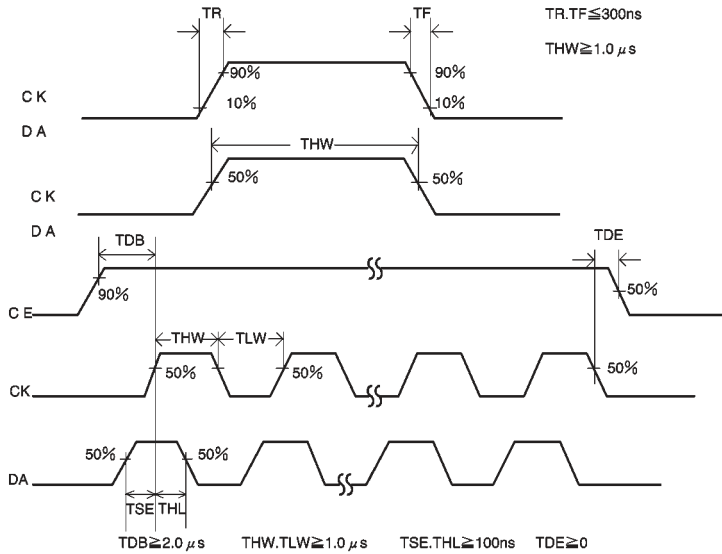
Divider values which can be set

Program divider: PS = 0: 256 to 65535, PS = 1: 3 to 4095

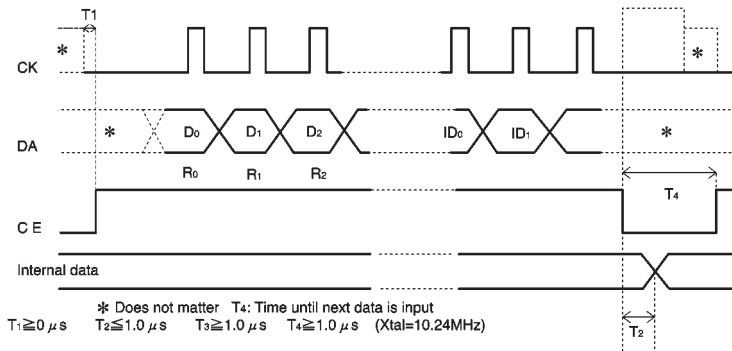
Reference frequency divider: 3 to 16383

●Circuit operation

Input data switching characteristics



Input data format



Programmable divider and control data input: TX side (ID₀ = 0, ID₁ = 0), RX side (ID₀ = 1, ID₁ = 0)

LSB ← Input from D₀

| | | | | | | | | | | | | | | | |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|------------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| D ₀ | D ₁ | D ₂ | D ₃ | D ₄ | D ₅ | D ₆ | D ₇ | D ₈ | D ₉ | D ₁₀ | D ₁₁ | D ₁₂ | D ₁₃ | D ₁₄ | D ₁₅ |
| | | | | P-T | TON | OFF | PS | T ₀ | T ₁ | ID ₀ | ID ₁ | | | | |
| | | | | (P-R | TON | OFF | PS | T ₀ | T ₁) | | | | | | |

MSB

Reference frequency divider data input: TX side (ID₀ = 0, ID₁ = 1), RX side (ID₀ = 1, ID₁ = 1)

| | | | | | | | | | | | | | | | |
|----------------|----------------|----------------|----------------|----------------|----------------|-----------------|-----------------|----------------|----------------|-----------------|-----------------|-----------------|-----------------|----|----|
| R ₀ | R ₁ | R ₂ | R ₃ | R ₄ | R ₅ | R ₆ | R ₇ | R ₈ | R ₉ | R ₁₀ | R ₁₁ | R ₁₂ | R ₁₃ | PL | PH |
| | | | | * | * | LD ₀ | LD ₁ | * | * | ID ₀ | ID ₁ | | | | |

MSB

* Does not matter (LD₀ and LD₁₀ are valid on TX side only)

Description of data

(1) Programmable divider data: D₀ ~ D₁₅

| | | | | | | | | | | | | | | | |
|--|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| D ₀ | D ₁ | D ₂ | D ₃ | D ₄ | D ₅ | D ₆ | D ₇ | D ₈ | D ₉ | D ₁₀ | D ₁₁ | D ₁₂ | D ₁₃ | D ₁₄ | D ₁₅ |
| Example: For a transmission frequency of 46.610MHz and a reference frequency of 5.00 kHz | | | | | | | | | | | | | | | |
| No. of divisions: 46.610 ÷ 5.00 kHz = 9322 (D) = 246A (H) | | | | | | | | | | | | | | | |
| 0 | 1 | 0 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 | 0 |
| A | | | | 6 | | | | 4 | | | | 2 | | | |

(2) Reference frequency data: R₀ ~ R₁₃

| | | | | | | | | | | | | | |
|--|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-----------------|-----------------|-----------------|-----------------|
| R ₀ | R ₁ | R ₂ | R ₃ | R ₄ | R ₅ | R ₆ | R ₇ | R ₈ | R ₉ | R ₁₀ | R ₁₁ | R ₁₂ | R ₁₃ |
| Example: When XTAL = 10.24 MHz and reference frequency is 5.00 kHz | | | | | | | | | | | | | |
| No. of divisions: 10.24 MHz ÷ 5.00 kHz = 2048 (D) = 800 (H) | | | | | | | | | | | | | |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| 0 | | | | 0 | | | | 8 | | | | 0 | |

(3) Output port control data : P-T (P-R) TON (RON)

1 : Open drain output ON (LO)

0 : Open drain output OFF (HI)

(4) OFF transmission side (reception side) : Operation stopped

F - T (F - R) pull-down : TPD (RPD) high-impedance, LD = OFF

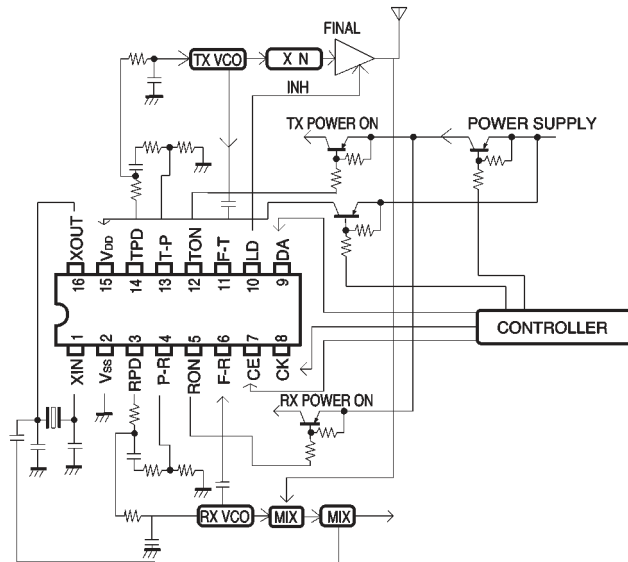
(5) PS

Programmable device change : No. of divisions = 3 ~ 4095

| | | | | | | | | | | | | | | | |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| D ₀ | D ₁ | D ₂ | D ₃ | D ₄ | D ₅ | D ₆ | D ₇ | D ₈ | D ₉ | D ₁₀ | D ₁₁ | D ₁₂ | D ₁₃ | D ₁₄ | D ₁₅ |
| * | * | * | * | LSB | | | | | | | | | | | MSB |
| DONT CARE | | | | | | | | | | | | | | | |

- (6) PL, PH, and PD pin control
 - 0 0 : PLL operation
 - 1 0 : Forced LO state
 - 0 1 : Forced HI state
 - 1 1 : Forced LO state
- (7) LD₀, LD₁, LD pin control (valid only on TX side)
 - 0 0 : ON when unlocked (LO)
 - 0 1 : Air pulse output
 - 1 0 : Forced ON state (LO)
 - 1 1 : Forced OFF state (HI)
- (8) Input (00) to test T₀ and T₁.

●Application example



※: Immediately after the power supply is turned on, the various pins remain unstable until data is input.

Fig. 1

●Electrical characteristic curves

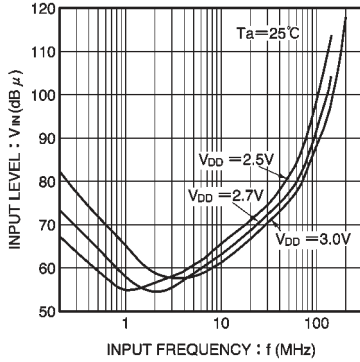


Fig. 2 Input frequency vs. input level

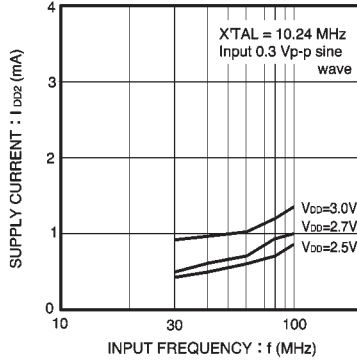


Fig. 3 Input frequency vs. supply current (for single operation)

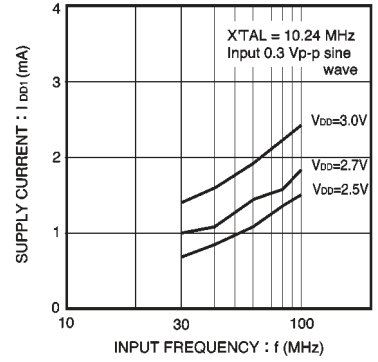
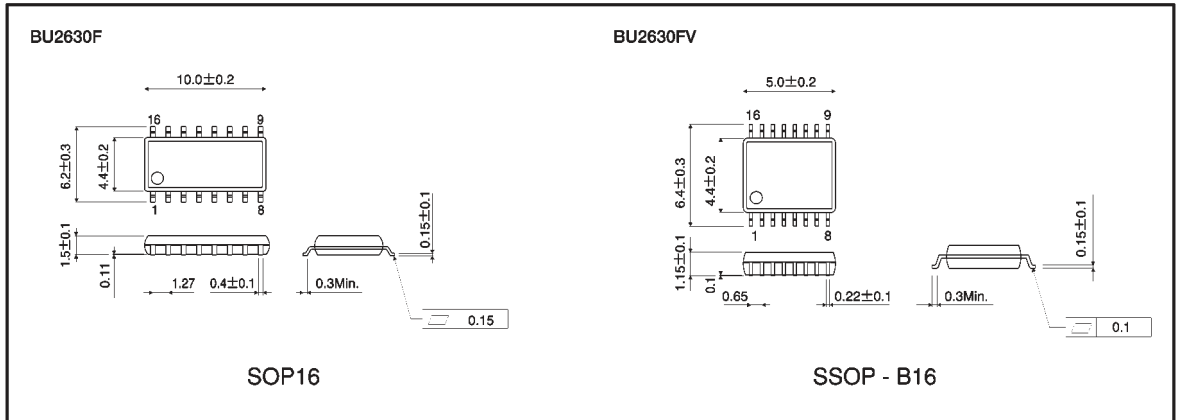


Fig. 4 Input frequency vs. supply current (for dual operation)

●External dimensions (Units: mm)



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